

Ex. 6 Shifted data problems

I.C. : $t = t_0$ instead of $t = 0$

(i) G.S. (L.T.) \rightarrow determine constants

(ii) Set $t = \tilde{t} + t_0$.

I.C. $t = t_0 \rightarrow \tilde{t} = 0$.

e.g. $y'' + y = 2t$ $y(\frac{\pi}{4}) = \frac{\pi}{2}$ $y'(\frac{\pi}{4}) = 2 - \sqrt{2}$

$$t = \tilde{t} + \frac{\pi}{4} \quad \tilde{y}(\tilde{t}) = y(t)$$

$$\tilde{y}'' + \tilde{y} = 2(\tilde{t} + \frac{\pi}{4}) \quad \tilde{y}(0) = \frac{\pi}{2}, \quad \tilde{y}'(0) = 2 - \sqrt{2}$$

Step 1. L.T.

$$s^2 \tilde{Y} - s(\frac{\pi}{2}) - (2 - \sqrt{2}) + \tilde{Y} = 2 \frac{1}{s^2} + \frac{\pi}{2} \frac{1}{s}$$

Step 2. $\tilde{Y} = \frac{2}{s^2(s^2+1)} + \frac{\pi/2}{s(s^2+1)} + \frac{\pi}{2} \frac{s}{s^2+1} + \frac{2-\sqrt{2}}{s^2+1}$

Step 3. $\tilde{y} = 2(\tilde{t} - \sin \tilde{t}) + \frac{\pi}{2}(1 - \cos \tilde{t}) + \frac{\pi}{2} \cos \tilde{t} + (2 - \sqrt{2}) \sin \tilde{t}$

$$\tilde{t} = t - \frac{\pi}{4}$$

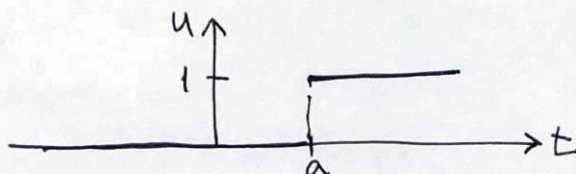
$$y = 2t - \sin t + \cos t$$

PS 5.2

1, 5, 9, 15, 19

5.3. Unit step function, ~~Dirac's Delta function~~

* unit step function $u(t-a)$



$$u(t-a) = \begin{cases} 0 & \text{if } t < a & \text{(off)} \\ 1 & \text{if } t > a & \text{(on)} \end{cases} \quad a \geq 0$$

Heaviside fn Fig 112/113.

Theorem 1. Second shifting theorem

$$\begin{aligned} \mathcal{L}\{f(t-a)u(t-a)\} &= e^{-as} \bar{f}(s) \\ &= e^{-as} \mathcal{L}\{f(t)\} \end{aligned}$$

$$f(t-a)u(t-a) = \mathcal{L}^{-1}\{e^{-as} \bar{f}(s)\}$$

pf.
$$\begin{aligned} e^{-as} \bar{f}(s) &= e^{-as} \int_0^{\infty} e^{-s\tau} f(\tau) d\tau \\ &= \int_0^{\infty} e^{-s(\tau+a)} f(\tau) d\tau \end{aligned}$$

$$\tau + a = t$$

$$\begin{aligned} e^{-as} \bar{f}(s) &= \int_a^{\infty} e^{-st} f(t-a) dt + \int_0^a 0 dt \\ &= \int_0^{\infty} e^{-st} f(t-a) u(t-a) dt \\ &= \mathcal{L}\{f(t-a)u(t-a)\} \end{aligned}$$

L.T. of unit step fn

$$\mathcal{L}\{u(t-a)\} = \frac{e^{-as}}{s} \quad (s > 0)$$

$$\mathcal{L}\{f\} = \int_0^{\infty} e^{-st} f(t) dt$$

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}$$

$$\mathcal{L}\{\cos \omega t\} = \frac{s}{s^2 + \omega^2} \quad \dots$$

shifting theorems

$$\left[\begin{array}{l} \mathcal{L}\{e^{at} f(t)\} = F(s-a) \\ \mathcal{L}\{f(t-a) u(t-a)\} = e^{-as} F(s) \end{array} \right.$$

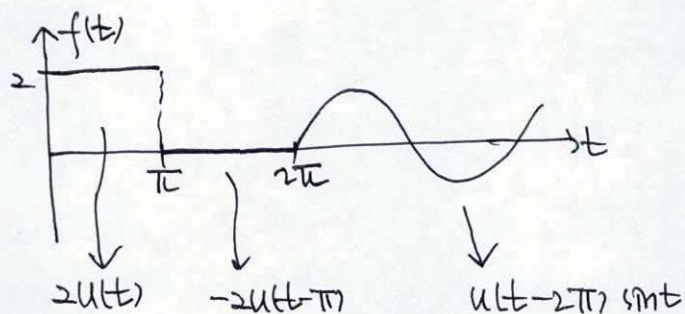
$$\mathcal{L}\{y'\} = sY - y(0)$$

$$\mathcal{L}\left\{\int_0^t f(\tau) d\tau\right\} = \frac{1}{s} F(s)$$

Ex. 1.*

$$f(t) = \begin{cases} 2 & 0 < t < \pi \\ 0 & \pi < t < 2\pi \\ \sin t & t > 2\pi \end{cases}$$

$$\mathcal{L}(f) = ?$$



$$f(t) = 2u(t) - 2u(t-\pi) + u(t-2\pi) \sin(t-2\pi)$$

$$\mathcal{L}(f) = \frac{2}{s} - 2 \frac{e^{-\pi s}}{s} + \frac{e^{-2\pi s}}{s^2+1}$$

Ex. 2.*

$$F(s) = \frac{2}{s^2} - \frac{2e^{-2s}}{s^2} - \frac{4e^{-2s}}{s} + \frac{se^{-\pi s}}{s^2+1}$$

$$f(t) = ?$$

$$f(t) = 2t - 2(t-2)u(t-2) - 4u(t-2) + \cos(t-\pi)u(t-\pi)$$

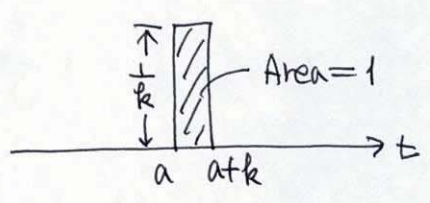
$$= 2t - 2tu(t-2) - \cos t u(t-\pi)$$

$$= \begin{cases} 2t & (0 < t < 2) \\ 0 & (2 < t < \pi) \\ -\cos t & (t > \pi) \end{cases}$$

Ex. 3. practice

6.4
* Short impulses, Dirac's delta fn

$$f_k(t-a) = \begin{cases} \frac{1}{k} & a \leq t \leq a+k \\ 0 & \text{otherwise} \end{cases}$$



Impulse $f_k = \int_0^{\infty} f_k(t-a) dt = \int_a^{a+k} \frac{1}{k} dt = 1$

$f_k(t-a) = \frac{1}{k} [u(t-a) - u(t-(a+k))]$

$\mathcal{L}\{f_k(t-a)\} = \frac{1}{ks} [e^{-as} - e^{-(a+k)s}] = e^{-as} \cdot \frac{1 - e^{-ks}}{ks}$

Dirac delta function (unit impulse fn)

$$\delta(t-a) = \lim_{k \rightarrow 0} f_k(t-a)$$

$$\mathcal{L}\{\delta(t-a)\} = e^{-as}$$

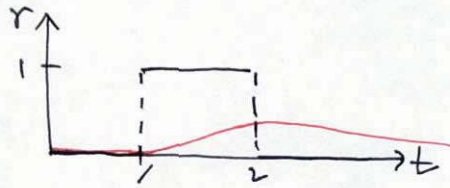
$$\delta(t-a) = \begin{cases} \infty & \text{if } t=a \\ 0 & \text{otherwise} \end{cases}$$

$$\int_0^{\infty} \delta(t-a) dt = 1.$$

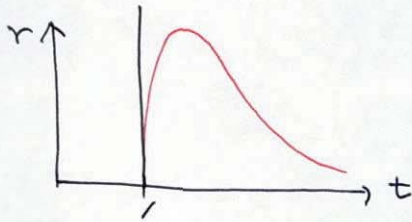
Ex. # 162 spring-mass-damper system.

$$y'' + 3y' + 2y = r(t), \quad y(0) = 0, \quad y'(0) = 0.$$

1. (A) $r(t) = u(t-1) - u(t-2)$



2. (B) $r(t) = \delta(t-1)$



Sol. (A) $s^2 Y + 3sY + 2Y = \frac{e^{-s}}{s} - \frac{e^{-2s}}{s}$

$$Y = \frac{1}{s(s+1)(s+2)} (e^{-s} - e^{-2s})$$

$$= \underbrace{\left(\frac{1/2}{s} - \frac{1}{s+1} + \frac{1/2}{s+2} \right)}_{\text{" } \bar{H}(s) \text{ "}} (e^{-s} - e^{-2s})$$

$$f(t) = \mathcal{L}^{-1}(\bar{H}) = \frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t}$$

$$y = \mathcal{L}^{-1} \{ \bar{H}(s)e^{-s} - \bar{H}(s)e^{-2s} \}$$

$$= f(t-1)u(t-1) - f(t-2)u(t-2)$$

$$= \begin{cases} 0 & (0 < t < 1) \\ \frac{1}{2} - e^{-(t-1)} + \frac{1}{2}e^{-2(t-1)} & (1 < t < 2) \\ -e^{-(t-1)} + \frac{1}{2}e^{-2(t-1)} + e^{-(t-2)} - \frac{1}{2}e^{-2(t-2)} & (t > 2) \end{cases}$$

Sol. (B)

$$s^2 Y + 3sY + 2Y = e^{-s}$$

$$Y = \frac{1}{(s+1)(s+2)} e^{-s}$$

$$= \underbrace{\left(\frac{1}{s+1} - \frac{1}{s+2} \right)}_{\hat{=}\hat{F}(s)} e^{-s}$$

$$f(t) = \mathcal{L}^{-1}(\hat{F}) = e^{-t} - e^{-2t}$$

$$y = \mathcal{L}^{-1} \{ \hat{F}(s) \cdot e^{-s} \}$$

$$= f(t-1) u(t-1) = \begin{cases} 0 & 0 \leq t < 1 \\ e^{-(t-1)} - e^{-2(t-1)} & t > 1 \end{cases}$$

ps 5.3 # 5, 7, 11, 19, 23, 29 → p.160

5.4 Differentiation and Integration of Transforms
p.160 → 6.6

$$\hat{F}(s) = \mathcal{L}\{f\} = \int_0^{\infty} e^{-st} f(t) dt$$

$$\hat{F}'(s) = - \int_0^{\infty} e^{-st} [t f(t)] dt$$

$$\therefore \mathcal{L}\{t f(t)\} = -\hat{F}'(s) = -\frac{d}{ds} \mathcal{L}\{f\}$$

$$\hat{F}'(s) = \mathcal{L}\{-t f\}$$

$$\mathcal{L}^{-1}\{\hat{F}'(s)\} = -t f(t)$$

Ex. 1. $\mathcal{L}\{t \sin \beta t\} = -\frac{d}{ds} \mathcal{L}\{\sin \beta t\} = -\frac{d}{ds} \cdot \left(\frac{\beta}{s^2 + \beta^2} \right)$
 $= \frac{\beta \cdot 2s}{(s^2 + \beta^2)^2} = \frac{2\beta s}{(s^2 + \beta^2)^2}$