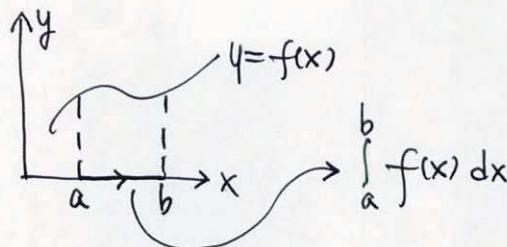


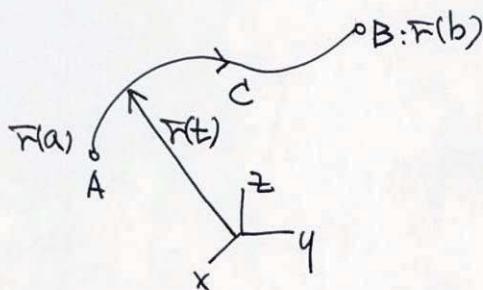
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Chap. 9 Vector Integral Calculus

Q. 1. Line Integrals

simple example



In general



Line integral of a vector function  $\bar{F}(\bar{r})$  over  $C$

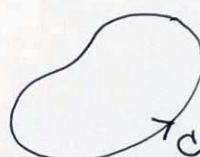
$$\int_C \bar{F}(\bar{r}) \cdot d\bar{r} = \int_a^b \bar{F}(r(t)) \cdot \frac{d\bar{r}}{dt} dt$$

noting that  $\bar{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$   
 $d\bar{r} = dx \hat{i} + dy \hat{j} + dz \hat{k}$

$$\begin{aligned} \int_C \bar{F}(\bar{r}) \cdot d\bar{r} &= \int_C (F_1 dx + F_2 dy + F_3 dz) \\ &= \int_a^b (F_1 x' + F_2 y' + F_3 z') dt \end{aligned}$$

$$x' = \frac{dx}{dt}$$

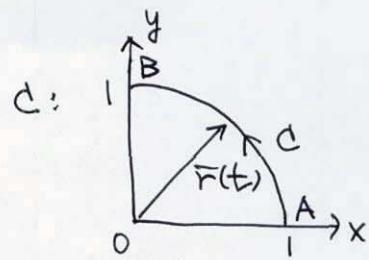
If  $C$  is closed:



$$\int_C = \oint_C$$

Ex. 1.  $\bar{F}(r) = -y\hat{i} - xy\hat{j}$

$$\int_C \bar{F} \cdot d\bar{r} = ?$$



$$\begin{aligned}\bar{r}(t) &= \cos t \hat{i} + \sin t \hat{j} & t: 0 \rightarrow \frac{\pi}{2} \\ &= x \hat{i} + y \hat{j}\end{aligned}$$

$$\bar{F}(r) = -\sin t \hat{i} - \sin t \cos t \hat{j}$$

$$\int_C \bar{F} \cdot d\bar{r} = \int_0^{\frac{\pi}{2}} \bar{F} \cdot \frac{d\bar{r}}{dt} dt$$

$$= \int_0^{\frac{\pi}{2}} (-\sin t \hat{i} - \sin t \cos t \hat{j}) \cdot (-\sin t \hat{i} + \cos t \hat{j}) dt$$

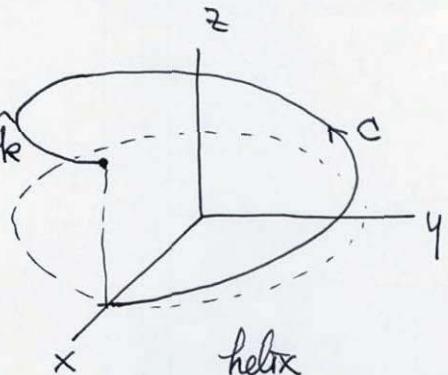
$$= \int_0^{\frac{\pi}{2}} (\sin^2 t - \sin t \cos^2 t) dt = \frac{\pi}{4} - \frac{1}{3}$$

Ex 2.  $\bar{F}(r) = z\hat{i} + x\hat{j} + y\hat{k}$

$$C: \bar{r}(t) = \cos t \hat{i} + \sin t \hat{j} + 3t \hat{k}$$

$$t: 0 \rightarrow 2\pi$$

$$\bar{r} = x\hat{i} + y\hat{j} + z\hat{k}$$



$$\int_C \bar{F} \cdot d\bar{r} = \int_0^{2\pi} \bar{F} \cdot \frac{d\bar{r}}{dt} dt$$

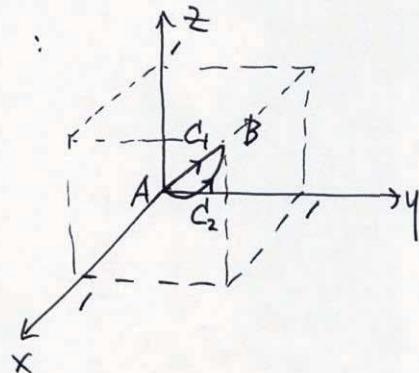
$$= \int_0^{2\pi} (3t\hat{i} + \cos t \hat{j} + \sin t \hat{k}) \cdot (-\sin t \hat{i} + \cos t \hat{j} + 3\hat{k}) dt$$

$$= 7\pi$$

~~Ex.3.~~ Dependence of a line integral on path

$$\bar{F}(F) = t\hat{i} + xy\hat{j} + x^2z\hat{k}$$

path :



$$C_1: \bar{r}_1(t) = [t, t, t] \quad 0 \leq t \leq 1$$

$$C_2: \bar{r}_2(t) = [t, t, t^2] \quad 0 \leq t \leq 1$$

$$\begin{aligned} \text{path 1: } \int_{C_1} \bar{F} \cdot d\bar{r} &= \int_0^1 (t\hat{i} + t^2\hat{j} + t^3\hat{k}) \cdot (\hat{i} + \hat{j} + \hat{k}) dt \\ &= \int_0^1 (t + t^2 + t^3) dt = \frac{37}{12} \end{aligned}$$

$$\begin{aligned} \text{path 2: } \int_{C_2} \bar{F} \cdot d\bar{r} &= \int_0^1 (t\hat{i} + t^2\hat{j} + t^3\hat{k}) \cdot (\hat{i} + \hat{j} + 2t\hat{k}) dt \\ &= \int_0^1 (t + t^2 + 2t^3) dt = \frac{28}{12} \end{aligned}$$

In general, line integral is path-dependent.

\* If  $\bar{F}(F)$ : force,  $d$ : displacement curve  $\rightarrow$

$$\text{Work} = \int_C \bar{F} \cdot d\bar{r}$$

~~Ex.5.~~ Work vs. kinetic energy

$$W = \int_C \bar{F} \cdot d\bar{r} = \int_a^b \bar{F} \cdot \frac{d\bar{r}}{dt} dt = \int_a^b \bar{F} \cdot \bar{v} dt$$

$$\text{2nd law: } \bar{F} = m\bar{r}''(t) = m\bar{v}'(t)$$

$$W = \int_a^b m\bar{v} \cdot \bar{v} dt = \int_a^b \frac{m}{2}(\|\bar{v}\|^2)' dt = \left. \frac{m}{2} \|\bar{v}\|^2 \right|_{t=a}^{t=b} = \Delta KE$$

\* Other forms of line integral

$$\int_C f(\bar{r}) dt = \int_a^b f(F(t)) dt$$

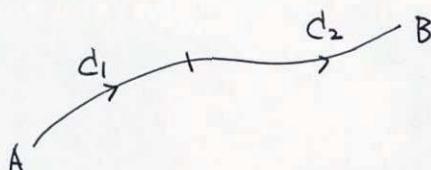
Ex. 6.  $f = (x^2 + y^2 + z^2)^{-\frac{1}{2}}$

$$\begin{aligned} d: \quad \bar{r}(t) &= \cos t \hat{i} + \sin t \hat{j} + 3t \hat{k} \\ &= x \hat{i} + y \hat{j} + z \hat{k} \end{aligned}$$

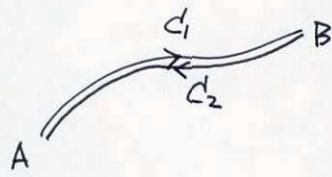
$$f = [\cos^2 t + \sin^2 t + (3t)^2]^{-\frac{1}{2}} = (1+9t^2)^{-\frac{1}{2}}$$

$$\int_C f(\bar{r}) dt = \int_0^{2\pi} (1+9t^2)^{-\frac{1}{2}} dt \approx 160.135.$$

\* General properties of line integral



$$\int_C \bar{F} \cdot d\bar{r} = \int_{C_1} \bar{F} \cdot d\bar{r} + \int_{C_2} \bar{F} \cdot d\bar{r}$$



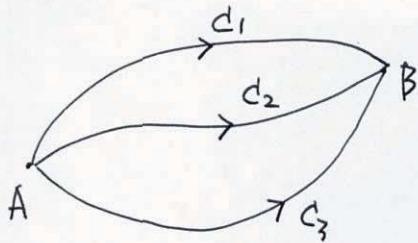
$$\int_{C_1} \bar{F} \cdot d\bar{r} = - \int_{C_2} \bar{F} \cdot d\bar{r}$$

PS 9.1 # 1, 7, 13, 19

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9.2

# Path independence of line integrals

## Line integrals independent of path



$$\int_{c_1} \bar{F} \cdot d\bar{r} = \int_{c_2} \bar{F} \cdot d\bar{r} = \dots \quad : \text{path-independent}$$

Theorem 1.  $\int_c \bar{F} \cdot d\bar{r}$  : path-independent

iff  $\bar{F} = \nabla f$  (f: potential)

OR  $F_1 = \frac{\partial f}{\partial x}, F_2 = \frac{\partial f}{\partial y}, F_3 = \frac{\partial f}{\partial z}$

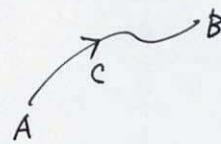
Proof.  $\bar{F} = \nabla f \rightarrow \int_c \bar{F} \cdot d\bar{r}$  : path-indep.

$$\begin{aligned}
 \int_c \bar{F} \cdot d\bar{r} &= \int_A^B (F_1 dx + F_2 dy + F_3 dz) \\
 &= \int_A^B \left( \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right) \\
 &= \int_a^b \left( \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} \right) dt \\
 &= \int_a^b \frac{df}{dt} dt = \left[ f(x(t), y(t), z(t)) \right]_{t=a}^{t=b} \\
 &= f(B) - f(A)
 \end{aligned}$$

: only depends on endpoints

$\therefore$  If a line integral is path-independent,

$$\boxed{\int_C \bar{F} \cdot d\bar{r} = \int_C \nabla f \cdot d\bar{r} = f(B) - f(A)}$$



Ex. 1.  $\int_C \bar{F} \cdot d\bar{r} = \int_C (2x dx + 2y dy + 4z dz)$  : path-indep.

$$\because \bar{F} = \nabla f$$

$$\frac{\partial f}{\partial x} = 2x, \quad \frac{\partial f}{\partial y} = 2y, \quad \frac{\partial f}{\partial z} = 4z$$

$$f = x^2 + y^2 + z^2.$$

$$d: A(0,0,0) \rightarrow B(2,2,2)$$

$$r(t) = t\hat{i} + t\hat{j} + t\hat{k}. \quad t: 0 \rightarrow 2$$

$$I = \int_0^2 (2t + 2t + 4t) dt = \int_0^2 8t dt = [4t^2]_0^2 = 16$$

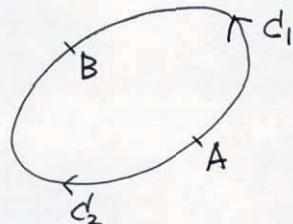
$$\text{OR } I = f(2,2,2) - f(0,0,0) = 16$$

Theorem 2.

$$\int_C \bar{F} \cdot d\bar{r} : \text{path-independent}$$

$$\text{iff } \oint \bar{F} \cdot d\bar{r} = 0.$$

Proof.



If  $\int_C \bar{F} \cdot d\bar{r}$  is path-indep.

$$\int_{C_1} \bar{F} \cdot d\bar{r} = \int_{C_2} \bar{F} \cdot d\bar{r}.$$

$$\oint \bar{F} \cdot d\bar{r} = \int_{C_1} \bar{F} \cdot d\bar{r} - \int_{C_2} \bar{F} \cdot d\bar{r} = 0.$$

\* Exactness and independence of path

$$\begin{aligned} \int_C \bar{F} \cdot d\bar{r} &= \int_C (\underbrace{F_1 dx + F_2 dy + F_3 dz}_{\text{exact}}) \\ \text{if } \bar{F} = \nabla f &\quad \leftarrow \text{exact} = df \quad \sim \text{path-independent.} \\ &= \int_C \left( \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \right) \\ &= \int_C df \end{aligned}$$

Theorem 3  $\int_C \bar{F} \cdot d\bar{r}$ : path-independent  $\Leftrightarrow \operatorname{curl} \bar{F} = 0$   
 $\bar{F} \cdot d\bar{r}$ : exact

Proof.  $\bar{F} = \nabla f$ .

$$\nabla \times (\nabla f) = 0.$$

$$\begin{cases} \frac{\partial F_3}{\partial y} = \frac{\partial F_1}{\partial z} \\ \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x} \\ \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y} \end{cases}$$

Ex 3.

$$I = \int_C [x^2 y z^2 dx + (x^2 z^2 + z \cos y z) dy + (2x^2 y z + y \sin y z) dz]$$

$$A(0, 0, 1) \rightarrow B(1, \frac{\pi}{2}, z)$$

$$\text{exact? } (F_3)_y = (F_2)_z \dots$$

$$I = \int df. \quad f = \int F_2 dy = x^2 z^2 y + \sin y z + g(x, z)$$

$$\frac{\partial f}{\partial x} = F_1 = 2x^2 z^2 y + \frac{\partial g}{\partial x} = 2x^2 y z^2$$

$$\therefore \frac{\partial g}{\partial x} = 0. \quad g = g(z)$$

$$\frac{\partial f}{\partial z} = F_3 \Rightarrow \frac{\partial g}{\partial z} = 0.$$

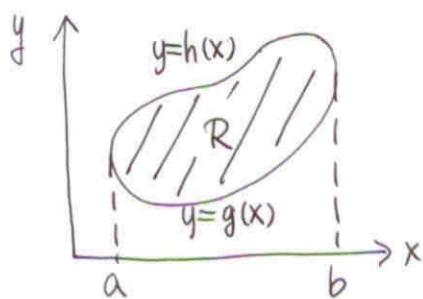
$$f(x, y, z) = x^2 y z^2 + \sin y z$$

$$I = f(B) - f(A) = \pi + 1$$

§ 9.2. # 9, 11

$$\iint_R f(x,y) dx dy = \int_c^d \left[ \int_{p(y)}^{q(y)} f(x,y) dx \right] dy$$

### 9.3. Double Integrals Optional



$$\begin{aligned} \iint_R f(x,y) dx dy &= \int_a^b \left[ \int_{g(x)}^{h(x)} f(x,y) dy \right] dx \end{aligned}$$

\* change of variables in double integrals

$$\int_a^b f(x) dx \stackrel{x \rightarrow u}{=} \int_{\alpha}^{\beta} f(x(u)) \frac{dx}{du} du$$

$$\iint_R f(x,y) dx dy \stackrel{(x,y) \rightarrow (u,v)}{=} \iint_{R^*} f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

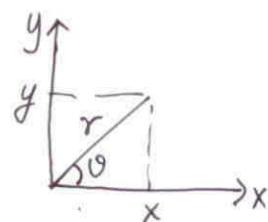
Jacobian  $J = \frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$

e.g. cartesian coordinates  $\rightarrow$  polar coordinates

$(x, y)$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$(r, \theta)$



$$J = \frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$$

$$\iint_R f(x,y) dx dy = \iint_{R^*} f(r \cos \theta, r \sin \theta) r dr d\theta$$