# Non-manifold modeling system

Human-centered CAD Lab.

# Manifold model

#### Every point on a surface

- Two dimensional
  every point has a neighborhood which is homeomorphic to a two dimensional disk
- Design is carried out in abstract shape in conceptual design stage ⇒ non-manifold model
- Dimension reduction(mixed dimension) is often used in analysis
  - ⇒ non-manifold model

## Manifold model – cont'

#### Design process

 Incomplete lower level description -> true solid
 whole design process can be supported by nonmanifold modeler

- Non-manifold modeler
- Wire-frame, surface, solid, cellular model, and their mixture can be handled

#### Manifold model – cont'



## Manifold model – cont'

#### Issues to develop a non-manifold modeler

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- Data structure
- Euler operator
- Modeling commands

#### Data structure

- Masuda's structure
  - Model is a collection of solid with volume+ laminar face + dangling edge etc.

 $\Rightarrow$  entity called complex stores these as a list

⇒ compact, easy to understand





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- Does not provide adjacency information between topological entities
- Insufficient information on adjacency between faces
  - Difficult to determine whether a shell S1 should be split into two or a laminar face should be added when a new face is added
  - Can be determined by geometric calculations but inefficient

- Weiler's radial edge data structure for adjacency, store cyclic ordering
- In manifold model, 2 cycles are enough
  - face-edge cycle : list of edges for each loop (face)
  - vertex-edge cycle : list of connected edges at a vertex

- In non-manifold model, 3 cycles are necessary
  - loop cycle : face-edge cycle
  - radial cycle : cycle of faces connected to a certain edge (in manifold models, there are two faces all the time)
  - Disk cycle :
  - -> similar to vertex-edge cycle
  - -> one vertex may have many disk cycles



- Weiler's radial edge representation
  - Stores radial cycle and loop cycle, not disk cycle
    models in the previous slide are represented by the same data
- Can be differentiated by geometric calculations, but inefficient
- In Gursoz and choi's Vertex Based Representation, disk cycle is stored explicitly

## Radial edge data structure

Model, region, shell, face, loop, edge, vertex

- Model = complex (group of regions) ,
- Region = volume (bounded by one or several shells)
- Single solid has two regions : Inside, outside
- Shell = boundary of region



- Model :
  - Equivalent to complex, simply means the group of all the regions involved
- Region :
  - Equivalent to the volume and bounded by one or several shells
  - Single solid has two regions, one for the inside and the other for outside
- Shell :
  - Oriented boundary surface of a region

- Additional topological entities
  - face-use, loop-use, edge-use, vertex-use
  - Similar to representing the connectivity between loops, vertices, and edges through half-edges indirectly
- face-use: inside and outside of a face, use of a face by a shell
- Ioop-use: boundary of face-use, same direction as face-use
- edge-use: boundary of loop-use
- vertex-use: boundary of edge-use

- shell <-> edge-use
  - wire-frame model
- shell <-> vertex-use
  - shell consists of a single vertex
- Ioop-use <-> vertex-use
  - isolated point on a face as its hole loop

#### Edge-use

Radial pointer points to the edge-use on the face-use radially adjacent to the face-use of the given edge-use

⇒ radial ordering of faces about an edge can be derived by tracing the pointers

#### vertex-uses

- Stores vertex-edge cycle
- By storing all the vertex-use for a vertex, all the edge-use connected to the vertex can be derived
- b disk cycle is not stored explicitly





Operators to manipulate topology

 Generalized Euler-Poincare formula for non-manifold models

$$v - e + (f-r) - (V-Vh+Vc) = C-Ch + Cc$$

 $\Box$  r = rings or holes in faces

- $\square$  V = number of closed volumes
- $\Box$  Vh = passages through the volumes
- $\Box$  Vc = voids in the volumes
- $\Box$  C = number of complexes, or disjoint objects
- $\Box$  Ch = passages through objects

 $\Box$  Cc = cavities and voids in the objects

 Each complex can be composed of several volume and dangling edge



For manifold case,

V = C, Vh = Ch, Vc = Cc  
V − e + (f-r) − (V-Vh+Vc) = V −Vh + Vc  
$$\therefore$$
 v − e + (f-r) = 2(V-Vh+Vc)

number of shells equals V + Vc

$$\therefore$$
 v - e + (f-r) = 2(s-Vh) (r = h, Vh = p)

Nine independent base vectors

⇒ nine operators

mvC (kvC): make(kill) vertex, complex

mev (kev): make(kill) edge, vertex



meCh (keCh): make(kill) edge, complex\_hole



mfkCh (kfmCh): make(kill) face, kill(make) complex\_hole



mfCc (kfCc): make (kill) face, complex\_cavity



mvr (kvr): make (kill) vertex, ring



mVkCc (kVmCc): make (kill) Volume, kill (make) complex\_cavity



mvVc (kvVc): make (kill) vertex, Volume\_cavity



meVh (keVh): make (kill) edge, Volume\_hole



