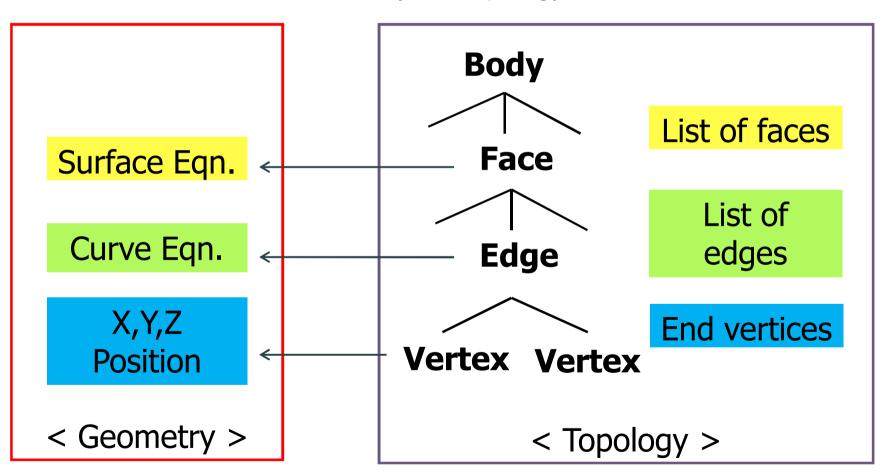
Representation and manipulation of curves

Human Centered CAD Lab.

1 2009-05-14

B-Rep Structure – review

Geometry vs. Topology



Types of curve equations

Parametric equation

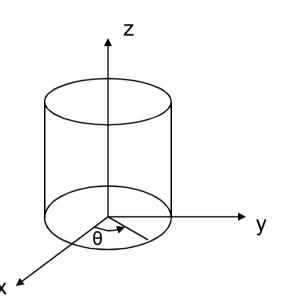
- \rightarrow x=x(t), y=y(t), z=z(t)
- \rightarrow Ex) x=Rcos θ , y=Rsin θ , z=0 (0 $\leq \theta \leq 2\pi$)

Implicit nonparametric

- $x^2 + y^2 R^2 = 0, \quad z = 0$
- F(x, y, z)=0, G(x, y, z)=0
- Intersection of two surfaces
- Ambiguous independent parameters

Explicit nonparametric

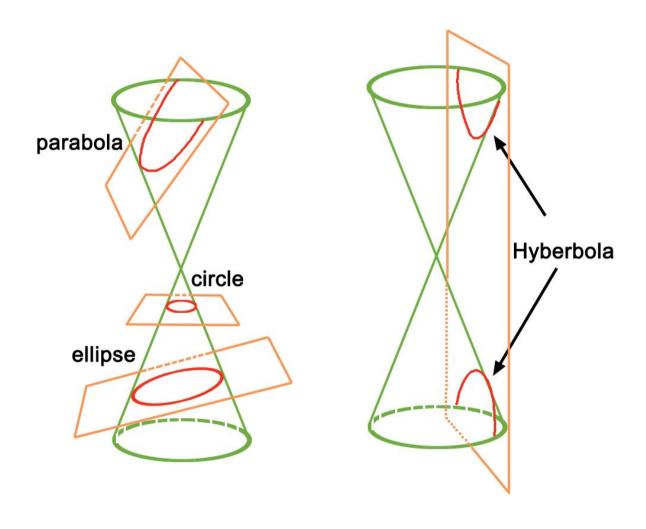
- $y = \pm \sqrt{R^2 x^2}, \quad z = 0$
- Should choose proper neighboring point during curve generation



Conic curves

- Curves obtained by intersecting a cone with a plane
- Circle (circular arc), ellipse, hyperbola, parabola
 - Ex) Circle (circular arc)
 - Circle in xy-plane with center (x_c, y_c) and radius R
 - $x = R\cos\theta + x_c$
 - $y = Rsin\theta + y_c$
 - z = 0
- Points on the circle are generated by incrementing θ by $\triangle \theta$ from 0, points are connected by line segments
- Equation of a circle lying on an arbitrary plane can be derived by transformation

Conic curves – cont'



Hermite curves

- Parametric eq. is preferred in CAD systems
 - Polynomial form of degree 3 is preferred :
 - C2 continuity is guaranteed when two curves are connected

$$\therefore \mathbf{P}(u) = [x(u) \ v(u) \ z(u)] = \mathbf{a}_0 + \mathbf{a}_1 \ u + \mathbf{a}_2 \ u^2 + \mathbf{a}_3 \ u^3 \qquad (1)$$

$$(0 \le u \le 1) : \text{algebraic eq.}$$

- Impossible to predict the shape change from change in coefficients ⇒ not intuitive
 - Bad for interactive manipulation

 Apply Boundary conditions to replace algebraic coefficients

Use
$$\mathbf{P}_{(0)}$$
, $\mathbf{P}_{(1)}$, $\mathbf{P}_{(0)}'$, $\mathbf{P}_{(1)}'$ \Rightarrow Substitute in Eq(1) $\mathbf{P}_{(0)}$, $\mathbf{P}_{(1)}$, $\mathbf{P}_{(1)}'$

$$\mathbf{P}_{(0)} = \mathbf{P}_{0} = \mathbf{a}_{0}
\mathbf{P}_{(1)} = \mathbf{P}_{1} = \mathbf{a}_{0} + \mathbf{a}_{1} + \mathbf{a}_{2} + \mathbf{a}_{3}
\mathbf{P}'_{(0)} = \mathbf{P}'_{0} = \mathbf{a}_{1}
\mathbf{P}'_{(1)} = \mathbf{P}'_{1} = \mathbf{a}_{1} + 2\mathbf{a}_{2} + 3\mathbf{a}_{3}$$
(2)

▶ Solve for \mathbf{a}_0 , \mathbf{a}_1 , \mathbf{a}_2 , \mathbf{a}_3 in Eq (2)

$$\mathbf{a}_0 = \mathbf{P}_0$$

$$\mathbf{a}_1 = \mathbf{P}_0'$$

$$\mathbf{a}_2 = -3\mathbf{P}_0 + 3\mathbf{P}_1 - 2\mathbf{P}_0' - \mathbf{P}_1'$$

$$\mathbf{a}_3 = 2\mathbf{P}_0 - 2\mathbf{P}_1 + \mathbf{P}_0' - \mathbf{P}_1'$$

Substitute (3) into (1)

$$\mathbf{P}(\mathbf{u}) = \begin{bmatrix} 1 - 3\mathbf{u}^2 + 2\mathbf{u}^3 & 3\mathbf{u}^2 - 2\mathbf{u}^3 & \mathbf{u} - 2\mathbf{u}^2 + \mathbf{u}^3 \end{bmatrix} \mathbf{P}_{\mathbf{u}}^{\prime}$$

$$\mathbf{P}_{\mathbf{u}}^{\prime}$$

$$\mathbf{P}_{\mathbf{u}}^{\prime}$$

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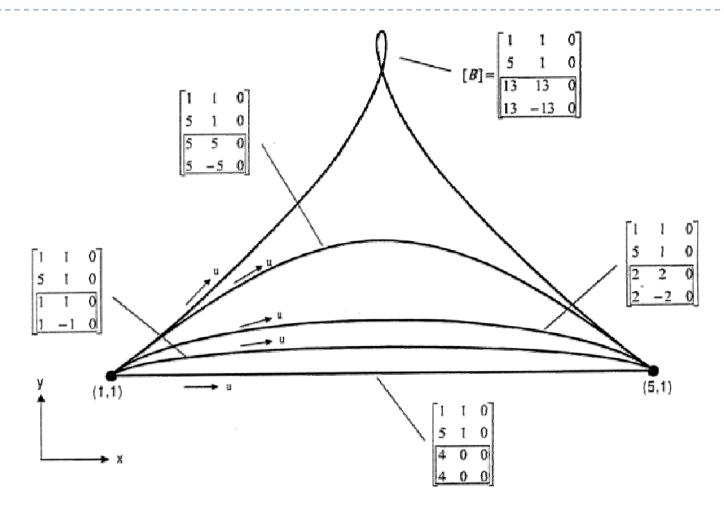
$$\mathbf{P}_{\mathbf{u}}^{\prime}$$

$$\mathbf{P}_{\mathbf{u}}^{\prime}$$

$$\mathbf{P}_{\mathbf{u}}^{\prime}$$

Hermite curve equation

It is possible to predict the curve shape change from the change in P₀, P₁, P₀′, P₁′ to some extent



Effect of P₀' and P₁' on curve shape

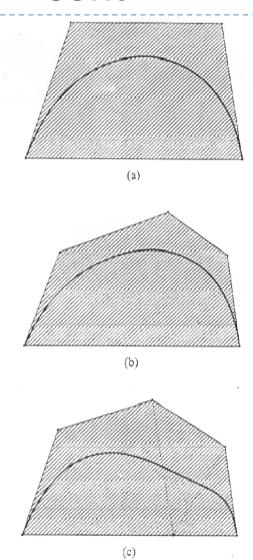
 $1-3u^2+2u^3$, $3u^2-2u^3$, $u-2u^2+u^3$, $-u^2+u^3$

determine the curve shape by blending the effects of P_0 , P_1 , P_0' , $P_1' \rightarrow$ blending function

Bezier curves

- It is difficult to realize a curve in one's mind by changing size and direction of P₀', P₁' in Hermite curves
- Bezier curves
 - Invented by Bezier at Renault
 - Use polygon that enclose a curve approximately
 - Control polygon, control point

- Passes through 1st and last vertex of control polygon
- Tangent vector at the starting point is in the direction of 1st segment of control polygon
- Tangent vector at the ending point is in the direction of the last segment
 - Useful feature for smooth connection of two Bezier curves
- The n-th derivative at starting or ending point is determined by the first or last (n+1) vertices of control polygon
- Bezier curve resides completely inside its convex hull
 - Useful property for efficient calculation of intersection points



$$\mathbf{P}(\mathbf{u}) = \sum_{i=0}^{n} \binom{n}{i} \mathbf{u}^{i} (1 - \mathbf{u})^{n-i} \mathbf{P}_{i} \qquad (0 \le \mathbf{u} \le 1)$$

$$\uparrow \quad \text{Control Point}$$

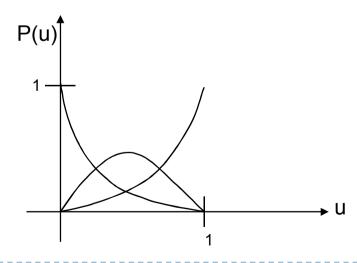
$$\mathbf{P}(u) = (1 - u)\mathbf{P}_{0} + u\mathbf{P}_{1}$$

: Straight line from P0 to P1 satisfies the desired qualities including convex hull property

$$\mathbf{P}(u) = (1-u)^{2} \mathbf{P}_{0} + 2(1-u)u\mathbf{P}_{1} + u^{2}\mathbf{P}_{2}$$

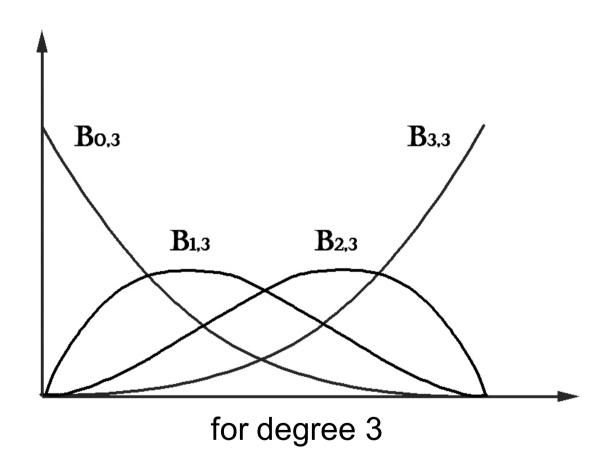
$$\Rightarrow (1-u)^{2} + 2(1-u)u + u^{2} = 1$$

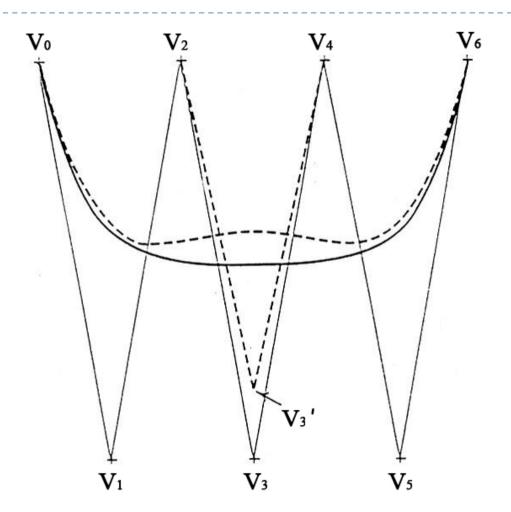
satisfies the desired qualities



- \mathbf{I} Highest term is \mathbf{u}^n for the curve defined by (n+1) control points
 - Polynomial of degree n
- Degree of curve is determined by number of control points
- Large number of control points are needed to represent a curve of complex shape → high degree is necessary.
 - Heavy computation, oscillation
 - Better to connect multiple Bezier curves
- Global modification property (not local modification)
 - Difficult to result a curve of desired shape by modifying portions

Blending functions in Bezier curve





Bezier Curve does NOT have local modification property

Derivative vectors

$$\frac{d\mathbf{r}(t)}{dt} = n \sum_{i=0}^{n-1} {n-1 \choose i} t^{i} (1-t)^{n-1-i} \mathbf{a}_{i}$$
where
$$\mathbf{a}_{i} = \mathbf{P}_{i+1} - \mathbf{P}_{i} \qquad i = 0, 1, \dots, n-1$$

$$\frac{d\mathbf{r}(t)}{dt} = \sum_{i=0}^{n} i \binom{n}{i} t^{i-1} (1-t)^{n-i} \mathbf{P}_{i} - \sum_{i=0}^{n} (n-i) \binom{n}{i} t^{i} (1-t)^{n-i-1} \mathbf{P}_{i}
= \sum_{i=1}^{n} i \binom{n}{i} t^{i-1} (1-t)^{n-i} \mathbf{P}_{i} - \sum_{i=0}^{n-1} (n-i) \binom{n}{i} t^{i} (1-t)^{n-i-1} \mathbf{P}_{i}
let j = i-1
$$\frac{d\mathbf{r}(t)}{dt} = \sum_{j=0}^{n-1} (j+1) \binom{n}{j+1} t^{j} (1-t)^{n-j-1} \mathbf{P}_{j+1} - \sum_{i=0}^{n-1} (n-i) \binom{n}{i} t^{i} (1-t)^{n-1-i} \mathbf{P}_{i}$$$$

Derivative vectors – cont'

$$(j+1) \binom{n}{j+1} = \frac{(j+1)n!}{(j+1)!(n-j-1)!} = \frac{n(n-1)!}{j!(n-j-1)!} = n \binom{n-1}{j}$$

$$(n-i) \binom{n}{i} = \frac{(n-i)n!}{i!(n-i)!} = \frac{n(n-1)!}{i!(n-i-1)!} = n \binom{n-1}{i}$$

$$\therefore \frac{d\mathbf{r}(t)}{dt} = n \sum_{i=0}^{n-1} \binom{n-1}{i} t^{i} (1-t)^{n-i-1} \mathbf{a}_{i}$$

$$(a)$$

Derivatives at the starting and the ending points

$$\dot{\mathbf{r}}(0) = n \times (\mathbf{P}_1 - \mathbf{P}_0)$$

$$\dot{\mathbf{r}}(1) = n \times (\mathbf{P}_n - \mathbf{P}_{n-1})$$

Derivative vectors – cont'

- Control polygon determines tangent vectors at the ends
- Differentiating (a) in the same way gives

$$\frac{d^{2}\mathbf{r}(t)}{dt^{2}} = n(n-1)\sum_{i=0}^{n-2} {n-2 \choose i} t^{i} (1-t)^{n-2-i} \mathbf{b}_{i}$$
where
$$\mathbf{b}_{i} = \mathbf{a}_{i+1} - \mathbf{a}_{i} \qquad (i = 0, \dots, n-2)$$

Elevation of a degree

Conversion of Bezier curve of degree n into degree (n+1), i.e. derivation of (n+1) control points into (n+2) control points

$$\mathbf{r}(t) = \sum_{i=0}^{n} \binom{n}{i} t^{i} (1-t)^{n-i} \mathbf{P}_{i} = \left\{ \mathbf{P}_{0}, \mathbf{P}_{1}, \cdots \mathbf{P}_{n} \right\}$$
Express
$$\mathbf{r}(t) = t\mathbf{r}(t) + (1-t)\mathbf{r}(t)$$

Elevation of a degree – cont'

$$t\mathbf{r}(t) = \sum_{i=0}^{n} {n \choose i} t^{i+1} (1-t)^{n-i} \mathbf{P}_{i}$$

$$let \quad i+1=k, \quad n+1=m$$

$$\therefore t\mathbf{r}(t) = \sum_{k=1}^{m} {m-1 \choose k-1} t^{k} (1-t)^{m-k} \mathbf{P}_{k-1}$$

$${m-1 \choose k-1} = \frac{(m-1)!}{(k-1)!(m-k)!} = \frac{k}{m} \frac{m!}{k!(m-k)!} = \frac{k}{m} {m \choose k}$$

$$\therefore t\mathbf{r}(t) = \sum_{k=0}^{m} {m \choose k} t^{k} (1-t)^{m-k} \frac{k}{m} \mathbf{P}_{k-1} \qquad (a)$$

Elevation of a degree – cont'

$$(1-t)\mathbf{r}(t) = \sum_{i=0}^{n} \binom{n}{i} t^{i} (1-t)^{n-i+1} \mathbf{P}_{i}$$

$$let \quad k = i, \quad m = n+1$$

$$(1-t)\mathbf{r}(t) = \sum_{k=0}^{m-1} \binom{m-1}{k} t^{k} (1-t)^{m-k} \mathbf{P}_{k}$$

$$\binom{m-1}{k} = \frac{(m-1)!}{k!(m-k-1)!} = \frac{m-k}{m} \frac{m!}{k!(m-k)!} = \frac{m-k}{m} \binom{m}{k}$$

$$\therefore (1-t)\mathbf{r}(t) = \sum_{k=0}^{m-1} \binom{m}{k} t^{k} (1-t)^{m-k} \frac{m-k}{m} \mathbf{P}_{k}$$

$$= \sum_{k=0}^{m} \binom{m}{k} t^{k} (1-t)^{m-k} \frac{m-k}{m} \mathbf{P}_{k} \qquad (b)$$

Elevation of a degree – cont'

From(a) & (b)

$$t\mathbf{r}(t) + (1-t)\mathbf{r}(t) = \sum_{k=0}^{n+1} {n+1 \choose k} t^k (1-t)^{n+1-k} \left(\frac{k\mathbf{P}_{k-1} + (n+1-k)\mathbf{P}_k}{n+1} \right)$$
 (c)

 Control points of the Bezier curve of degree (n+1) can be derived from (c) as below

$$\left\{ \mathbf{P}_{0}, \frac{\mathbf{P}_{0} + n\mathbf{P}_{1}}{n+1}, \frac{2\mathbf{P}_{1} + (n-1)\mathbf{P}_{2}}{n+1}, \cdots, \frac{n\mathbf{P}_{n-1} + \mathbf{P}_{n}}{n+1}, \mathbf{P}_{n} \right\}$$

de Casteljau algorithm

The Value of curve at t of Bezier Curve

$$\mathbf{r}(u) = \sum_{i=0}^{n} \mathbf{P}_{i} B_{n,i}(u) \text{ is } \mathbf{P}_{0}^{n} \text{ as calculated below.}$$

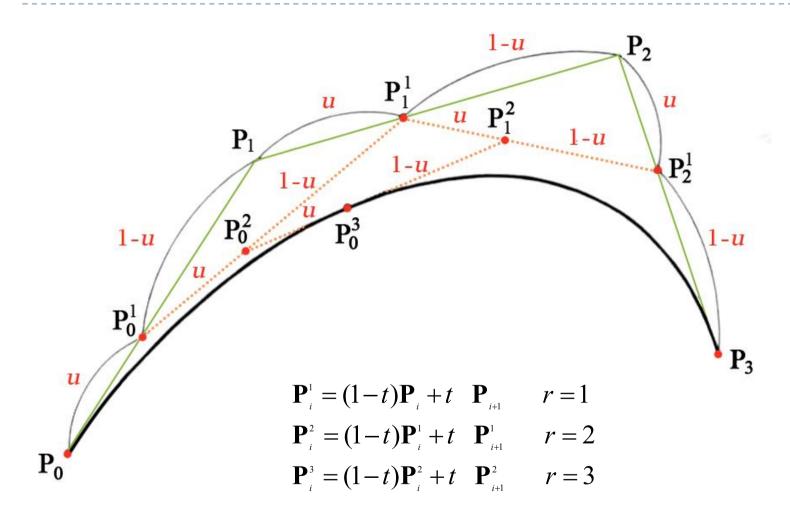
$$\mathbf{P}_{i}^{r} = (1-t) \mathbf{P}_{i}^{r-1} + t \quad \mathbf{P}_{i+1}^{r-1}$$

$$r = 1, \dots, n$$

$$i = 0, \dots, n-r$$

$$\mathbf{P}_{i}^{0} = \mathbf{P}_{i}$$
For Cubic Bezier

de Casteljau algorithm – cont'



de Casteljau algorithm – cont'

