

Chapter 2.

Laplace Transform

Nise Ch.2.1-2.3
MIT OCW Lec.3
Palm Ch.3



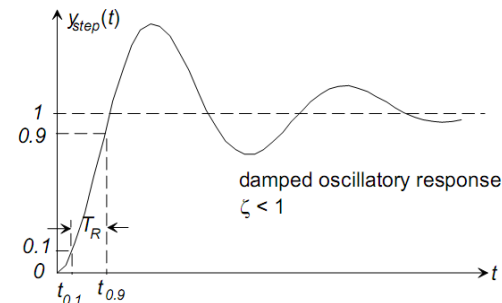
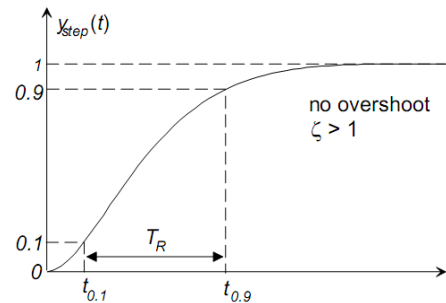
Review of the Last Lecture

System Model

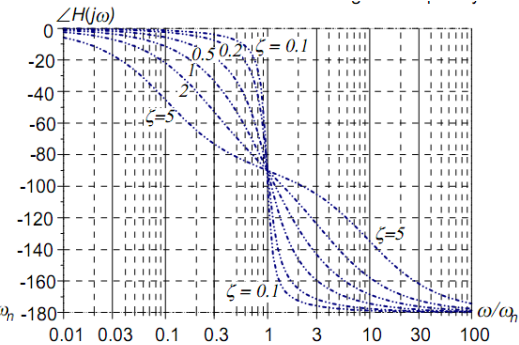
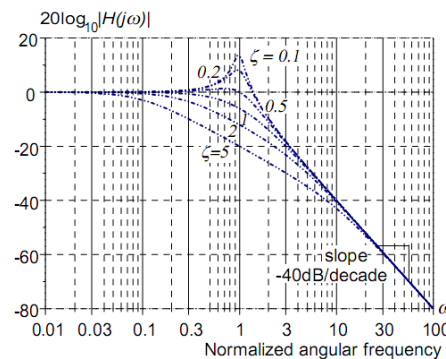
system represented in a "standard" form

$$u(t) \text{ input} \longrightarrow \frac{d^2y}{dt^2} + 2\zeta\omega_n \frac{dy}{dt} + \omega_n^2 y = u \longrightarrow y(t) \text{ output}$$

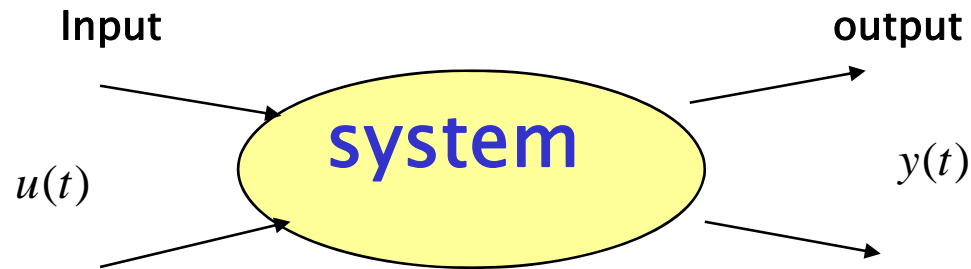
Step input response. (Transient response)



Frequency response. (Sinusoidal input response)



System, Input and Output



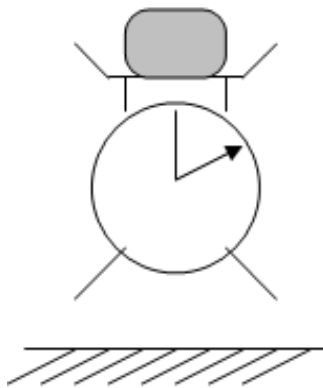
Output depends on inputs !

Depending on the system input output relationship,

- **Static System vs. Dynamic system**
- **Linear System vs. Nonlinear System**

Static System vs. Dynamic System

Ex) Balance



Static System $Weight = K \cdot x$



Dynamic System $Weight = K \cdot x$,
Settling time =

Interested in static weight
measurement

=> Static System

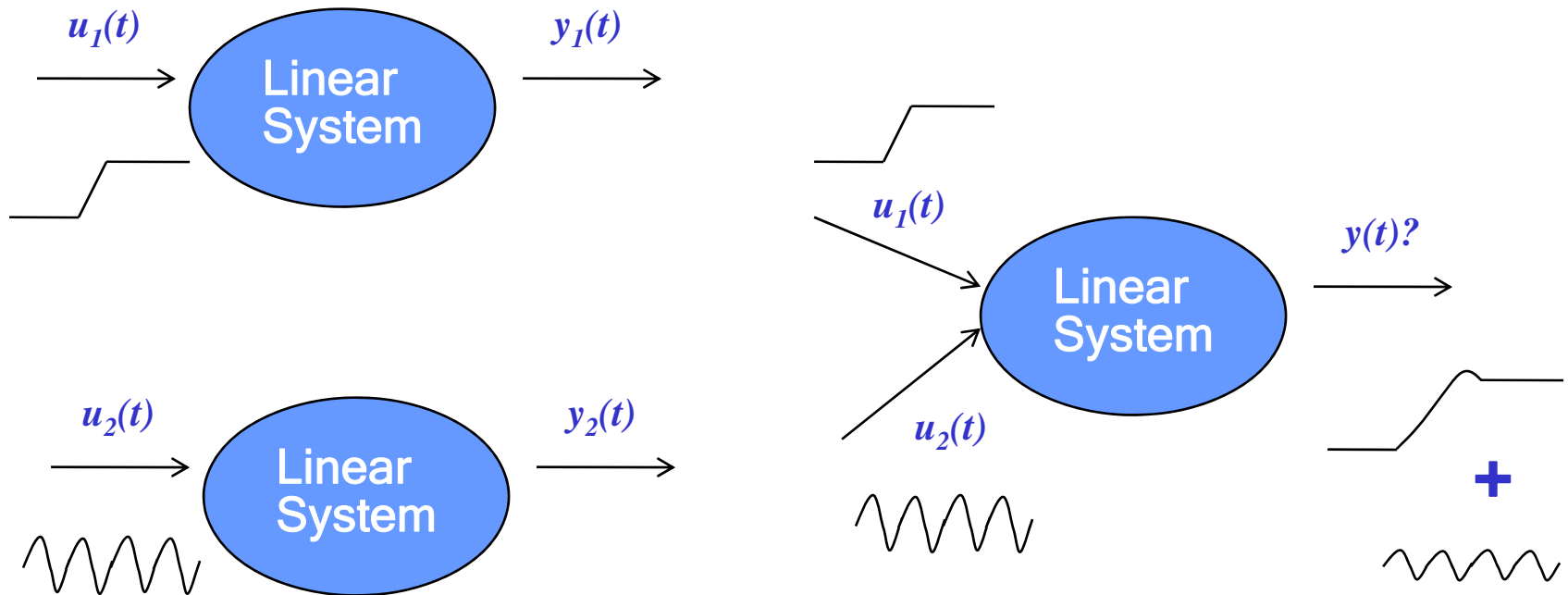
Interested in FAST weight
measurement
Settling time < 0.1 msec

=> Dynamic System

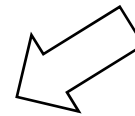
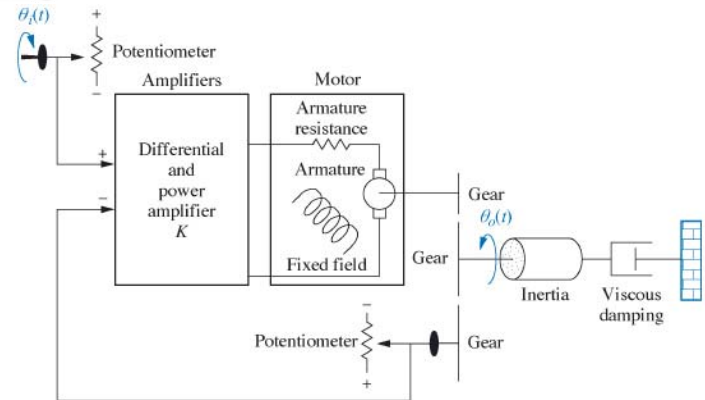
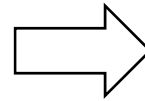
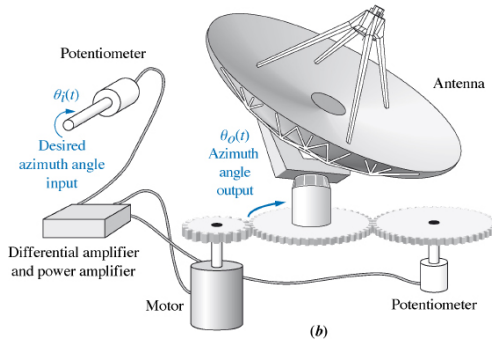
Linear vs. Nonlinear

Linear systems : linear superposition principle

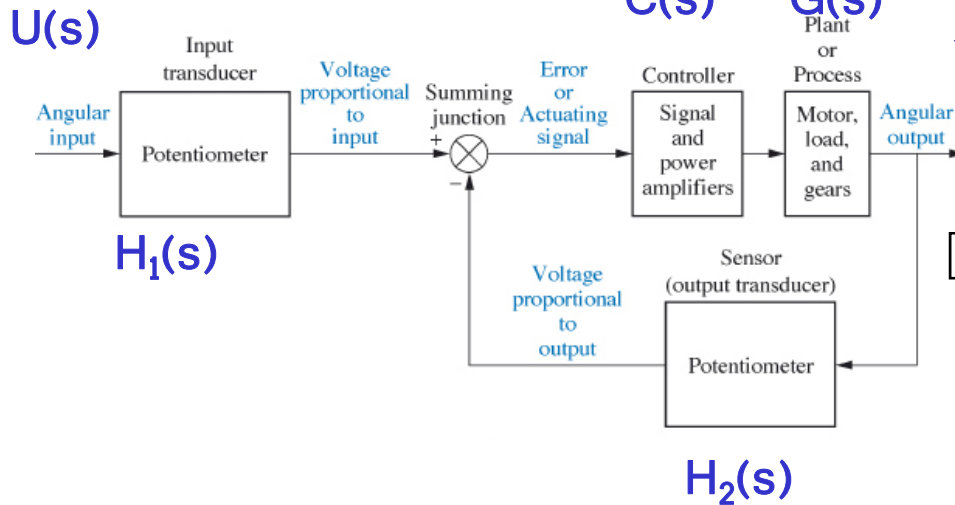
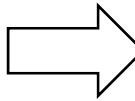
$$u(t) = \alpha_1 u_1(t) + \alpha_2 u_2(t) \longrightarrow y(t) = \alpha_1 y_1(t) + \alpha_2 y_2(t)$$



System → Schematic → Block Diagram → Transfer Functions



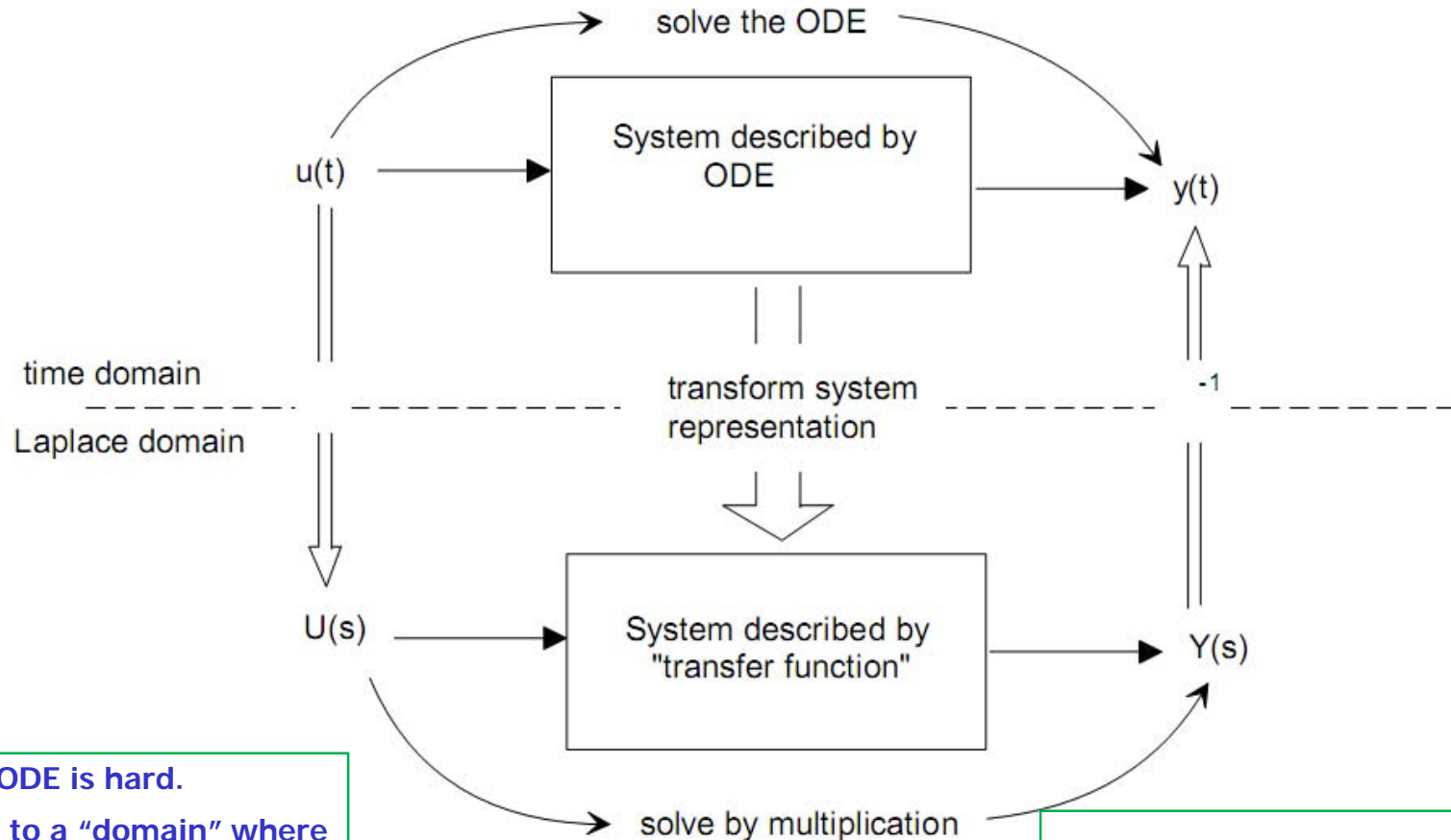
$Y(s)$



$$Y(s) = \frac{C(s)G(s)H_1(s)}{1 + C(s)G(s)H_2(s)} U(s)$$

Why use Laplace Transform?

Algebraic Manipulation of ODE



Solution of ODE is hard.
Transform in to a "domain" where it's easier to solve
Solve in the new domain
Perform "inverse" transform.



Laplace Transformation

· Definition: $\mathcal{L} [f(t)] = \boxed{} = F(s)$
 $\mathcal{L}: f(t) \Rightarrow F(s), \quad s = \sigma + j\omega$ (complex variable)

$f(t)$: a time function such that $f(t)=0$ for $t < 0$

· Inverse Laplace Transformation

$$\mathcal{L}^{-1}[F(s)] = f(t)$$



Existence of Laplace Transformation

- $f(t)$ Laplace – transformable

if i) $f(t)$ piecewise–continuous

ii) $f(t)$ of exponential order as t approaches infinity

– $e^{\alpha t} |f(t)|$ bounded, α exist.

– or $e^{-\sigma t} |f(t)|$ approaches zero as t approaches infinity.

- If
$$\lim_{t \rightarrow \infty} e^{-\sigma t} |f(t)| = \begin{cases} 0 & \text{for } \sigma > \sigma_c \\ \infty & \text{for } \sigma < \sigma_c \end{cases}$$

the σ_c : the abscissa of convergence



Existence of Laplace Transformation

example : 1) $t, \sin \omega t, t \sin \omega t \dots$

$$\lim_{t \rightarrow \infty} e^{-\sigma t} |t \sin \omega t| = \begin{cases} 0 & \text{if } \sigma > 0 \\ \infty & \text{if } \sigma < 0 \end{cases} \quad \text{the abscissa of convergence } \sigma_c = 0$$

2) $e^{-ct}, te^{-ct}, e^{-ct} \sin \omega t, \quad c = \text{const.}$

$$\lim_{t \rightarrow \infty} e^{-\sigma t} |te^{-ct}| = \begin{cases} 0 & \text{if } \sigma > -c \\ \infty & \text{if } \sigma < -c \end{cases} \quad \text{the abscissa of convergence } \sigma_c = -c$$

- e^{t^2}, te^{t^2} does not possess L. T.

- $f(t) = \begin{cases} e^{t^2} & \text{for } 0 \leq t \leq T < \infty \\ 0 & \text{for } t < 0, T < t \end{cases} \quad \text{L}[f(t)] \text{ exists.}$

- The signals that can be physically generated always have corresponding

Laplace transforms



Laplace Transformation of simple function

- Exponential function

$$f(t) = \begin{cases} 0 & \text{for } t < 0 \\ Ae^{-\alpha t} & \text{for } t \geq 0 \end{cases}$$

α : constants

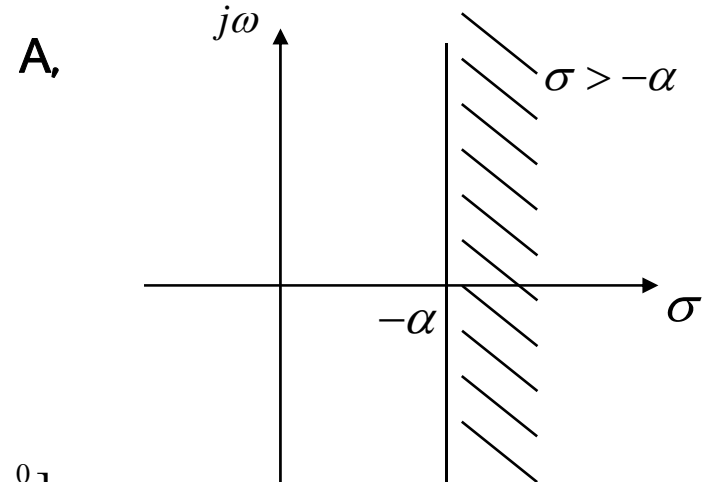
$$\mathcal{L}[Ae^{-\alpha t}] = \int_0^{\infty} Ae^{-\alpha t} \cdot e^{-st} dt$$

$$= \int_0^{\infty} Ae^{-(\alpha+s)t} dt$$

$$= A \left[-\frac{1}{s+\alpha} e^{-(s+\alpha)\cdot\infty} + \frac{1}{s+\alpha} e^0 \right]$$

$$= A \left[-\frac{1}{s+\alpha} e^{-(\sigma+\alpha)\cdot\infty - j\omega\cdot\infty} + \frac{1}{s+\alpha} \right]$$

$$= A \left[0 + \frac{1}{s+\alpha} \right] = \boxed{\phantom{A \frac{1}{s+\alpha}}}$$

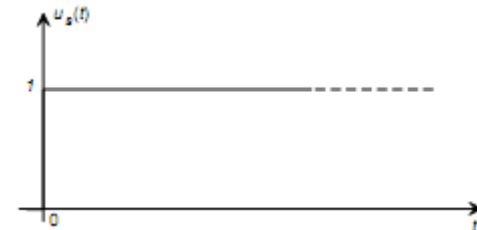


($s = \sigma + j\omega$)

Laplace Transformation of simple function

- step function

$$f(t) = \begin{cases} A & t \geq 0 \\ 0 & t < 0 \end{cases}$$



$$\begin{aligned} \mathcal{L}[f(t)] &= \int_0^{\infty} A e^{-st} dt = A \left[-\frac{1}{s} e^{-s \cdot \infty} + \frac{1}{s} e^{-s \cdot 0} \right] \\ &= A \left[0 + \frac{1}{s} \right] \quad \text{if } \operatorname{Re}[s] > 0 \end{aligned}$$

- unit step input function $1(t-t_0) = \begin{cases} 1 & t \geq t_0 \\ 0 & t < t_0 \end{cases}$

$$1(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$\mathcal{L}[1(t)] = \boxed{}$$

Laplace Transformation of simple function

- Sinusoidal Functions

$$f(t) = \begin{cases} A \sin \omega t & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$\cos \omega t = \frac{1}{2}(e^{j\omega t} + e^{-j\omega t})$$

$$\sin \omega t = \frac{1}{2j}(e^{j\omega t} - e^{-j\omega t})$$

$$\begin{aligned} \mathcal{L}[A \sin \omega t] &= \int_0^{\infty} \frac{A}{2j} (e^{j\omega t} - e^{-j\omega t}) e^{-st} dt \\ &= \frac{1}{2j} \left(\frac{1}{s - j\omega} - \frac{1}{s + j\omega} \right) \end{aligned}$$

$$=$$

$$\mathcal{L}[A \cos \omega t] =$$

- Ramp function

$$f(t) = \begin{cases} At & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$\mathcal{L}[At] = A \int_0^{\infty} t e^{-st} dt$$

$$= A \left(t \frac{e^{-st}}{-s} \Big|_0^{\infty} - \int_0^{\infty} \frac{e^{-st}}{-s} dt \right)$$

$$= A \cdot \frac{1}{s} \int_0^{\infty} e^{-st} dt =$$



Laplace Transformation of simple function

- Pulse function

$$f(t) = \begin{cases} \frac{A}{t_0} & \text{for } 0 \leq t \leq t_0 \\ 0 & \text{for } t < 0, t_0 < t \end{cases}$$

$$f(t) = \frac{A}{t_0} 1(t) - \frac{A}{t_0} 1(t - t_0)$$

$$\mathcal{L}[f(t)] = \mathcal{L}\left[\frac{A}{t_0} 1(t)\right] - \mathcal{L}\left[\frac{A}{t_0} 1(t - t_0)\right]$$

$$= \boxed{\phantom{\frac{A}{t_0} \left(\frac{1}{s} - \frac{e^{-t_0 s}}{s}\right)}}$$

- Impulse function

$$f(t) = \begin{cases} \lim_{t_0 \rightarrow \infty} \frac{A}{t_0} & \text{for } 0 \leq t < t_0 \\ 0 & \text{for } t < 0, t_0 < t \end{cases}$$

$$\mathcal{L}[f(t)] = \lim_{t_0 \rightarrow 0} \left[\frac{A}{t_0} \frac{1}{s} (1 - e^{-t_0 s}) \right]$$

$$= \lim_{t_0 \rightarrow 0} \frac{\frac{d}{dt_0} [A(1 - e^{-t_0 s})]}{\frac{d}{dt_0} (t_0 s)} = \frac{A \cdot s}{s} = \boxed{}$$

Laplace Transformation of simple function

- Unit impulse function ; impulse function of magnitude 1

$$f(t) = \begin{cases} \lim_{t_0 \rightarrow \infty} \frac{1}{t_0} & \text{for } 0 \leq t < t_0 \\ 0 & \text{for } t < 0, t_0 < t \end{cases}$$

$$\delta(t) = \begin{cases} \infty & t = 0 \\ 0 & t \neq 0 \end{cases} \quad \mathcal{L}[\delta(t)] = \int_0^{\infty} \delta(t) e^{-st} dt = \int_{0^-}^{0^+} \delta(t) dt = \boxed{}$$

The unit-impulse function occurring at $t = t_0$

$$\delta(t) = \begin{cases} \infty & t = t_0 \\ 0 & t \neq t_0 \end{cases} \quad \mathcal{L}[\delta(t - t_0)] = \int_0^{\infty} \delta(t - t_0) e^{-st} dt = \int_{t_0^-}^{t_0^+} \delta(t - t_0) e^{-st_0} dt = \boxed{}$$

$$\delta(t - t_0) = \frac{d}{dt} 1(t - t_0)$$

Useful Theorems

Theorem 1. Linearity

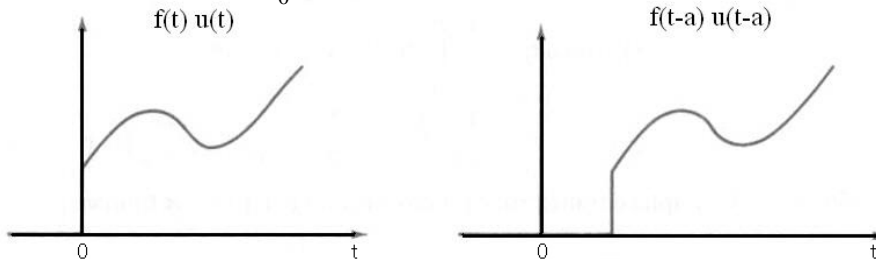
$$\mathcal{L}[af(t)] = aF(s)$$

Theorem 2. Superposition

$$\mathcal{L}[f_1(t) \pm f_2(t)] = F_1(s) \pm F_2(s)$$

Theorem 3. Translation in time.

$$\begin{aligned} \mathcal{L}[f(t-a)u(t-a)] &= \int_0^{\infty} f(t-a)u(t-a)e^{-st} dt \quad (a > 0) \\ &= \int_{-a}^{\infty} f(\tau)u(\tau)e^{-s(\tau+a)} d\tau \quad (\text{let } t-a = \tau) \\ &= \int_0^{\infty} f(\tau)u(\tau)e^{-s\tau} e^{-sa} d\tau = \boxed{} \quad (\because f(\tau)u(\tau) = 0 \text{ for } \tau < 0) \end{aligned}$$



Useful Theorems

Theorem 4. Complex differentiations

$$\mathcal{L}[tf(t)] = -\frac{d}{ds} F(s)$$

$$\mathcal{L}[1] = \frac{1}{s} \quad \mathcal{L}[t \cdot 1] = -\frac{d}{ds} F(s) = \frac{1}{s^2}$$

$$\mathcal{L}[t^2] = \mathcal{L}[t \cdot t] = -\frac{d}{ds} \left(\frac{1}{s^2} \right) = \frac{2}{s^3} \quad \mathcal{L}[tf(t)] = -\frac{d}{ds} F(s)$$

proof) let. $F(s) = \int_0^{\infty} f(t)e^{-st} dt$

$$\frac{d}{ds} F(s) = \int_0^{\infty} \frac{\partial}{\partial s} [f(t)e^{-st}] dt = -\int_0^{\infty} tf(t)e^{-st} dt = -\mathcal{L}[tf(t)]$$

similarly, $\mathcal{L}[t^2 f(t)] = (-1)^2 \frac{d^2}{ds^2} F(s)$ $\mathcal{L}[t^n f(t)] = (-1)^n \frac{d^n}{ds^n} F(s)$

Theorem 5. Translation in the s-domain

$$\mathcal{L}[e^{at} f(t)] = F(s - a)$$

$$\mathcal{L}[e^{at} \cos \omega t] =$$



Useful Theorems

Theorem 6. Real Differentiation

$$Df(t) = \frac{d}{dt} f(t)$$

proof) let. $\mathcal{L}\left[\frac{d}{dt} f(t)\right] = \int_0^{\infty} \frac{d}{dt} f(t) e^{-st} dt$

$$= f(t) e^{-st} \Big|_0^{\infty} - \int_0^{\infty} f(t) e^{-st} dt (-s)$$
$$= -f(0) + s \cdot F(s)$$
$$= \boxed{}$$

similarly, $\mathcal{L}[D^2 f(t)] = \mathcal{L}[D \cdot Df(t)] = \mathcal{L}[Df'(t)]$

$$= s \{s \cdot F(s) - f(0)\} = s^2 \cdot F(s) - s \cdot f(0) - f'(0)$$

$$\mathcal{L}\left[\frac{d^n}{dt^n} f(t)\right] = s^n \cdot F(s) - s^{n-1} \cdot f(0) - s^{n-2} \cdot f'(0)$$
$$\dots - f^{(n-1)}(0)$$



Useful Theorems

Theorem 7. Real Integration

$$\int_0^t f(t)dt = D^{-1}f(t) - D^{-1}f(0)$$

$$\mathcal{L}\left[\int_0^t f(t)dt\right] = \int_0^\infty \int_0^t f(\tau)d\tau \cdot e^{-st} dt$$

$$= -\frac{1}{s} e^{-st} \int_0^t f(\tau)d\tau \Big|_0^\infty - \int_0^\infty -\frac{1}{s} e^{-st} f(t)dt$$

$$= \frac{1}{s} \int_0^t f(\tau)d\tau \Big|_{t=0} + \frac{1}{s} \int_0^\infty e^{-st} f(t)dt = \boxed{\phantom{\int_0^\infty e^{-st} f(t)dt}}$$

Theorem 8. Complex Integration

$$\mathcal{L}\left[\frac{f(t)}{t}\right] = \int_s^\infty F(s)ds$$



Useful Theorems

Theorem 9. Final value Theorem

$$\lim_{t \rightarrow \infty} f(t) = \boxed{}$$

Theorem 10. Initial value Theorem

$$\lim_{t \rightarrow 0} f(t) = \boxed{}$$



Inverse Laplace Transformation

$$\mathcal{L}: f(t) \rightarrow F(s)$$

$$\mathcal{L}^{-1}: F(s) \rightarrow f(t)$$

$$f(t) = \mathcal{L}^{-1}[F(s)] = \frac{1}{2\pi j} \int_{c-j\omega}^{c+j\omega} F(s)e^{st} ds \quad (\text{c : real constant})$$

* Inverse Laplace Transformation by Partial Fraction Method

$$F(s) = \frac{P(s)}{Q(s)} = \frac{a_m s^m + a_{m-1} s^{m-1} + \cdots + a_0}{s^n + b_{n-1} s^{n-1} + \cdots + b_1 s + b_0} \quad (n \geq m)$$

$s^n + b_{n-1} s^{n-1} + \cdots + b_1 s + b_0 \Rightarrow$ real complex conjugate, a, b : real num.

$$= (s - c_1)(s - c_2) \cdots (s^2 + d_1 s + d_2)$$

$$\Rightarrow F(s) = \frac{\alpha_1}{s - c_1} + \frac{\alpha_2}{s - c_2} + \cdots + \frac{\beta_1 s + \beta_2}{s^2 + d_1 s + d_2} + \cdots$$



Examples of Inverse Laplace Transformation

$$\text{ex)} \quad F(s) = \frac{1}{(s+2)^2(s+3)} = \frac{a}{s+2} + \frac{b}{(s+2)^2} + \frac{c}{s+3}$$

$$a(s+2)(s+3) + b(s+3) + c(s+2)^2 = 1$$

let $s = -2$, then $b = 1$, let $s = -3$, then $c = 1$

$$a(s+2) + b + c \cdot \frac{s+2}{s+3} = \frac{1}{s+3} \quad \xrightarrow{\frac{d}{ds}} \quad a + c \cdot \frac{(s+3) - (s+2)}{s+3} = \frac{-1}{(s+3)^2}$$

$$\therefore a = -1, b = 1, c = 1, \quad F(s) = \frac{-1}{s+2} + \frac{1}{(s+2)^2} + \frac{1}{s+3}$$

=> Inverse Laplace Transformation

$$f(t) = -e^{-2t} + te^{-2t} + e^{-3t}$$

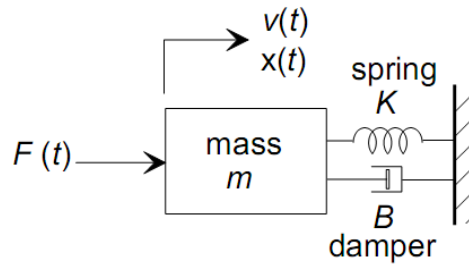
(partial fraction method)

$$\text{ex)} \quad F(s) = \frac{10}{s^2 + 6s + 25} = \frac{10 \times \frac{1}{4} \times 4}{(s+3)^2 + 4^2} = \frac{10}{4} \frac{4}{(s+3)^2 + 4^2}$$

$$\therefore f(t) = \frac{10}{4} \sin 4te^{-3t}$$



Solution of Differential Equation by Laplace Transformation



$$m\ddot{x} + B\dot{x} + Kx = F.$$

$$y'' + 2y' + 4y = 1 \quad y(0) = 0, \quad y'(0) = 2$$

L.T:

$$Y(s) = \frac{2s+1}{s(s^2+2s+4)} = \frac{1}{4s} - \frac{1}{4} \frac{s+1-1}{(s+1)^2 + (\sqrt{3})^2}$$

$\therefore y(t) =$



Laplace Transform Table

| Item no. | $f(t)$ | $F(s)$ |
|----------|----------------------|---------------------------------|
| 1. | $\delta(t)$ | 1 |
| 2. | $u(t)$ | $\frac{1}{s}$ |
| 3. | $tu(t)$ | $\frac{1}{s^2}$ |
| 4. | $t^n u(t)$ | $\frac{n!}{s^{n+1}}$ |
| 5. | $e^{-at} u(t)$ | $\frac{1}{s+a}$ |
| 6. | $\sin \omega t u(t)$ | $\frac{\omega}{s^2 + \omega^2}$ |
| 7. | $\cos \omega t u(t)$ | $\frac{s}{s^2 + \omega^2}$ |

Nise Ch.2



Laplace Transform Theorems

Nise Ch.2

| Item no. | Theorem | Name |
|----------|--|------------------------------------|
| 1. | $\mathcal{L}[f(t)] = F(s) = \int_{0-}^{\infty} f(t)e^{-st} dt$ | Definition |
| 2. | $\mathcal{L}[kf(t)] = kF(s)$ | Linearity theorem |
| 3. | $\mathcal{L}[f_1(t) + f_2(t)] = F_1(s) + F_2(s)$ | Linearity theorem |
| 4. | $\mathcal{L}[e^{-at} f(t)] = F(s + a)$ | Frequency shift theorem |
| 5. | $\mathcal{L}[f(t - T)] = e^{-sT} F(s)$ | Time shift theorem |
| 6. | $\mathcal{L}[f(at)] = \frac{1}{a} F\left(\frac{s}{a}\right)$ | Scaling theorem |
| 7. | $\mathcal{L}\left[\frac{df}{dt}\right] = sF(s) - f(0-)$ | Differentiation theorem |
| 8. | $\mathcal{L}\left[\frac{d^2f}{dt^2}\right] = s^2F(s) - sf(0-) - f'(0-)$ | Differentiation theorem |
| 9. | $\mathcal{L}\left[\frac{d^nf}{dt^n}\right] = s^nF(s) - \sum_{k=1}^n s^{n-k} f^{(k-1)}(0-)$ | Differentiation theorem |
| 10. | $\mathcal{L}\left[\int_{0-}^1 f(\tau)d\tau\right] = \frac{F(s)}{s}$ | Integration theorem |
| 11. | $f(\infty) = \lim_{s \rightarrow 0} sF(s)$ | Final value theorem ¹ |
| 12. | $f(0+) = \lim_{s \rightarrow \infty} sF(s)$ | Initial value theorem ² |