

Wireless Medium Access Control (MAC)

Kyunghan Lee Networked Computing Lab (NXC Lab) Department of Electrical and Computer Engineering Seoul National University https://nxc.snu.ac.kr kyunghanlee@snu.ac.kr

Adapted from Prof. Sunghyun Choi's slides

Medium Access Control (MAC)

- □ Layer 2 in the layered architecture
- Determines when (or which resource to use) to transmit a packet to the channel
 - Resource = time, frequency, code, antenna, etc.
 - Dependent on the multiple access (MA) scheme
- Provides MAC-specific framing
 - Fragmentation
 - Splitting into time/frequency slots
- Provides error control mechanism
 - How to detect the erroneous transmission
 - How to recover from the error if needed
 - ARQ, FEC, ...





Distributed vs. Centralized

Distributed and contention-based

- Typically, random access (see Token Passing)
- Simple, robust to a single point failure
- Good for bursty traffic in light load \rightarrow possible lower delay
- Centralized and controlled
 - Controlled by an BS \rightarrow well fit into cellular
 - More controllable \rightarrow QoS support
 - Could be more efficient, esp., with many users in heavy load





Slotted ALOHA

Assumptions

- all frames same size time is divided into equal size slots, time to transmit 1 frame
- nodes start to transmit frames only at beginning of slots
- nodes are synchronized
- collision is detected
- Operation
 - when node obtains fresh frame, it transmits in next slot
 - no collision, node can send new frame in next slot
 - if collision, node retransmits frame in each subsequent slot with prob. p until success

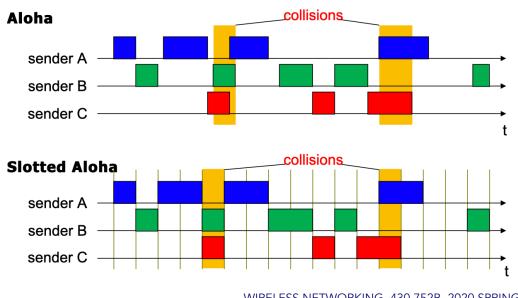




Slotted ALOHA

□ Pros

- single active node can continuously transmit at full rate of channel
- highly decentralized
- simple
- □ Cons
 - collisions, wasting slots
 - idle slots due to probabilistic retransmission



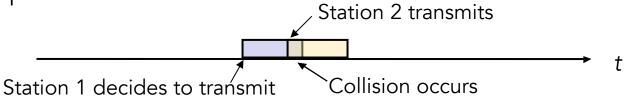


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Collision

 Collision: Two or more users' transmissions overlap (in time) resulting in packet loss



- Recognition: Some way of recognizing that a collision has occurred and signaling users involved
 - (a) Use a central controller to recognize collisions (signal distortions) and then signal users ← original Aloha
 - (b) Use a positive ACK with timeout
 - (c) Stations listen and detect their own collisions ← bus architectures
- Retransmission: After a collision, attempt again after some random time has elapsed (back-off)
 - The amount of time is specified by a collision resolution protocol.





- \Box Assume *N* stations
 - Each station transmits λ (new) packets/sec
 - Arrival of (new) packets from each station is Poisson
 - Fixed packet lengths with transmission time = m

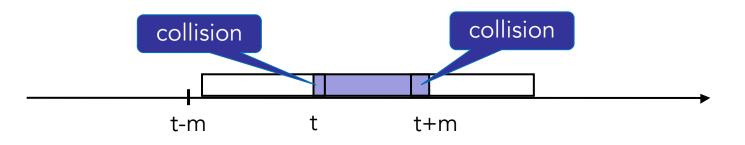
Normalized throughput (S) = $\frac{\text{Rate of transmitting new packets}}{\text{Max. channel transmission rate}}$ = $\frac{N\lambda \text{ packets/sec}}{\frac{1}{m} \text{ packets/sec}}$

- Additional assumption: retransmitted packets are also Poisson distributed
 - Not true: Since retransmissions depend on collision instance
 - (Okay if random retransmission delay is long minor impact to Poisson rate)





- □ Let λ' be total rate of packets attempting transmission, then $\lambda' \ge \lambda$
- □ Let G be actual traffic intensity or utilization, then $G = N\lambda'm$
- \Box Consider a typical packet transmitted at time t



• Any transmissions by any station between times t - m and t + m will cause a collision.





 $\Box \operatorname{Pr}\{\operatorname{Successful\ transmission}\}$

- $= \Pr\{\text{No arrivals in } [t m, t + m] \mid \text{An arrival occurs at } t\}$
- $= \Pr\{\text{No arrivals in } [t-m, t+m]\}$
- $= \Pr\{$ No arrivals in time interval of $2m\}$

$$\Box \text{ From } G = N\lambda'm,$$

$$P_s = \Pr\{\text{Successful transmission}\} = e^{-2G}$$

$$\text{Recall that Poisson process gives}$$

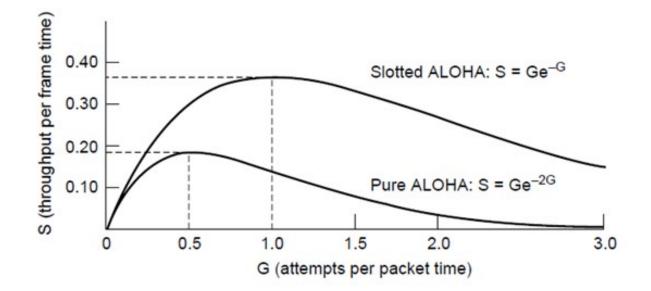
$$P_{N(t) = n\} = \frac{(\lambda t)^n}{n!}e^{-\lambda t}.$$

$$\Box \text{ Also, } P_s = \frac{\# \text{ of successfully transmitted packets}}{\# \text{ of totally transmitted packets}}$$
$$= \frac{(\text{throughput with new packets})}{(\text{throughput with all packets})} \xrightarrow{S} G$$

$$\Box$$
 Hence, $P_s = \frac{S}{G}$



Pure Aloha throughput: $S = Ge^{-2G}$ • S has the peak value $S_{max} = \frac{1}{2e}$, when $G = G^* = \frac{1}{2}$



For Aloha, the max throughput is 18% of channel capacity.

Thus it is suitable for either low traffic rate, or for highly bursty traffic





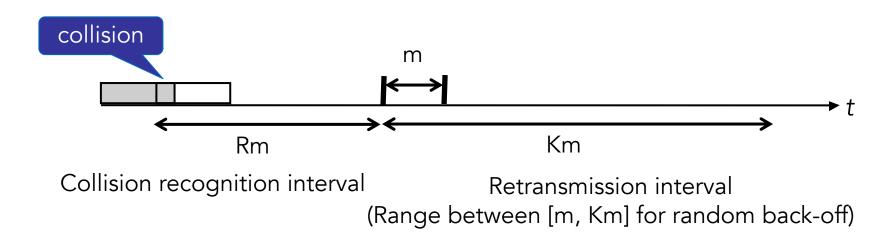
Time Delay Analysis of Pure Aloha

- Our simple throughput analysis of Pure Aloha is "independent" of the retransmission policy
 - However, for time delay analysis, we need to specify the retransmission policy
- □ Retransmission Policy:
 - Suppose that each message lengths is of *m* seconds
 - If a collision occurs, we choose an arbitrary time interval, whose length is equivalent to K-message unit times ($K \cdot m$)
 - Retransmission randomly occurs in the interval, i.e., following the uniform distribution





Time Delay Analysis of Pure Aloha



□ Collision cognition interval:

- Retransmission will take place, only after the sender noticed that a collision has occurred
- Let the round-trip delay plus processing time required to obtain the collision information be *R* intervals (times *m*)





Time Delay Analysis of Pure Aloha

□ Let *D* be average time for a successful transmission

$$D = m + Rm + E\left(Rm + \frac{K+1}{2}m\right)$$
Average delay of
where *m* is message transmission time (\in [m, Km])
Rm is recognition time

• Note that *E* is expected number of retransmissions

$$1 + E = \frac{\text{avg. } \# \text{ of attempted transmissions}}{\text{avg. } \# \text{ of successful transmissions}} = \frac{G}{S} \longleftarrow S = Ge^{-2G}$$

$$\Box \text{ Hence,}$$

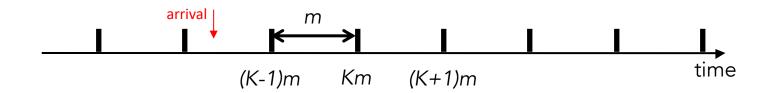
$$D = m + Rm + (e^{2G} - 1) \cdot \left(Rm + \frac{K+1}{2}m\right)$$



Slotted Aloha

□ Time is slotted into units of message transmission times

- Messages can only be transmitted <u>at beginning of time slot</u>
- Collision occurs if another message is transmitted at the same time slot (This message arrives during ((K-1)m, Km))



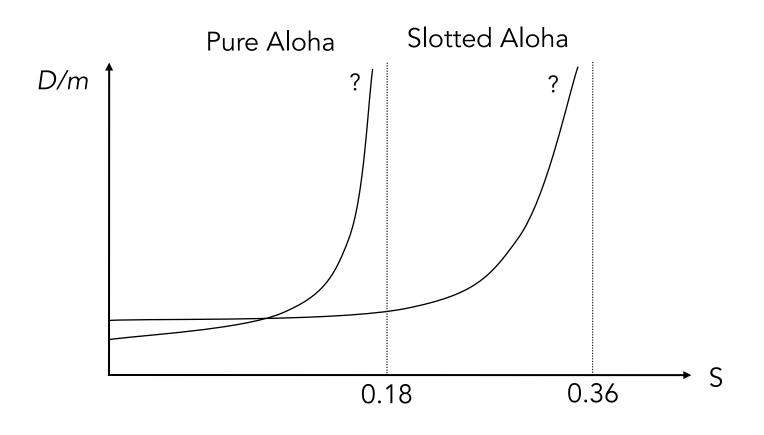
□ Following the same line of analysis as Pure Aloha, $Pr{Success} = e^{-G}, S = Ge^{-G}$ $D = 1.5m + Rm + (e^{G} - 1) \cdot \left(Rm + 0.5m + \frac{K+1}{2}m\right)$ Try to get this result by yourself





Performance Comparison

□ Throughput-delay curve







Comments

- Slotted ALOHA is often used as part of TDMA and CDMA for random access channel
 - To associate with the BS
 - To send a short message
- For pure distributed wireless systems, more efficient random access schemes are used as follows





CSMA (Carrier Sense Multiple Access)

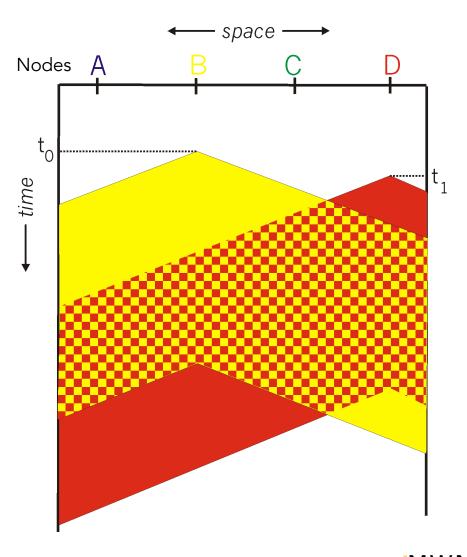
- □ Listen before transmit:
- □ If channel sensed idle: transmit entire frame
- □ If channel sensed busy, defer transmission
- Human analogy: don't interrupt others!





CSMA collisions

- Collisions can still occur:
 - propagation delay means two nodes may not hear each other's transmission
- \Box collision:
 - entire packet transmission time wasted
- □ note:
 - role of distance & propagation delay in determining collision probability







CSMA/CD (Collision Detection)

Carrier sensing, deferral as in CSMA

- Collisions detected within short time
- Colliding transmissions aborted, reducing channel wastage
- Collision detection:
 - Easy in wired LANs: measure signal strengths, compare transmitted, received signals
 - Used in the popular Ethernet
 - Rather impossible in wireless LANs:
 - receiver shut off while transmitting
 - even if not, impossible due to high path loss





After a collision is detected

- Current packet transmission is aborted
- A retransmission attempt is made at a random time, uniformly chosen within a given time interval (similar to Aloha)
- Each time a collision occurs (for the same packet), this time interval is "doubled" (up to a maximum value) thereby reducing chance of collisions
- Known as binary exponential backoff.

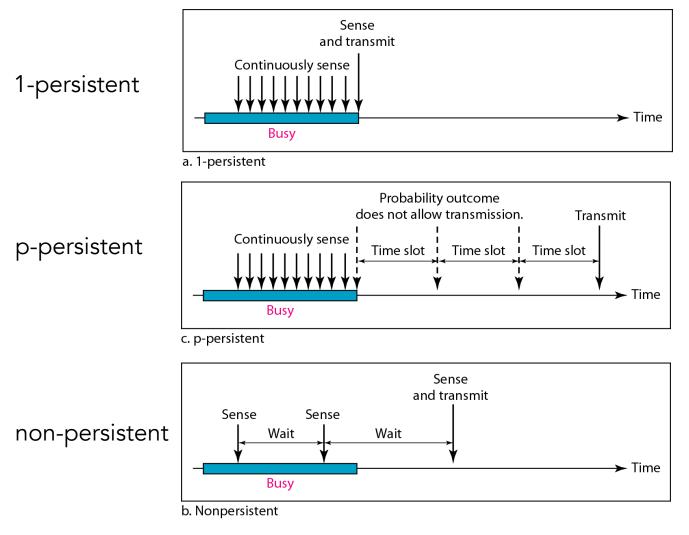




- $\hfill\square$ In case that the channel is busy
 - There are variants based on what to do when the channel is sensed busy
 - 1-persistent: Attempt transmission as soon as channel is sensed idle (Ethernet)
 - p-persistent: Attempt transmission with probability p once channel goes idle. With probability (1-p), wait for a propagation delay interval τ and try again!
 - Non-persistent: Reschedule after a <u>random waiting</u> time, sense channel and if idle, transmit, if busy, repeat.









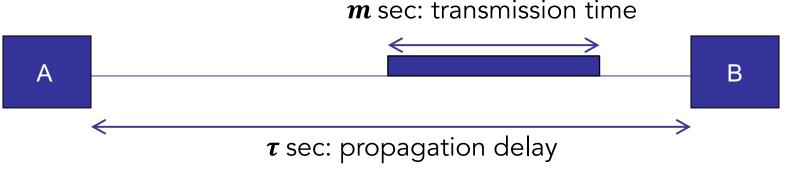


□ All carrier sense protocols rely on stations being able to

- Sense that a transmission has ended, soon after its completion
- Sense that a transmission has started, soon after it begins
- Need $a = \tau/m \ll 1$ for high throughput

□ Suitable for

- Local Area Network (small au)
- Large Networks that are low speed (large m)

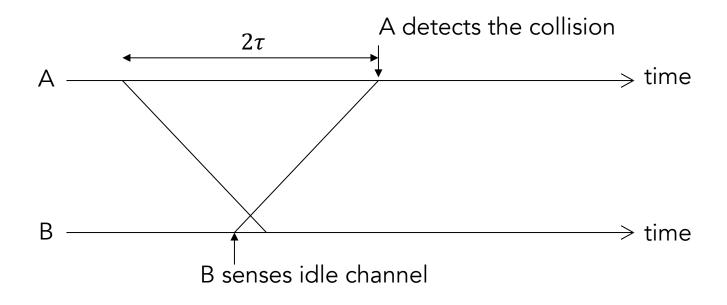






Collision

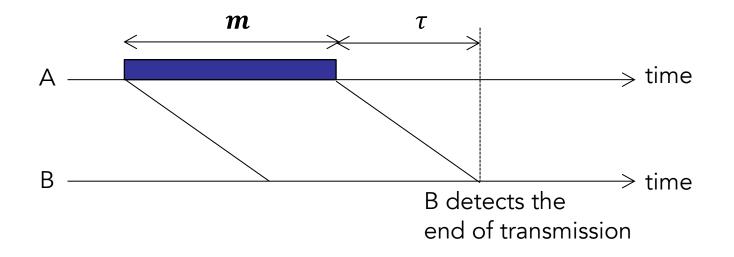
- Suppose that a collision takes place between A's & B's transmission
- In the worst case, it takes 2τ sec for A & B to detect the collision and turn off their transmissions





□ Sensing

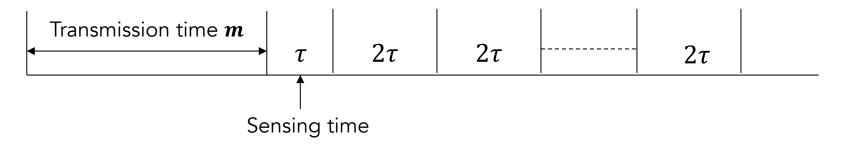
 After A finishes transmission, it takes τ seconds for B to determine that A has finished transmission (idle channel)







Considering intervals for both collision and sensing, we consider τ and 2τ intervals after transmission as follows:



- □ Let J denote the expected number of 2τ intervals before a successful transmission taking place
 - J depends on the retransmission policy, e.g., binary exponential back-off etc.





 \square Worst-case calculation of transmission time t_v

- t_v is the time interval between two successful transmissions
- Given J collisions, it takes $2\tau J$ units of time to resolve it

$$t_v = m + \tau + 2\tau J = m(1 + a(1 + 2J)), \text{ where } a = \tau/m$$

Use a simple model of retransmissions backed by simulation

- Assume length of collision interval is geometrically distributed in units of 2τ , with parameter $v = Pr\{no \text{ collision happens}\}$
- Then $\Pr\{\text{collision interval} = n \cdot 2\tau\} = v(1-v)^{n-1}$

$$J = \sum_{k=1}^{\infty} kv(1-v)^{k-1} = \frac{1}{v}$$

• So we focus on finding *v*.





- Assume n stations are involved
 - Each station attempts to transmit in a 2τ interval with probability p, independent of others
 - $p = \Pr\{A \text{ station wants to transmits in a } 2\tau \text{ interval}\}$
 - $v = \Pr\{\text{no collisions happening}\}$
 - $= \Pr\{\text{exactly one station transmits}\}$

$$= np(1-p)^{n-1}$$

- $p = \frac{1}{n}$ will maximize v and provides the greatest chances of success
 - \rightarrow maximized $v \rightarrow$ smallest J
 - \rightarrow max (worst-case) throughput.





 \square Now, by setting $p = \frac{1}{n}$, we obtain that

$$v_{\max} = \left(1 - \frac{1}{n}\right)^{n-1} \to e^{-1}, \text{ as } n \to \infty$$

$$t_v = m(1 + a(1 + 2J)) = m(1 + a(1 + 2e))$$

max throughput $\lambda_{\max} = \frac{1}{t_v} = \frac{1}{m(1 + a(1 + 2e))}$

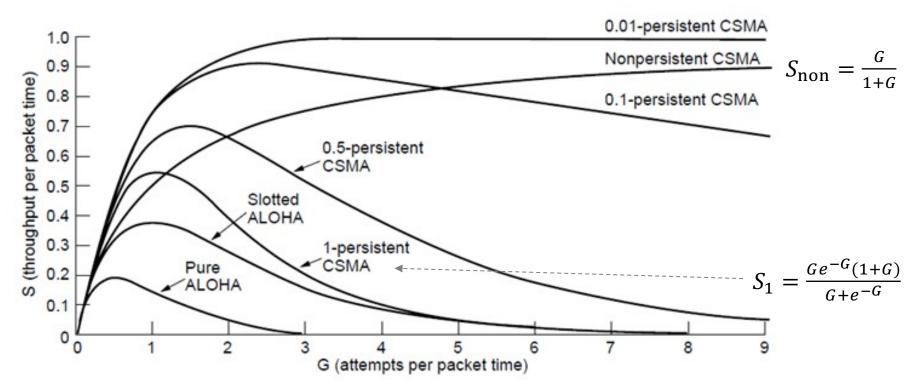
 \Box Let link utilization be $\rho = m\lambda_{\max}$

- Recall $a = \tau/m$: transmission time (m) must be much larger than the propagation delay (τ) for system to work well
- If a = 0.1, then $\rho < 0.6$
- If a = 0.01, then $\rho < 0.94$





Throughput Comparison



Does this graph mean that 0.01-persistent outperforms others? If not, why? Reading this graph correctly is important!

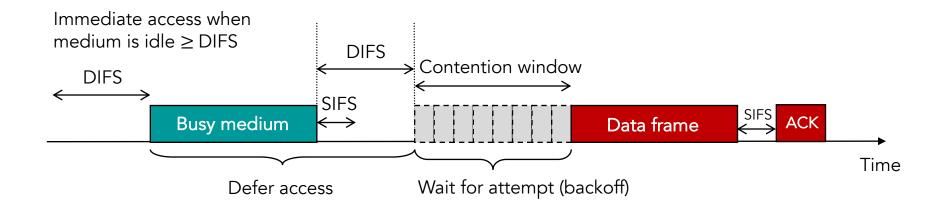
L. Kleinrock and F. Tobagi, "Packet Switching in Radio Channels: Part I - Carrier Sense Multiple-Access Modes and Their Throughput-Delay Characteristics," in *IEEE Transactions on Communications*, vol. 23, no. 12, pp. 1400-1416, December 1975.





CSMA/CA (Collision Avoidance)

- □ Used in IEEE 802.11 mandatory MAC
- Transmit after a backoff even if an idle channel is detected
- □ Interframe spacing (in 802.11)
 - Short IFS (SIFS): Typically to complete exchange in progress
 - i.e., between data frame and ACK
 - DCF IFS (DIFS): Time to detect idle medium







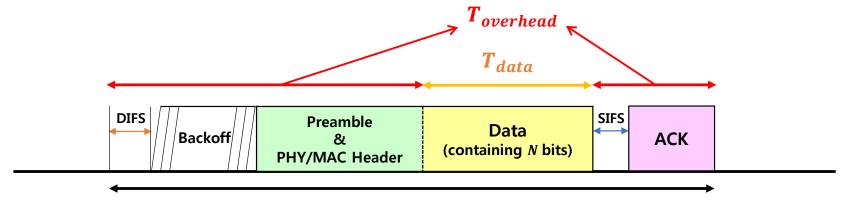
CSMA/CA Throughput

□ Average throughput with a single transmitter

$$Th(bits/sec) = \frac{N}{T} = \frac{N}{T_{data} + T_{overhead}} = \frac{N}{(N/PHY_rate) + T_{overhead}} = \frac{1}{(1/PHY_rate) + (T_{overhead}/N)}$$

□ Protocol overhead for a single transmission is independent of frame length

- \Box Even with extremely high PHY rate, throughput is bounded by (N/T_{overhead})
- \Box As N becomes larger, throughput can approach the PHY rate

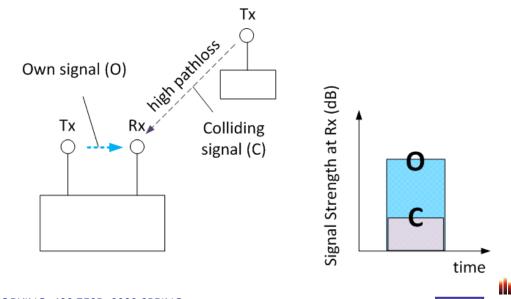






Collision Detection Impossible in Wireless?

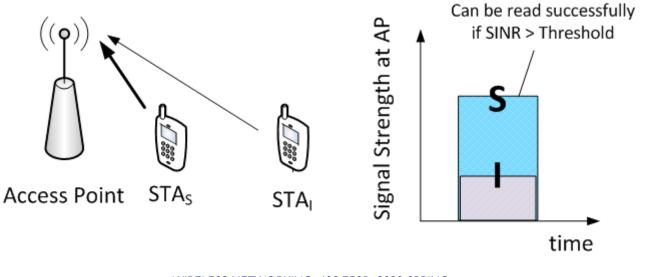
- With a single radio, Tx and Rx cannot occur simultaneously
- Even with two radios, compared with its own signal, strength of the received signal from another station is typically much smaller
 - Collision does not make much difference
 - $P_{O} \approx P_{O} + P_{C}$
 - cf. CD is possible with Full Duplex





Capture Effect

- Even when a collision occurs, a packet (not all) can be successfully received if SINR (Signal-to-Interference and Noise Ratio) is above threshold
- Threshold is a function of MCS (Modulation and Coding Scheme)
- □ In practice, there are a lot of captures





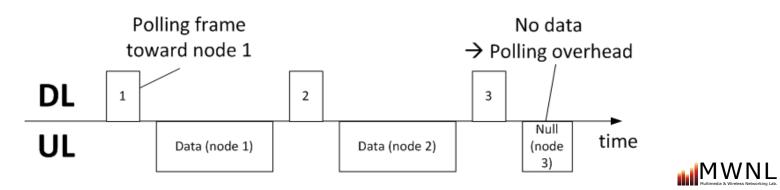
Polling MAC

□ A master polls a slave station for the transmission

- based on the polling order scheduling
- TDD inherently
- □ Used in IEEE 802.11 MAC as an optional mode

□ Concern:

- Polling overhead
- Latency, esp. when lightly loaded
- Single point of failure (master)

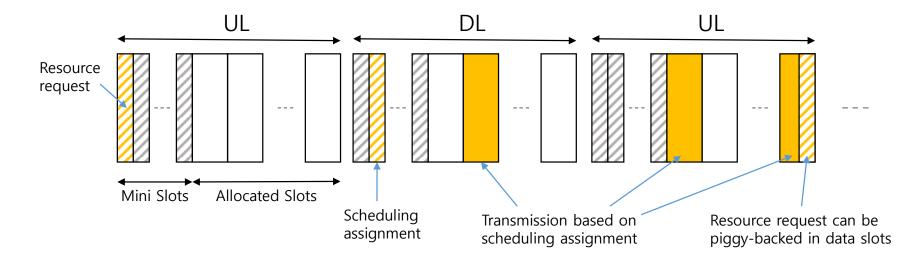






Dynamic TDMA

- Frames divided into resource request (in mini slots) and data slots
 - ALOHA variation be used for request
 - Data slots are allocated based on requests and scheduling
- □ Example, for TDD

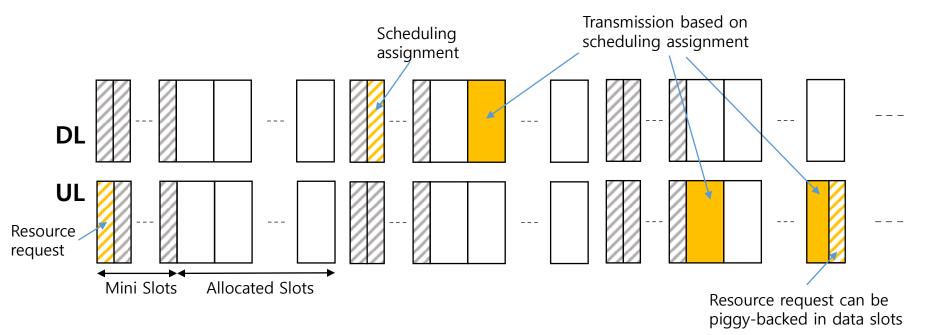






Dynamic TDMA

- Frames divided into resource request (in mini slots) and data slots
 - ALOHA variation be used for request
 - Data slots are allocated based on requests and scheduling
- □ Example, for FDD







Comments

- Different MAC approaches should be used depending on the system requirements
 - Target application
 - Target environment, e.g., licensed or unlicensed bands
- Many detailed features should be considered
 - QoS provisioning, power consumption, ...



