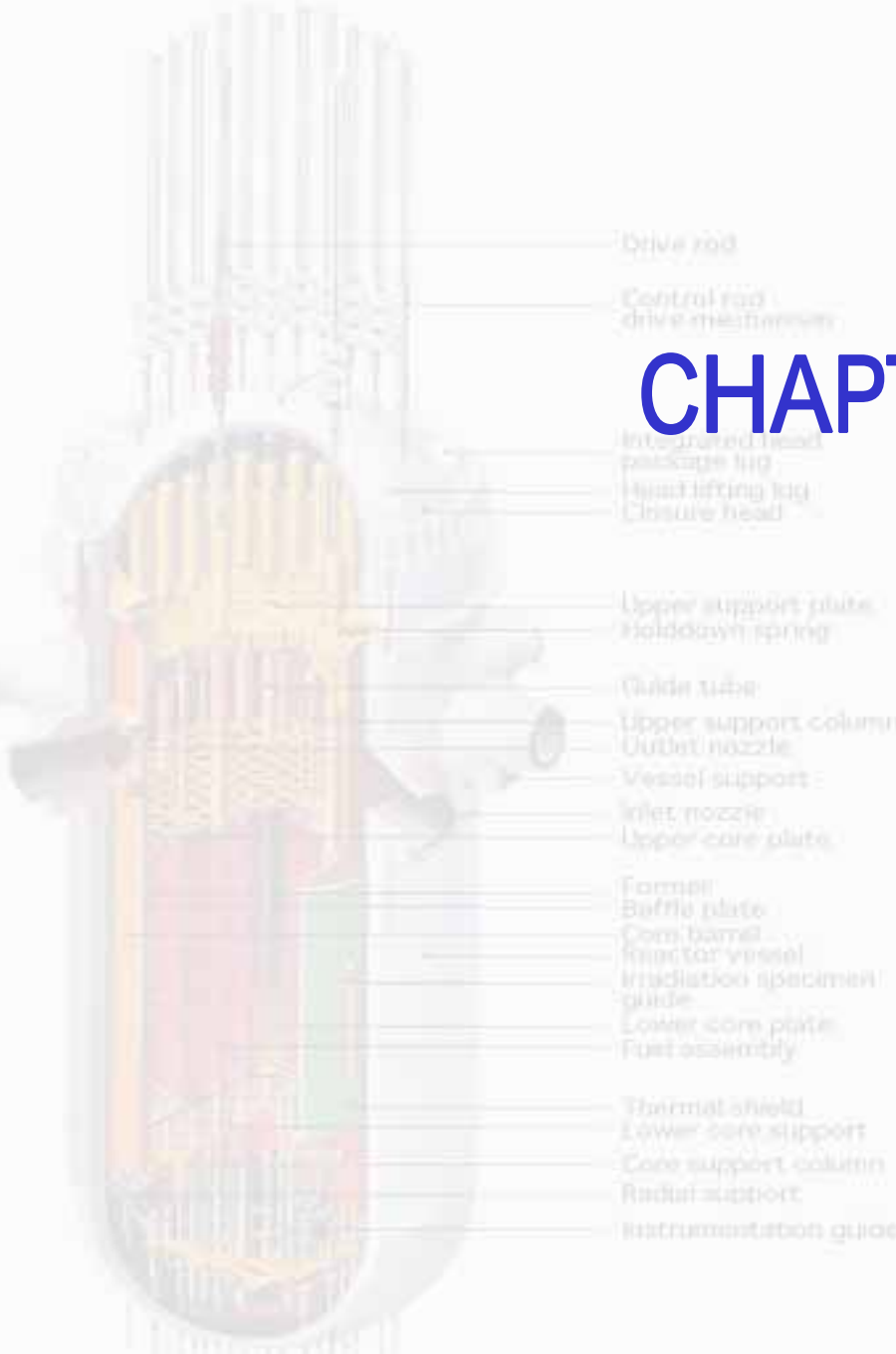


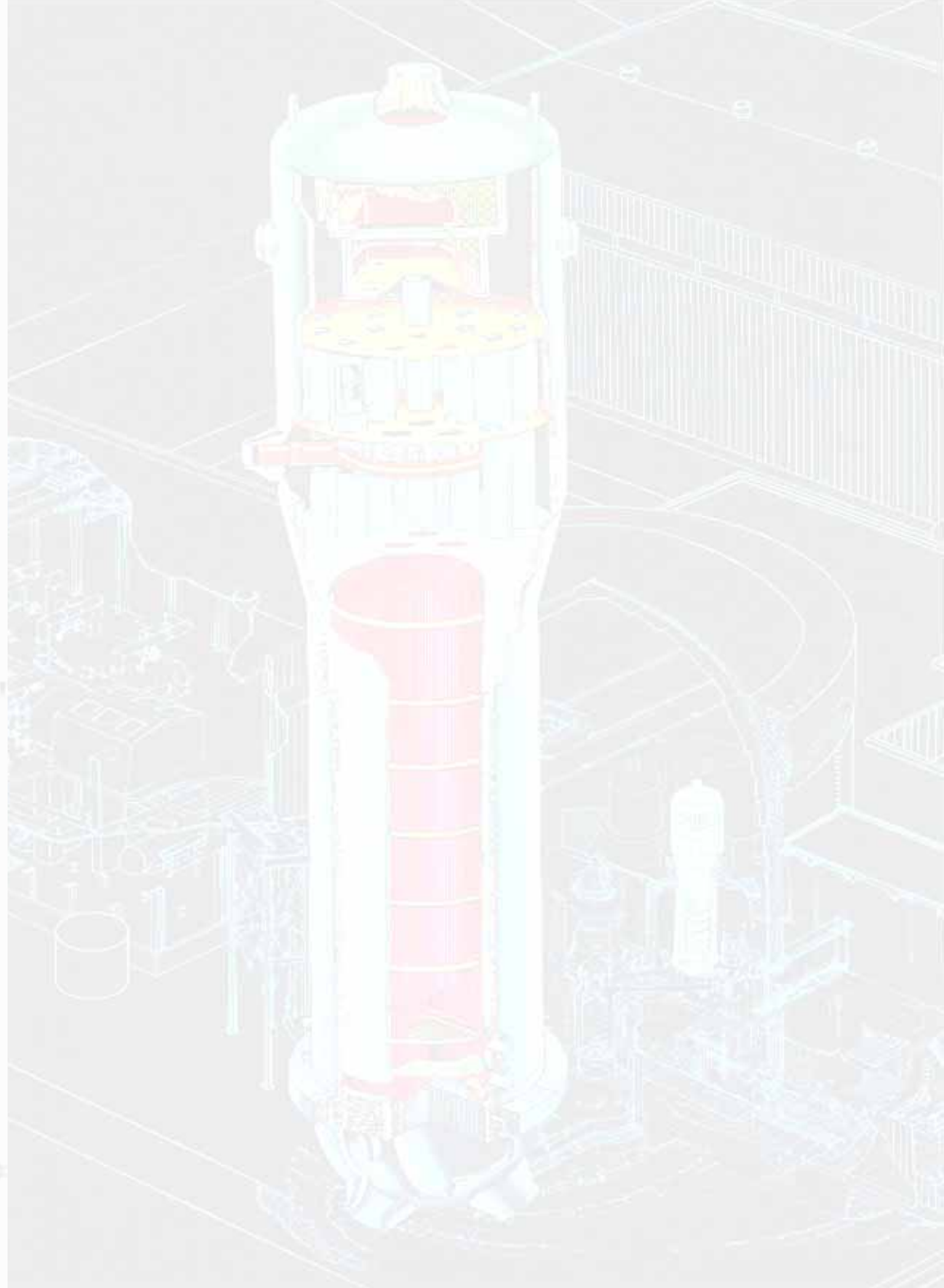
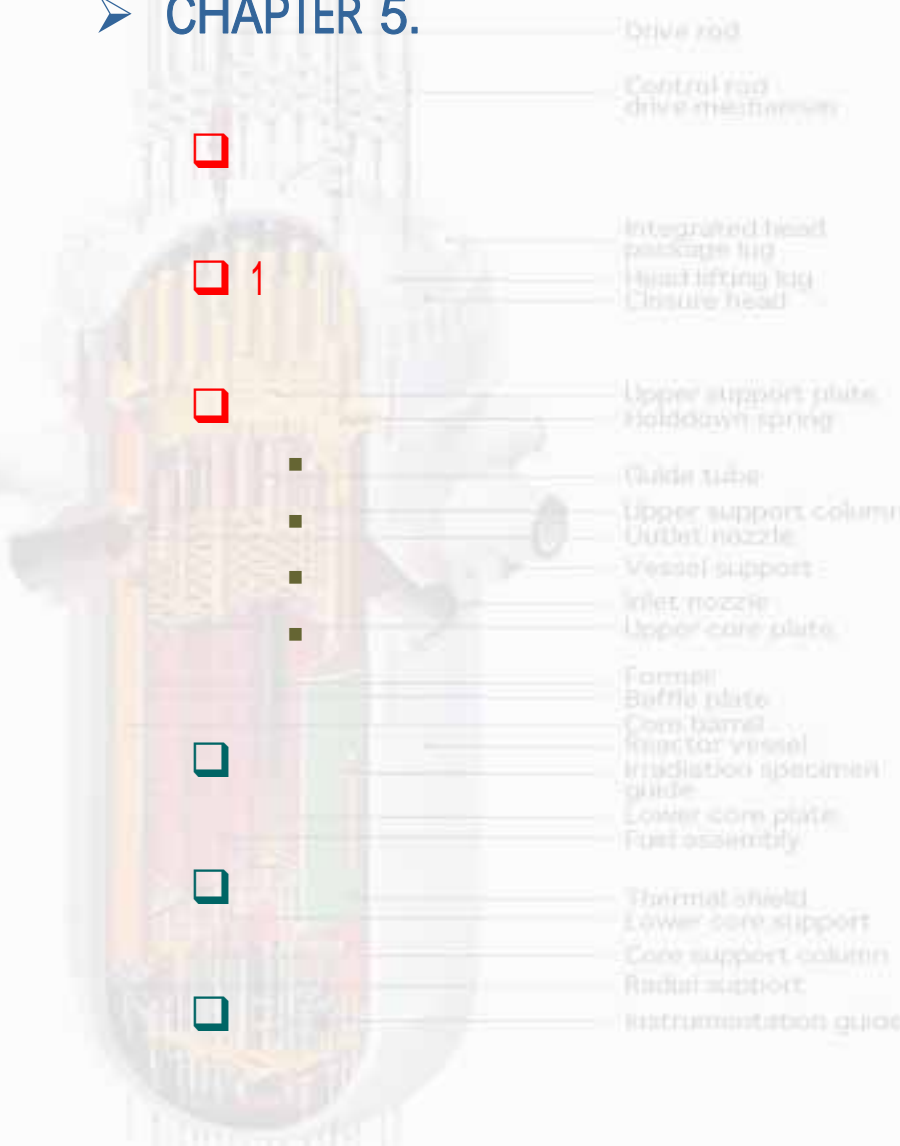
# CHAPTER 5-1



U.C.Lee



# ➤ CHAPTER 5.



REACTOR VESSEL AND INTERNALS (with STEAM GENERATOR)



1.



$$\Sigma_f(\vec{r})\phi(\vec{r})$$

$$P(\vec{r}) = \kappa \Sigma_f(\vec{r})\phi(\vec{r}) \quad 5.1$$

$\kappa =$

•  $P(\vec{r})$

$r$

$$P = \int_{V_R} P(\vec{r}) dV = \kappa \int_{V_R} \Sigma_f(\vec{r})\phi(\vec{r}) dV \quad 5.2$$

$V_R =$



1.

□  $\Sigma_f(\vec{r})$  ( ) rod

$$\Sigma_f(\vec{r}) = N_f(\vec{r}) \sigma_f$$

$N_f(\vec{r})$

□  $\sigma_f$



- Control rod
- Integrated head package lig
- Head lifting lig
- Closure head
- Upper support plate
- Holddown spring
- Guide tube
- Upper support column
- Outlet nozzle
- Vessel support
- Inlet nozzle
- Upper core plate
- Former
- Baffle plate
- Core barrel
- Reactor vessel
- radiation specimen guide
- Lower core plate
- Fuel assembly
- Thermal shield
- Lower core support
- Core support column
- Radial support
- Instrumentation guide



# 2. 1

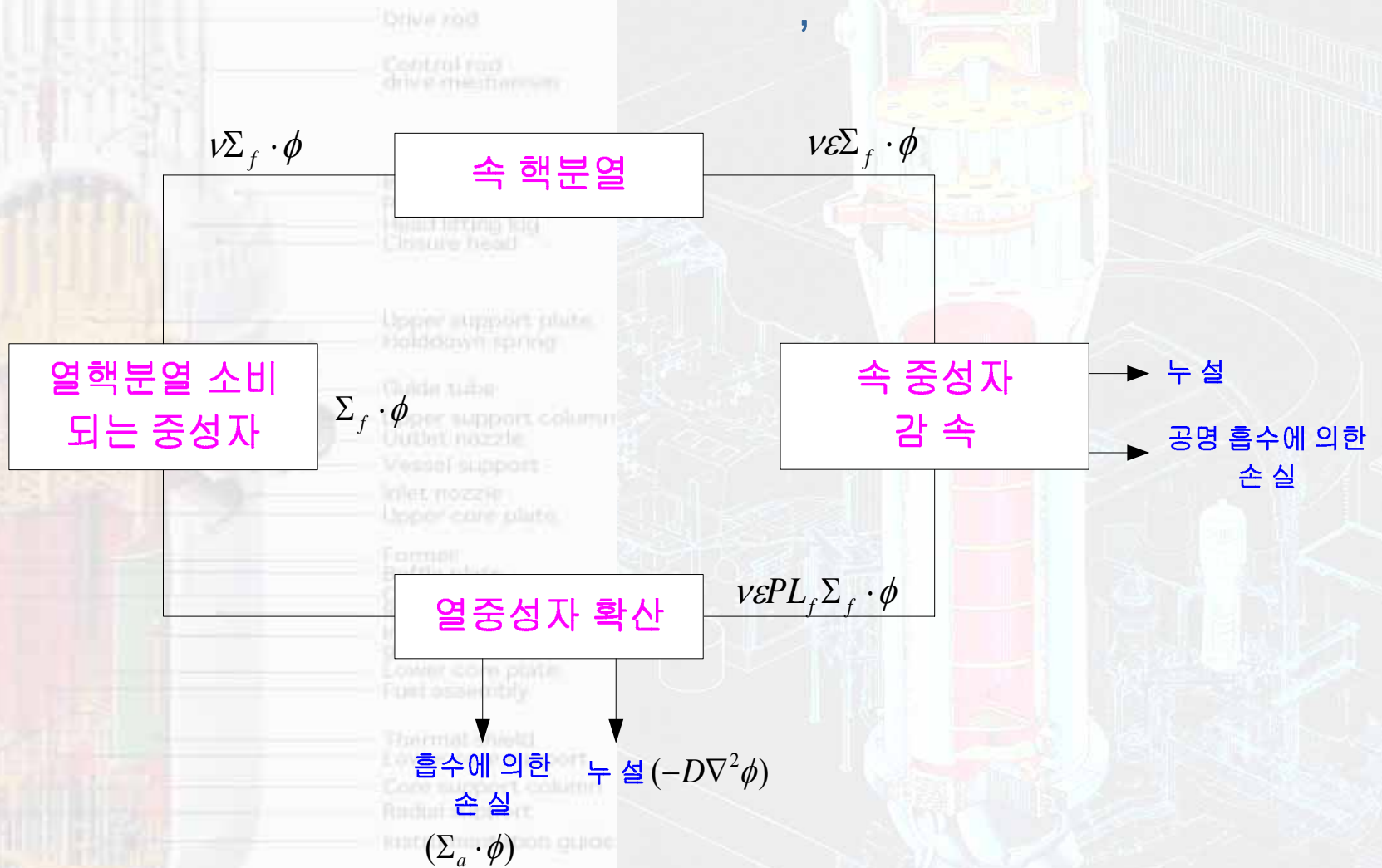


그림 5.1 노심내 중성자의 거동



# 2.1



Drive rod 5.1  
가  
control rod  
drive mechanism



(I)

+



(II)

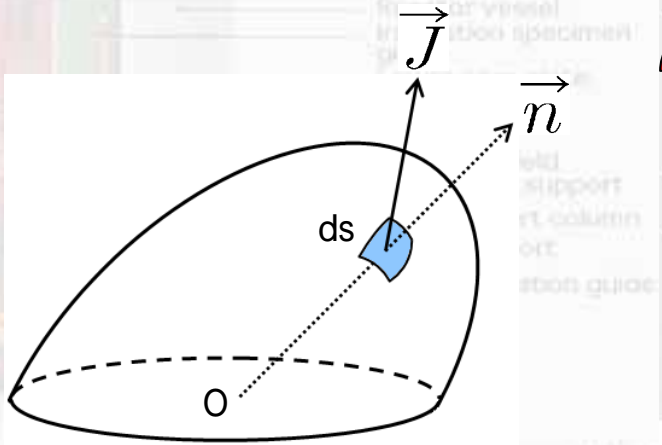
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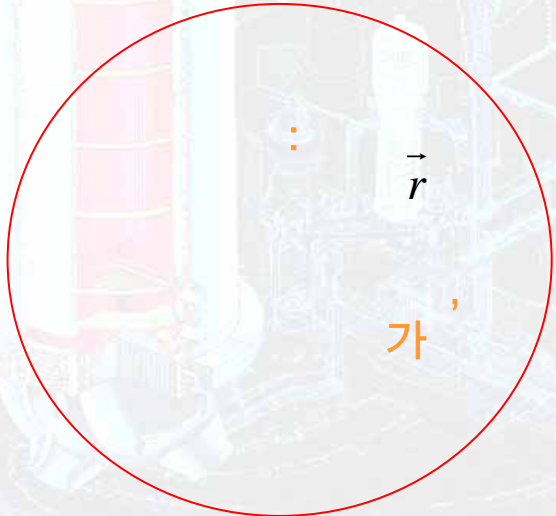
(III)



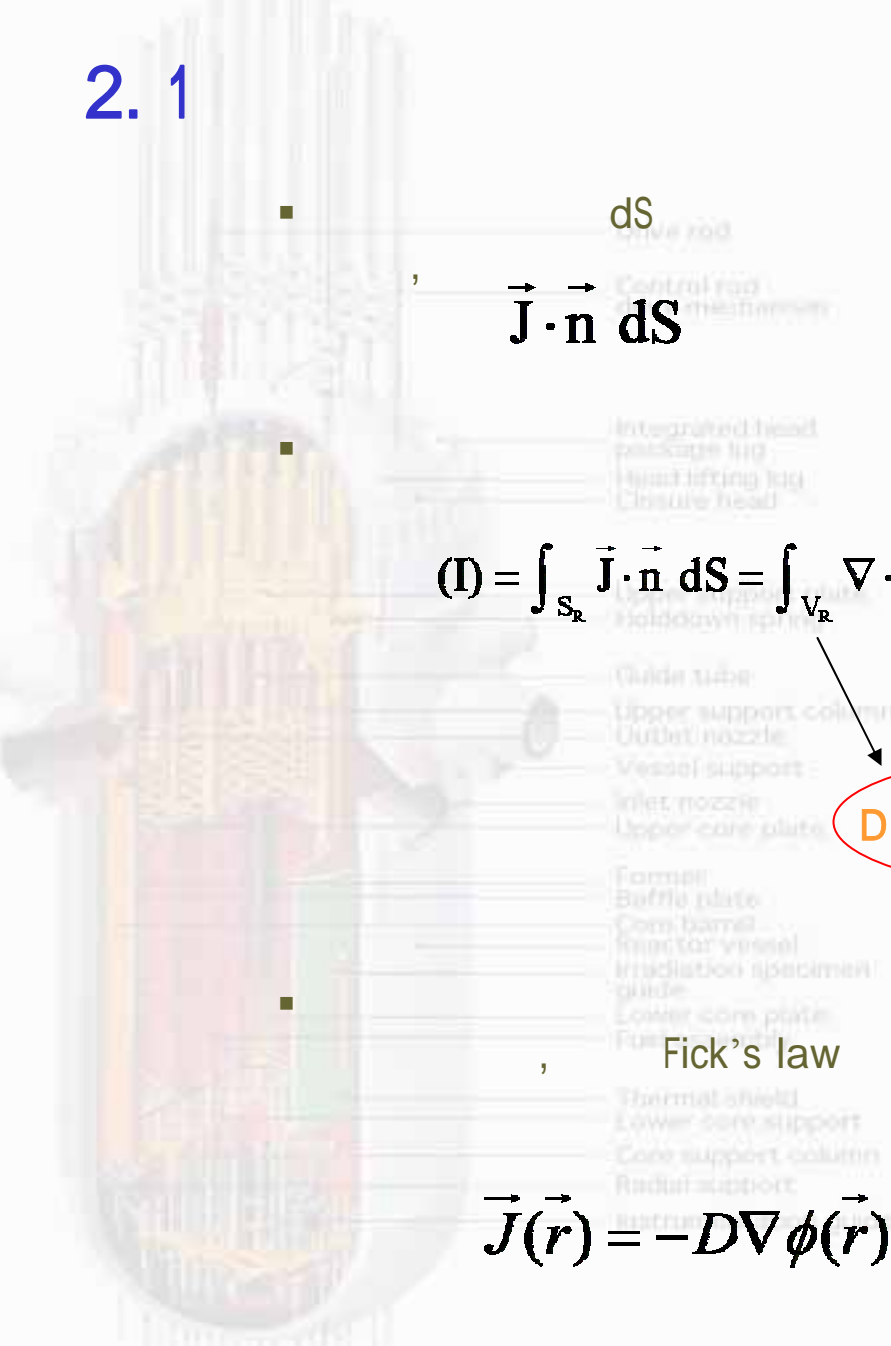
Former  
Baffle plate  
Core barrel  
Inlet vessel  
Inlet station specimen  
guide



5.3



# 2.1

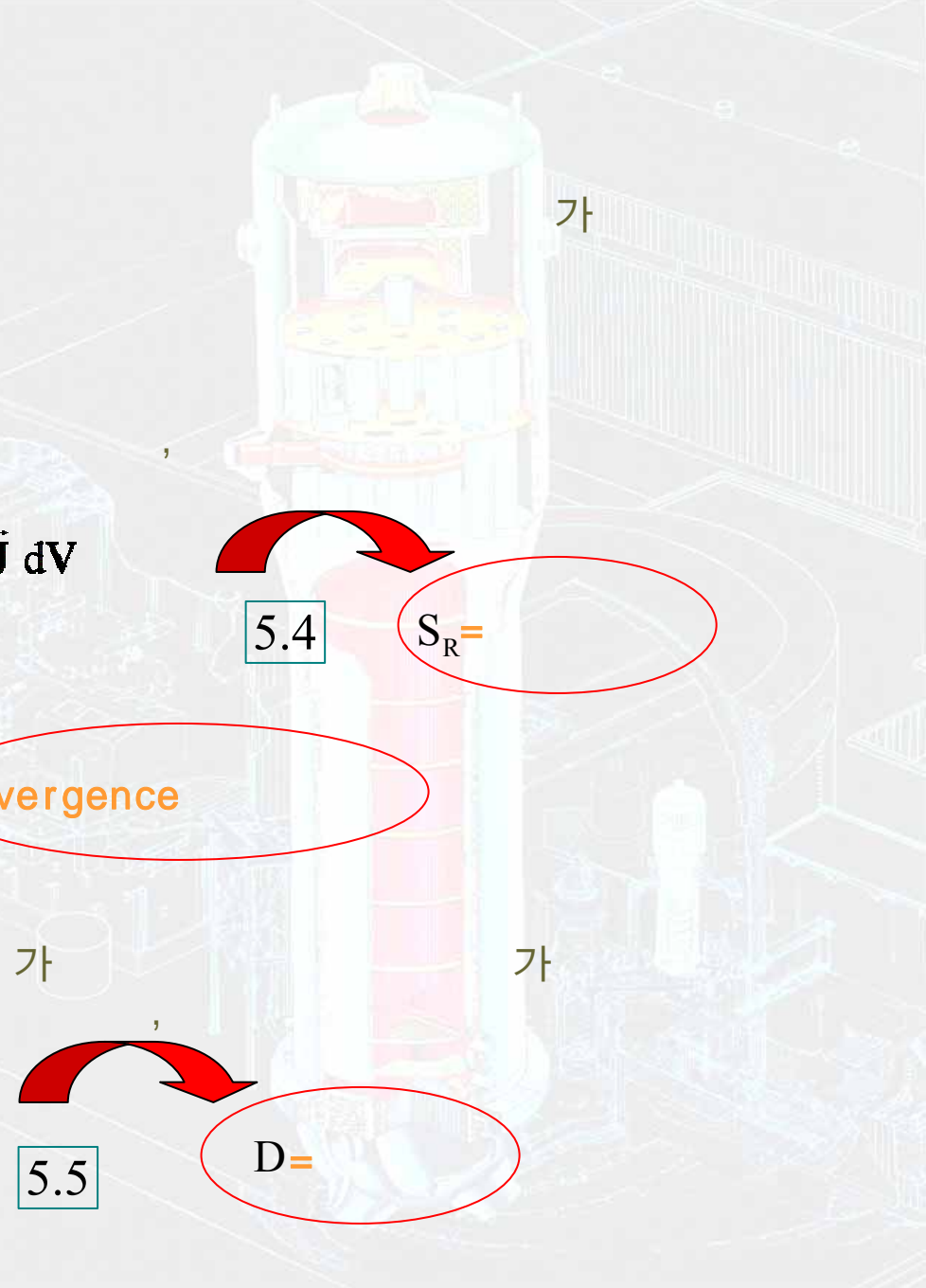


$$\vec{J} \cdot \vec{n} \, dS$$

$$(I) = \int_{S_R} \vec{J} \cdot \vec{n} \, dS = \int_{V_R} \nabla \cdot \vec{J} \, dV$$

Divergence

$$\vec{J}(\vec{r}) = -D \nabla \phi(\vec{r})$$



5.4

$S_R =$

5.5

$D =$



# 2.1

(5.5) Drive rod  
(5.4) 가  
Control rod  
drive mechanism

$$(I) = -\int_{V_R} \nabla \cdot D \nabla \phi(\vec{r}) dV \quad 5.6$$

$$(II) = \int_{V_R} \Sigma_a \phi(\vec{r}) dV \quad 5.7$$

$$(III) = \int_{V_R} v \epsilon p L_f \Sigma_f \phi(\vec{r}) dV \quad 5.8$$

$\Sigma_f \phi(\vec{r}) =$   
 $V =$   
 $\epsilon =$   
 $p =$   
 $L_f =$





# 2.1

- (5.6)~(5.8)

$$-\int_{V_R} \nabla \cdot D \nabla \phi(\vec{r}) dV + \int_{V_R} \Sigma_a \phi(\vec{r}) dV = \int_{V_R} \nu \epsilon p L_f \Sigma_f \phi(\vec{r}) dV \quad 5.9$$

- (5.9)

$$-\nabla \cdot D \nabla \phi(\vec{r}) + \Sigma_a \phi(\vec{r}) = \nu \epsilon p L_f \Sigma_f \phi(\vec{r}) \quad 5.10$$

- (5.10) 1

□ 1

- 

$$\phi(\hat{r}_s) = 0 \quad 5.11$$

$\hat{r}_s =$



# 2.1

$$\hat{r}_s = \vec{r}_s + d \quad 5.12$$

$$d = 0.71\lambda_{tr} \quad 5.13$$

$$D = \frac{1}{3}\lambda_{tr} \quad 5.14$$

$$\lambda_{tr} = \frac{1}{\frac{\Sigma_{tr}}{1} + \frac{1}{\Sigma_s \cdot (1 - \overline{\mu}_0)}} \quad 5.15$$

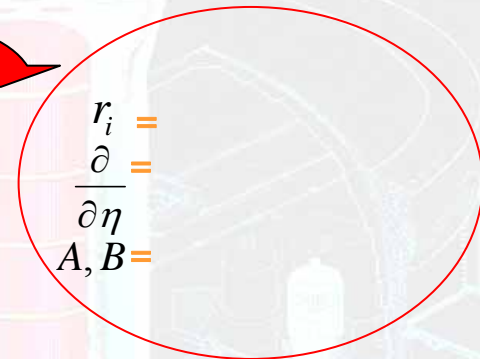


# 2.1

- Drive rod
- (Control rod drive mechanism)
- 가 가
- Integrated head package lig
- Head lifting lig
- Closure head

$$\phi_A(r_i) = \phi_B(r_i) \quad 5.16a$$

$$-D_A \frac{\partial \phi_A(r_i)}{\partial \eta} = -D_B \frac{\partial \phi_B(r_i)}{\partial \eta} \quad 5.16b$$



- (5.10)  $D, \Sigma_a, \Sigma_f$
- Thermal shield
- Lower core support
- $D, \Sigma_a, \Sigma_f$
- Instrumentation guide



# 2.1

- $$-D \nabla^2 \phi = -D \nabla^2 \phi \quad (5.10)$$

$$-\nabla \cdot D \nabla \phi = -D \nabla^2 \phi$$

(5.10)

- $$-D \cdot \nabla^2 \phi(\vec{r}) + \Sigma_a \phi(\vec{r}) = v \epsilon p L_f \Sigma_f \phi(\vec{r}) \quad 5.17$$

(5.17)

$$\nabla^2 \phi(\vec{r}) + \frac{v \epsilon p L_f \Sigma_f - \Sigma_a}{D} \phi(\vec{r}) = 0 \quad 5.18a$$

$$\nabla^2 \phi(\vec{r}) + B^2 \phi(\vec{r}) = 0 \quad 5.18b$$

$$B^2 = \frac{v \epsilon p L_f \Sigma_f - \Sigma_a}{D} \quad 5.19$$

# 2.1



(5.17)

$$\nabla^2$$

(Laplacian)

- 5.1

	<p>Drive rod Control rod drive mechanism</p>	$(\nabla^2)$
	<p>Upper support plate, Hold-down spring Guide tube Upper support column Guide nose Vessel support</p> <p><math>P(x,y,z)</math></p>	$\nabla^2 = \frac{\partial^2}{\partial X^2} + \frac{\partial^2}{\partial Y^2} + \frac{\partial^2}{\partial Z^2}$
	<p>Upper plate Former Baffle plate Core barrel Reactor vessel Inner former Inner plate</p> <p><math>p(r, \phi, z)</math></p>	$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial Z^2}$
	<p>Thermal shield Lower core support Core support Radial support Neutron absorption guide</p> <p><math>p(r, \theta, \phi)</math></p>	$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$



# 3.

## ➤ 3.1



## 5.2

Drive rod  
Control rod  
drive mechanism

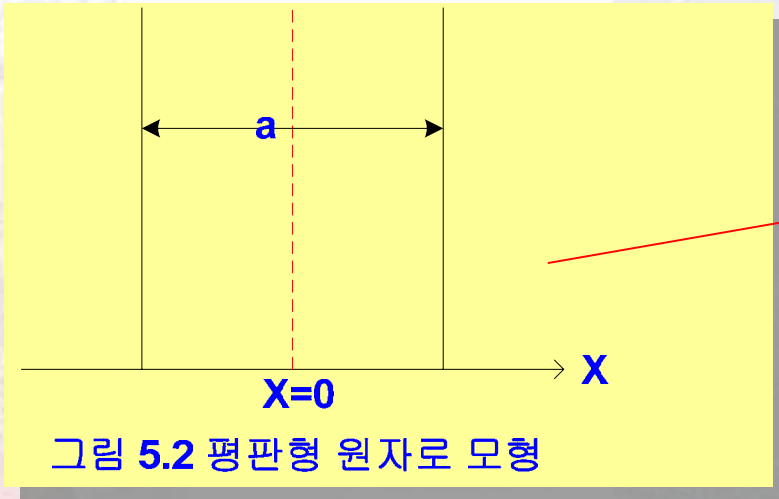
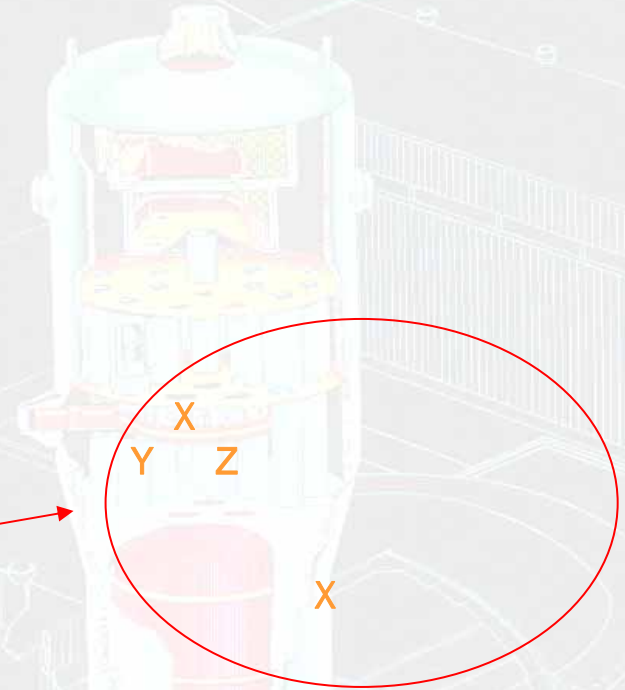


그림 5.2 평판형 원자로 모형

(5.18)

$$\frac{d\phi(\vec{r})}{dX^2} + B^2\phi(\vec{r}) = 0$$

5.20



### 3.

▪ (5.20)

$$\phi(x) = A \cos Bx + C \sin Bx$$

▪ A C

$$\phi(x) = \phi(-x)$$

$$2C \sin Bx = 0$$

$$\phi\left(\pm \frac{\hat{a}}{2}\right) = 0$$

$$\phi\left(\pm \frac{\hat{a}}{2}\right) = A \cdot \cos B\left(\pm \frac{\hat{a}}{2}\right) = 0$$

$$, \hat{a} = a + 2d$$

5.21

(5.21)

C=0

5.22



# 3.

(5.22)

A 가

$$\cos B\left(\pm \frac{\hat{a}}{2}\right) = 0$$

$$\frac{B\hat{a}}{2} = \frac{n\pi}{2}$$

$$B_n = \frac{n\pi}{\hat{a}} \quad (n = 1, 3, 5, 7, \dots) \quad \boxed{5.23}$$

- (5.18)  $n = 1, 3, 5, 7, \dots$

- $B_1, B_3, \dots$  (5.20)

- $\varphi_n(x) = \cos B_n x \quad (n = 1, 3, 5, \dots)$

(Eigenvalue)

(Eigenfunction)

(5.20)

가  
,  $B_3$

$B_3$

$B_1$

(5.20)



3.

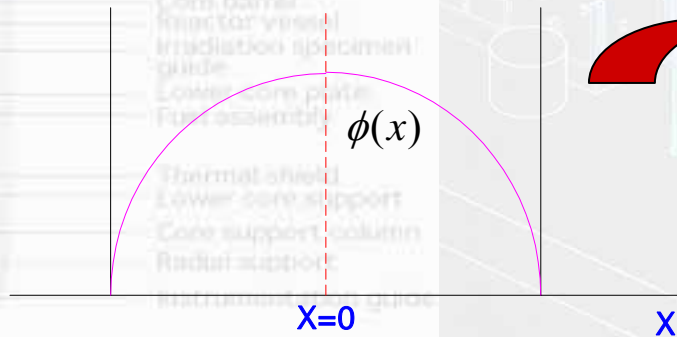
$$B_1^2 = \left(\frac{\pi}{\hat{a}}\right)^2$$

$$B_g^2 = B_1^2 = \left(\frac{\pi}{\hat{a}}\right)^2$$

5.24

$$\phi(x) = A \cdot \cos Bx = A \cdot \cos \frac{\pi x}{\hat{a}}$$

5.25



$(B_g^2)$

( ) ,

5.3

가  
가  
가



3.

(5.25) Drive rod  
 Core rod drive mechanism

(5.2) Integrated head package lig  
 Head lifting lig  
 Closure head

$$P = \int_{-a/2}^{a/2} P(x) dx \quad 5.26$$

Upper support plate  
 Holddown spring  
 Upper support col  
 Outlet nozzle  
 Vessel support :  
 Inlet nozzle  
 Upper core plate  
 Former (d=0) (5.26)

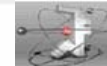
$$A = \frac{\pi P}{2\alpha k \epsilon \Sigma_f} \quad 5.27$$

Baffle plate  
 Core barrel  
 Reactor vessel  
 Irradiation specimen  
 Lower core plate  
 Lower core support  
 Core support column  
 Radial support  
 Instrumentation guide



$$P(x) = \kappa \epsilon \Sigma_f \phi(x)$$

A



# 3.

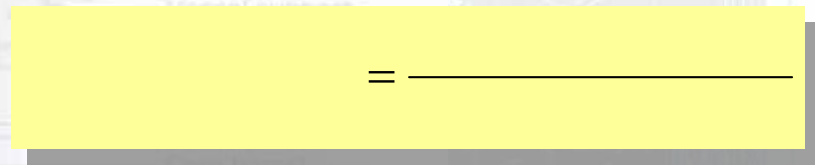


(5.25)

가 cosine

가

가



5.28

$$\bar{P} = \frac{P}{a} = \frac{1}{a} \int_{-\frac{a}{2}}^{\frac{a}{2}} P(x) dx = \frac{2\kappa\epsilon\Sigma_f A}{\pi} \cdot \frac{\hat{a}}{a} \sin \frac{\pi a}{2\hat{a}}$$

5.29



3.

$$P_{\max} = P(0) = \kappa \epsilon \Sigma_f A \quad 5.30$$

$$P_f = \frac{\frac{\pi}{2} \cdot \frac{a}{\hat{a}}}{\sin \frac{\pi a}{2 \hat{a}}} \quad 5.31$$

$$P_f = \frac{\pi}{2} \cong 1.57 \quad 5.32$$

$x=0$

$P_f$

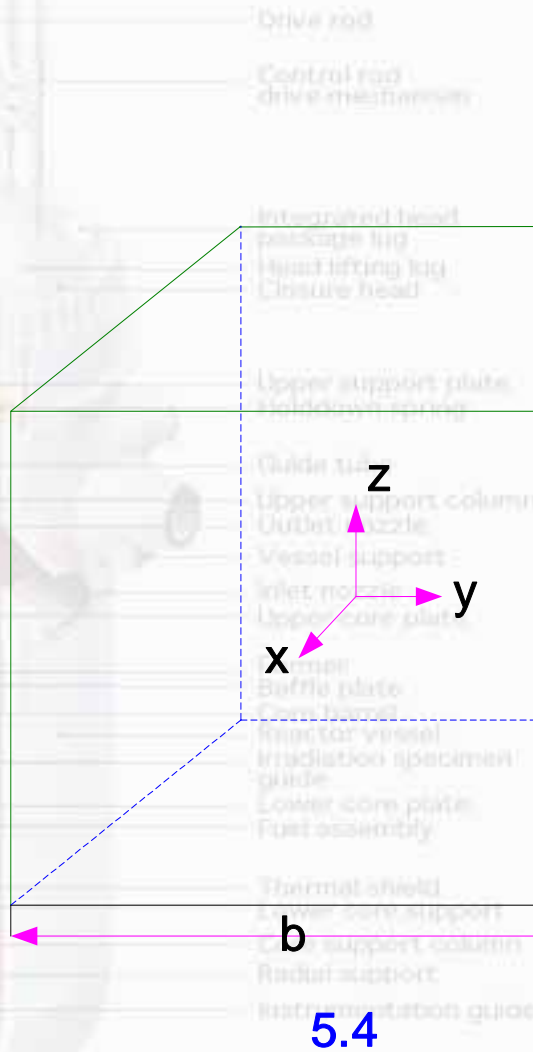


# 3.

## ➤ 3.2

□ 3

가



5.4



# 3.



가

$$\frac{\partial^2 \phi(x, y, z)}{\partial x^2} + \frac{\partial^2 \phi(x, y, z)}{\partial y^2} + \frac{\partial^2 \phi(x, y, z)}{\partial z^2} + B^2 \phi(x, y, z) = 0 \quad 5.33$$

가

$$\phi\left(\pm \frac{\hat{a}}{2}, y, z\right) = \phi\left(x, \pm \frac{\hat{b}}{2}, z\right) = \phi\left(x, y, \pm \frac{\hat{c}}{2}\right) = 0 \quad 5.34$$



$$\begin{aligned} \hat{a} &= a + 2d \\ \hat{b} &= b + 2d \\ \hat{c} &= c + 2d \end{aligned}$$

$$5.35$$



# 3.

▪ (5.33) 3

•

$$\phi(x, y, z) = X(x)Y(y)Z(z) \quad 5.36$$

• (5.36) (5.33)

$$\frac{1}{X(x)} \frac{d^2 X(x)}{dx^2} + \frac{1}{Y(y)} \frac{d^2 Y(y)}{dy^2} + \frac{1}{Z(z)} \frac{d^2 Z(z)}{dz^2} + B^2 = 0 \quad 5.37$$

• (5.37)

B

x,y,z

B



# 3.

Drive rod

$$\frac{1}{X(x)} \frac{d^2}{dx^2} X(x) = -\alpha^2$$

Integrated head

$$\frac{1}{Y(y)} \frac{d^2}{dy^2} Y(y) = -\beta^2$$

Upper support plate

$$\frac{1}{Z(z)} \frac{d^2}{dz^2} Z(z) = -\gamma^2$$

(5.37)

$$\alpha^2 + \beta^2 + \gamma^2 = B^2 \quad (5.39)$$

Former

Baffle plate

Core barrel

Shield for vessel

Shield for vessel

Lower core plate

Fuel assembly

Thermal shield

Lower core support

Core support column

Radial support

Instrumentation guide

5.38

가





3.

(5.34)

$$X(x) = A_1 \cos \alpha x$$

$$Y(y) = A_2 \cos \beta y$$

$$Z(z) = A_3 \cos \gamma z$$

$$\alpha = \frac{\pi}{\hat{a}}, \beta = \frac{\pi}{\hat{b}}, \gamma = \frac{\pi}{\hat{c}} \quad (5.41)$$

• (5.40)  $A_1, A_2, A_3$

(5.40) (5.36)

5.40

# 3.

$$\phi(x, y, z) = A \cos \frac{\pi}{\hat{a}} x \cos \frac{\pi}{\hat{b}} y \cos \frac{\pi}{\hat{c}} z \quad 5.42$$

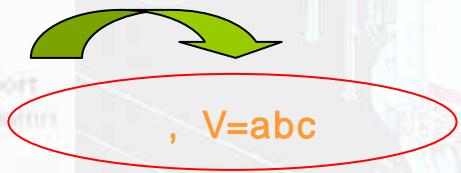


$$B^2 = \left(\frac{\pi}{\hat{a}}\right)^2 + \left(\frac{\pi}{\hat{b}}\right)^2 + \left(\frac{\pi}{\hat{c}}\right)^2 \quad (5.39) \quad (5.41)$$

$$B_g^2 = \left(\frac{\pi}{\hat{a}}\right)^2 + \left(\frac{\pi}{\hat{b}}\right)^2 + \left(\frac{\pi}{\hat{c}}\right)^2 \quad 5.43$$

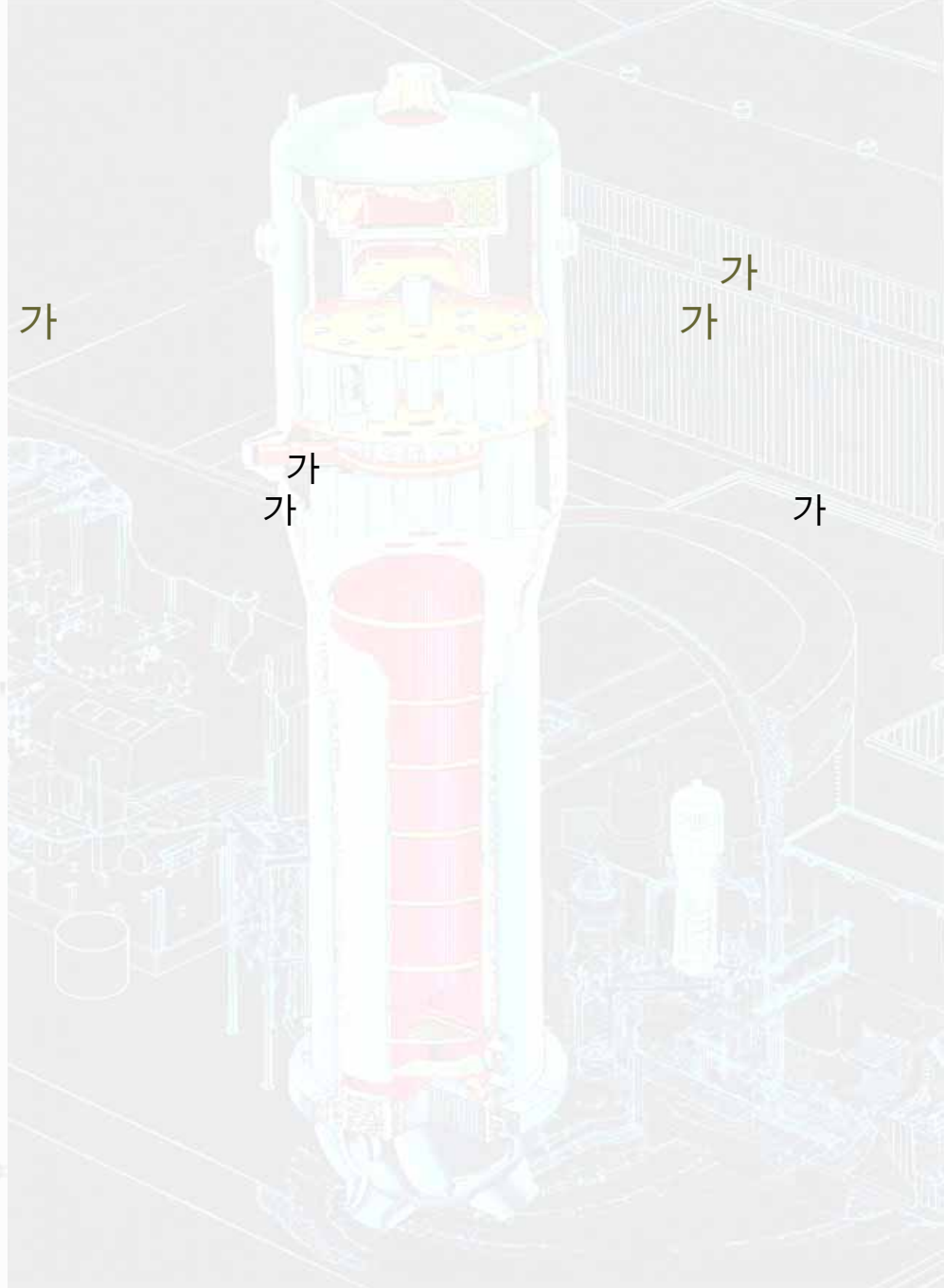
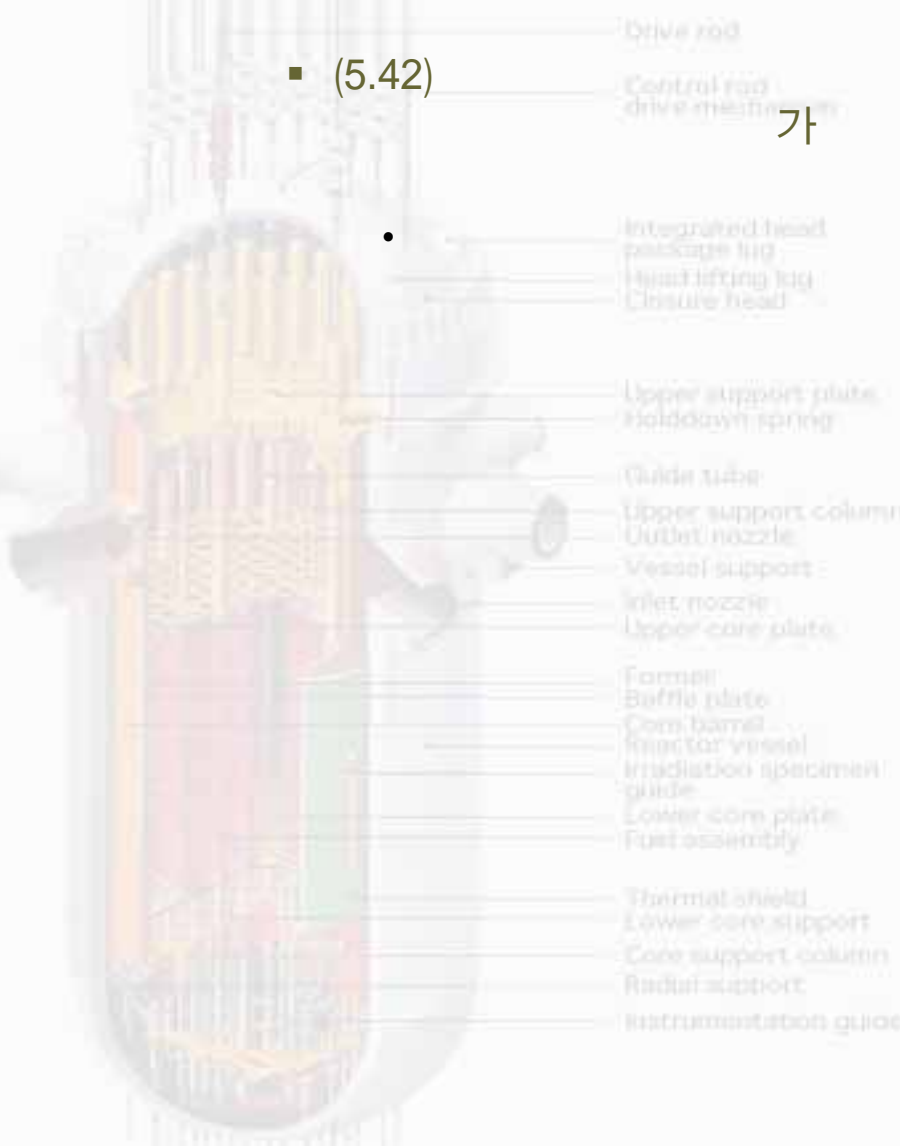
$$(5.42) \quad A$$

$$A = \frac{\pi^3 P}{8V \kappa \epsilon \Sigma_f} \quad 5.44$$



# 3.

▪ (5.42)



# 3.

## ➤ 3.3

□ R

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \phi(r)}{\partial r} \right) + B^2 \phi(r) = 0 \quad (5.45)$$

$$\phi(\hat{R}) = 0 \quad (5.46)$$



$$\hat{R} = R + d$$

□ (5.45)

▪  $\phi(r) = U(r)/r$

$U(r)$

$$\frac{d^2 U(r)}{dr^2} + B^2 U(r) = 0 \quad (5.47)$$



3.

$$U(r) = A \sin Br + C \cos Br \quad 5.48$$

, A C

$$\phi(r) = A \frac{\sin Br}{r} + C \frac{\cos Br}{r} \quad 5.49$$

(5.49)  
가

r=0가  
C=0

$$\phi(\hat{R}) = 0$$

$$B_n = \frac{n\pi}{\hat{R}} \quad 5.50$$

, n

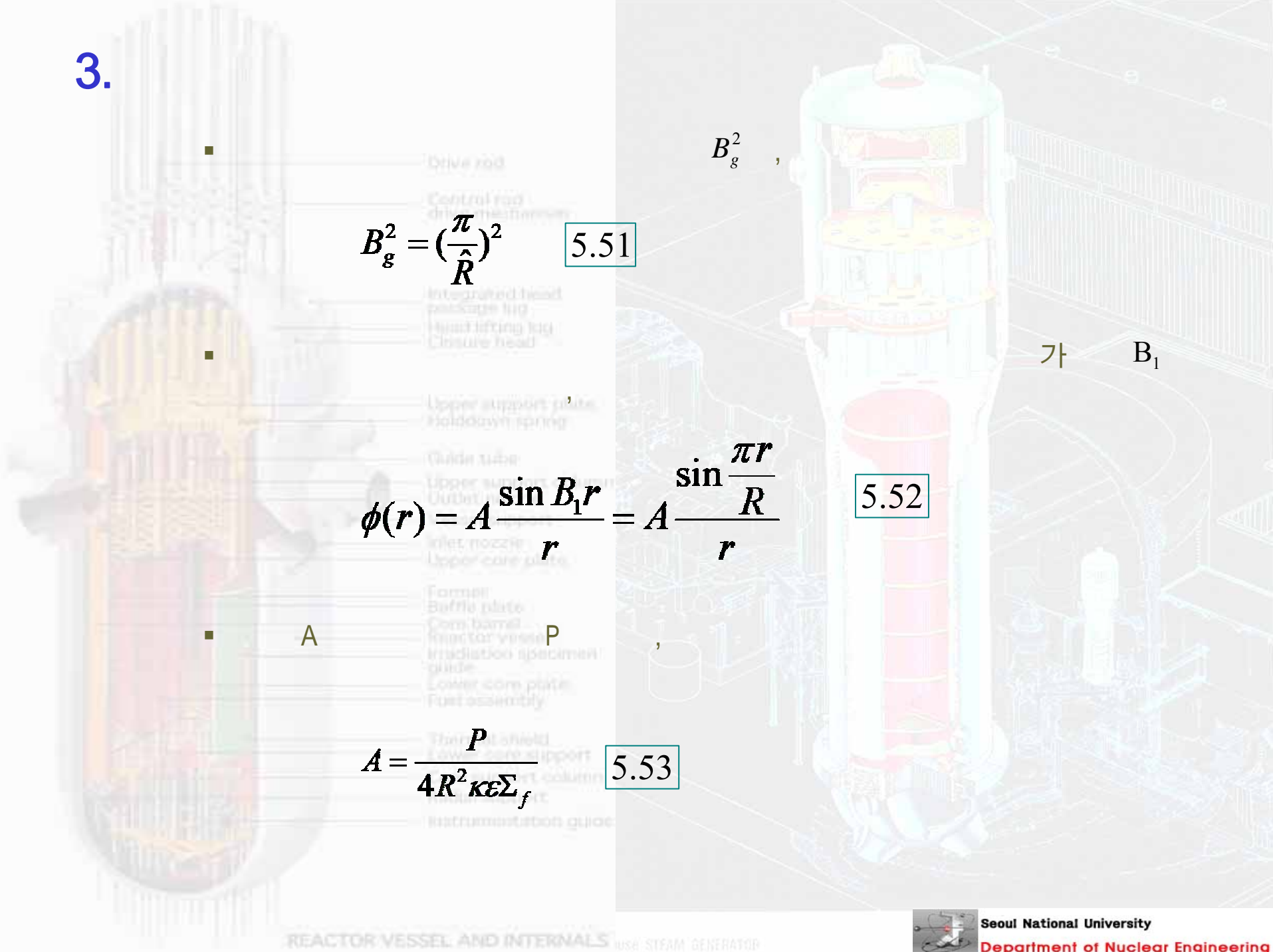


3.

$$B_g^2 = \left(\frac{\pi}{\hat{R}}\right)^2 \quad 5.51$$

$$\phi(r) = A \frac{\sin B_1 r}{r} = A \frac{\sin \frac{\pi r}{R}}{r} \quad 5.52$$

$$A = \frac{P}{4R^2 k \epsilon \Sigma_f} \quad 5.53$$

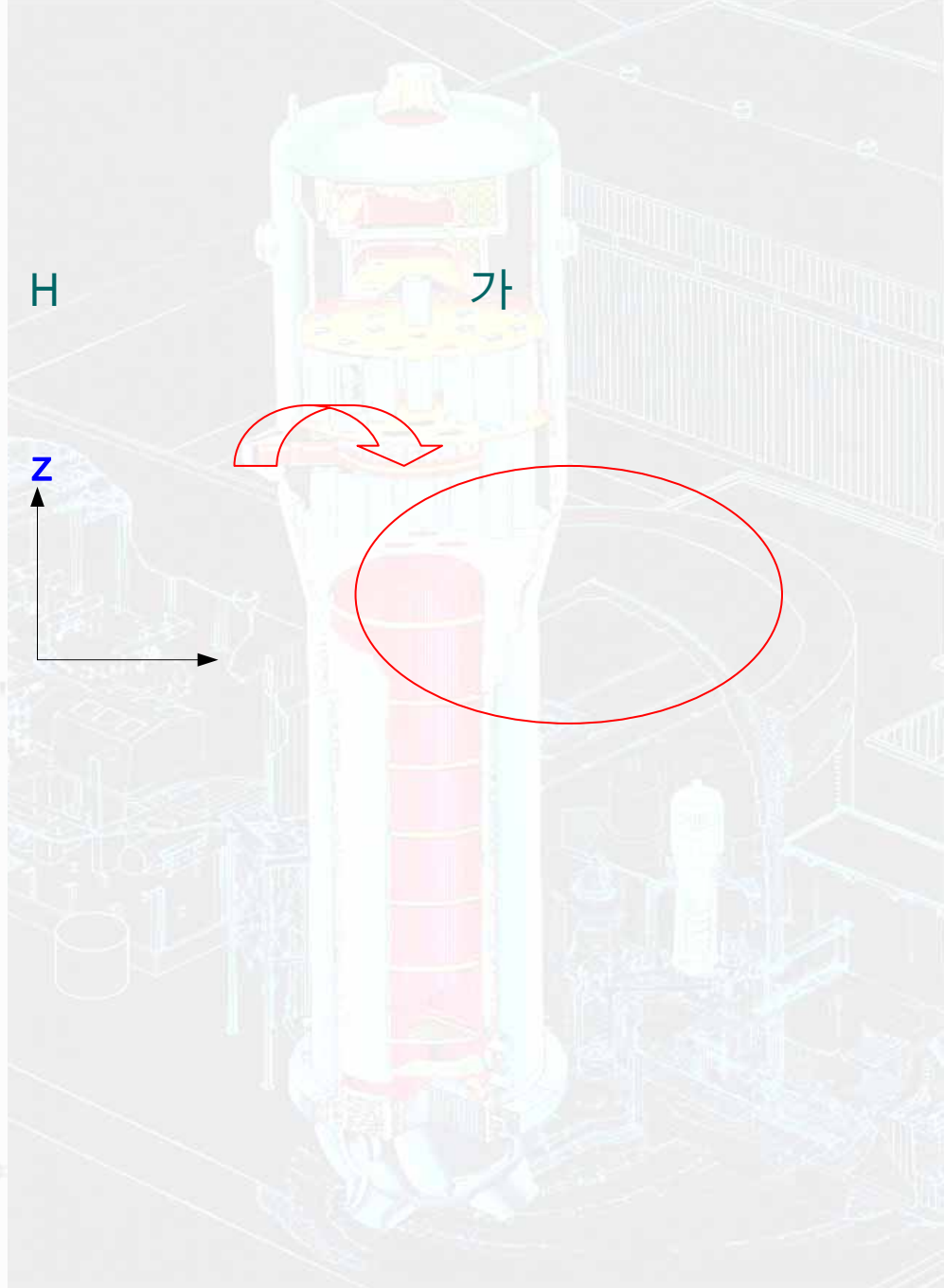
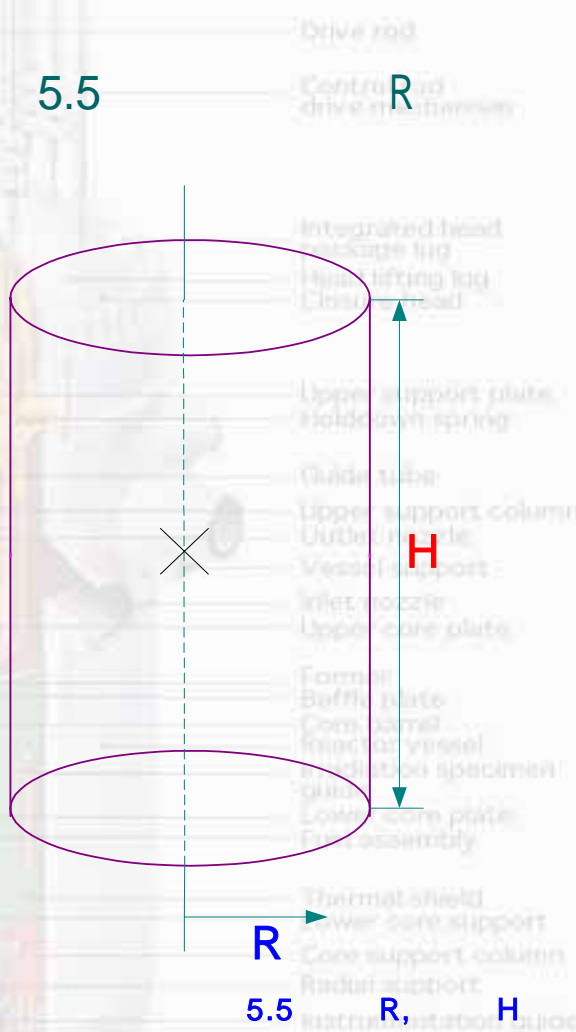


# 3.

## ➤ 3.4



5.5



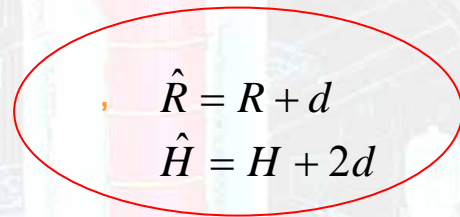
# 3.



$$\frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial^2 \phi(r, z)}{\partial r} \right) + \frac{\partial^2 \phi(r, z)}{\partial z^2} + B^2 \phi(r, z) = 0 \quad 5.54$$



$$\phi(\hat{R}, Z) = \phi\left(r, \pm \frac{\hat{H}}{2}\right) = 0 \quad 5.55$$



$$\phi(r, z) = R(r) \cdot Z(z) \quad 5.56$$





### 3.

▪ (5.56) (5.54)

$$\frac{1}{rR(r)} \frac{d}{dr} \left( r \frac{dR(r)}{dr} \right) + \frac{1}{Z(z)} \frac{d^2 Z(z)}{dz^2} + B^2 = 0$$

(5.56)

$B^2$

$$\frac{1}{rR(r)} \frac{d}{dr} \left( r \frac{dR(r)}{dr} \right) = -\alpha^2$$

5.57a

$$\frac{1}{Z(z)} \frac{d^2 Z(z)}{dz^2} = -\beta^2$$

5.57b

$$\alpha^2 + \beta^2 = B^2$$

5.58

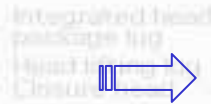


# 3.

- (5.57a) Bessel

$$R(r) = AJ_0(\alpha r) + CY_0(\alpha r) \quad 5.59$$

- (5.59)



$$Y_0(\alpha r) \quad r=0 \quad C=0 \quad (5.57)$$

- $R(r) = J_0(\alpha r)$

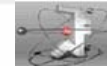
- $\alpha$

$$AJ_0(\alpha \hat{r}) = 0$$

$$\alpha = \frac{2.405}{\hat{R}} \quad 5.60$$

- (5.57b)

$$Z(z) = A' \cdot \cos \beta z = A' \cos \frac{\pi z}{\hat{H}} \quad 5.61$$



3.

$$\phi(r, z) = AJ_0\left(\frac{2.405}{\hat{R}}r\right) \cos\frac{\pi z}{\hat{H}} \quad 5.62$$

$$B_g^2 = \left(\frac{2.405}{\hat{R}}r\right)^2 + \left(\frac{\pi}{\hat{H}}\right)^2 \quad 5.63$$

$$A = \frac{2.405\pi P}{4V\kappa\epsilon\Sigma_f J_1(2.405)} = \frac{3.63P}{V\kappa\epsilon\Sigma_f} \quad 5.64$$



# 3.

## 5.2

### 5.2

Integrated head package (IG) Head lifting lug Closure head		$B_g^2$
Upper support plate Hold-down spring Guide tube Upper support column Guide tube	$(\frac{\pi}{a})^2$	$\phi_0 \cos(\frac{\pi}{a} x)$
Vessel support Inlet nozzle Upper core plate Former Fuel plate	$(\frac{\pi}{a})^2 + (\frac{\pi}{b})^2 + (\frac{\pi}{c})^2$	$\phi_0 \cos(\frac{\pi}{a} x) \cos(\frac{\pi}{b} y) \cos(\frac{\pi}{c} z)$
Core barrel Reactor vessel Radiation specimen guide Lower core plate Fuel assembly	$(\frac{\pi}{R})^2$	$\frac{\phi_0}{r} \sin(\frac{\pi r}{R})$
Thermal shield Lower core plate Core support Radial support Instrumentation guide	$(\frac{2.405}{\hat{R}} r)^2 + (\frac{\pi}{\hat{H}})^2$	$\phi_0 J_0(\frac{2.405}{\hat{R}} r) \cos \frac{\pi z}{\hat{H}}$

3.



5.6

1.0

0.5

0.0

0.5

1.0

- Drive rod
- Control rod drive mechanism
- Integrated head penetrator lig
- Head injection lig
- Pressure head
- Upper support plate
- Holddown spring
- Guide tube
- Upper support column
- Outlet nozzle
- Vessel support
- Inlet nozzle
- Upper core plate
- Former
- Baffle plate
- Core barrel
- Reactor vessel
- radiation specimen guide
- Lower core plate
- Fuel assembly
- Thermal shield
- Lower core support
- Core support column
- Radial support
- Instrumentation guide

5.6

