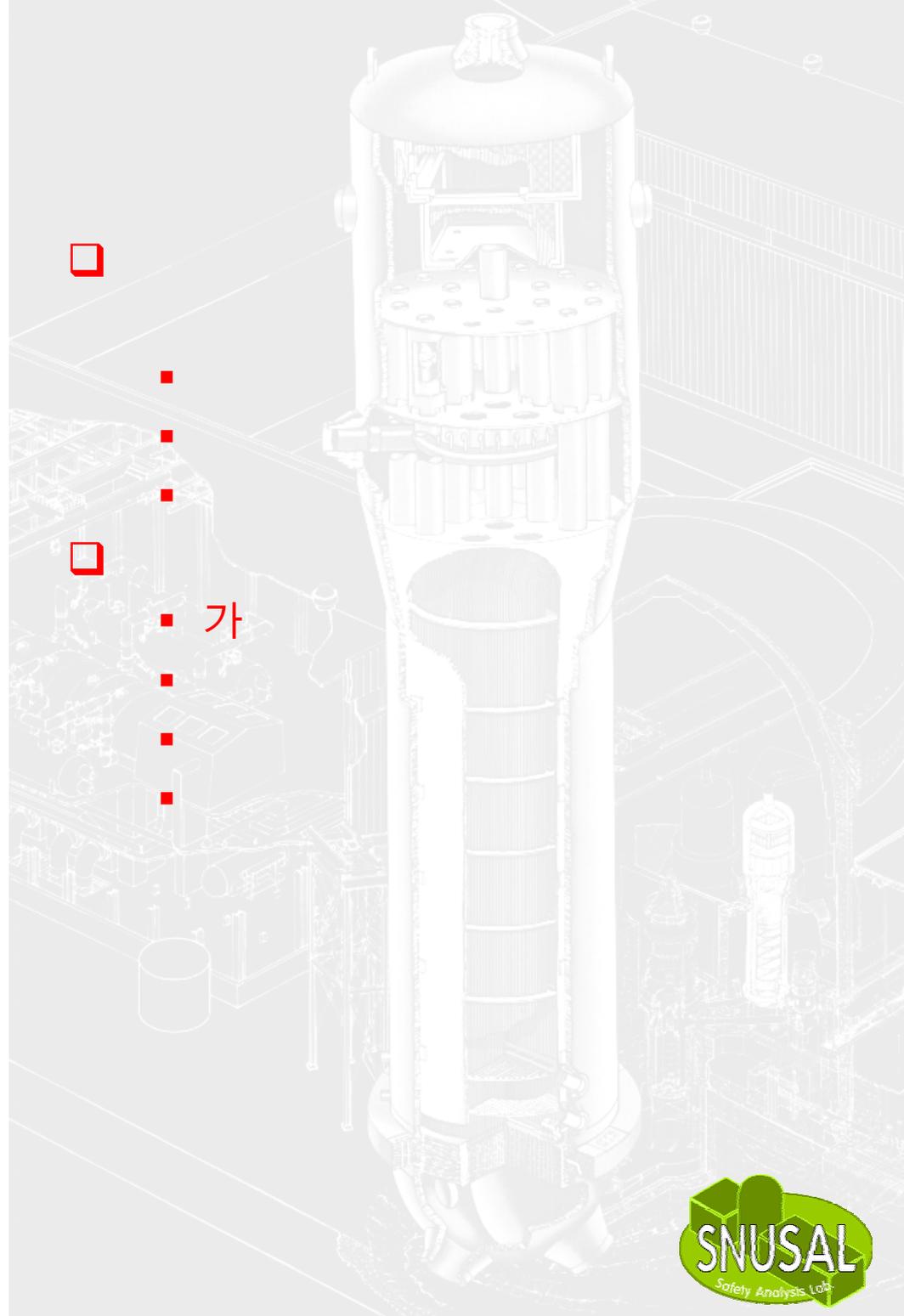
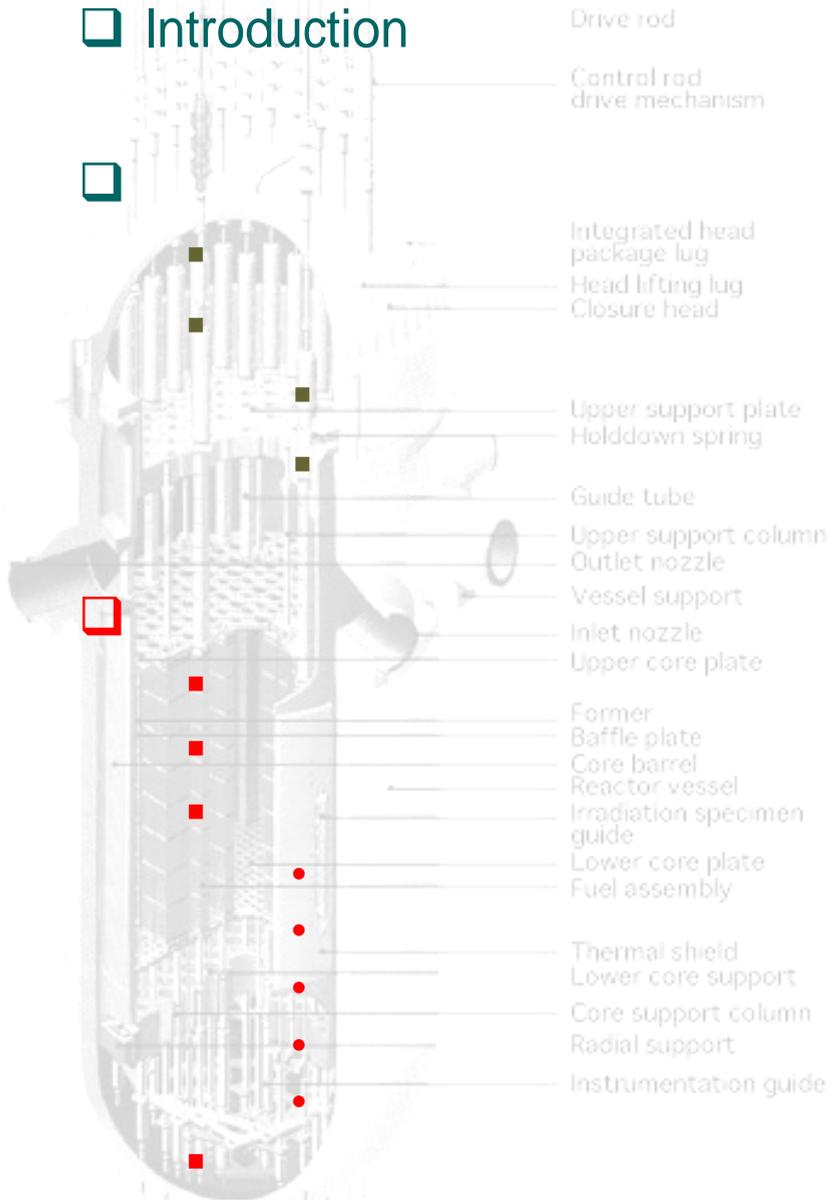


CHAPTER 6-2

U. C . Lee

➤ CHAPTER 6.

□ Introduction



3.

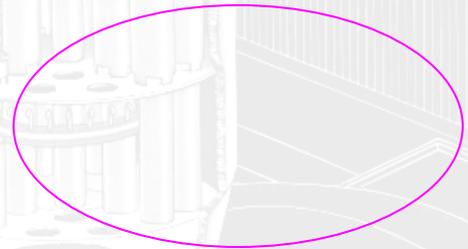
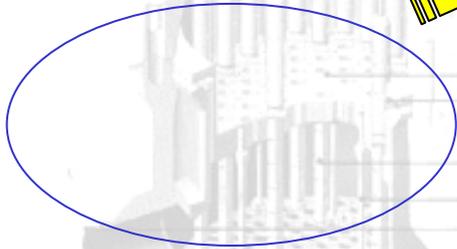
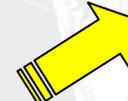
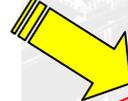
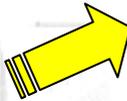
➤ 3.1.

(Feedback effect)



(Drive rod Control rod drive mechanism)

Integrated head package lug
Head lifting lug
Closure head



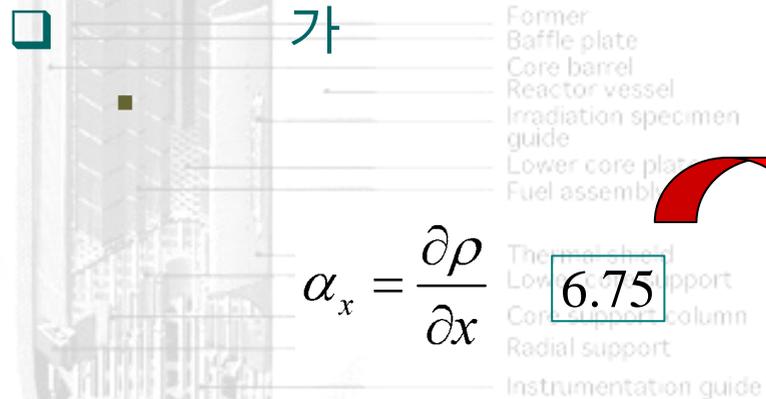
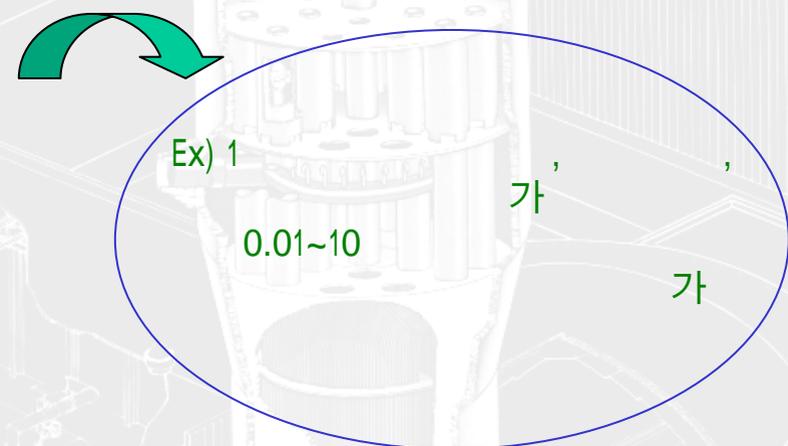
- Upper support plate
- Holddown spring
- Guide tube
- Upper support column
- Outlet nozzle
- Vessel support
- Inlet nozzle
- Upper core plate
- Former
- Baffle plate (6.35)
- Core barrel
- Reactor vessel
- Irradiation specimen guide
- Lower core plate
- Fuel assembly
- Thermal shield
- Lower core support
- Core support column
- Radial support
- Instrumentation guide



3.

6.4

	Drive rod	X	
	Control rod drive mechanism		
1	P	0.01~0.1	
	Integrated heat package lug	0.05~0.1	
	Head lifting lug		
	Closure head	T_f	0.1~10
	Upper support plate	T_m	0.1~1000
	Hold-down spring		
Xe Sm	Guide tube	X_e, S_m	10
	Upper support column		
	Outer nozzle		
	Vessel support	B	1~10
	Inlet nozzle		
	Upper support		

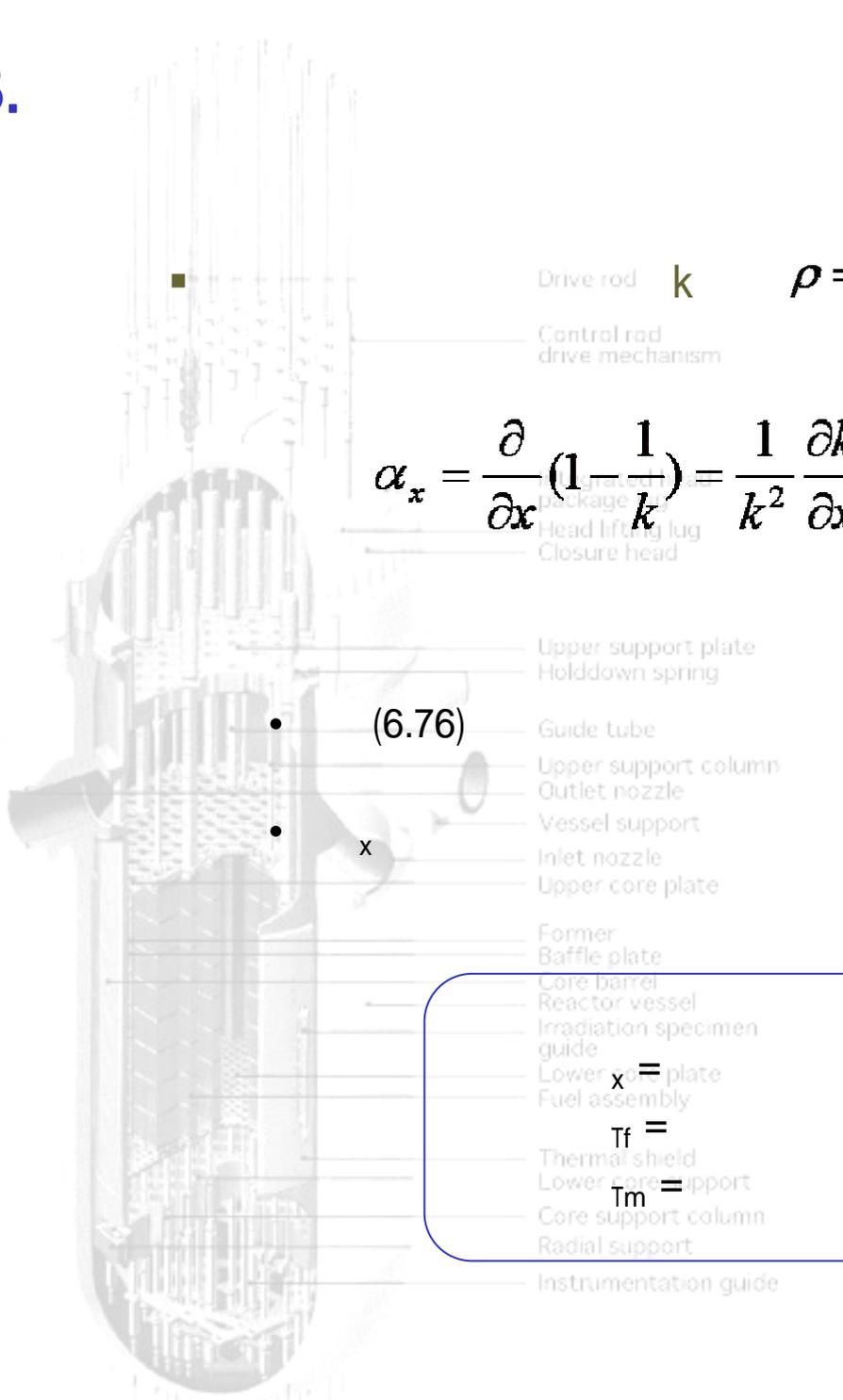


$$\alpha_x = \frac{\partial \rho}{\partial x}$$

6.75

$$x = X = X$$

3.



Drive rod k

$$\rho = (k-1)/k$$

$$\alpha_x = \frac{\partial}{\partial x} \left(1 - \frac{1}{k} \right) = \frac{1}{k^2} \frac{\partial k}{\partial x} \cong \frac{1}{k} \frac{\partial k}{\partial x} \quad 6.76$$

(6.76)

가

k 가 1

3.

3.2

가

가

Drive rod
Control rod drive mechanism

Integrated head package lug
Head lifting lug
Closure head

Upper support plate
Hold down spring
Support column
Outlet nozzle

Vessel support
Jet nozzle

Core support plate
Core barrel
Reactor vessel

Irradiation specimen guide
Lower core plate
Fuel assembly

Lower core support
Core support column
Radial support
Instrumentation guide

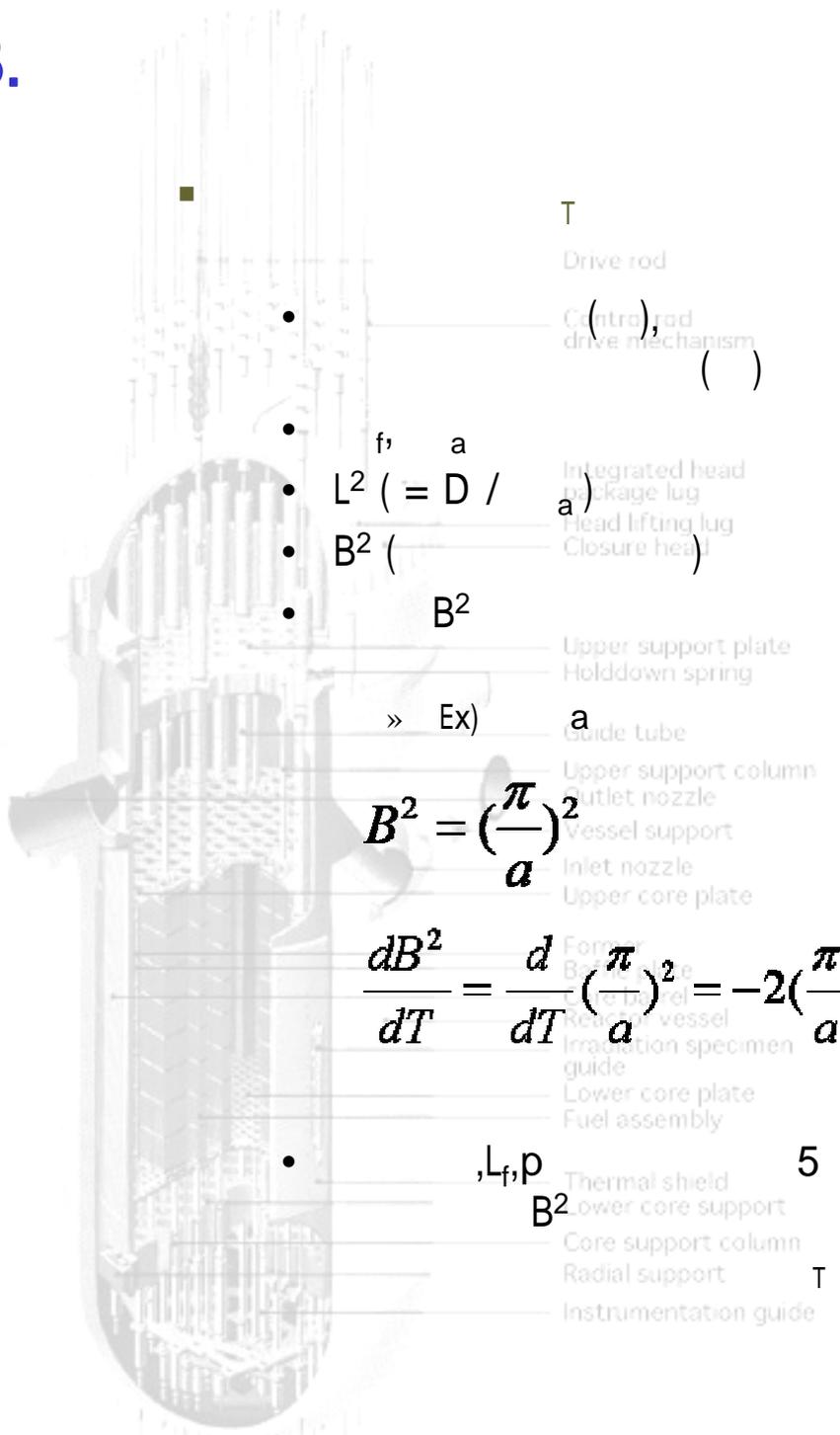
$$k = \frac{\epsilon P L_f v \Sigma_f / \Sigma_a}{1 + L^2 B^2}$$

$$\alpha_T = \frac{1}{k} \frac{\partial k}{\partial T} \quad 6.77$$

$$\alpha_T = \frac{1}{\epsilon} \frac{\partial \epsilon}{\partial T} + \frac{1}{L_f} \frac{\partial L_f}{\partial T} + \frac{1}{P} \frac{\partial P}{\partial T} + \frac{1}{v} \frac{\partial v}{\partial T} + \frac{1}{\Sigma_f} \frac{\partial \Sigma_f}{\partial T} - \frac{1}{\Sigma_a} \frac{\partial \Sigma_a}{\partial T} - \frac{1}{1 + L^2 B^2} \frac{\partial}{\partial T} (1 + L^2 B^2)$$

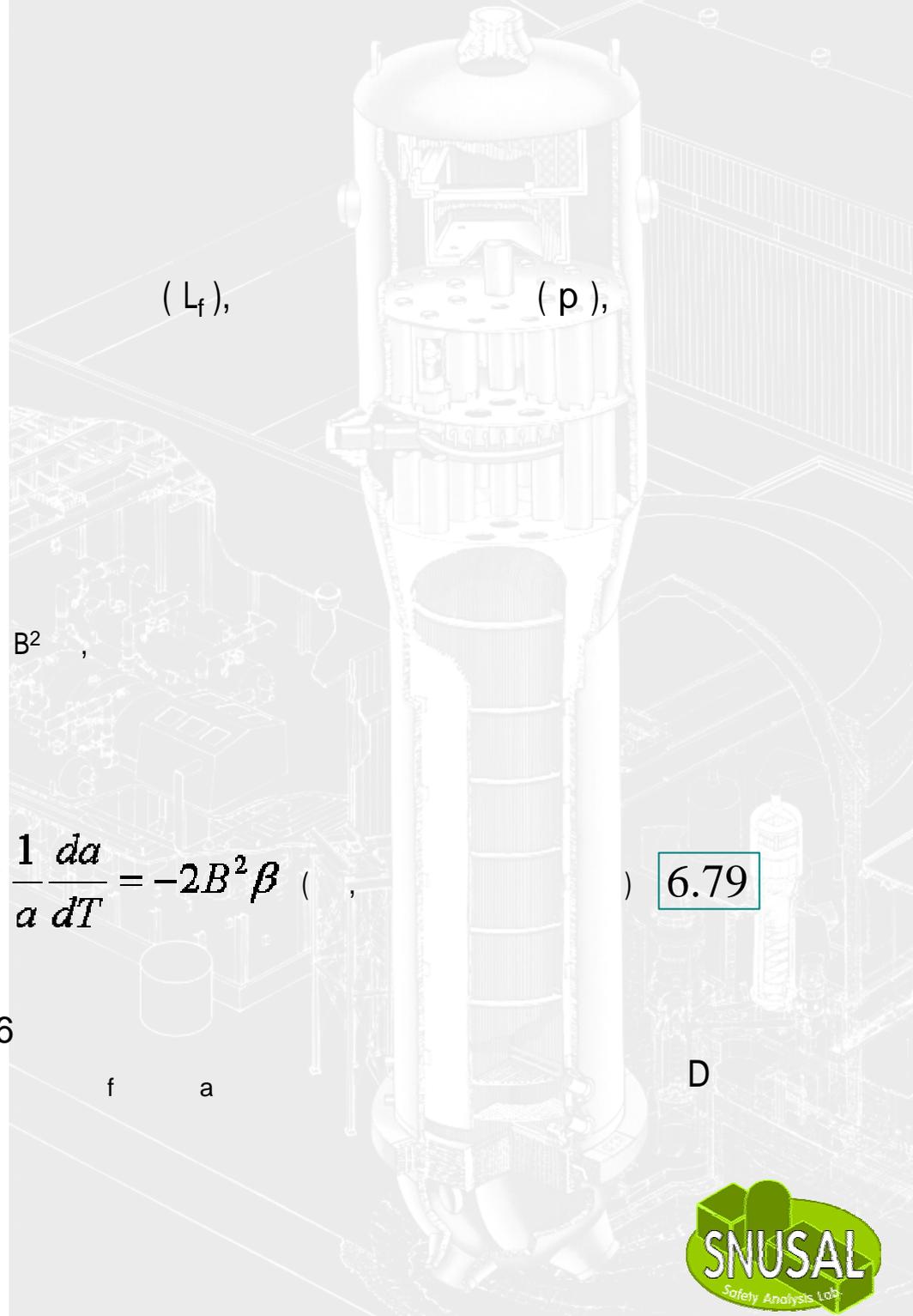
6.78

3.



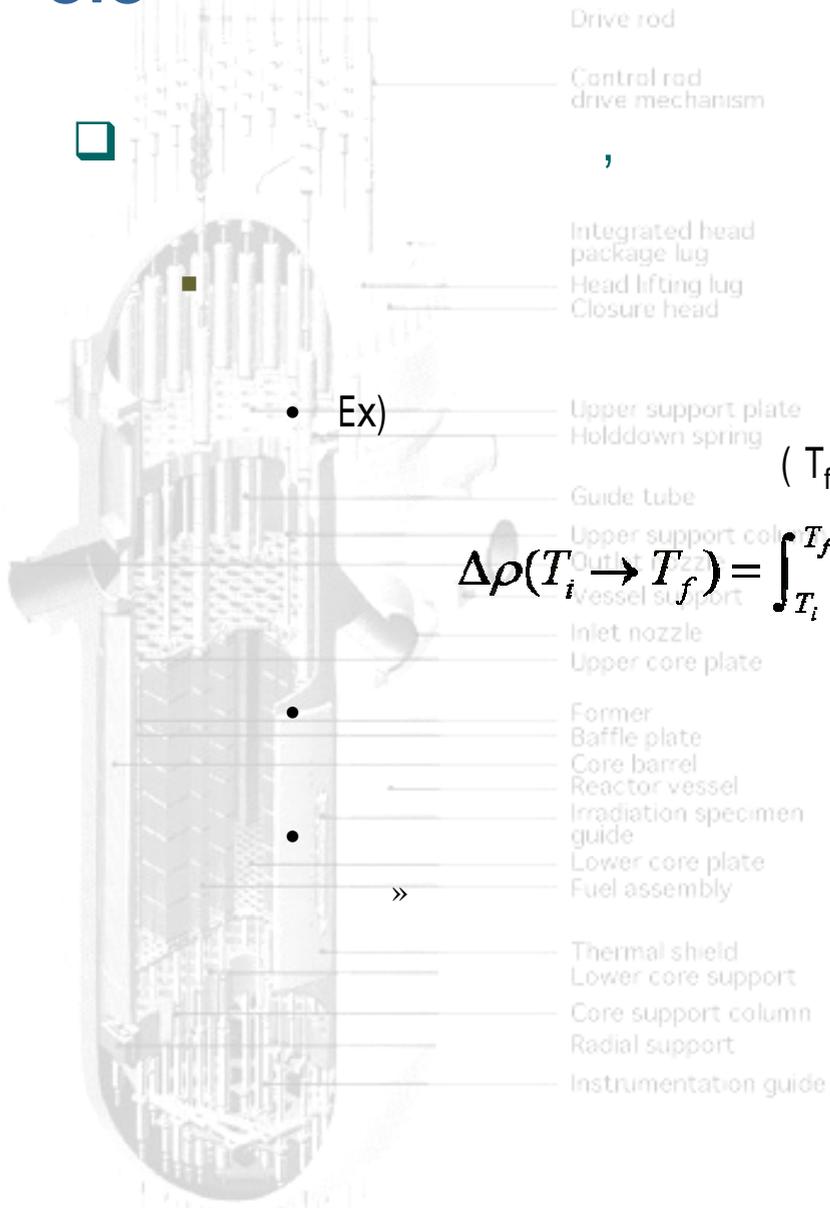
$$B^2 = \left(\frac{\pi}{a}\right)^2$$

$$\frac{dB^2}{dT} = \frac{d}{dT} \left(\frac{\pi}{a}\right)^2 = -2\left(\frac{\pi}{a}\right)^2 \frac{1}{a} \frac{da}{dT} = -2B^2 \beta \quad (6.79)$$



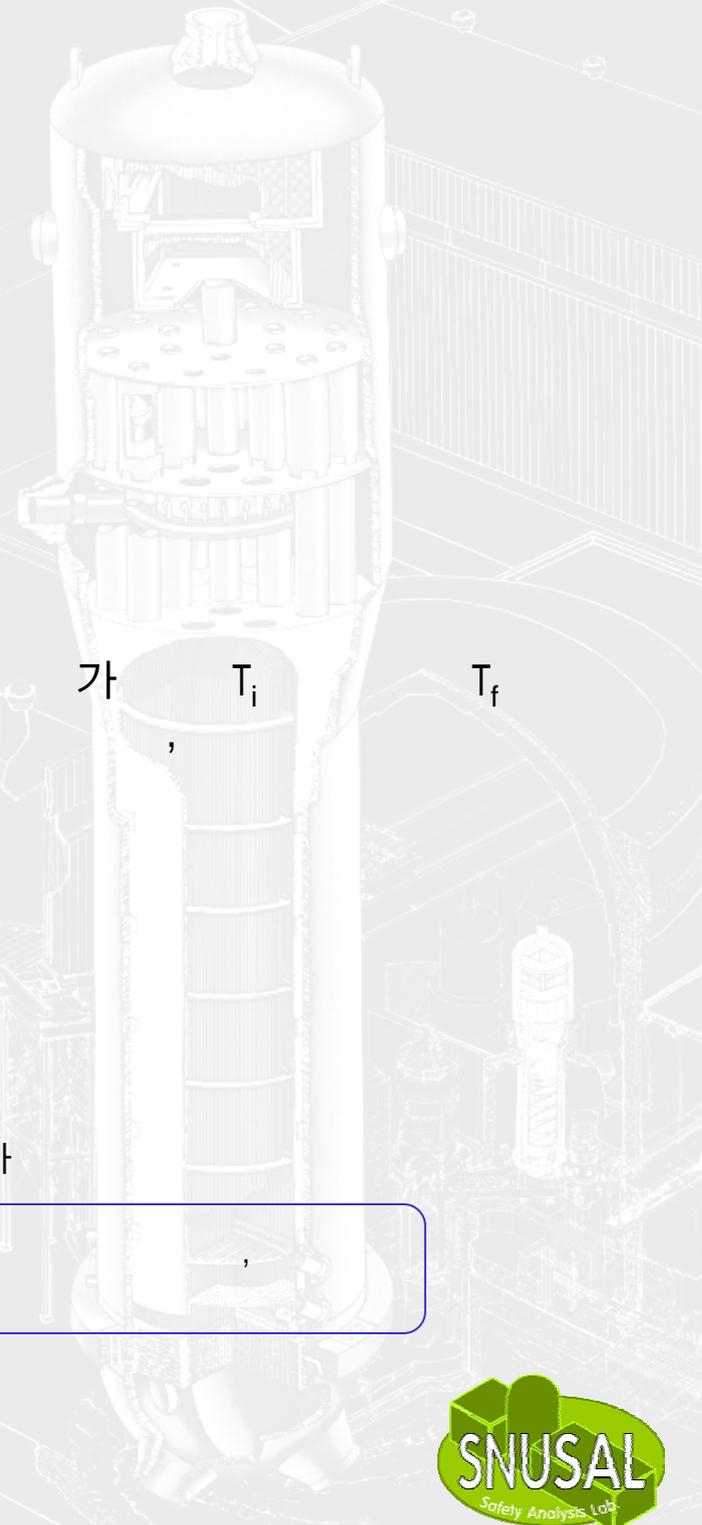
3.

▶ 3.3



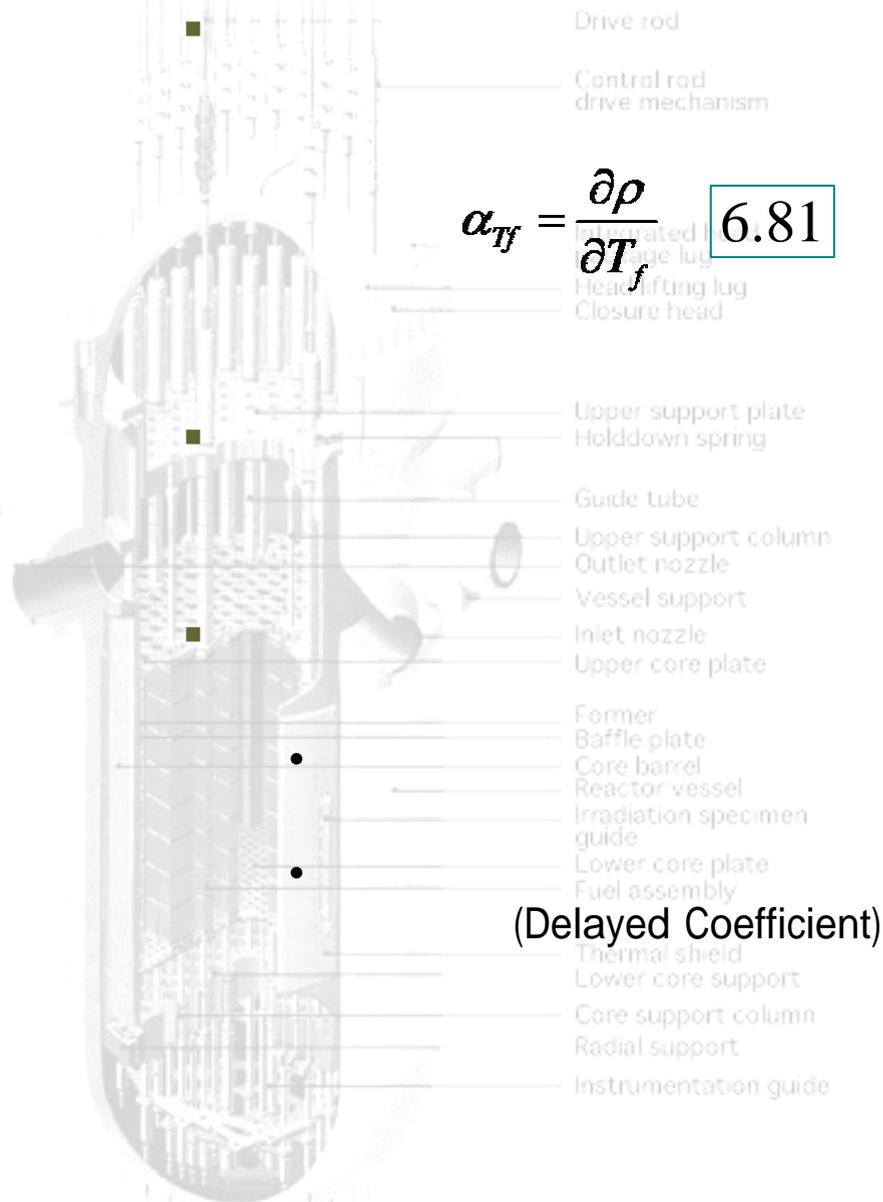
$$\Delta\rho(T_i \rightarrow T_f) = \int_{T_i}^{T_f} \alpha_{Tf} dT \quad 6.80$$

가
 $(T_f - T_i)$
Tf



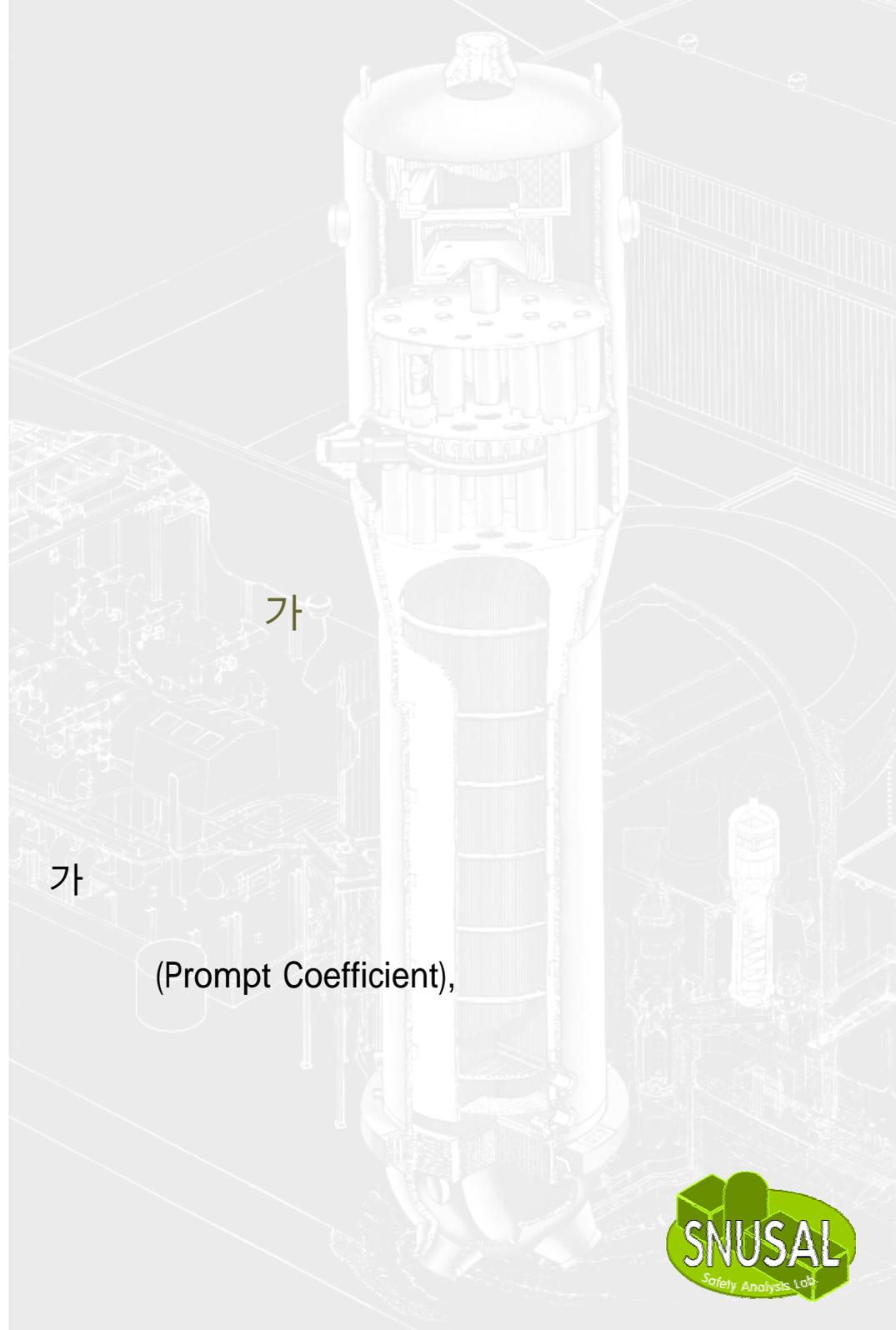
3.

3.3.1.

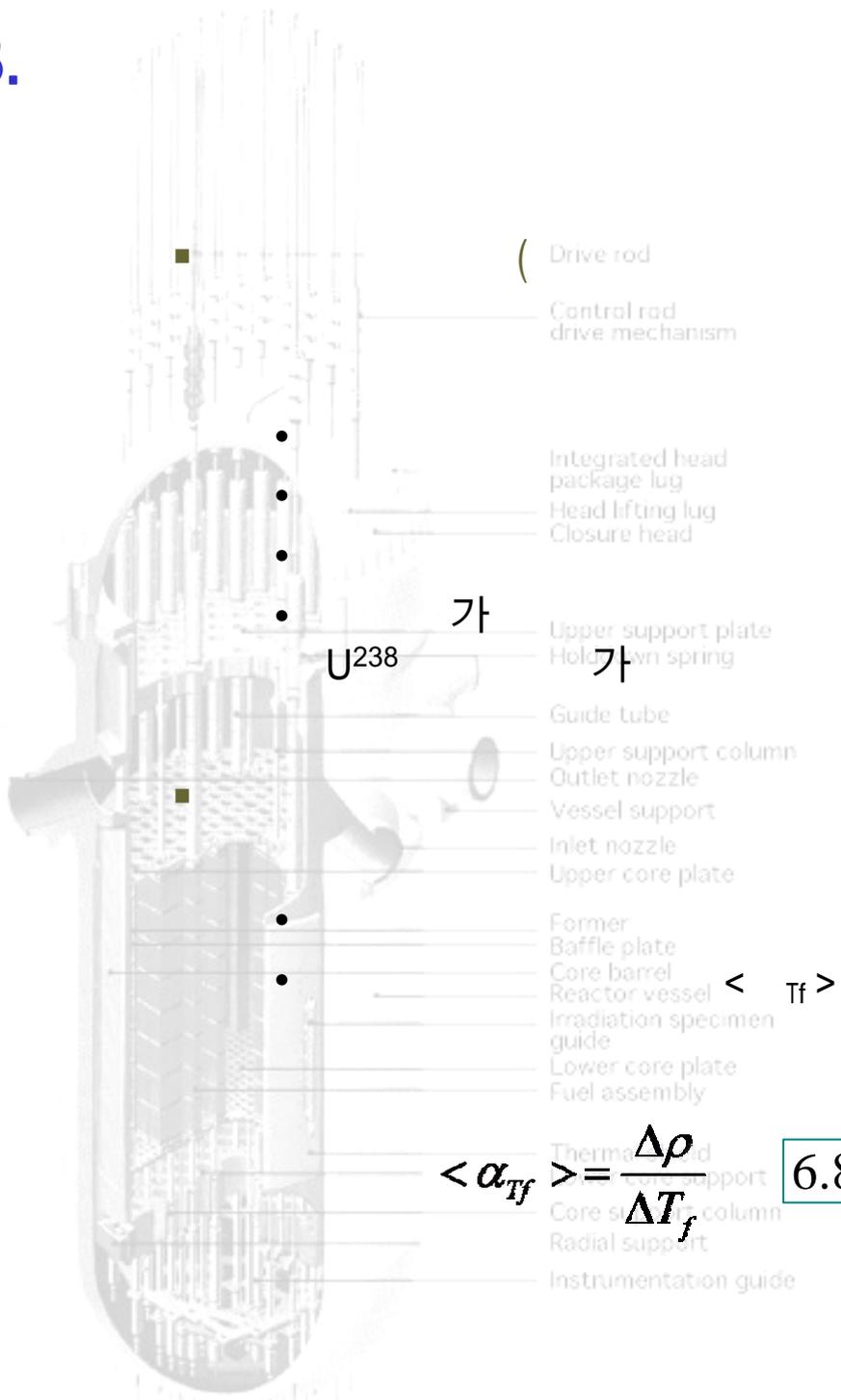


$$\alpha_{Tf} = \frac{\partial \rho}{\partial T_f} \quad \boxed{6.81}$$

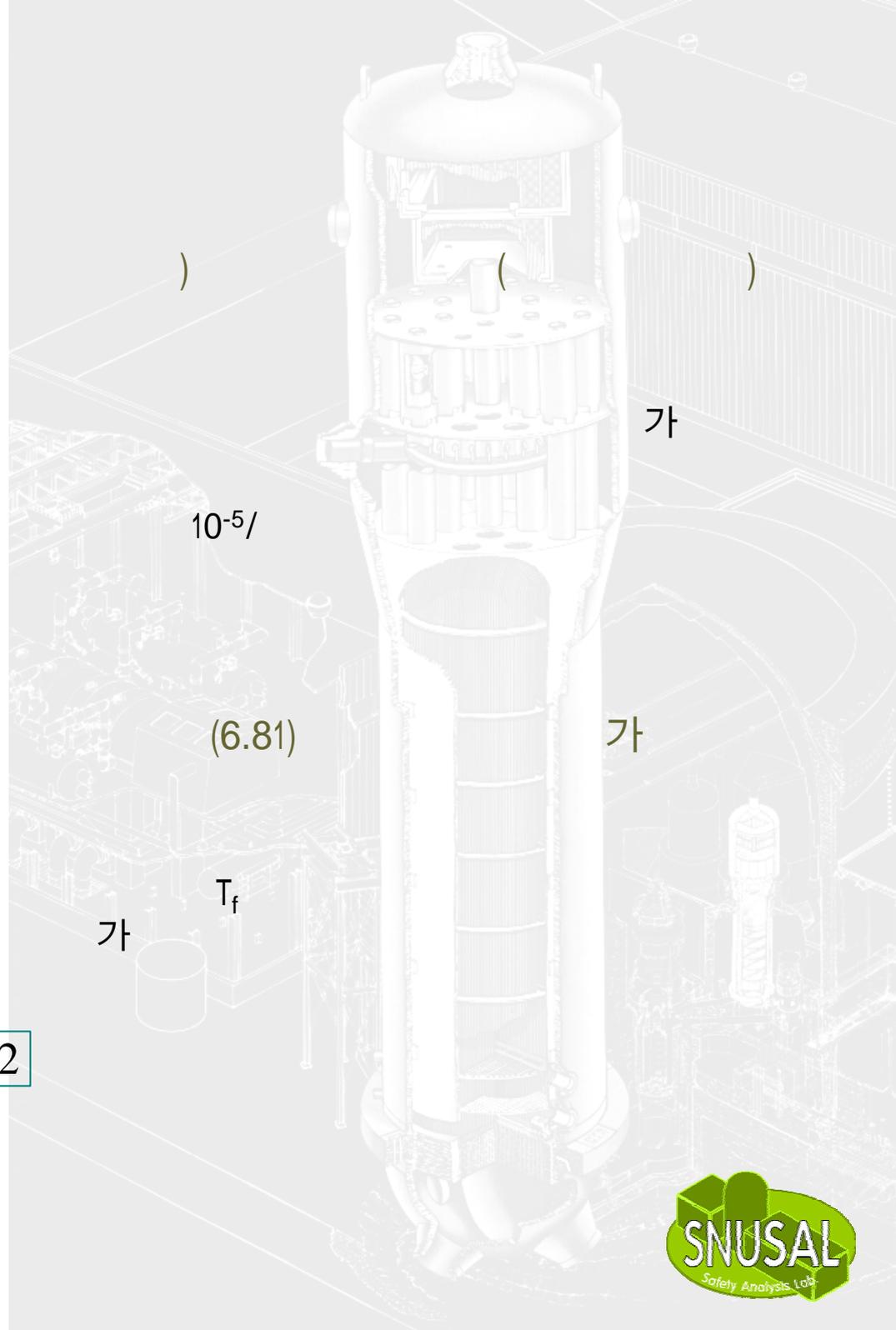
(Delayed Coefficient)



3.

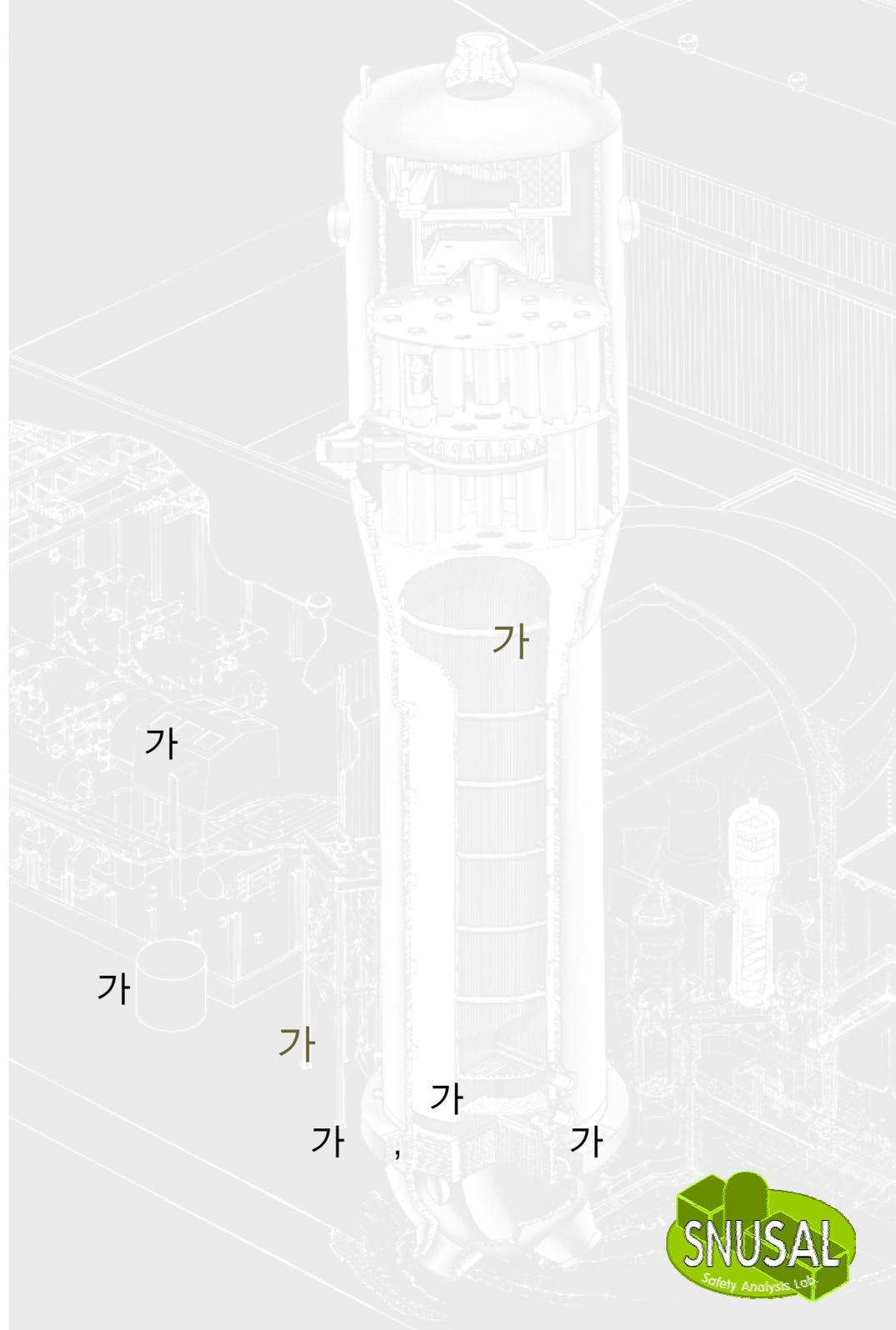
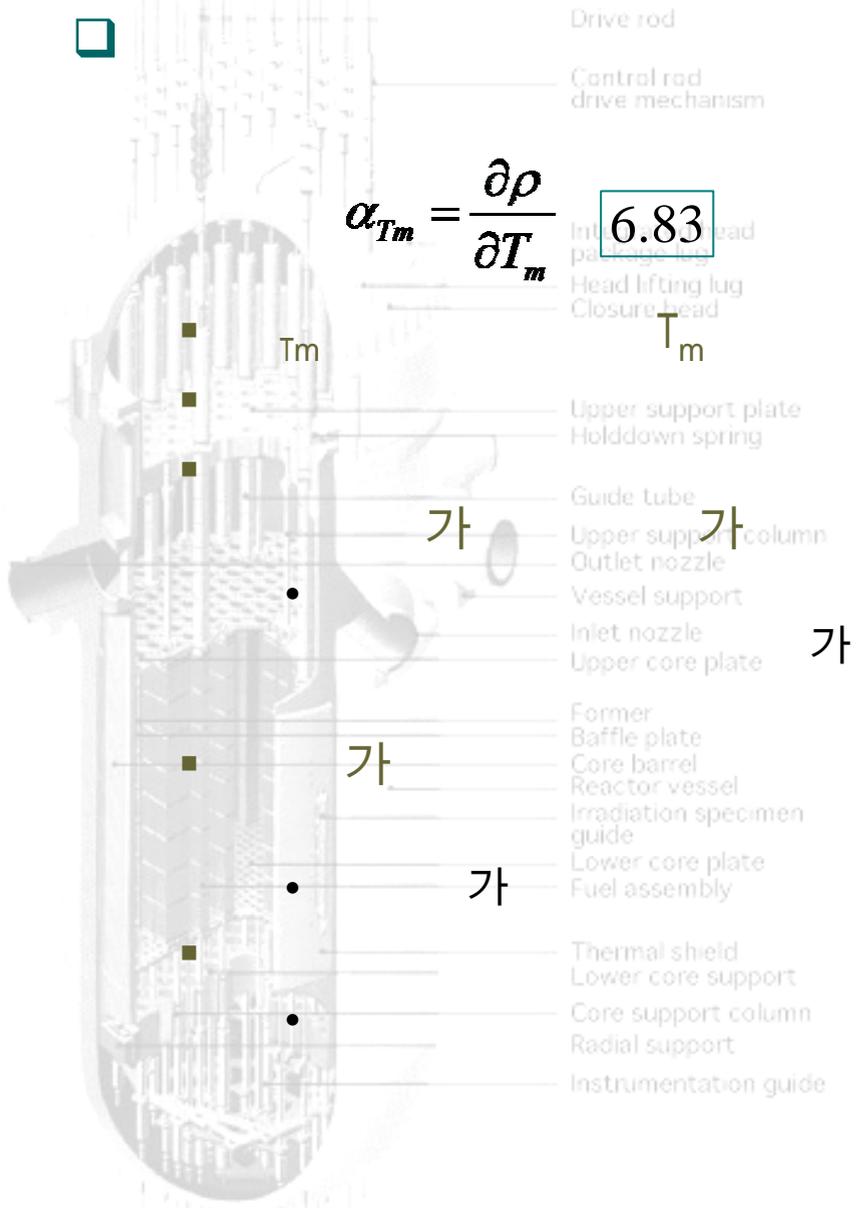


$$\langle \alpha_{Tf} \rangle = \frac{\Delta \rho}{\Delta T_f} \quad 6.82$$



3.

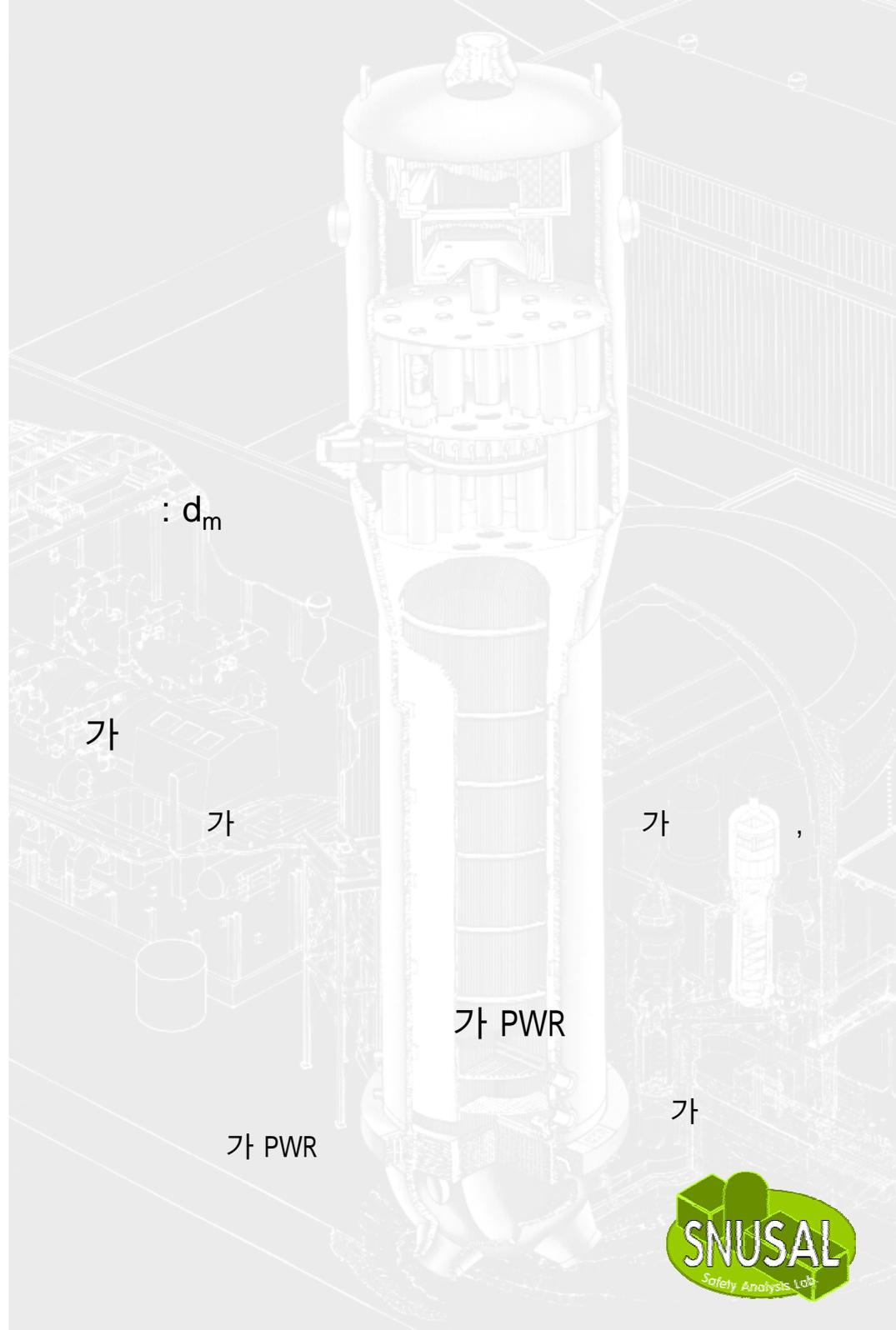
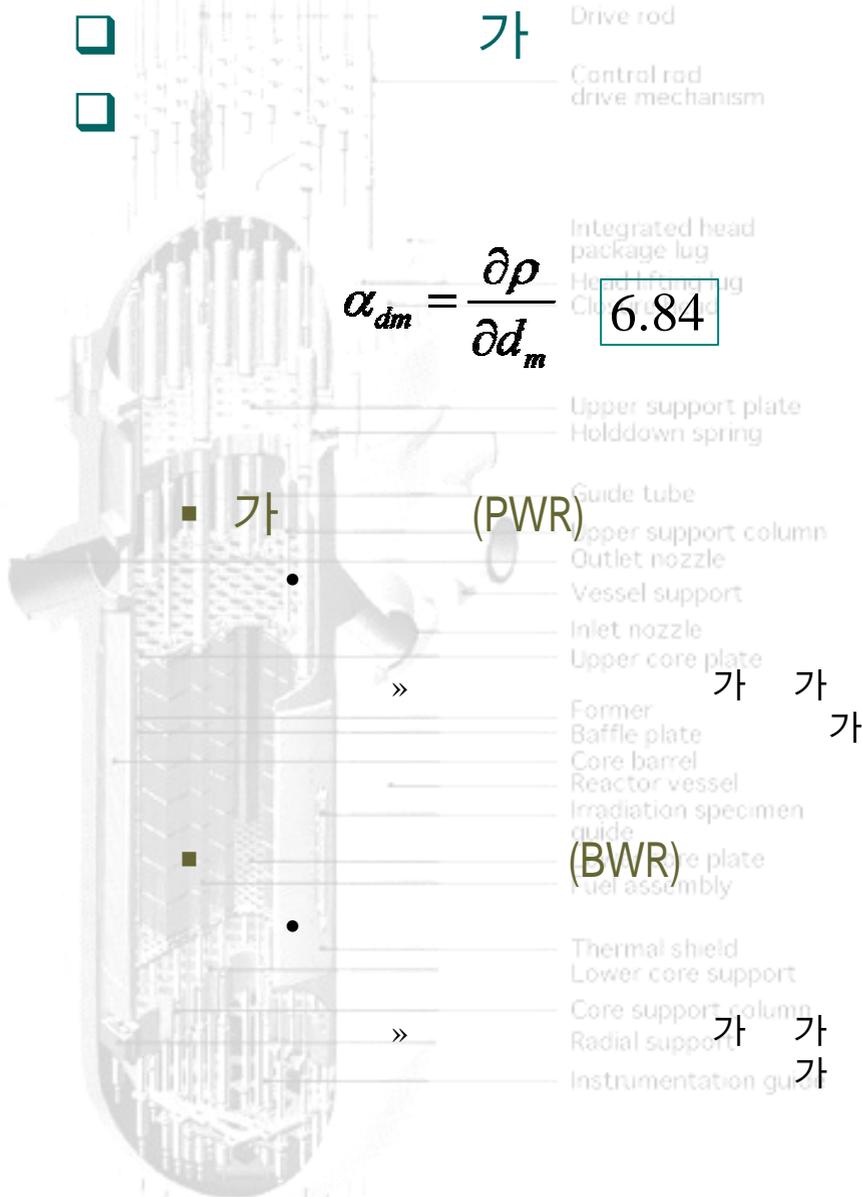
3.3.2



3.

3.3.3

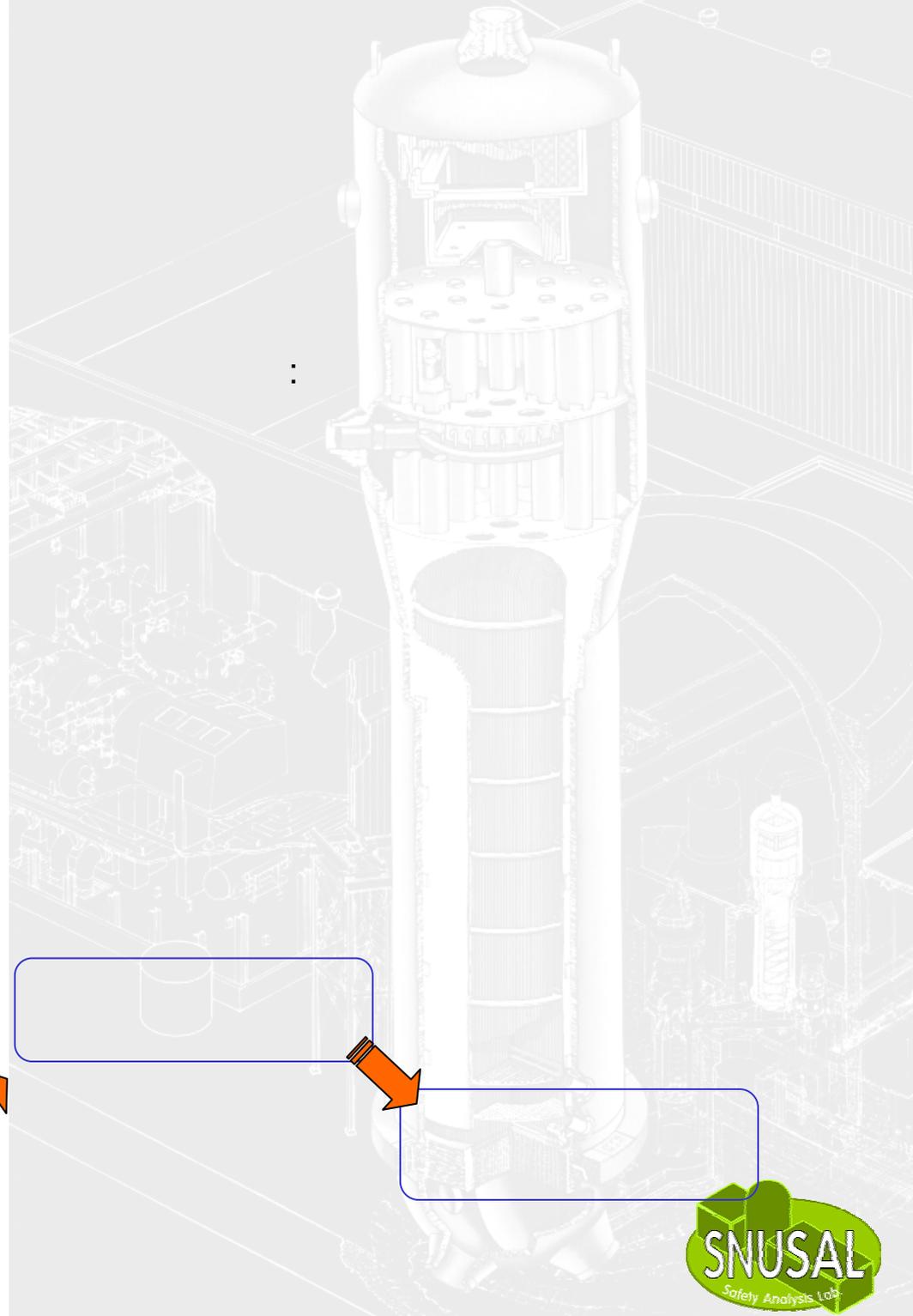
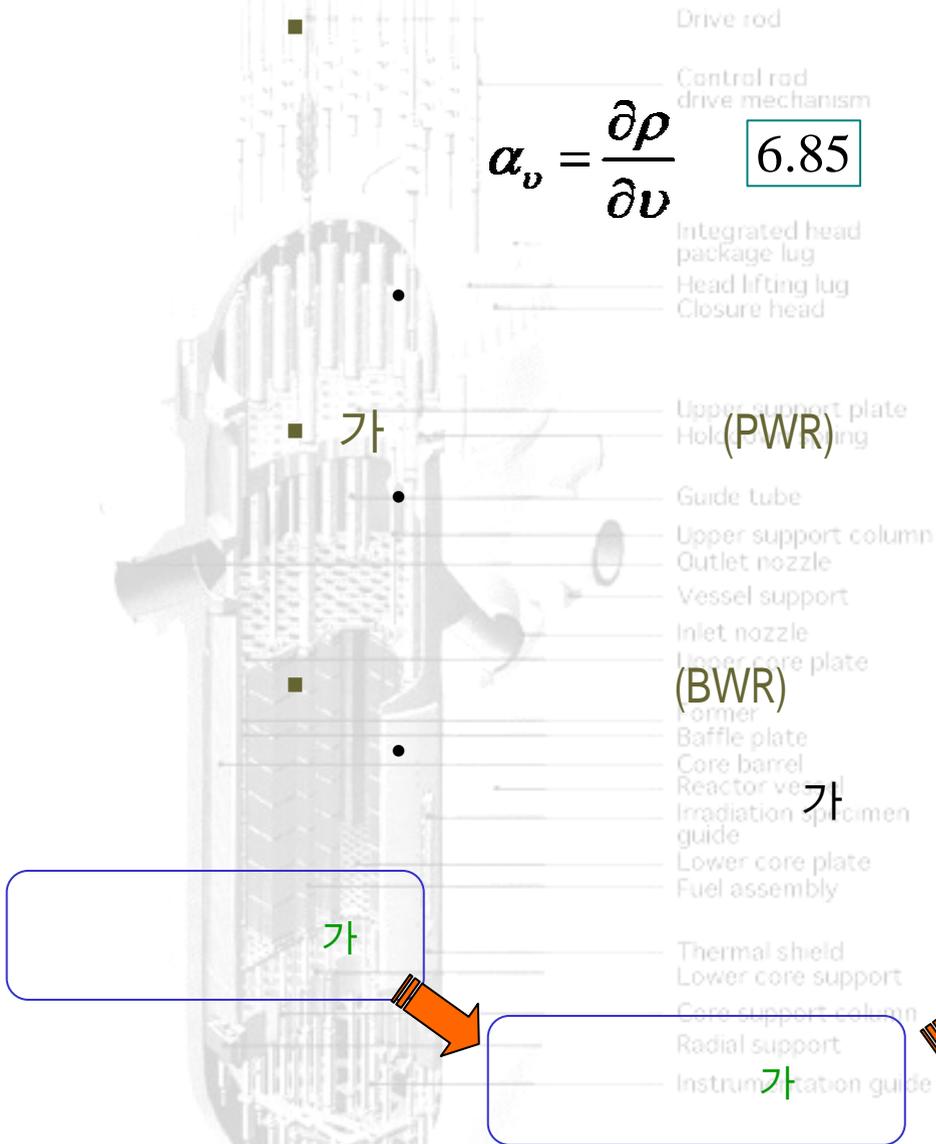
-
-



3.



$$\alpha_v = \frac{\partial \rho}{\partial v} \quad \boxed{6.85}$$



3.

3.3.4



Drive rod
Control rod drive mechanism

가

Ex) PWR: 2250psi, BWR: 1020psi, Candu: 1500psi

- PWR BWR Integrated head package lug
- Head lifting lug
- Closure head



가 (PWR)

Upper support plate
Holddown spring
Guide tube
Upper support column
Nozzle
Vessel support
Inlet nozzle
Upper core plate

Former
Baffle plate
Core barrel
Reactor vessel
Irradiation specimen guide
Lower core plate
Fuel assembly
Thermal shield
Lower core support
Core support column
Radial support
Instrumentation guide

가

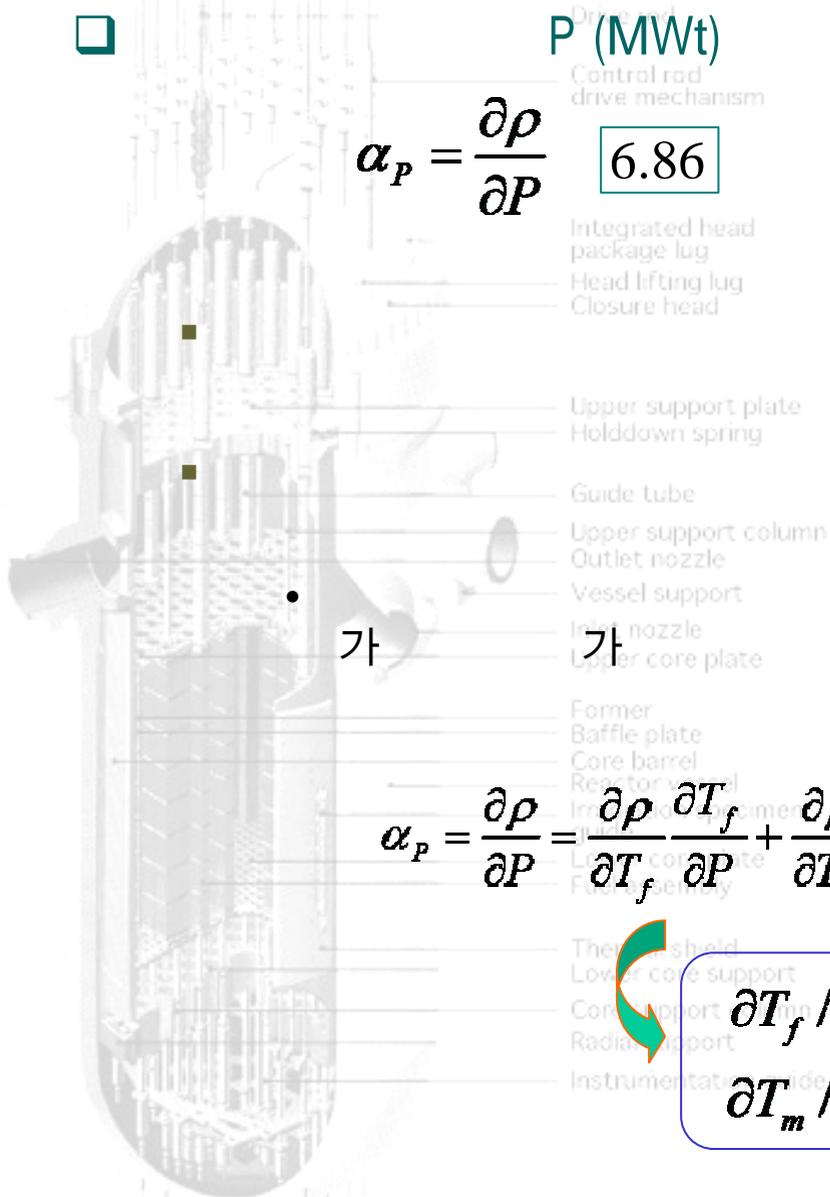
가

가

가

3.

➤ 3.3.5



P (MWt)

$$\alpha_P = \frac{\partial \rho}{\partial P} \quad \boxed{6.86}$$

P

$$\alpha_P = \frac{\partial \rho}{\partial P} = \frac{\partial \rho}{\partial T_f} \frac{\partial T_f}{\partial P} + \frac{\partial \rho}{\partial T_m} \frac{\partial T_m}{\partial P} = \alpha_{Tf} \frac{\partial T_m}{\partial P} + \partial T_m \frac{\partial T_m}{\partial P} \quad \boxed{6.87}$$

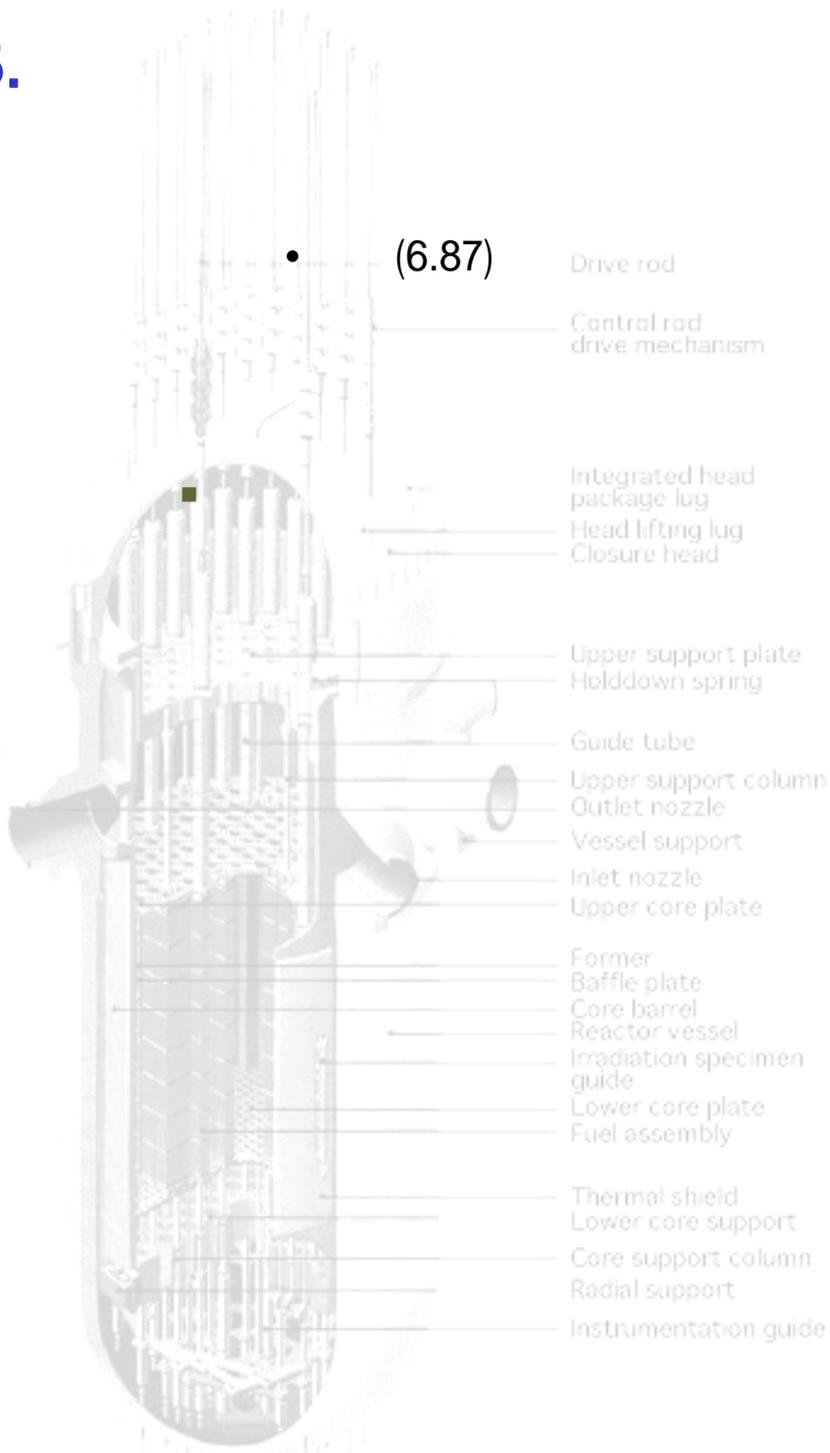
$\frac{\partial T_f}{\partial P} :$

$\frac{\partial T_m}{\partial P} :$

p

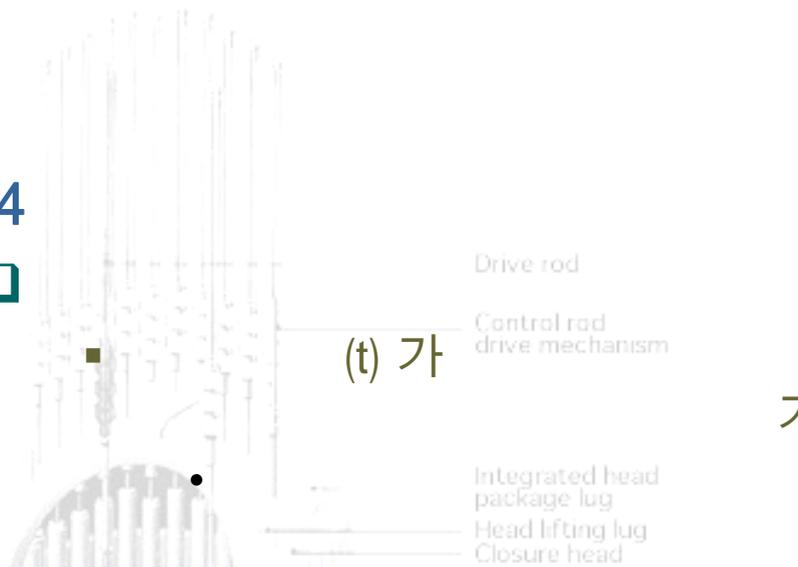
가

3.



3.

3.4



(t) 가

가

가

가

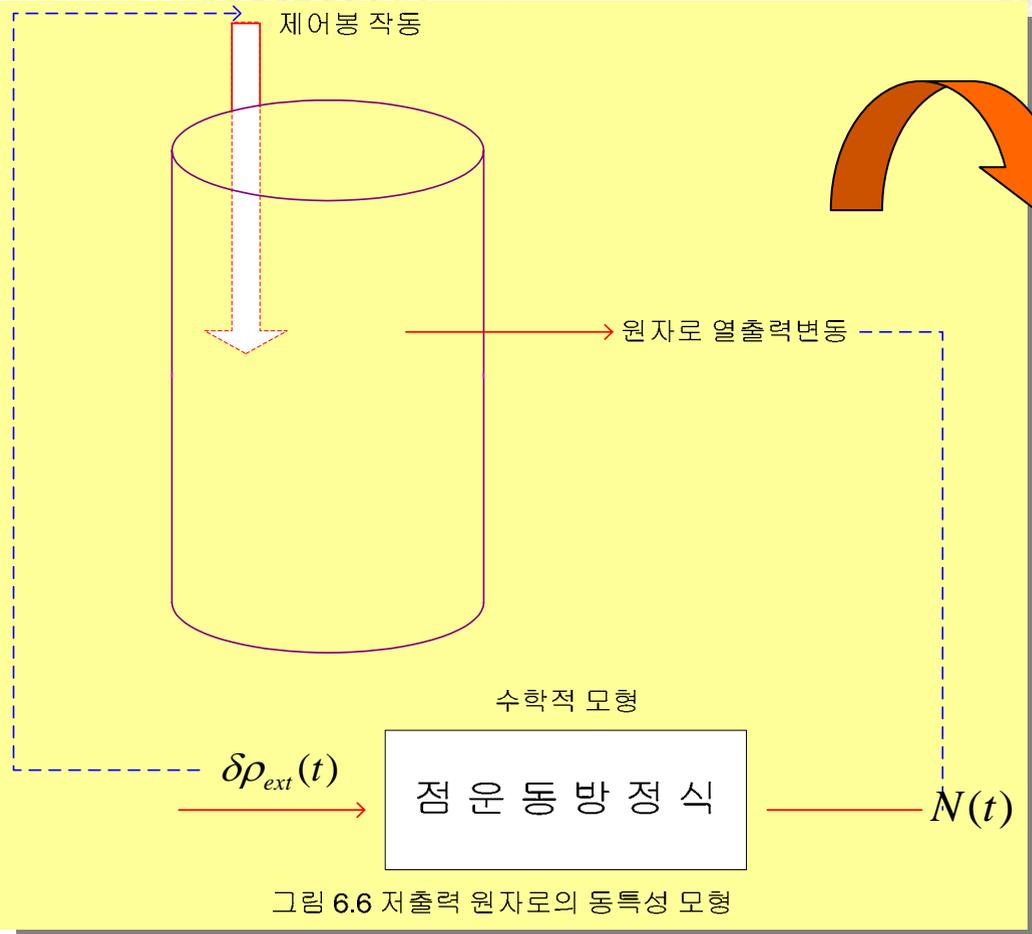


그림 6.6 저출력 원자로의 동특성 모형

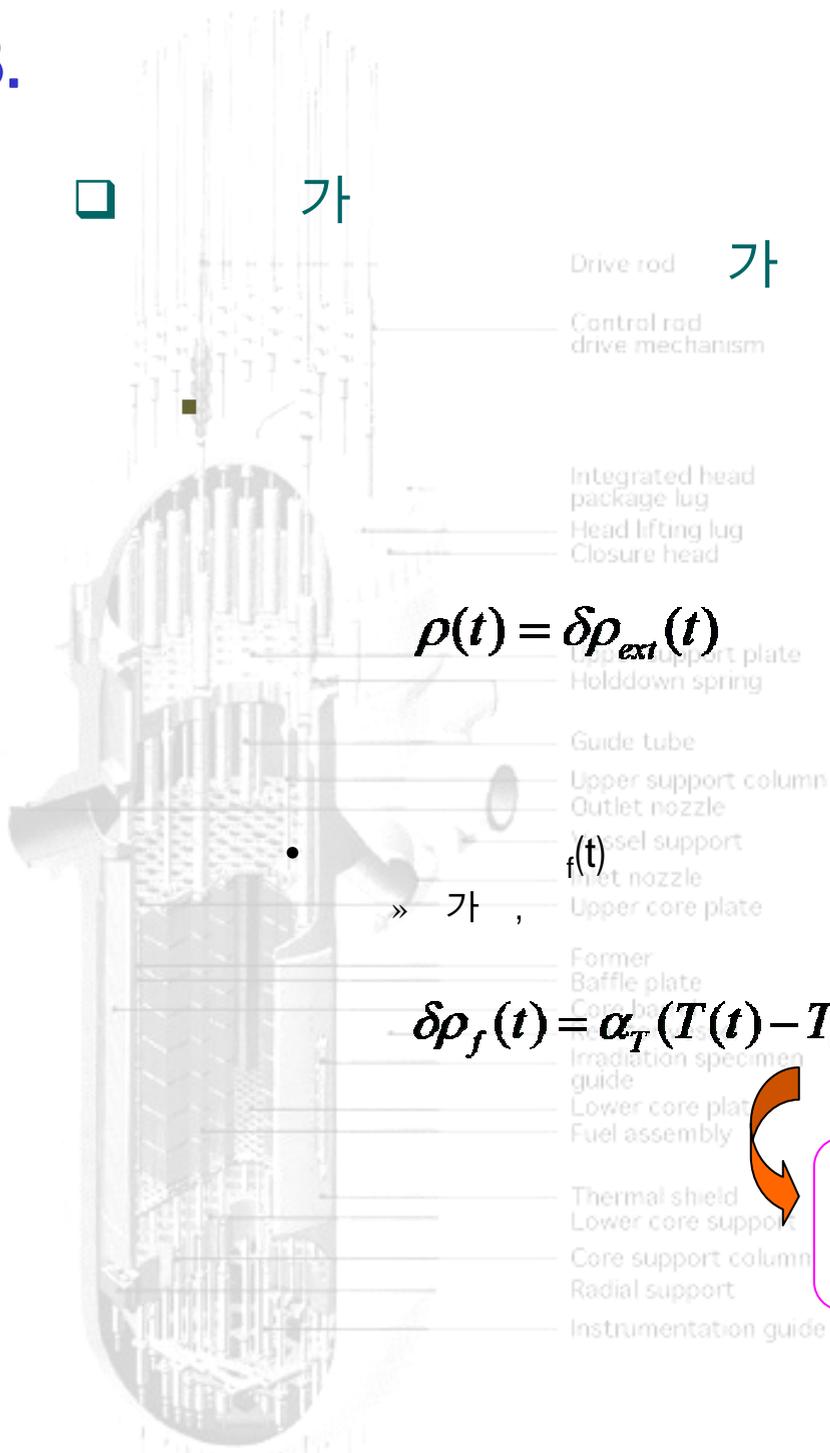
3.



가

가

6.6



$$\rho(t) = \delta\rho_{ext}(t)$$

$\rho_{ext}(t)$

6.88

$$\delta\rho_f(t) = \alpha_T(T(t) - T_0)$$

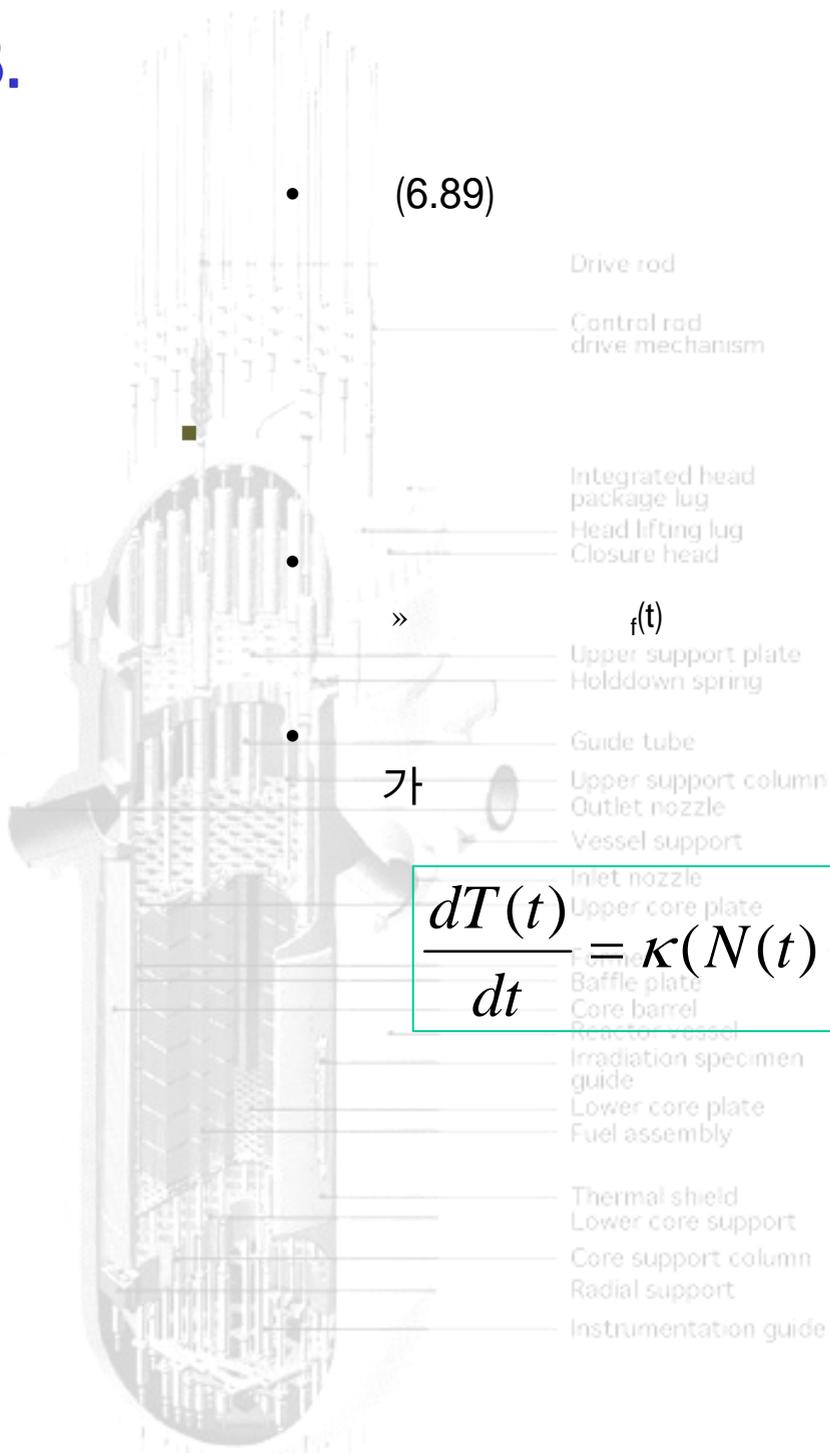
6.89

T_0 :

$T(t)$:



3.



(6.89)

» $f(t)$

가

$$\frac{dT(t)}{dt} = \kappa(N(t) - N_0) - \gamma(T(t) - T_0)$$

6.90

$f(t)$, $T(t)$

: Heat capacity
:

3.

■ (6.90) → **Newton**

6.90 + 6.88 →

6.7
Integrat 가
package lug
Head lifting lug
Closure head



$\delta\rho_f$
Newton

6.7
Thermal shield
Lower core support
Core support column
Radial support
Instrumentation guide

3.

• II) $\tau < 0$



(6.77)

k/τ



가 가

Control rod drive mechanism

가

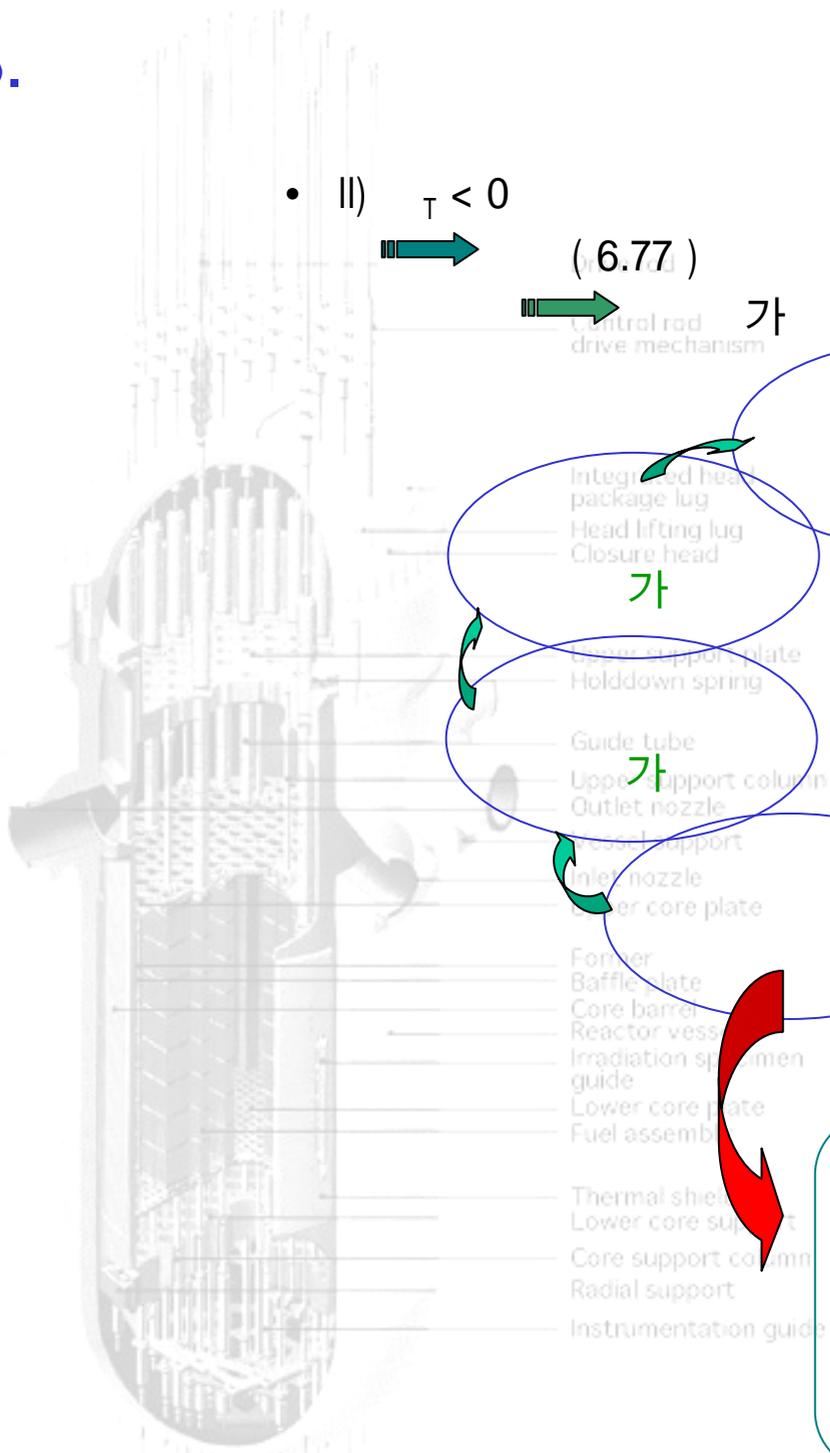
가

가

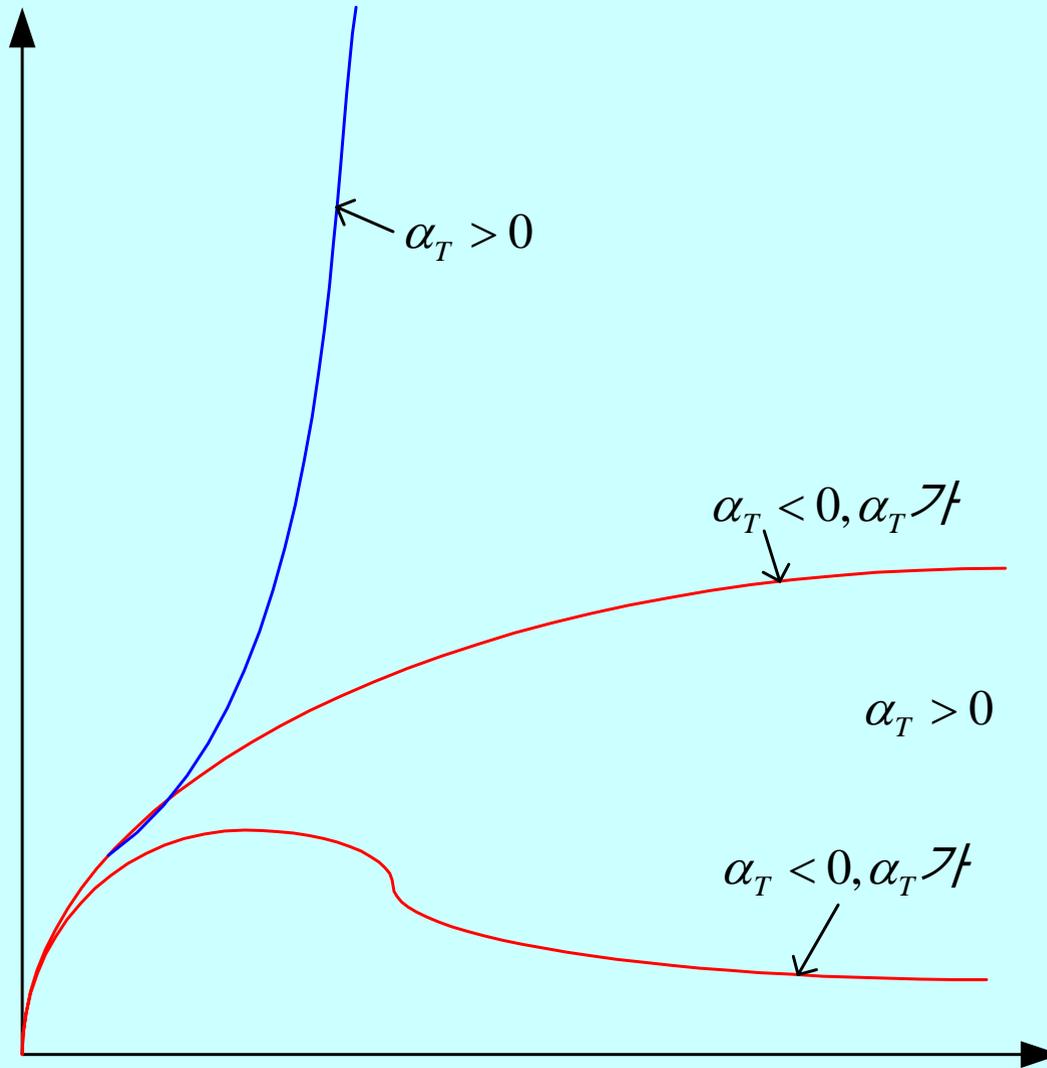
가

가

$\tau < 0$



3.



6.8 α_T

4.



(Fuel depletion or Fuel burnup)



?

Drive rod
Control rod
drive mechanism

Integrated head
package lug
Head lifting lug
Closure head

Upper support plate
Holddown spring

Guide tube
Upper support column
Outlet nozzle
Vessel support
Inlet nozzle
Upper core

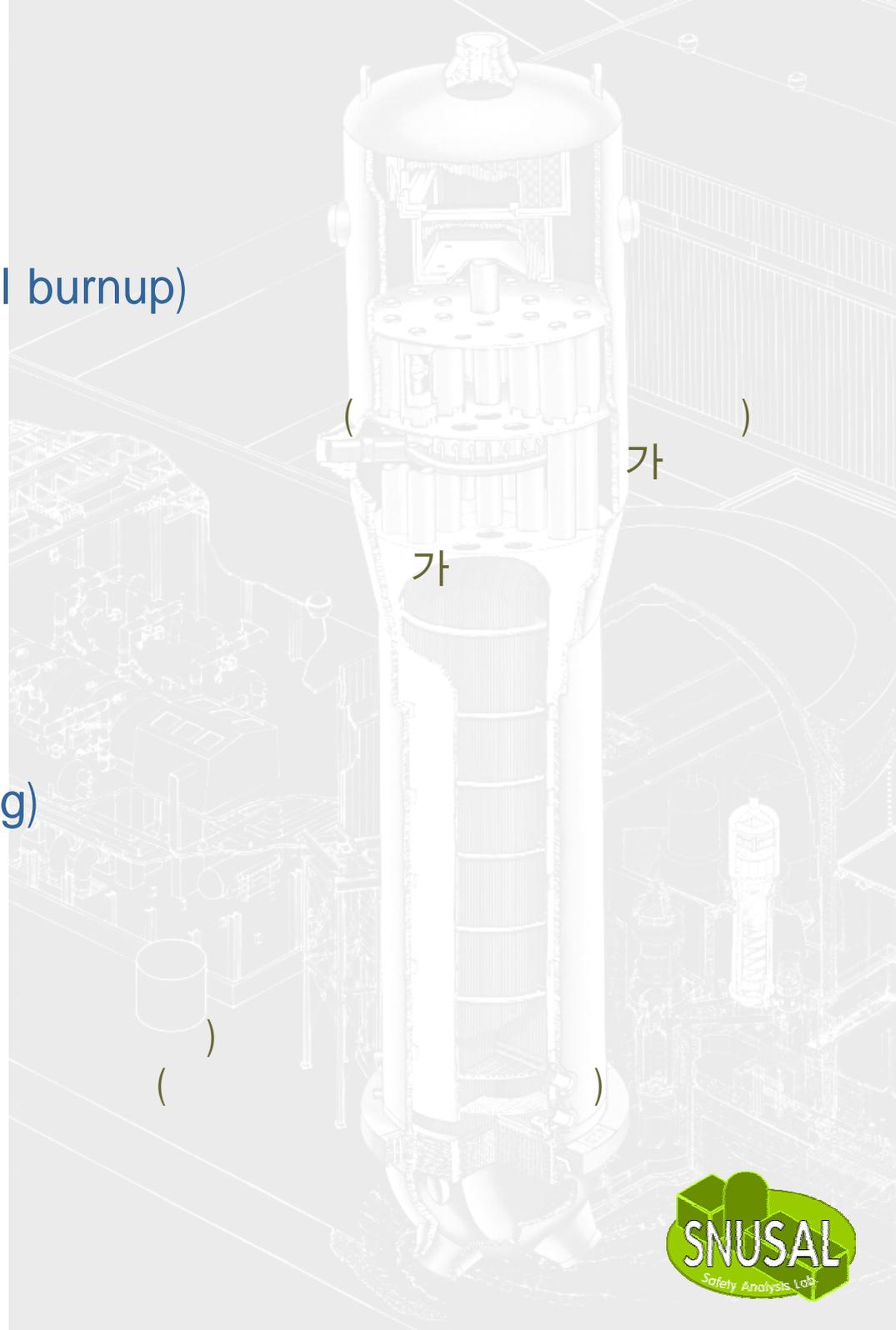
(Poisoning)



?

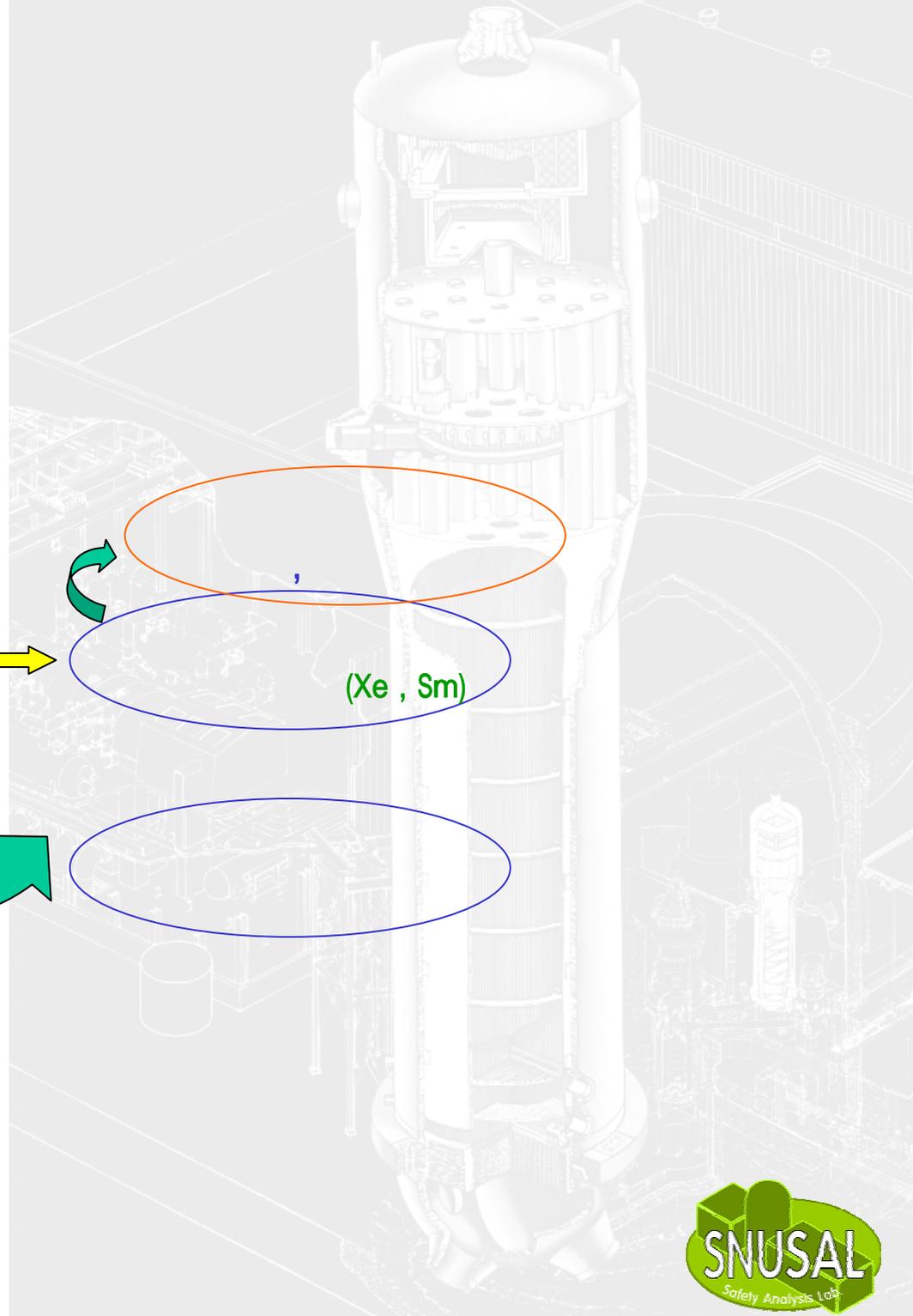
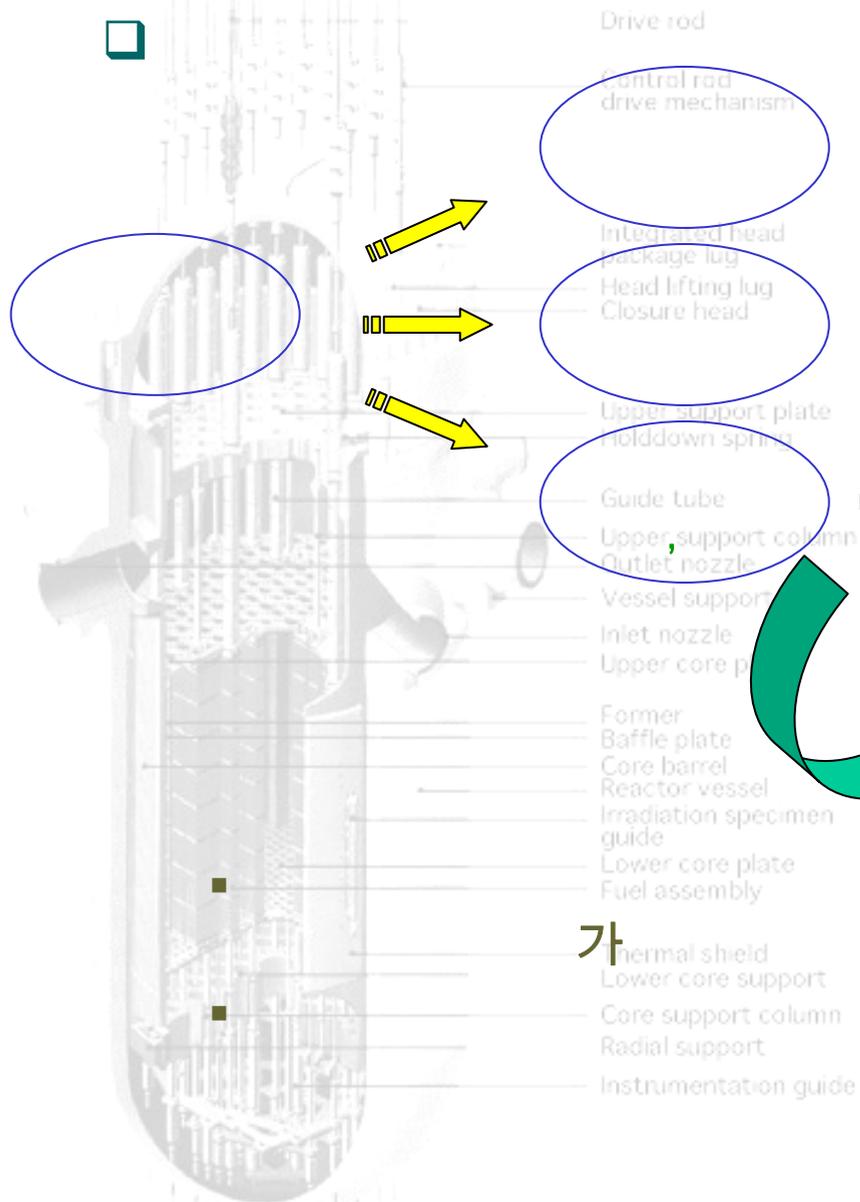
Former
Baffle plate
Core barrel
Reactor vessel
Irradiation specimen
guide
Lower core plate
Fuel assembly

Thermal shield (가)
Lower core support (가)
Core support column
Radial support (가)
Instrumentation guide



4.

4.1



4.

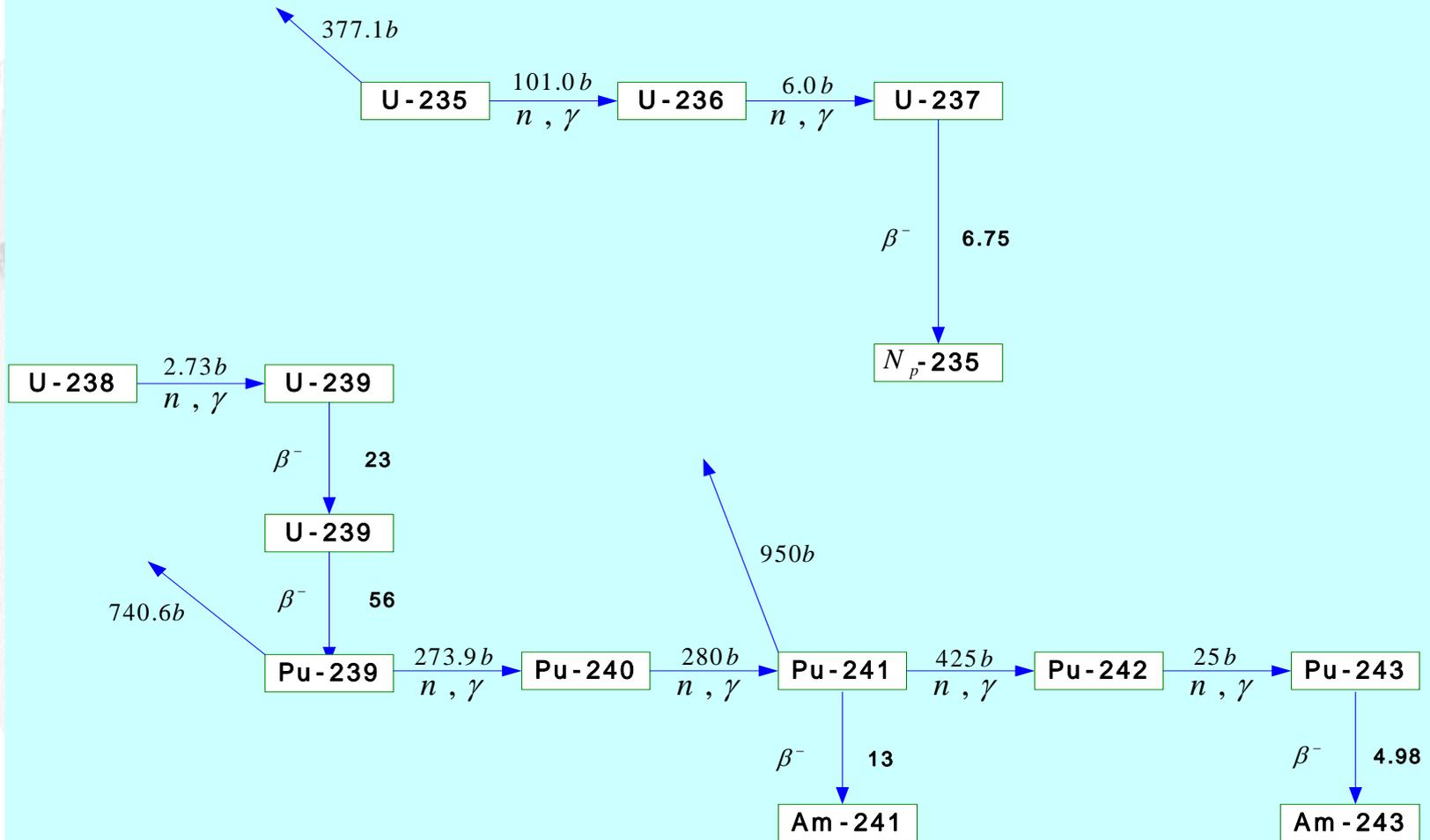


||

Drive rod
Control rod
drive mechanism

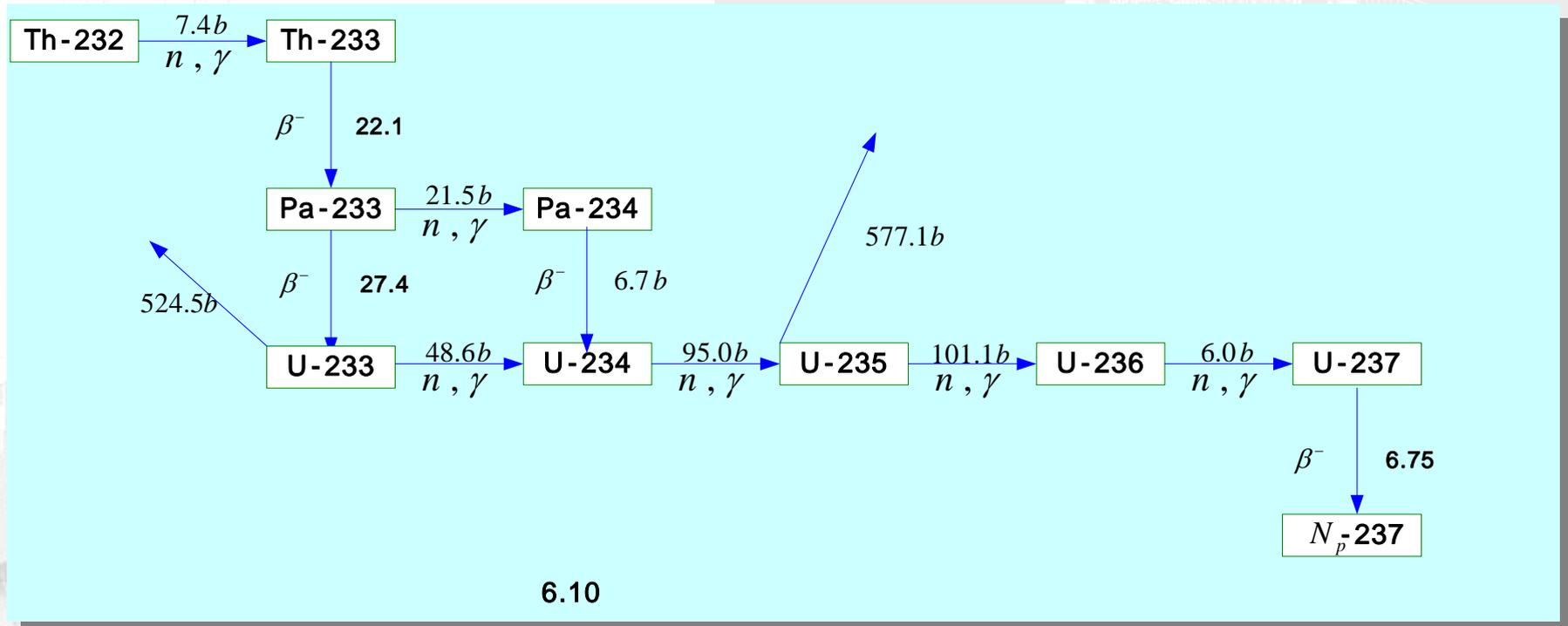
6.9 6.10

Integrated head
package, bus



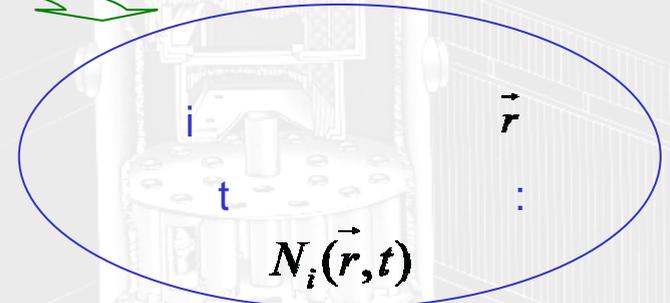
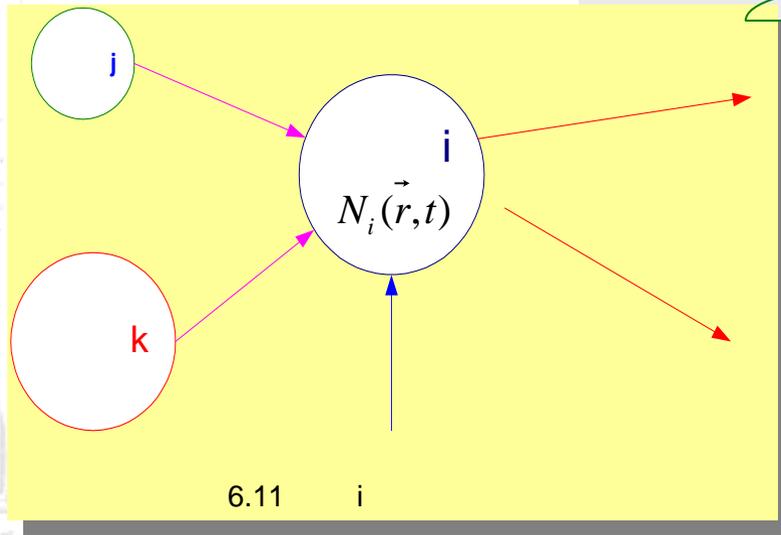
6.9

4.



4.

Ex)



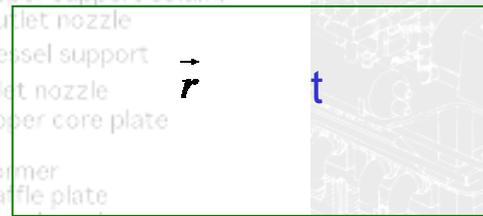
6.11 i



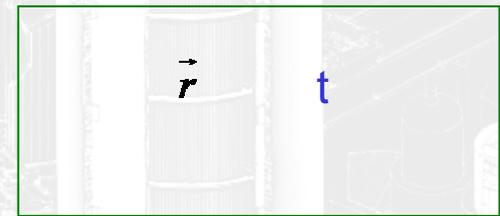
6.11

- Hold-down spring
- Guide tube
- Upper support column
- Outlet nozzle
- Vessel support
- Inlet nozzle
- Upper core plate
- Former
- Baffle plate
- Core barrel
- Reactor vessel
- Irradiation specimen guide
- Lower core plate
- Fuel assembly
- Thermal shield
- Lower core support
- Core support column
- Radial support
- Instrumentation guide

=



-



6.91

Or

$$\frac{\partial N_i(\vec{r}, t)}{\partial t}$$

=



+



+



-



-

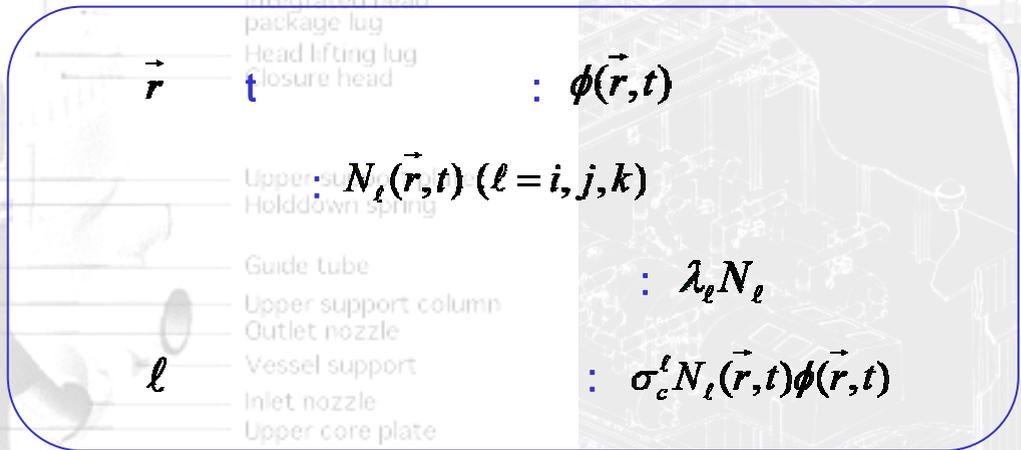


6.92

4.

• (6.92)

$$\frac{\partial N_i(\vec{r}, t)}{\partial t} = \lambda_j N_j(\vec{r}, t) + \sigma_c^k N_k(\vec{r}, t) \phi(\vec{r}, t) + \gamma_i \Sigma_f \phi(\vec{r}, t) - \lambda_i N_i(\vec{r}, t) - \sigma_c^i N_i(\vec{r}, t) \phi(\vec{r}, t) \quad \boxed{6.93}$$



σ_c^l = 핵종 l 의 중성자 포획 단면적 ($l = i, k$)

γ_i = 핵분열당 핵종 i 의 생성율

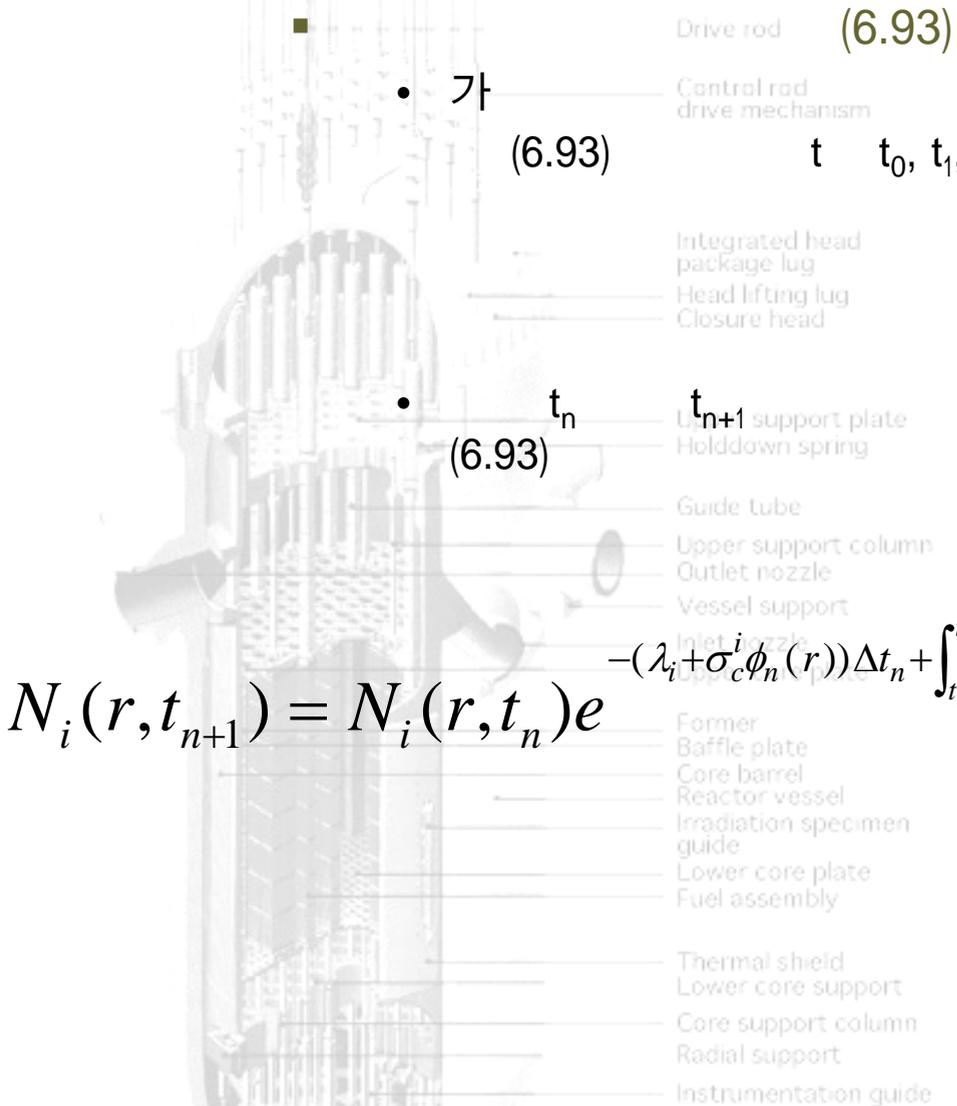
• (6.93)



(6.93)



4.



$$N_i(r, t_{n+1}) = N_i(r, t_n) e^{-(\lambda_i + \sigma_c^i \phi_n(r)) \Delta t_n + \int_{t_n}^{t_{n+1}} \{ \lambda_j N_j(r, t') + \sigma_c^k N_k(r, t') \phi_n(r) + \gamma_i \Sigma_f \phi_n(r) \} e^{-(\lambda_i + \sigma_c^i \phi_n)(t' - t_n)} dt'}$$

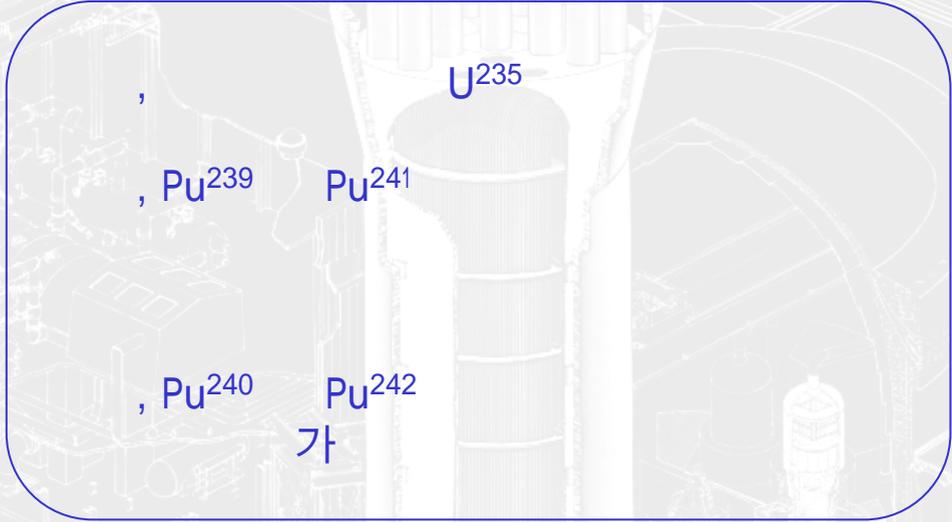
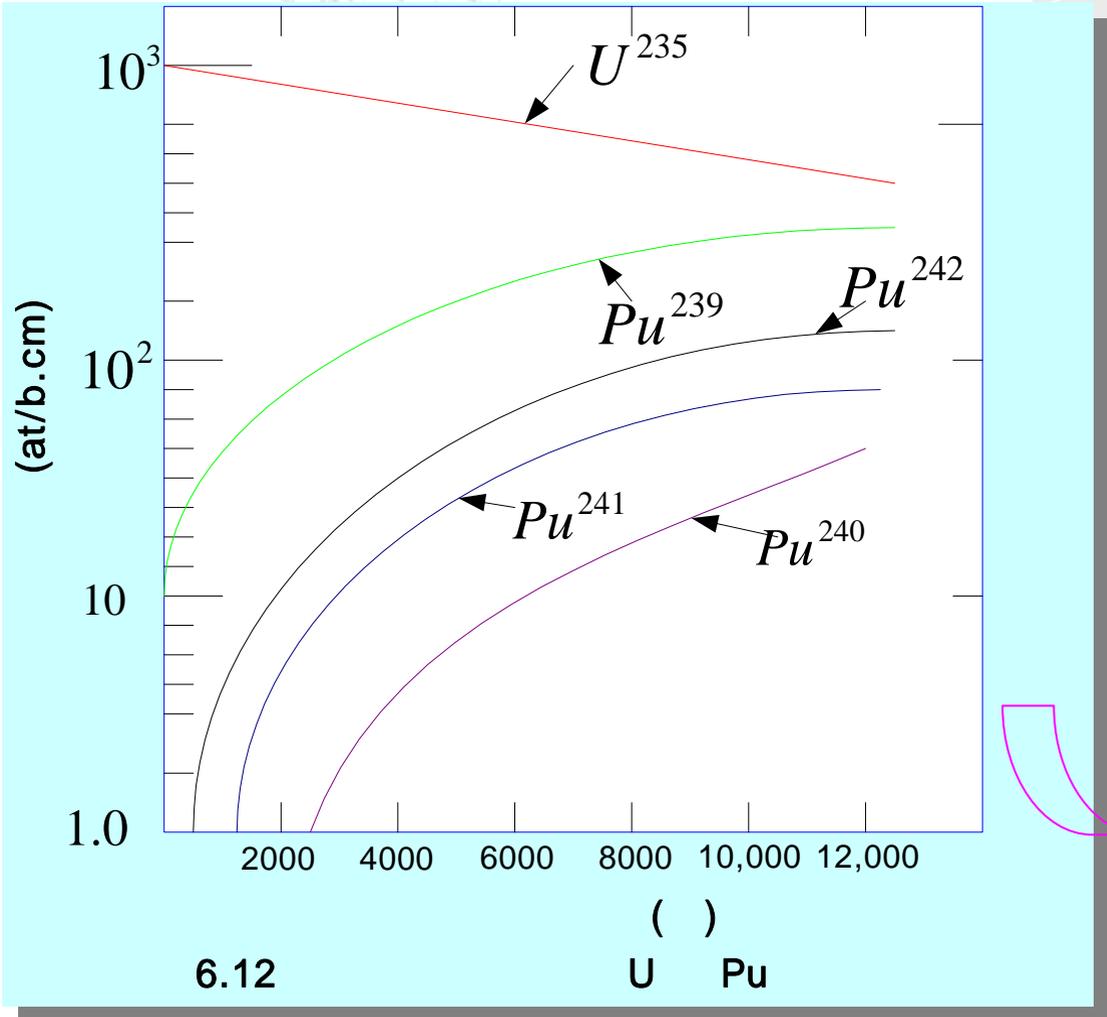
$$\phi(\vec{r}, t), \phi(\vec{r}, t_n), \phi_n(\vec{r})$$

6.95

$$\Delta t_n = t_{n+1} - t_n$$

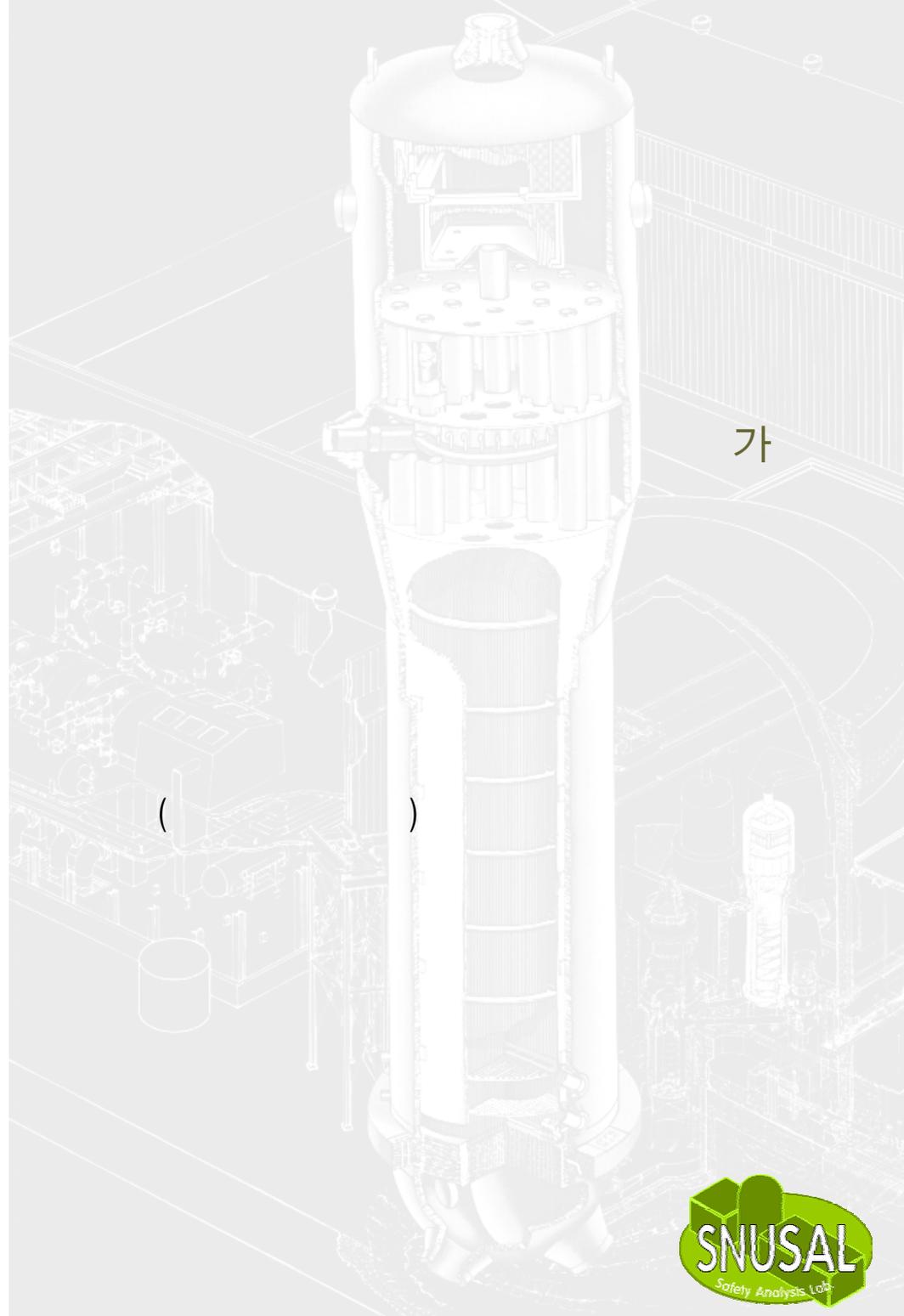
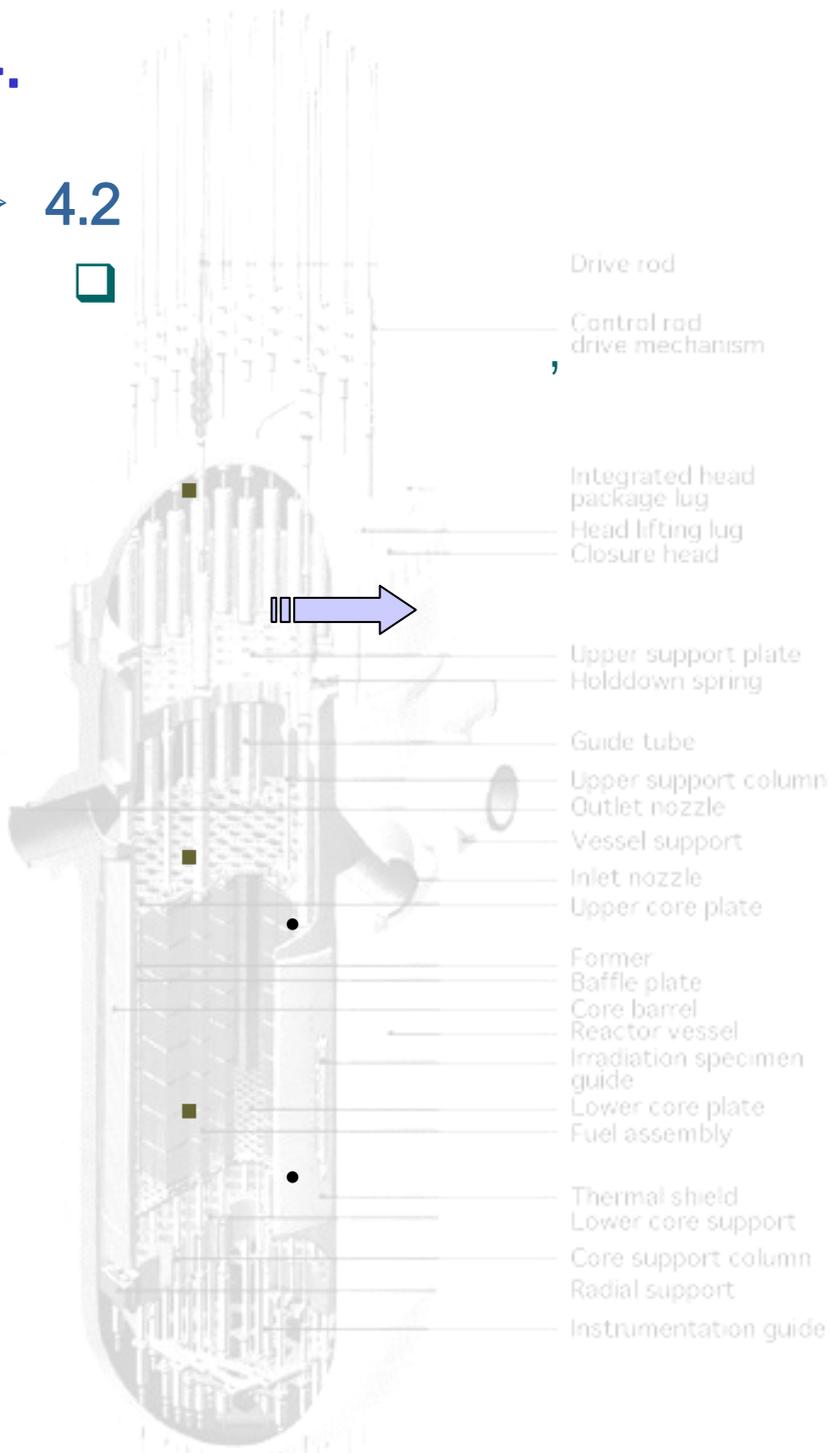
4.

6.12 UO₂ Drive rod
Control rod drive mechanism



4.

➤ 4.2

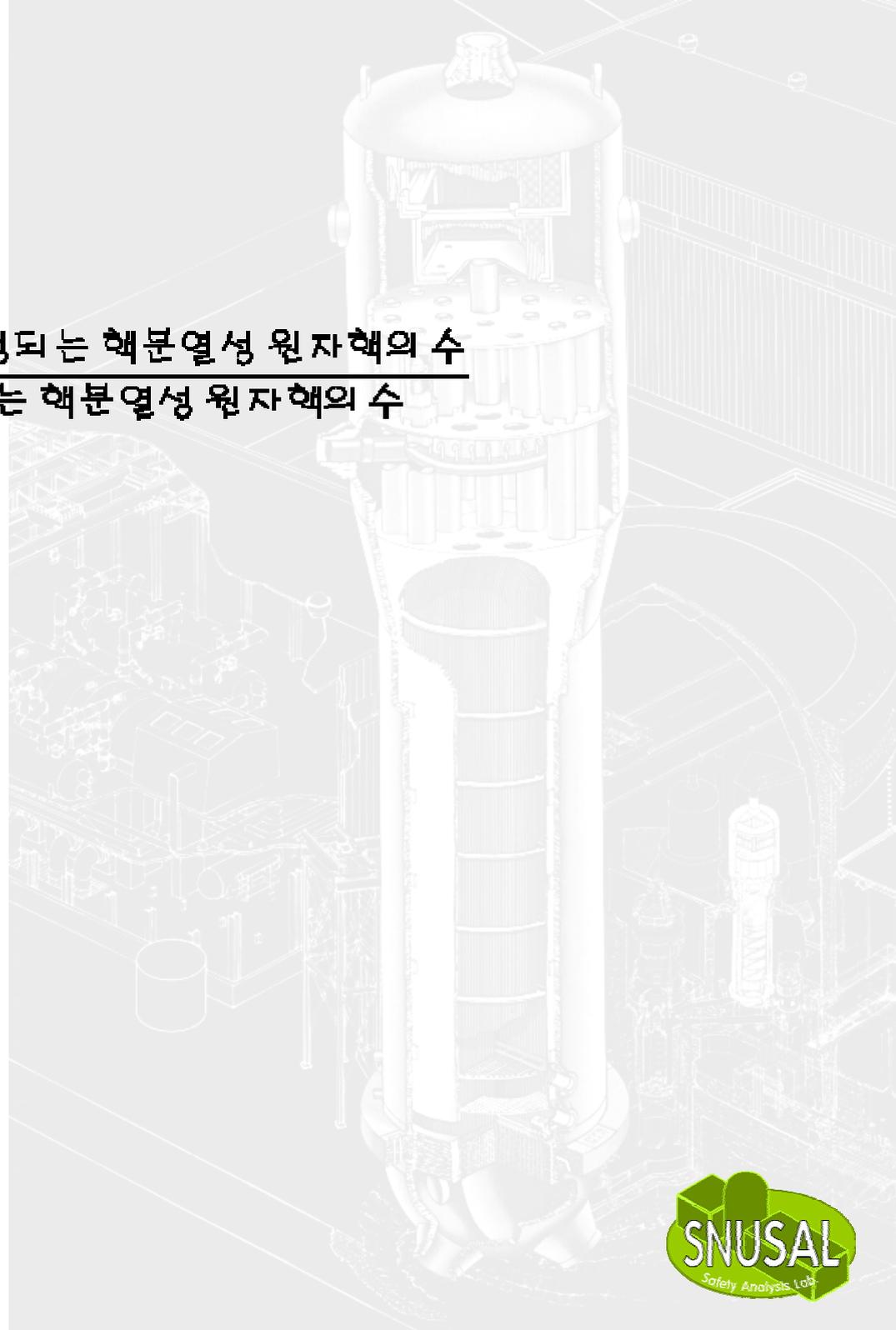
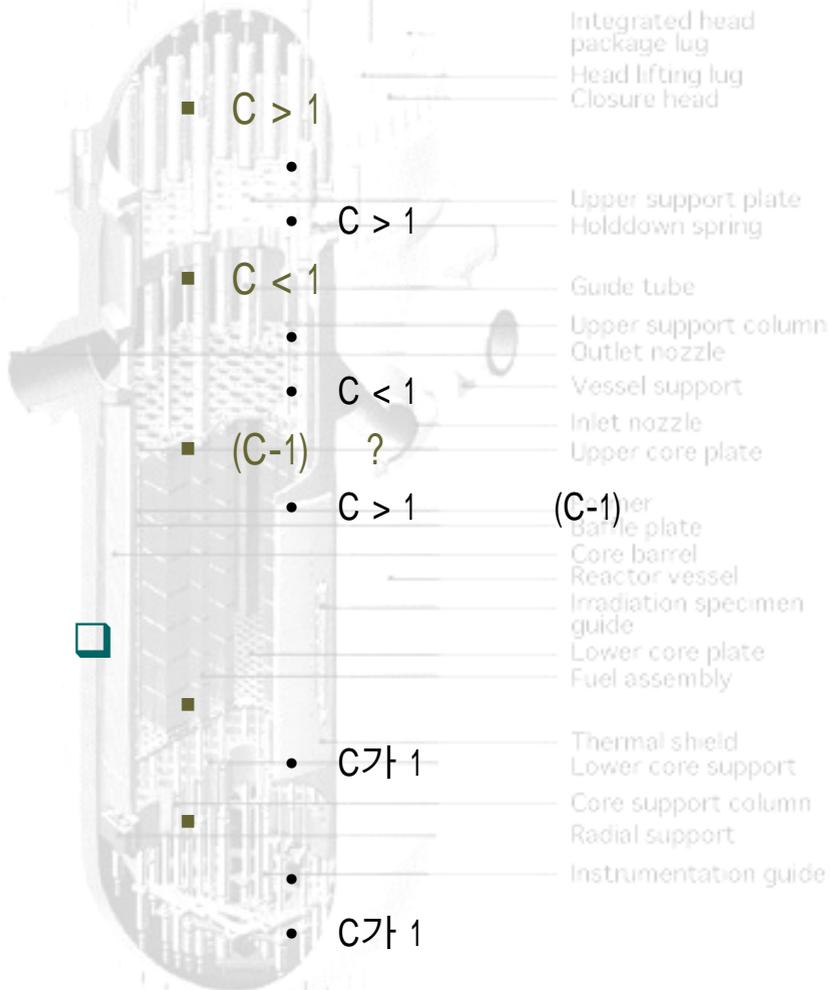


4.



()

$$C = \frac{\text{단위시간당 새로이 생성되는 핵분열성 원자핵의 수}}{\text{단위시간당 소모되는 핵분열성 원자핵의 수}}$$



4.

6.5

6.5

		()
BWR	Integrated head package lug Head lifting lug Closure head U^{235} (2~4 W/O)	0.6
PWR	Upper support plate Hold-down spring U^{235} (2~4 W/O)	0.6
CANDU	Guide tube Upper support column Outlet nozzle Vessel support Inlet nozzle U^{235} (~5 W/O)	0.8
LMFBR	Upper core plate Former Baffle plate Pu (10~20 W/O)	1.0~1.6

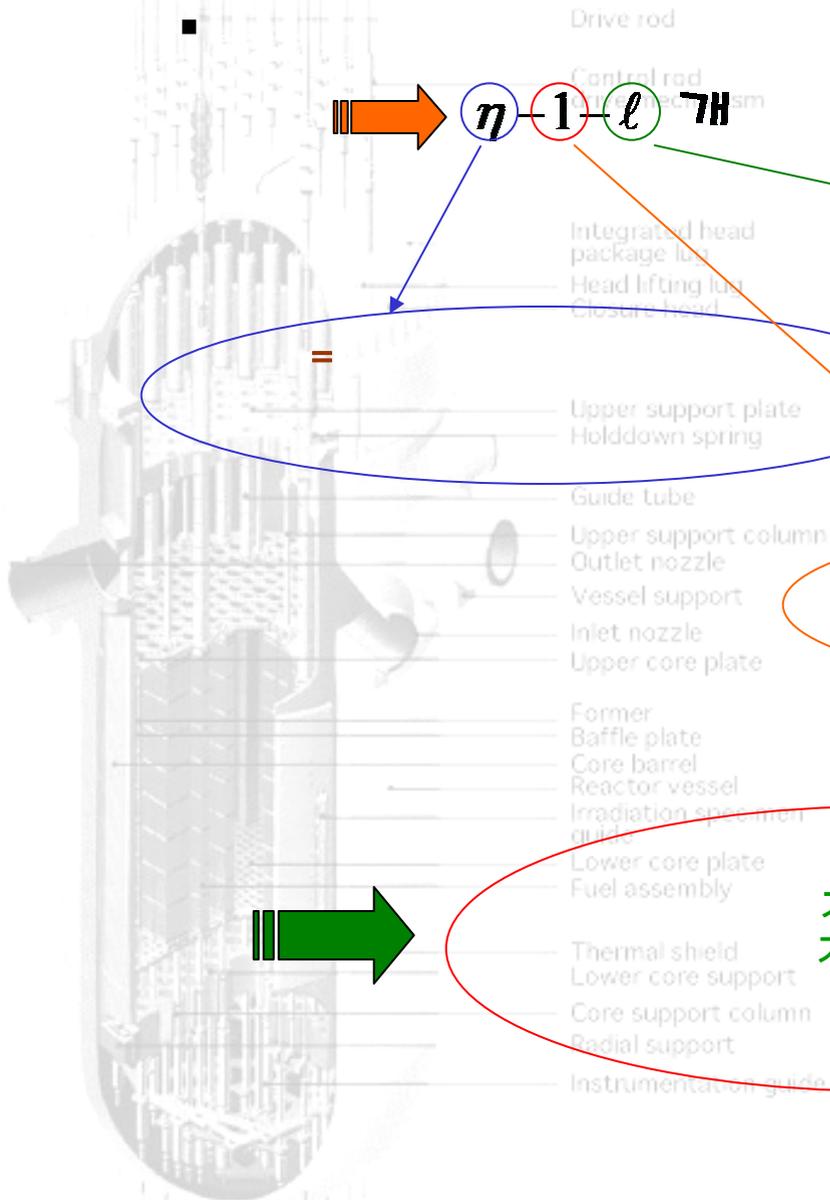
- BWR PWR
- CANDU

Reactor vessel
Irradiation specimen guide
Lower core plate
Fuel assembly
Thermal shield
Lower core support
Core support column
Radial support
Instrumentation guide

가
가
가

U^{238} Pu

4.



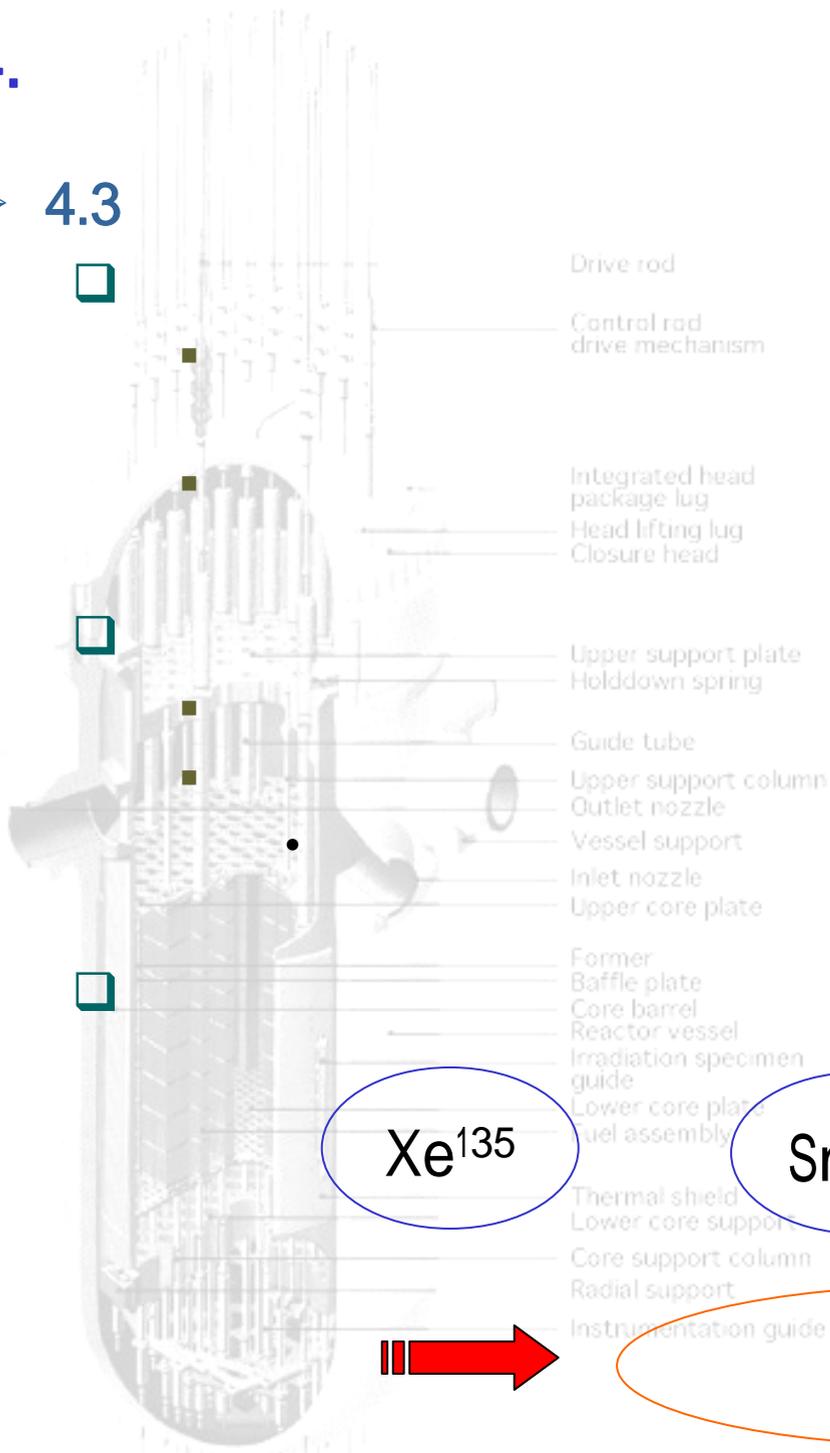
가 가
가 2
(< 2) 가

$\ell =$ (,)

1 =

4.

4.3



Xe^{135}

Sm^{149}



가

k

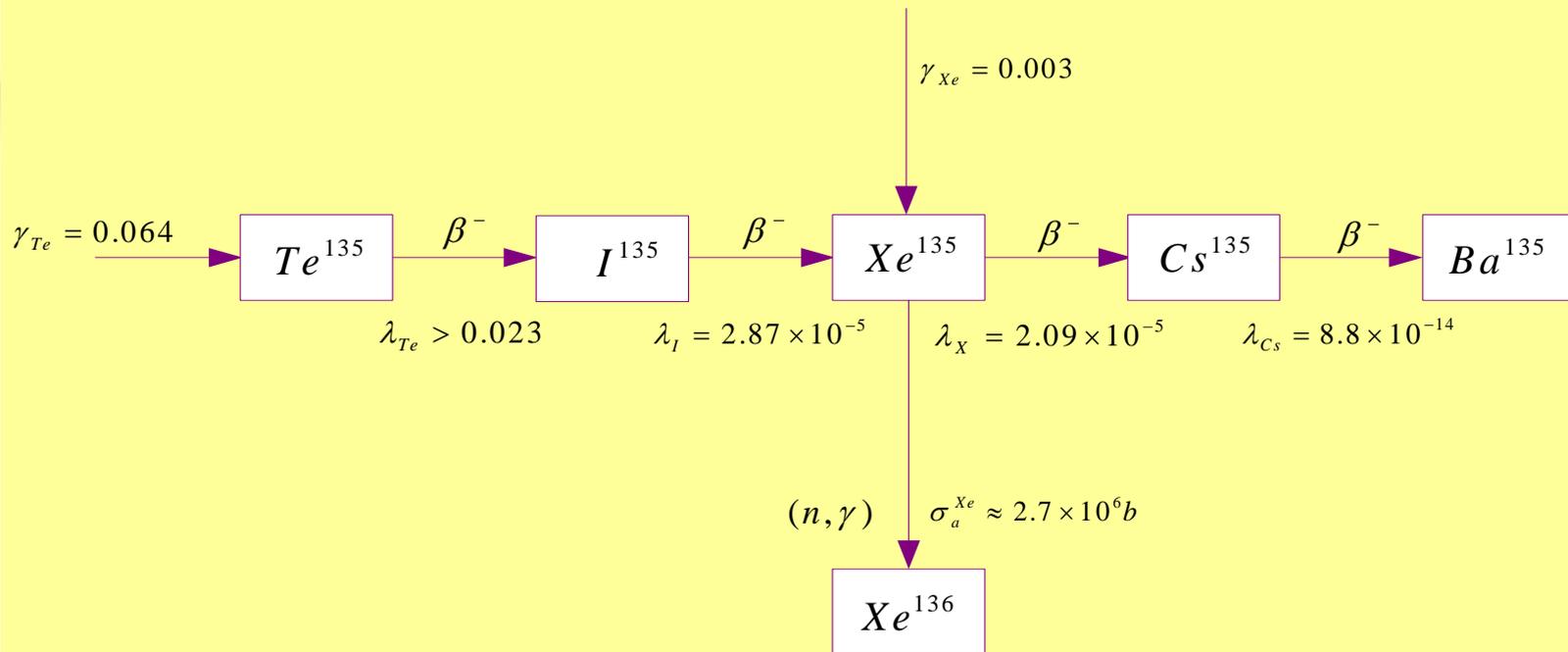


4.

4.3.1 Xe¹³⁵

□ Xe¹³⁵

- Xe¹³⁵
 - Control rod drive mechanism
- Xe¹³⁵
 - Integrated head package lug E = 0.082eV
 - Head lifting lug E = 0.082eV
 - Closure head 2.7 X 10⁶ barn
- Xe¹³⁵
 - Upper support plate



6.13 Xe¹³⁵

4.

- 6.13

가 가

□ Xe¹³⁵

▪ 가

- Te¹³⁵ (30.1) << I¹³⁵ (6.7)

→ Te¹³⁵

6.13

I¹³⁵ Xe¹³⁵

$$\frac{dI(t)}{dt} = \gamma_I \sum_f \phi(t) - \lambda_I I(t) \quad 6.97a$$

$$\frac{dX(t)}{dt} = \gamma_x \sum_f \phi(t) + \lambda_I I(t) - [\sigma_{ax} \phi(t) + \lambda_x] X(t) \quad 6.97b$$



6.6

I¹³⁵, Xe¹³⁵, Pm¹⁴⁹

	U ²³³	U ²³⁵	Pu ²³⁹	Pu ²⁴¹	
λ _I (%)	4.884	6.386	6.100	7.694	λ _I = 0.1035 hr ⁻¹
λ _X (%)	1.363	0.228	1.087	0.255	λ _X = 0.0753 hr ⁻¹
λ _P (%)	0.66	1.13	1.3		λ _P = 0.0128 hr ⁻¹

4.

■ (6.97)

$$I(t) = [I(0) + \gamma_I \int_0^t dt' \Sigma_f \phi(t') e^{\lambda_I t'}] e^{-\lambda_I t} \quad 6.98a$$

$$X(t) = \{X(0) + \int_0^t dt' (\lambda_I I(t') + \gamma_x \Sigma_f \phi(t')\} \exp[-\int_0^t dt'' (\lambda_x + \sigma_{ax} \phi(t''))] \quad 6.98b$$

• (6.98) 가

(가)

• 가

$$I(0)=0, X(0)=0,$$

• (6.98) $\phi(t) = \phi_0$

$$I(t) = \frac{\gamma_I \Sigma_f \phi_0}{\lambda_I} (1 - e^{-\lambda_I t}) \quad 6.99a$$

$$X(t) = \frac{(\gamma_I + \gamma_x) \Sigma_f \phi_0}{\lambda_x + \sigma_{ax} \phi_0} \{1 - e^{-(\lambda_x + \sigma_{ax} \phi_0)t}\} + \frac{\gamma_I \Sigma_f \phi_0}{\lambda_x - \lambda_I + \sigma_{ax} \phi_0} \{e^{-(\lambda_x + \sigma_{ax} \phi_0)t} - e^{-\lambda_I t}\} \quad 6.99b$$

4.

• (6.99) 가 ^{135}Xe 6.14

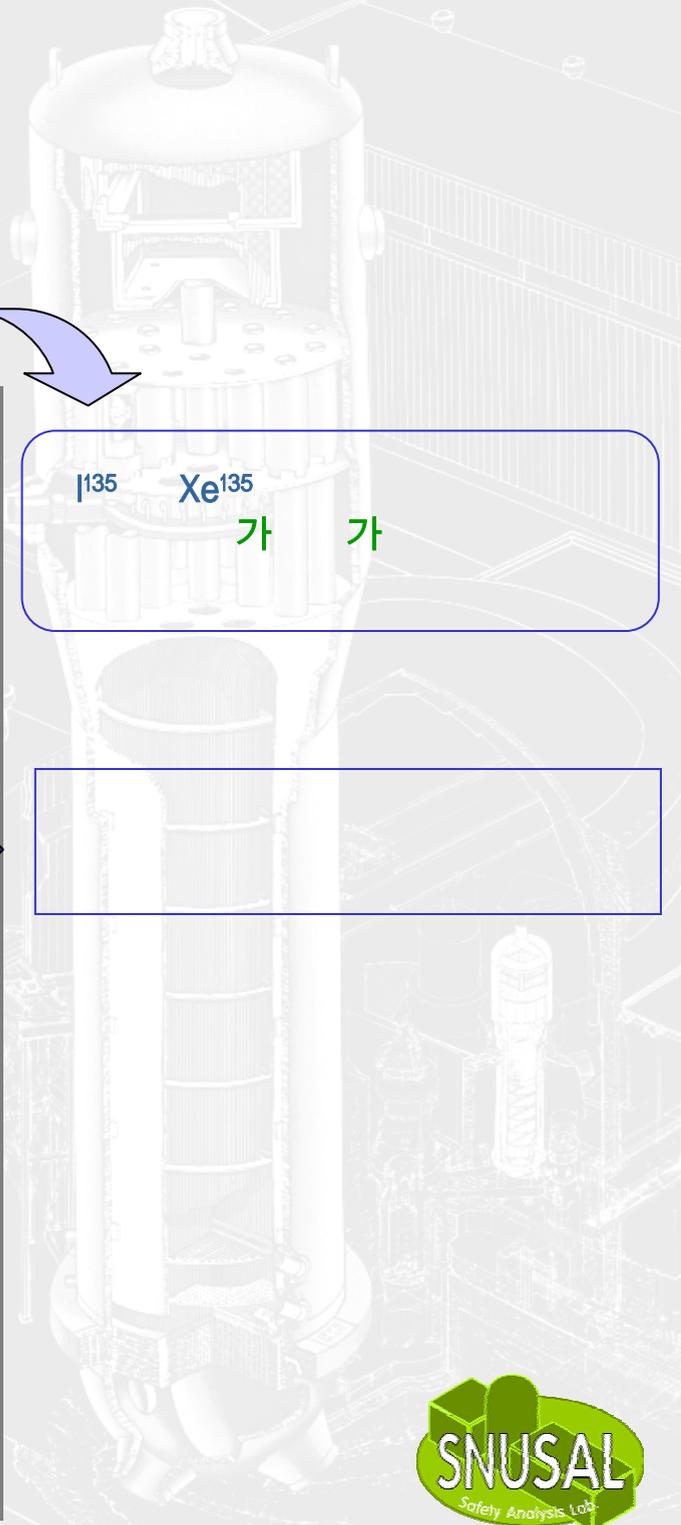
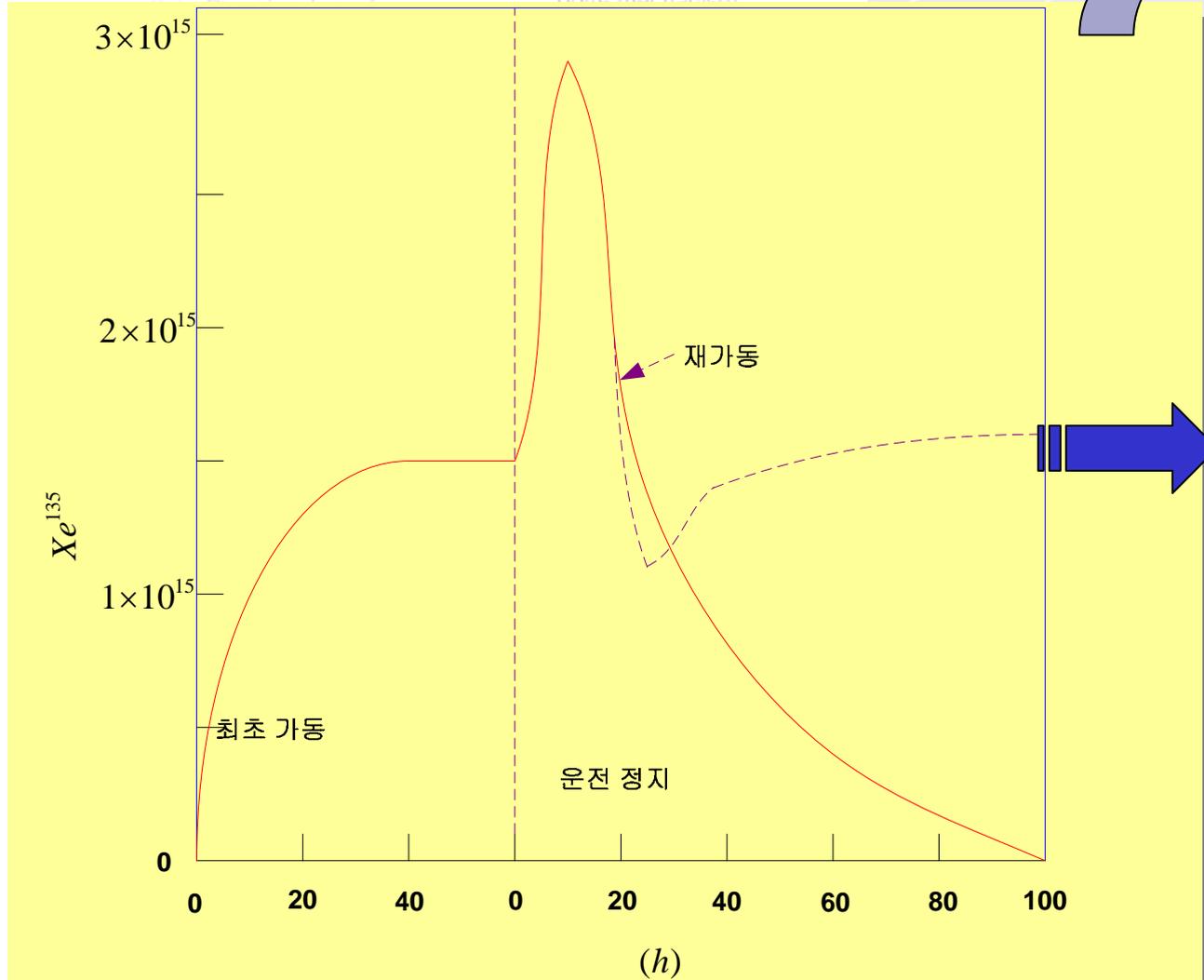


그림 6.14 운전조건에 따른 Xe^{135} 의 수밀도 변화

4.

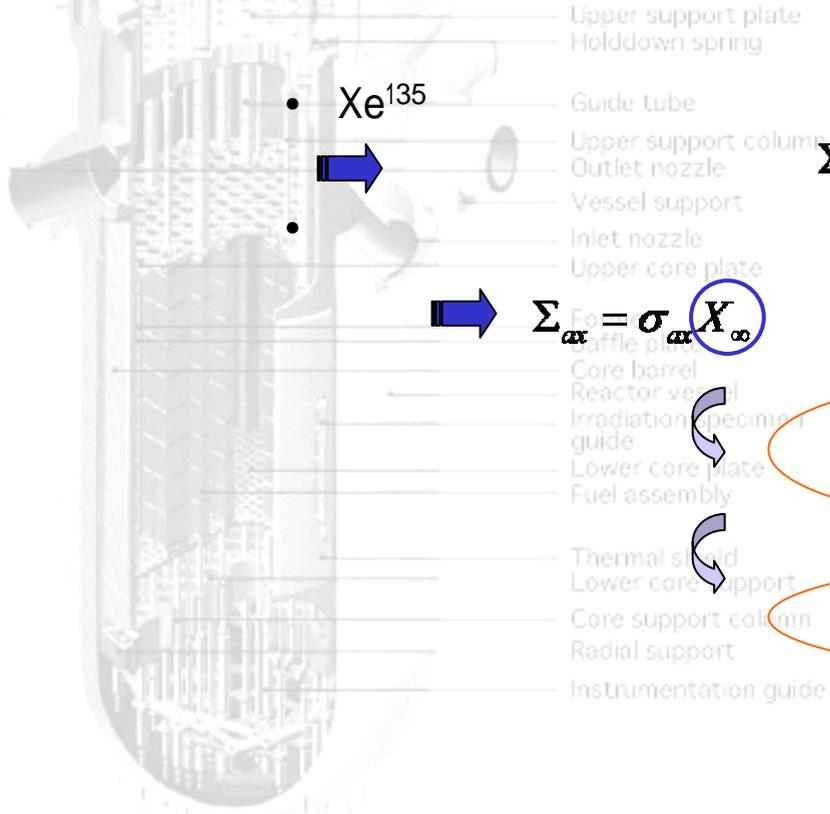
- $dL / dt = 0 \quad dX / dt$

(6.97) $t =$

$$I_{\infty} = \frac{\gamma_I \Sigma_f \phi_0}{\lambda_I}$$

$$X_{\infty} = \frac{(\gamma_I + \gamma_x) \Sigma_f \phi_0}{\sigma_{ax} \phi_0 + \lambda_x}$$

6.100

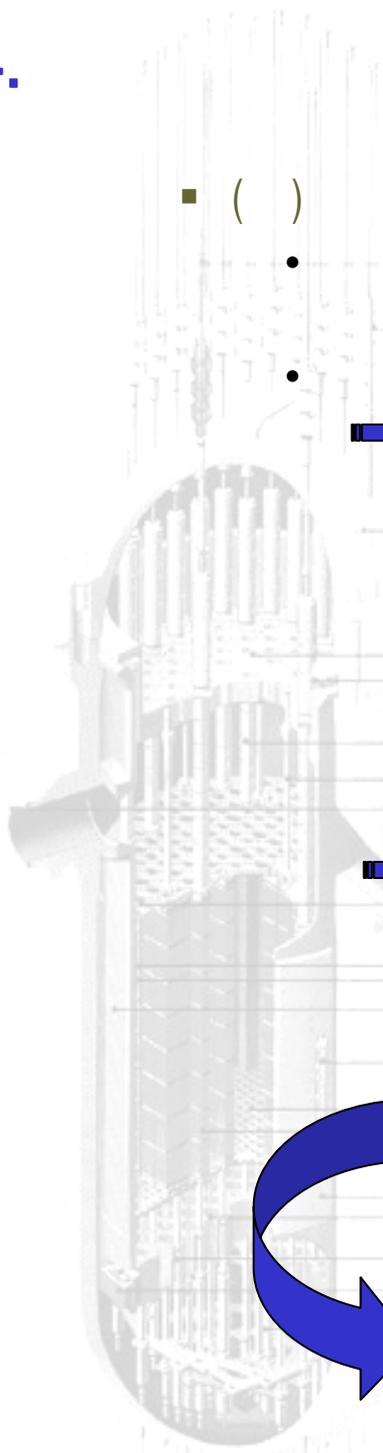


$$\Sigma_{ax} = \sigma_{ax} X(t)$$

$$X_{\infty} \quad \phi_0$$

4.

I^{135} Xe^{135}



가 Drive rod Xe^{135} 가
 I^{135} 가 Control rod drive mechanism

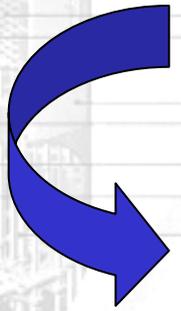
→ (6.97) $\phi(t) = 0$

$\frac{dI(t)}{dt} = -\lambda_I I(t)$ 6.101a

$\frac{dX(t)}{dt} = \lambda_I I(t) - \lambda_X X(t)$ 6.101b

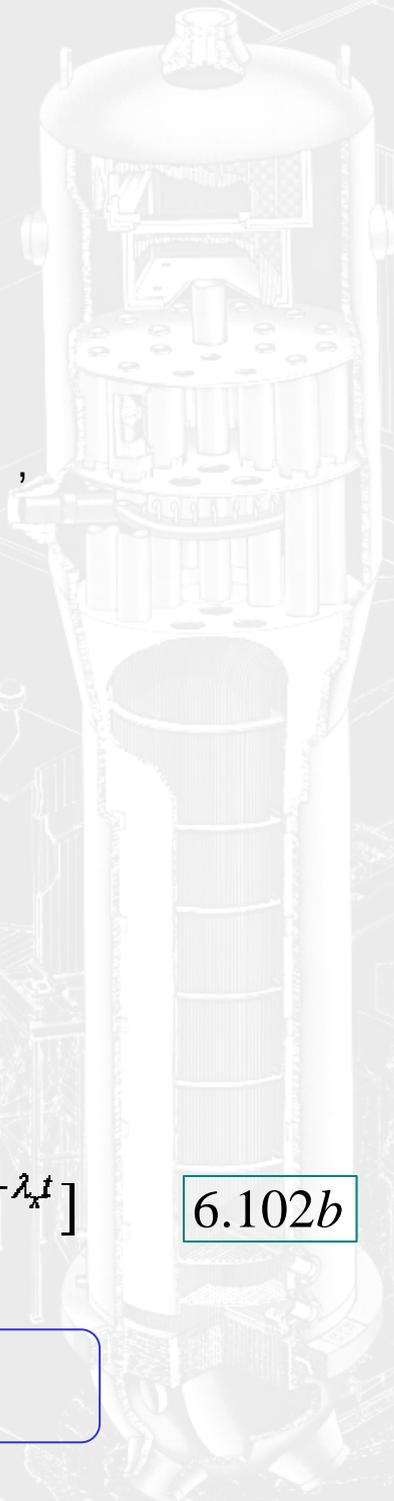
$I(t) = I(0)e^{-\lambda_I t}$ 6.102a

$X(t) = X(0)e^{-\lambda_X t} + \frac{\lambda_I I(0)}{\lambda_I - \lambda_X} [e^{-\lambda_I t} - e^{-\lambda_X t}]$ 6.102b

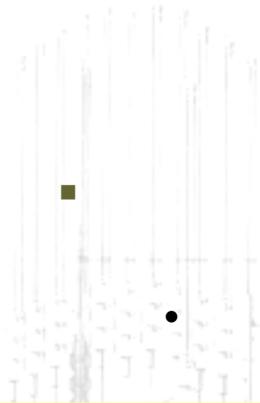


$I(0), X(0) =$ I^{135} Xe^{135}

Xe^{135} 가
 I^{135} Xe^{135}



4.

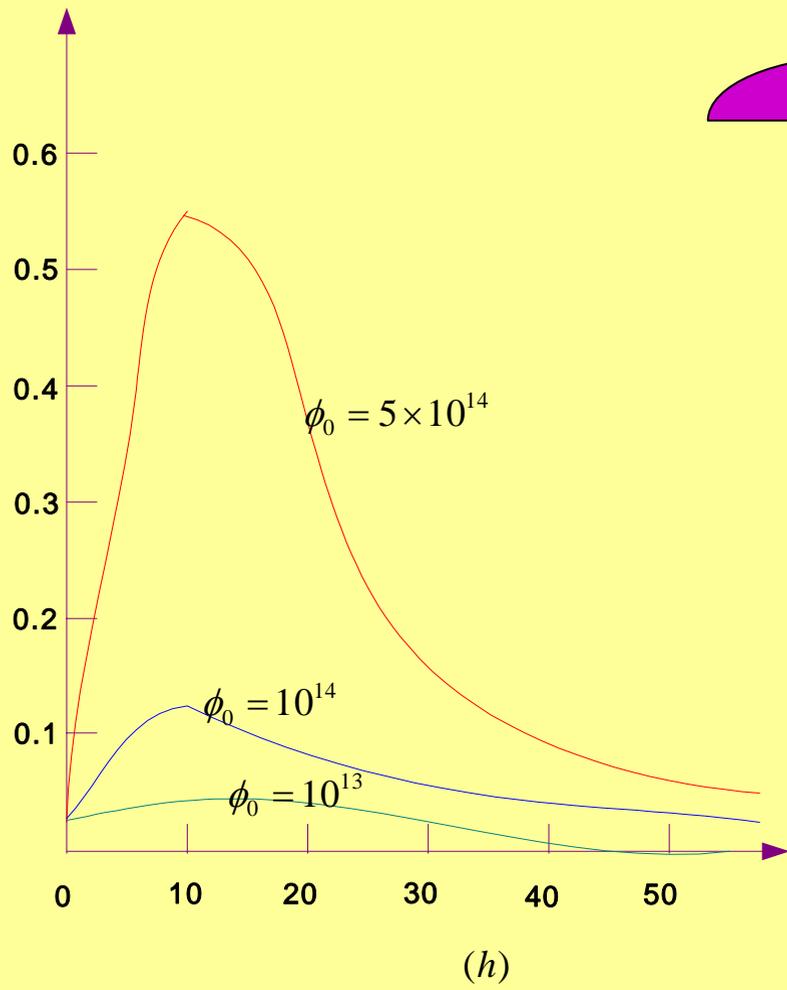
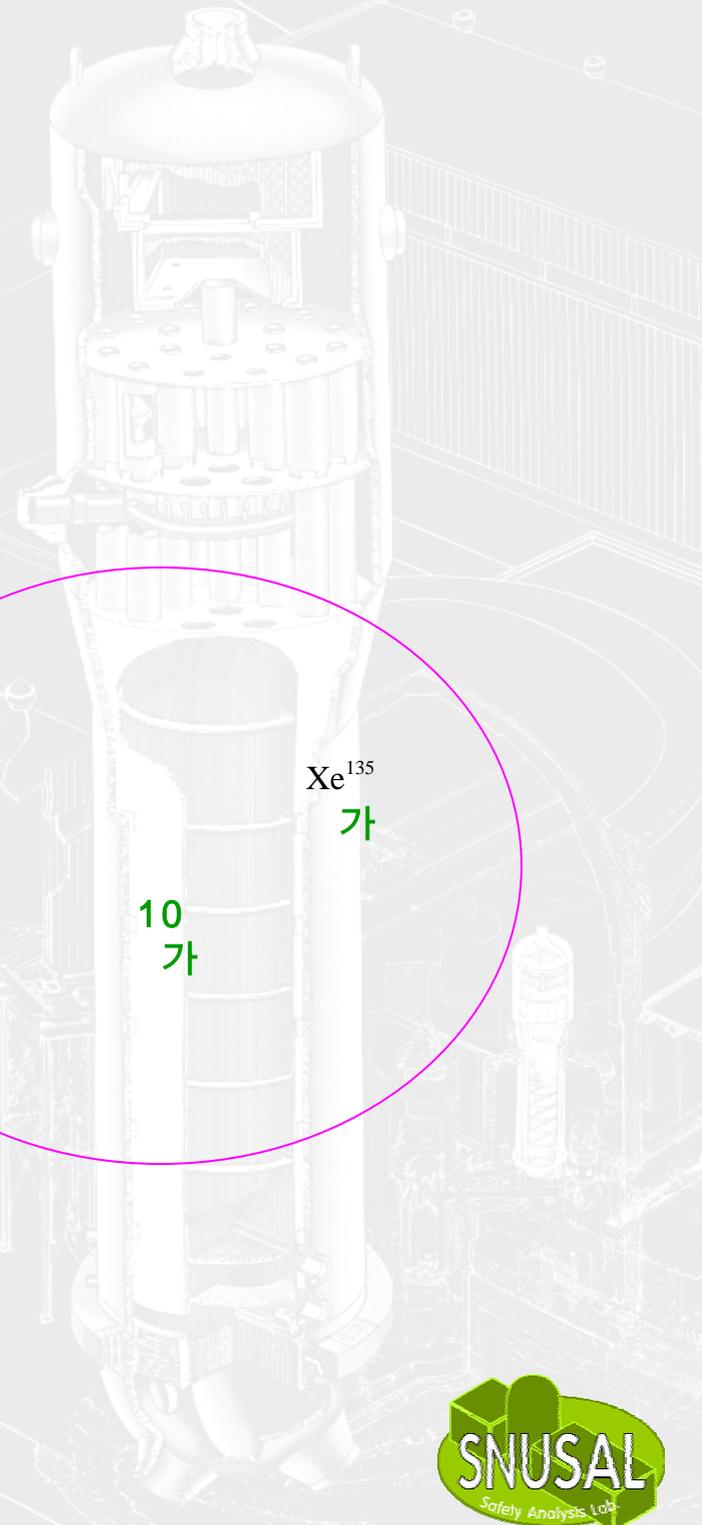


Xe^{135}

가 가 가

Drive rod
6.15 Control rod drive mechanism

Xe^{135}



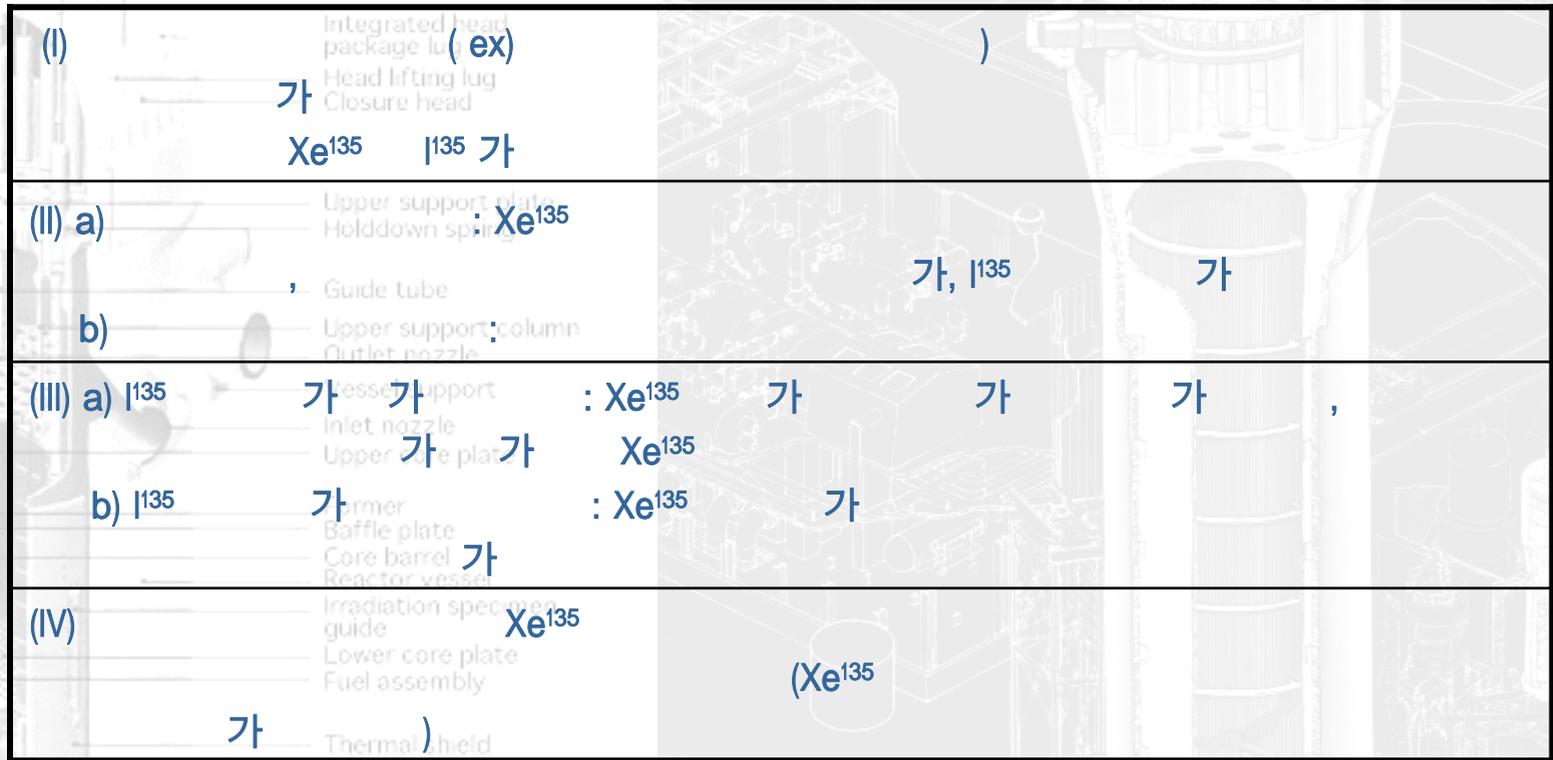
6.15

Xe^{135}

4.

☐ Xe¹³⁵

- Xe¹³⁵ Drive rod
- Xe¹³⁵ 가 Control rod drive mechanism
 - Xe¹³⁵



4.

4.3.2 Sm^{149}

□ Sm^{149}

■ Sm^{149}

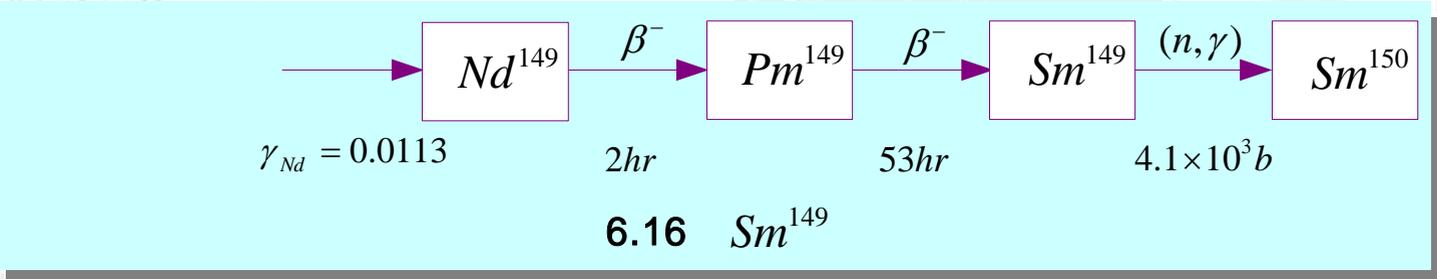
Xe^{135}

Xe^{135}

$E = 0.025eV$

$4.1 \times 10^3 \text{ barn}$

가



□ Sm^{149}

■ 가

• Nd^{149}

→ Nd^{149}

$(2 \text{ }) \ll Pm^{149}$

Pm^{149} 가

(53)

가

4.

- (6.93) Pm^{149} Sm^{149}

$$\frac{dP(t)}{dt} = \gamma_{Nd} \Sigma_f \phi(t) - \lambda_p P(t)$$

6.103a

$$\frac{dS(t)}{dt} = \lambda_p P(t) - \sigma_{as} S(t) \phi(t)$$

6.103b

$P(t), S(t) : Pm^{149}$ Sm^{149}
 $Nd : Nd^{149}$

6.6

- (6.103)

- $\phi(t)$ ϕ_0 가 (6.103)

$$P(t) = \frac{\gamma_p \Sigma_f \phi_0}{\lambda_p} (1 - e^{-\lambda_p t}) + P(0) e^{-\lambda_p t}$$

$$S(t) = S(0) e^{-\sigma_{as} \phi_0 t} + \frac{\gamma_p \Sigma_f}{\sigma_{as}} (1 - e^{-\sigma_{as} \phi_0 t}) - \frac{\gamma_p \Sigma_f \phi_0 - \lambda_p P(0)}{\lambda_p - \sigma_{as} \phi_0} (e^{-\sigma_{as} \phi_0 t} - e^{-\lambda_p t})$$

6.104

$P(0), S(0) : t=0$ Pm^{146} Sm^{149}



4.

■ (가)

가

•

가 rod

• Pm¹⁴⁹

Sm¹⁴⁹

$$P_{\infty} = \frac{\gamma_{Nd} \Sigma_f \phi_0}{\lambda_p} \quad 6.105a$$

$$S_{\infty} = \frac{\gamma_{Nd} \Sigma_f}{\sigma_{as}} \quad 6.106a$$

• ()

(6.104)

$$P(t) = P_{\infty} e^{-\lambda_p t}$$

$$S(t) = S_{\infty} + P_{\infty} (1 - e^{-\lambda_p t})$$

P(0)=0 , S(0)=0

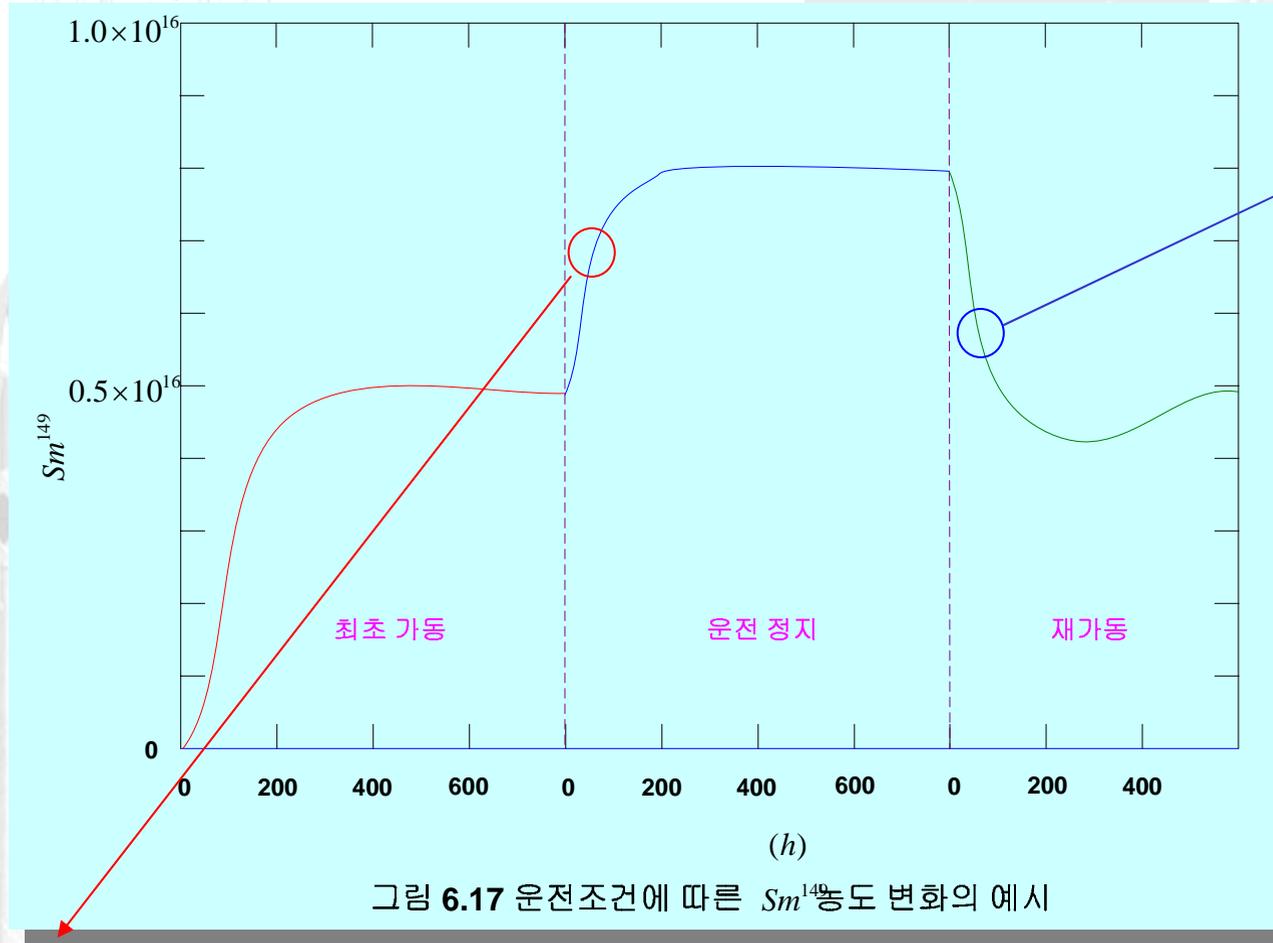
P(t)

S(t)

6.106a

6.106b

4.



Sm^{149}
가

Sm^{149}
 Pm^{149}
가
가

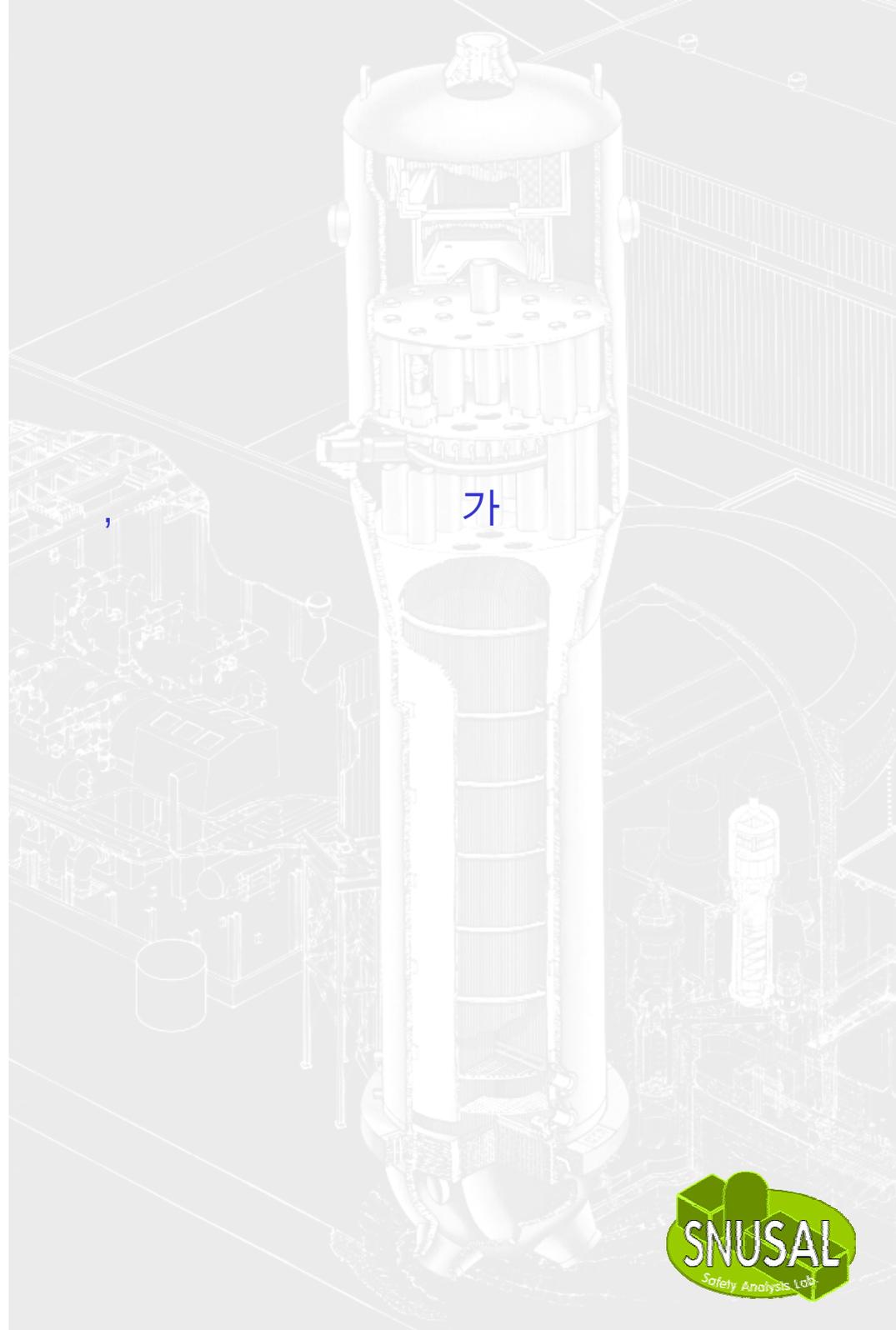
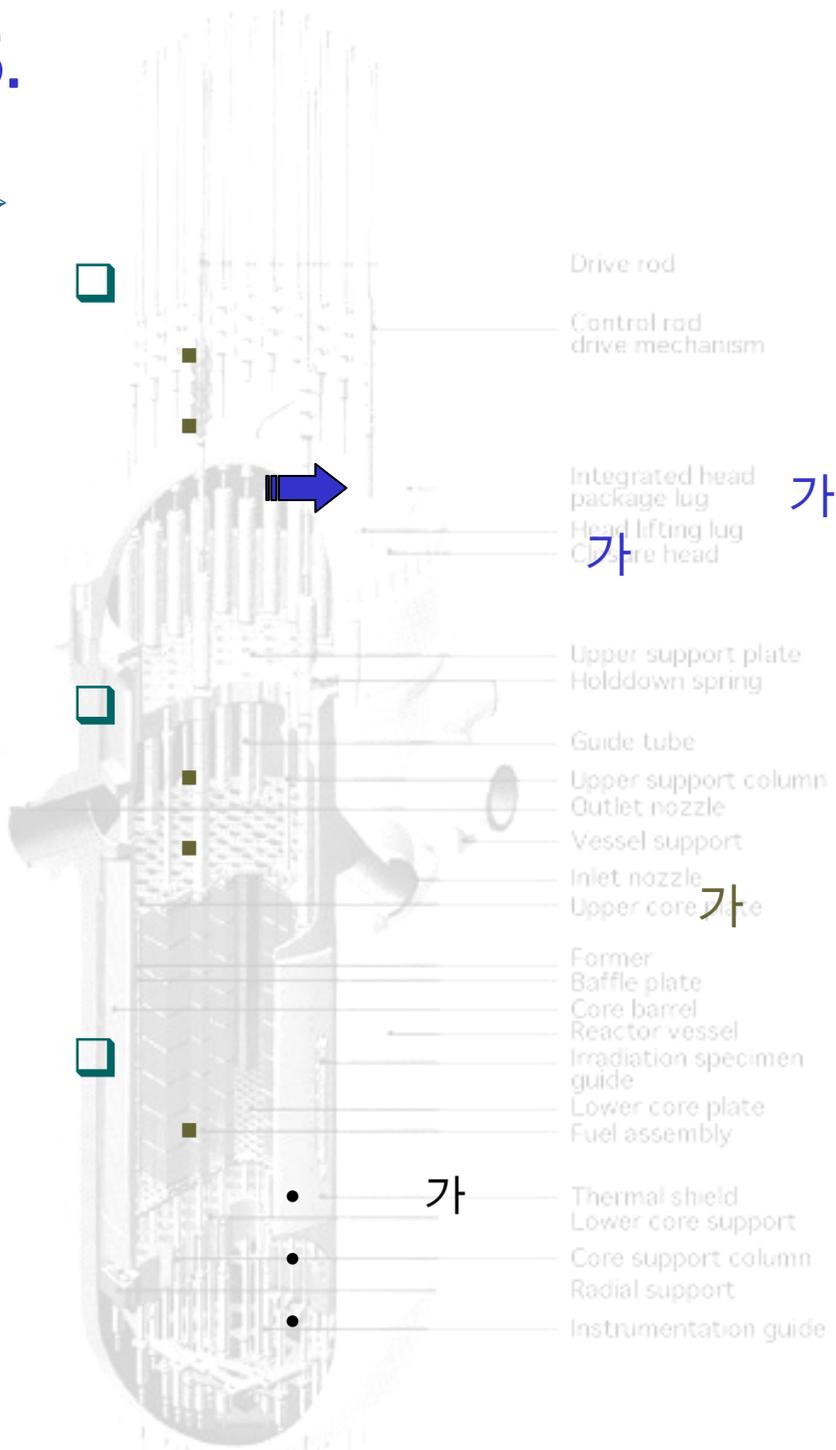
가

Sm^{149}
가

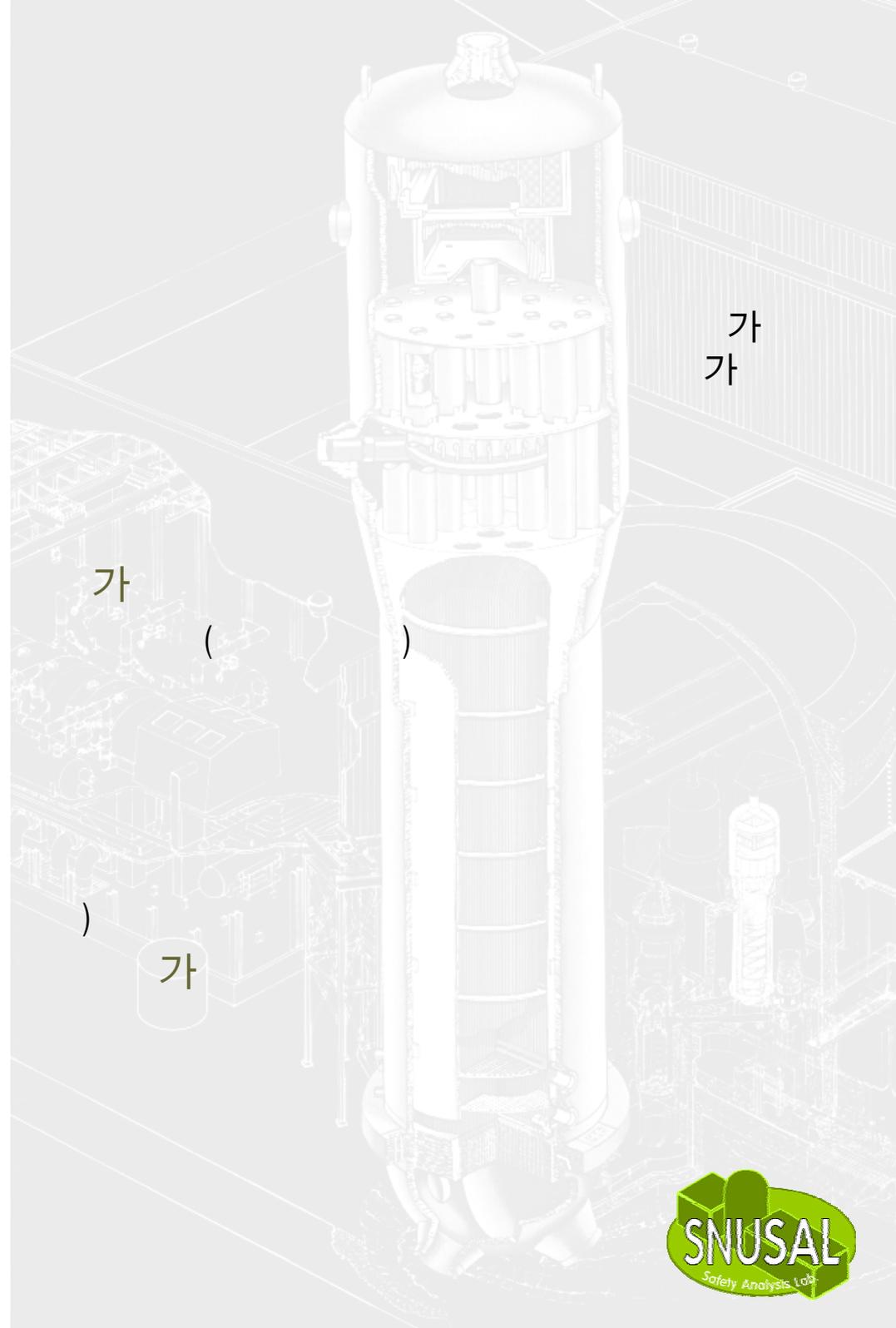
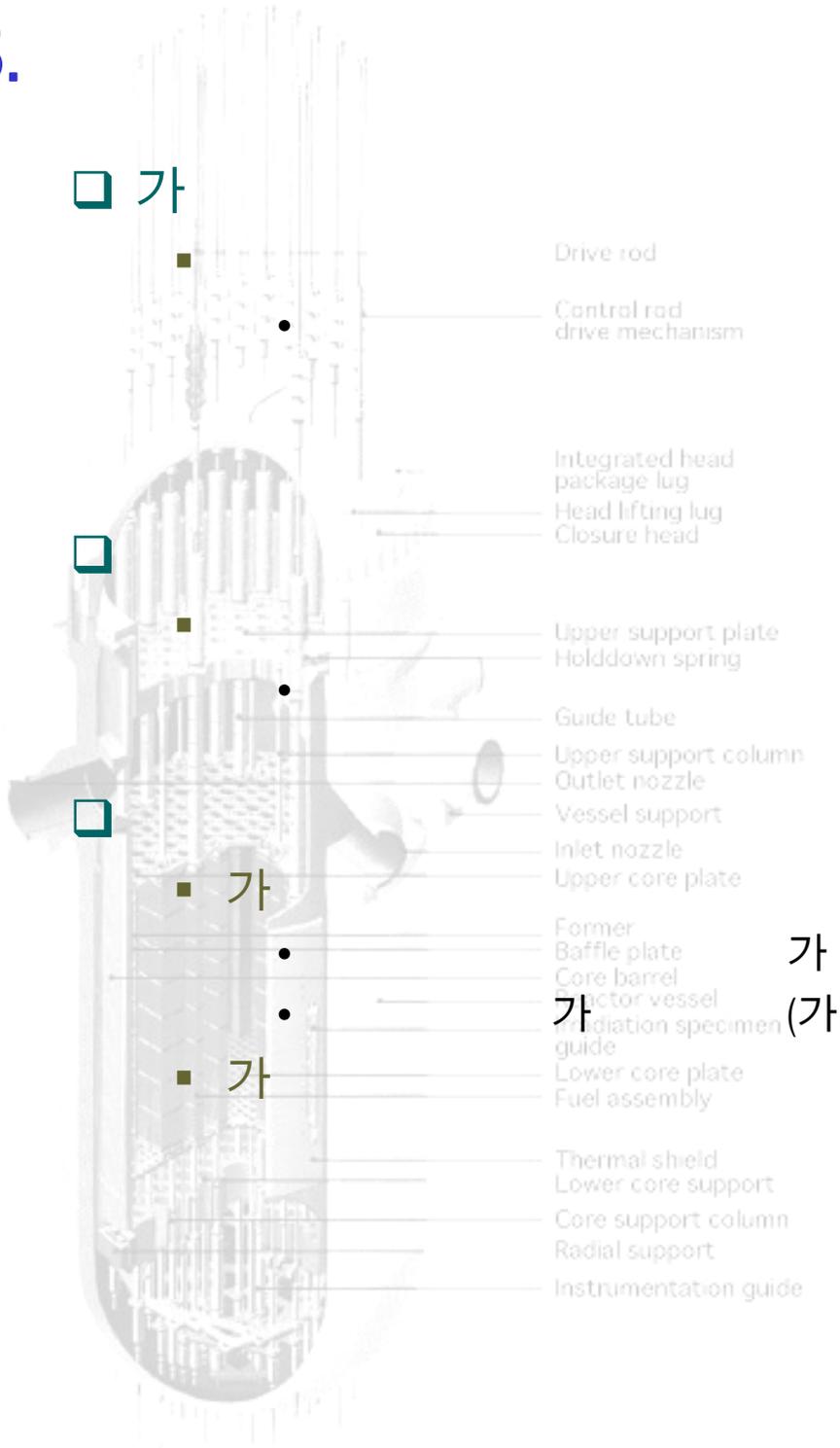
가
, Sm^{149}
가

가

5.



5.



5.

6.18 가

가

Drive rod

			13		12						
			14								
			24		5		24				
			24		8	45	8		24		
		24		8		8		8		24	
	24		8		8		8		8	24	
12		8		8		12		8		8	12
	8		8		12		12		8		8
12		8		8		12		8		8	12
	14		8		8		8		8		24
		24		8		5		8		24	
			24		8	45	8		24		
			24		8		24				
					12		12		14		

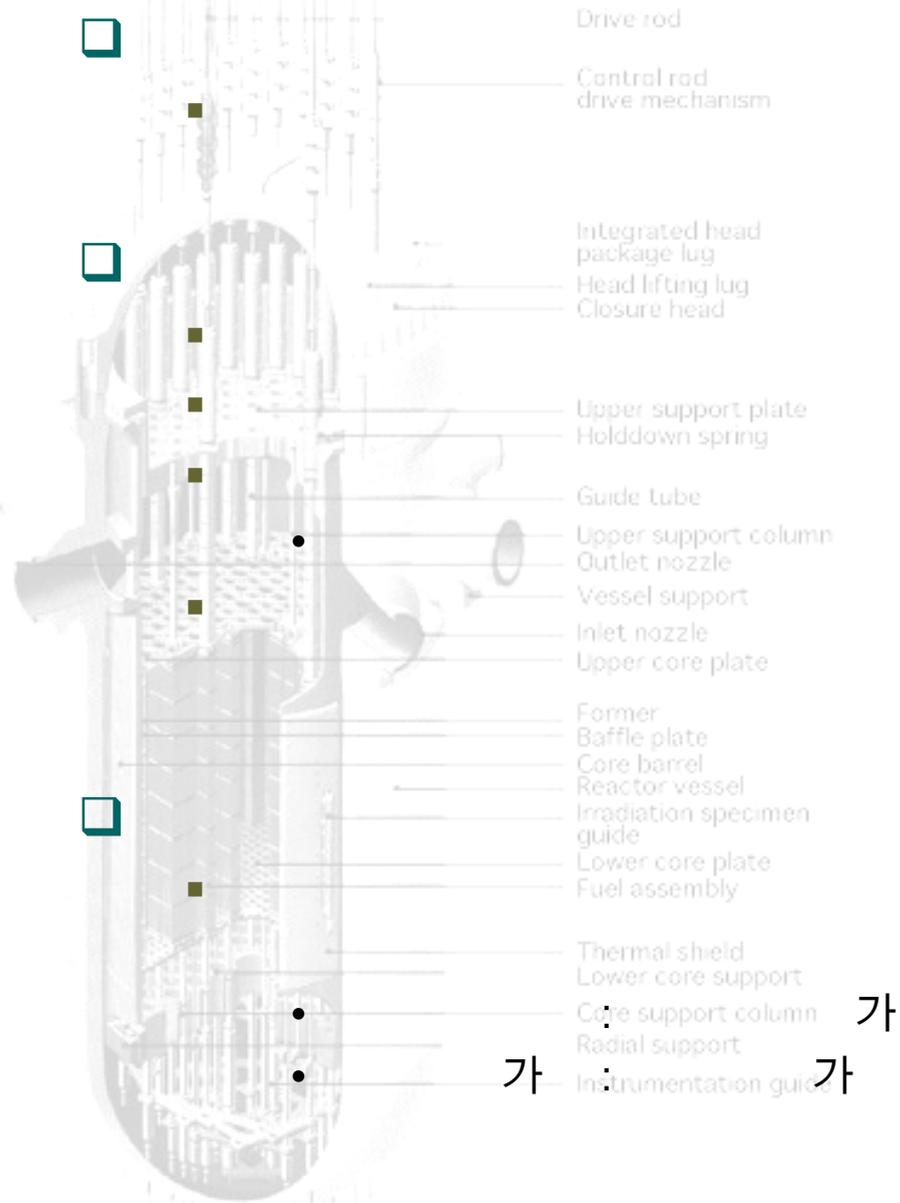
6.18 가
(

가

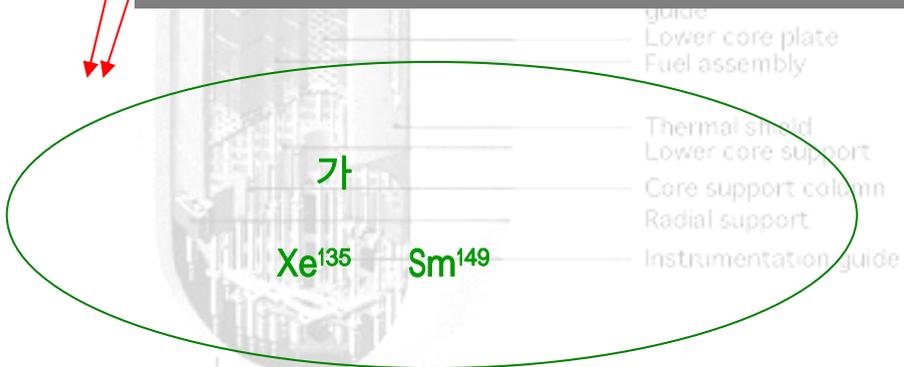
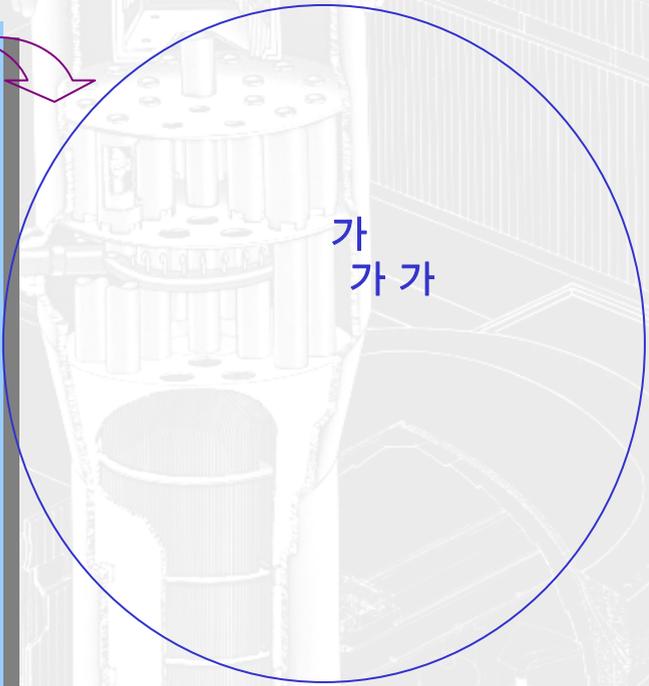
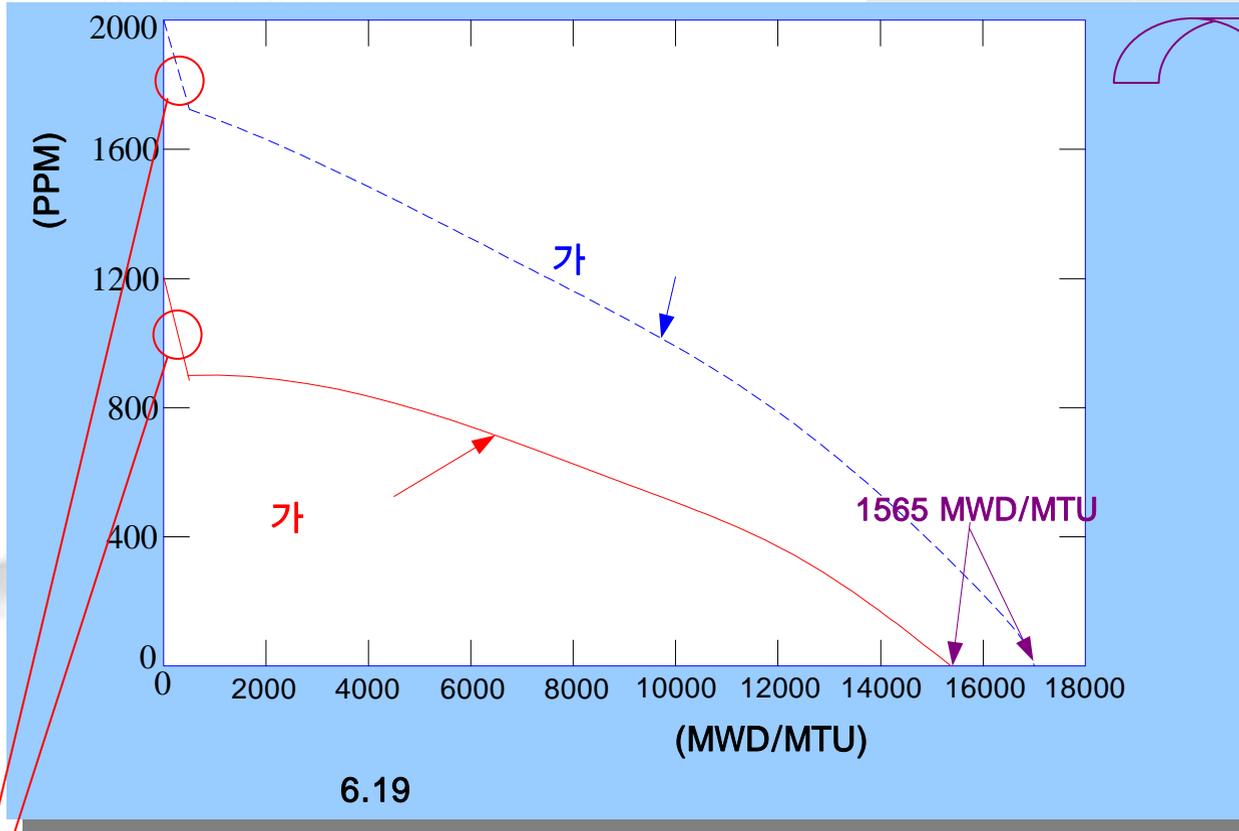
)

5.

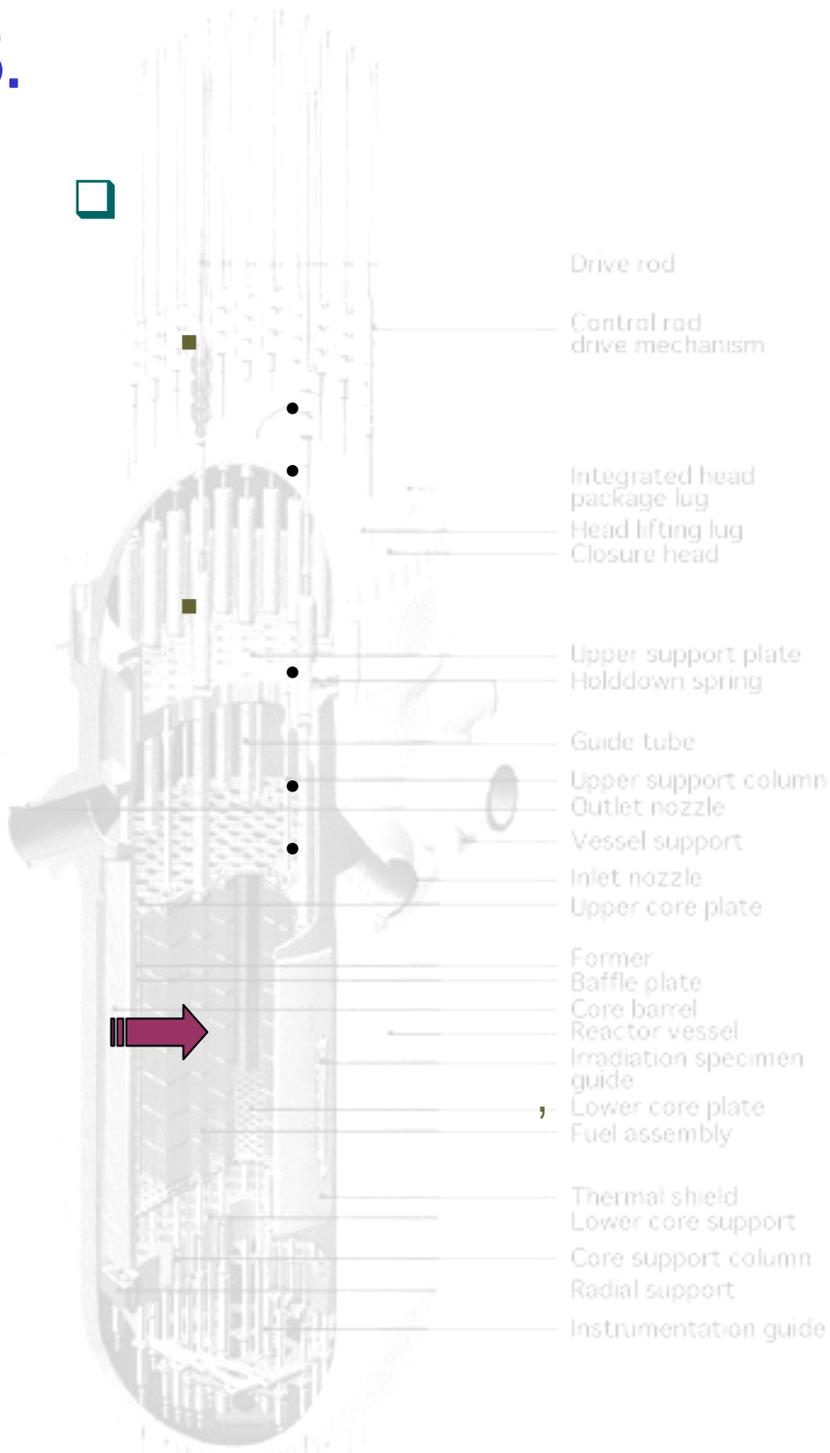
➤ 5.2



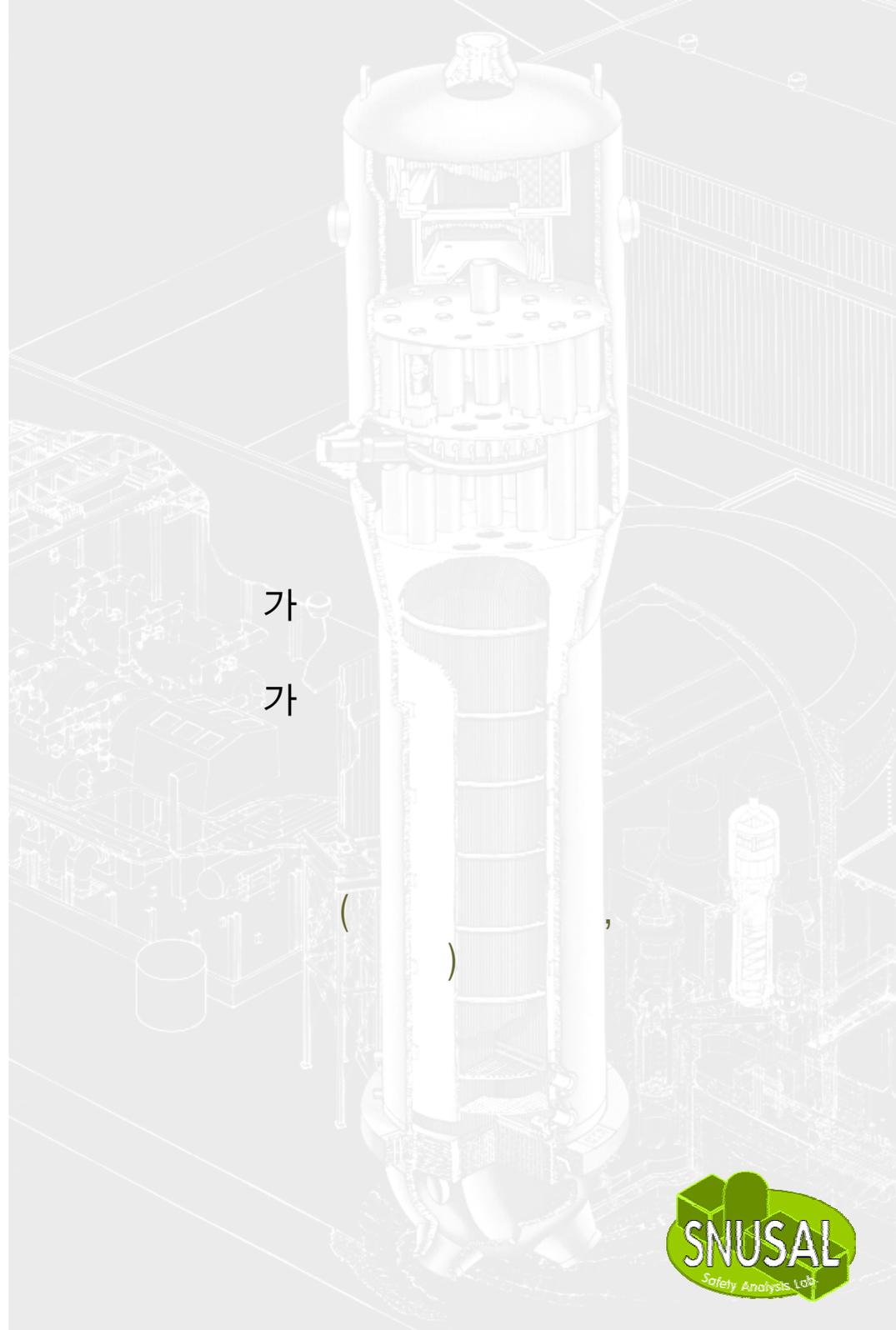
5.



5.



가

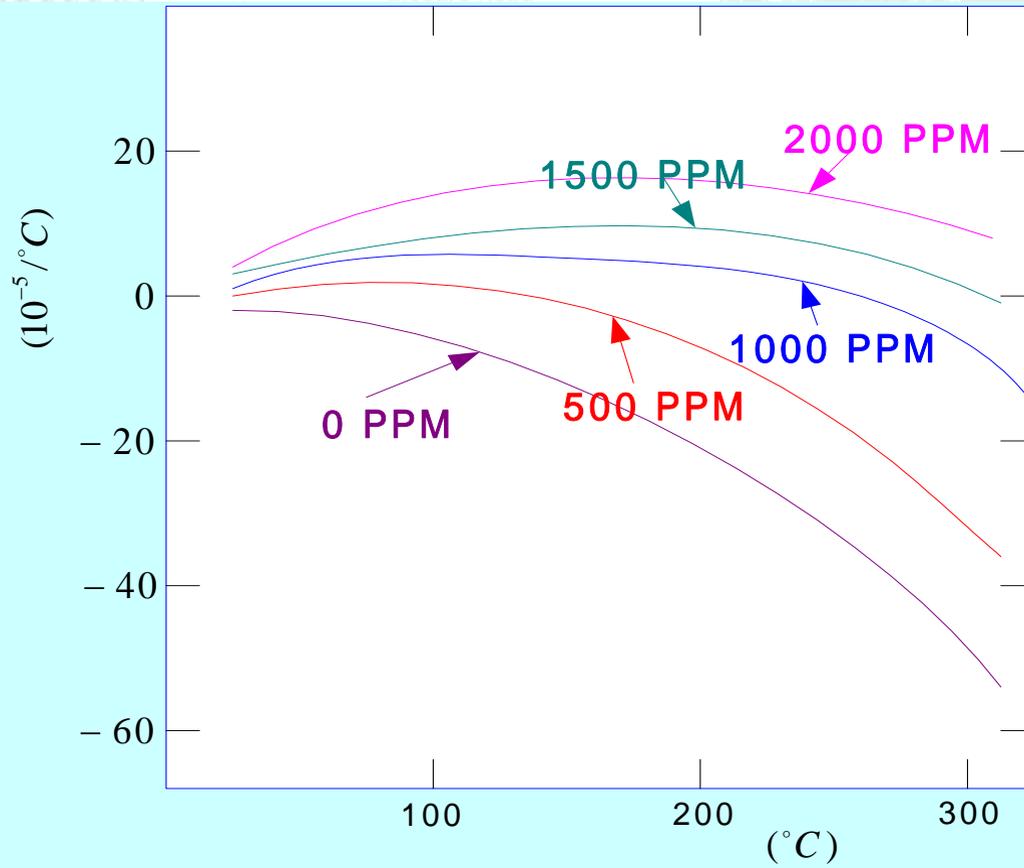


5.



6.20 가

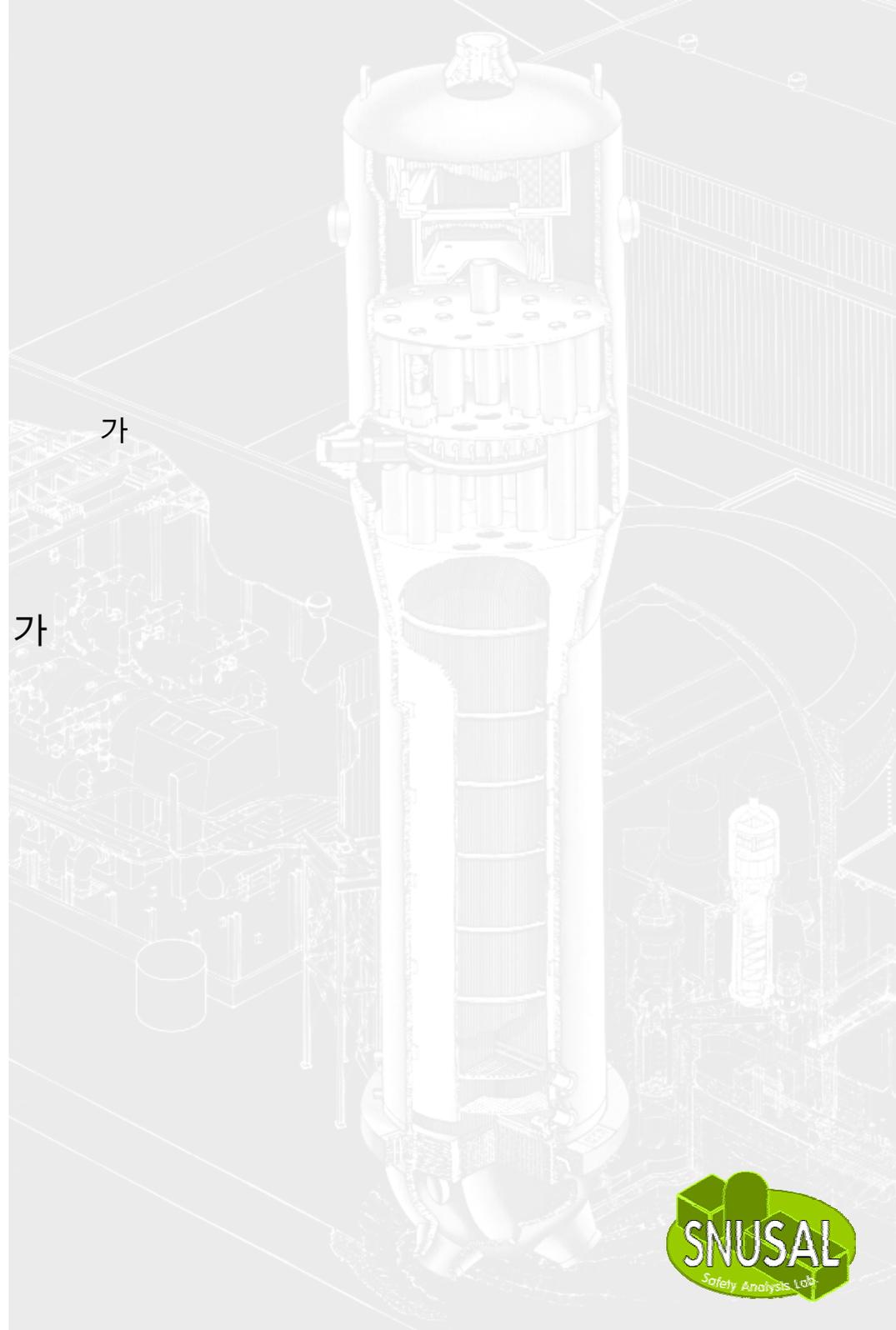
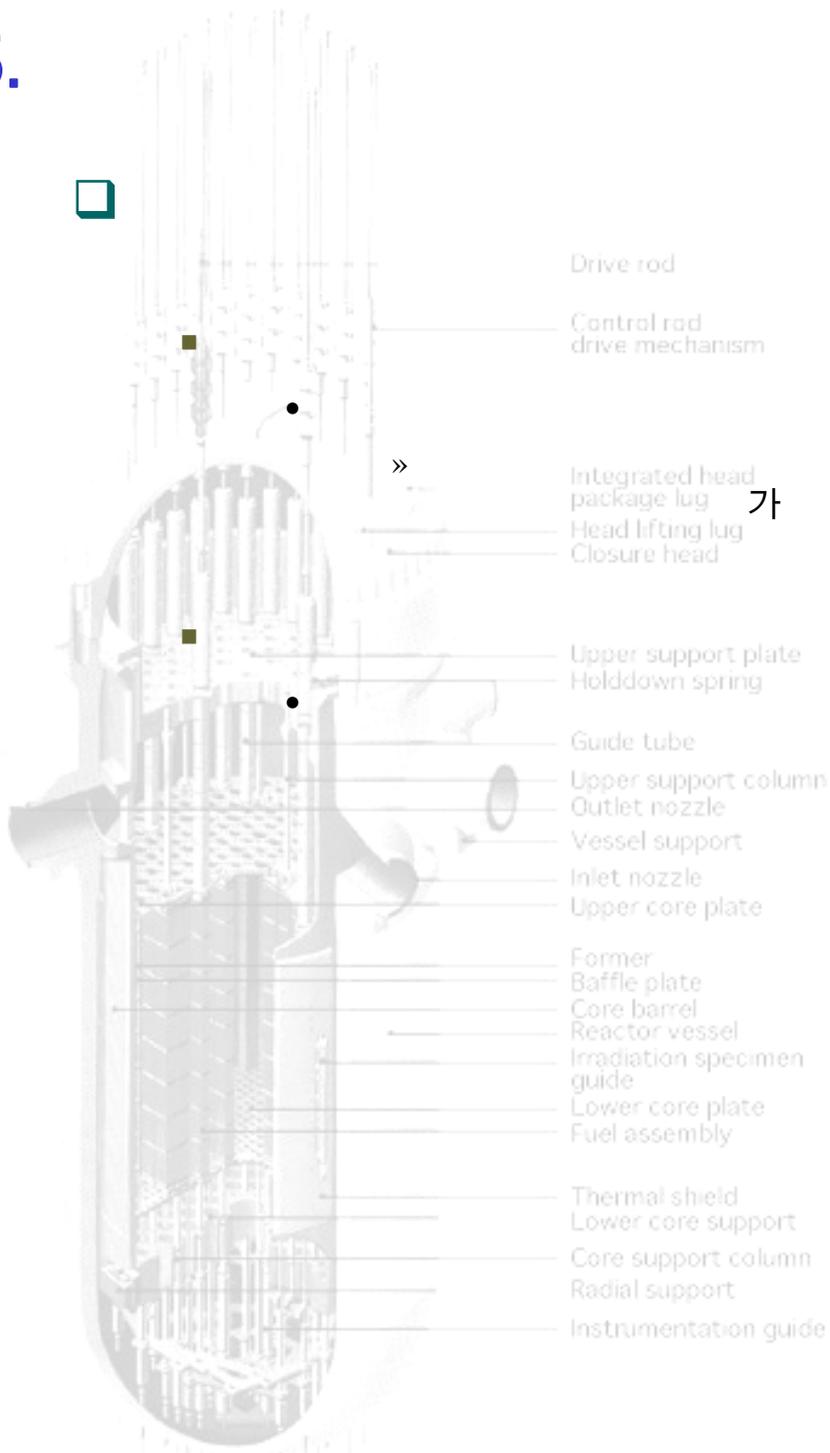
Drive rod
Control rod drive mechanism
Integrated head package lug
Head lifting lug
Closure head



6.20 가

가

5.



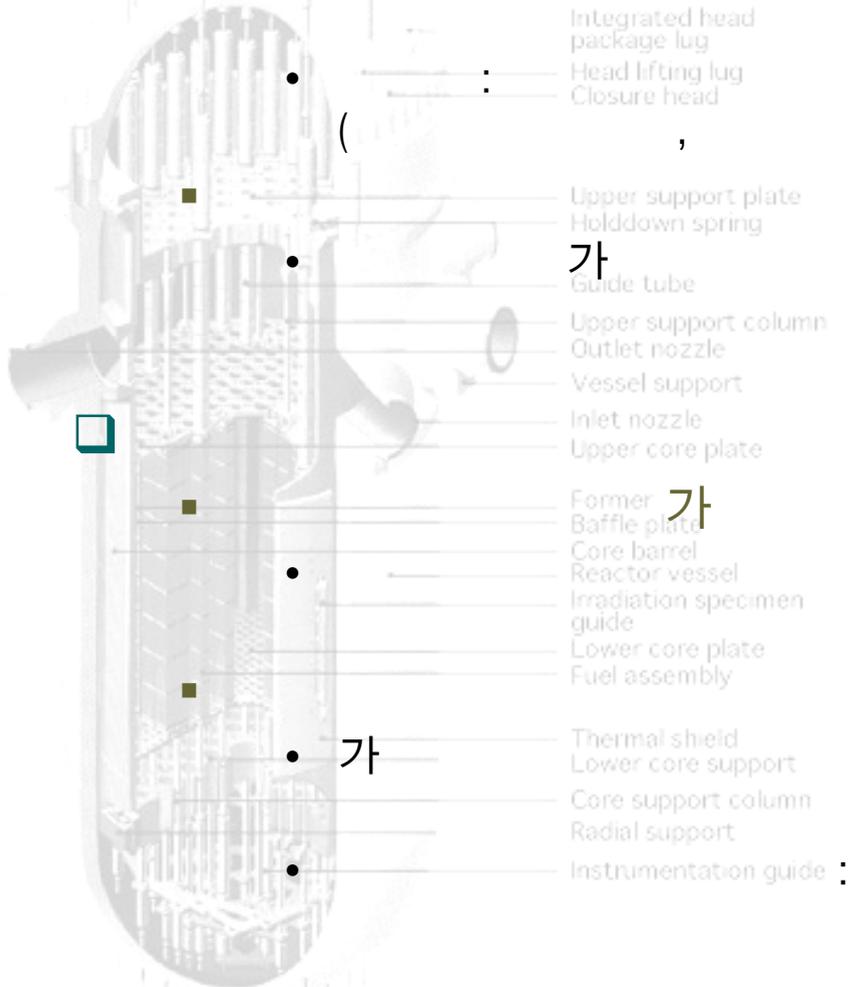
5.

➤ 5.3



가

가



Drive rod

Control rod drive mechanism

Integrated head package lug
Head lifting lug
Closure head

Upper support plate
Holddown spring

가
Guide tube
Upper support column
Outlet nozzle

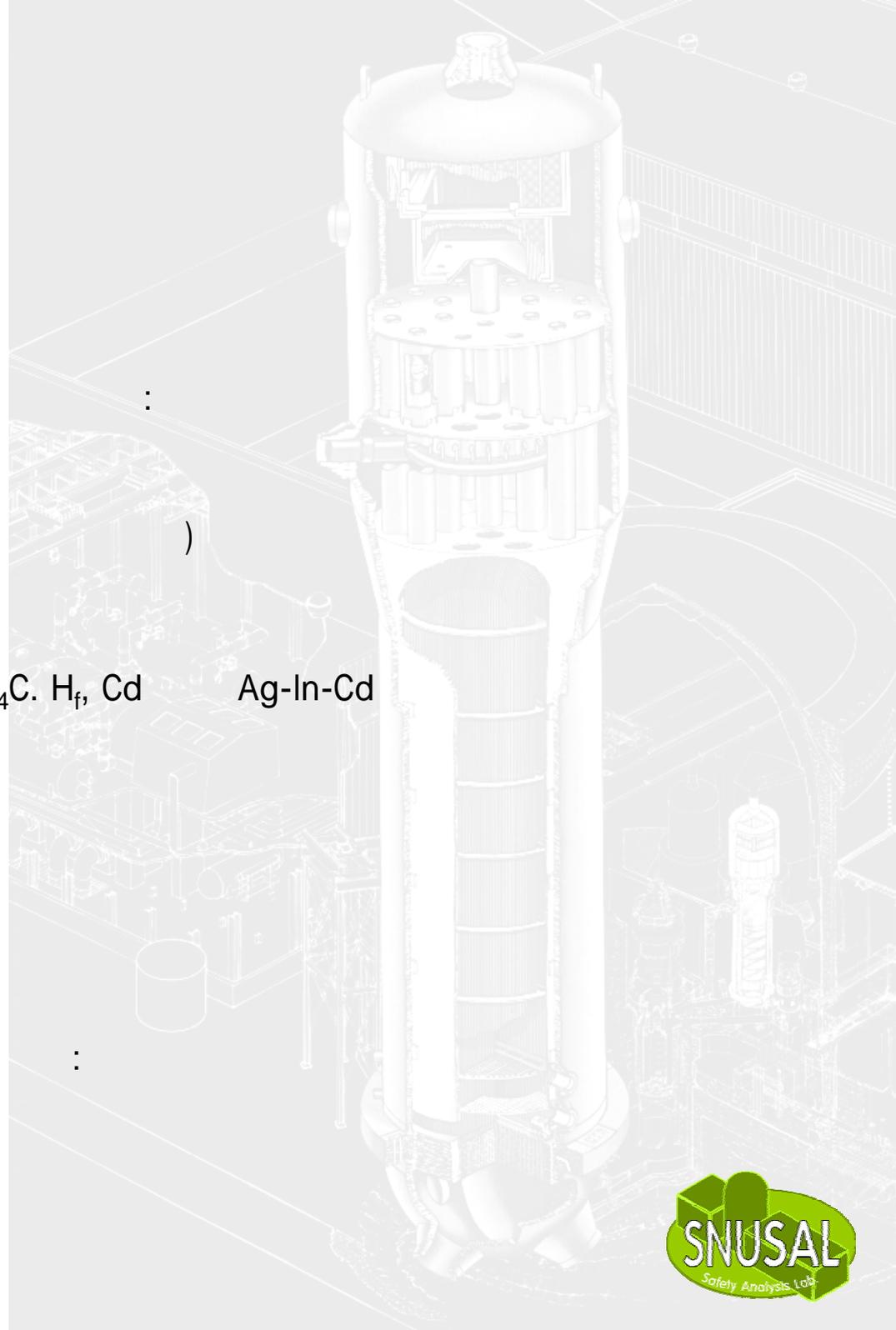
Vessel support
Inlet nozzle
Upper core plate

Former 가
Baffle plate
Core barrel
Reactor vessel
Irradiation specimen guide
Lower core plate
Fuel assembly

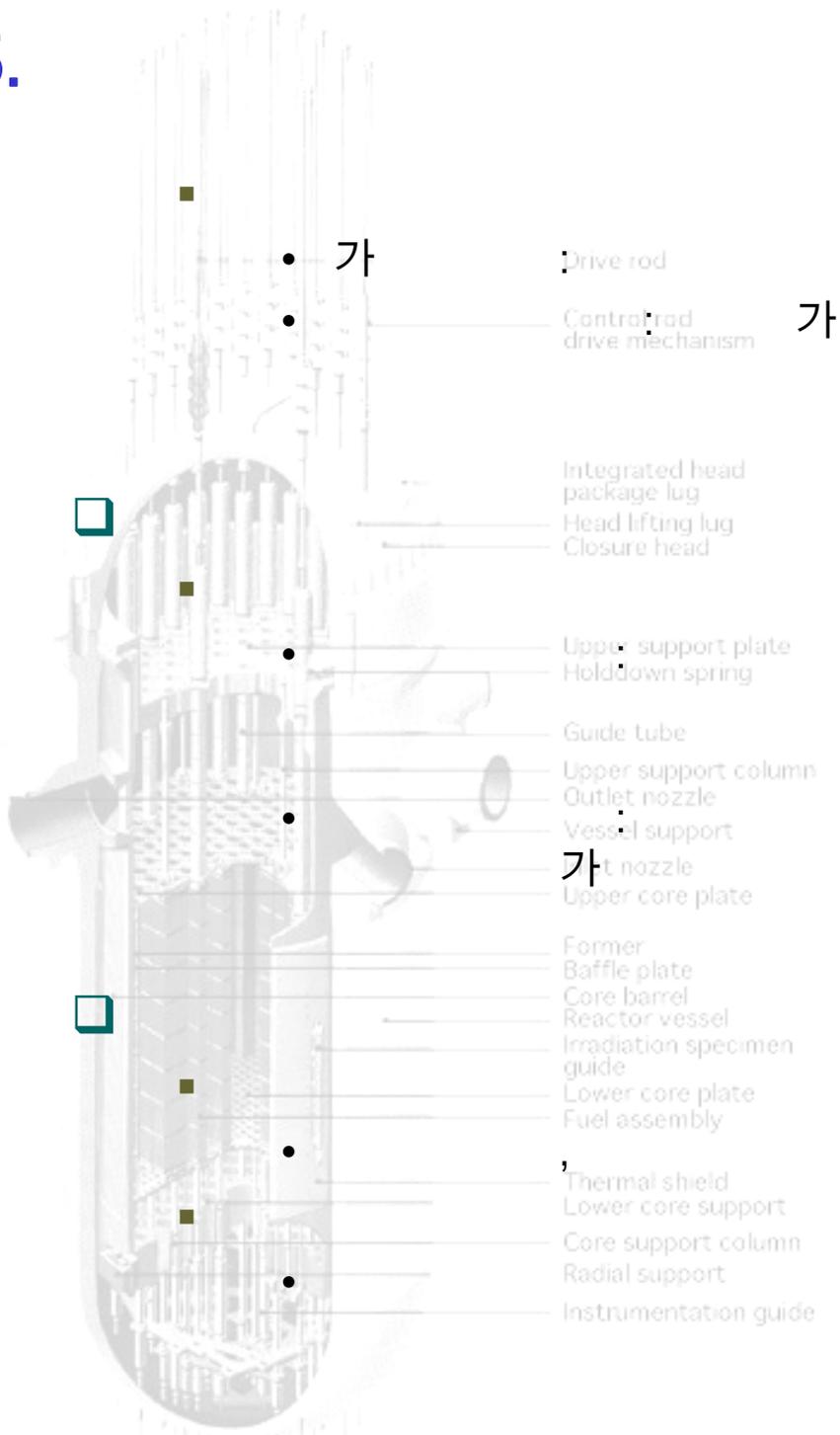
가
Thermal shield
Lower core support
Core support column
Radial support
Instrumentation guide :

B_4C , H_f , Cd

Ag-In-Cd



5.



5.

➤ 5.4

