



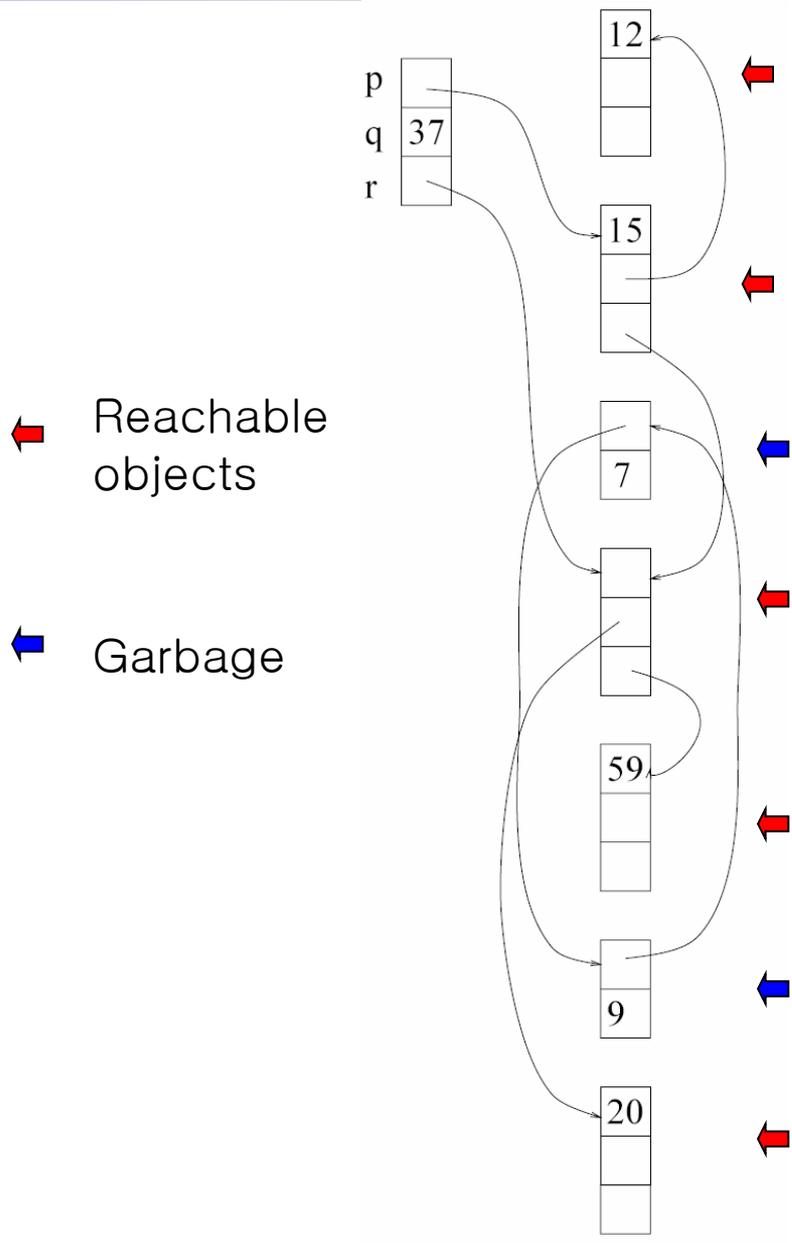
# Garbage Collection

# Garbage

- Heap-allocated objects **not reachable** by any chain of pointers from program variables
  - `Car c; c= new car(); ... c= new truck();`
- **Garbage collection (GC)** is reclaiming the memory space occupied by garbage
  - GC is performed not by the compiler but by the run-time system (the support program linked with the compiled code or by virtual machine)
  - GC recently enjoys its renewed popularity due to Java
    - Reduced time-to-market, improved S/W reliability...

# Garbage Collection

- How can we identify garbage?
  - When we need GC (i.e., run out of memory), we can view **program variables** and **heap-allocated, live objects** form a **DAG** where variables are **roots**
    - Why? a live object  $n$  is reachable in the DAG since there will be a path starting from some root  $r$  to  $n$
    - An object is garbage if it is not reachable in the DAG



# Root Sets

- How to identify **roots** when GC occurs?
  - In Java, local variables (including parameters) and temporaries are located in stack
  - If JIT compiler is employed, some of them can reside in registers as well
  - So, we need an information on locations of variables in order to identify roots precisely
    - Who knows this information? Compiler does
- Two approaches: **precise GC** and **conservative GC**

# Precise GC

- Compiler generates a map of (variables, locations) for all places in the code where GC can possibly occur
  - At object allocation point: `new()`
  - Some blocking operations in some VM
    - Function calls, synchronizations, loop back edges...
  - When GC occurs, GC gets roots using the map

# Conservative GC

- Presume all locations that can potentially have pointers as roots
  - If they are really pointers, then everything is fine
  - If not, then we might regard a dead object as a live one, so GC might not be able to collect it
- Simple but not-effective GC
- Not used in a real VM



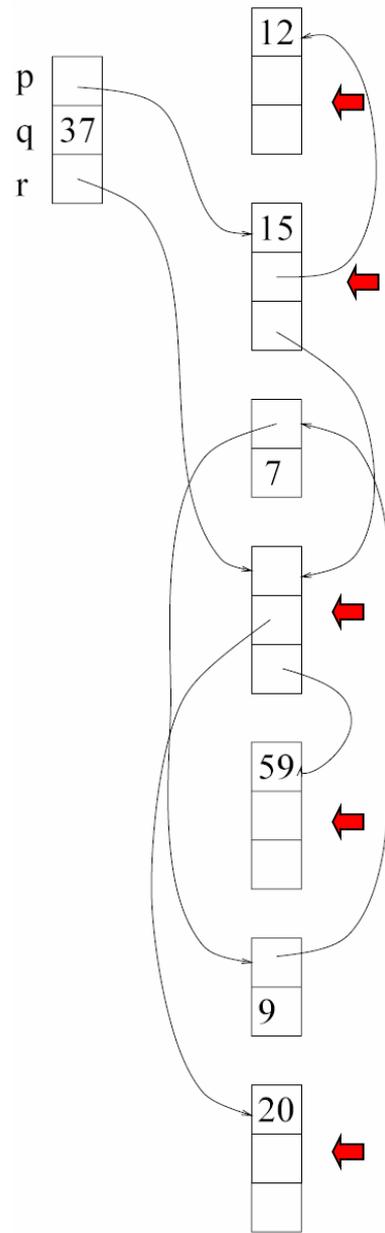
# GC Techniques

- Mark-and-Sweep
- Copying
- Generational

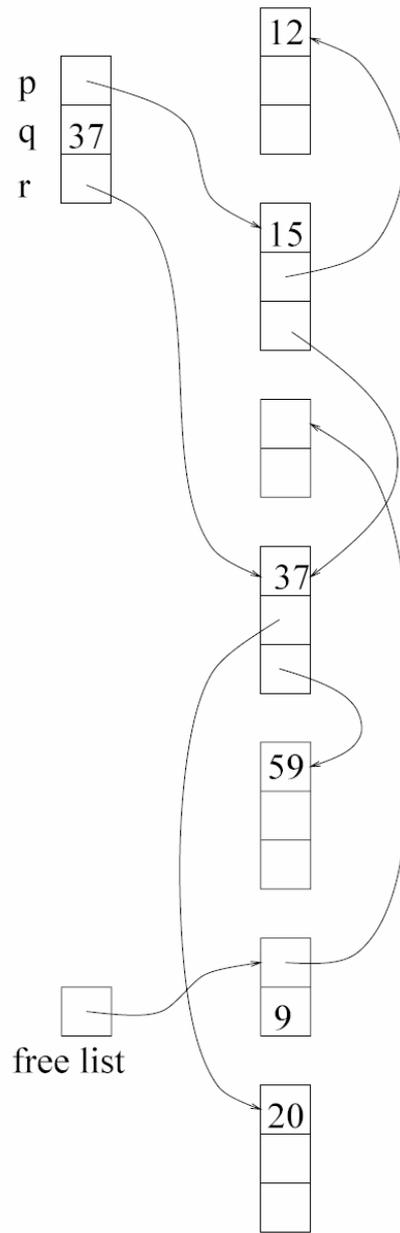


# Mark-and-Sweep Collection

- Simplest garbage collection algorithm
- **Mark phase**
  - Mark all reachable nodes by graph traversal
    - E.g, depth-first traversal
- **Sweep phase**
  - Scan through the entire heap, looking for nodes that are not marked; these nodes will be reclaimed into a linked list (`freeList`)



(a) Marked



(b) Swept

```
function DFS(x)
  if x is a pointer into the heap
    if record x is not marked
      mark(x)
      for each field f of record x
        DFS(x.f)
```

Sweep phase:

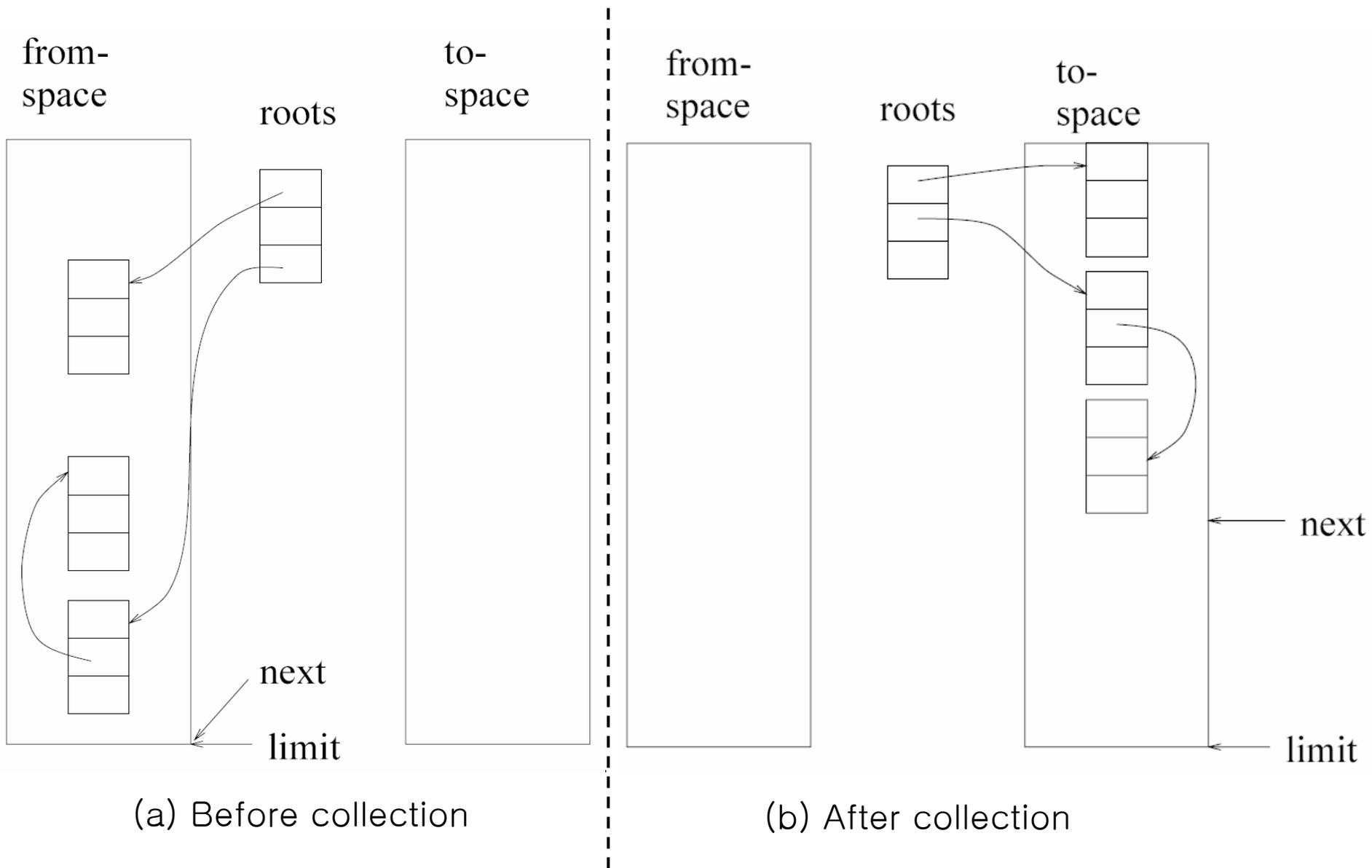
```
p = first address in heap
while ( p < last address in heap )
  if record p is marked
    unmark p
  else let f1 be the first field in p
    p.f1 = freelist
    freelist = p
p = p + size_of_record(p)
```

# An Array of freelist

- For efficient allocation, an array of freelists is used so that `freelist[i]` is a list of all records of size  $i$ 
  - Can allocate a node of size  $i$  by taking `freelist[i]`
  - If attempt to allocate from an empty `freelist[i]`, it can try to grab a larger record from `freelist[j]` ( $j > i$ ) and split it, putting unused portion back on `freelist[j-i]` (if this fails, we need GC).

# Copying Collection

- Heap is divided into **from-space** and **to-space**
  - Memory is allocated only from the **from-space** initially
  - The collector traverses the DAG in the **from-space**, building an **isomorphic copy** in the fresh **to-space**
  - The to-space copy is compact, occupying contiguous memory without fragmentation
    - Incrementing the next pointer contiguously
  - The roots are made to point at the to-space copy
  - Then, the entire from-space is collected
  - Change the role and continue



(a) Before collection

(b) After collection

# Generational Collection

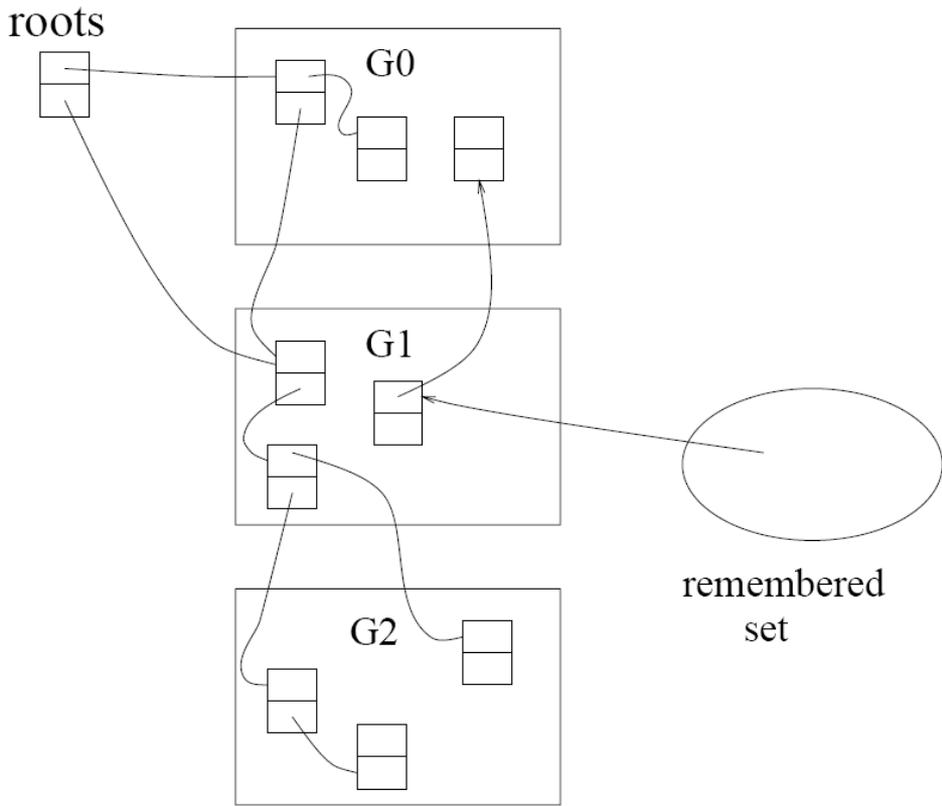
- In many programs, **newly created objects** are likely to die soon while objects that are still reachable after many collections will **survive** more collections
- GC should focus its efforts more on “**young**” data
- **Generational GC**: divide the heap into **generations**
  - With the youngest objects in generation G0; G1 objects are older than G0, G2 objects are older than G1, and so on
  - Collection of G0 just starts from its roots
    - Can use either mark-and-sweep or copying collection
  - After several collections of G0, G1 may have enough garbage, so both G0 and G1 are collected altogether.
  - If an object at  $G_i$  survives two or three collections, it promotes to  $G_{i+1}$

# Problem of Generational GC

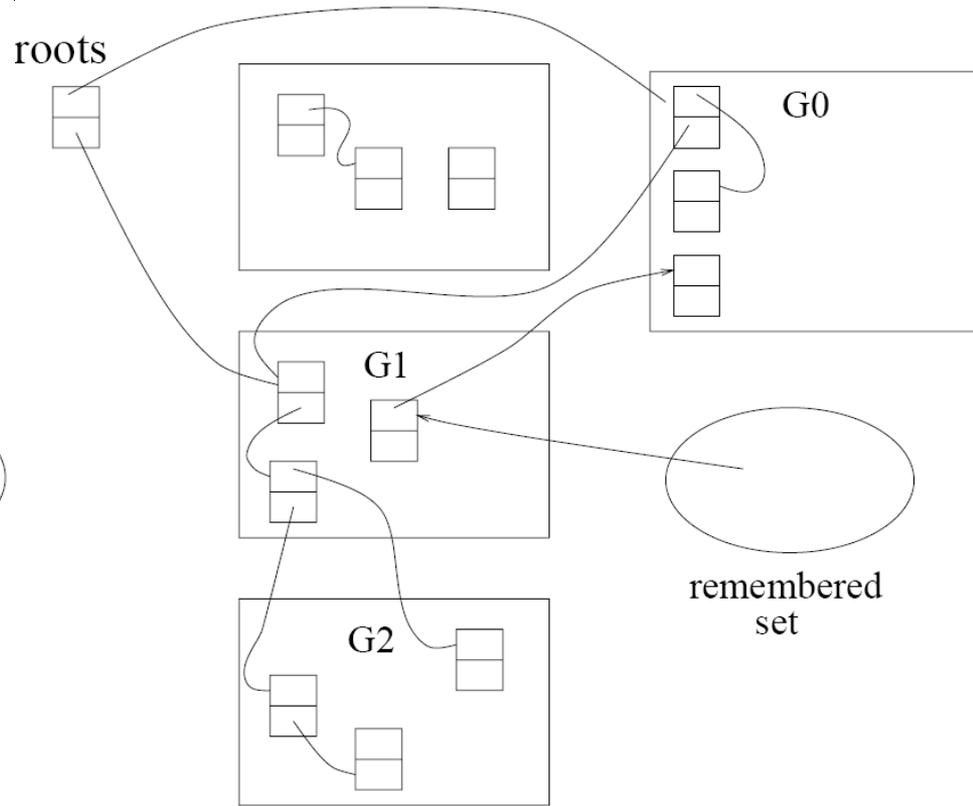
- **Roots for G0** are **not just program variables**; it can include any pointer within G1/G2 that points into G0
  - If too many of these “old” roots. Searching time for roots might be longer than traversal of G0
  - Fortunately, it is rare for an old record to point to a much younger object; an object is initialized when created by pointing other **older** objects
  - An old object **b** can point to a newer object if some field of **b** is updated long after **b** is created

# Remembered List and Set

- In order to the search of all  $G_1, G_2, \dots$  for roots of  $G_0$ , we **make the program remember** where there are pointers from older objects to new objects
  - Remembered list: when there is an update  $b.f = a$ , (generate code to) put  $b$  into a vector of updated objects. At each GC, the collector scans the list looking for old objects that point to  $G_0$
  - Remembered set: use a bit within  $b$  to record that  $b$  is already in the vector; then the code can check this bit to avoid duplicate references to  $b$  in the vector



(a) Before collection



(b) After collection

# GC Summary

- Most modern programming languages are equipped with GC for faster development
- Compiler for GC language generally interact with the collector by generating code that describes locations of root
- **Generational copying collection** is most popular, with some incremental collection