8 Symmetric Matrices

8.1 Properties of Symmetric matrix

We know that an $n \times n$ symmetric matrix A has only real eigenvalues.

$$\frac{(A - \lambda I)x}{\text{real}}x = 0$$

so the eigenvectors are also real. They are, in fact, perpendicular.

Example.

(symmetric)

$\cdot \mathbf{A} = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix}$ has an orthonormal basis of eigenvectors

$$\cdot \mathbf{A} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \text{ has an orthonormal basis of eigenvectors}$$

$$\begin{array}{c} \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\1\\ 1 \end{bmatrix}, & \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\-1\\ \end{bmatrix} \\ \rightarrow \lambda_1 = 8 & \rightarrow \lambda_2 = 2 \\ \begin{array}{c} 1\\0\\ 0 \end{bmatrix}, & \begin{bmatrix} 0\\1\\ \end{bmatrix} \\ \rightarrow \lambda_{1,2} = 1 \end{array}$$

(Not symmetric)

 $\cdot \mathbf{A} = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix} \text{ has only one eigenvector } \begin{bmatrix} c \\ 0 \end{bmatrix}$

Theorem An $n \times n$ real symmetric matrix has an <u>orthonormal basis</u> of eigenvector for \mathbb{R}^n

Partial Proof

(Eigenvectors of a real sym.matrix corresponding to different eigenvalues are perpendicular) :

Recall Diagonalization $A = X\Lambda X^{-1}$ For a symmetric matrix A, Construct X using n orthonormal eigenvectors. Then

$$\mathbf{X}^{\mathrm{T}}\mathbf{X} = \begin{bmatrix} -- & x_1^{\mathrm{T}} & -- \\ & \vdots & \\ -- & x_n^{\mathrm{T}} & -- \end{bmatrix} \begin{bmatrix} | & | & | \\ x_1 & \cdots & x_n \\ | & | \end{bmatrix} = \begin{bmatrix} 1 & 0 \cdots & 0 \\ & \ddots & \\ & 1 \end{bmatrix} = I.$$
$$\therefore \quad \mathbf{X}^{-1} = \mathbf{X}^{\mathrm{T}}$$

Theorem [Spectral Theorem or Principal Axis Theorem]

Every symmetric matrix has the factorization $\mathbf{A} = \mathbf{X} \Lambda \mathbf{X}^{T}$ with real eigenvalues in Λ and orthonormal eigenvectors in \mathbf{X} .

 \cdot Consider a quadratic form then,

$$q = \mathbf{x}^{\mathrm{T}} \mathbf{X} \mathbf{\Lambda} \mathbf{X}^{\mathrm{T}} \mathbf{x}$$
set $\mathbf{y} = \mathbf{X}^{\mathrm{T}} \mathbf{x}$. Then $\mathbf{x} = \mathbf{X} \mathbf{y}$, and $\mathbf{x}^{\mathrm{T}} \mathbf{X} = \mathbf{y}^{\mathrm{T}}$
 $\therefore q = \mathbf{y}^{\mathrm{T}} \mathbf{\Lambda} \mathbf{y} = \sum_{i=1}^{n} \lambda_{i} y_{i}^{2} \quad \leftarrow \text{(This is called the principal axis form})}$

Example . Find the axes of the tilted ellipse

The eigenvalues of A :

$$\lambda_1 = 9, \lambda_2 = 1 \qquad \Rightarrow \quad \Lambda = \begin{bmatrix} 9 \\ & 1 \end{bmatrix}$$

Corresponding eigenvectors :

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1\\1 \end{bmatrix}, \quad \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\-1 \end{bmatrix} \qquad \Rightarrow \quad \mathbf{X} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1&1\\1&-1 \end{bmatrix}$$

 Set

$$\mathbf{y} = \mathbf{X}^{\mathrm{T}}\mathbf{x} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1\\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}$$

This example shows why the previous theorem is called the principal axis theorem.

8.2 Positive Definite Matrices

Note In the above example, for any nonzero vector
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
,
 $q = \mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x} = \lambda_1 y_1^2 + \lambda_2 y_2^2 > 0$

Such a matrix A is called positive definite. (Strang, page331)

Recall

$$q = \mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x} = \sum_{i=1}^{n} y_i^2 \lambda_i$$
 where $\lambda_1, \cdots, \lambda_n$ are eigenvalues of A

• Suppose that
$$\lambda_k \leq 0$$
. Then for $\mathbf{y} = \begin{bmatrix} 0\\ \vdots\\ 0\\ 1\\ 0\\ \vdots\\ 0 \end{bmatrix} \leftarrow k^{th}$,

 $q = \lambda_k \leq 0$. Thus, there exists a nonzero vector $\mathbf{x} = \mathbf{X}\mathbf{y}$ s.t. $q \leq 0$. If all $\lambda_i >$, then q > 0 for every nonzero \mathbf{x} .

Therefore we have the following theorem : **Theorem** $A: n \times n$ symmetric matrix. Then,

 $\begin{array}{l} \underbrace{\operatorname{All } \mathbf{n} \text{ eigenvalues are positive}}_{\left\{\begin{array}{l} \mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x} > \mathbf{0} \text{ except at } \mathbf{x} = \mathbf{0} \end{array}}_{\left\{\begin{array}{l} \mathbf{A} \text{ is positive definite}\right\}},\\ \underline{\mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x} > \mathbf{0} \text{ except at } \mathbf{x} = \mathbf{0} \end{array}}_{\left\{\begin{array}{l} \mathbf{a} \text{ is positive definite}\right\}},\\ \underline{\mathbf{2} \times 2 \text{ case}} \qquad \mathbf{A} = \begin{bmatrix} a & b \\ b & c \end{bmatrix}, \text{ when is A positive definite}?\\ \left|\mathbf{A} - \lambda \mathbf{I}\right| = (a - \lambda)(c - \lambda) - b^{2} = \lambda^{2} - (a + c)\lambda + ac - b^{2} = \mathbf{0} \right.\\ \left|\mathbf{A} - \lambda \mathbf{I}\right| = (a - \lambda)(c - \lambda) - b^{2} = \lambda^{2} - (a + c)\lambda + ac - b^{2} = \mathbf{0}\\ \cdot \text{ If } \lambda_{1}, \lambda_{2} > \mathbf{0}, \qquad \begin{array}{l} \lambda_{1} + \lambda_{2} = a + c > \mathbf{0} \\ \lambda_{1}\lambda_{2} = ac - b^{2} > \mathbf{0} \\ \text{ If } a > \mathbf{0} \text{ and } c \leq \mathbf{0}, \quad \text{then } ac - b^{2} \leq \mathbf{0}\\ \text{ If } a \leq \mathbf{0} \text{ and } c > \mathbf{0}, \quad \text{then } ac - b^{2} \leq \mathbf{0}\\ \text{ Therefore, we have } a > \mathbf{0}, c > \mathbf{0} \text{ and } ac - b^{2} > \mathbf{0} \end{array}$

 $\begin{array}{l} \cdot \text{ Now, suppose } \underline{a > 0} \text{ and } \underline{ac - b^2 > 0} \\ 1 \times 1 \text{ upper left } \\ \text{determinant} \end{array} \\ \end{array} \\ \begin{array}{l} 2 \times 2 \text{ determinant} \end{array}$

This foces c > 0

$$\Rightarrow \qquad \lambda_1 + \lambda_2 > 0, \quad \lambda_1 \lambda_2 > 0$$
$$\therefore \ \lambda_1, \lambda_2 > 0$$

$$\begin{aligned} \cdot \mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x} &= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ &= a x_1^2 + 2b x_1 x_2 + c x_2^2 \\ &= a \left(x_1 + \frac{b}{a} x_2 \right)^2 + \left(\frac{ac - b^2}{a} \right) x_2^2 \\ &= \begin{bmatrix} x_1 + \frac{b}{a} x_2 & x_2 \end{bmatrix} \begin{bmatrix} a \\ \frac{ac - b^2}{a} \end{bmatrix} \begin{bmatrix} x_1 + \frac{b}{a} x_2 \\ x_2 \end{bmatrix} \\ &= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{b}{a} & 1 \end{bmatrix} \begin{bmatrix} a \\ \frac{ac - b^2}{a} \end{bmatrix} \begin{bmatrix} 1 & \frac{b}{a} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \\ &= \mathbf{x}^{\mathrm{T}} \mathrm{LDL}^{\mathrm{T}} \mathbf{x} \end{aligned}$$

Recall the factorization of a symmetric matrix $A = LDL^{T}$ D contains the diagonal elements of the upper triangular matrix, and they are pivots!

$$\begin{array}{c|c} & & \\ & & \\ \hline & & \\ b & c \end{array} \end{array} \begin{array}{c} (if \ a > 0) \\ & \\ \hline & \\ & \\ \end{array} \end{array} \begin{array}{c} a & b \\ & \\ & \\ & \\ & \\ \end{array} \begin{array}{c} a & b \\ & \\ & \\ & \\ & \\ \end{array} \end{array} \begin{array}{c} a & b \\ & \\ & \\ & \\ & \\ \end{array} \end{array} \right]$$

second pivot

Thus, $x^{T}Ax > 0$ except at x = 0 mean positive pivots and vice versa.

The above analysis holds for $n \times n$ symmetric matrices.

Theorem For an $n \times n$ symmetric matrix A, the following are equivalent.

- 1. All n eigenvalues are positive.
- 2. All n upperleft determinants are positive.
- 3. All n pivots are positive.
- 4. $x^{T}Ax > 0$ except at x = 0. (A is positive definite)



(ii) the quadratic function

$$f(x) = \mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x}$$

has a minimum at x = 0.