

# Programming Methodology

Spring 2009

Control and Execution



**Expression evaluation**

**Statement execution**

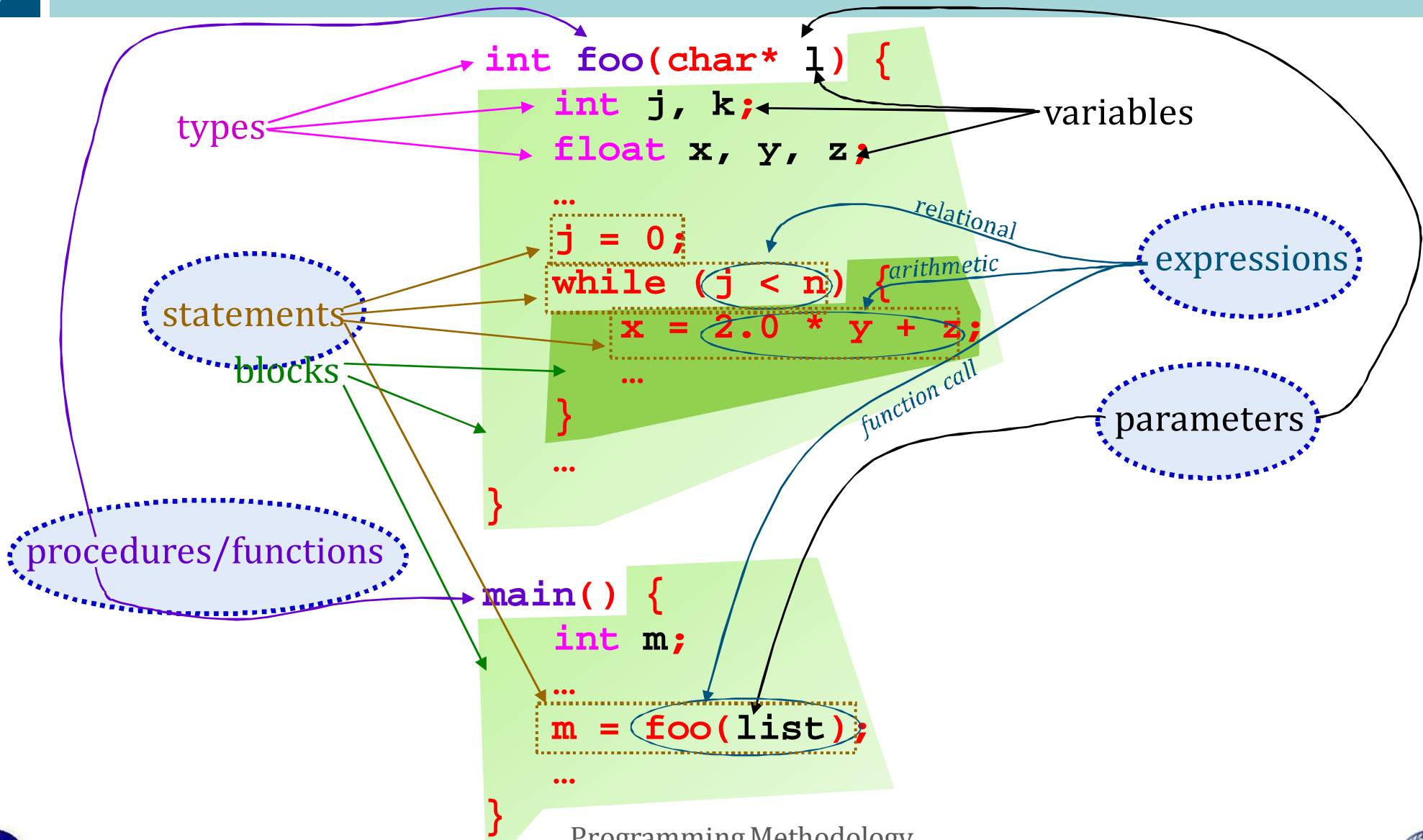
**Function/Procedure call (with parameters)**

**Iterations vs. Recursions**

**Exceptions**

# Programming language constructs

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# Control structures

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- Control structures control the order of execution of operations in a program.
- **expression-level** control structures
  - precedence/associativity rules, parentheses, function calls
- **statement-level** control structures
  1. sequential structures: *stmt<sub>1</sub>; stmt<sub>2</sub>; ...; stmt<sub>n</sub>;*
    - a sequence of compound statements
  2. selective structures: *if-then-else, case/switch*
  3. iterative structures: *for, while, do, repeat*
  4. escape/exception/branch: *exit, break, goto, continue*
  5. recursive structures: by recursive function calls

# Expressions

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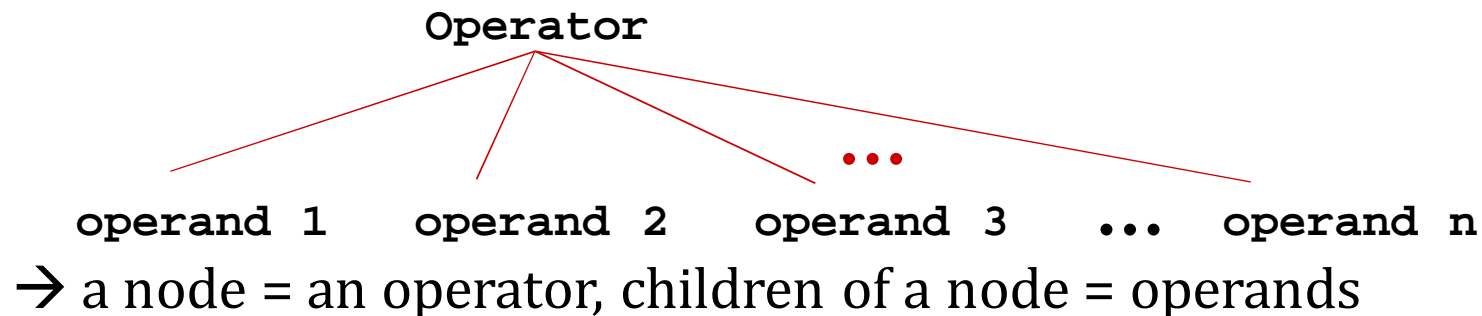


- An expression is ...
  - a means of specifying computations in a program.
  - composed of one or more operations.
- An operation = an operator + zero or more operands
  - operators: arithmetic, logical, relational, assignment, procedure call, reference/dereference, comma, id, constant, ...
  - operands: sub expressions

C++

```
p = &z;  
x = y + *p / 0.4;  
a[i] = (z > 0 ? foo(x, y, p) : -1);
```

- Syntax tree: abstract representation of expressions



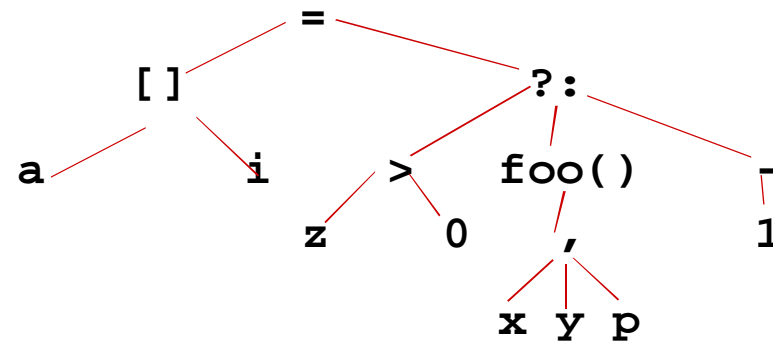
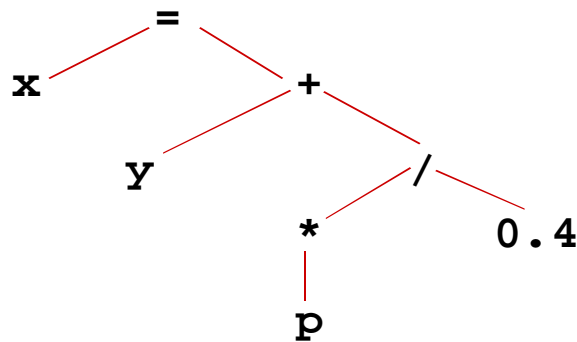
# Evaluation of expressions

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- Executing a program is actually a sequence of evaluation of expressions in the program.
- How does the compiler/machine determine the evaluation order of an expression?

→ use a *syntax tree*



- The expression evaluation order in a language (in other words, the way to build a syntax tree) is defined by the language semantics.

# Rules specifying evaluation orders

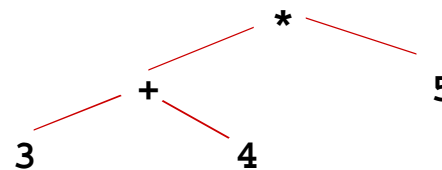
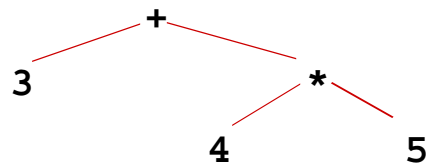
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- **Precedence rule:** the relative priority of operators when more than one kinds of operator are present

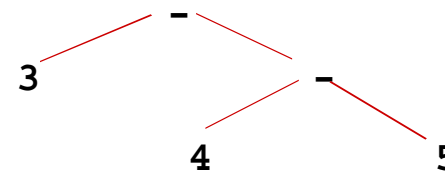
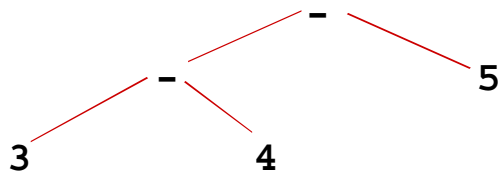
Ex: “\* has higher precedence than +”

→ thus,  $3+4*5$  is equal to  $3+(4*5)$ , not  $(3+4)*5$ .



- **Associativity rule:** the relative priority of operators when two adjacent operators with the same precedence occur in an expression

Ex: “- is left-associative” → thus,  $3-4-5$  is equal to  $(3-4)-5$ , not  $3-(4-5)$



# Operator precedence/associativity in C

++++q →

t->r.x

\*p++

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Precedence	Operators	Associativity
15	-> . [] ()	Left
14	++ -- ~ ! unary+ unary- * &	Right
13	* / %	Left
12	+ -	Left
11	<< >>	Left
10	< > <= =>	Left
9	== !=	Left
8	&	Left
7	^	Left
6		Left
5	&&	Left
4		Left
3	? :	Left
2	=	Right
1	,	Left

p+++q →  
p++++q →

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p+++ +q →  
p++++-q →



# Sequential structures

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- When is the order of a sequence of compound statements important?

```
C {  
    statement1;  
    statement2;  
    ...  
    statementn;  
}
```

→ It is when there is *data dependence* between the statements. That is, when the same location is modified by different statements.

- Find data dependences in the following statements.

```
a[2] = a[1] + 1  
x = a[3] * x  
a[4] = a[3] / y
```

```
x = z;  
y = 2.3 + z;  
w = z / 0.6;  
print z;
```

```
x = 3.4  
y = x - 2.1;
```

```
read y;  
x = 5.0;  
x = 7.1;  
y = x * 1.1;
```

```
x = 8.8;  
y = 3.9 * 1.2;  
z = 4.1;
```

```
b[i] = j + 0.1;  
b[i+1] = b[i-1];  
i = i + 1;  
m = b[i] + b[i-1];
```

# Selective, iterative structures

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- Selective structures:
  - choose control flow depending on conditional test
  - Most languages support → if/then/else, switch/case
- Iterative structures
  - looping construct
  - C → while, for, do-while
- *goto* statements
  - efficient, general purpose, easy to use and translate to machine codes
  - flattens hierarchical program structures into a linear collection of statements → difficult to read/understand
  - difficult to optimize or verify programs

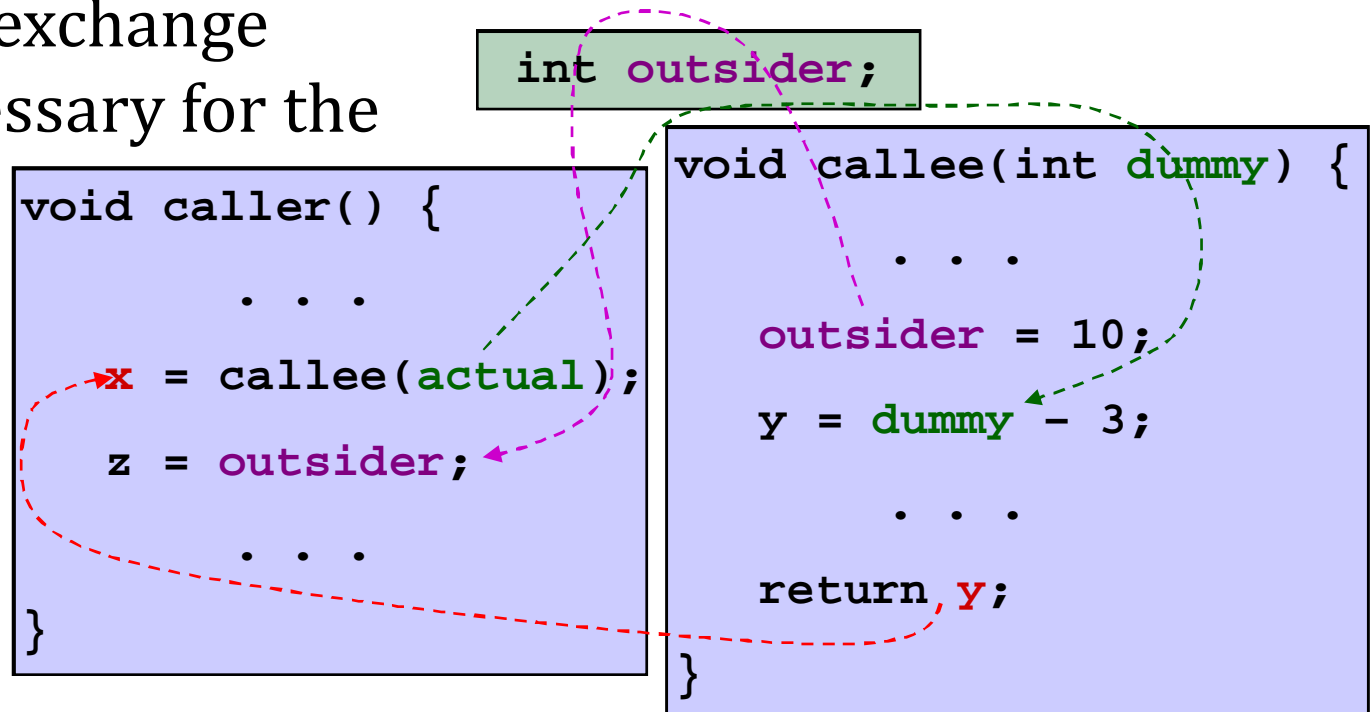
# Function/Procedure calls

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- Why is a **function call/invocation** a universal feature in programming languages?
- A function call involves a **caller** and a **callee**.
- The caller and the callee involved in the same call should communicate to exchange information necessary for the call. Then, how?

- using global variables
- using parameters and returning values



# Passing function parameters

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- Given a function invocation  $\mathbf{func}(a_1, a_2, \dots, a_n)$ , and a function declaration  $\mathit{type} \mathbf{func}(\mathit{type}_1 \mathbf{d}_1, \mathit{type}_2 \mathbf{d}_2, \dots, \mathit{type}_n \mathbf{d}_n)$ ,
  - $a_i$  represents an expression for the  $i$ -th *actual parameter/argument* for the invocation provided by the caller
  - $d_i$  represents a variable for the  $i$ -th *dummy/formal parameter* for the callee  $\mathbf{func}$ .
- parameter/argument passing
  - ➔ Study of the different ways of communication between a caller and a callee with parameters and results
- parameter passing methods
  - Two most popular ones: **call-by-value**, **call-by-reference**
  - Others: call-by-result, call-by-value-result, call-by-sharing, call-by-name, call-by-need ➔ *Out of our scope!*

# Call-by-value

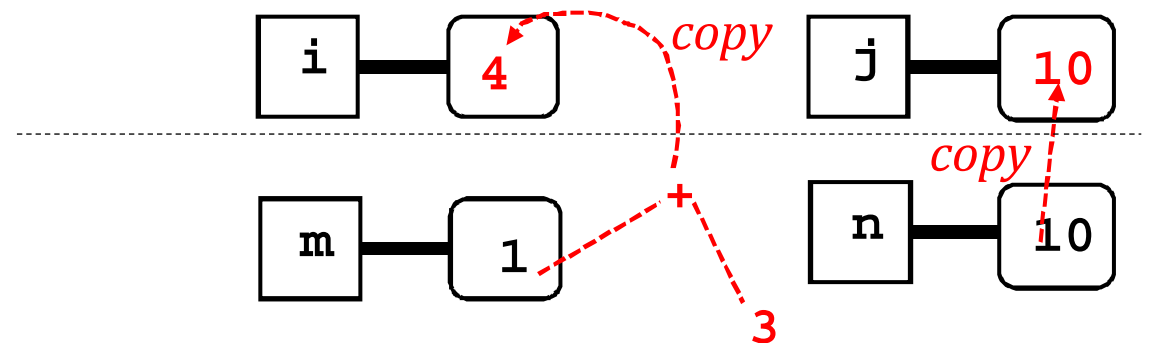
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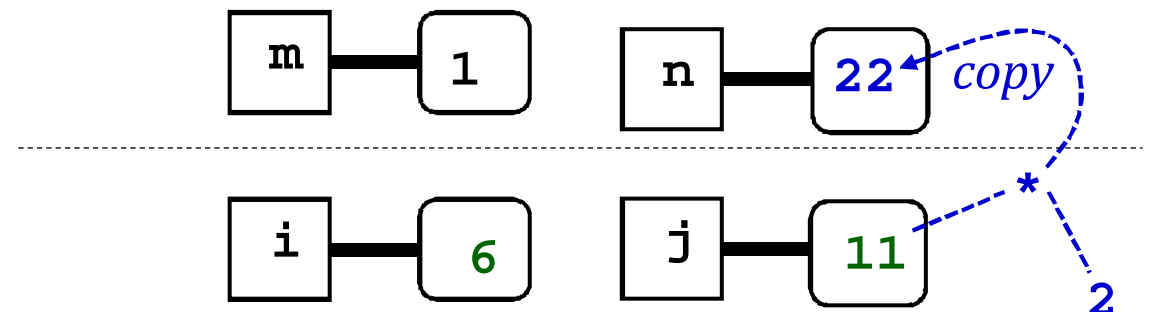
- When a procedure is called, the r-value of an actual parameter is assigned to the l-value of the matching formal parameter.
- secure because changes made on formal parameters do not affect the actual ones.

```
int foo(int i, int j) {  
    ...  
    i = j++ - i;  
    return j * 2;  
}  
  
void bar() {  
    int m = 1;  
    int n = 10;  
    ...  
    n = foo(m+3, n);  
}
```

when `foo` is called



when `foo` returns



just before `foo` returns

# Call-by-value



- Typically, not appropriate if a callee wants to return multiple output results

```
int foo(int a, int b, ...) {  
    ...  
    return c;  
}  
  
int main() {  
    ...  
    z = foo(x, y, ...) ...  
    ...  
}
```

*single output* (pink arrow from `z = foo(x, y, ...)` to `return c;`)

*... multi inputs* (brown arrows from `x, y, ...` to `int a, int b, ...`)

- But it is not impossible to return multi-results with call-by-value → use !
- Also, possibly expensive if **large data** needs to be passed. →

```
struct S {  
    int x, y;  
    float a[1000][1000];  
};  
  
void foo(S dum) {  
    ...  
    cout << dum.a[1][1];  
    dum.a[1][1] = 99;  
    ...  
}  
  
int main() {  
    S act;  
    ...  
    act.a[1][1] = 55;  
    foo(act);  
    cout << act.a[1][1];  
}
```

Blue arrows point from the `act` variable in `main` to the `dum` parameter in `foo`, and from the `dum.a[1][1]` assignment in `foo` back to the `act.a[1][1]` output in `main`.

# Call-by-reference/location

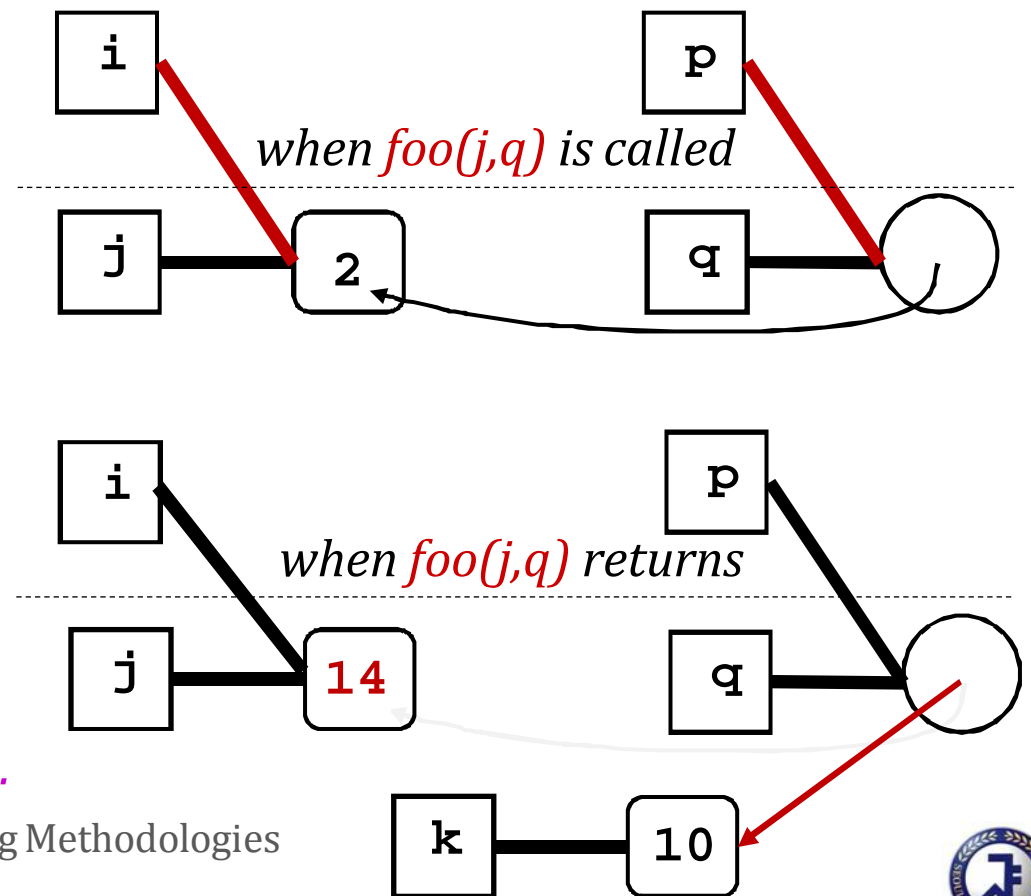
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- When a procedure is called, the l-value of an actual parameter is shared with the matching dummy parameter. → **aliasing**
- For this, C++ uses a **reference type** for dummy parameters.

```
int k = 10;
void foo(int &i, int* &p) {
    i = 7;
    *p = i + *p;
    p = &k;
}
void bar() {
    int j = 2;
    int* q = &j;
    . . .
    foo(j, q);
    cout << j << *q;
    foo(j+3, q);
}
```

*error: j+3 has not l-value.*



# Call-by-reference/location

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- can be used to return multiple output results

```
int foo(int a, int &b, ...) {  
    ...  
    b = ...  
    return c;  
}  
  
int main() {  
    ...  
    z = foo(x, y, ...) ...  
    ...  
}
```

*one output* (arrow from `z = foo(x, y, ...)` to `return c;`)

*... multi inputs* (arrows from `x, y, ...` to `int a, int &b, ...`)

*one more output* (arrow from `return c;` to `z = foo(x, y, ...)`)

- can be efficient via aliasing when **large data** needs to be passed. 

```
struct S {  
    int x, y;  
    float a[1000][1000];  
};  
  
void foo(S &dum) {  
    ...  
    cout << dum.a[1][1];  
    dum.a[1][1] = 99;  
    ...  
}  
  
int main() {  
    S act;  
    ...  
    act.a[1][1] = 55;  
    foo(act);  
    cout << act.a[1][1];  
}
```

Diagram showing aliasing: `act` in `main` and `dum` in `foo` are the same memory location, indicated by blue arrows pointing to a single box.



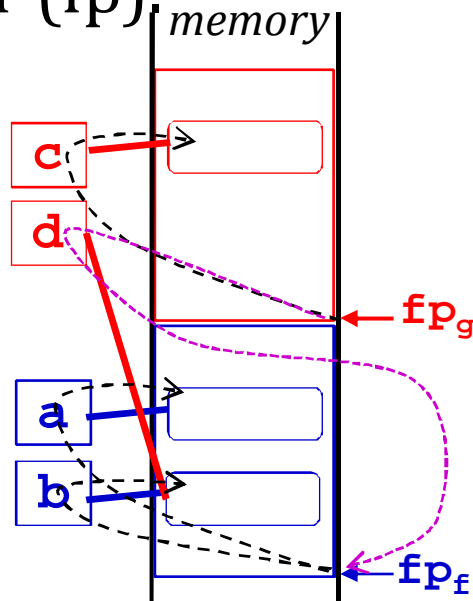
# Call-by-reference/location

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- causes *aliasing*, which makes the code ...
  - generally more efficient (ex: long arrays); but
  - error prone due to *side effects*, and
  - in some cases, even less efficient because call-by-reference is often implemented with **an extra level of indirection** thru a frame pointer (fp)

```
g(int c, int& d) {  
    ... = c + d  
    ...  
}  
f() {  
    int a, b;  
    ... g(a, b);  
    ...  
}
```



```
...  
load r1, [fp_g+<c>]    ← c  
load r2, [fp_g+<fp_f>] ← fp_f  
load r3, [r2+<b>]     ← d = b  
add r4, r1, r3        ← c + d  
...
```

```
...  
load r14, [fp_f+<a>]  ← a  
load r15, [fp_f+<b>] ← b  
call g  
...
```

# Write protection thru constant dummy

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- Using *constant dummy parameters* may prevent erroneous updates or side effects due to aliases created by call-by-reference.
  - Still call-by-reference, so avoid copying.
  - Yet, providing write-protection on dummy parameters

*The function gee guarantees that the actual parameter (not only **y** but also **x**) is never modified inside gee.*

```
void foo(int a) { // by value
    ...
}
void bar(int& b) { // by ref
    ...
}
void gee(const int& c) { // by const ref
    ...
    c = ... // Compile error: write protection
}
int main() {
    int x = 1965;
    const int y = 2009;
    foo(x); // OK?
    foo(y); // OK?
    bar(x); // OK?
    bar(y); // OK?
    gee(x); // OK?
    gee(y); // OK?
}
```

# Simulating call-by-reference thru pointers

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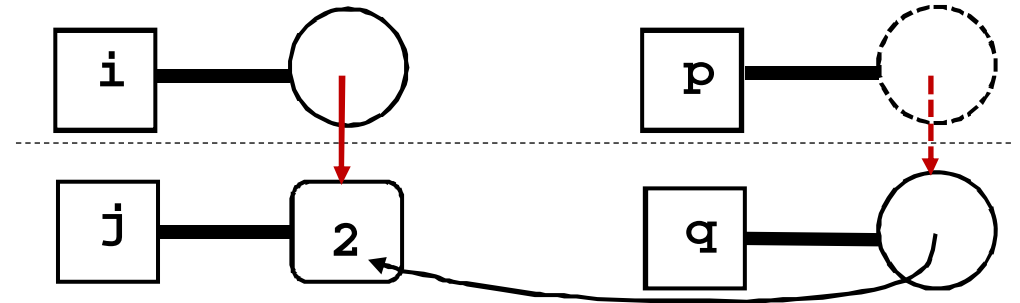
- C cannot support true call-by-ref. (*:: no reference type included*)
- But, it can simulate call-by-ref. by using **pointers** as call-by-value parameters.

```
int k = 10;
void foo(int *i, int* *p) {
    *i = 7;
    **p = *i + **p;
    *p = &k;
}
void bar() {
    int j = 2;
    int* q = &j;
    foo(&j, &q);
    cout << j << *q;
}
```

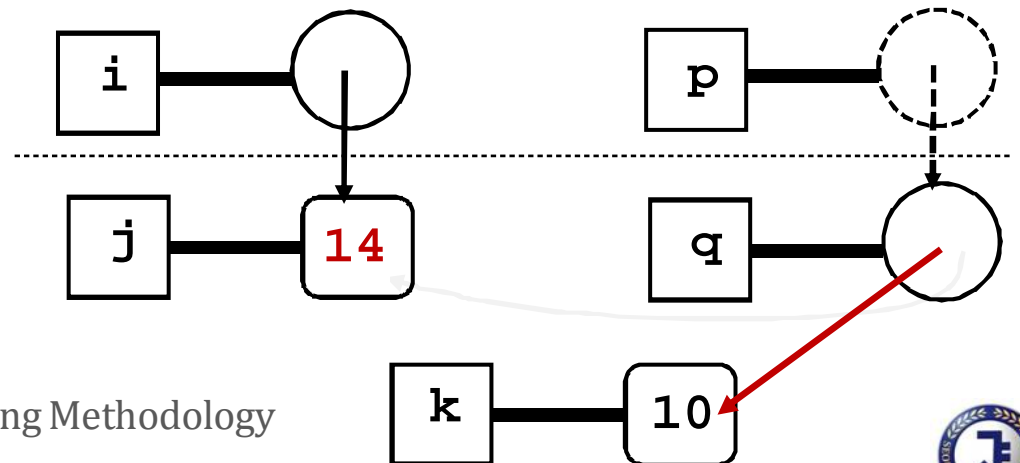


*Same results as the original code  
with reference type dummies*

when **foo(&j, &q)** is called



when **foo(&j, &q)** returns



# Multidimensional arrays as parameters

Note: `gee` and `foo/bar` may be compiled in separate files! ←

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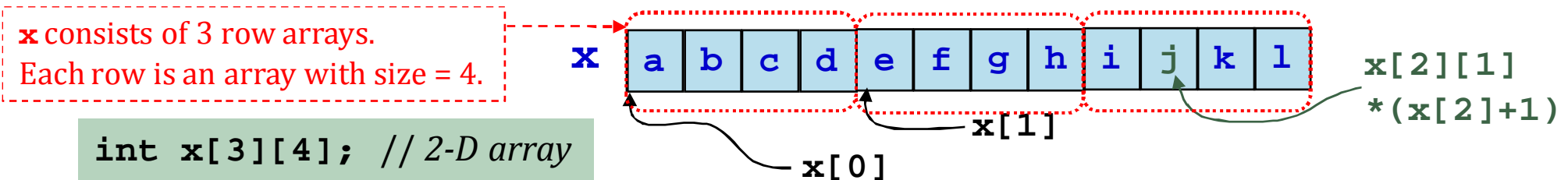
- When a multidimensional array is passed, the callee should know the original dimension of the array declared in the caller.

```
void foo () {
    int a[5][9];
    ... gee(a) ...
}
```

```
void bar () {
    int b[7][3];
    ... gee(b) ...
}
```

```
void gee (int c[][]) {
    ...c[2][6]... //error
}
// (or **c)
```

- `c[2][6]` is invalid when `bar` calls `gee`. → How can the compiler find this?
- It is valid when `foo` calls `gee`. → But how to determine its exact address?
- Recall: a multidimensional array in C/C++ is an *array of arrays*, and physically stored to 1-D memory in *row-major* order.



- To compute the exact address for `c[i][j]`, the compiler must evaluate  

$$\text{address of } c[i][j] = c + i \cdot n + j$$
 → `n` = size of row array = # of columns
- What does **this** imply? → Compiler must know `n` when `gee` is called.

# Multidimensional arrays as parameters

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- One solution for the above case

```
void foo () {  
    int a[5][9];  
    ... geefoo(a) ...  
}
```

```
void bar () {  
    int b[7][3];  
    ... geebar(b) ...  
}
```

```
void geefoo (int c[][9]) {  
    ...c[2][6]... // = *(c + 24)  
}
```

```
void geebar (int c[][3]) {  
    ...c[2][6]... // Now the compiler  
                // knows this is error since 6 > 3  
}
```

- The problem of this solution?
  - Poor reusability of code and increase of code size
  - Ex: a new function for **gee** must be written for every different row size.

- Alternative solution

- Pass the array as a *pointer* along with its dimension information

```
#define gee_c(i,j) (*(c + ((i) * n) + (j)))  
...  
void gee1 (int *c, int m, int n) { // indicating c[m][n]  
    ... gee_c(2,6) ... // = *(c+24) if called by foo  
                    // = *(c+12) if called by bar  
}
```

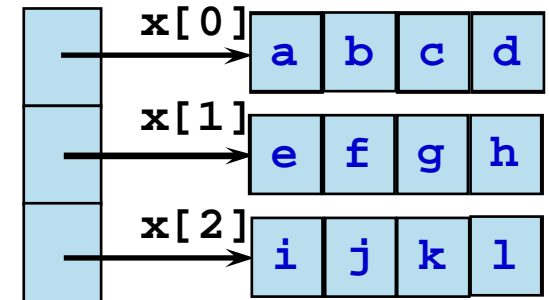
- The same function **gee1** can be used for **foo** and **bar**, regardless of the caller's array dimension.

# Multidimensional arrays as parameters

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- The problem with **gee1**? → Yes, indeed... because we need ...
  - a special statement ‘#define’ → awkward
  - to manage dimensions (**m**, **n**) separately → inconvenient, error prone
  - a different ‘#define’ for other array parameters: **gee\_d**, **gee\_e**, ...
- A better solution? → Create a new **class** (i.e., ADT)!
  - In Java (also C#), arrays are objects of a system class, say *Array*.
  - Array objects are all 1-dimensional, but their elements can be also objects of *Array*. → For example, 2-D array **x[3][4]**
  - The *Array* class offers a named constant ‘**length**’ that is set to the length of the array when the array object is created.



```
Java Code
int[][] x = new int[3][4];
... x.length ... // = 3
... x[i].length ... // = 4
```

# Multidimensional arrays as parameters

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- Using Array objects for parameter passing
  - No need to separately pass dimensions for a multidimensional array since the compiler can extract them from the internal constant **length**.

Java Code

```
void gee2 (int[][] c) { // setting c.length and c[i].length
... c[2][6] ... // valid if called by foo
// error if called by bar since 6 > b[i].length = 3
```

```
void foo () {
int[][] a = new int[5][9];
... gee2(a) ...
```

```
void bar () {
int[][] b = new int[7][3];
... gee2(b) ...
```

- Good reusability and code size reduction
- How about C++?
  - Unlike Java, C++ doesn't support such a system class as Array by default.
  - But, the programmers can create similar objects for multidimensional arrays by using the **class** construct.

# Functions as parameters



- The traditional view of a function  $f: \mathcal{D} \rightarrow \mathcal{R}$ 
  - Ordinary data objects of primitive types have first-class values. *integers, characters, real numbers, strings ...*
  - $f$  is a static piece of code for mapping input values of first-class into first-class output values.
  - Such a function is said to be **first-order**.
- In programming languages such as C/C++, Java, and Fortran, most functions are first-order.
  - Ex)  $\text{foo}: \mathbf{Z}$  (*integer*)  $\rightarrow \mathbf{R}$  (*real*)
- In some languages, **functions** themselves can be considered as first-class values so that they can be passed as inputs to or as output from **other functions**.

```
float foo (int x) {  
    ...  
}
```

```
int main () {  
    ... f(&g) ...  
}
```

```
... f ( ... ) {  
    ...  
}
```

```
int g (int n) {  
    ...  
}
```





# Functions as parameters

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- A function that takes functions as parameters or returns as outputs is called a **higher-order function** (HOF).
- C++ support a limited form of HOFs.
  - A C++ function may take another function as its parameters.
  - For this, C++ uses a *function pointer*.

```
int (*pf) (int);
pf = &square; // pf = square
cout << pf(5); // 25
pf = &double; // Now pf = double
cout << pf(5); // 10
```

```
int square(int x) {
    return x * x;
}
int double(int y) {
    return y + y;
}
```

- C++ HOF **foo**:

```
void foo(int (*pf) (int)) { ... }
...
int main() {
    ...
    foo(&square);
    foo(&double);
    ...
}
```

→ ≠ int \*pf (int)

# HOFs



- HOFs are sometimes powerful and useful.
  - Treating functions as values increase the expressive power of a language. → functions handling functions : sums ( $\Sigma$ ), derivatives ( $d, \partial$ )
  - They help abstract out common control patterns, leading to very concise programs. → repetitive applications of similar tasks
- Where HOFs are useful for concise programming
  - For example, the *summation* in mathematics (denoted by the notation  $\Sigma$ ) is a HOF since it takes a function  $f$  as a parameter.

$$\sum_{j=1}^m f(j) = f(1) + f(2) + \dots + f(m)$$

- A notation  $\Sigma$  makes a mathematical expression concise and brief by capturing the common patterns among the expression.

$$\sum_{i=1}^l \sum_{j=1}^m \sum_{k=1}^n f(i, j, k) = f(1,1,1) + \dots + f(1,1,n) + f(1,2,1) + \dots + f(l, m, n)$$



# HOFs



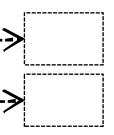
- Where HOFs are useful for concise programming (cont'd)
  - $\Sigma$  in math can be represented briefly by a HOF **sig** in C++.
  - Like  $\Sigma$  does for math, **sig** will make a program concise by taking any function  $f$  as a parameter of the common input/output types.

```
int sig(int (*f) (int), int m) {
    int result = 0;
    for (int j = 1; j < m; j++)
        result += f(j);    //  $\Sigma_j f(j)$ 
    return result;
}

int main () {
    cout << sig(&square, 5);    //  $\Sigma_j j^2$ 
    cout << sig(&double, 5);   //  $\Sigma_j 2j$ 
}
```

```
int square(int x) {
    return x * x;
}

int double(int y) {
    return y + y;
}
```



What if we cannot use HOFs for this example in C++?

- But, **sig** is not as flexible as  $\Sigma$ . → ... **sig(&sig(&f,m),n); //error:  $\Sigma_i \Sigma_j f(i,j)$**

→ Such flexibility is possible in *functional languages* like scheme and ML.

# Another example of HOFs

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! trapezoidal approximation for the definite integral

```
function integral (f,a,b,n) result(t)
```

```
  interface
```

```
    function f(x)
```

```
    real::f,x
```

```
  end interface
```

```
  real, intent(in)::a, b
```

```
  integer, intent(in):: n
```

```
  real::t
```

```
  real::h, sum
```

```
  integer:: i
```

```
  h = (b - a) / n
```

```
  sum = 0.5 * (f(a) + f(b))
```

```
  do i = 1, n-1
```

```
    sum = sum + f(a+i*h)
```

```
  enddo
```

```
  t = h * sum
```

```
end function integral
```

```
function bar(x) ...
```

```
...
```


```
end function bar
```

```
program main ...
```

```
...
```

```
write (*,*) integral(sin,l=0.0,u=3.14,n=100) ! calculate the approximation of  $\int_0^\pi \sin(x)dx$ 
```

```
...  
write (*,*) integral(bar,l=1.0,u=2.0,n=15) ! calculate the approximation of  $\int_1^2 \text{bar}(x)dx$ 
```


$$\int_a^b f(x)dx = h\left(\frac{f(a)+f(b)}{2} + f(a+h) + \dots + f(b-h)\right)$$

- Integral  $\int$  in math is another example where HOFs are useful for programming.
- Like C++, Fortran90 also supports a function that takes another function as its input parameter.
- The function `integral` can be implemented by using function parameters in C++.

# Evaluation order of function arguments

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- Given a function invocation  $\mathbf{func}(a_1, a_2, \dots, a_n)$ , and a function declaration  $\mathit{type} \mathbf{func}(\mathit{type}_1 \mathbf{d}_1, \mathit{type}_2 \mathbf{d}_2, \dots, \mathit{type}_n \mathbf{d}_n)$ ,
  - $a_i$  represents an expression for the  $i$ -th *actual argument* for the invocation
  - $d_i$  represents a variable for the  $i$ -th *dummy argument* for  $\mathbf{func}$ .
  - all the expressions for actual arguments are usually evaluated before  $\mathbf{func}$  is called. (consider the syntax tree)
- The order of evaluation is imposed differently depending on specific languages or compilers.
  - no order imposed  $\rightarrow$  Fortran
  - right-to-left  $\rightarrow$  gnu C++, Visual C++
- The order is important due to s\_\_\_\_\_t of expressions.

# Evaluation order of function arguments

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- **right-to-left** → *gnu C++*

```
void foo(int m, int n) { cout << m * 10 + n; }
void bar(int &a, int &b) { cout << a * 100 + b; }

int main() {
    int k = 5;
    ← foo(k+1, k+1); // call-by-value w/o side effect
    ← foo(++k, ++k); // w/ side effect
    ← foo(k++, k++); // w/ side effect
    bar(k+1, k+1); // call-by-ref. w/o side effect → error:
    ← bar(++k, ++k); // w/ side effect
    bar(k++, k++); // w/ side effect → error:
}
```

output

- **left-to-right**
- Comparison of expressions **k++** and **++k**

□ **++k** ≡ (&b=(k=k+1; k) } So... → **++k = 10; // ok**  
□ **k++** ≡ (&b=(k; k=k+1) } **k++ = 10; // error**

# Evaluation order of function arguments

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- Visual C++: *also right-to-left, but slightly different from gnu C++*

```
void foo(int m, int n) {
    cout << m * 10 + n;
}
void bar(int &a, int &b) {
    cout << a * 100 + b;
}
int main() {
    int k = 5;
    foo(k++, k++); // output → [ ] : [ ] gnu C++
    foo(++k, ++k); // output → [ ] : [ ] gnu C++
    foo(k++, ++k); // output → [ ] : [ ] gnu C++
    foo(++k, k++); // output → [ ] : [ ] gnu C++
    bar(++k, ++k); // output → [ ] : [ ] gnu C++
}
```

## gnu C++

`foo(x++, ++y)` // from r-2-l  
`n = ++y;` // assign expr  
`m = x++;` // assign expr

## Visual C++ // from r-2-l

`++y;` // for pre, compute first  
`m = x++;` // for post, assign expr  
`n = y;` // now assign var for pre

- What lesson do we take from the different results of compilers?
  - Do not make any assumption on the evaluation order even with C/C++.
  - For better portability, compute all actual arguments that have potential side effects before the function invocation.

`x = k++;`  
`y = ++k;`  
`foo(x, y)`

# Recursive structures

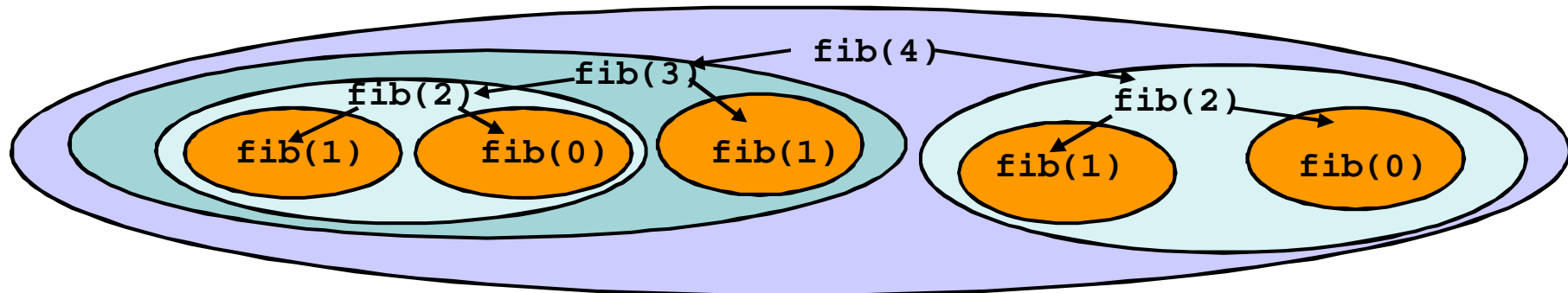
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- A function  $f$  is *recursive* if it contains an application of  $f$  in its definition.

```
int fib(int n) {  
    return ((n==0 || n==1) ? 1 : fib(n-1)+fib(n-2));  
}
```

- Recursion simplifies programming by exploiting a divide-and-conquer method. → “*divide a large problem into smaller ones*”



- Rewrite the function **fib** without using recursion, and find how many more lines you need for your code without recursion.



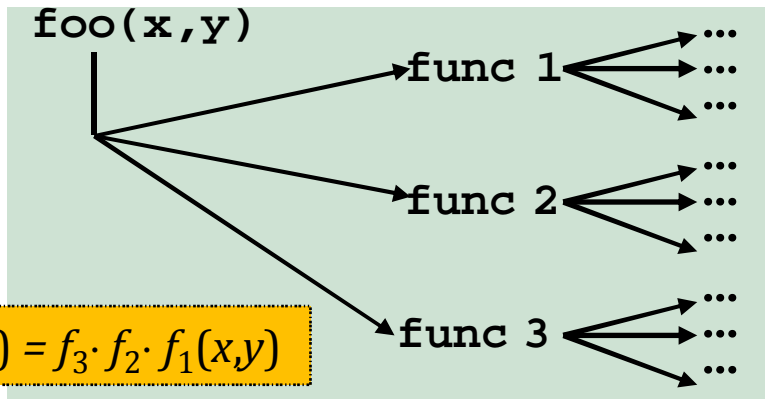
# Recursive structures

→ Ex:  $f_1 = F, f_2 = f_3 = \Sigma \rightarrow foo(i, j) = \sum_j \sum_i F(i, j)$

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- Recursion allows users to implement their algorithms in the applicative style rather than the imperative style.



*Applicative/Functional Programming*

```
foo(x, y) {  
  do this;  
  do that;  
  ...  
  do this;  
  do that;  
}
```

*Procedural/Imperative Programming*

- Recursion can be expensive if not carefully used.

→ Compare these two functions that compute the factorial

**compute the factorial with recursion**

```
int fac(int n) {  
  return (n==0 ? 1 : n*fac(n-1));  
}
```

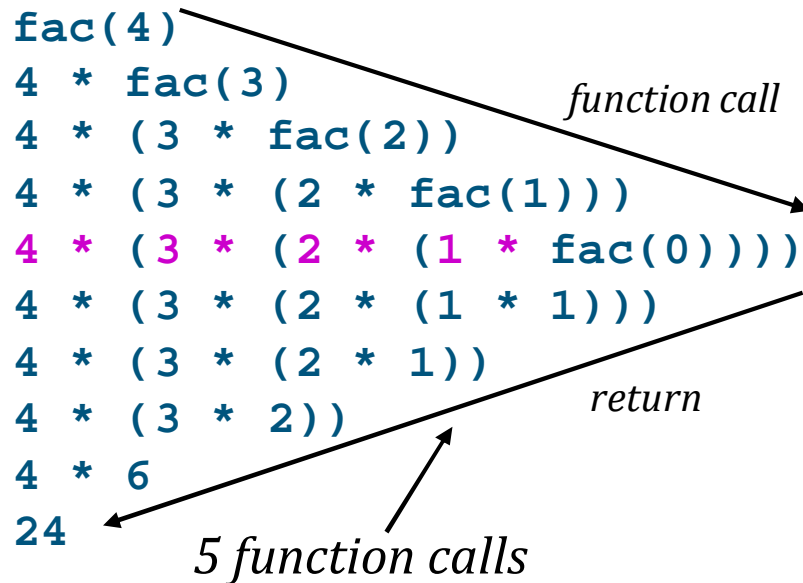
**compute the factorial with iteration**

```
int faci(int n) {  
  for (int p=1; n>0; n--) p=n*p;  
  return p;  
}
```

# Comparison of `fac` and `faci`

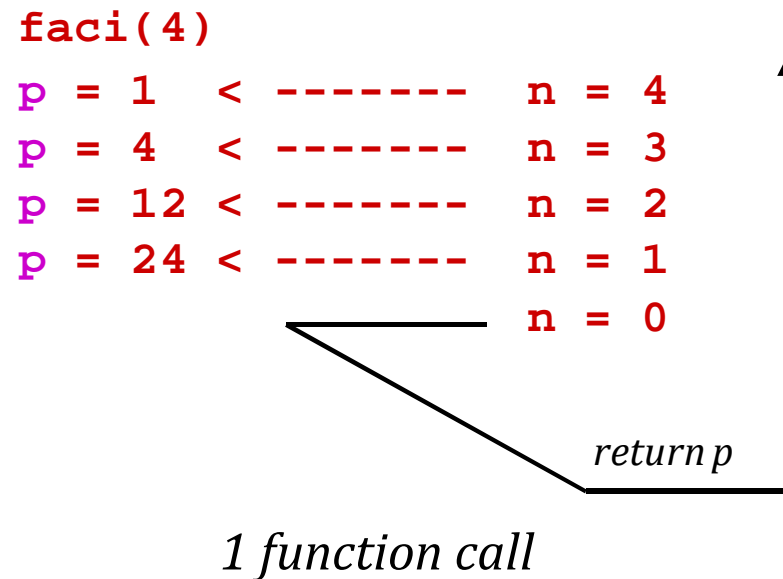


## Computation of `fac(4)`



upto 4 words to store the temporal data

## Computation of `faci(4)`



1 word to store the temporal data

- The main problem with the recursive version is that `fac` needs more memory space and function calls as the problem size `n` increases.
- In contrast, `faci` always needs only 1 function call and 1 word regardless of the value of `n`. → Suppose `n = 1000!`

# Tail recursion



- A function  $f$  is **tail-recursive** if it is a recursive function that returns either *a value without needing recursion* or *the result of a recursive activation*.

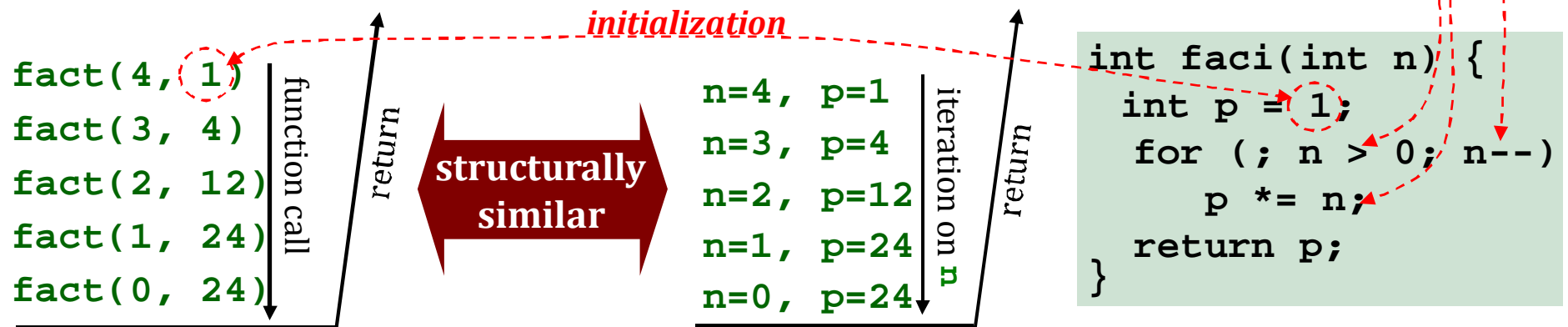
```
Ex: void fact(int n, int& p) { if (n > 0) { p*=n; fact(n-1,p); } }
```

no int!

→ cf: Neither **fib** nor **fac** is tail-recursive.

- What are tail-recursive functions so great about?

→ It is can always be translated to iterative structure.



# Application of tail recursion

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- Write a tail-recursive version of fib. → efficient & simple

```
void fibt(int n, int& l, int& r) {  
    if (n > 0) { l+=r; r=l; fibt(n-1,l,r); }  
}
```

`fibt(4,1,0)`

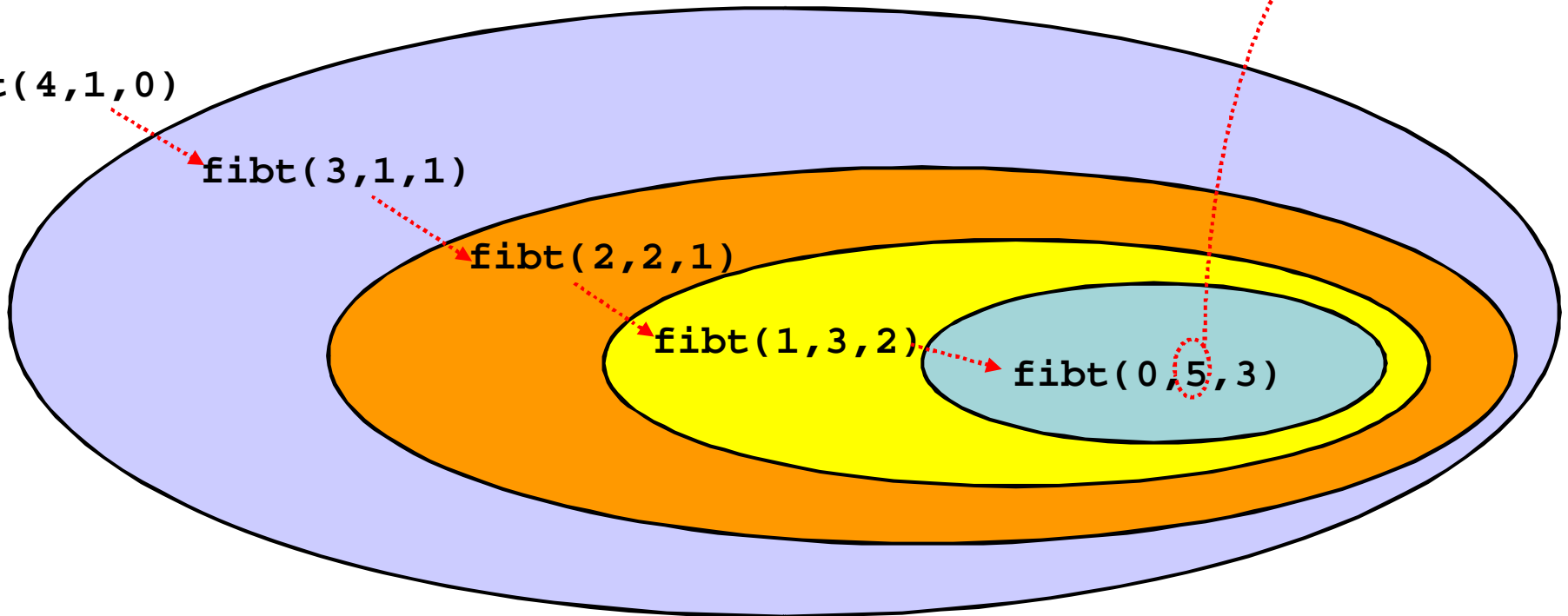
`fibt(3,1,1)`

`fibt(2,2,1)`

`fibt(1,3,2)`

`fibt(0,5,3)`

*return '5'*



# Inlining

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- While enjoying the advantages of using functions, can we minimize the overhead for function calls?
- For this, some languages such as C++ support *explicit inlining*.
- Pros and cons of inlining
  - removes the overhead for function call.
  - Reckless use may increase the code size.
  - Inlined code is generally less readable and maintainable.
    - So, inlining is ideal for a small procedure invoked within frequently executed regions (e.g., loops).
    - How about procedure with recursion?

```
void foo() {
    int x, y, z;
    ...
    y = bar(z, 99);
    z = bar(88, y);
    ...
}

inline int bar(int a, b) {
    int x, t;
    x = a * b;
    t = a - b;
    return x / t;
}
```



```
void foo() {
    int x, y, z, x1, t, x2, t1;
    ...
    x1 = z * 99;
    t = z - 99;
    y = x1 / t;
    x2 = 88 * y;
    t1 = 88 - y;
    z = x2 / t1;
    ...
}
```

# Exceptions

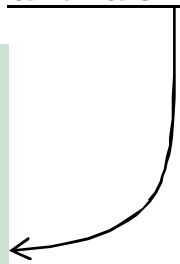
38



- Diverse types of error may occur in program execution
  - overflow, type error, segment faults, divide by zero, ...

- Example

```
int a = 9;
int b = 3;
...
... = 10 / (a - b * 3);
```



- **Exceptions** are such errors detected at run time.
- What would happen if your program ignores exceptions?
  - Errors will eventually cause *low-level message* (from O/S or hardware) to be printed and to terminate the program execution.
  - Low-level message from Linux

```
$ a.out
Abort (core dump)
```

# Exceptions

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- What is the problem with low-level messages?
  - They do not provide sufficient information about the error that caused your program to end.
  - They may even produce an unpredictable result or cause unexpected damage to your system. → *sudden crash of an aviation control system?*

- Alternative solution: *use test code defined by languages or users*

```
test_result = foo(a,b,c);  
if (test_result is error) raise exception;
```

- When an exception is raised, the normal program control is interrupted and the control is transferred to an **exception handler**, a special routine that handles the exception.
- Errors are controlled by the user, so they can be led to safer, predictable and user-guided states.

# Exception handling models

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```
foo (int i, char c) {  
    float a[10];  
    ...  
    if (error occurs)  
        raise exception(error-type);  
    ...  
}
```

```
exception_handler {  
    switch (error-type) {  
        case 1: handler1 ...  
        case 2: handler2 ...  
        ...  
        case n: handlern ...  
    }  
}
```

*continue*

*resumption model*

*abort*

*termination model*

*error analysis*  
*error report/print*  
*error correction*

- ❑ Exception handling makes programs robust & reliable.
- ❑ But, it may be tedious because it needs to test possible errors.
- ❑ This might be inefficient if errors occurs infrequently.



# Exception handling in C++

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- ❑ C++ originally had no explicit support for exceptions.
- ❑ In 1990, the ANSI C++ accepted the exception handling.
  - ❑ It provides a programming construct with **three keywords** for exception handlers : **try, catch, throw**

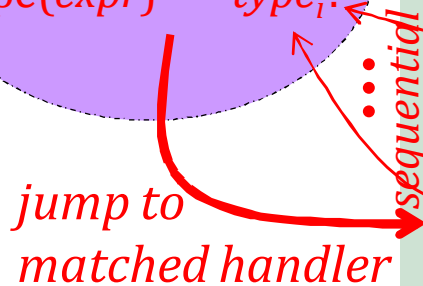
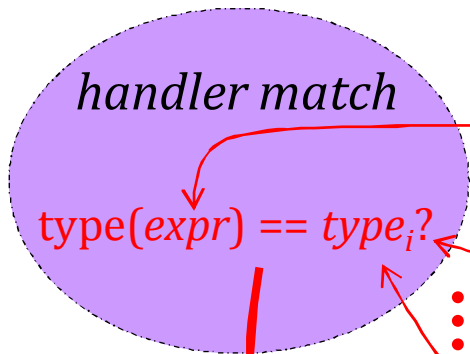
## ❑ Example

```
void foo(...) {  
    ...  
    try {  
        ... // code that is expected to raise a exception  
        throw expr // raise an exception with actual parameter  
    }  
    catch(type1 var1) { // a single formal parameter  
        ... //code for an exception handler1  
    }  
    ...  
    catch(typen varn) { // a single formal parameter  
        ... //code for an exception handlern  
    }  
    ...  
}
```

*try block*

*handler block*

*resume execution from the first instruction following the try/handler block after exception is handled*



# Example: exception handling in C++

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a derived class of standard library class **exception**

```
#include <cstdlib>
#include <iostream>
#include <stdexcept>
using std;

class Divide_by_0:
    public runtime_error {
public:
    Divide_by_0() :
        runtime_error("No, you cannot!") {}
};
```

```
Give two integers: 10 3
Can I divide 10 with 3?
Yes, you can divide 10 by 3.
```

```
Give two integers: 11 0
Can I divide 11 with 0?
Exception: No, you cannot!
```

```
Give two integers: ...
```

functional call expression

```
void is_dividable(int a, int b) {
    if (!b) throw Divide_by_0();
    cout << "Yes, you can divide ";
}

int main() {
    int x, y;
    cout << "Give two integers:";
    while (cin >> x >> y) {
        cout << "Can I divide " <<
            x << " with " << y << "?\n";
        try {
            is_dividable(x, y);
            cout << x << " by " << y
                << ".\n";
        }
        catch(Divide_by_0& d) {
            cout << "Exception: "
                << d.what() << endl;
        }
        cout << "\nGive two integers:";
    }
    return 0; // normal termination
}
```