

Chap. 7. Shape and Drag : Motile Animals

- streamlining : continuously facing into oncoming current) → animals (swimmers, flyers)
definite, noncompliant shape

§ Streamlining and the comparison of drag coefficients

* converting drag coefficients from one reference area to another

i) sphere



$$C_{D, \text{frontal}} = \frac{F_D}{\frac{1}{2}\rho U^2 (\pi R^2)} \sim \frac{1}{\pi R^2}$$

$$C_{D, \text{plan form}} = \quad \quad \quad "$$

$$C_{D, \text{wetted area}} = \frac{F_D}{\frac{1}{2}\rho U^2 (4\pi R^2)} \sim \frac{1}{4\pi R^2}$$

$$\frac{C_{D, w}}{C_{D, f}} = \frac{1}{4}$$

$$C_{D, V^{2/3}} = \frac{F_D}{\frac{1}{2}\rho U^2 \left(\frac{4}{3}\pi R^3\right)^{2/3}} \sim \frac{1}{2.16 R^2}$$

$$\frac{C_{D, V^{2/3}}}{C_{D, f}} = \frac{\pi}{2.16} = 1.208$$

ii) cylinder

iii) prolate spheroids



plan form area for sphere : πR^2

p.s. ($l:R=2:1$) : $\pi l R = 2\pi R^2$

$$\frac{C_{D, p.s.}}{C_{D, s}} = \frac{1}{2}$$

...> Table 7.1.

* quality of streamlining

streamlining ~ prevents separation

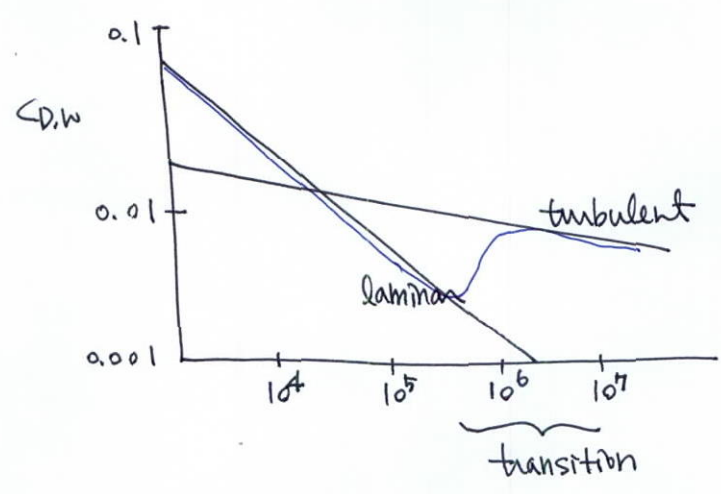
ideal nonseparating flow ~ flow across a flat plate parallel to the flow.

for flat plate,

$C_{D,w} = 1.33 Re_L^{-0.5}$ (laminar)

$C_{D,w} = 0.072 Re_L^{-0.2}$ (turbulent)

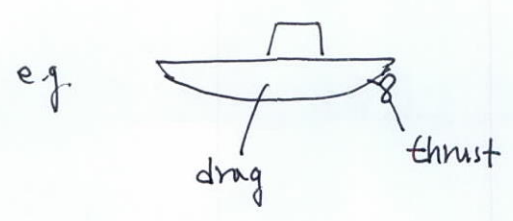
L-T transition : $\sim 5 \times 10^5 \sim 1 \times 10^7$



§ Drag and thrust

drag = thrust in steady speed horizontal motion otherwise still medium

separation bet. thrust-generating and drag-sustaining structures.



In biological systems, the separation is imperfect.

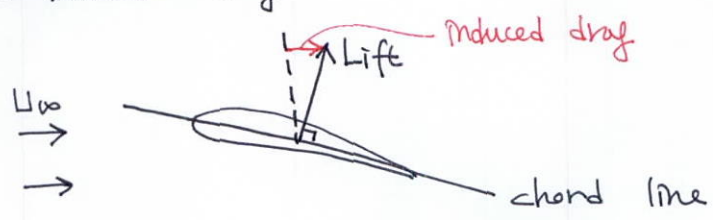
- non-thrust-producing structures are subjected to
 - simple and smooth oncoming flow
 - complex and temporally varying flow from wings or legs
- some fish / invertebrate larvae with ciliated region
 - ~ whole body participates in propulsion

e.g. ciliated microorganism
 flow with the cilia beating
 ≠ flow around the creature falling under gravity at the same speed

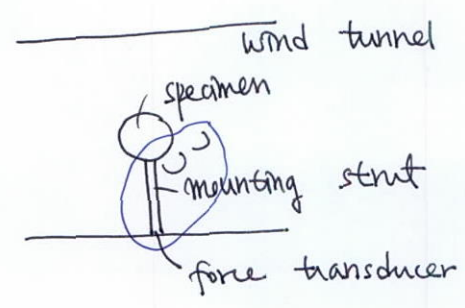
Types of drag

① parasite drag (when thrust-producing appendages involved)
 = combined drag of all non-thrust-producing structures (external drag that the thrust producer has to offset)

② induced drag



③ interference drag



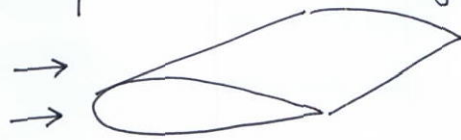
④ added mass

· simple way to get (sometimes) drag figures for swimming / flying animals

∴ they don't swim / fly continuously
- "gliding" is quite a normal event.

§ Looking for streamlined struts (2-D)

· relatively uncommon among organisms.



e.g. mayfly nymph legs (living in rapid stream)
crab legs (walk around or stand erect in water currents)

hammerhead sharks



water/air interface → chap. 17

e.g. skimmer bill, fishing bat toe

§ A diversity of streamlined bodies (3-D)

· 3-D streamlined body ~ hallmark of virtually every competent swimmer or flyer

Fig. 17.3.

* Smallish arthropods

· reduction of maximum travel range by resistance (air drag)

baseball: 19%

golf ball: 36%

jumping locust: 16% , geertz flea: 83%

- * For small insects, drag becomes more important relative to gravity

$$\begin{aligned} \therefore \text{area} &\sim L^2 & L \downarrow & - \frac{V \downarrow}{\uparrow} \\ \text{volume} &= L^3 \end{aligned}$$

Fig. 7.4

- drag coeff. of small arthropods : bet spheres and plates

- * several undistinguished swimmers
eg. frogs, crabs, ducks underwater
- high C_D

* Fish

* Birds

: feather increases C_D

* Penguins

: lowest cost of transport (energy expenditure per unit mass and distance) in all aquatic endotherms
(온혈동물)

* Marine mammals

⊗ Tricks for reducing drag - hope and reality

- well documented ways organisms minimize drag
- ① extreme flexibility in flow
 - ② streamlining
 - ③ growth to great length in oscillating flow
 - ④ staying close to a solid surface
 - ⑤ expulsion of water through opercula in ram ventilation in fish

other schemes

: mostly describe ways organisms, largely large swimming animals, can get body drag down below that of a flat plate with turbulent flow.

$$(f) C_{D,turb} \approx 3.4 C_{D,laminar} \quad \text{at } Re = 10^6.$$

* compliant surfaces

e.g. cetacean



mechanism: damping of incipient turbulence

* Mucus secretions (점액)

e.g. fish, dolphin

mechanism: adding long-chained polymers to a flow, especially if they're added in the velocity gradients at surfaces, can reduce drag

skepticism: (1) rate of polymer secretion for good effect
> rate fish can reasonably manage
(2) cost of producing such secretions
> benefit of drag reduction

cf. snail indeed uses mucus secretion for locomotion

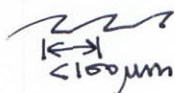
* surface heating e.g.: cetacean

mech: $\mu_{water} \downarrow$ as $T \uparrow$


drag on hot surface < drag on cold surface

* surface morphology

e.g. ridging characteristics of dermal scales of sharks



mechanism: reduction of skin friction
not postponement of separation

physical evidence: riblets 
on racing yachts, airplane wings.

* Drag-based locomotion e.g. mammals, birds, arthropods

- appendage moving back and forth
drag in power stroke > drag in recovery stroke
- drag reduction in recovery stroke
: appendage folded or twisted
~ close to body, parallel to flow
setae lie back
- drag increase in power stroke
: appendage (setae) stick out