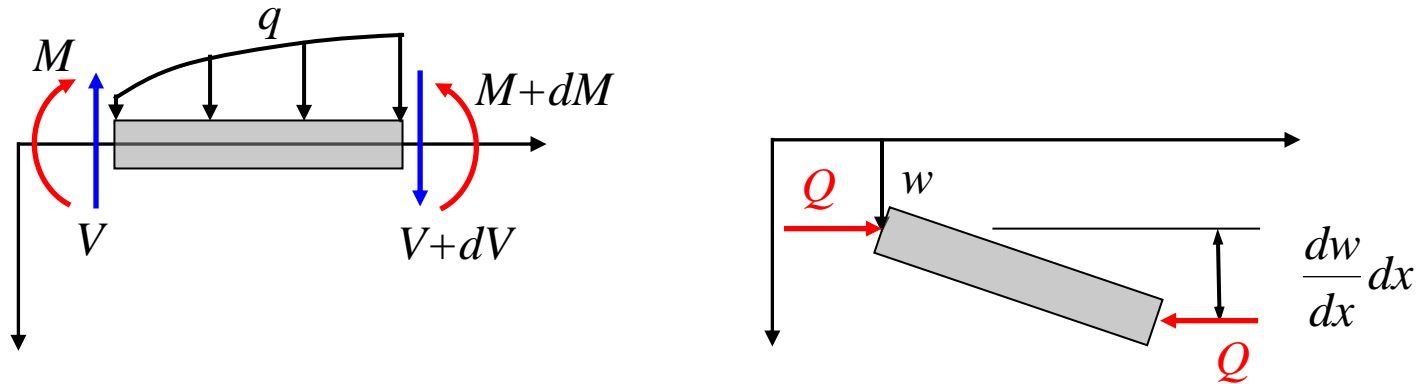


Chapter 1

Beam Equations

1.1 Governing Equation for a Beam with Axial Force



- **Equilibrium for vertical force**

$$(V + dV) - V + (q - kw - m \frac{d^2 w}{dt^2}) dx = 0 \rightarrow \frac{dV}{dx} - kw = -q + m \frac{d^2 w}{dt^2}$$

- **Equilibrium for moment**

$$(M + dM) - M - Vdx + (q - kw - m \frac{d^2 w}{dt^2}) dx \frac{dx}{2} - Q \frac{dw}{dx} dx = 0 \rightarrow \frac{dM}{dx} - Q \frac{dw}{dx} = V$$

- **Elimination of shear force**

$$\frac{d^2 M}{dx^2} - Q \frac{d^2 w}{dx^2} - kw = -q + m \frac{d^2 w}{dt^2}$$

- **Strain-displacement relation**

$$\varepsilon = -\frac{d^2w}{dx^2}y + \frac{du}{dx}$$

- **Stress-strain relation (Hooke law)**

$$\sigma = E\varepsilon = -E\frac{d^2w}{dx^2}y + E\frac{du}{dx}$$

- **Definition of Moment**

$$M = \int_A \sigma y dA = \int_A E\varepsilon y dA = -\int_A (E\frac{d^2w}{dx^2}y^2 - E\frac{du}{dx}y) dA = -EI\frac{d^2w}{dx^2}$$

- **Beam Equation with Axial Force**

$$EI\frac{d^4w}{dx^4} + Q\frac{d^2w}{dx^2} + kw = q - m\frac{d^2w}{dt^2}$$

1.2 General Solution

- **Characteristic Equation for $Q > 0$**

$$w = e^{\lambda x}$$

$$e^{\lambda x}(\lambda^4 + \beta^2 \lambda^2) = 0 \rightarrow \lambda = \pm \beta i, 0 \quad \text{where } \beta^2 = \frac{Q}{EI}$$

- **Homogeneous solution**

$$w = Ae^{\beta ix} + Be^{-\beta ix} + Cx + D$$

- **Homogeneous solution**

$$\begin{aligned} w &= A(\cos \beta x + i \sin \beta x) + B(\cos \beta x - i \sin \beta x) + Cx + D \\ &= (A + B) \cos \beta x + i(A - B) \sin \beta x + Cx + D \\ &= A \cos \beta x + B \sin \beta x + Cx + D \end{aligned}$$

- **Characteristic Equation for $Q < 0$**

$$w = e^{\lambda x}$$

$$e^{\lambda x}(\lambda^4 - \beta^2 \lambda^2) = 0 \rightarrow \lambda = \pm \beta, 0 \quad \text{where } \beta^2 = \left| \frac{Q}{EI} \right|$$

- **Homogeneous solution for $Q < 0$**

$$\begin{aligned}
 w &= Ae^{\beta x} + Be^{-\beta x} + Cx + D \\
 &= (A + B) \frac{e^{\beta x} + e^{-\beta x}}{2} + (A - B) \frac{e^{\beta x} - e^{-\beta x}}{2} + Cx + D \\
 &= A \cosh \beta x + B \sinh \beta x + Cx + D
 \end{aligned}$$

- **General Solution**

$$w = w_h + w_p = A \cos \beta x + B \sin \beta x + Cx + D + w_p$$

$$EI \frac{d^4(w_h + w_p)}{dx^4} + Q \frac{d^2(w_h + w_p)}{dx^2} = EI \frac{d^4 w_h}{dx^4} + Q \frac{d^2 w_h}{dx^2} + EI \frac{d^4 w_p}{dx^4} + Q \frac{d^2 w_p}{dx^2} = EI \frac{d^4 w_p}{dx^4} + Q \frac{d^2 w_p}{dx^2} = q$$

- **Four Boundary Conditions for Simple Beams**

$$w(0) = A + D + w_p(0) = 0$$

$$M(0) = -EIw''(0) = -EI(-A\beta^2 + w_p''(0)) = 0$$

$$w(L) = A \cos \beta L + B \sin \beta L + CL + D + w_p(L) = 0$$

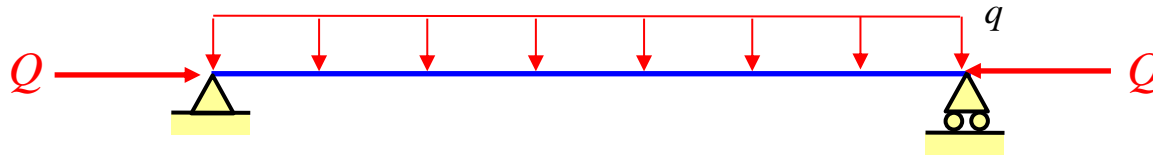
$$M(L) = -EIw''(L) = -EI(-A\beta^2 \cos \beta L - B\beta^2 \sin \beta L + w_p''(L)) = 0$$

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ -\beta^2 & 0 & 0 & 0 \\ \cos\beta L & \sin\beta L & L & 1 \\ -\beta^2 \cos\beta L & -\beta^2 \sin\beta L & 0 & 0 \end{bmatrix} \begin{pmatrix} A \\ B \\ C \\ D \end{pmatrix} + \begin{pmatrix} w_p(0) \\ w_p''(0) \\ w_p(L) \\ w_p''(L) \end{pmatrix} = 0 \rightarrow \mathbf{KX} + \mathbf{F} = 0$$

- The homogenous solution is for the boundary conditions, while the particular solution is for the equilibrium.

1.3 Analysis of Beam-Columns and Buckling Load

- **Beam Column - Simple Beam Subject to a Uniformly Distributed Load**



- Governing Equation

$$EI \frac{d^4 w}{dx^4} + Q \frac{d^2 w}{dx^2} = q$$

- Particular Solution

$$w_p(x) = \frac{q}{2Q} x^2$$

- General Solution

$$w(x) = A \cos \beta x + B \sin \beta x + Cx + D + \frac{q}{2Q} x^2$$

$$w''(x) = -A\beta^2 \cos \beta x - B\beta^2 \sin \beta x + \frac{q}{Q}$$

- Boundary Condition

$$w(0) = A + D = 0 \quad , \quad M(0) = -EIw''(0) = -EI(-A\beta^2 + \frac{q}{Q}) = 0 \rightarrow A = \frac{q}{Q\beta^2}, D = -\frac{q}{Q\beta^2}$$

$$w(L) = B\sin\beta L + CL + \frac{q}{Q\beta^2}(\cos\beta L - 1) + \frac{q}{2Q}L^2 = 0$$

$$M(L) = -EIw''(L) = -EI(-A\beta^2 \cos\beta L - B\beta^2 \sin\beta L + \frac{q}{Q}) = 0$$

$$-\frac{q}{Q}\cos\beta L - B\beta^2 \sin\beta L + \frac{q}{Q} = 0 \rightarrow B\beta^2 \sin\beta L = -\frac{q}{Q}(\cos\beta L - 1)$$

$$B\beta^2 2\sin\frac{\beta L}{2}\cos\frac{\beta L}{2} = -\frac{q}{Q}(1 - 2\sin^2\frac{\beta L}{2} - 1) \rightarrow B = \frac{1}{\beta^2} \frac{q}{Q} \tan\frac{\beta L}{2}$$

$$C = -\frac{q}{2Q}L$$

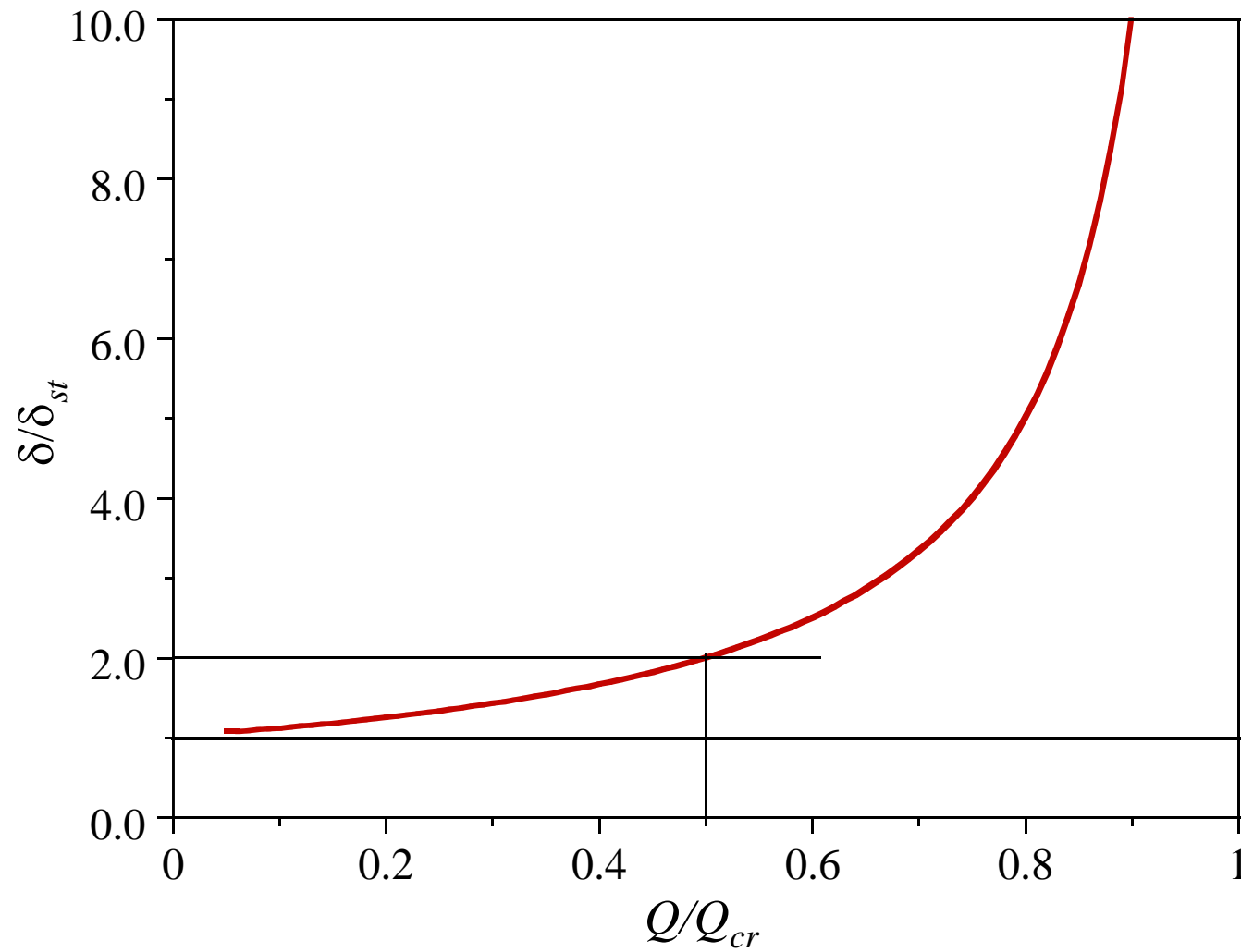
- Final solution

$$w(x) = \frac{q}{\beta^2 Q}(\cos\beta x - 1) + \frac{q}{\beta^2 Q} \tan\frac{\beta L}{2} \sin\beta x - \frac{q}{2Q}Lx + \frac{q}{2Q}x^2$$

$$M(x) = -EIw''(x) = EI\left(\frac{q}{Q}\cos\beta x + \frac{q}{Q} \tan\frac{\beta L}{2} \sin\beta x - \frac{q}{Q}\right)$$

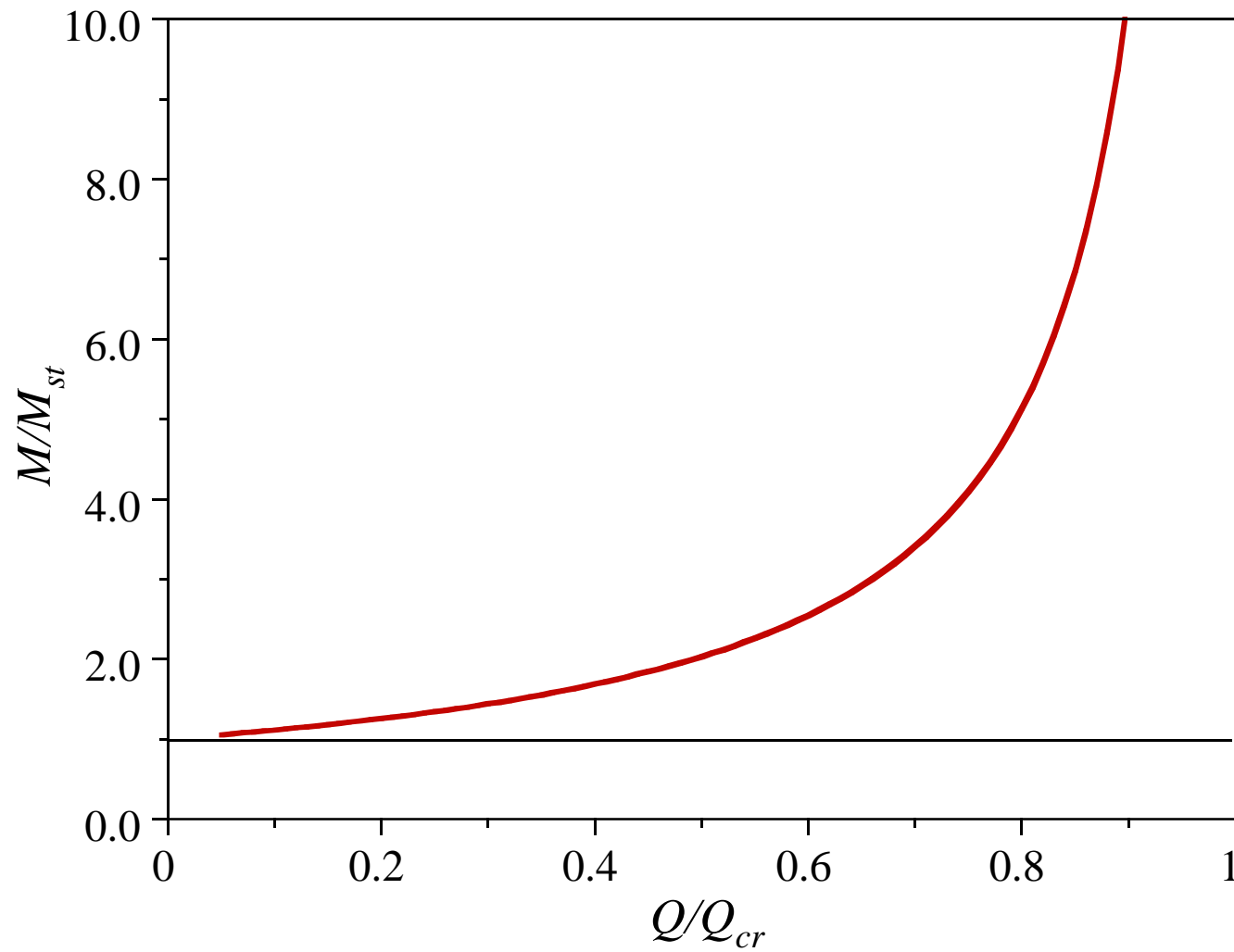
- Deflection at the Mid-span

$$\begin{aligned}
w\left(\frac{L}{2}\right) &= \frac{q}{\beta^2 Q} \left(\cos \frac{\beta L}{2} - 1\right) + \frac{1}{\beta^2} \frac{q}{Q} \tan \frac{\beta L}{2} \sin \frac{\beta L}{2} - \frac{q}{8Q} L^2 \\
&= \frac{q}{\beta^2 Q} \left(\cos \frac{\beta L}{2} + \tan \frac{\beta L}{2} \sin \frac{\beta L}{2} - 1\right) - \frac{q}{8Q} L^2 \\
&= \frac{q}{\beta^2 Q} \left(\frac{1}{\cos \frac{\beta L}{2}} - 1 - \frac{L^2 \beta^2}{8}\right) \\
&= \frac{5qL^4}{384EI} \frac{384}{5\pi^4} \frac{\pi^4 EI^2}{Q^2 L^4} \left(\frac{1}{\cos \frac{\pi}{2} \sqrt{L^2 Q / \pi^2 EI}} - 1 - \frac{\pi^2}{8} \frac{QL^2}{\pi^2 EI}\right) \\
&= \delta_{st} 0.7884 \left(\frac{Q_{cr}}{Q}\right)^2 \left(\frac{1}{\cos \frac{\pi}{2} \sqrt{Q / Q_{cr}}} - 1 - \frac{\pi^2}{8} \frac{Q}{Q_{cr}}\right) \\
&= \delta_{st} \frac{0.7884}{t^2} \left(\frac{1}{\cos \frac{\pi}{2} \sqrt{t}} - 1 - \frac{\pi^2}{8} t\right) \quad \left(t = \frac{Q}{Q_{cr}}\right)
\end{aligned}$$

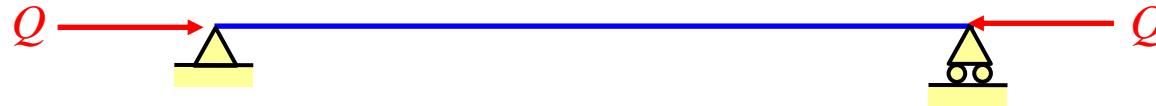


- Moment at the Mid-span

$$\begin{aligned}
M\left(\frac{L}{2}\right) &= EI \frac{q}{Q} \left(\cos \beta \frac{L}{2} + \tan \frac{\beta L}{2} \sin \frac{\beta L}{2} - 1 \right) \\
&= \frac{qL^2}{8} \frac{8}{\pi^2} \frac{\pi^2 EI}{QL^2} \left(\cos \beta \frac{L}{2} + \tan \frac{\beta L}{2} \sin \frac{\beta L}{2} - 1 \right) \\
&= M_{st} \frac{8}{\pi^2} \frac{Q_{cr}}{Q} \left(\frac{1}{\cos \frac{\pi}{2} \sqrt{Q/Q_{cr}}} - 1 \right) \\
&= M_{st} 0.811 \frac{1}{t} \left(\frac{1}{\cos \frac{\pi}{2} \sqrt{t}} - 1 \right)
\end{aligned}$$



• **Buckling Analysis of Simple Beam**



- Boundary Condition

$$w(0) = A + D = 0 \quad , \quad w''(0) = -A\beta^2 = 0 \rightarrow A = 0$$

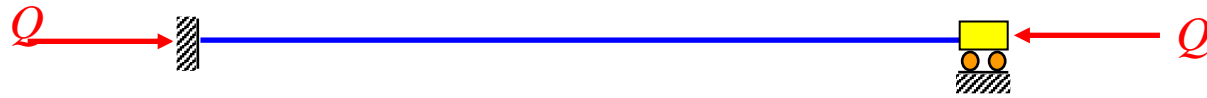
$$w(L) = B \sin \beta L + CL = 0 \quad , \quad w''(L) = -B\beta^2 \sin \beta L = 0 \rightarrow B = C = 0$$

- Characteristic Equation

$$A = B = C = D = 0 \rightarrow w = 0 \quad (???) \quad \text{or} \quad \beta L = n\pi \rightarrow Q = \frac{n^2 \pi^2 EI}{L^2} \quad , \quad n = 1, 2, 3, \dots$$

$$w = B \sin \beta x = B \sin \frac{n\pi}{L} x$$

- Buckling Analysis of Fixed-Fixed Beam**



- Boundary Condition

$$w(0) = A + D = 0, \quad w'(0) = \beta B + C = 0$$

$$w(L) = A \cos \beta L + B \sin \beta L + CL + D = 0, \quad w'(L) = -A\beta \sin \beta L + B\beta \cos \beta L + C = 0 \quad \text{or}$$

- Characteristic Equation

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & \beta & 1 & 0 \\ \cos \beta L & \sin \beta L & L & 1 \\ -\beta \sin \beta L & \beta \cos \beta L & 1 & 0 \end{bmatrix} \begin{pmatrix} A \\ B \\ C \\ D \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \text{Det} \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & \beta & 1 & 0 \\ \cos \beta L & \sin \beta L & L & 1 \\ -\beta \sin \beta L & \beta \cos \beta L & 1 & 0 \end{pmatrix} = 0$$

$$\begin{vmatrix} 1 & 0 & 0 & 1 \\ 0 & \beta & 1 & 0 \\ \cos \beta L & \sin \beta L & L & 1 \\ -\beta \sin \beta L & \beta \cos \beta L & 1 & 0 \end{vmatrix} = \begin{vmatrix} \beta & 1 & 0 \\ \sin \beta L & L & 1 \\ \beta \cos \beta L & 1 & 0 \end{vmatrix} - \begin{vmatrix} 0 & \beta & 1 \\ \cos \beta L & \sin \beta L & L \\ -\beta \sin \beta L & \beta \cos \beta L & 1 \end{vmatrix}$$

$$-\beta - (-\beta \cos \beta L) - (-\beta(\cos \beta L + \beta L \sin \beta L) + \beta) = \beta(2 \cos \beta L - 2 + \beta L \sin \beta L) = 0$$

$$2 \cos \beta L - 2 + \beta L \sin \beta L = 2(\cos \beta L - 1) + \beta L \sin \beta L = -4 \sin^2 \frac{\beta L}{2} + 2\beta L \sin \frac{\beta L}{2} \cos \frac{\beta L}{2} = 0$$

$$\sin \frac{\beta L}{2} \left(\frac{\beta L}{2} \cos \frac{\beta L}{2} - \sin \frac{\beta L}{2} \right) = 0 \rightarrow \sin \frac{\beta L}{2} = 0 \text{ or } \frac{\beta L}{2} \cos \frac{\beta L}{2} - \sin \frac{\beta L}{2} = 0$$

- Eigenvalues

$$w(0) = A + D = 0, \quad w'(0) = \beta B + C = 0$$

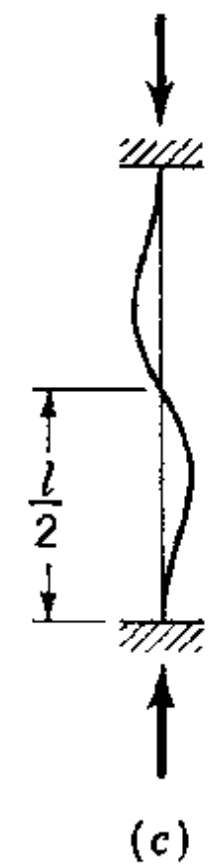
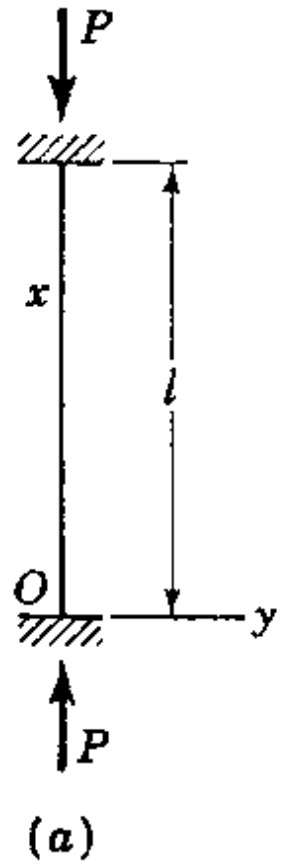
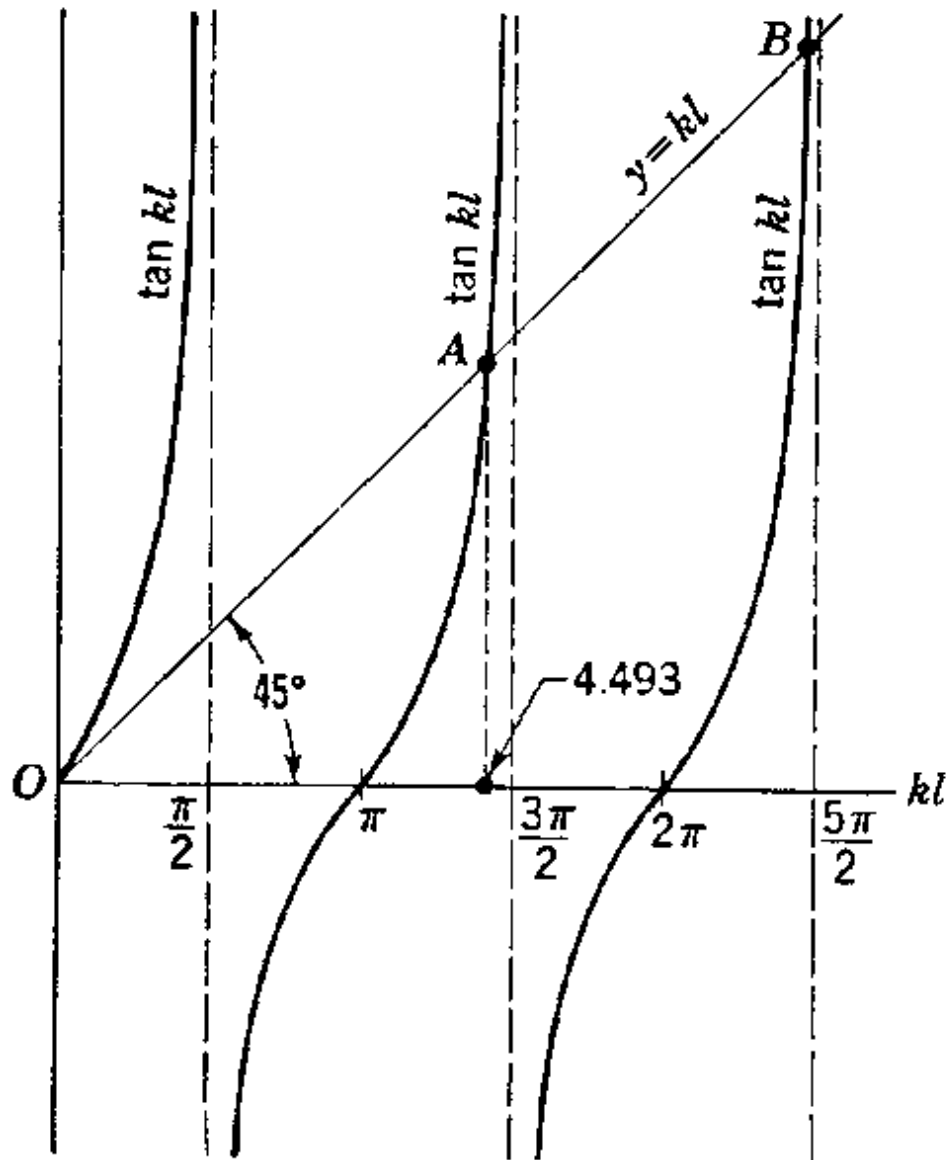
$$w(L) = A \cos \beta L + B \sin \beta L + CL + D = 0, \quad w'(L) = -A\beta \sin \beta L + B\beta \cos \beta L + C = 0$$

Symmetric modes: $\sin \frac{\beta L}{2} = 0 \rightarrow \frac{\beta L}{2} = n\pi \rightarrow Q = \frac{4n^2 \pi^2 EI}{L^2}, \quad n = 1, 2, 3, \dots$

$$w(0) = A + D = 0, \quad w'(0) = \beta B + C = 0, \quad w(L) = A + CL + D = 0, \quad w'(L) = \beta B + C = 0$$

$$A + D = 0 \rightarrow A = -D \rightarrow w = A \left(\cos \frac{2n\pi}{L} x - 1 \right) \text{ for } A \neq 0$$

Anti-symmetric modes: $\frac{\beta L}{2} \cos \frac{\beta L}{2} - \sin \frac{\beta L}{2} = 0 \rightarrow \frac{\beta L}{2} = \tan \frac{\beta L}{2} \rightarrow Q = \frac{8.18\pi^2 EI}{L^2}$



- **Buckling Analysis of Cantilever Beam**



- Boundary Condition

$$w(0) = A + D = 0$$

$$w'(0) = \beta B + C = 0$$

$$M(L) = -EIw''(L) = -EI(-A\beta^2 \cos \beta L - B\beta^2 \sin \beta L) = 0$$

$$V(L) = -EI \frac{d^3 w}{dx^3} - Q \frac{dw}{dx} = 0$$

- Buckling load

$$Q = \frac{n^2 \pi^2 EI}{4L^2}, \quad n = 1, 2, 3, \dots$$