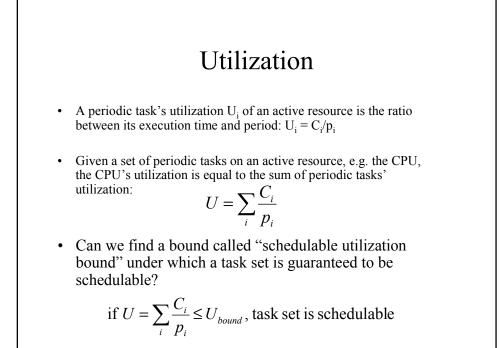
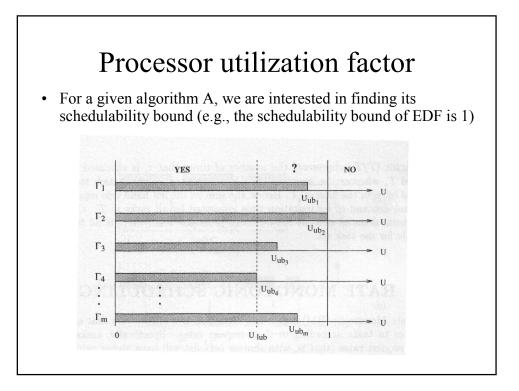
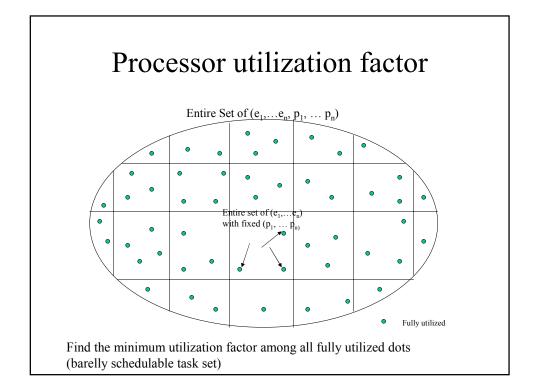
Priority-Driven Scheduling of Periodic Tasks (2) - Chapter 6 -

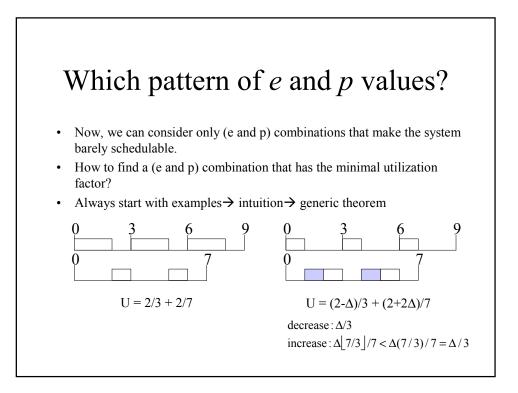
Schedulable utilization bound

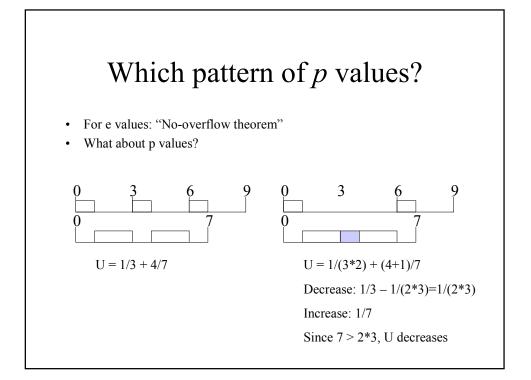
• Simpler method for the schedulability check

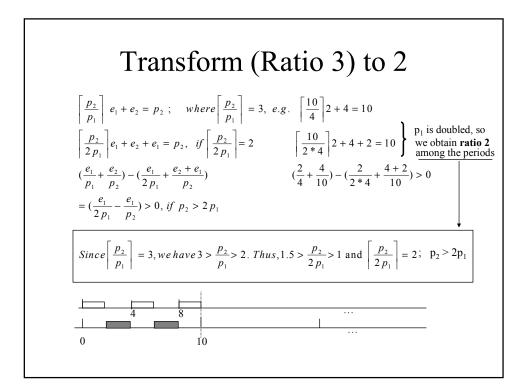




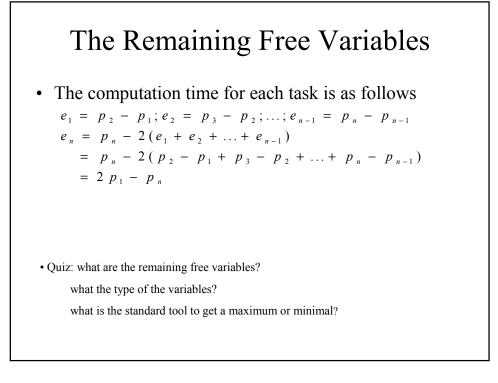


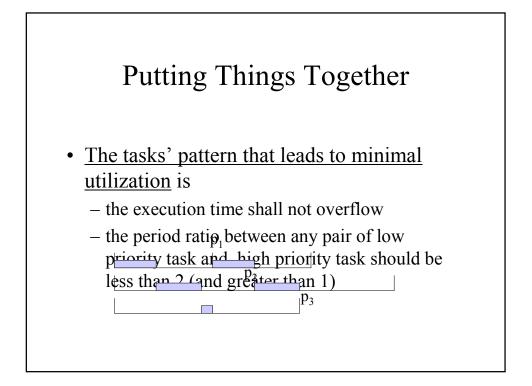


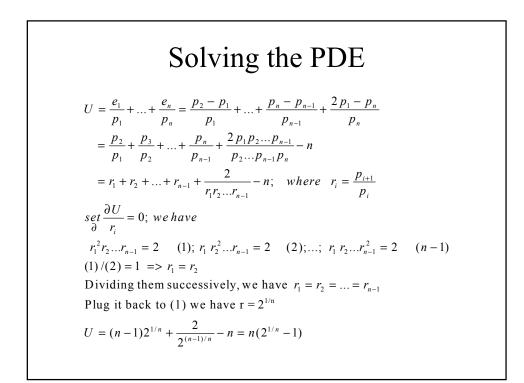




$$\begin{aligned} & \operatorname{Transform} \left(\operatorname{Ratio} k \ge 2 \right) \text{ to } 2 \\ & \left[\frac{p_2}{p_1} \right] = k, \text{ we have } k \ge \frac{p_2}{p_1} \ge k-1. \text{ Thus, } \frac{k}{k-1} \ge \frac{p_2}{(k-1)p_1} \ge 1 \text{ and } \left[\frac{p_2}{(k-1)p_1} \right] = 2 \\ & \left[\frac{p_2}{p_1} \right] e_1 + e_2 = p_2; \text{ original} \\ & \left[\frac{p_2}{(k-1)p_1} \right] e_1 + e_2 + (k-2)e_1 = 2e_1 + e_2 + (k-2)e_1 = p_2; \text{ after transform} \\ & \left(\frac{e_1}{p_1} + \frac{e_2}{p_2} \right) - \left(\frac{e_1}{(k-1)p_1} + \frac{e_2 + (k-2)e_1}{p_2} \right) \\ & = \left(\frac{(k-2)e_1}{(k-1)p_1} + \frac{(k-2)e_1}{p_2} \right) \ge 0, \text{ since } (k-1)p_1 \le p_2 \end{aligned}$$





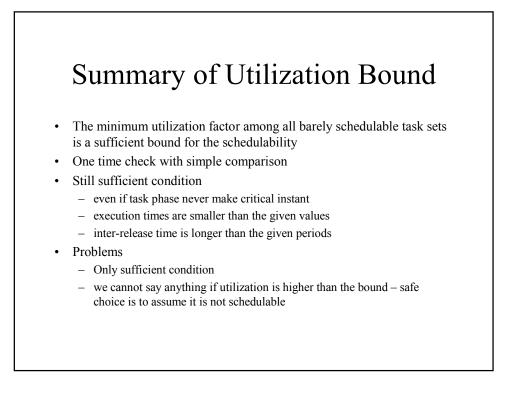


The L&L Bound

A set of *n* periodic task is schedulable if :

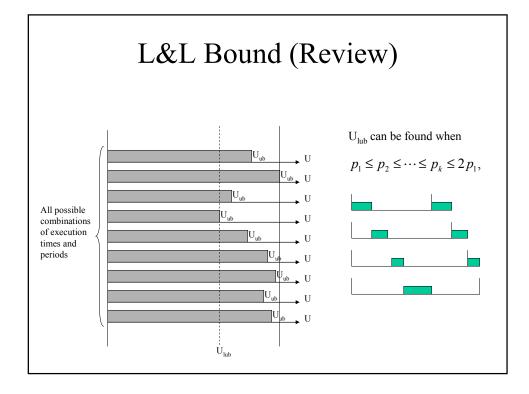
$$\frac{e_1}{p_1} + \frac{e_2}{p_2} + \dots + \frac{e_n}{p_n} \le n(2^{1/n} - 1)$$

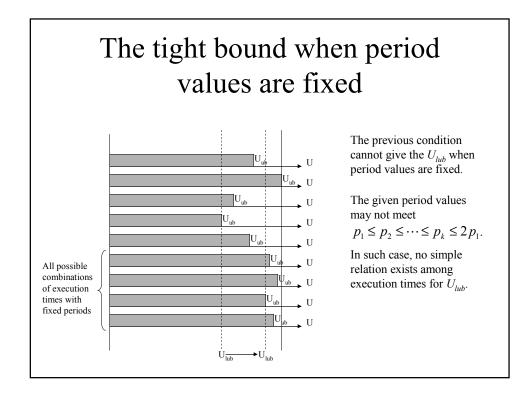
- U(1) = 1.0 U(4) = 0.756 U(7) = 0.728
- U(2) = 0.828 U(5) = 0.743 U(8) = 0.724
- U(3) = 0.779 U(6) = 0.734 U(9) = 0.720
- For harmonic task sets, the utilization bound is U(n)=1.00 for all n. For large n, the bound converges to *ln* 2 ~ 0.69.
- The L&L bound for rate monotonic algorithm is one of the most significant results in real-time scheduling theory. Its derivation also shows a wealth of analysis techniques that are useful in many new situations when considering static priority scheduling.

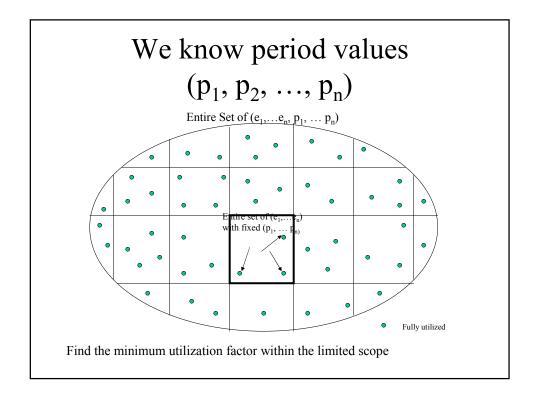


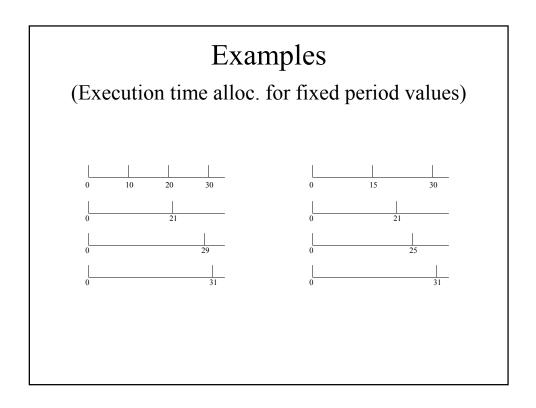
Enhancement of Utilization Bound

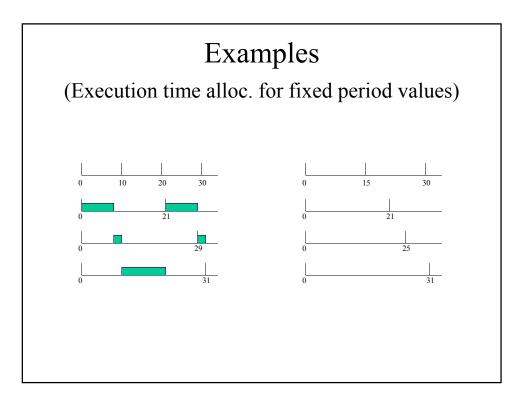
- L&L bound takes the worst case (with minimum utilization factor) worrying about all possible values of execution times and periods
- If some parameters are fixed, L&L worst case may not happen, and hence L&L bound is unnecessarily pessimistic for such limited problem scope
- What if we know period values?
- The more we know the higher is the schedulability bound.

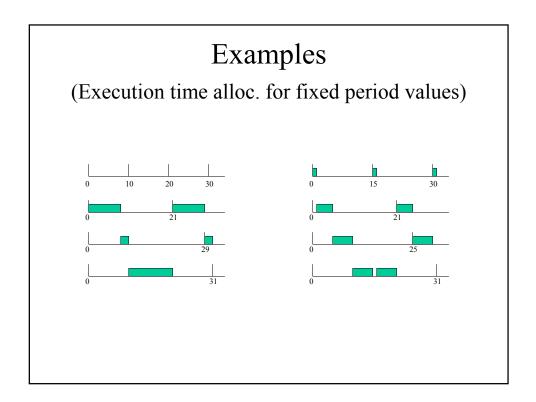


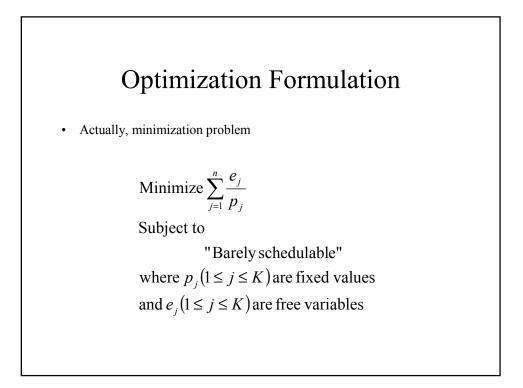


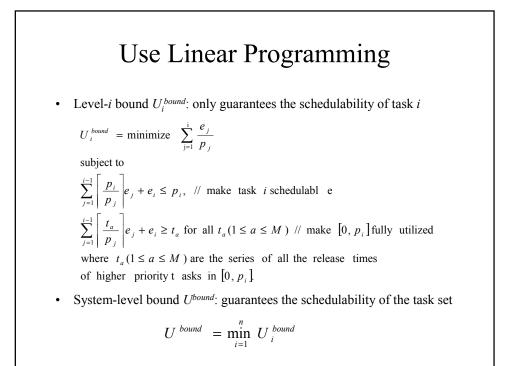


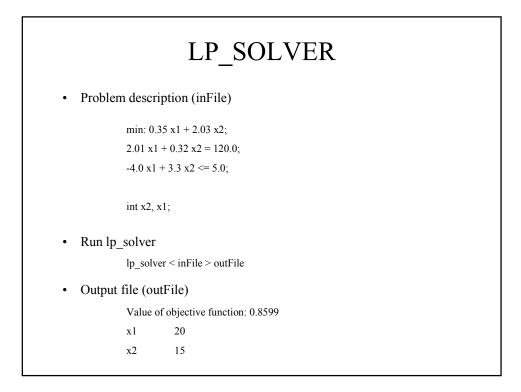












Practical Issues

- Practical Issues
 - What if there is a non-preemptable code section (e.g., system call)?
 - What if the context switch overhead is not negligible?
 - Tick scheduling?
 - The deadline is earlier than the period?

Non-preemptable code section

- a non-preemptable code section (NPS) of a low priority task *blocks* high priority task
 - How to take this into account in time-demand analysis?

$$b_i = \max_{j=i+1}^n NPS_j$$
$$r_i = e_i + b_i + \sum_{j=1}^{i-1} \left[\frac{r_i}{p_j} \right] e_j$$

