

# Engineering Mathematics I

## - Chapter 1. First-Order ODEs

(1계 상미분 방정식)

민기복

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# Introduction



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1. Basic Concepts. Modeling
2. Geometric Meaning of  $y'=f(x,y)$ . Directional Fields
3. Separable ODEs (변수분리형 상미분방정식). Modeling
4. Exact ODEs (완전 상미분방정식). Integrating Factors.
5. Linear ODEs (선형 상미분방정식). Bernoulli Equation. Population Dynamics
6. Orthogonal Trajectories (직교곡선족). *Optional*
7. Existence and Uniqueness of Solutions (해의 존재성과 유일성)

# Introduction

## Physical problem vs. mathematical modeling



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- Many physical behavior can be expressed as differential equation (containing derivatives of unknown function)
- Three Steps
  1. Deriving them from physical or other problems (modeling)
  2. Solving them by standard methods
  3. Interpreting solutions and their graphs in terms of a given problem

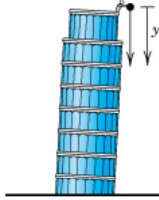

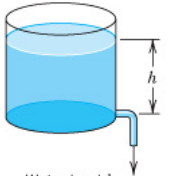
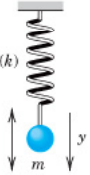
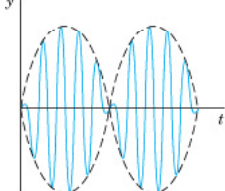
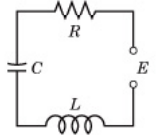
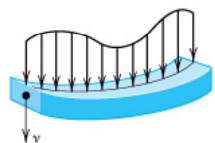
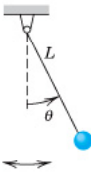
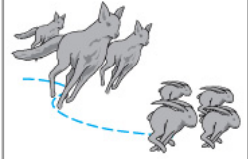
 <p>Falling stone  <math>y'' = g = \text{const.}</math>                      (Sec. 1.1)</p>	 <p>Parachutist  <math>mv' = mg - bv^2</math>                      (Sec. 1.2)</p>	 <p>Water level <math>h</math>                      Outflowing water  <math>h' = -k\sqrt{h}</math>                      (Sec. 1.3)</p>
 <p>Displacement <math>y</math>                      Vibrating mass on a spring  <math>my'' + ky = 0</math>                      (Secs. 2.4, 2.8)</p>	 <p>Beats of a vibrating system  <math>y'' + \omega_0^2 y = \cos \omega t, \quad \omega_0 = \omega</math>                      (Sec. 2.8)</p>	 <p>Current <math>I</math> in an RLC circuit  <math>LI'' + RI' + \frac{1}{C}I = E'</math>                      (Sec. 2.9)</p>
 <p>Deformation of a beam  <math>EIy^{iv} = f(x)</math>                      (Sec. 3.3)</p>	 <p>Pendulum  <math>L\theta'' + g \sin \theta = 0</math>                      (Sec. 4.5)</p>	 <p>Lotka-Volterra predator-prey model  <math>y_1' = ay_1 - by_1y_2</math>  <math>y_2' = ky_1y_2 - ly_2</math>                      (Sec. 4.5)</p>

Fig.1 Some applications of differential equations

# 1.1 Basic Concepts. Modeling

## ODE vs PDE



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- Differential Equation: An equation containing derivatives of an unknown function

- Ordinary Differential Equation (상미분방정식) : contains one or several derivatives of an unknown function of one independent variables (독립변수 1개)

Ex.  $y' = \cos x, \quad y'' + 9y = 0, \quad x^2 y''' + 2e^x y'' = (x^2 + 2)y^2$

- Partial Differential Equation (편미분방정식) : contains partial derivatives of an unknown function of two or more variables (독립변수 2개 이상)

Ex.  $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$

# 1.1 Basic Concepts. Modeling

## Order, Explicit vs. Implicit



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- Order: The highest derivatives of the unknown function
  - Ex. (1)  $y' = \cos x \Rightarrow$  1<sup>st</sup> Order (1계)
  - (2)  $y'' + 9y = 0 \Rightarrow$  2<sup>nd</sup> order (2계)
  - (3)  $x^2 y''' y' + 2e^x y'' = (x^2 + 2)y^2 \Rightarrow$  3<sup>rd</sup> order (3계)
- First-order ODE: Equations contain only the first derivatives  $y'$  and may contain  $y$  and any given functions of  $x$ 
  - Explicit form:  $y' = f(x, y)$
  - Implicit form:  $F(x, y, y') = 0$

# 1.1 Basic Concepts. Modeling

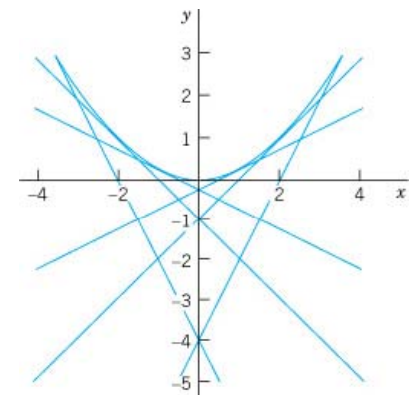
## Types of Solution



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- Solution: functions that make the equation hold true
  - General solution (일반 해): a solution that contains an arbitrary constant
  - Particular solution (특수 해): a solution in which we choose a specific constants
  - Singular solution (특이 해): an additional solution that cannot be obtained from the general solution

Ex 16) ODE  $y^2 - xy' + y = 0$ , general solution  $y = cx - c^2$   
singular solution  $y = x^2/4$ .



# 1.1 Basic Concepts. Modeling Initial Value Problem



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- Initial Value Problem
  - An ordinary differential equation together with specified value of the unknown function at a given point in the domain of the solution

$$y' = f(x, y) , \quad y(x_0) = y_0$$

# 1.1 Basic Concepts. Modeling

## Example 4.



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- Solve the initial value problem

$$y' = \frac{dy}{dx} = 3y, \quad y(0) = 5.7$$

- Step 1 Find the general solution.

$$y(x) = ce^{3x}$$

- Step 2 Apply the initial condition.

$$y(0) = ce^0 = c = 5.7$$

Particular solution :  $y(x) = 5.7e^{3x}$



# 1.1 Basic Concepts. Modeling

## Physical phenomena → Mathematical model



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- Typical steps of Modeling
    - Step 1 : The transition from the physical situation to its mathematical formulation
    - Step 2: The solution by a mathematical method
    - Step 3: The physical interpretation of differential equations and their applications

# 1.1 Basic Concepts. Modeling

## Example 5.



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- Given an amount of a radioactive substance, say 0.5 g(gram), find the amount present at any later time.
  - Physical Information: Experiments show that at each instant a radioactive substance decomposes at a rate proportional to the amount present.
  - Step 1 Setting up a mathematical model(a differential equation) of the physical process.  
By the physical law :  $\frac{dy}{dt} \propto y \Rightarrow \frac{dy}{dt} = ky$   
The initial condition :  $y(0) = 0.5$
  - Step 2 Mathematical solution.  
General solution :  $y(t) = ce^{kt}$   
Particular solution :  $y(0) = ce^0 = c = 0.5 \Rightarrow y(t) = 0.5e^{kt}$   
Always check your result :
  - Step 3 Interpretation of result.  
The limit of  $y$  as  $t \rightarrow \infty$  is zero.

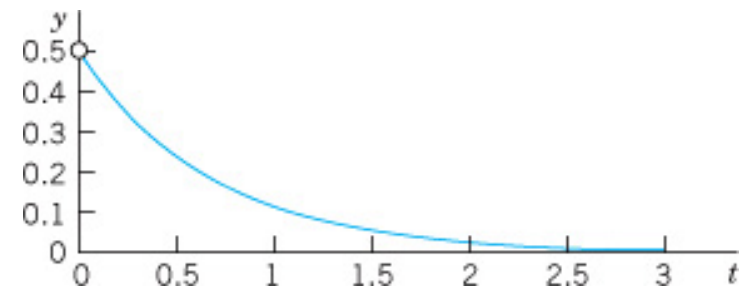


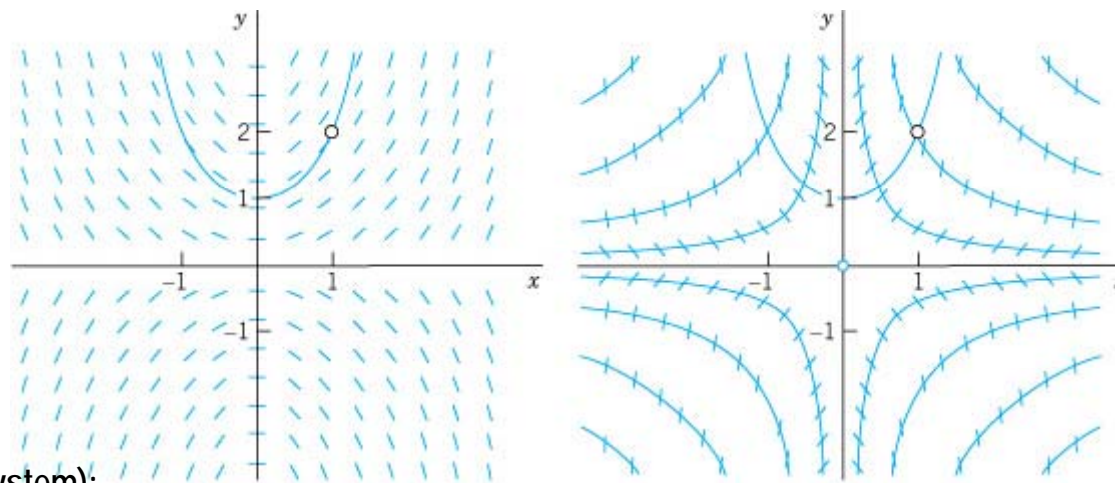
Fig.4. Radioactivity (Exponential decay,  $y = 0.5e^{kt}$ , with  $k = -1.5$  as an example



# 1.2 Geometric meaning of $y'=f(x,y)$ . Direction Fields

- Direction Field (방향장)
  - The graph with line segments (tangent line to the solution).
- Reason of importance of the direction field
  - You need not solve a ODE
  - The method shows the whole family of solutions and their typical properties.

$$y' = xy$$



(a) By a CAS

(b) By isoclines

Isoclines: curves of equal inclination

Fig. 7 Direction field of  $y' = xy$

\*CAS (Computer Algebra System):  
ex) Maple, Mathematica, Matlab

# 1.3 Separable ODEs. Modeling

## Definition



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- Separable Equation

$$g(y)y' = f(x)$$

- 왼쪽은  $y$ , 오른쪽은  $x$ 만으로 구성 가능한 형태

- Method of separation of variables (변수분리법)

$$g(y)y' = f(x) \quad \Rightarrow \quad \int g(y) dy = \int f(x) dx + c \quad \left( \because \frac{dy}{dx} dx = dy \right)$$

# 1.3 Separable ODEs. Modeling

## Example.1



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Solve  $y' = 1 + y^2$

$$\frac{y'}{1+y^2} = 1 \quad \Rightarrow \quad \frac{dy/dx}{1+y^2} = 1 \quad \Rightarrow \quad \frac{dy}{1+y^2} = dx \quad \text{(변수분리형)}$$

$$\Rightarrow \int \frac{1}{1+y^2} dy = \int dx + c \quad \Rightarrow \quad \arctan y = x + c \quad \text{(적분)}$$

$$\Rightarrow y = \tan(x + c) \quad \text{(정리)}$$

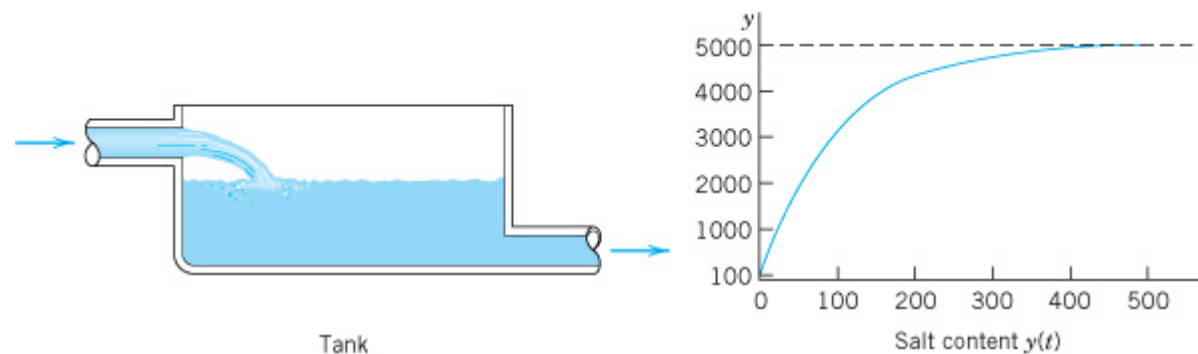
# 1.3 Separable ODEs. Modeling

## Example 3. Mixing Problem



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- Initial Condition: 1000 gal of water, 100 lb salt, initially brine runs in 10 gal/min, 5 lb/gal, stirring all the time, brine runs out at 10 gal/min
- Amount of salt at  $t$ ?
- Step1. Setting up a model
- Step2. Solution of the model





# 1.3 Separable ODEs. Modeling

## Extended Method: Reduction to Separable Form

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- When equation is not separable???
- Extended Method: Reduction to Separable Form
  - A certain 1<sup>st</sup> order equation can be made separable by a simple change of variables

$$y' = f\left(\frac{y}{x}\right) \quad \text{Ex. } \cos\left(\frac{y}{x}\right)$$

$$\left( y = ux \Rightarrow u = \frac{y}{x} \ \& \ y' = (ux)' = u'x + u \right)$$

$$y' = f\left(\frac{y}{x}\right) \Rightarrow u'x + u = f(u) \Rightarrow \frac{du}{f(u) - u} = \frac{dx}{x}$$

# 1.3 Separable ODEs. Modeling

## Example 6. Reduction to Separable form



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- 
- Example 6. Reduction to Separable Form. Solve

$$2xyy' = y^2 - x^2$$





# 1.3 Separable ODEs. Modeling

## Example 6. Reduction to Separable form

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- Example 6. Reduction to Separable Form. Solve

$$2xyy' = y^2 - x^2$$

$$2xyy' = y^2 - x^2 \Rightarrow y' = \frac{1}{2} \left( \frac{y}{x} - \frac{x}{y} \right) \quad (2xy \text{로 나눔})$$

$$\Rightarrow y = ux, \quad u = \frac{y}{x}, \quad y' = u'x + u = \frac{1}{2} \left( u - \frac{1}{u} \right)$$

$$u'x = -\frac{1}{2} \left( u + \frac{1}{u} \right) = -\frac{u^2 + 1}{2u} \Rightarrow \frac{du}{dx} \frac{2u}{u^2 + 1} = -\frac{1}{x} \Rightarrow \frac{2u}{u^2 + 1} du = -\frac{1}{x} dx$$

$$\int \frac{2u}{u^2 + 1} du = -\int \frac{1}{x} dx + c^* \Rightarrow \ln|u^2 + 1| = -\ln|x| + c^* = \ln \frac{1}{|x|} + \ln|c| = \ln \left| \frac{c}{x} \right|, \quad c = e^{c^*}$$

$$u^2 + 1 = \frac{c}{x} \Rightarrow \left( \frac{y}{x} \right)^2 + 1 = \frac{c}{x} \Rightarrow x^2 + y^2 = cx$$

$$\left( x - \frac{c}{2} \right)^2 + y^2 = \frac{c^2}{4}$$

# 1. 4 Exact ODEs. Integrating Factors

## Basic Ideas



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For  $u(x, y)$ , its differential (미분) is

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy$$

if  $u(x, y) = c$ , then  $du = 0$

For example, if  $u = x + x^2 y^3 = c$

$$du = (1 + 2xy^3)dx + (3x^2 y^2)dy = 0$$

$$\text{or } y' = \frac{dy}{dx} = -\frac{1 + 2xy^3}{3x^2 y^2}$$

# 1. 4 Exact ODEs. Integrating Factors

## Definition



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- Exact Differential Equation (완전 미분방정식) :

$$M(x, y)dx + N(x, y)dy = 0$$

- If the differential form  $M(x, y)dx + N(x, y)dy$  is exact
- This means that this form is the differential of  $u(x, y)$

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy \quad \Rightarrow \quad du = 0 \quad \Rightarrow \quad u(x, y) = c$$

- Condition for exactness

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \quad \left( \because \frac{\partial M}{\partial y} = \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} \right) = \frac{\partial^2 u}{\partial x \partial y} = \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial y} \right) = \frac{\partial N}{\partial x} \right)$$

# 1. 4 Exact ODEs. Integrating Factors Solution method



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- Solution method of exact differential equation  
(완전미분방정식 해법) :

$$M(x, y)dx + N(x, y)dy = \frac{\partial u}{\partial x}dx + \frac{\partial u}{\partial y}dy = 0$$

Case 1)

$$M(x, y) = \frac{\partial u}{\partial x} \Rightarrow \underline{u(x, y) = \int M(x, y)dx + k(y)}$$

$$\Rightarrow \frac{\partial u}{\partial y} = N(x, y) \Rightarrow \frac{dk}{dy} \text{ \& } k(y)$$

Case 2)

$$N(x, y) = \frac{\partial u}{\partial y} \Rightarrow \underline{u(x, y) = \int N(x, y)dy + l(x)}$$

$$\Rightarrow \frac{\partial u}{\partial x} = M(x, y) \Rightarrow \frac{dl}{dx} \text{ \& } l(x)$$

# 1. 4 Exact ODEs. Integrating Factors

## Example 1.



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• Solve  $\cos(x + y) dx + (3y^2 + 2y + \cos(x + y)) dy = 0$

– Step 1 Test for exactness.  $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$

$$M(x, y) = \cos(x + y) \Rightarrow \frac{\partial M}{\partial y} = -\sin(x + y)$$

$$N(x, y) = 3y^2 + 2y + \cos(x + y) \Rightarrow \frac{\partial N}{\partial x} = -\sin(x + y)$$

– Step 2 Implicit general solution.

$$u(x, y) = \int M(x, y) dx + k(y) = \int \cos(x + y) dx + k(y) = \sin(x + y) + k(y)$$

$$\Rightarrow \frac{\partial u}{\partial y} = \cos(x + y) + \frac{dk}{dy} = N(x, y) \Rightarrow \frac{dk}{dy} = 3y^2 + 2y \Rightarrow k = y^3 + y^2 + c^*$$

$$\therefore u(x, y) = \sin(x + y) + y^3 + y^2 = c$$

– Step 3 Checking an implicit solution.



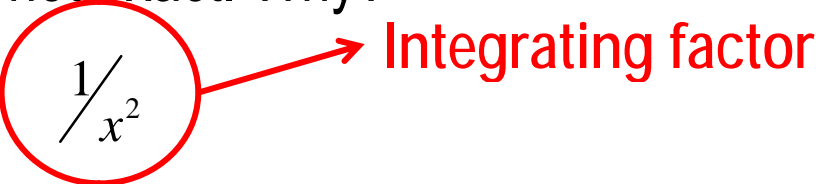
# 1. 4 Exact ODEs. Integrating Factors

## Integrating Factors

- Reduction to Exact Form, Integrating Factors
  - Some equations can be made exact by multiplication by some function (called the Integrating Factor, 적분인자)

- Ex 3.  $-ydx + xdy = 0$

- This equation is not exact. Why?

- multiplying it by  $\frac{1}{x^2}$   **Integrating factor**

$$-\frac{y}{x^2}dx + \frac{1}{x}dy = 0 \left( \because \frac{\partial}{\partial y} \left( -\frac{y}{x^2} \right) = -\frac{1}{x^2} = \frac{\partial}{\partial x} \left( \frac{1}{x} \right) \right)$$

- Issue is then how to find this integrating factor (when it is not simple)?



# 1. 4 Exact ODEs. Integrating Factors

## Integrating Factors

- Given a nonexact equation

$$Pdx + Qdy = 0$$

- Finding Integrating Factors (F)

$$FPdx + FQdy = 0$$

- The exactness condition

$$\frac{\partial}{\partial y}(FP) = \frac{\partial}{\partial x}(FQ) \quad \Rightarrow \quad \frac{\partial F}{\partial y}P + F\frac{\partial P}{\partial y} = \frac{\partial F}{\partial x}P + F\frac{\partial Q}{\partial x}$$

# 1. 4 Exact ODEs. Integrating Factors

## Integrating Factors



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- Golden Rule: Solve a simpler one. Hence we look for an integrating factor depending *only* on one variable.

$$F = F(x) \quad \Rightarrow \quad \frac{\partial F}{\partial x} = F', \quad \frac{\partial F}{\partial y} = 0$$

$$FP_y = F'Q + FQ_x \quad \Rightarrow \quad \frac{1}{F} \frac{dF}{dx} = R(x) \quad \text{where} \quad R(x) = \frac{1}{Q} \left( \frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right)$$

$$\Rightarrow \quad \therefore F(x) = \exp\left(\int R(x) dx\right)$$

$$F^* = F^*(y) \quad \Rightarrow \quad \frac{1}{F^*} \frac{dF^*}{dy} = R^* \quad \text{where} \quad R^* = \frac{1}{P} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \quad \Rightarrow \quad F^*(y) = \exp\left(\int R^*(y) dy\right)$$



# 1. 4 Exact ODEs. Integrating Factors

## Integrating Factors



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### Integrating Factor $F(x)$

If (12) is such that the right side  $R$  of (16), depends only on  $x$ , then (12) has an integrating factor  $F = F(x)$ , which is obtained by integrating (16) and taking exponents on both sides,

(17)

$$F(x) = \exp \int R(x) dx.$$

$$R(x) = \frac{1}{Q} \left( \frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right)$$

### Integrating Factor $F^*(y)$

If (12) is such that the right side  $R^*$  of (18) depends only on  $y$ , then (12) has an integrating factor  $F^* = F^*(y)$ , which is obtained from (18) in the form

(19)

$$F^*(y) = \exp \int R^*(y) dy.$$

$$R^* = \frac{1}{P} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$$

# 1. 4 Exact ODEs. Integrating Factors

## Integrating Factors



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- Integrating factor for Exact Differential Equation???

$$F(x) = \exp\left(\int R(x) dx\right)$$

$$R(x) = \frac{1}{Q} \left( \frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right)$$

$$F^*(y) = \exp\left(\int R^*(y) dy\right)$$

$$R^* = \frac{1}{P} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right)$$



# 1. 4 Exact ODEs. Integrating Factors

## Example 5 - Integrating Factors

- EX. 5 Find Integrating Factor and solve the following initial value problem

$$\left( e^{x+y} + ye^y \right) dx + \left( xe^y - 1 \right) dy = 0, \quad y(0) = -1$$

- Step 1. Nonexactness
- Step 2. Integrating factor. General Solution
- Step 3. Particular Solution

# 1. 4 Exact ODEs. Integrating Factors

## Example 5 - Integrating Factors



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$$(e^{x+y} + ye^y)dx + (xe^y - 1)dy = 0, \quad y(0) = -1$$

– Step 1. Nonexactness

$$P(x, y) = e^{x+y} + ye^y \Rightarrow \frac{\partial P}{\partial y} = e^{x+y} + e^y + ye^y$$

$$Q(x, y) = xe^y - 1 \Rightarrow \frac{\partial Q}{\partial x} = e^y$$

$$\frac{\partial P}{\partial y} \neq \frac{\partial Q}{\partial x}$$

– Step 2.

$$R = \frac{1}{Q} \left( \frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) = \frac{1}{xe^y - 1} (e^{x+y} + e^y + ye^y - e^y) = \frac{1}{xe^y - 1} (e^{x+y} + ye^y) \Rightarrow \text{fails}$$

$$R^* = \frac{1}{P} \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) = \frac{1}{e^{x+y} + ye^y} (e^y - e^{x+y} - e^y - ye^y) = -1 \Rightarrow F^*(y) = e^{-y}$$

$$\therefore (e^x + y)dx + (x - e^{-y})dy = 0$$

$$u = \int (e^x + y)dx = e^x + xy + k(y) \Rightarrow \frac{\partial u}{\partial y} = x + k'(y) = x - e^{-y} \Rightarrow k'(y) = -e^{-y}, \quad k(y) = e^{-y}$$

$$u(x, y) = e^x + xy + e^{-y} = c$$

– Step 3. Particular Solution

$$y(0) = -1 \Rightarrow u(0, -1) = e^0 + 0 + e = 3.72 \quad \therefore u(x, y) = e^x + xy + e^{-y} = 3.72$$

# Last Lecture



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- Exact differential equation

$$M(x, y)dx + N(x, y)dy = 0$$

$$\leftarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$M(x, y) = \frac{\partial u}{\partial x} \Rightarrow u(x, y) = \int M(x, y)dx + k(y) \Rightarrow \frac{\partial u}{\partial y} = N(x, y) \Rightarrow \frac{dk}{dy} \text{ \& } k(y)$$

- Non exact differential equation (finding integrating factors)

$$Pdx + Qdy = 0$$

$$FPdx + FQdy = 0$$

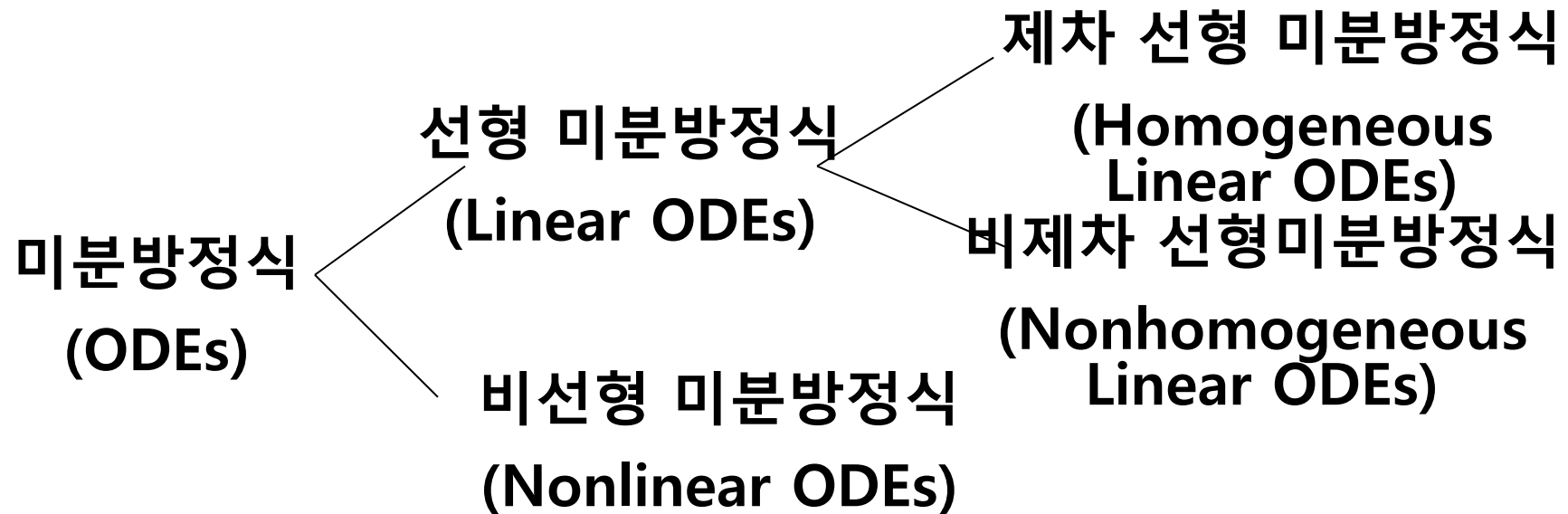
$$F(x) = \exp\left(\int R(x)dx\right), \text{ where } R(x) = \frac{1}{Q}\left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x}\right)$$

# 1.5 Linear ODEs

## Introduction



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Linear ODE (선형미분방정식): 종속변수와 그 도함수가 모두 1차인 미분방정식. 각 계수는 독립변수에만 의존



# 1.5 Linear ODEs

## Definition and Standard Form

- Linear ODEs are models of various phenomena
- Linear ODEs: linear in both the unknown function and its derivatives.  $p(x)$  and  $r(x)$  can be any given functions of  $x$ .

– ex)  $y' + p(x)y = r(x)$   $\longrightarrow$  Standard Form  
(start with  $y'$ )

$$y' \cos x + y \sin x = x$$

↗ Homogeneous Linear ODEs ( $r(x)$  is zero for all  $x$ )  $r(x) \equiv 0$

ex)  $y' + p(x)y = 0$

↗ Nonhomogeneous Linear ODEs

ex)  $y' + p(x)y = r(x) \neq 0$

- Nonlinear ODEs = Not linear ODEs.

Ex)  $y' + p(x)y = r(x)y^2$

# 1.5 Linear ODEs

## Solution method



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- 
- Homogeneous Linear ODE.(Apply the method of separating variables)

$$y' + p(x)y = 0$$

- Nonhomogeneous Linear ODE.(Find integrating factor and solve )

$$y' + p(x)y = r(x)$$



# 1.5 Linear ODEs

## Solution method



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- Homogeneous Linear ODE.(Apply the method of separating variables)

$$y' + p(x)y = 0 \quad \Rightarrow \quad \frac{dy}{y} = -p(x)dx \quad \Rightarrow \quad \ln|y| = -\int p(x)dx + c^*$$

$$y = ce^{-\int p(x)dx}$$

When  $c=0 \rightarrow$  trivial solution (자명해)

- Nonhomogeneous Linear ODE.(Find integrating factor and solve )

$$y' + p(x)y = r(x) \quad \Rightarrow \quad (py - r)dx + dy = 0 \quad \text{Not exact!} \quad \left( \because \frac{\partial}{\partial y}(py - r) = p \neq 0 = \frac{\partial}{\partial x}(1) \right)$$

$$R = \frac{1}{Q} \left( \frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right) = p \quad \Rightarrow \quad \frac{1}{F} \frac{dF}{dx} = p \quad \Rightarrow \quad \therefore F = e^{\int p dx}$$

$$e^{\int p dx} (py - r)dx + e^{\int p dx} dy = 0$$

$$u = ye^{\int p dx} + l(x) \quad \Rightarrow \quad \frac{\partial u}{\partial x} = pye^{\int p dx} + l'(x) = e^{\int p dx} (py - r) \quad \Rightarrow \quad l'(x) = -re^{\int p dx}, \quad l(x) = -\int re^{\int p dx} dx + c$$

$$\Rightarrow \quad u = ye^{\int p dx} - \int re^{\int p dx} dx = c \quad \Rightarrow \quad ye^{\int p dx} = \int re^{\int p dx} dx + c$$

$$y = e^{-\int p dx} \left[ \int re^{\int p dx} dx + c \right]$$

# 1.5 Linear ODEs.

## Example 1. Linear ODE



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- EX.1 solve the linear ODE  $y' - y = e^{2x}$

$$p = -1, \quad r = e^{2x}, \quad h = \int p dx = -x \quad \Rightarrow$$

$$\therefore y = e^{-h} \left[ \int e^h r dx + c \right] = e^x \left[ \int e^{-x} e^{2x} dx + c \right] = e^x \left[ e^x + c \right] = e^{2x} + ce^x$$

# 1.5 Linear ODEs.

## Example 2. Linear ODE



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- 
- Example 2)

$$y' + y \tan x = \sin 2x \quad y(0) = 1$$

# 1.5 Linear ODEs. Bernoulli Equation



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- Bernoulli Equation (nonlinear  $\rightarrow$  linear)

$$y' + p(x)y = g(x)y^a \quad (a \neq 0 \ \& \ a \neq 1)$$

$$u(x) = [y(x)]^{1-a}$$

$$\Rightarrow u' = (1-a)y^{-a}y' = (1-a)y^{-a}(gy^a - py) = (1-a)(g - py^{1-a}) = (1-a)(g - pu)$$

$$\Rightarrow u' + (1-a)pu = (1-a)g$$

# 1.5 Linear ODEs.

## Bernoulli Equation (Logistic Equation)

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- Ex. 4 Logistic Equation  $y' = Ay - By^2$

# 1. 6 Orthogonal Trajectories (직교궤적)



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- Orthogonal (직교의) ~ perpendicular
- Orthogonal Trajectory:
  - A family of curves in the plane that intersect a given family of curves at right angles.
- Find the orthogonal trajectories by using ODEs.
  - Step 1 Find an ODE  $y' = f(x, y)$  for which the give family is a general solution.
  - Step 2 Write down the ODE  $\tilde{y}' = -\frac{1}{f(x, \tilde{y})}$  of the orthogonal trajectories.
  - Step 3 Solve it.

# 1. 6 Orthogonal Trajectories. Example



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- Example. A one-parameter family of quadratic parabolas is given by

$$y = cx^2$$

- Step 1 find an ODE

$$\frac{y}{x^2} = c \quad \Rightarrow \quad \frac{y'x^2 - 2xy}{x^4} = 0 \quad \Rightarrow \quad y' = \frac{2y}{x}$$

- Step 2 Write down the ODE of the orthogonal trajectories

$$\tilde{y}' = -\frac{x}{2\tilde{y}}$$

- Step 3 solve above ODE

$$2\tilde{y}\tilde{y}' + x = 0 \quad \Rightarrow \quad \tilde{y}^2 + \frac{1}{2}x^2 = c^*$$

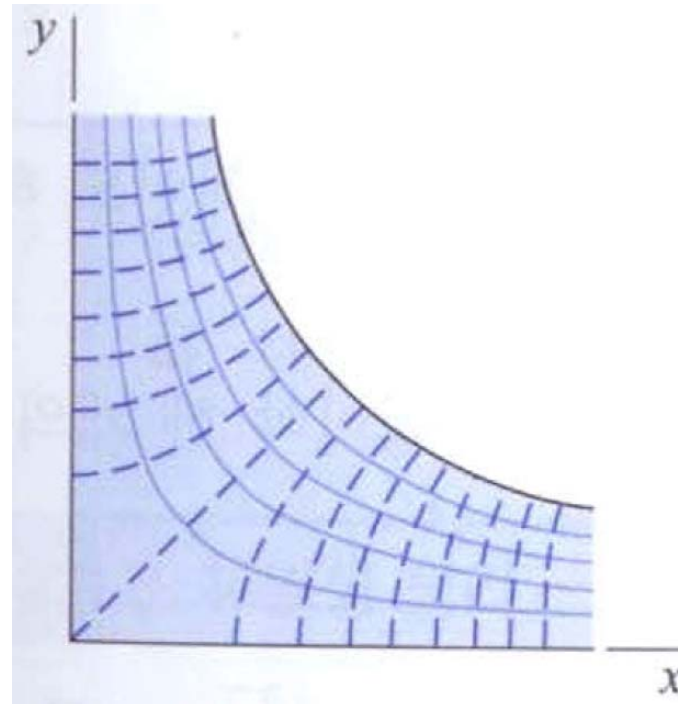
# 1. 6 Orthogonal Trajectories.

## Example – Problem set 1.6 – 16.



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- Streamlines and equipotential lines



Flow in a channel



# 1.7 Existence and Uniqueness of Solutions



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- An initial value problem may have no solution, precisely one solution, or more than one solution

$$|y'| + |y| = 0, \quad y(0) = 1 \quad \Rightarrow \quad \text{No solution}$$

$$y' = 2x, \quad y(0) = 1 \quad \Rightarrow \quad \text{Precisely one solution} \quad \Rightarrow \quad y = x^2 + 1$$

$$xy' = y - 1, \quad y(0) = 1 \quad \Rightarrow \quad \text{Infinitely many solutions} \quad \Rightarrow \quad y = 1 + cx$$

- Problem of Existence
  - Under what conditions does an initial value problem have at least one solution (hence one or several solutions)?
- Problem of Uniqueness
  - Under what conditions does that problem have at most one solution (hence excluding the case that it has more than one solution)?

# 1.7 Existence and Uniqueness of Solutions



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## ● Theorem 1 Existence Theorem

Let the right side  $f(x,y)$  of the ODE in the initial value problem

$$(1) \quad y' = f(x, y), \quad y(x_0) = y_0$$

be continuous at all points  $(x,y)$  in some rectangle

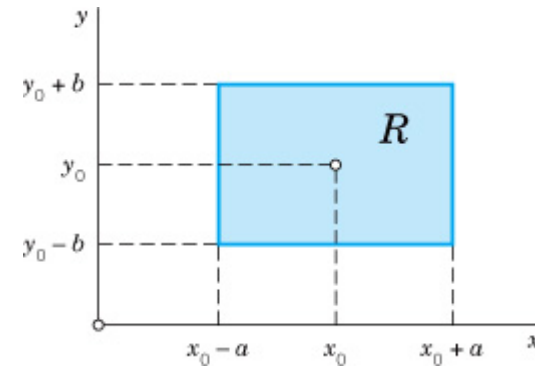
$$R : |x - x_0| < a, \quad |y - y_0| < b$$

and bounded in  $R$ ; that is, there is a number  $K$  such that

$$(2) \quad |f(x, y)| \leq K \quad \text{for all } (x,y) \text{ in } R.$$

Then the initial value problem (1) has at least one solution  $y(x)$ . This solution exists at least for

all  $x$  in the subinterval  $|x - x_0| < \alpha$  of the interval  $|x - x_0| < a$ ; here,  $\alpha$  is the smaller of the two numbers  $a$  and  $b/K$ .



# 1.7 Existence and Uniqueness of Solutions



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## ● Theorem 2 Uniqueness Theorem

Let  $f$  and its partial derivative  $f_y = \partial f / \partial y$  be continuous for all  $(x, y)$  in the rectangle  $R$  and bounded, say,

$$(3) \quad (a) \quad |f(x, y)| \leq K \quad (b) \quad |f_y(x, y)| \leq M \text{ for all } (x, y) \text{ in } R.$$

Then the initial value problem (1) has at most one solution  $y(x)$ . Thus, by the Existence Theorem, the problem has precisely one solution. This solution exists at least for all  $x$  in that subinterval

$$|x - x_0| < \alpha$$

# 1. First-Order ODEs Summary (1)



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- 
- Differential Equation?
    - ODE vs. PDE,
    - 1<sup>st</sup> order, 2<sup>nd</sup> order, ...
    - linear vs. nonlinear
  - Physical behavior → mathematical model and solution
  - Solution method
    - Separation of variables & Reduction to separable form
    - Exact differential Equation & Integrating Factors
    - Linear ODEs & Bernoulli Eq (nonlinear)

# 1. First-Order ODEs Summary (2)



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- Separation of variables & Reduction to separable form

- Separation of variables

$$g(y)y' = f(x)$$

$$g(y)y' = f(x) \quad \Rightarrow \quad \int g(y) dy = \int f(x) dx + c$$

- Extended Method: Reduction to separable form

$$y' = f\left(\frac{y}{x}\right)$$

$$y' = f\left(\frac{y}{x}\right) \Rightarrow u'x + u = f(u) \Rightarrow \frac{du}{f(u) - u} = \frac{dx}{x}$$

# 1. First-Order ODEs Summary (3)



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- Exact differential equation

$$M(x, y)dx + N(x, y)dy = 0 \quad \leftarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$M(x, y) = \frac{\partial u}{\partial x} \quad \Rightarrow \quad u(x, y) = \int M(x, y)dx + k(y) \quad \Rightarrow \quad \frac{\partial u}{\partial y} = N(x, y) \quad \Rightarrow \quad \frac{dk}{dy} = N(x, y) \quad \& \quad k(y)$$

- Non exact differential equation (finding integrating factors)

$$Pdx + Qdy = 0 \quad \quad FPdx + FQdy = 0$$

$$F(x) = \exp\left(\int R(x)dx\right), \text{ where } R(x) = \frac{1}{Q}\left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x}\right)$$

# 1. First-Order ODEs Summary (4)



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- Linear ODEs  $y' + p(x)y = r(x)$

- Homogeneous ODEs

$$y' + p(x)y = 0 \quad \Rightarrow \quad y = ce^{-\int p(x)dx}$$

- Nonhomogeneous ODEs

$$y' + p(x)y = r(x) \quad \Rightarrow \quad (py - r)dx + dy = 0$$
$$y = e^{-h} \left[ \int e^h r dx + c \right], \text{ where } h = \int p dx$$

- Bernoulli Equation (reduction to linear ODEs)

$$y' + p(x)y = g(x)y^a \quad (a \neq 0 \ \& \ a \neq 1)$$

$$u' + (1-a)pu = (1-a)g \quad \leftarrow \quad u(x) = [y(x)]^{1-a}$$

# Acknowledgement and References



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- All the figures and problems sets are from the following book unless otherwise stated.
    - Erwin Kreyszig, 2006, Advanced Engineering Mathematics, 9th Ed., Wiley