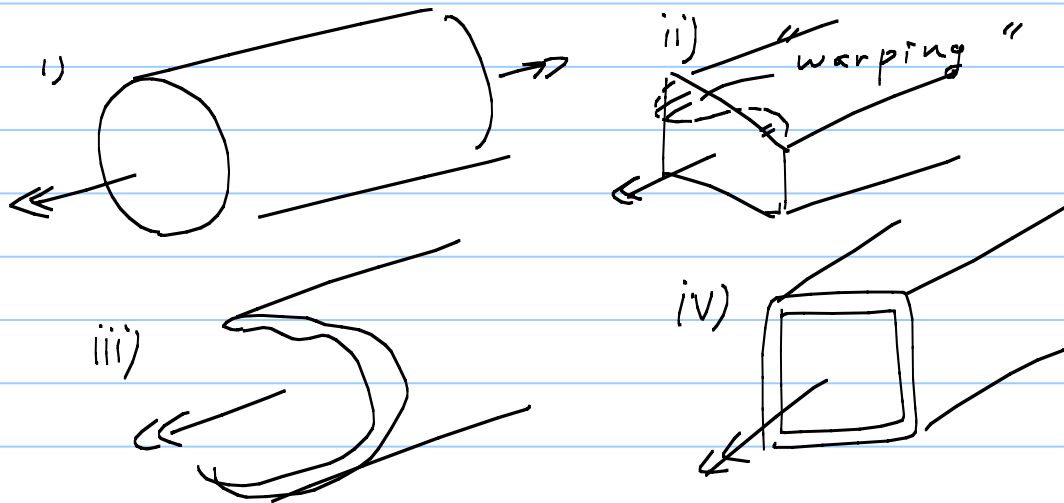


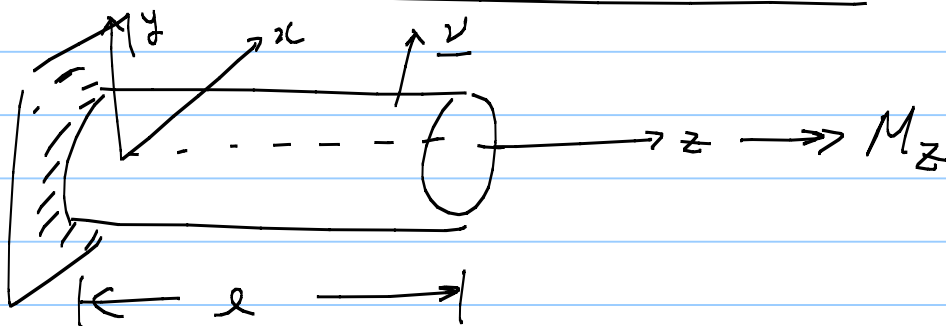
# Lecture 3-1

## < Torsion in a shaft >

노트 제목



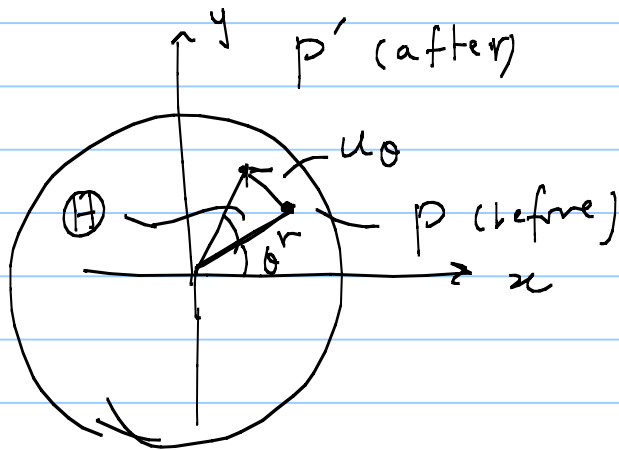
## < Torsion in a circular shaft >



### Under torsion

- i) cross-section remain circular
  - ii) no warping
- $\Rightarrow$  i, ii) due to circular symmetry  
(see strength of Materials books)

□ look at the cross section



$$\begin{cases} u_r = 0 \\ u_z = 0 \\ u_\theta = r \textcircled{+} \\ = r(\alpha z) \\ = \alpha r z \end{cases}$$

twist rate  
(twist angle / length)

In Cartesian coordinates

$$\begin{cases} u_x = -u_\theta \sin \theta = -\alpha z r \sin \theta \\ = -\alpha z y \\ u_y = u_\theta \cos \theta = \alpha z x \end{cases}$$

• Stresses

1) polar coordinates

$$\sigma_{\theta z} = \mu \left( \frac{1}{r} \frac{\partial u_z}{\partial \theta} + \frac{\partial u_\theta}{\partial z} \right) = \mu \alpha r$$

$$\sigma_{\theta\theta} = \sigma_{rr} = \sigma_{zz} = \sigma_{rz} = \sigma_{r\theta} = 0$$

2) Cartesian coordinates

$$\sigma_{zx} = -\mu \alpha y ; \sigma_{zy} = \mu \alpha x$$

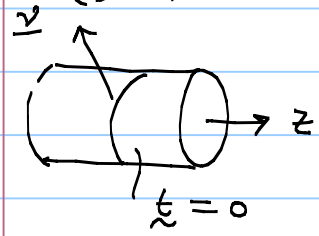
(other  $\sigma_{ij} = 0$ )

<check>

① satisfy eqm?

$$\begin{cases} \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xy}}{\partial y} + \frac{\partial \sigma_{xz}}{\partial z} = 0 \\ \frac{\partial \sigma_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \sigma_{yz}}{\partial z} = 0 \\ \frac{\partial \sigma_{xz}}{\partial x} + \frac{\partial \sigma_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} = 0 \end{cases}$$

② traction bc's (on C)



$$\begin{aligned} \underline{v} &= \underline{e}_r ; \underline{t} = \underline{v} \cdot \underline{\sigma} \\ &= \sigma_{rr} \underline{e}_r + \sigma_{r\theta} \underline{e}_\theta + \sigma_{rz} \underline{e}_z \\ &\equiv 0 \end{aligned}$$

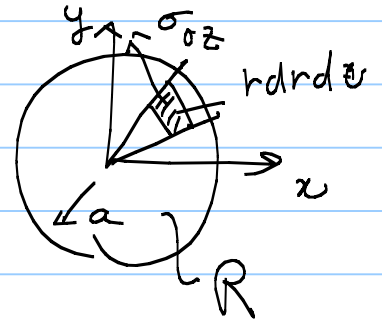
- Applied Moment = Moment by internal stress

$$M_z = \int_R (\sigma_{\theta z} r dr d\theta) \times r$$

$$= \int_R \mu \alpha r^2 (r dr d\theta)$$

$$= \mu \alpha \int_R r^2 dA = \mu \alpha I_{zz}$$

$\uparrow$  polar moment of inertia



( for circular section:

$$I_{zz} = \int_R r^2 dA = \int_0^{2\pi} \int_0^a r^2 r dr d\theta$$

$$= \frac{\pi}{2} a^4$$

)

Define "torsional rigidity  $C_t$ ":

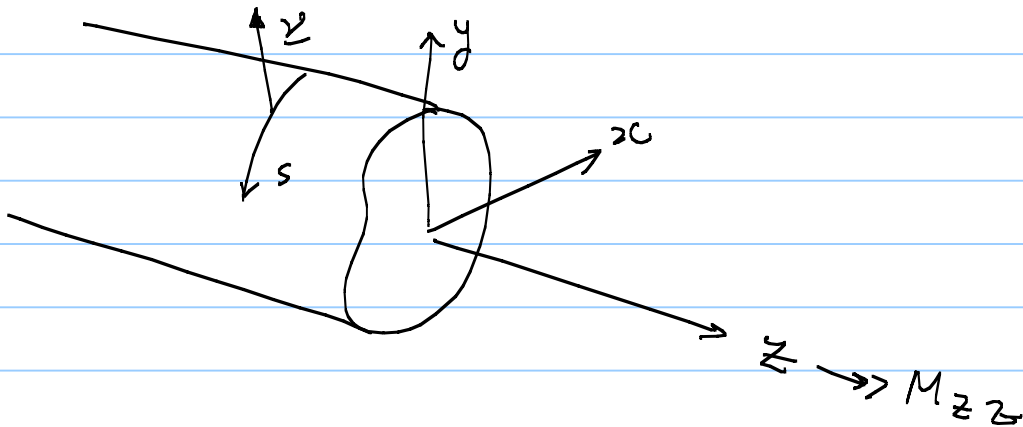
$$\underline{M_z = C_t \cdot \alpha}$$

In circular section:

$$C_t = \mu I_{zz} = \frac{\pi \mu a^4}{2} \approx 0.159 \mu A^2$$

( $A = \pi a^2$ )

## Torsion in non circular shafts



\* non-circular section; no circular symmetry  
 $\Rightarrow$  warping can take place  
 (i.e.,  $u_z \neq 0$ )

As before  $\begin{cases} u_\theta = r \oplus = r \alpha z \\ u_r = 0 \end{cases}$

$$\Rightarrow \begin{aligned} u_x &= -\alpha z y \\ u_y &= +\alpha z x \end{aligned}$$

$$\oplus u_z = \alpha \phi(x, y) \leftarrow \text{unknown fun } \phi \text{ of } \\ \text{not } \phi(x, y, z) \quad \text{"Warping fun"}$$

$\Rightarrow$  To find governing eq. for  $\phi(x, y)$ ,  
 consider eqm. equation.

So, stress calculation:

$$(A) \left\{ \begin{aligned} \sigma_{zx} &= \mu \left( \frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right) \\ &= \mu \alpha \left( \frac{\partial \phi}{\partial x} - y \right) \\ \sigma_{zy} &= \mu \left( \frac{\partial u_z}{\partial y} + \frac{\partial u_y}{\partial z} \right) \\ &= \mu \alpha \left( \frac{\partial \phi}{\partial y} + x \right) \end{aligned} \right.$$

Other  $\sigma_{ij} = 0$

Check 1) Eqm

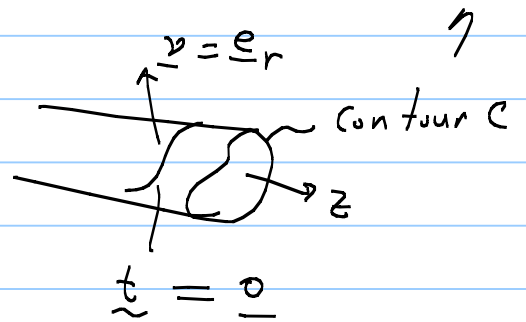
$$\frac{\partial \sigma_{zx}}{\partial x} + \frac{\partial \sigma_{zy}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} = 0$$

$$(A) \Rightarrow \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 ; \quad \boxed{\nabla^2 \phi(x, y) = 0} \quad (1)$$

Laplace's equation

check 2) traction BC's  
on C

$$\underline{t}_z = \sigma_{rz} \underline{e}_r + \sigma_{\theta z} \underline{e}_\theta + \underbrace{\sigma_{zz}}_{t_z} \underline{e}_z \equiv \underline{0}$$



$$\begin{aligned} t_z &= \underline{v} \cdot \underline{\sigma} \cdot \underline{e}_z \\ &= (v_x \underline{e}_x + v_y \underline{e}_y) \cdot (\sigma_{xz} \underline{e}_x + \sigma_{yz} \underline{e}_y) \\ &= \sigma_{xz} v_x + \sigma_{yz} v_y \\ &= \mu \alpha \left[ \left( \frac{\partial \phi}{\partial x} - y \right) v_x + \left( \frac{\partial \phi}{\partial y} + x \right) v_y \right] = 0 \end{aligned}$$

$$\therefore \frac{\partial \phi}{\partial x} v_x + \frac{\partial \phi}{\partial y} v_y = y v_x - x v_y$$

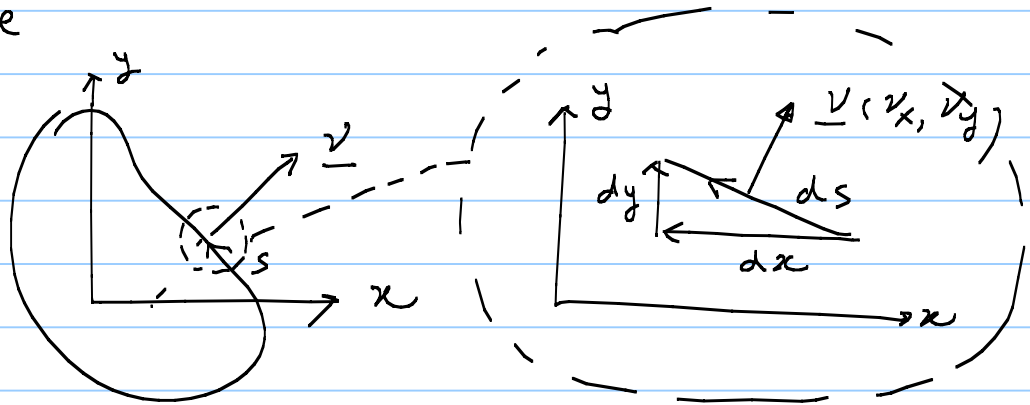
OR

$$\boxed{\underline{\nabla} \phi \cdot \underline{v} = \frac{d\phi}{ds} = y v_x - x v_y \text{ on } C}$$

②

①, ② ; Neumann-type BVP  
(cf: Dirichlet-type BVP)

Note



$$v_x = \frac{dy}{ds}, \quad v_y = -\frac{dx}{ds}$$

Then

$$\begin{aligned} \text{RHS of (2)} &= y v_x - x v_y \\ &= y \frac{dy}{ds} + x \frac{dx}{ds} \\ &= \frac{1}{2} \frac{d}{ds} (x^2 + y^2) \end{aligned}$$

Because

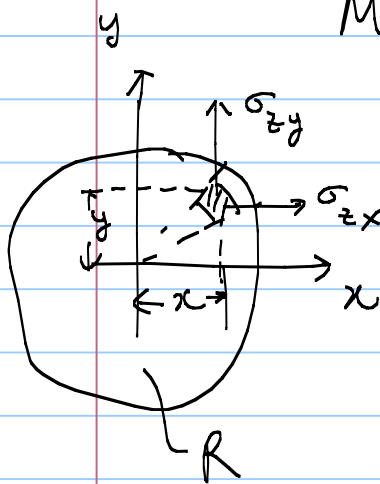
$$\oint_C (y v_x - x v_y) ds = \oint_C \frac{1}{2} \frac{d}{ds} (x^2 + y^2) ds = 0,$$

$$\oint_C \frac{d\phi}{ds} ds \equiv 0 \leftarrow \text{"Condition satisfied for Neumann-type problems"}$$



To calculate  $C_t = M_z / \alpha$ ,

determine  $M_z$  by



$$\begin{aligned}
 M_z &= \int_R (x \sigma_{yz} - y \sigma_{xz}) dA \\
 &= \mu \alpha \int_R \left[ x \left( \frac{\partial \phi}{\partial y} + x \right) - y \left( \frac{\partial \phi}{\partial x} - y \right) \right] dA \\
 &= \mu \alpha \int_R \left( x^2 + y^2 + x \frac{\partial \phi}{\partial y} - y \frac{\partial \phi}{\partial x} \right) dA
 \end{aligned}$$

check:

$$\begin{aligned}
 C_t &= \mu \int_R (x^2 + y^2) dA \\
 &\quad - \mu \int_A \left[ \left( \frac{\partial \phi}{\partial x} \right)^2 + \left( \frac{\partial \phi}{\partial y} \right)^2 \right] dA \\
 &\leq \mu \int_R (x^2 + y^2) dA = \mu I_{zz}
 \end{aligned}$$

physics: Due to warping,  $C_t$  decreases.

## < Prandtl Stress Function Formulation >

- Prandtl started with eqm equation and used the above result

→ what's advantage? "Membrane Analogy"

↓  
easier analysis  
& experiment

1) • Eqm Eq

$$\bullet \frac{\partial \sigma_{zx}}{\partial x} + \frac{\partial \sigma_{zy}}{\partial y} = 0 \quad (\text{non-trivial eqm})$$

$$\bullet \text{Choose } \left\{ \begin{array}{l} \sigma_{zx} = \mu \alpha \frac{\partial \psi}{\partial y} \\ \sigma_{zy} = -\mu \alpha \frac{\partial \psi}{\partial x} \end{array} \right\} \quad (A)$$

- Use displacement-based result

$$\left\{ \begin{array}{l} \sigma_{zx} = \mu \alpha \left( \frac{\partial \phi}{\partial x} - y \right) \\ \sigma_{zy} = \mu \alpha \left( \frac{\partial \phi}{\partial y} + x \right) \end{array} \right\} \quad (B)$$

(A)  $\equiv$  (B) (meaning? "compatibility")

$$\frac{\partial \psi}{\partial y} = \frac{\partial \phi}{\partial x} - y ; \quad -\frac{\partial \psi}{\partial x} = \frac{\partial \phi}{\partial y} + x \quad (a, b)$$

//

Eliminate  $\phi$  from (a, b)

$$\rightarrow \frac{\partial}{\partial y} (a) - \frac{\partial}{\partial x} (b)$$

$$\boxed{\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = -2} \quad (1)$$

2) BC's on C

$$t_z = \sigma_{zx} v_x + \sigma_{zy} v_y$$



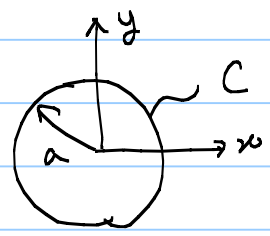
$$= \mu \alpha \left[ \frac{\partial \psi}{\partial y} \frac{dy}{ds} + \left( -\frac{\partial \psi}{\partial x} \right) \left( -\frac{dx}{ds} \right) \right]$$

$$= \mu \alpha \frac{d\psi}{ds} \equiv 0$$

$$\Rightarrow \psi = k \text{ (constant) on } C$$

$$\Rightarrow \boxed{\psi = 0 \text{ on } C} \quad (\sigma \sim \text{derivative of } \psi) \dots (2)$$

(1), (2) : Dirichlet-type problem



Circular section  
 $C: x^2 + y^2 - a^2 = 0,$

Try  $\psi = c_1 (x^2 + y^2 - a^2)$

→ satisfies ②

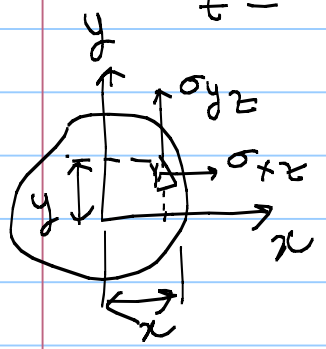
→ satisfies ① if  $c_1 = -\frac{1}{2}$

$$\therefore \boxed{\psi = -\frac{1}{2} (x^2 + y^2 - a^2)}$$

↳ exact sol. for circular sections

Torsional Rigidity  $C_t$  in terms of  $\psi$

$$C_t = M_z / \alpha = \left[ \int_R (x \sigma_{yz} - y \sigma_{xz}) dA \right] / \alpha$$



$$= -\mu \int_R \left[ x \frac{\partial \psi}{\partial x} + y \frac{\partial \psi}{\partial y} \right] dA$$

$$= -\mu \left[ \int_R \left[ \frac{\partial}{\partial x} (x \psi) + \frac{\partial}{\partial y} (y \psi) - 2\psi \right] dA \right]$$

$$= -\mu \int_R \left[ \frac{\partial}{\partial x} (x\psi) + \frac{\partial}{\partial y} (y\psi) \right] dA$$

$$+ 2\mu \int_R \psi dA$$

Check:  $\int_R \left[ \frac{\partial}{\partial x} (x\psi) + \frac{\partial}{\partial y} (y\psi) \right] dA$

$\underbrace{\hspace{10em}}_{\equiv \nabla \cdot (x\psi, y\psi)}$

Div. Th.  $\Rightarrow \oint_C \nabla \cdot (x\psi, y\psi) dA$

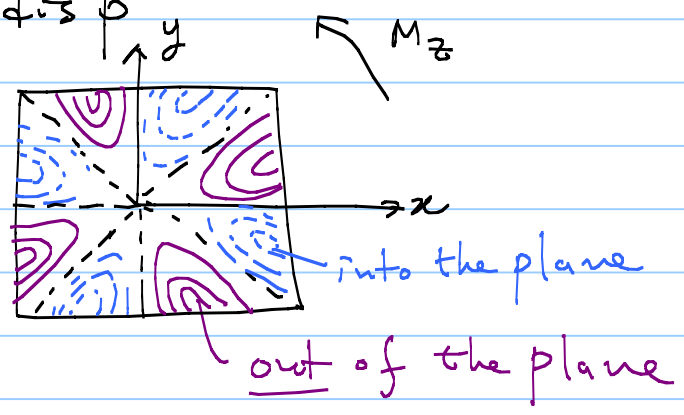
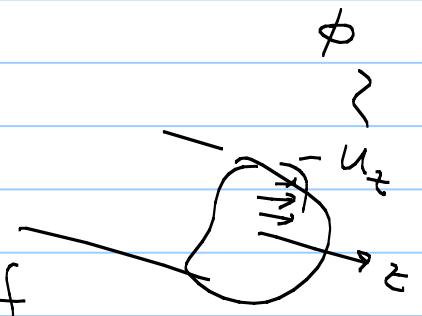
$$= \oint_C (xv_x + yv_y) \psi dA$$

$$= 0 \quad \text{Because } \psi = 0 \text{ on } C$$

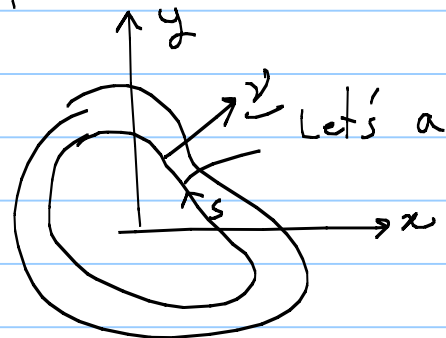
$$\therefore C_t = 2\mu \int_R \psi dA$$

Significance of  $\phi = \text{CONST}$  line  
 $\psi = \text{CONST}$  line

1)  $\phi = \text{CONST}$  line  
 $\phi \rightarrow$  warping, out-of-of plane dis  $\rho$



2)  $\psi = \text{CONST}$  line



Let's assume  $\psi = \text{CONST}$  here

• Along the  $\psi = \text{CONST}$

$$0 = \frac{d\psi}{ds} = \frac{\partial \psi}{\partial x} \frac{dx}{ds} + \frac{\partial \psi}{\partial y} \frac{dy}{ds}$$

$$= \left( \frac{\partial \psi}{\partial y}, -\frac{\partial \psi}{\partial x} \right) \cdot \left( \frac{dy}{ds}, -\frac{dx}{ds} \right)$$

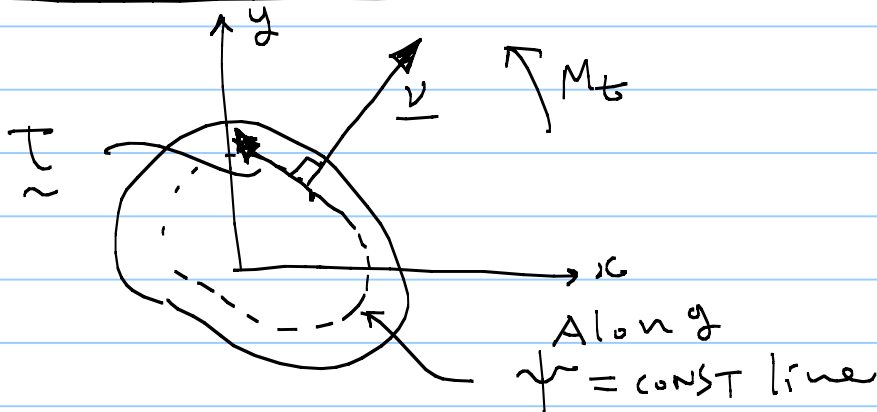
$$\begin{aligned} \sigma_{zx} &= \mu \alpha \frac{\partial \psi}{\partial y} \\ \sigma_{zy} &= -\mu \alpha \frac{\partial \psi}{\partial x} \end{aligned}$$

$$= \frac{1}{\mu \alpha} (\sigma_{zx}, \sigma_{zy}) \cdot \underline{v}$$

$$0 \triangleq \frac{1}{\mu \alpha} \underline{\tau} \cdot \underline{v} \quad (\text{along } \psi = \text{CONST line}) \quad (*)$$

↑ called traction vector

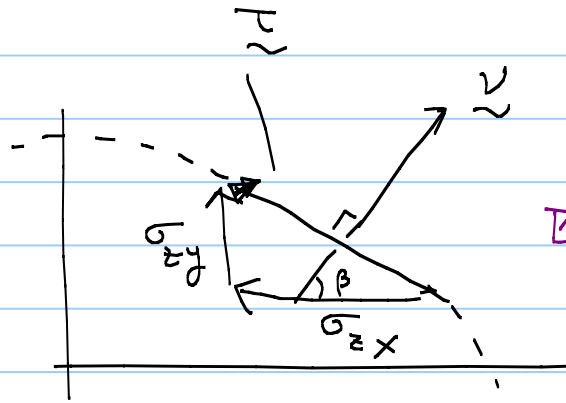
Meaning of (\*)



the resultant vector  $\underline{\tau}$  of the shear stress must be orthogonal to  $\underline{v}$

Thus

$$\begin{pmatrix} \cos \beta = v_x \\ \sin \beta = v_y \end{pmatrix}$$



Ratio of  $\sigma_{zy}$  to  $\sigma_{zx}$  is determined!

$$\tau = |\vec{p}| = (\sigma_{zx}^2 + \sigma_{zy}^2)^{\frac{1}{2}}$$

$$\text{or } -\sigma_{zx} \sin \beta + \sigma_{zy} \cos \beta$$

$$= -\sigma_{zx} v_y + \sigma_{zy} v_x$$

$$= -\left(\mu \alpha \frac{\partial \psi}{\partial y}\right) v_y + \left(-\mu \alpha \frac{\partial \psi}{\partial x}\right) v_x$$

$$= -\mu \alpha \left( \frac{\partial \psi}{\partial y} v_y + \frac{\partial \psi}{\partial x} v_x \right)$$

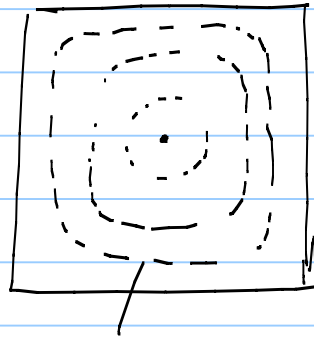
$$= -\mu \alpha \frac{d\psi}{dr}$$

$$\Rightarrow \text{shear stress } \tau \parallel \frac{d\psi}{dr}$$

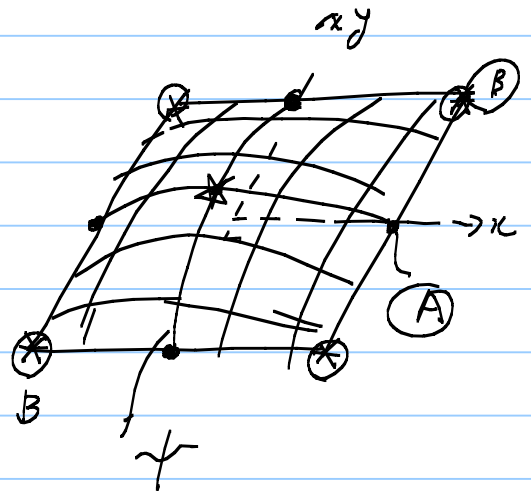
$\hat{=}$  the amount of change in  $\psi$  along the normal direction  $\underline{v}$



example



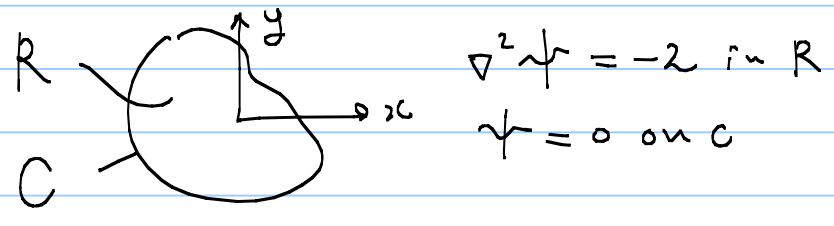
lines of  $\psi = \text{const}$



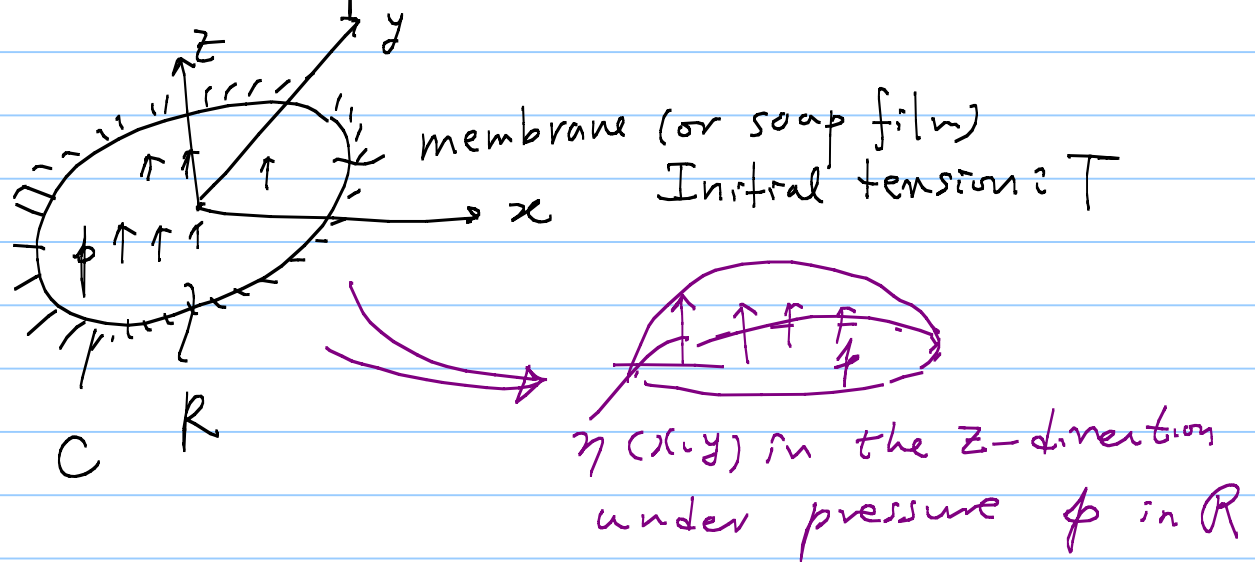
● : Max shear stress  $\rightarrow d\psi/dv = \max$   
\*, (●) : no shear stress  $\rightarrow d\psi/dv = 0$

# Membrane Analogy (Prandtl Function)

- Prandtl Stress Function:  $\psi$



- Equation for thin Membrane Deflection under pressure



$$\begin{cases} \nabla^2 \eta(x,y) = -\frac{p}{T} & \text{in } R \\ \eta = 0 & \text{on } C \end{cases}$$

Analogy

$$\eta = \frac{\rho}{2T} \sqrt{v}$$

$$\textcircled{2} \quad \tau = -\mu d \frac{dv}{dv} = \frac{-2\mu d}{T} \frac{d\eta}{dv}$$

shear  
stress

$\Rightarrow \tau \propto$  Change rate of  
membrane deflection

$$\textcircled{3} \quad C_t = 2\mu \int_R \tau dA$$

$$= \frac{4\mu T}{\rho} \int_R \eta dA$$

Volume enclosed by  
the  $\eta$  surface and the  
x-y plane

~~\*\*~~ Remark 1) : Complicated physics in torsion  
can be easily understood or visualized  
by membrane analogy in terms of  
membrane deflection

⇒ Key Advantage of using Prandtl  
stress function

Remark 2) : Experiment in torsion  
⇒ done with membrane