457.643 Structural Random Vibrations In-Class Material: Class 13

II-2. Stochastic Calculus (contd.)

Second Ergodicity



Average over the time domain is actually a ______ variable. Consider

$$M_T = \frac{1}{T} \int_0^T X(t) dt = \langle X(t) \rangle$$
$$\phi_T(\tau) = \frac{1}{T - \tau} \int_0^{T - \tau} X(t + \tau) X(t) dt$$

These are random variable and function because the results depend on random outcome (selection) of a time history.

 "Ergodic" process: If X(t) is an ergodic process, one can use the temporal average from a time history x(t) as a substitute for an ______ expectation. 2) Basic ______ condition for ergodicity: stationarity



What if X(t) is NOT stationary? $\mu(t_1) \neq \mu(t_2)$

- 3) Condition for ergodicity in the mean M_T
 - $\lim_{T \to \infty} \mathbb{E}[M_T] = \mu_X(t) = \mathbb{E}[X(t)]$ ~ automatically satisfied for _____ process

 $\lim_{T \to \infty} \operatorname{Var}[M_T] = 0 \leftrightarrow \lim_{T \to \infty} \frac{1}{\tau} \int_0^T \Gamma_{XX}(\tau) d\tau = 0$ (See Lin 1967, p. 64)

This is the condition for "ergodicity in the mean"

- 4) Condition for ergodicity in the correlation function $\phi_T(\tau)$
 - $\lim_{T \to \infty} E[\phi_T(\tau)] = R_{XX}(\tau)$ ~ automatically satisfied for _____ process

• $\lim_{T\to\infty} \operatorname{Var}[\phi_T(\tau)] = 0$

The latter is equivalent to (Lin 1967, p. 65)

$$\lim_{T \to \infty} \frac{1}{T} \int_0^T \mathbb{E}\{ [X(t+\tau)X(t) - R_{XX}(\tau)] [X(t+\tau+u)X(t+u) - R_{XX}(\tau)] \} du = 0$$

Example: Telegraph Random Process

 $\Gamma_{XX}(\tau) = \sigma^2 \exp(-2\nu|\tau|)$

Is the process ergodic in the mean?

Example: Y(t) = A + X(t) where X(t) is the random telegraph process, and E[A] = 0 and $Var[A] = \sigma^2$. Is Y(t) ergodic in the mean?

III. Random Vibration of Linear Structures

Stochastic response of "linear" structural system

Recall the system equation introduced in 0. Introduction

 $\mathcal{D}[\mathcal{X}(x,t)] = \mathcal{Y}(x,t), \qquad t \ge 0, \qquad x \in D \subset \mathcal{R}^d$

- 1. Deterministic systems and input (457.516 Dynamics of Structures)
- 2. Deterministic systems and stochastic input (457.643 Structural Random Vibrations)
- 3. Stochastic systems and deterministic input (457.646 Topics in Structural Reliability)
- 4. Stochastic systems and input

We consider the second case in this course. Note that the system is "linear" when the differential equation is linear, i.e. s_____ principle works.

e.g. if $x_1(t)$ is the response to $y_1(t)$, and $x_2(t)$ is the response to the input $y_2(t)$, the response to $y_1(t) + y_2(t)$ is _____

III-1. Response Functions of Structural Systems

Characterization of linear systems

1) Time-domain: "Impulse Response Function"



2) Frequency-domain: "Frequency Response Function"



Impulse response function of a linear system

Consider the differential equation (DE) of a general linear system

 $a_n \frac{d^n x}{dt^n} + a_{n-1} \frac{d^{n-1} x}{dt^{n-1}} + \dots + a_1 \frac{dx}{dt} + a_0 x = p(t)$

Impulse response function of a linear system h(t) is the solution of the DE when $p(t) = \delta(t)$, i.e.

$$a_n \frac{d^n h}{dt^n} + a_{n-1} \frac{d^{n-1} h}{dt^{n-1}} + \dots + a_1 \frac{dh}{dt} + a_0 h = \delta(t) \cdots (*)$$

 $h(t) = h_h(t) + h_p(t)$

where $h_h(t)$: homogeneous solution and $h_p(t)$: particular solution

Strategy: Model the dirac delta input function by a triangular function for $t \in (-\epsilon, \epsilon)$. Then, obtain $h(t) = h_h(t)$ with the initial conditions caused by the impulse.



From (*), it is clear that only the _____est term can be dirac delta function because if an non-highest-order term is dirac delta, the higher-order-terms will blow up.

$$\therefore a_n \frac{d^{n_h}}{dt^n} = \delta(t), \ 0^- < t < 0^+$$

$$a_n \frac{d^{n-1}h}{dt^{n-1}} \bigg|_{0^-}^{0^+} = \int_{0^-}^{0^+} \delta(t) dt = \longrightarrow a_n \frac{d^{n-1}h}{dt^{n-1}} \bigg|_{t=0^+} =$$

Therefore, the initial conditions at $t = 0^+$ are

$$\frac{d^{n-1}h}{dt^{n-1}} =$$
, $\frac{d^{n-2}h}{dt^{n-2}} = \dots = h =$