

# Chapter 8.

## Principal-Components Analysis

*Neural Networks and Learning Machines*  
(Haykin)

Lecture Notes of  
Self-learning Neural Algorithms

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# 8.1 Introduction

## ■ Supervised learning

- Learning from labeled examples

## ■ Semisupervised learning

## ■ Unsupervised learning

- Learning from examples without a teacher

### ● Self-organized learning

- Neurobiological considerations
- Locality of learning (immediate local behavior of neurons)

### ● Statistical learning theory

- Mathematical considerations
- Less emphasis on locality of learning

## 8.2 Principles of Self-Organization (1/2)

### ■ Principle 1: **Self-amplification** (self-reinforcement)

- Synaptic modification self-amplifies by Hebb's postulate of learning
  - 1) If two neurons of a synapse are activated **simultaneously**, then synaptic strength is selectively **increased**.
  - 2) If two neurons of a synapse are activated **asynchronously**, then synaptic strength is selectively **weakened** or eliminated.

$$\Delta w_{kj}(n) = \eta y_k(n) x_j(n)$$

### ● **Four key mechanisms of Hebbian synapse**

- Time-dependent mechanism
- Local mechanism
- Interactive mechanism
- Conjunctional or correlational mechanism

## 8.2 Principles of Self-Organization (2/2)

### ■ Principle 2: Competition

- Limitation of available resources
- The most vigorously growing (fittest) synapses or neurons are selected at the expense of the others.
- Synaptic plasticity (adjustability of a synaptic weight)

### ■ Principle 3: Cooperation

- Modifications in synaptic weights at the neural level and in neurons at the network level tend to cooperate with each other.
- Lateral interaction among a group of excited neurons

### ■ Principle 4: Structural information

- The underlying structure (redundancy) in the input signal is acquired by a self-organizing system
- Inherent characteristic of the input signal

## 8.3 Self-organized Feature Analysis

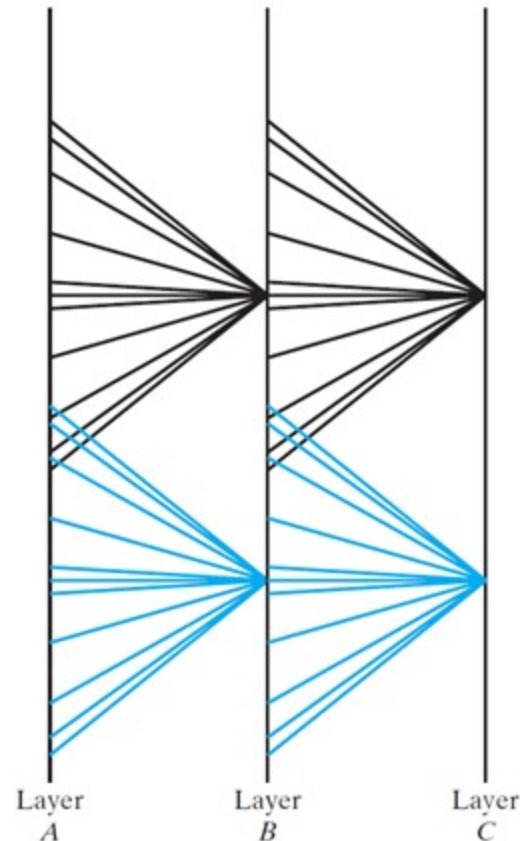


Figure 8.1 Layout of modular self-adaptive Linsker's model, with overlapping receptive fields. Mammalian visual system model.

## 8.4 Principal-Components Analysis (1/8)

Does there exist an invertible linear transformation  $\mathbf{T}$  such that the truncation of  $\mathbf{T}\mathbf{x}$  is optimum in the mean-square-error sense?

$\mathbf{x}$ :  $m$ -dimensional vector

$\mathbf{X}$ :  $m$ -dimensional random vector

$\mathbf{q}$ :  $m$ -dimensional unit vector

Projection :

$$A = \mathbf{X}^T \mathbf{q} = \mathbf{q}^T \mathbf{X}$$

Variance of  $A$ :

$$\sigma^2 = E[A^2] = E[(\mathbf{q}^T \mathbf{X})(\mathbf{X}^T \mathbf{q})] = \mathbf{q}^T E[\mathbf{X}\mathbf{X}^T] \mathbf{q} = \mathbf{q}^T \mathbf{R} \mathbf{q}$$

$\mathbf{R}$ :  $m$ -by- $m$  correlation matrix

$$\mathbf{R} = E[\mathbf{X}\mathbf{X}^T]$$

## 8.4 Principal-Components Analysis (2/8)

$$\psi(\mathbf{q}) = \sigma^2 = \mathbf{q}^T \mathbf{R} \mathbf{q} \quad **$$

For any small perturbation  $\delta \mathbf{q}$ :

$$\psi(\mathbf{q} + \delta \mathbf{q}) = \psi(\mathbf{q})$$

.....

Introduce a scalar factor  $\lambda$ :

$$\mathbf{R} \mathbf{q} = \lambda \mathbf{q} \quad (\text{eigenvalue problem})$$

$\lambda_1, \lambda_2, \dots, \lambda_m$ : Eigenvalues of  $\mathbf{R}$

$\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_m$ : Eigenvectors of  $\mathbf{R}$

$$\mathbf{R} \mathbf{q}_j = \lambda_j \mathbf{q}_j \quad j = 1, 2, \dots, m$$

$$\lambda_1 > \lambda_2 > \dots > \lambda_j > \dots > \lambda_m$$

$$\mathbf{Q} = [\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_j, \dots, \mathbf{q}_m]$$

$$\mathbf{R} \mathbf{Q} = \mathbf{Q} \Lambda$$

$$\mathbf{R} \mathbf{Q} = \mathbf{Q} \Lambda$$

Eigen decomposition:

$$\text{i) } \mathbf{Q}^T \mathbf{R} \mathbf{Q} = \Lambda$$

$$\mathbf{q}_j^T \mathbf{R} \mathbf{q}_k = \begin{cases} \lambda_j, & k = j \\ 0, & k \neq j \end{cases} \quad **$$

$$\text{ii) } \mathbf{R} = \mathbf{Q} \Lambda \mathbf{Q}^T = \sum_{i=1}^m \lambda_i \mathbf{q}_i \mathbf{q}_i^T$$

(spectral theorem)

From \*\*, we see that

$$\psi(\mathbf{q}_j) = \lambda_j \quad j = 1, 2, \dots, m$$



## 8.4 Principal-Components Analysis (3/8)

- Summary of the eigenstructure of PCA
  - 1) The eigenvectors of the correlation matrix  $\mathbf{R}$  for the random vector  $\mathbf{X}$  define the unit vectors  $\mathbf{q}_j$ , representing the principal directions along with the variance probes  $\psi(\mathbf{q}_j)$  have their extremal values.
  - 2) The associated eigenvalues define the extremal values of the variance probes  $\psi(\mathbf{u}_j)$

## 8.4 Principal-Components Analysis (4/8)

Data vector  $\mathbf{x}$ : a realization of  $\mathbf{X}$

$a$ : a realization of  $A$

$$a_j = \mathbf{q}_j^T \mathbf{x} = \mathbf{x}^T \mathbf{q}_j \quad j = 1, 2, \dots, m$$

$a_j$ : the projections of  $\mathbf{x}$  onto principal directions

(principal components)

Reconstruction (synthesis) of the original data  $\mathbf{x}$ :

$$\mathbf{a} = [a_1, a_2, \dots, a_m]^T = [\mathbf{x}^T \mathbf{q}_1, \mathbf{x}^T \mathbf{q}_2, \dots, \mathbf{x}^T \mathbf{q}_m]^T = \mathbf{Q}^T \mathbf{x}$$

$$\mathbf{Q}\mathbf{a} = \mathbf{Q}\mathbf{Q}^T \mathbf{x} = \mathbf{I}\mathbf{x} = \mathbf{x}$$

$$\mathbf{x} = \mathbf{Q}\mathbf{a} = \sum_{j=1}^m a_j \mathbf{q}_j$$

# 8.4 Principal-Components Analysis (5/8)

Dimensionality reduction

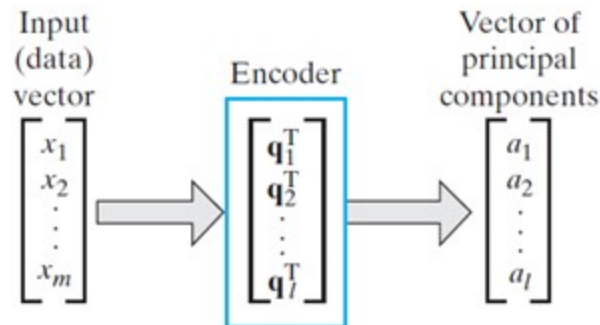
$\lambda_1, \lambda_2, \dots, \lambda_\ell$  : largest  $\ell$  eigenvalues of  $\mathbf{R}$

$$\hat{\mathbf{x}} = \sum_{j=1}^{\ell} a_j \mathbf{q}_j = [\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_\ell] \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_\ell \end{bmatrix}, \quad \ell \leq m$$

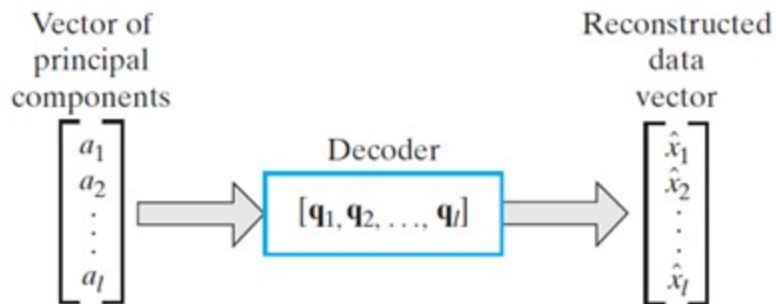
Encoder for  $\mathbf{x}$ : linear projection from  $\mathbb{R}^m$  to  $\mathbb{R}^\ell$

$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_\ell \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1^T \\ \mathbf{q}_2^T \\ \vdots \\ \mathbf{q}_\ell^T \end{bmatrix} \mathbf{x}, \quad \ell \leq m$$

Figure 8.2 Two phases of PCA  
(a) Encoding, (b) Decoding



(a)



(b)

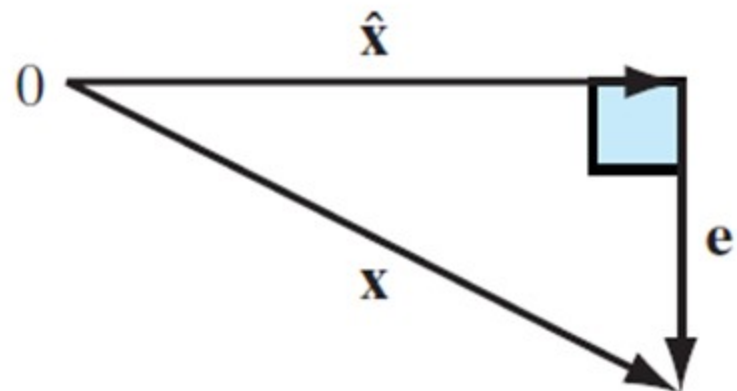
## 8.4 Principal-Components Analysis (6/8)

Approximation error vector:

$$\mathbf{e} = \mathbf{x} - \hat{\mathbf{x}}$$

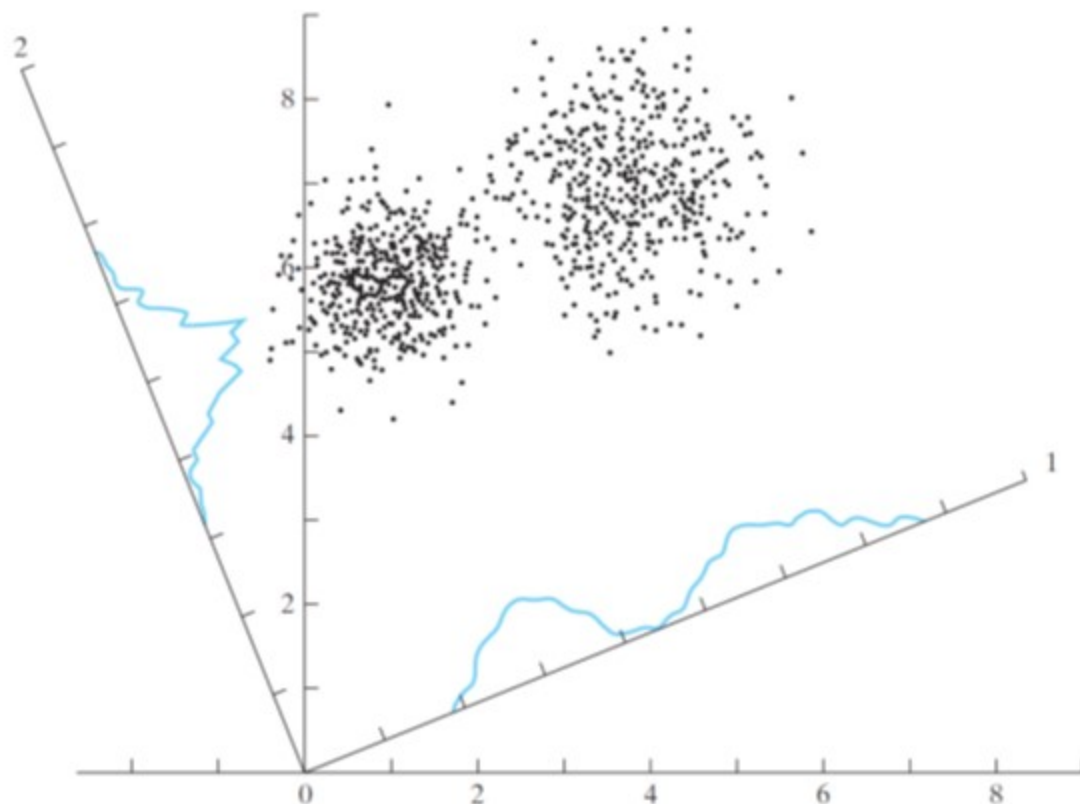
$$\mathbf{e} = \sum_{i=\ell+1}^m a_i \mathbf{q}_i$$

Figure 8.3: Relationship between data vector  $\mathbf{x}$ , its reconstructed version  $\hat{\mathbf{x}}$  and error vector  $\mathbf{e}$ .



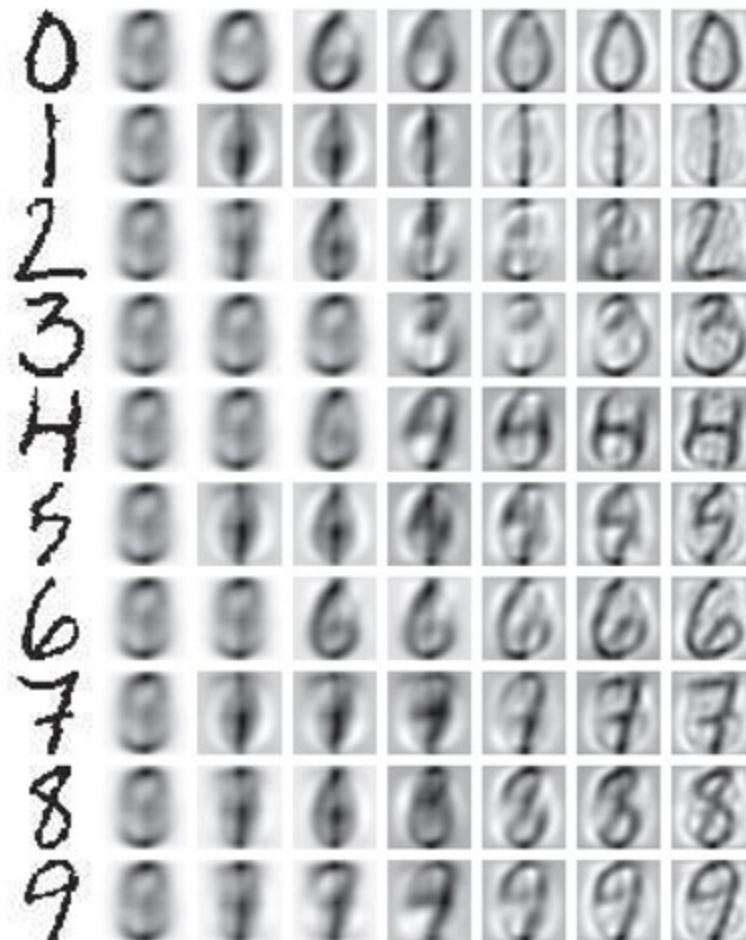
## 8.4 Principal-Components Analysis (7/8)

Figure 8.4: A cloud of data points. Projection onto Axis 1 has maximum variance and shows bimodal.



## 8.4 Principal-Components Analysis (8/8)

Figure 8.5: Digital compression of handwritten digits using PCA.



## 8.5 Hebbian-Based Maximum Eigenfilter (1/4)

Linear neuron with Hebbian adaptation

$$y = \sum_{i=\ell+1}^m w_i x_i$$

Synaptic weight  $w_i$  varies with time

$$w_i(n+1) = w_i(n) + \eta y(n) x_i(n), \quad i = 1, 2, \dots, m$$

...

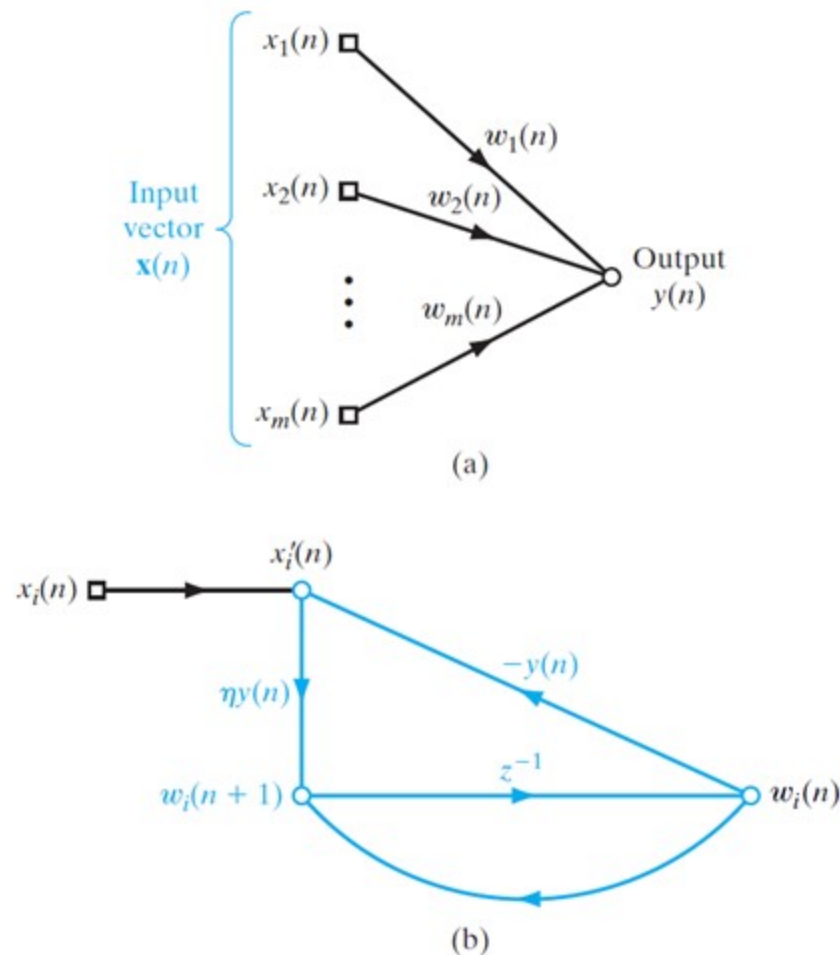
$$w_i(n+1) = w_i(n) + \eta y(n) (x_i(n) - y(n) w_i(n))$$

$$x_i'(n) = x_i(n) - y(n) w_i(n)$$

$$w_i(n+1) = w_i(n) + \eta y(n) x_i'(n)$$

## 8.5 Hebbian-Based Maximum Eigenfilter (2/4)

Figure 8.6: Signal-flow graph representation of maximum eigenfilter





## 8.5 Hebbian-Based Maximum Eigenfilter (3/4)

Matrix formulation

$$\mathbf{x}(n) = [x_1(n), x_2(n), \dots, x_m(n)]^T$$

$$\mathbf{w}(n) = [w_1(n), w_2(n), \dots, w_m(n)]^T$$

$$y(n) = \mathbf{x}^T(n)\mathbf{w}(n) = \mathbf{w}^T(n)\mathbf{x}(n)$$

$$\mathbf{w}(n+1) = \mathbf{w}(n) + \eta y(n) [\mathbf{x}(n) - y(n)\mathbf{w}(n)]$$

$$= \mathbf{w}(n) + \eta \mathbf{x}^T(n)\mathbf{w}(n) [\mathbf{x}(n) - \mathbf{w}^T(n)\mathbf{x}(n)\mathbf{w}(n)]$$

$$= \mathbf{w}(n) + \eta [\mathbf{x}^T(n)\mathbf{x}(n)\mathbf{w}(n) - \mathbf{w}^T(n)\mathbf{x}(n)\mathbf{x}^T(n)\mathbf{w}(n)\mathbf{w}(n)]$$

## 8.5 Hebbian-Based Maximum Eigenfilter (4/4)

Asymptotic stability of maximum eigenfilter

$$\mathbf{w}(t) \rightarrow \mathbf{q}_1 \quad \text{as } t \rightarrow \infty$$

A single linear neuron governed by the self-organizing learning rule adaptively extracts the first principal component of a stationary input.

$$\mathbf{x}(n) = y(n)\mathbf{q}_1 \quad \text{for } n \rightarrow \infty$$

A Hebbian-based linear neuron with learning rule

$$\mathbf{w}(n+1) = \mathbf{w}(n) + \eta y(n)[\mathbf{x}(n) - y(n)\mathbf{w}(n)]$$

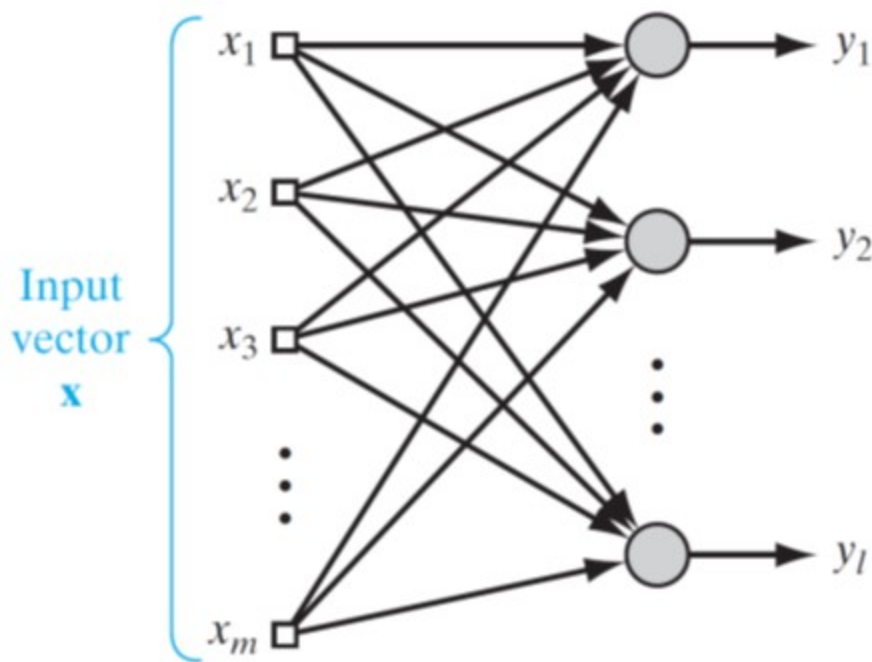
converges with probability 1 to a fixed point:

$$1) \lim_{n \rightarrow \infty} \sigma^2(n) = \lambda_1$$

$$2) \lim_{n \rightarrow \infty} \mathbf{w}(n) = \mathbf{q}_1 \quad \text{with} \quad \lim_{n \rightarrow \infty} \|\mathbf{w}(n)\| = 1$$

## 8.6 Hebbian-Based PCA (1/3)

Figure 8.7: Feedforward network with a single layer of computational nodes



linear neuron

$m$  inputs,  $l$  outputs:  $l < m$

$w_{ji}$  : synaptic weight from  $i$  to  $j$

$$y_j(n) = \sum_{i=1}^m w_{ji}(n)x_i(n) \quad j = 1, 2, \dots, l$$

## 8.6 Hebbian-Based PCA (2/3)

### Generalized Hebbian Algorithm (GHA)

$$y_j(n) = \sum_{i=1}^m w_{ji}(n) x_i(n) \quad j = 1, 2, \dots, \ell$$

Weight update rule:

$$\Delta w_{ji}(n) = \eta \left( y_j(n) x_i(n) - y_j(n) \sum_{k=1}^j w_{ki}(n) y_k(n) \right)$$

Rewriting as

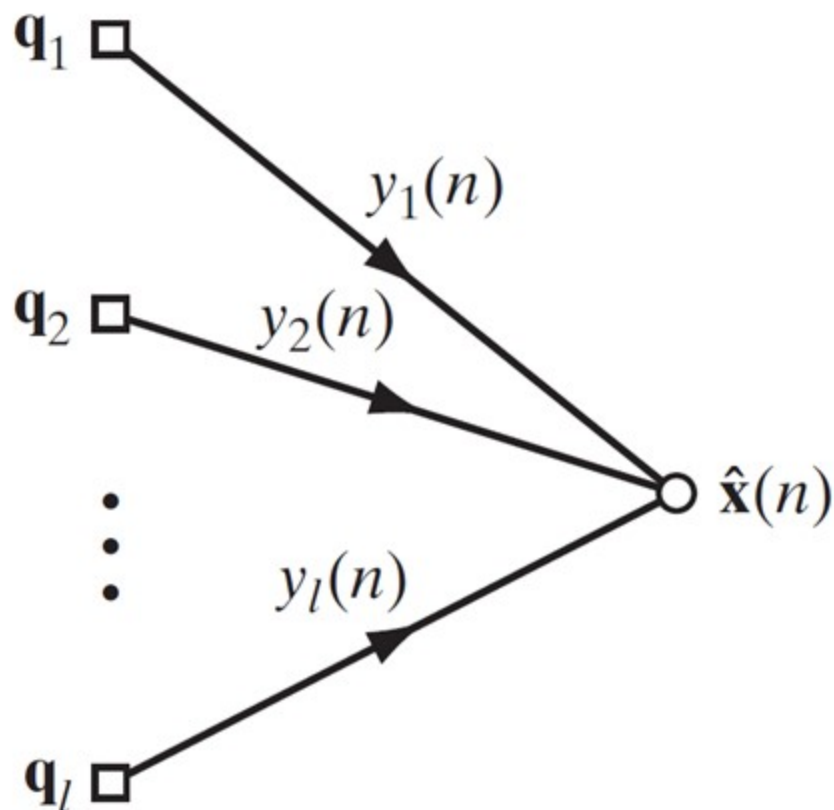
$$\Delta w_{ji}(n) = \eta y_j(n) \left[ x_i'(n) - w_{ji}(n) y_j(n) \right]$$

$$x_i'(n) = x_i(n) - \sum_{k=1}^{j-1} w_{ki}(n) y_k(n)$$



## 8.7 Case Study: Image Decoding (1/3)

Figure 8.9: Signal-flow graph representation of how the reconstructed vector  $\hat{\mathbf{x}}$  is computed in the GHA.



$$\hat{\mathbf{x}}(n) = \sum_{k=1}^{\ell} y_k(n) \mathbf{q}_k$$

## 8.7 Case Study: Image Decoding (2/3)

Figure 8.10: (a) An image of Lena used in the image-coding experiment. (b)  $8 \times 8$  masks representing the synaptic weights learned by the GHA. (c) Reconstructed image of Lena obtained using the dominant 8 principal components without quantization. (d) Reconstructed image of Lena with an 11-to-1 compression ratio using quantization



# 8.7 Case Study: Image Decoding (3/3)

Figure 8.11: Image of peppers

Using First 8 Components



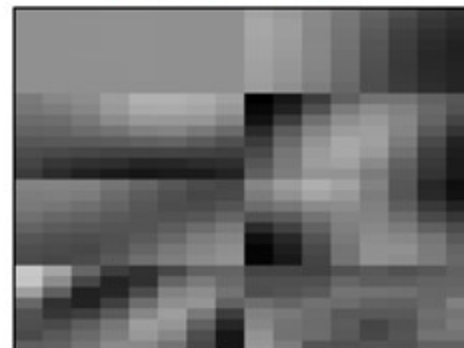
12 to 1 compression



12 to 1 compression



Weights From Lena





# Summary and Discussion

- PCA = dimensionality reduction = compression
- Generalized Hebbian algorithm (GHA) = Neural algorithm for PCA

- Dimensionality reduction
  - 1) Representation of data
  - 2) Reconstruction of data

$$\mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_\ell \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1^T \\ \mathbf{q}_2^T \\ \vdots \\ \mathbf{q}_\ell^T \end{bmatrix} \mathbf{x}, \quad \ell \leq m$$

- Two views of unsupervised learning

- 1) Bottom-up view
- 2) Top-down view

$$\hat{\mathbf{x}} = \sum_{j=1}^{\ell} a_j \mathbf{q}_j = [\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_\ell] \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_\ell \end{bmatrix}, \quad \ell \leq m$$

- Nonlinear PCA methods

- 1) Hebbian networks
- 2) Replicator networks or autoencoders
- 3) Principal curves
- 4) Kernel PCA

$$\mathbf{e} = \mathbf{x} - \hat{\mathbf{x}}$$

$$\mathbf{e} = \sum_{i=\ell+1}^m a_i \mathbf{q}_i$$