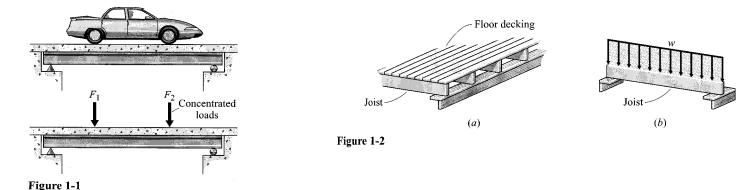
1. Essential Concepts

1.1 Introduction

- Mechanics
 - Classical -, Quantum -, Relativistic –, etc.
 - Statics: concerned with analysis of loads on physical systems in static equilibrium.
 - Dynamics: kinematics (운동학-시간과 속도, 가속도) and kinetics (운동역학 힘과 운동). Normally dealing with particles and rigid bodies.
 - Mechanics of materials: concerned with the behavior of solid materials such as bars, beams and columns on axial, torsional, and/or flexural loading.
- Primary objects of this course
 - Understanding relations between the load and deformation, load and stress, and stress and strain of a body
 - Familiar with fundamental concepts and skills for structural and machine design

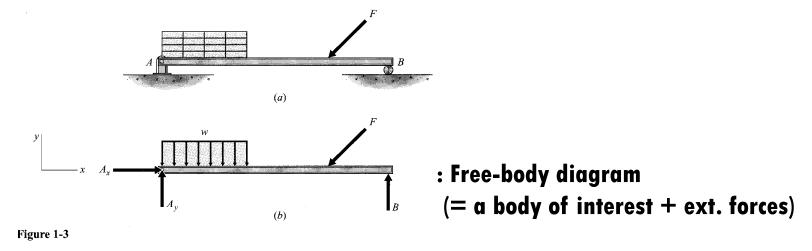
1.2 Classification of forces

- Newton's three laws of Motion
 - The law of inertia: every object tends to remain in a state of motion without an external force on it.
 - F = ma: force equals mass times acceleration.
 - The law of action-reaction: To every action there is an equal and opposite reaction.
- Classification of forces
 - Contact force vs. body force: person standing on a sidewalk, electromagnetic, gravitation...
 - Concentrated force (load) vs. distributed force



1.2 Classification of forces

- Applied force vs. reaction force

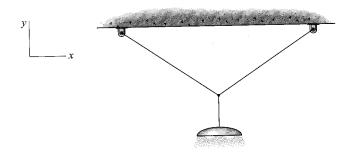


- External force vs. internal force: force on an object exerted by external sources force at a section of an object

• Equilibrium conditions (equations) of a rigid body

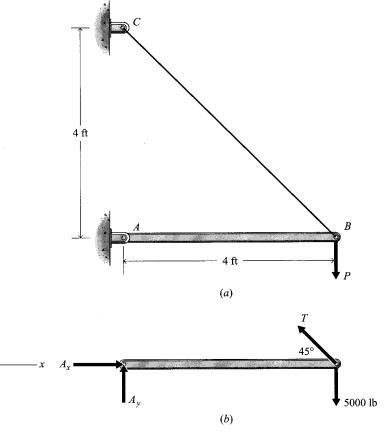
-
$$\sum F = 0 \left(\equiv \sum F_x = 0, \sum F_y = 0, \text{ and } \sum F_z = 0 \right)$$

- $\sum M_0 = 0 \left(\equiv \sum M_x = 0, \sum M_y = 0, \text{ and } \sum M_z = 0 \right)$
- For 2D cases: $\sum F_x = 0, \sum F_y = 0, \text{ and } \sum M_z = 0$
- For coplanar and concurrent cases: $\sum F_x = 0, \sum F_y = 0$



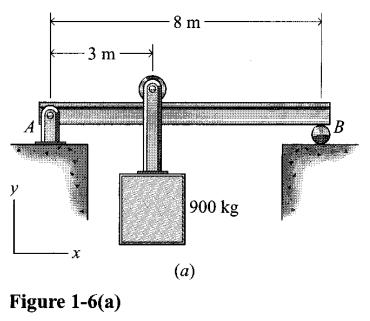


- Example problem 1-1
- Force at A and B



|y|

- Example problem 1-2
- Force at A and B neglecting the beam mass
- Force at A and B at the beam mass of 8.5kg/m



- Example problem 1-4
- Forces on member BH

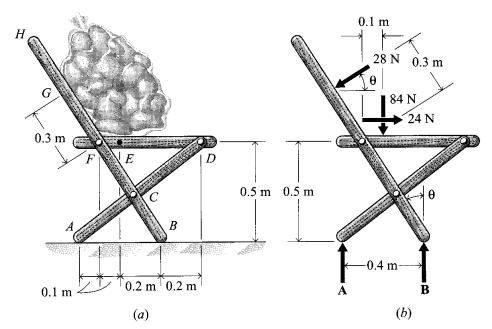
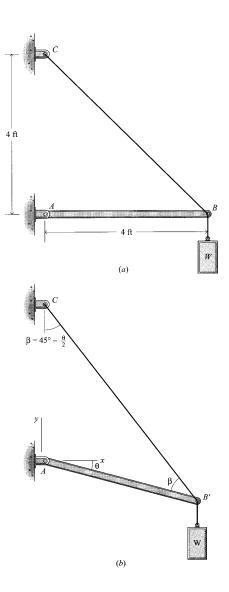


Figure 1-8

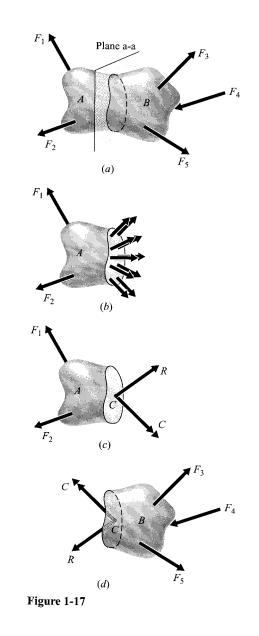
1.4 Equilibrium of a deformable body

- Considerations
- Equation of equilibrium
- Force-deformation relationship
- Deformation
- Example problem 1-8
- Tension in the deformable wire at k = 5000 lb/in, 2500 lb/in, and 1000 lb/in (W=5000 lb)
- → Tension (force) depends on the force-deformation relationship of the deformable body



- Equilibrium of parts of a body
- If a whole body is in equilibrium any part of the body is also in equilibrium.
- Forces distributed on a section can be represented by a resultant force.

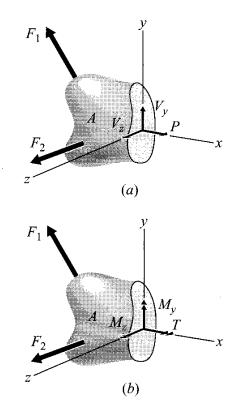
$$\sum F = 0: \quad F_1 + F_2 + R = 0$$
$$\sum M_c = 0: M_1 + M_2 + C = 0$$



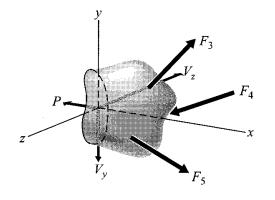
- Internal forces in a section
- Select an *xyz*-coordinate system in which *x* is perpendicular to the section and *y* and *z* lie in the section.

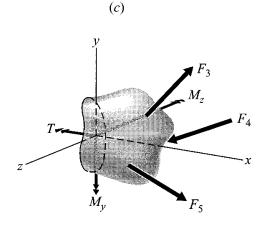
The components of *R* and *C* perpendicular to the section are called **normal force** (P) and **twisting couple** (T; twisting moment or torque).

- The components of *R* and *C* lying in the section are called **shear forces** (V_y, V_z) and **bending couples** $(M_y, M_z;$ bending moments).

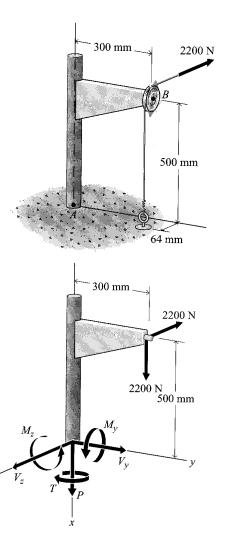


- -A section is called a positive (negative) section when its outward normal points in a positive coordinate direction.
- The component of *R* or *C* is defined as positive if both the section direction and the component direction are positive or negative.

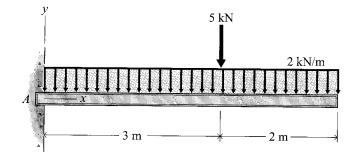




- Example problem 1-9
- Internal force components on a section A
- Internal moment components on a section A



- Example problem 1-10
- Support reaction force and moment at A
- Internal force and moment on a section 4 m to the right of the support A



- Example problem 1-11
- Internal force and moment on a mid-point section between D and F

