

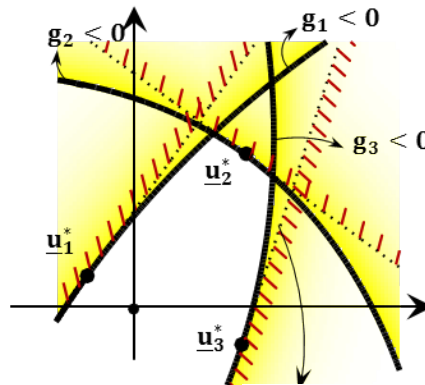
457.646 Topics in Structural Reliability

In-Class Material: Class 18

© FORM approximation (Hohenbichler & Rackwitz 1983)

① Series system

$$\begin{aligned}
 P(E_{sys}) &= P\left(\bigcup_{i=1}^m E_i\right) \\
 &= P\left(\bigcup_{i=1}^m g_i(\mathbf{x}) \leq 0\right) \\
 &\stackrel{FORM}{\cong} P\left(\bigcup_{i=1}^m \dots \leq 0\right)
 \end{aligned}$$



$n \rightarrow$ # rv's
 $m \rightarrow$ # comp's

Let $Z_i = \hat{\alpha}_i \mathbf{u}$, $i = 1, \dots, m$

$$E[Z_i] =$$

$$Var[Z_i] = \|\dots\|^2 =$$

$$\begin{aligned}
 G_i(\mathbf{u}) &\approx G_i(\mathbf{u}_i^*) + \nabla G_i(\mathbf{u}_i^*)(\mathbf{u} - \mathbf{u}_i^*) \\
 &= \nabla G_i(\mathbf{u}_i^*)(\mathbf{u} - \mathbf{u}_i^*) \leq 0
 \end{aligned}$$

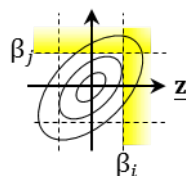
$$\Leftrightarrow \dots \leq 0$$

Therefore, $Z_i \sim (\dots, \dots)$

$$\begin{aligned}
 \rho_{Z_i, Z_j} &= \frac{[\dots, \dots]}{\dots} = E[\dots] - E[\dots] \cdot E[\dots] \\
 &= E[\dots \cdot \dots^T] = E[\dots] = E[\mathbf{u}\mathbf{u}^T] = \dots
 \end{aligned}$$

$\therefore \mathbf{Z} \sim (\dots, \dots)$, $\rho_{Z_i, Z_j} =$

$$\begin{aligned}
 \therefore P(E_{sys}) &\stackrel{FORM}{\cong} P\left(\bigcup_{i=1}^m \dots \leq 0\right) \\
 &= 1 - P\left(\bigcap_{i=1}^m \dots \leq \dots\right)
 \end{aligned}$$



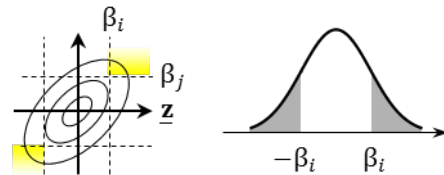
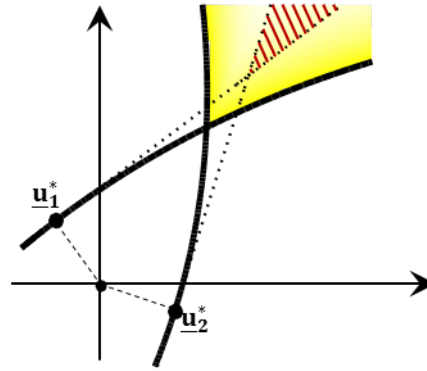
$$= 1 - \Phi_m(\dots, \dots; \mathbf{R})$$

Joint normal CDF of $\mathbf{Z} \sim N(\mathbf{0}; \mathbf{R})$

Where $\Phi_m(\boldsymbol{\beta}; \mathbf{R}) = \int_{-\infty}^{\beta_1} \dots \int_{-\infty}^{\beta_m} \phi_m(\mathbf{Z}; \mathbf{R}) d\mathbf{z}$

② Parallel system

$$\begin{aligned}
 P(E_{sys}) &= P\left(\bigcap_{i=1}^m E_i\right) \\
 &= P\left(\bigcap_{i=1}^m g_i(\mathbf{x}) \leq 0\right) \\
 &\stackrel{FORM}{\cong} P\left(\bigcap_{i=1}^m \left(\frac{g_i(\mathbf{u}_i^*)}{\|\mathbf{u}_i^*\|} \leq 0 \right)\right) \\
 &= P\left(\bigcap_{i=1}^m \left(\beta_i \geq 0 \right)\right) \\
 &\stackrel{sym}{=} P\left(\bigcap_{i=1}^m \left(\beta_i \leq 0 \right)\right) \\
 &= \Phi_m\left(\beta_1, \dots, \beta_m; \mathbf{R} \right)
 \end{aligned}$$



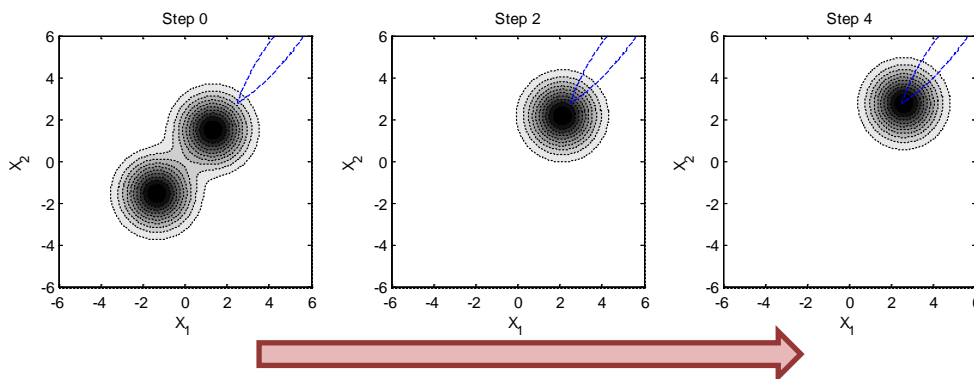
→ may have huge errors due to curvatures

→ better linearization point?

“joint design point”
 Hard to find or may not exist

Note: One could find such important domain using an adaptive sampling technique

Kurtz, N., and J. Song (2013). Cross-entropy-based adaptive importance sampling using Gaussian mixture. *Structural Safety*. Vol. 42, 35-44.



③ General system?

⇒ No direct FORM approximation