

Energy storage and conversion for hybrid & electrical vehicles

1. Why electric systems?
2. Power demand in vehicles
3. Battery electrical vehicle
4. Hybrid vehicle
5. Fuel cell hybrid systems



Why electric and hybrid-electric systems?

- Renewable energy
- Rechargeable energy storage system (RESS)

- Motivation & goals for electric and hybrid-electric vehicles
 - (1) Reduce petroleum use
 - (2) Lower releases of greenhouse gases
 - (3) Decreased emissions of criteria pollutants
 - (4) Increased energy efficiency

ICE(internal combustion engine) vehicle

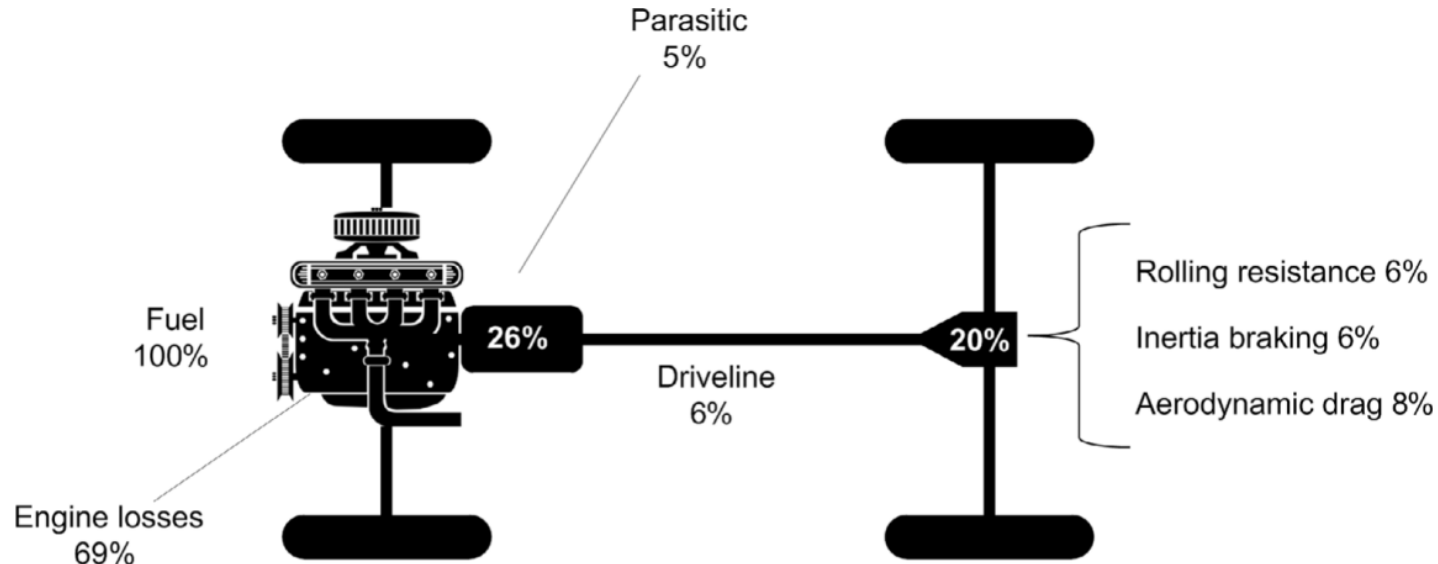


Figure 12.1 Representation of where the energy of the fuel goes for a typical vehicle driving a combination of city and highway.
Source: Data taken from <http://www.fueleconomy.gov/feg/atv.shtml>

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not efficient use of the energy!

Hybrid-electric vehicle

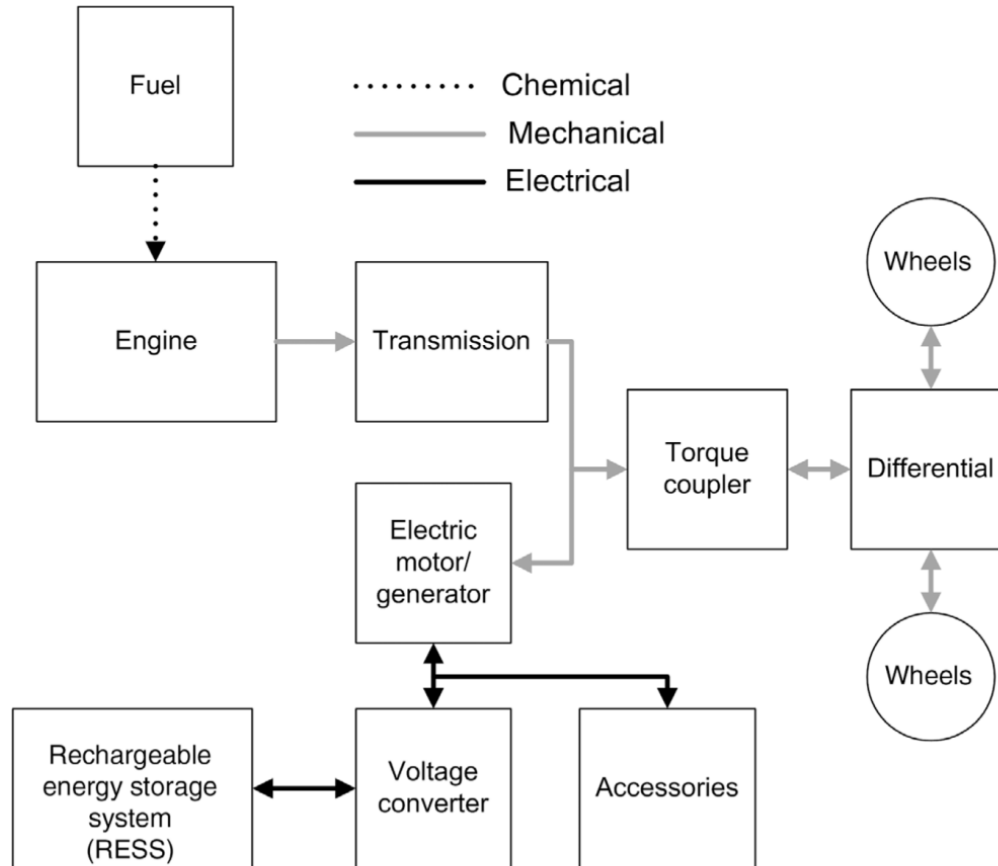


Figure 12.2 Parallel-hybrid architecture, one implementation of a hybrid vehicle.

Parallel hybrid system

Power demand in vehicles

Driving schedule: speed as a function of time

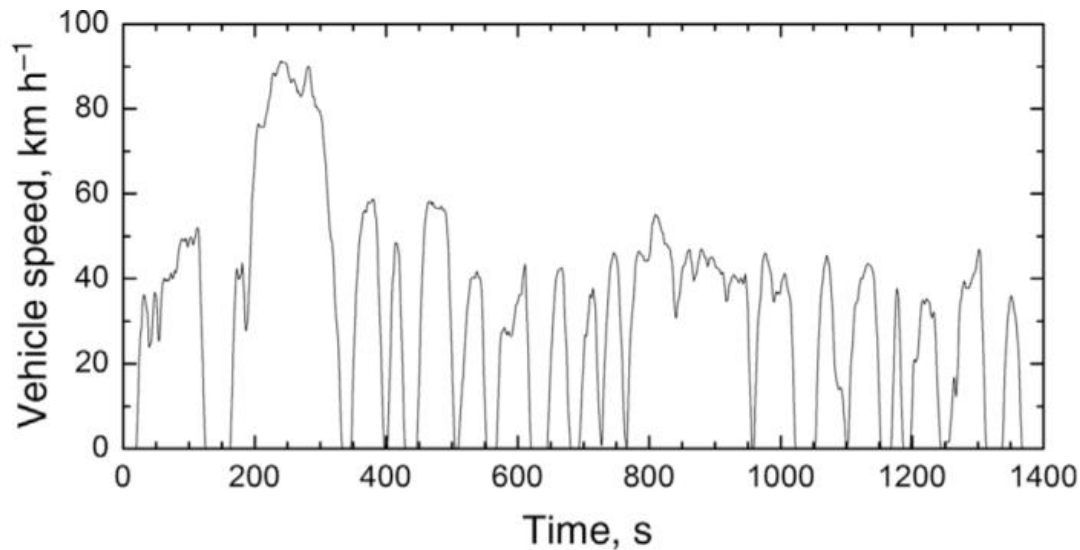
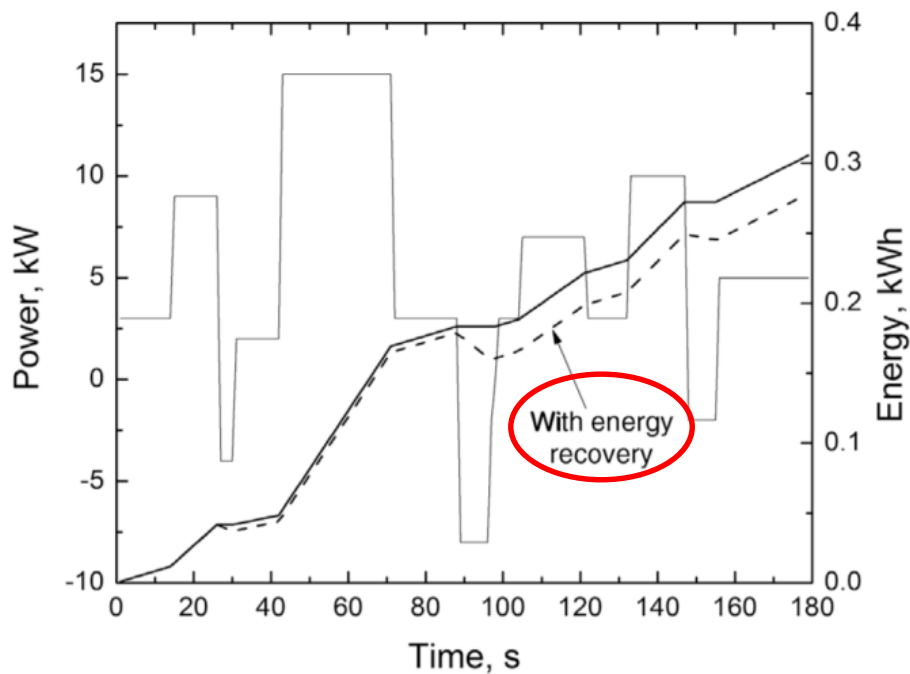


Figure 12.3 Urban dynamometer driving schedule produced by the EPA. **Urban driving, average speed, 40 km/h**

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Power:
 Positive: power is needed
 Negative: deceleration
 (energy recovery and storage)

Energy:
 Solid: no energy recovered
 Dashed: energy recovered
 (hybrid system)

Figure 12.4 Driving schedule converted to power (left axis) and energy in kWh on right axis.

Table 12.1 Energy Associated with Different Driving Schedules for a 1500 kg Vehicle

	FTP-75, city driving, frequent stops, idling	FTP-75, highway driving, no stops	US06, high speed, aggressive driving
Average speed [$\text{km}\cdot\text{h}^{-1}$]	27.9	79.3	77.5
Maximum speed [$\text{km}\cdot\text{h}^{-1}$]	86.4	97.7	128.05
Traction energy [$\text{kWh}\cdot 100\text{ km}^{-1}$]	10.47	10.45	17.03
Traction energy efficiency [$\text{km}\cdot\text{kWh}^{-1}$]	9.6	9.6	5.9
Braking energy, [$\text{kWh}\cdot 100\text{ km}^{-1}$]	4.52	0.98	5.30

The traction energy is at the wheels.

Source: Adapted from Ehsani 2009.

city driving: braking energy ~50% of total energy

Battery electric vehicle

$$V = V_{ocv} - IR_{\Omega}$$

$$P_{max} = V_{ocv}^2 / 4R_{\Omega}$$

Run-time = energy / power

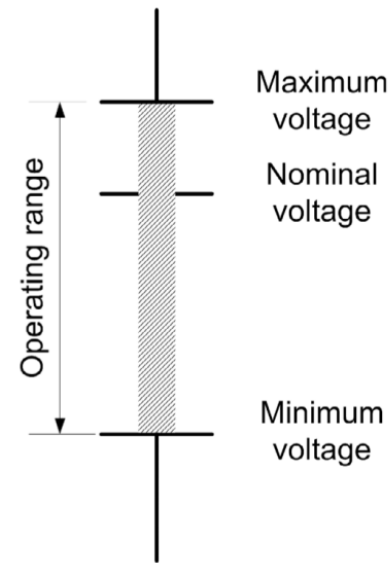


Figure 12.5 Range of operating voltage for electrochemical device.

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An electric vehicle (battery) Specification

e.g. 300 km driving distance

40 kWh battery, Power 90 kW

(Energy density 140 Wh/kg, Power density 250 W/kg)

550 Wh/L

Battery weight 300 kg

Efficiency 7 km/kWh

cf. Gasoline engine: ~800 km, 60~70 *liter* tank, 12 km/*liter*

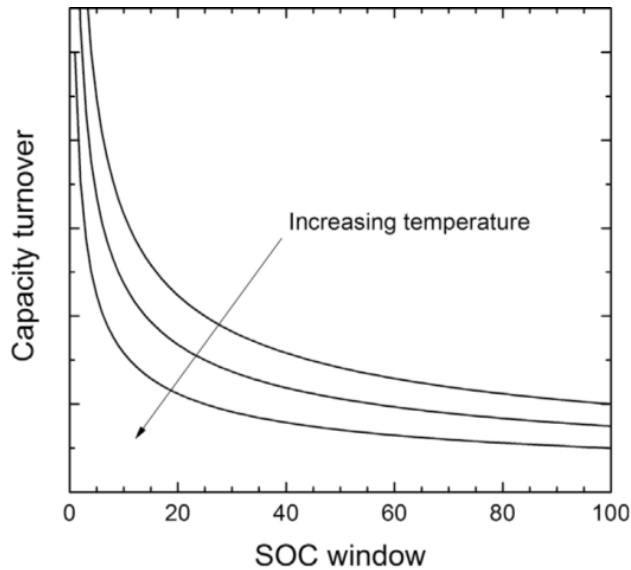


Figure 12.6 Capacity turnover for a hypothetical rechargeable battery.

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Lifetime → capacity turnover

Coulombs passed before the capacity is no longer acceptable

$$CT = \frac{\text{Coulombs passed before the capacity is no longer acceptable}}{\text{Nominal capacity of the battery}}$$

capacity turnover ↓ with SOC window ↑

capacity turnover ↓ with temperature ↑

Ragone plots

-Power and energy are key design aims of an electrochemical system for energy storage and conversion

Power [W, kW], $P_{ave} = (1/t_d) \int IV(t)dt$

specific power [kW/kg],
specific energy [kWh/kg],
power density [kW/L],
energy density [kWh/L]

-Ragone plot:
trade-off between power and energy

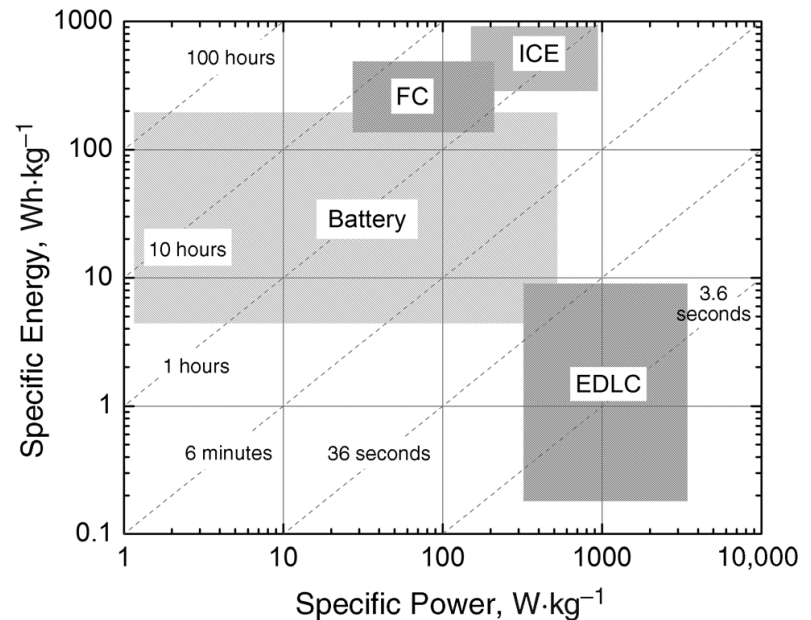


Figure 7.10 Ragone plot illustrating the strengths of different energy storage and conversion devices.

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Hybrid vehicle

Start-stop hybrid: micro-hybrid

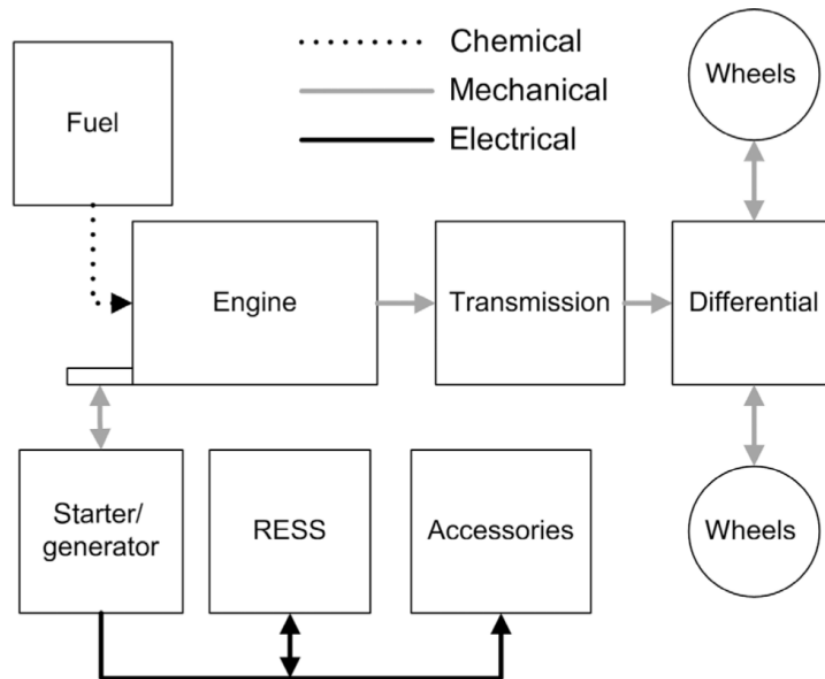


Figure 12.7 Start-stop hybrid.

5~8% fuel efficiency increase

Series hybrid system

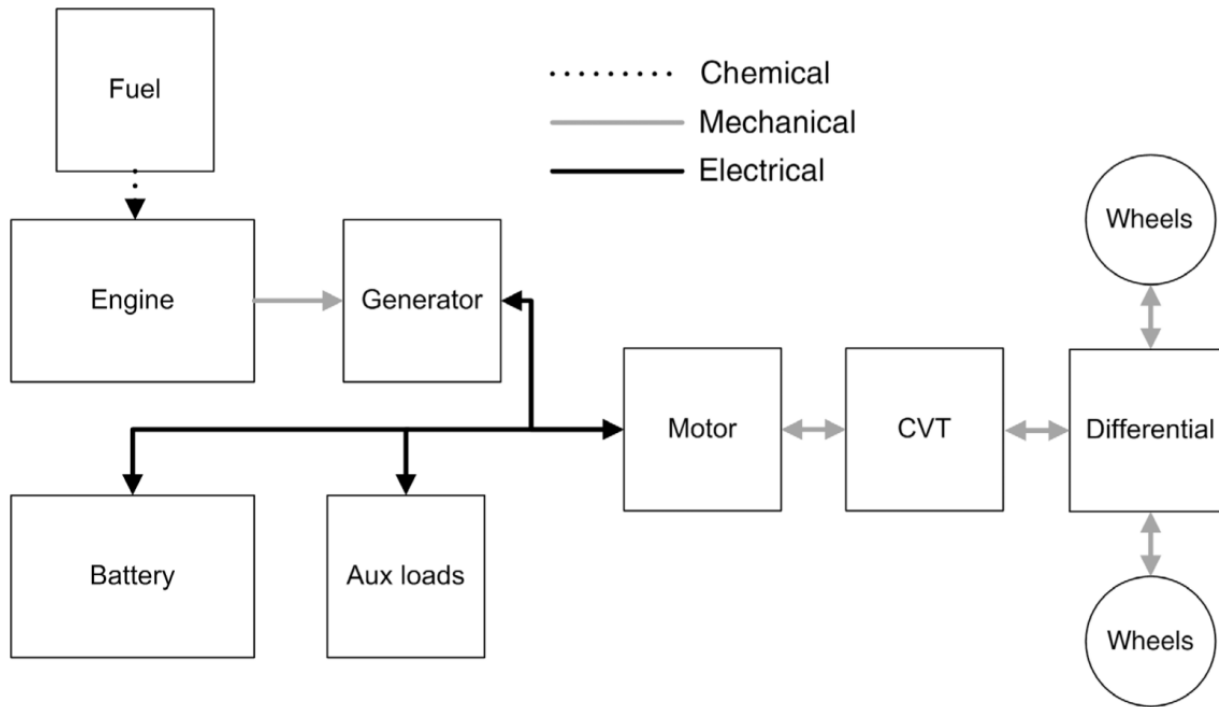


Figure 12.8 Series hybrid system.

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Start-stop hybrid

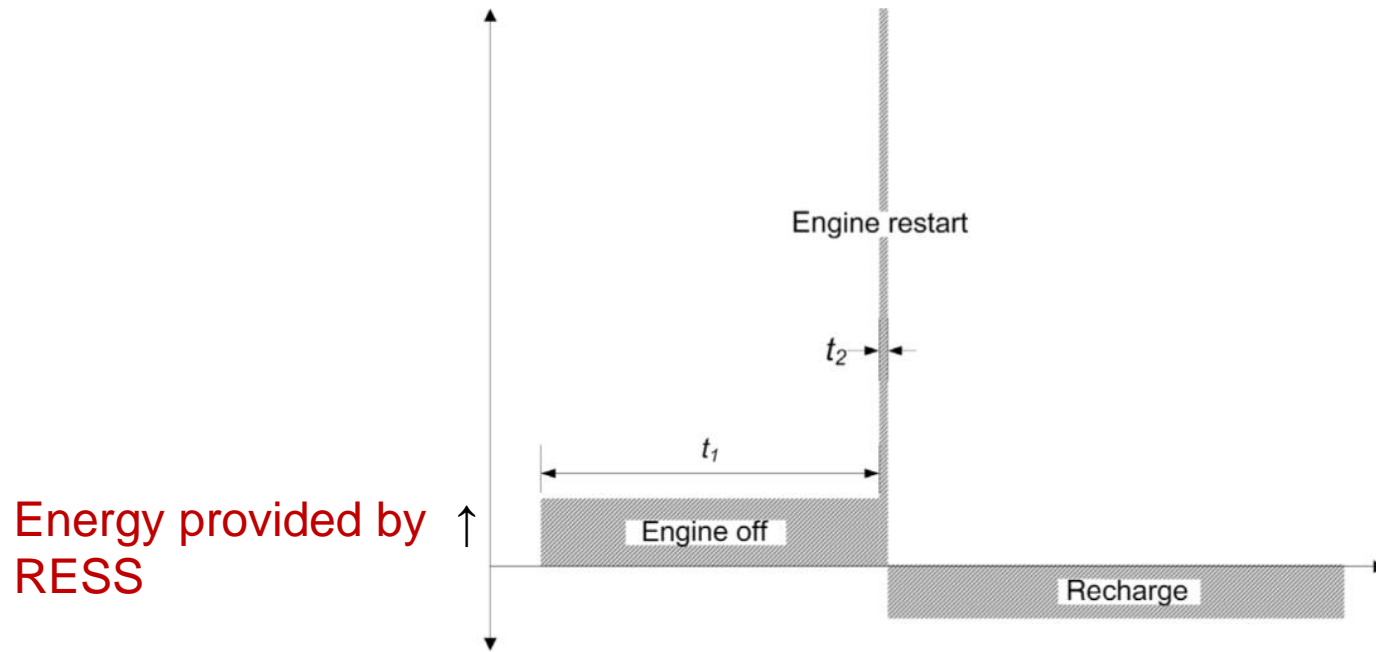


Figure 12.9 Power cycle for a start-stop hybrid.

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$$\text{Useable energy} = (3/4)(1/2CV_{\max}^2) = (3/8)CV_{\max}^2$$

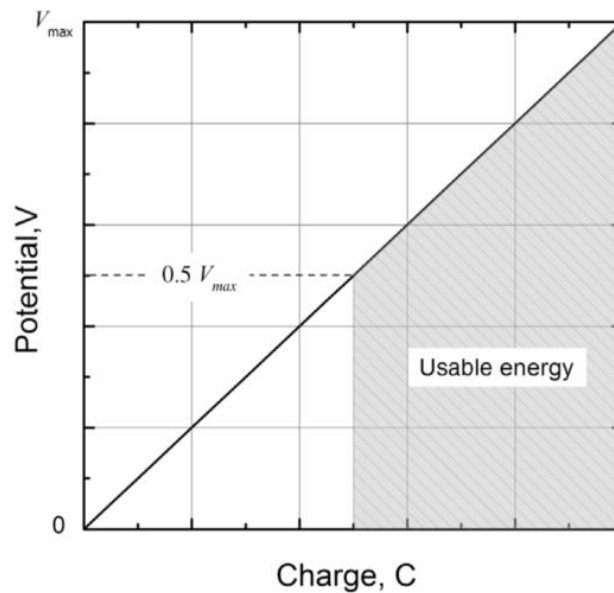


Figure 12.10 Energy for EDLC is equal to the area under the curve. Limiting voltage to half of V_{\max} results in 25% of energy unavailable.

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Batteries for full-hybrid electric vehicles

$$\text{Efficiency of ICE} = \frac{1}{\text{Specific fuel consumption (SFC) (g/kWh)}}$$

SFC is function of engine speed

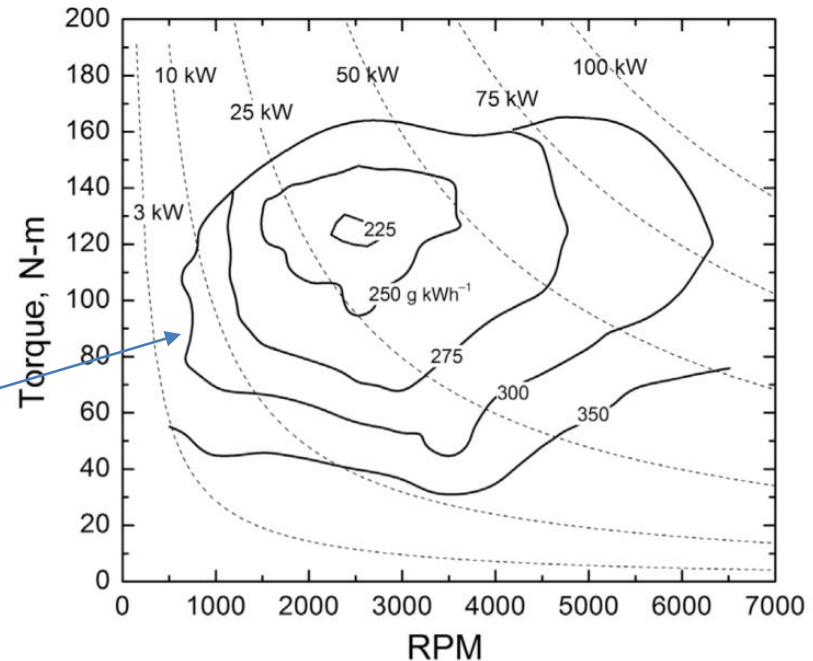


Figure 12.11 Engine map for a 1.9 L spark ignition engine.

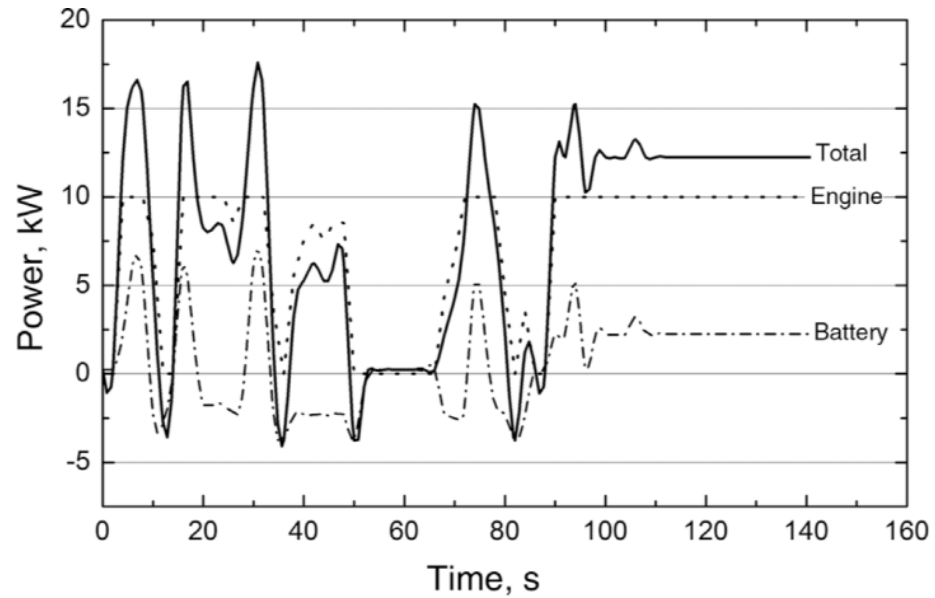


Figure 12.12 Example of power usage for parallel hybrid. Power of RESS (battery) is positive for discharging and negative for charging.

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Charge-sustaining mode

Degree of hybridization (DOH) = battery power / (engine power + battery power)

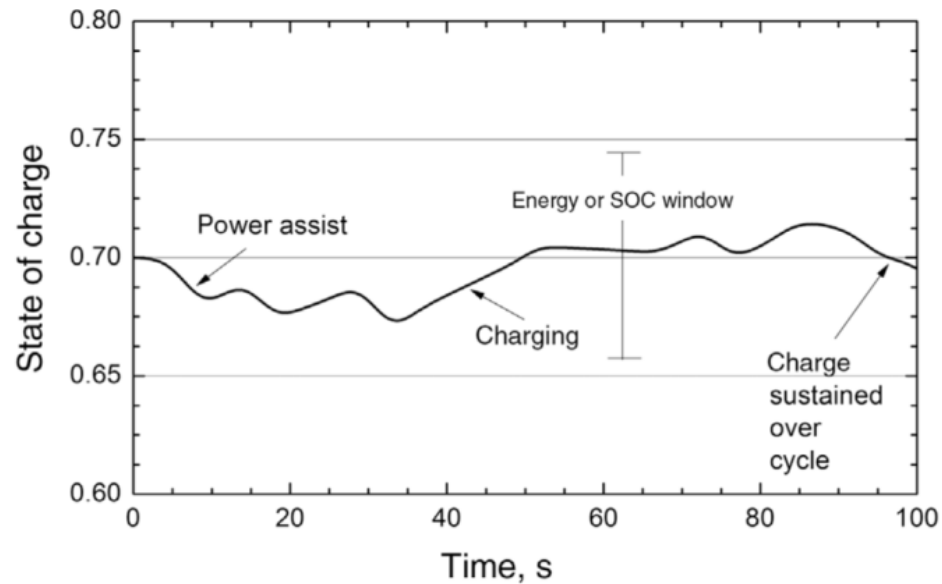


Figure 12.13 Charge-sustaining details. Battery SOC is maintained in a small window.

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Charge-depleting mode

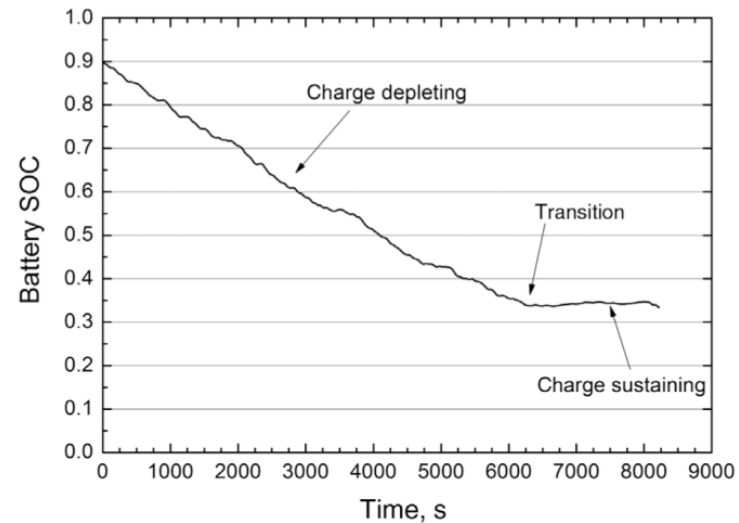


Figure 12.14 Window over which state of charge is varied for a full-hybrid operating in charge depleting mode.

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Table 12.2 Comparison of Batteries for Hybrid and All-Electric Vehicles

	Mild hybrid	Strong hybrid	All electric vehicle
Average power	5 kW	20 kW	20 kW
Energy	0.5 kWh	8 kWh	25 kWh
Run-time	0.1 hours	0.4 hours	1.2 hours

Summary of hybrid designs

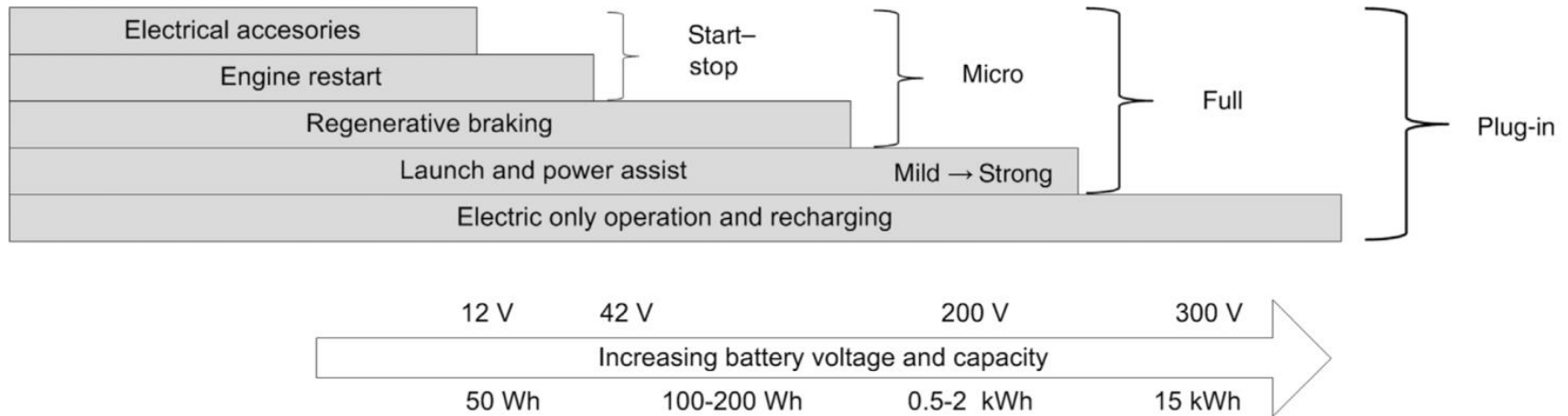


Figure 12.15 Summary of hybrid-electric vehicles. As the degree of hybridization increases, the voltage of the battery and its capacity increase.

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Fuel cell hybrid systems vehicles

System efficiency,

$$\eta_{\text{sys}} = (IV - \text{ancillary power} - \text{electrical loss}) / \text{availability of the fuel}$$

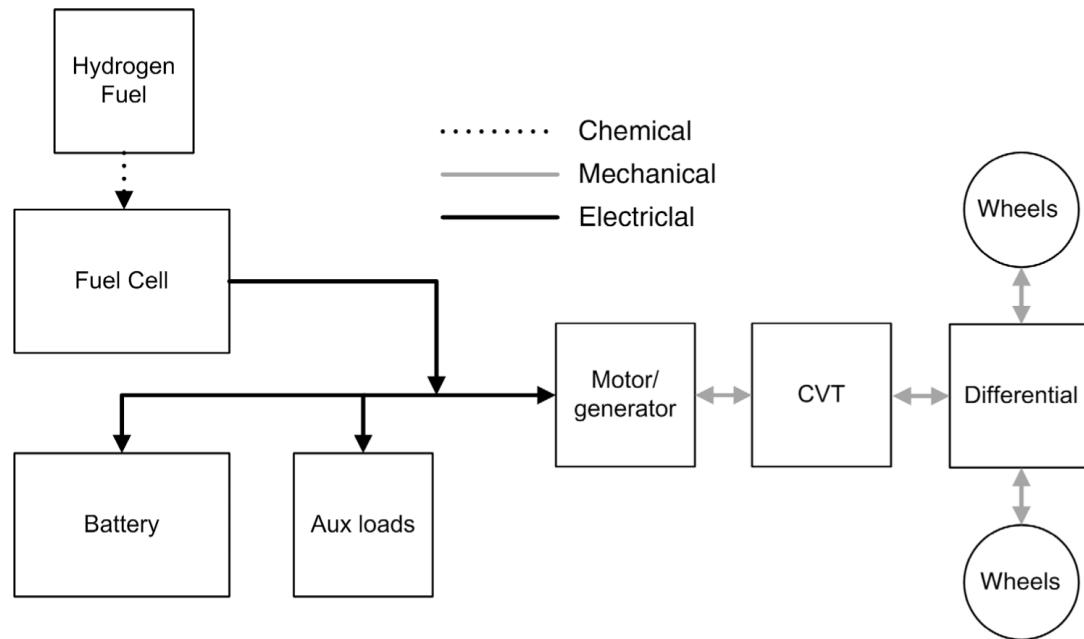


Figure 12.16 Typical architecture for a fuel-cell hybrid system.

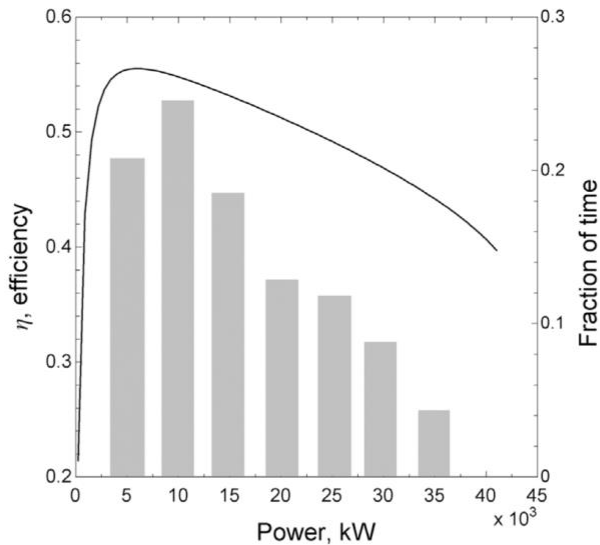


Figure 12.17 Fuel-cell system efficiency (solid line) as a function of fuel-cell power. The bars represent the frequency of time spent at each power level for an example driving schedule.

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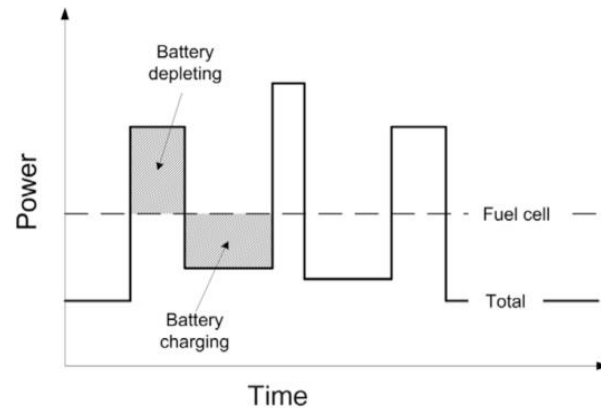


Figure 12.18 Typical method of operating a fuel-cell hybrid. Fuel-cell power is constant.

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Hydrogen fuel cell vehicle 460 km driving distance

Power 113 kW

Power density 3 kW/l, 2kW/kg

FC weight 56 kg + (5 kg H₂ in tank (87 kg))

Efficiency 6 km/kWh



cf. Gasoline engine: ~800 km, 60~70 liter tank, 12 km/liter