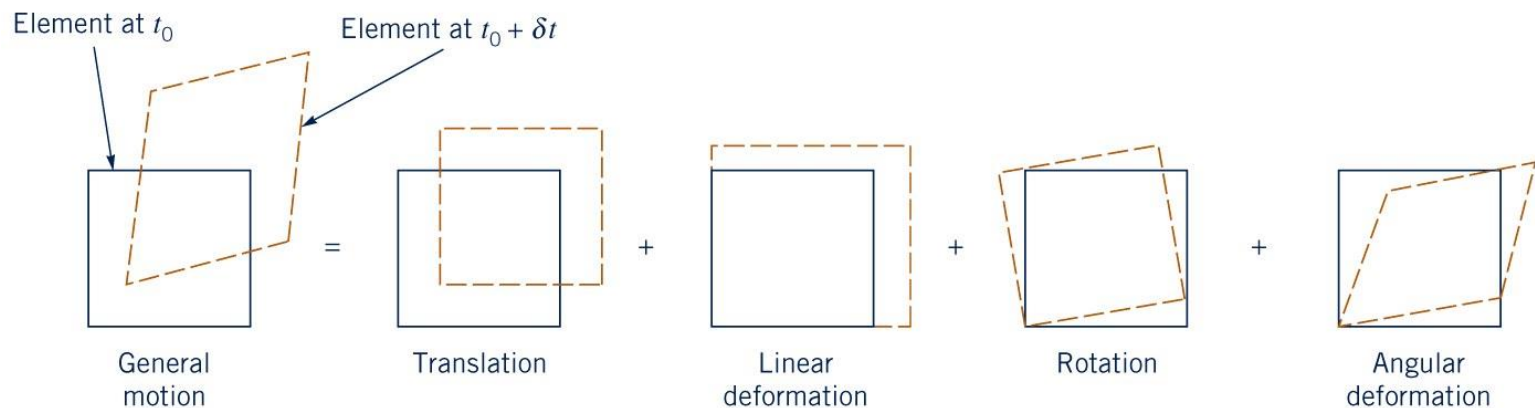


# Lecture 9

## Stress-Strain Relation (2)



# Lecture 9 Stress-Strain Relation (2)

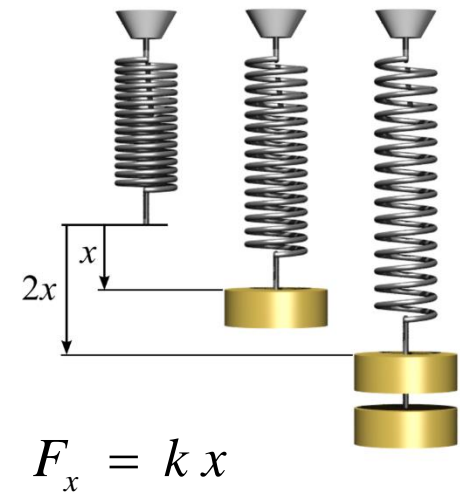
## Contents

9.1 Relations Between Stress and Strain for Elastic Solids

9.2 Relations Between Stress and Rate of Strain for Newtonian Fluids

## Objectives

- Study Hooke's law of stress-strain relations for solid
- Study solid mechanics to deduce stress-rate of strain relations for fluid



# 9.1 Relations between Stress and Strain for Elastic Solids

## 9.1.1 Normal Stresses

Hooke's law: Stress is linear with strain (linear elastic).

$$\sigma_x \propto \varepsilon_x^\circ$$

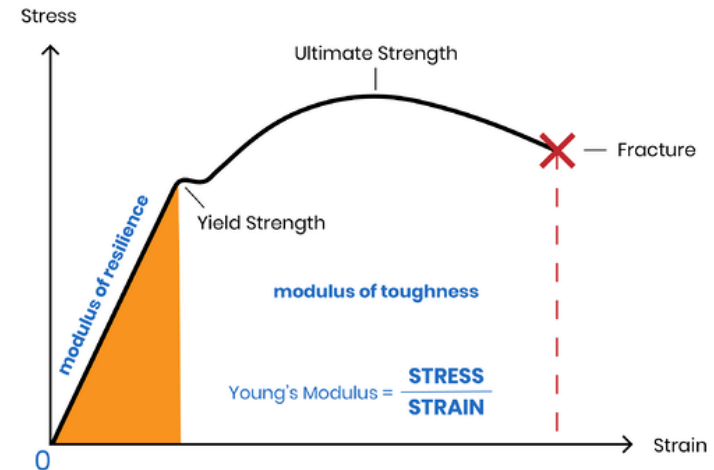
$$\sigma_x = E \varepsilon_x^\circ$$

$$\varepsilon_x^\circ = \frac{1}{E} \sigma_x \quad (9.1a)$$

$$\varepsilon_x = \frac{\partial \xi}{\partial x} \rightarrow \text{non-dimensional}$$

in which  $E =$  Young's modulus of elasticity (N/m<sup>2</sup>) 탄성계수

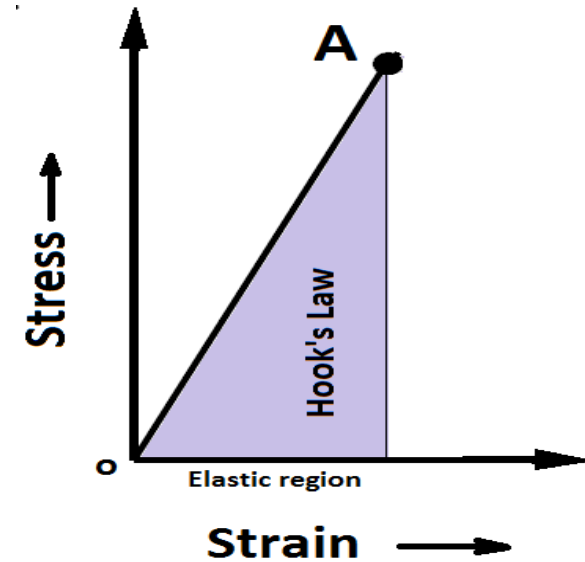
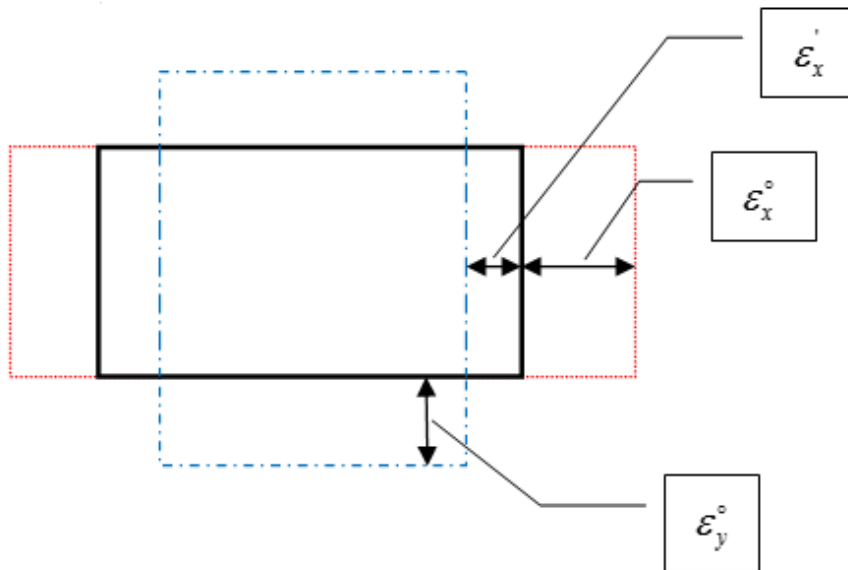
$\varepsilon_x^\circ =$  elongation in the  $x$ - *dir* due to normal stress,  $\sigma_x$



# 9.1 Relations between Stress and Strain for Elastic Solids

$$y - dir. : \varepsilon_y^{\circ} = \frac{\sigma_y}{E} \quad (9.1b)$$

$$z - dir. : \varepsilon_z^{\circ} = \frac{\sigma_z}{E} \quad (9.1c)$$



# 9.1 Relations between Stress and Strain for Elastic Solids

Now, we have to consider other elongations because of lateral contraction of matter under tension for isotropic material.

$\varepsilon_x'$  = elongation in the  $x$ -dir. due to  $\sigma_y$

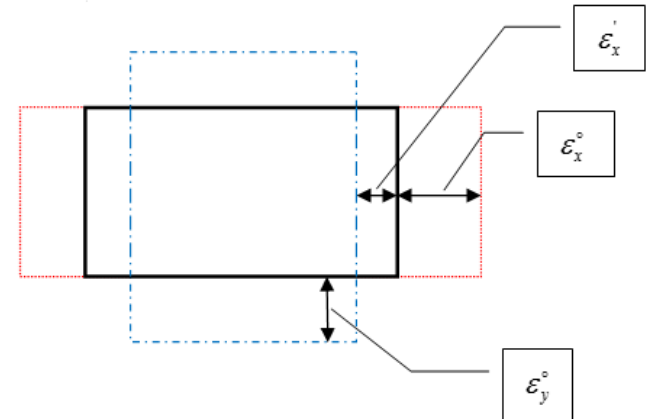
$\varepsilon_x''$  = elongation in the  $x$ -dir. due to  $\sigma_z$

Now, define

$$\varepsilon_x' = -n\varepsilon_y^\circ = -n\frac{\sigma_y}{E} \quad (9.2)$$

$$\varepsilon_x'' = -n\varepsilon_z^\circ = -n\frac{\sigma_z}{E} \quad (9.3)$$

where  $n = \text{Poisson's ratio}$



# 9.1 Relations between Stress and Strain for Elastic Solids

Poisson's ratio:  $\nu = 0 \sim 0.5$

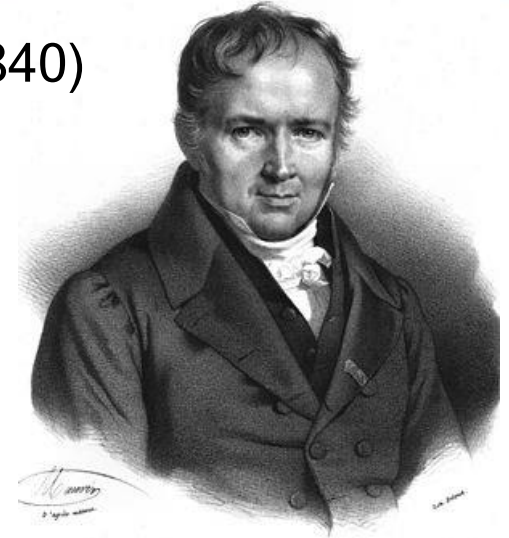
S. D. Poisson (1781~1840)

rubber:  $\sim 0.5$  (비압축성)

metal:  $\sim 0.3$

concrete:  $0.1 \sim 0.2$

cork:  $\sim 0$



# 9.1 Relations between Stress and Strain for Elastic Solids

## [Practical Example]

- Cork in the wine bottle: The cork must be easily inserted and removed, yet it also must withstand the pressure from within the bottle.
- Corrugated rubber: It is used in shoe (sneaker) insoles and in vibration isolators for machinery. Foam ( $n = 0.3$ ) is used in shoes and in wrestling mats.



## 9.1 Relations between Stress and Strain for Elastic Solids

- Generalized Hooke's law

The total strain  $\varepsilon_x$  is given as

$$\varepsilon_x = \varepsilon_x^{\circ} + \varepsilon_x' + \varepsilon_x'' = \frac{\sigma_x}{E} - \frac{n}{E}(\sigma_y + \sigma_z) = \frac{1}{E}[\sigma_x - n(\sigma_y + \sigma_z)] \quad (9.4a)$$

$$\varepsilon_y = \frac{1}{E}[\sigma_y - n(\sigma_z + \sigma_x)] \quad (9.4b)$$

$$\varepsilon_z = \frac{1}{E}[\sigma_z - n(\sigma_x + \sigma_y)] \quad (9.4c)$$



# 9.1 Relations between Stress and Strain for Elastic Solids

## 9.1.2 Shear Stress

~ Hooke's law  $\tau_{xy} = G \gamma_{xy}$

$$\gamma_{xy} = \frac{\tau_{xy}}{G} = \frac{\partial \eta}{\partial x} + \frac{\partial \xi}{\partial y} \quad (9.5a)$$

$$\gamma_{yz} = \frac{\tau_{yz}}{G} = \frac{\partial \zeta}{\partial y} + \frac{\partial \eta}{\partial z} \quad (9.5b)$$

$$\gamma_{zx} = \frac{\tau_{zx}}{G} = \frac{\partial \xi}{\partial z} + \frac{\partial \zeta}{\partial x} \quad (9.5c)$$

## 9.1 Relations between Stress and Strain for Elastic Solids

where  $G =$  **shear modulus of elasticity** (N/m<sup>2</sup>) 전단탄성계수

$$G = \frac{E}{2(1+n)} \quad (9.6)$$

- Most materials resist a change in volume as determined by the Young's modulus  $E$  more than they resist a change in shape, as determined by the shear modulus  $G$ .

$E = 2G$  for  $n = 0.0$  (compressible material)

$E = 3G$  for  $n = 0.5$  (incompressible material)

## 9.1 Relations between Stress and Strain for Elastic Solids

- Volume dilation (dilatation; 팽창)

$$\begin{aligned}
 e = \varepsilon_x + \varepsilon_y + \varepsilon_z &= \frac{1}{E} \left[ \sigma_x - n(\sigma_y + \sigma_z) \right] \\
 &\quad + \frac{1}{E} \left[ \sigma_y - n(\sigma_z + \sigma_x) \right] \\
 &\quad + \frac{1}{E} \left[ \sigma_z - n(\sigma_x + \sigma_y) \right] \\
 e &= \frac{1}{E} \left[ (1 - 2n)(\sigma_x + \sigma_y + \sigma_z) \right] \tag{9.7}
 \end{aligned}$$

$$e = \nabla \cdot \vec{\delta} = \nabla \cdot (\xi \vec{i} + \eta \vec{j} + \zeta \vec{k}) = \frac{\partial \xi}{\partial x} + \frac{\partial \eta}{\partial y} + \frac{\partial \zeta}{\partial z}$$

# 9.1 Relations between Stress and Strain for Elastic Solids

- $\bar{\sigma}$  = arithmetic mean of 3 normal stresses

$$\bar{\sigma} = \frac{1}{3}(\sigma_x + \sigma_y + \sigma_z) \quad (9.8)$$

Combine Eqs. (9.4), (9.6) and (9.7)

$$\sigma_x = 2G \left[ \varepsilon_x + \frac{ne}{1-2n} \right] \quad (9.9)$$

# 9.1 Relations between Stress and Strain for Elastic Solids

Therefore

$$\begin{aligned}\sigma_x - \bar{\sigma} &= 2G \left( \varepsilon_x - \frac{e}{3} \right) \\ \sigma_y - \bar{\sigma} &= 2G \left( \varepsilon_y - \frac{e}{3} \right) \\ \sigma_z - \bar{\sigma} &= 2G \left( \varepsilon_z - \frac{e}{3} \right)\end{aligned}\tag{9.10}$$

$$\tau_{xy} = \tau_{yx} = G \left( \frac{\partial \eta}{\partial x} + \frac{\partial \xi}{\partial y} \right)$$

## 9.1 Relations between Stress and Strain for Elastic Solids

$$\begin{aligned}\tau_{zy} = \tau_{yz} &= G \left( \frac{\partial \zeta}{\partial y} + \frac{\partial \eta}{\partial z} \right) \\ \tau_{xz} = \tau_{zx} &= G \left( \frac{\partial \xi}{\partial z} + \frac{\partial \zeta}{\partial x} \right)\end{aligned}\quad (9.11)$$

[Proof] Derivation of Eqs. (9.9) & (9.10)

$$(9.7) \rightarrow e = \frac{1}{E} (1 - 2n) (\sigma_x + \sigma_y + \sigma_z) \quad (A)$$

$$(9.4) \rightarrow \varepsilon_x = \frac{1}{E} \left[ \sigma_x - n (\sigma_y + \sigma_z) \right] \quad (B)$$

$$(9.6) \rightarrow G = \frac{E}{2(1+n)} \rightarrow E = 2G(1+n) \quad (C)$$

## 9.1 Relations between Stress and Strain for Elastic Solids

i) Combine (A) and (B)

$$+ \left\{ \begin{aligned} \frac{n}{(1-2n)} \times e &= \frac{n}{(1-2n)} \frac{(1-2n)}{E} (\sigma_x + \sigma_y + \sigma_z) = \frac{n}{E} (\sigma_x + \sigma_y + \sigma_z) \\ \varepsilon_x &= \frac{1}{E} [\sigma_x - n(\sigma_y + \sigma_z)] \end{aligned} \right.$$

$$\frac{n}{(1-2n)} e + \varepsilon_x = \frac{1+n}{E} \sigma_x \quad G = \frac{E}{2(1+n)}$$

$$\therefore \sigma_x = \frac{E}{1+n} \left[ \varepsilon_x + \frac{n}{(1-2n)} e \right] \quad (D)$$

## 9.1 Relations between Stress and Strain for Elastic Solids

Substitute (C) into (D)

$$\therefore \sigma_x = 2G \left[ \varepsilon_x + \frac{n}{(1-2n)} e \right] \quad \rightarrow \quad \text{Eq. (9.9)}$$

ii) Subtract (9.8) from (9.9)

$$\sigma_x - \bar{\sigma} = 2G \left[ \varepsilon_x + \frac{n}{(1-2n)} e \right] - \frac{1}{3} (\sigma_x + \sigma_y + \sigma_z) \quad (\text{E})$$

Substitute (A) into (E); (A):  $\sigma_x + \sigma_y + \sigma_z = \frac{E}{(1-2n)} e$



## 9.1 Relations between Stress and Strain for Elastic Solids

$$\begin{aligned}
 \therefore \text{RHS of } (E) &= 2G \left[ \varepsilon_x + \frac{n}{(1-2n)} e \right] - \frac{1}{3} \frac{E}{(1-2n)} e \\
 &= 2G \varepsilon_x + \left[ \frac{2Gn}{(1-2n)} - \frac{1}{3} \frac{2G(1+n)}{(1-2n)} \right] e = 2G \left\{ \varepsilon_x \left[ \frac{n}{(1-2n)} - \frac{1+n}{3} \right] e \right\} \\
 &= 2G \left\{ \varepsilon_x + \frac{-\frac{1}{3}(1-2n)}{(1-2n)} e \right\} = 2G \left( \varepsilon_x - \frac{1}{3} e \right) \quad \rightarrow \text{Eq. (9.10)}
 \end{aligned}$$

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

Experimental evidence suggests that, in fluid, stress is linear with time rate of strain.

$$\rightarrow stress \propto \frac{\partial}{\partial t}(strain)$$

→ Newtonian fluid (**Newton's law of viscosity**)

[Cf] For solid,

$$stress \propto strain$$

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

### 9.2.1 Normal stress

For solid, Eq. (9.10) can be used as

$$\text{Hookeian elastic solid: } \sigma_x - \bar{\sigma} = 2 \left( \frac{F}{L^2} \right) \left( \varepsilon_x - \frac{e}{3} \right)$$

Non-dimensional

$G$

By analogy,

$$\text{Newtonian fluid: } \sigma_x - \bar{\sigma} = 2 \left( \frac{Ft}{L^2} \right) \frac{\partial}{\partial t} \left( \varepsilon_x - \frac{e}{3} \right) \quad (9.12)$$

Now set  $\mu \equiv \frac{Ft}{L^2} = \text{dynamic viscosity (N}\cdot\text{s/m}^2\text{)}$

Time rate of strain [1/t]

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

Then,

$$\sigma_x - \bar{\sigma} = 2\mu \frac{\partial \varepsilon_x}{\partial t} - \frac{2}{3}\mu \frac{\partial e}{\partial t} \quad (9.13)$$

By the way,

$$\varepsilon_x = \frac{\partial \xi}{\partial x}, \quad e = \nabla \cdot \vec{\delta}$$

$$u = \frac{\partial \xi}{\partial t}, \quad v = \frac{\partial \eta}{\partial x}, \quad w = \frac{\partial \zeta}{\partial t} \quad (\xi, \eta, \zeta = \text{displacement})$$

Therefore,

$$\frac{\partial \varepsilon_x}{\partial t} = \frac{\partial}{\partial t} \left( \frac{\partial \xi}{\partial x} \right) = \frac{\partial}{\partial x} \left( \frac{\partial \xi}{\partial t} \right) = \frac{\partial u}{\partial x} \quad (9.14)$$

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

$$\frac{\partial e}{\partial t} = \nabla \cdot \frac{\partial \vec{\delta}}{\partial t} = \nabla \cdot \vec{q} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \quad (9.15)$$

$$\begin{aligned} \vec{\delta} &= \xi \vec{i} + \eta \vec{j} + \zeta \vec{k} \\ \vec{q} &= \frac{\partial \vec{\delta}}{\partial t} = u \vec{i} + v \vec{j} + w \vec{k} \\ \nabla \cdot \vec{q} &= \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \end{aligned}$$

Eq. (9.13) becomes

$$\sigma_x = \bar{\sigma} + 2\mu \frac{\partial u}{\partial x} - \frac{2}{3}\mu (\nabla \cdot \vec{q})$$

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

For compressible fluid,

$$\sigma_x = \bar{\sigma} + 2\mu \frac{\partial u}{\partial x} - \frac{2}{3}\mu(\nabla \cdot \vec{q})$$

$$\sigma_y = \bar{\sigma} + 2\mu \frac{\partial v}{\partial y} - \frac{2}{3}\mu(\nabla \cdot \vec{q})$$

$$\sigma_z = \bar{\sigma} + 2\mu \frac{\partial w}{\partial z} - \frac{2}{3}\mu(\nabla \cdot \vec{q})$$

(9.16)

For incompressible fluid,

$$\frac{de}{dt} = \nabla \cdot \vec{q} = 0 \quad \leftarrow \text{time rate of volume expansion}=0$$

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

$$\rightarrow \nabla \cdot \vec{q} = 0 \quad \rightarrow \text{Continuity Eq.}$$

Therefore, Eq. (9.16) becomes

$$\sigma_x = \bar{\sigma} + 2\mu \frac{\partial u}{\partial x}$$

$$\sigma_y = \bar{\sigma} + 2\mu \frac{\partial v}{\partial y}$$

$$\sigma_z = \bar{\sigma} + 2\mu \frac{\partial w}{\partial z}$$

(9.17)

## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

- Relation between thermodynamic pressure  $p$  and mean normal stress  $\bar{\sigma}$

1) Assume viscous effects are completely represented by the viscosity  $\mu$  for incompressible fluid

$$\bar{\sigma} = -p = \frac{1}{3}(\sigma_x + \sigma_y + \sigma_z) \quad (9.18)$$

~ minus sign accounts for pressure (compression)

2) For compressible fluid

$$\bar{\sigma} = -p + \mu'(\nabla \cdot \vec{q}) \quad (9.19)$$

in which  $\mu' =$  **2nd coefficient of viscosity** associated solely with dilation  
= bulk viscosity



## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

Since, dilation effect is small for most cases

$$\nabla \cdot \vec{q} \rightarrow 0 \quad \therefore \bar{\sigma} = -p \quad (9.20)$$

For zero-dilation effects, (9.16) becomes

$$\begin{aligned} \sigma_x &= -p + 2\mu \frac{\partial u}{\partial x} - \frac{2}{3}\mu(\nabla \cdot \vec{q}) \\ \sigma_y &= -p + 2\mu \frac{\partial v}{\partial y} - \frac{2}{3}\mu(\nabla \cdot \vec{q}) \\ \sigma_z &= -p + 2\mu \frac{\partial w}{\partial z} - \frac{2}{3}\mu(\nabla \cdot \vec{q}) \end{aligned} \quad (9.21)$$

Normal stress

pressure

Viscous effects

# 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

## 9.2.2. Shear stress

By following the same analogy

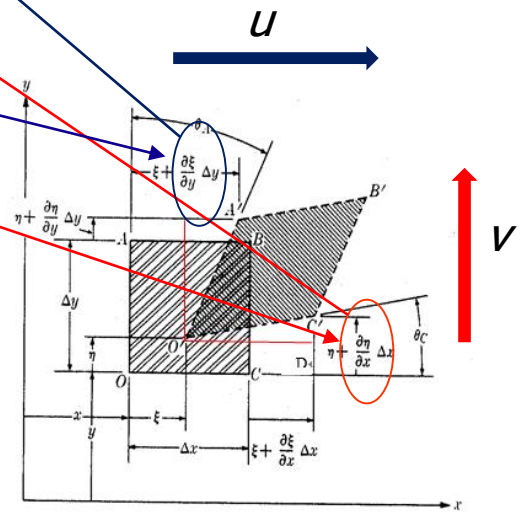
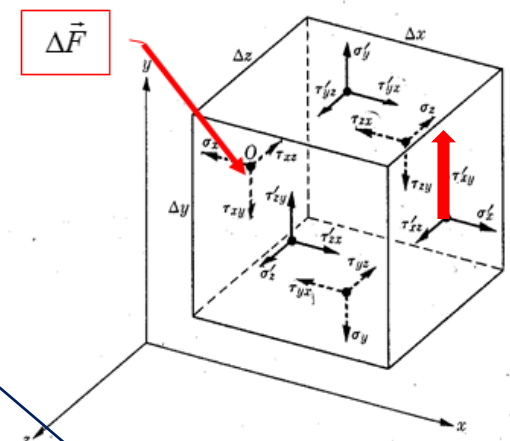
$\mu$

$$\tau_{xy} = G \left( \frac{\partial \eta}{\partial x} + \frac{\partial \xi}{\partial y} \right) = \left( \frac{Ft}{L^2} \right) \frac{\partial}{\partial t} \left( \frac{\partial \eta}{\partial x} + \frac{\partial \xi}{\partial y} \right)$$

$$= \mu \frac{\partial}{\partial x} \left( \frac{\partial \eta}{\partial t} \right) + \mu \frac{\partial}{\partial y} \left( \frac{\partial \xi}{\partial t} \right) = \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$

$$\frac{\partial \eta}{\partial t} = v$$

$$\frac{\partial \xi}{\partial t} = u$$



## 9.2 Relations between Stress and Rate of Strain for Newtonian Fluids

### ■ Shear stresses in a real fluid

$$\tau_{xy} = \tau_{yx} = \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$

$$\tau_{yz} = \tau_{zy} = \mu \left( \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right)$$

$$\tau_{xz} = \tau_{zx} = \mu \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)$$

(9.22)

For zero viscous effects ( $\mu = 0$ ) → ideal fluids in motion and for all fluids at rest

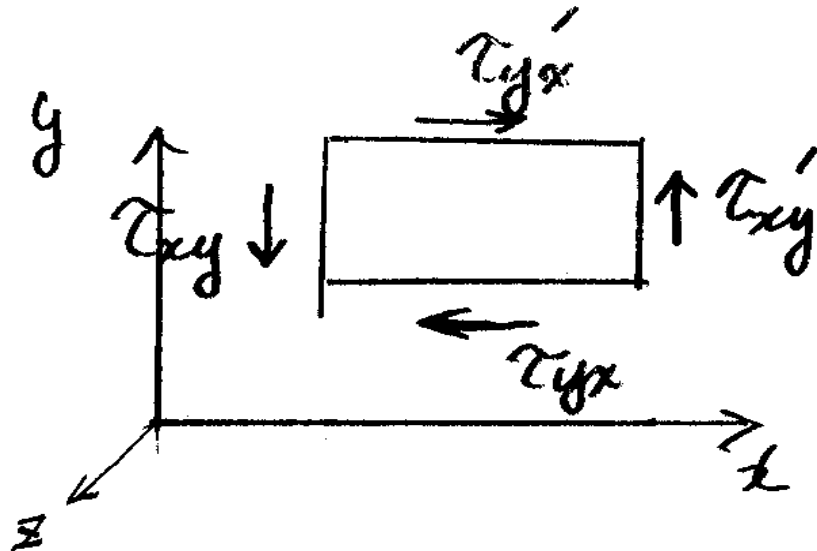
$$\sigma_x = \sigma_y = \sigma_z = \bar{\sigma} = -p$$

$$\tau_{xy} = \tau_{yz} = \tau_{zx} = 0$$

# Appendix

## [Appendix 1]

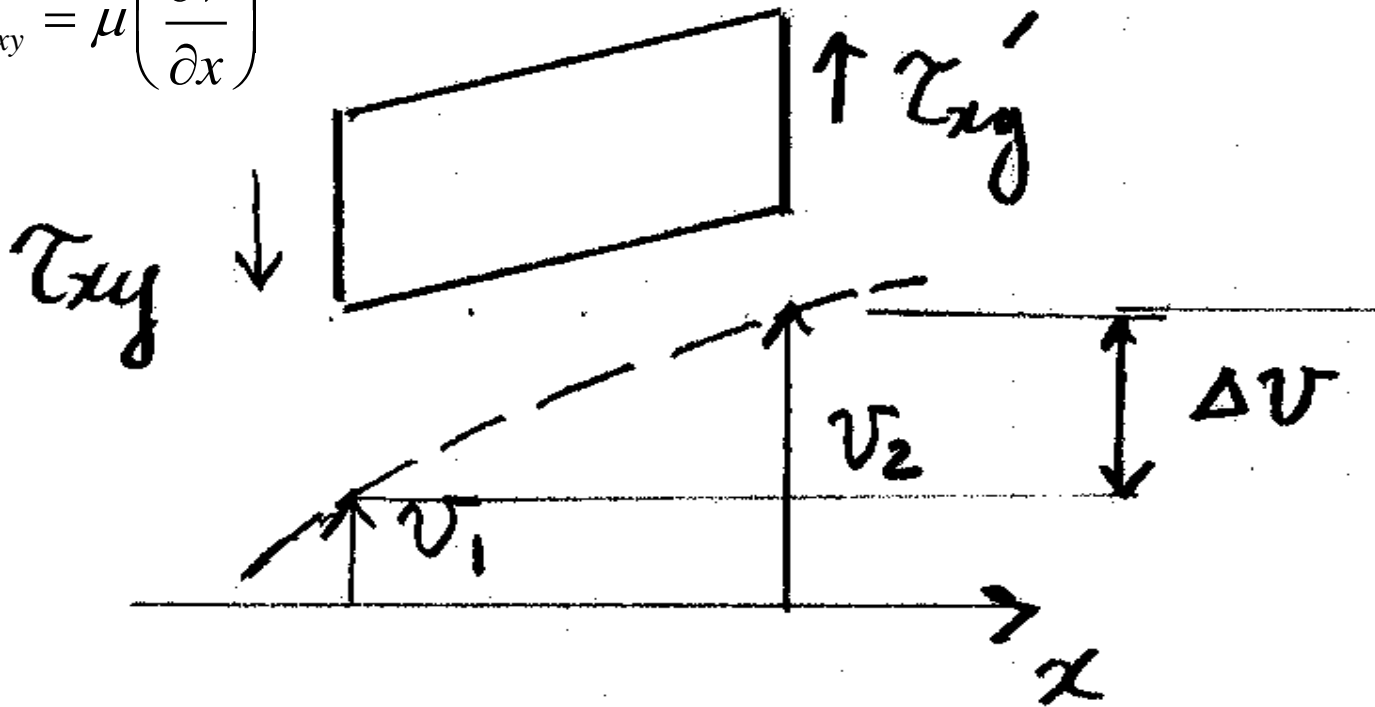
$$\tau_{xy} = \tau_{yx} = \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$



# Appendix

i)  $\tau_{xy}, \tau_{xy}'$

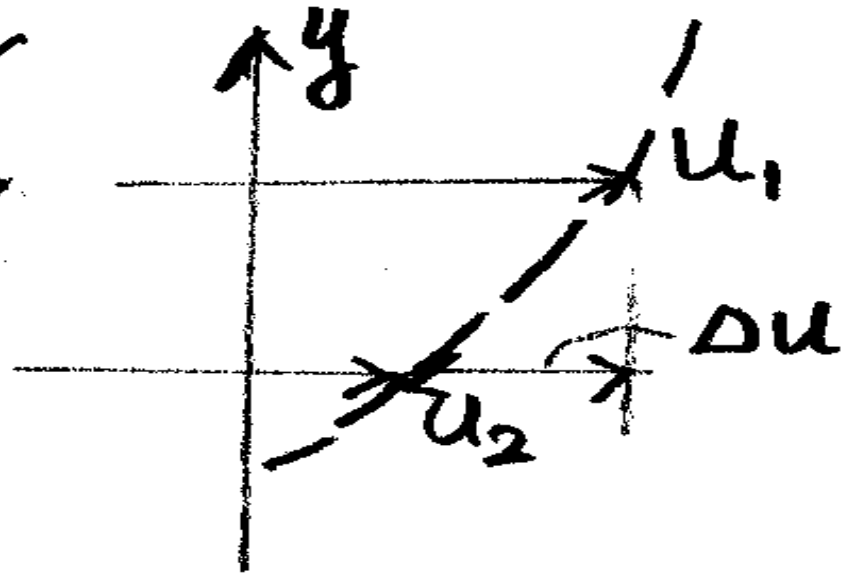
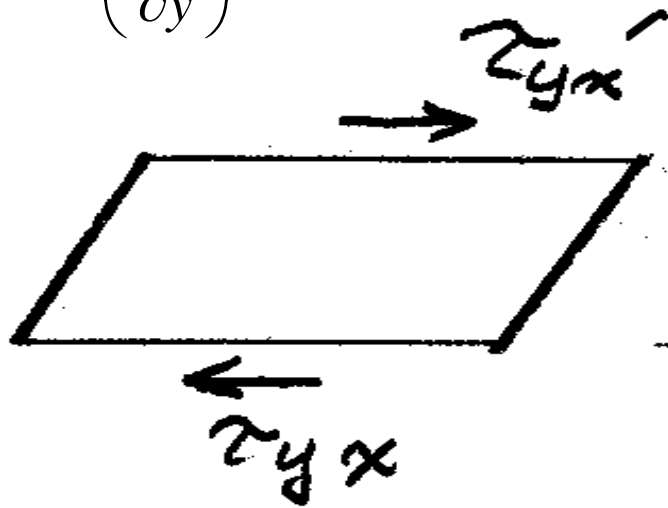
$$\tau_{xy} = \mu \left( \frac{\partial v}{\partial x} \right)$$



# Appendix

ii)  $\tau_{yx}, \tau'_{yx}$

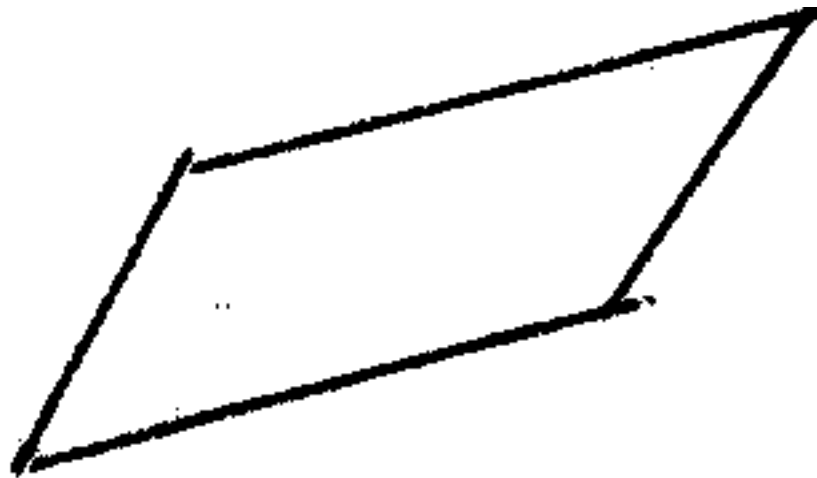
$$\tau_{yx} = \mu \left( \frac{\partial u}{\partial y} \right)$$



# Appendix

iii) composition

$$\tau_{xy} = \tau_{yx} = \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$



# Problems

## Homework Assignment # 4

Due: 1 week from today

1. Consider a fluid element under a general state of stress as illustrated in Fig. 5-1 (Daily & Harleman, 1966). Given that the element is in a gravity field, show that the equilibrium requirement between surface, body and inertial forces leads to the equations

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho g_x = \rho a_x$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho g_y = \rho a_y$$

$$\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_z}{\partial z} + \rho g_z = \rho a_z$$



# Problems

2. Prove the equation given below:

$$G = \frac{E}{2(1+n)}$$