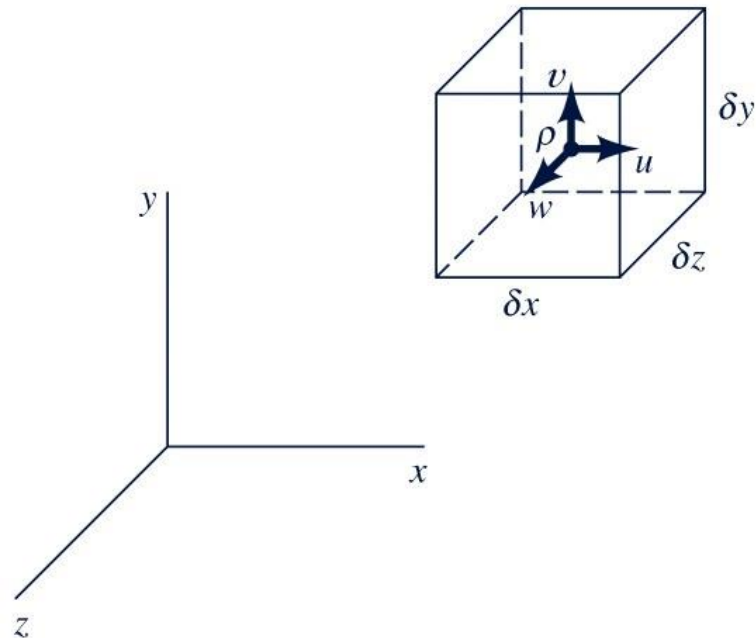


Lecture 11

Equations of Continuity and Motion (2/6)



Lecture 11 Equations of Continuity and Motion (2)

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11.1 Equations of Motion

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Objectives

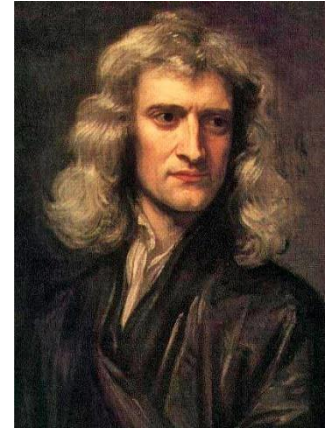
- Derive 3D equations of motion
- Derive Navier-Stokes equation for Newtonian fluid

11.1 Equations of Motion

- Apply Newton's 2nd law of motion

$$\sum \vec{F} = m\vec{a}$$

$$\Delta F_x = \Delta m a_x \quad (A)$$

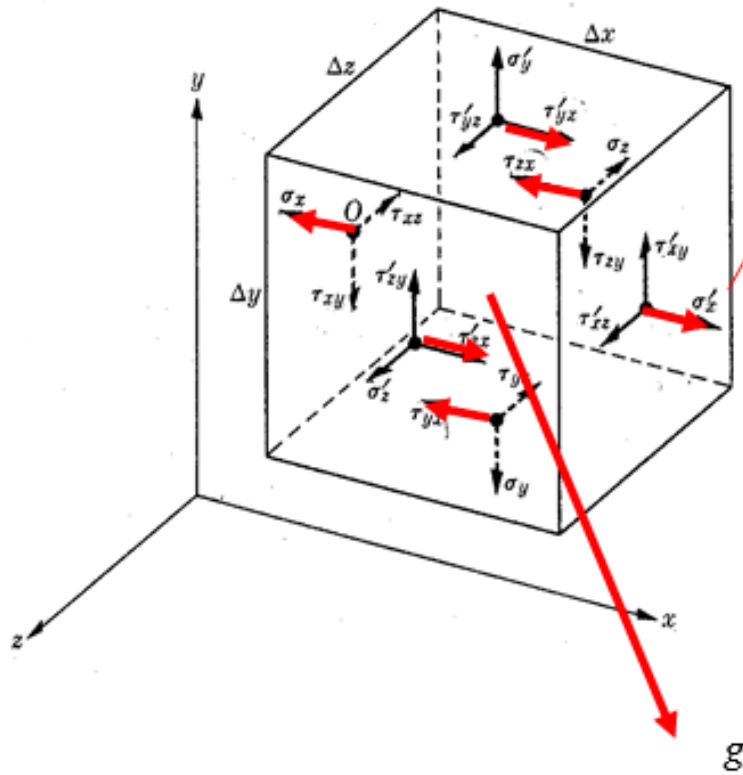


I. Newton (1643~1727)

- External forces = surface force + body force
 - Surface force:
 - ~ normal force + tangential force
 - Body forces:
 - ~ due to gravitational or electromagnetic fields, no contact
 - ~ act at the centroid of the element → centroidal force

11.1 Equations of Motion

STRESS-STRAIN RELATIONS



$$\sigma_x + \frac{\partial \sigma_x}{\partial x} \Delta x$$

11.1 Equations of Motion

Consider only gravitational force

$$\vec{g} = \vec{i}g_x + \vec{j}g_y + \vec{k}g_z$$

LHS of (A):

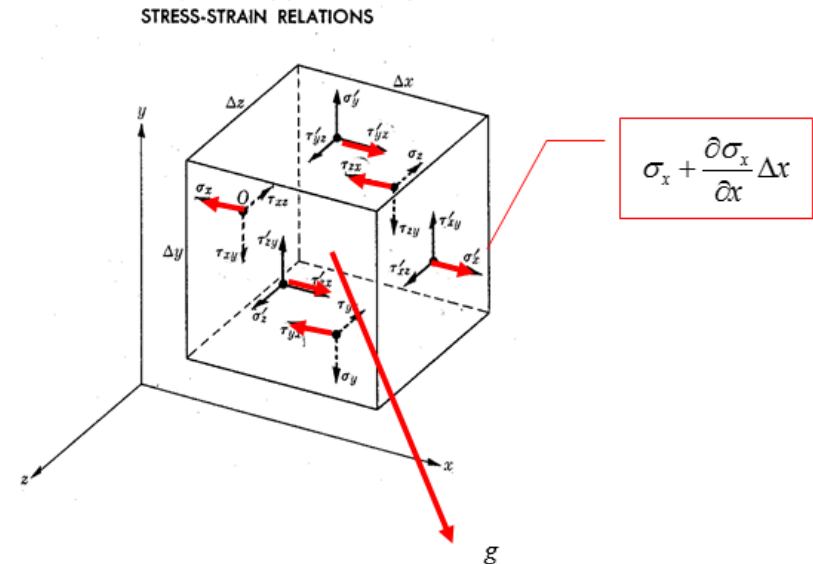
$$\Delta F_x = (\rho \Delta x \Delta y \Delta z) g_x$$

$$-\sigma_x \Delta y \Delta z + \left(\sigma_x + \frac{\partial \sigma_x}{\partial x} \Delta x \right) \Delta y \Delta z$$

$$-\tau_{yx} \Delta x \Delta z + \left(\tau_{yx} + \frac{\partial \tau_{yx}}{\partial y} \Delta y \right) \Delta x \Delta z$$

$$-\tau_{zx} \Delta x \Delta y + \left(\tau_{zx} + \frac{\partial \tau_{zx}}{\partial z} \Delta z \right) \Delta x \Delta y$$

(B)



11.1 Equations of Motion

Divide (B) by volume of element

$$\frac{\Delta F_x}{\Delta x \Delta y \Delta z} = \rho g_x + \frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \quad (C)$$

RHS of (A):

$$\frac{\Delta m a_x}{\Delta x \Delta y \Delta z} = \rho a_x \quad (D)$$

11.1 Equations of Motion

Combine (C) and (D)

$$\rho g_x + \frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} = \rho a_x$$

$$\rho g_y + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} = \rho a_y$$

$$\rho g_z + \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_z}{\partial z} = \rho a_z$$

(11.1)

→ A general equation of motion containing 9 unknowns (6+3)

11.2 Navier-Stokes Equations

11.2.1 3D Navier-Stokes equations

- Eq (11.1) ~ general equation of motion containing 9 unknowns
- For **Newtonian fluids** (with single viscosity coeff.), use stress-strain relation given in (9.21) and (9.22) to reduce the number of unknowns
→ **Navier-Stokes equations**

Eq. (9.21a):

$$\sigma_x = \underline{-p} + \underline{2\mu \frac{\partial u}{\partial x} - \left(\frac{2}{3}\right)\mu(\nabla \cdot \vec{q})}$$

pressure normal stress due to fluid deformation and viscosity

11.2 Navier-Stokes Equations

$$\sigma_y = -p + 2\mu \frac{\partial v}{\partial y} - \left(\frac{2}{3}\right)\mu(\nabla \cdot \vec{q}) \quad (11.2)$$

$$\sigma_z = -p + 2\mu \frac{\partial w}{\partial z} - \left(\frac{2}{3}\right)\mu(\nabla \cdot \vec{q})$$

From Eq. (9.22):

$$\tau_{yx} = \tau_{xy} = \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$

$$\tau_{yz} = \tau_{zy} = \mu \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \right) \quad (11.3)$$

$$\tau_{zx} = \tau_{xz} = \mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)$$

11.2 Navier-Stokes Equations

Substitute Eqs. (11.2) & (11.3) into (11.1)

$$\rho g_x - \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left[2\mu \frac{\partial u}{\partial x} - \frac{2}{3} \mu (\nabla \cdot \vec{q}) \right] + \frac{\partial}{\partial y} \left[\mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial z} \left[\mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right] = \rho a_x$$

Assume constant viscosity (neglect effect of pressure and temperature on viscosity variation)

$$\rho g_x - \frac{\partial p}{\partial x} + \mu \frac{\partial}{\partial x} \left[2 \frac{\partial u}{\partial x} - \frac{2}{3} (\nabla \cdot \vec{q}) \right] + \mu \frac{\partial}{\partial y} \left[\left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \mu \frac{\partial}{\partial z} \left[\left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \right] = \rho a_x$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

11.2 Navier-Stokes Equations

Expand and simplify

normal stress

shear stress

$$L.H.S = \rho g_x - \frac{\partial p}{\partial x} + 2\mu \frac{\partial^2 u}{\partial x^2} - \frac{2}{3} \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + \mu \left(\frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial x \partial z} \right)$$

$$= \rho g_x - \frac{\partial p}{\partial x} + \mu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] + \frac{1}{3} \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right)$$

$$= \rho g_x - \frac{\partial p}{\partial x} + \mu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] + \frac{1}{3} \mu \frac{\partial}{\partial x} (\nabla \cdot \vec{q})$$

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

normal stress + shear stress

11.2 Navier-Stokes Equations

$$\rho g_x - \frac{\partial p}{\partial x} + \mu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] + \frac{1}{3} \mu \frac{\partial}{\partial x} (\nabla \cdot \vec{q}) = \rho a_x$$

$$\rho g_y - \frac{\partial p}{\partial y} + \mu \left[\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right] + \frac{1}{3} \mu \frac{\partial}{\partial y} (\nabla \cdot \vec{q}) = \rho a_y$$

$$\rho g_z - \frac{\partial p}{\partial z} + \mu \left[\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right] + \frac{1}{3} \mu \frac{\partial}{\partial z} (\nabla \cdot \vec{q}) = \rho a_z \quad (11.4)$$

→ Navier-Stokes equation for compressible fluids with constant viscosity

11.2 Navier-Stokes Equations

◆ Vector form

$$\rho \vec{g} - \nabla p + \mu \nabla^2 \vec{q} + \frac{\mu}{3} \nabla (\nabla \cdot \vec{q}) = \rho \frac{\partial \vec{q}}{\partial t} + \rho (\vec{q} \cdot \nabla) \vec{q} \quad (11.5)$$

where $\vec{a} = \frac{d\vec{q}}{dt} = \frac{\partial \vec{q}}{\partial t} + (\vec{q} \cdot \nabla) \vec{q}$

1) For **inviscid (ideal)** fluid flow, ($\mu = 0$) \rightarrow viscous forces are neglected.

$$\rho \vec{g} - \nabla p = \rho \frac{\partial \vec{q}}{\partial t} + \rho (\vec{q} \cdot \nabla) \vec{q}$$

\rightarrow **Euler equations for ideal fluid**

11.2 Navier-Stokes Equations

2) For incompressible fluids, $\nabla \cdot \vec{q} = 0$ (Continuity Eq.)

$$\rho \vec{g} - \nabla p + \mu \nabla^2 \vec{q} = \rho \frac{\partial \vec{q}}{\partial t} + \rho (\vec{q} \cdot \nabla) \vec{q} \quad (11.6)$$

Define acceleration due to gravity as

$$\left. \begin{aligned} g_x &= -g \frac{\partial h}{\partial x} \\ g_y &= -g \frac{\partial h}{\partial y} \\ g_z &= -g \frac{\partial h}{\partial z} \end{aligned} \right\} \vec{g} = -g \nabla h$$

11.2 Navier-Stokes Equations

where h = vertical direction measured positive upward

For Cartesian axes oriented so that h and z coincide

$$g_x = g_y = 0 \quad , \quad \frac{\partial h}{\partial z} = 1 \quad (11.7)$$

$$g_z = -g$$

→ minus sign indicates that acceleration due to gravity is in the negative h direction

Then, N-S equation for incompressible fluids and isothermal flows are

11.2 Navier-Stokes Equations

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -g \frac{\partial h}{\partial x} - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{\rho} \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right]$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -g \frac{\partial h}{\partial y} - \frac{1}{\rho} \frac{\partial p}{\partial y} + \frac{\mu}{\rho} \left[\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right]$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -g \frac{\partial h}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial z} + \frac{\mu}{\rho} \left[\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right]$$

(11.8)

Local
acceleration

Convective
acceleration

Body force
per mass

Pressure force
per mass

Viscosity force
per mass

11.2 Navier-Stokes Equations

Eq. (11.8): 4 unknowns - u, v, w, p 4원 2차 비선형 편미분 연립 방정식

→ We need one more equation to obtain a solution when the boundary conditions are specified.

→ Eq. of continuity for incompressible fluid

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

◆ Boundary conditions

1) kinematic BC: velocity normal to any rigid boundary (wall) equal the boundary velocity (velocity = 0 for stationary boundary)

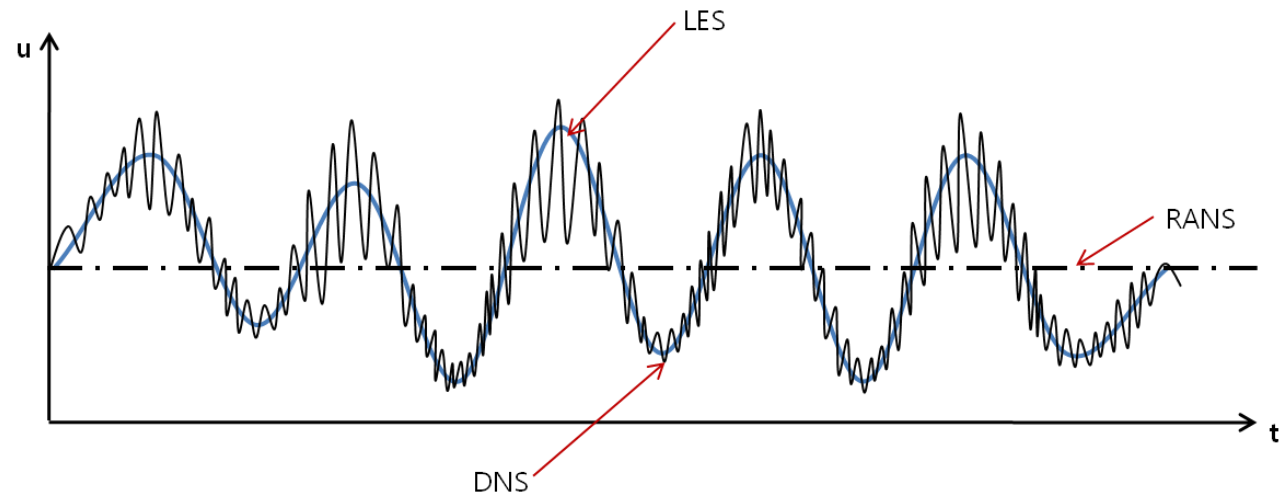
2) physical BC: no slip condition (continuum stick to a rigid boundary)

→ tangential velocity relative to the wall vanish at the wall surface

11.2 Navier-Stokes Equations

- General solutions for Navier-Stokes equations are not available because of the nonlinear, 2nd-order nature of the partial differential equations.
- Only particular solutions may be obtained by simplifications.
- **Numerical solutions** are usually sought.

- ① DNS
- ② RANS
- ③ LES



11.2 Navier-Stokes Equations

[Re] Navier-Stokes existence and smoothness

- Millennium Prize Problems by Clay Mathematics Institute (CMI)
- Prove or give a counter-example of the following statement: In three space dimensions and time, given an initial velocity field, there exists a vector velocity and a scalar pressure field, which are both smooth and globally defined, that solve the Navier-Stokes equations.



11.2 Navier-Stokes Equations

11.2.2 Navier-Stokes equations in cylindrical coordinates

- Navier-Stokes equations in cylindrical coordinates for constant density and viscosity

r - component:

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right)$$

$$= \rho g_r - \frac{\partial p}{\partial r} + \mu \left[\frac{\partial}{\partial r} \left\{ \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right\} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

11.2 Navier-Stokes Equations

θ - component:

$$\begin{aligned} & \rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} - \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) \\ &= \rho g_\theta - \frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{\partial}{\partial r} \left\{ \frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right\} + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right] \end{aligned}$$

z - component:

$$\begin{aligned} & \rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) \\ &= \rho g_z - \frac{\partial p}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] \end{aligned} \quad (11.9)$$

11.2 Navier-Stokes Equations

Continuity eq. for incompressible fluid

$$\frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{1}{r} \frac{\partial}{\partial \theta} (v_\theta) + \frac{\partial}{\partial z} (v_z) = 0 \quad (11.10)$$

Normal & shear stresses for constant density and viscosity

$$\sigma_r = -p + 2\mu \frac{\partial v_r}{\partial r}$$

$$\sigma_\theta = -p + 2\mu \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right)$$

$$\sigma_z = -p + 2\mu \frac{\partial v_z}{\partial z}$$

11.2 Navier-Stokes Equations

$$\tau_{r\theta} = \mu \left[r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right]$$

$$\tau_{\theta z} = \mu \left[\frac{\partial v_\theta}{\partial z} + \frac{1}{r} \frac{\partial v_z}{\partial \theta} \right]$$

$$\tau_{zr} = \mu \left[\frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \right]$$