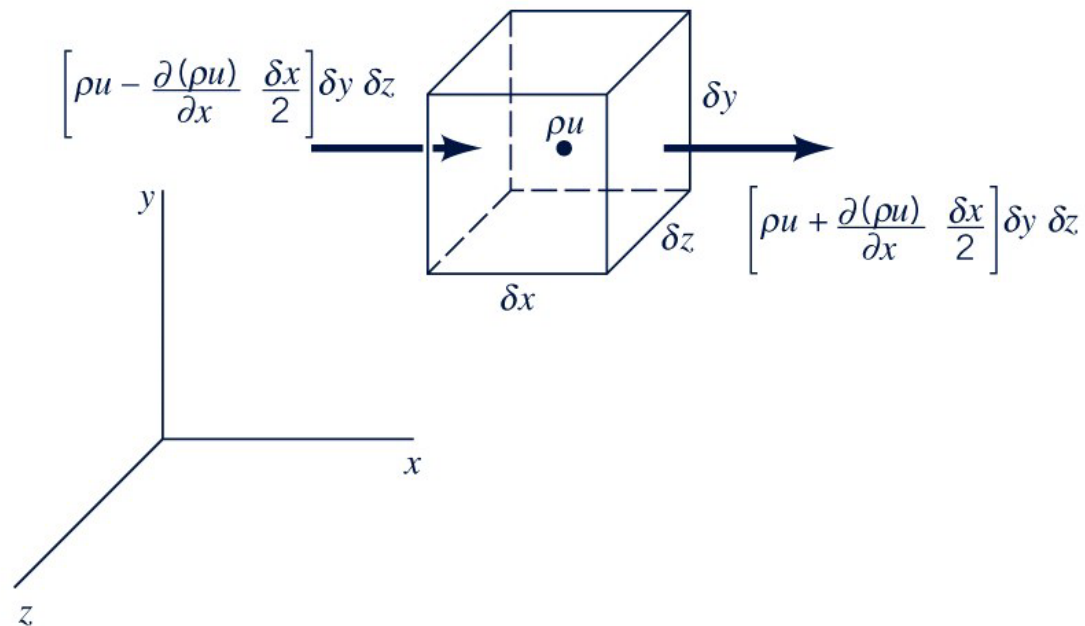


Chapter 6 Equations of Continuity and Motion

Session 6-1 Continuity equation



Chapter 6 Equations of Continuity and Motion

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Chapter 6 Equations of Continuity and Motion

Objectives

- Derive 3D equations of continuity and motion
- Derive Navier-Stokes equation for Newtonian fluid
- Study solutions for simplified cases of laminar flow
- Derive Bernoulli equation for irrotational motion and frictionless flow
- Study solutions for vortex motions

6.1 Continuity Equation

- Derivation of 3-D Eq.

{ conservation of mass \rightarrow continuity eq.
 { conservation of momentum \rightarrow eq. of motion \rightarrow Navier-Stokes eq.

Consider infinitesimal control volume ($\Delta x \Delta y \Delta z$) \rightarrow point form

[Cf] Finite control volume – arbitrary CV \rightarrow integral form

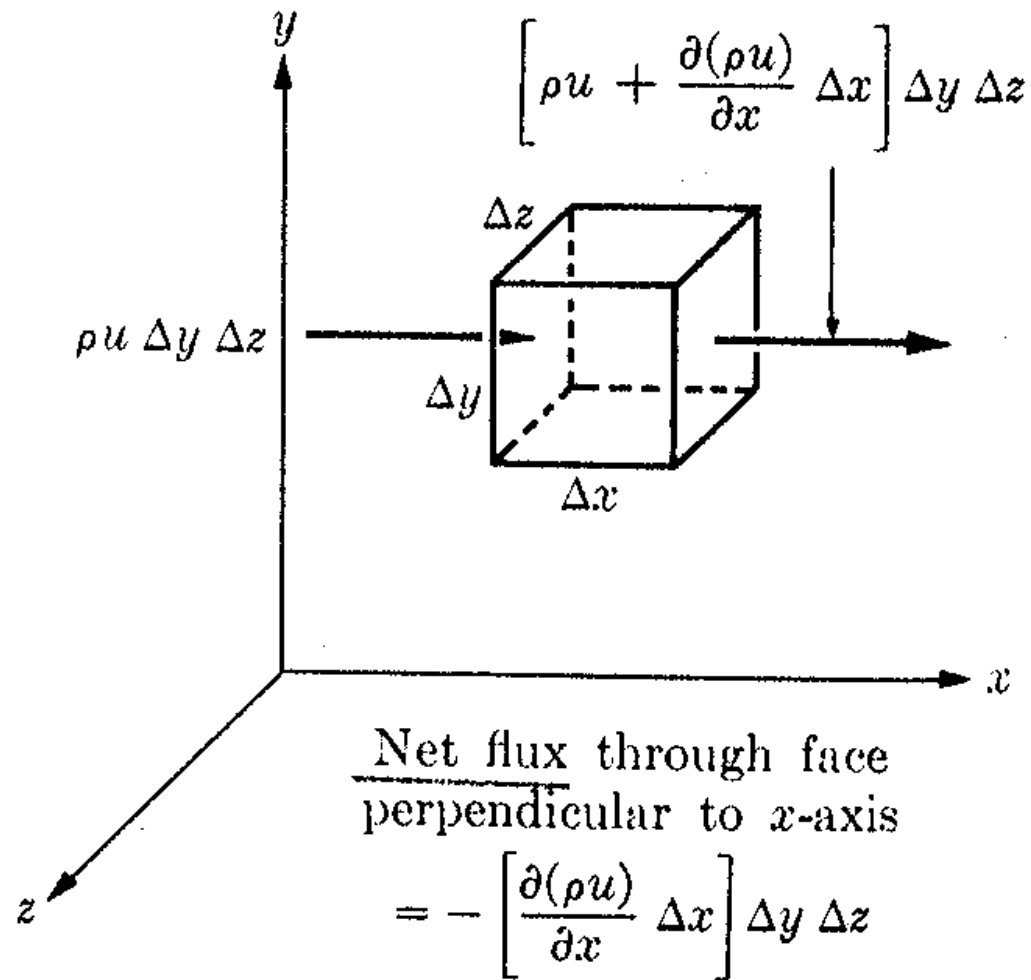
Apply principle of conservation of matter to the CV

\rightarrow sum of net flux = time rate change of mass inside C.V.

1) mass flux per unit time (mass flow)

$$= \frac{\text{mass}}{\text{time}} = \rho \frac{\text{vol}}{\text{time}} = \rho Q = \rho u \Delta A$$

6.1 Continuity Equation



6.1 Continuity Equation

- net flux through face perpendicular to x -axis

= flux in –flux out

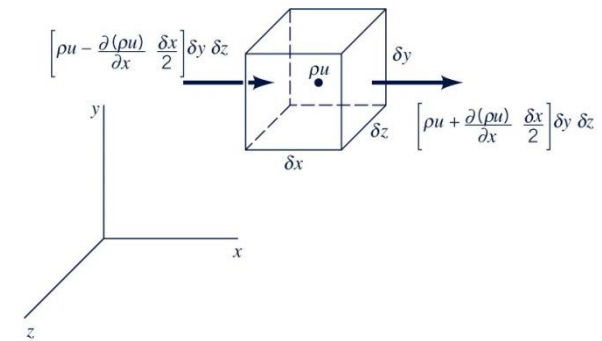
$$= \rho u \Delta y \Delta z - \left(\rho u + \frac{\partial(\rho u)}{\partial x} \Delta x \right) \Delta y \Delta z = -\frac{\partial(\rho u)}{\partial x} \Delta x \Delta y \Delta z$$

- net flux through face perpendicular to y -axis

$$= -\frac{\partial(\rho v)}{\partial y} \Delta x \Delta y \Delta z$$

- net flux through face perpendicular to z -axis

$$= -\frac{\partial(\rho w)}{\partial z} \Delta x \Delta y \Delta z$$



(A)

6.1 Continuity Equation

2) time rate change of mass inside C.V.

$$= \frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z) \quad (\text{B})$$

Thus, equating (A) and (B) gives

$$\frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z) = -\frac{\partial(\rho u)}{\partial x} \Delta x \Delta y \Delta z - \frac{\partial(\rho v)}{\partial y} \Delta x \Delta y \Delta z - \frac{\partial(\rho w)}{\partial z} \Delta x \Delta y \Delta z$$

$$LHS = \frac{\partial}{\partial t} (\rho \Delta x \Delta y \Delta z) = \rho \frac{\partial}{\partial t} (\Delta x \Delta y \Delta z) + \Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t}$$

6.1 Continuity Equation

Since C.V. is fixed $\rightarrow \frac{\partial(\Delta x \Delta y \Delta z)}{\partial t} = 0$

$$\therefore LHS = \Delta x \Delta y \Delta z \frac{\partial \rho}{\partial t}$$

Cancelling terms makes

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{q} = 0$$

(6.1)

\rightarrow Continuity Eq. for compressible fluid in unsteady flow (point form)

6.1 Continuity Equation

The 2nd term of Eq. (6.1) can be expressed as

$$\nabla \cdot (\rho \vec{q}) = \underbrace{\vec{q} \nabla \rho}_{\text{I}} + \underbrace{\rho \nabla \cdot \vec{q}}_{\text{II}}$$

$$\text{(I): } \vec{q} \nabla \rho = (u\vec{i} + v\vec{j} + w\vec{k}) \left(\frac{\partial \rho}{\partial x} \vec{i} + \frac{\partial \rho}{\partial y} \vec{j} + \frac{\partial \rho}{\partial z} \vec{k} \right)$$

gradient

$$= u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z}$$

divergence

$$\text{(II): } \rho \nabla \cdot \vec{q} = \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$\therefore \nabla \cdot (\rho \vec{q}) = u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \quad \text{(i)}$$

6.1 Continuity Equation

Substituting (i) into Eq (6.1) yields

$$\frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$\frac{d\rho}{dt}$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{q} = 0$$

(6.1)

$$\frac{d\rho}{dt} + \rho \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

(6.2a)

$$\frac{d\rho}{dt} + \rho(\nabla \cdot \vec{q}) = 0$$

(6.2b)

6.1 Continuity Equation

[Re] Total derivative (total rate of density change)

$$\begin{aligned}\frac{d\rho}{dt} &= \frac{\partial\rho}{\partial t} + \frac{\partial\rho}{\partial x} \frac{dx}{dt} + \frac{\partial\rho}{\partial y} \frac{dy}{dt} + \frac{\partial\rho}{\partial z} \frac{dz}{dt} \\ &= \frac{\partial\rho}{\partial t} + u \frac{\partial\rho}{\partial x} + v \frac{\partial\rho}{\partial y} + w \frac{\partial\rho}{\partial z}\end{aligned}$$

1) For steady-state conditions

$$\rightarrow \frac{\partial\rho}{\partial t} = 0$$

6.1 Continuity Equation

Then (6.1) becomes

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = \nabla \cdot (\rho \vec{q}) = 0 \quad (6.3)$$

2) For incompressible fluid (whether or not flow is steady)

$$\rightarrow \frac{d\rho}{dt} = 0 \quad (6.4)$$

Then (6.2) becomes

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \nabla \cdot \vec{q} = 0 \quad (6.5)$$

6.1 Continuity Equation

[Re] Continuity equation in polar (cylindrical) coordinates

u, r - radial

v, θ - azimuthal

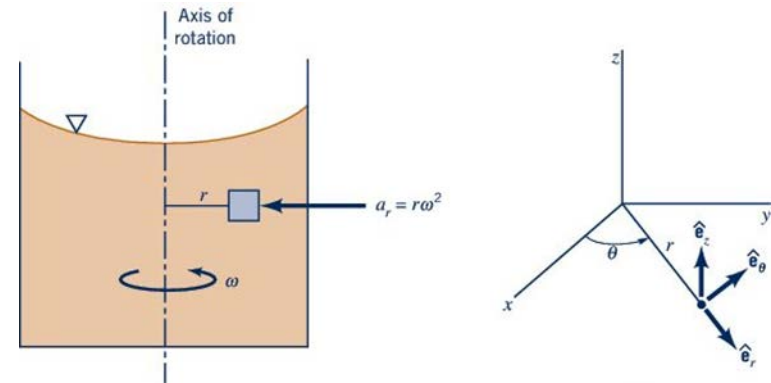
w, z - axial

For compressible fluid of unsteady flow

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial(\rho u r)}{\partial r} + \frac{1}{r} \frac{\partial(\rho v)}{\partial \theta} + \frac{\partial(\rho w)}{\partial z} = 0$$

For incompressible fluid

$$\frac{1}{r} \frac{\partial(ur)}{\partial r} + \frac{1}{r} \frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial z} = 0$$



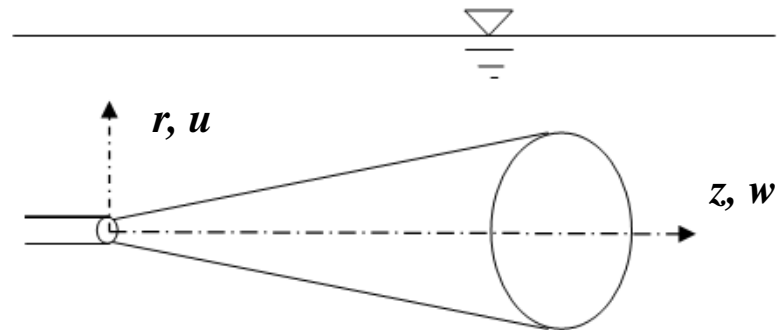
6.1 Continuity Equation

For incompressible fluid and flow of axial symmetry

$$\frac{\partial \rho}{\partial t} = 0, \quad \frac{\partial \rho}{\partial r} = \frac{\partial \rho}{\partial \theta} = \frac{\partial \rho}{\partial z} = 0, \quad \frac{\partial(\rho v)}{\partial \theta} = 0$$

$$\therefore \frac{1}{r} \frac{\partial(ur)}{\partial r} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \text{2-D boundary layer flow}$$

Example: submerged jet



6.2 Stream Function in 2-D, Incompressible Flows

- 2-D incompressible continuity eq. is

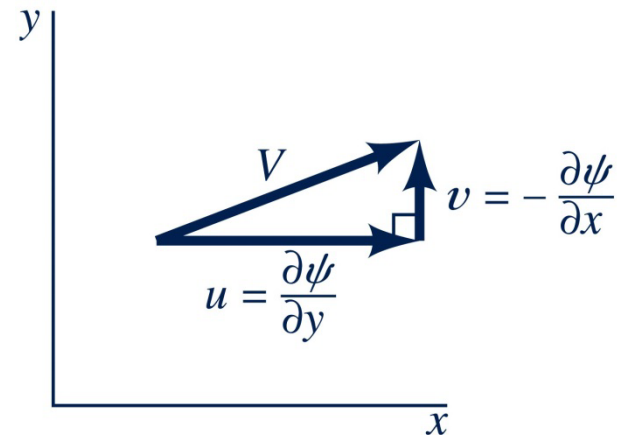
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad (6.7)$$

In 2D flowfield, define stream function $\psi(x, y)$ as

$$u = -\frac{\partial \psi}{\partial y} \quad (6.8)$$

$$v = \frac{\partial \psi}{\partial x} \quad (6.9)$$

- We can have a simplified equation to determine only one unknown function.



6.2 Stream Function in 2-D, Incompressible Flows

Then LHS of Eq. (6.7) becomes

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = \frac{\partial}{\partial x} \left(-\frac{\partial \psi}{\partial y} \right) + \frac{\partial}{\partial y} \left(\frac{\partial \psi}{\partial x} \right) = -\frac{\partial^2 \psi}{\partial x \partial y} + \frac{\partial^2 \psi}{\partial x \partial y} = 0 \quad (6.10)$$

→ Thus, continuity equation is satisfied.

1) Apply stream function to the equation for a stream line in 2-D flow

$$\text{Eq. (2.10): } v dx - u dy = 0 \quad (6.11)$$

Substitute (6.8) into (6.11)

$$\frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} dy = d\psi = 0 \quad (6.12)$$

6.2 Stream Function in 2-D, Incompressible Flows

$$\psi = \text{constant} \quad (6.13)$$

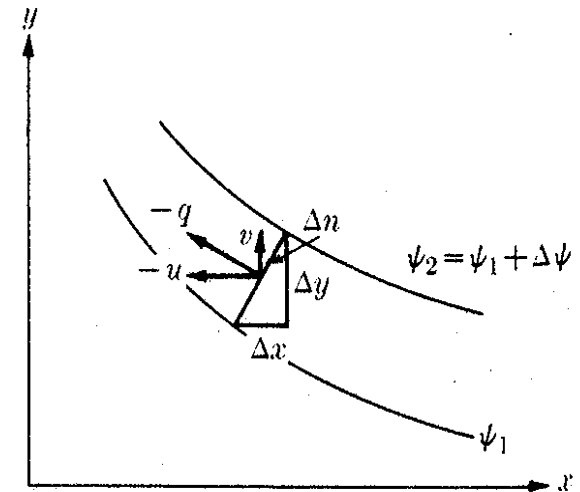
→ The stream function is constant along a streamline.

2) Apply stream function to the law of conservation of mass

$$-qdn = -udy + vdx \quad (6.14)$$

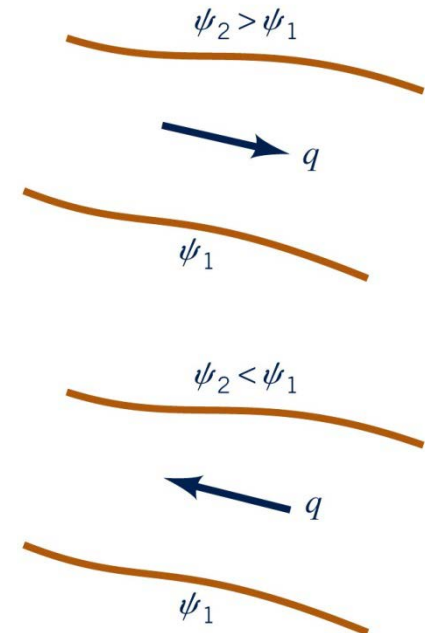
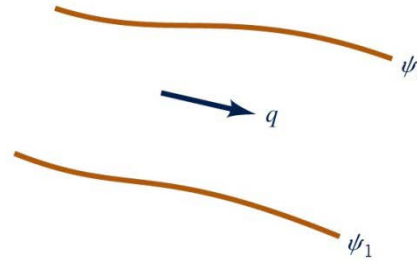
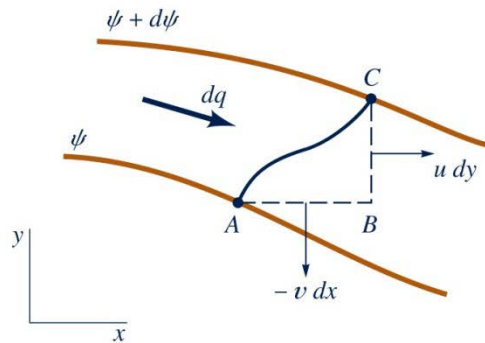
Substitute (6.8) into (6.14)

$$-qdn = \frac{\partial \psi}{\partial y} dy + \frac{\partial \psi}{\partial x} dx = d\psi \quad (6.15)$$



6.2 Stream Function in 2-D, Incompressible Flows

→ Change in ψ ($d\psi$) between adjacent streamlines is equal to the volume rate of flow per unit width.



- Stream function in cylindrical coordinates

$$v_r = -\frac{\partial \psi}{r \partial \theta} \quad \text{radial} \quad v_\theta = \frac{\partial \psi}{\partial r} \quad \text{azimuthal}$$

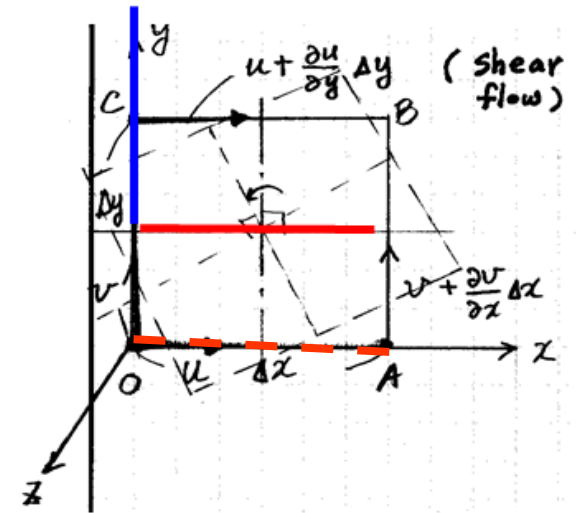
6.3 Rotational and Irrotational Motion

6.3.1 Rotation and vorticity

Assume the rate of rotation of fluid element Δx and Δy about z -axis is positive when it rotates counterclockwise.

- time rate of rotation of Δx -face about z -axis

$$= \frac{1}{\Delta t} \left[\left\{ v + \left(\frac{\partial v}{\partial x} \right) \Delta x \right\} - v \right] \Delta t = \frac{\partial v}{\partial x}$$



6.3 Rotational and Irrotational Motion

- time rate of rotation of Δy -face about z -axis

$$= \frac{1}{\Delta t} \left[u + \left(\frac{\partial u}{\partial y} \Delta y \right) - u \right] \Delta t = -\frac{\partial u}{\partial y}$$

net rate of rotation = average of rotations of Δx -and Δy -face

$$\omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

6.3 Rotational and Irrotational Motion

Doing the same way for x -axis, and y -axis

$$\omega_x = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right)$$

$$\omega_y = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \quad (6.16a)$$

1) Rotation

$$\vec{\omega} = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \vec{i} + \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \vec{j} + \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \vec{k}$$

$$= \frac{1}{2} (\nabla \times \vec{q}) = \frac{1}{2} \text{curl } \vec{q} \quad (6.16b)$$

6.3 Rotational and Irrotational Motion

Magnitude:

$$|\vec{\omega}| = \sqrt{\omega_x^2 + \omega_y^2 + \omega_z^2}$$

a) Ideal fluid → irrotational flow

$$\nabla \times \vec{q} = 0$$

$$\omega_x = \omega_y = \omega_z = 0$$

$$\frac{\partial w}{\partial y} = \frac{\partial v}{\partial z}, \quad \frac{\partial u}{\partial z} = \frac{\partial w}{\partial x}, \quad \frac{\partial v}{\partial x} = \frac{\partial u}{\partial y} \quad (6.17)$$

b) Viscous fluid → rotational flow

$$\nabla \times \vec{q} \neq 0$$

6.3 Rotational and Irrotational Motion

2) Vorticity

$$\vec{\zeta} = \text{curl } \vec{q} = \nabla \times \vec{q} = 2\vec{\omega}$$

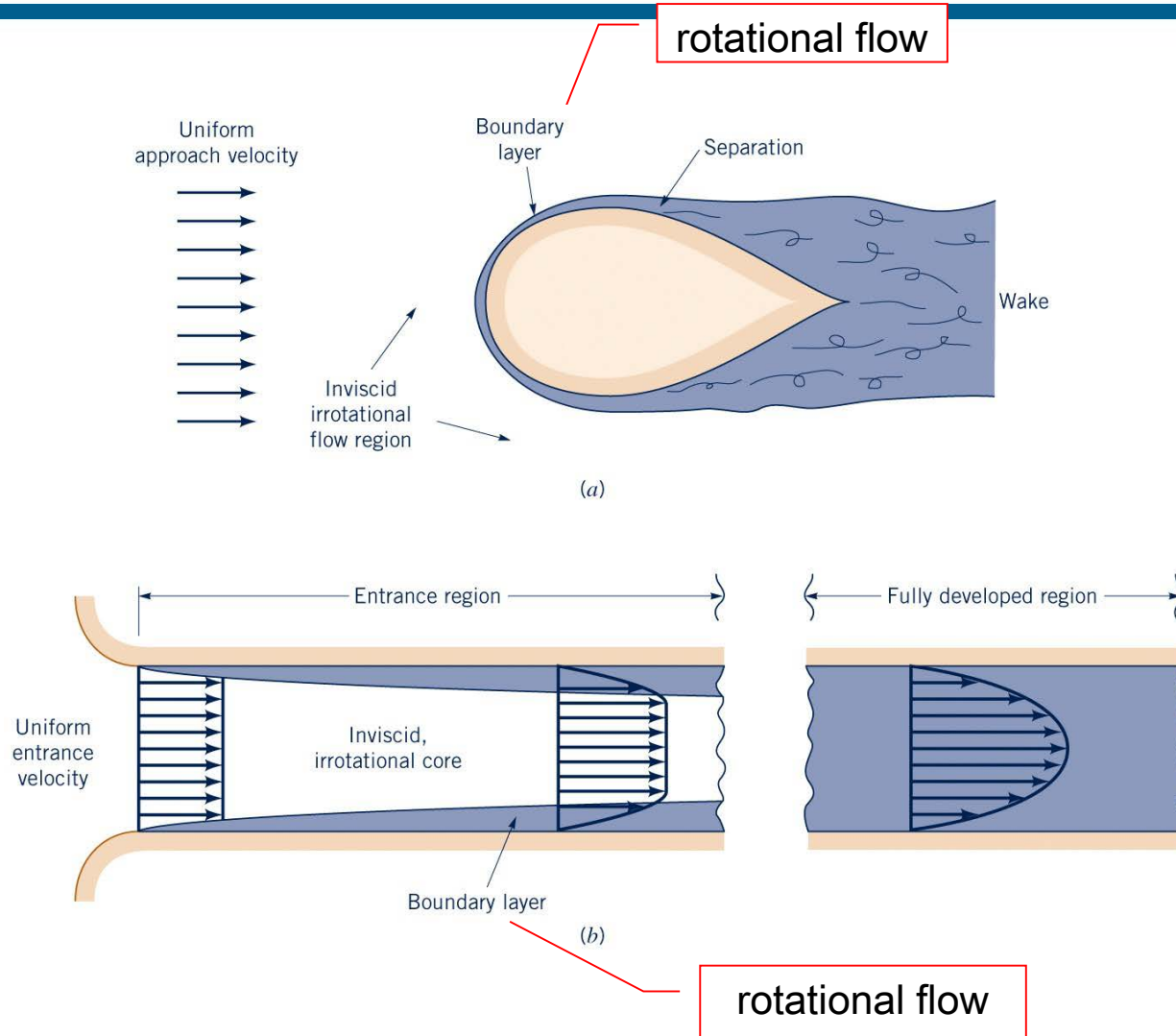
- Rotation in cylindrical coordinates

$$\omega_r = \frac{1}{2} \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right)$$

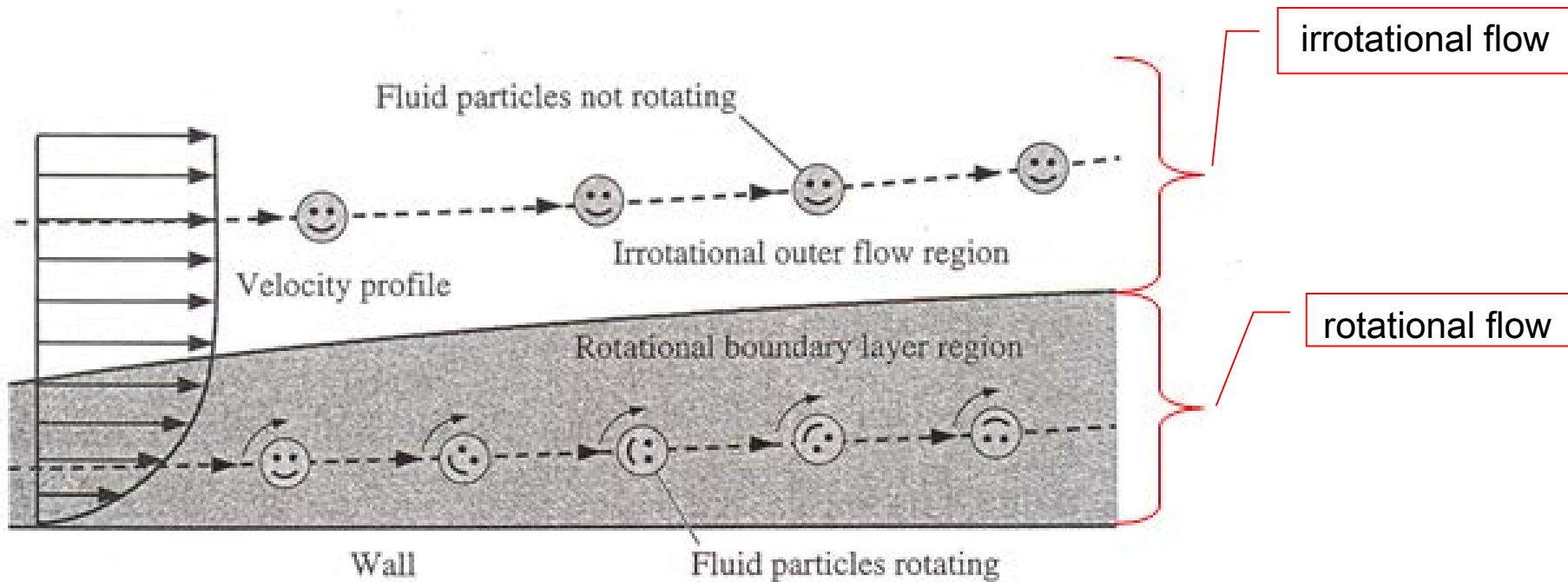
$$\omega_\theta = \frac{1}{2} \left(\frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right)$$

$$\omega_z = \frac{1}{2} \left(-\frac{1}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\theta}{r} + \frac{\partial v_\theta}{\partial r} \right)$$

6.3 Rotational and Irrotational Motion



6.3 Rotational and Irrotational Motion

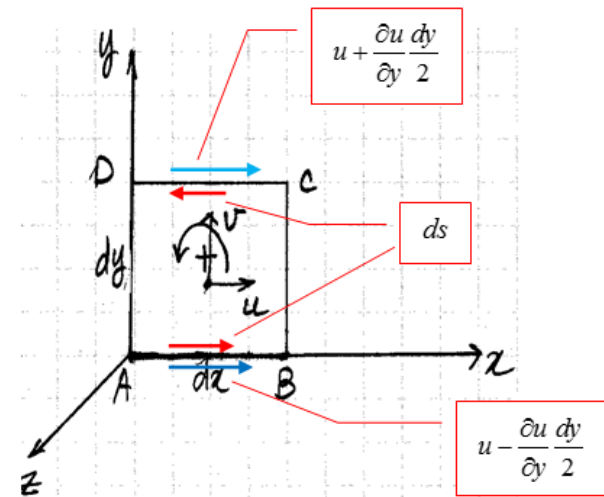


6.3 Rotational and Irrotational Motion

6.3.2 Circulation

$\Gamma =$ line integral of the tangential velocity component about any closed contour S

$$\Gamma = \oint \vec{q} \cdot d\vec{s} \quad (6.19)$$



6.3 Rotational and Irrotational Motion

– take line integral from A to B, C, D, A ~ infinitesimal CV

$$d\Gamma \cong \left[u - \frac{\partial u}{\partial y} \frac{dy}{2} \right] dx + \left[v + \frac{\partial v}{\partial x} \frac{dx}{2} \right] dy - \left[u + \frac{\partial u}{\partial y} \frac{dy}{2} \right] dx - \left[v - \frac{\partial v}{\partial x} \frac{dx}{2} \right] dy$$

$$= \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) dx dy$$

$$d\Gamma \cong \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) dx dy$$

$$\Gamma = \iint_A \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) dA = \iint_A 2\omega_z dA = \iint_A (\nabla \times \vec{q})_z dA \quad (6.20)$$

6.3 Rotational and Irrotational Motion

For irrotational flow,

circulation $\Gamma = 0$ (if there is no singularity vorticity source).

[Re] Fluid motion and deformation of fluid element

Motion { translation
rotation

Deformation { linear deformation
angular deformation

