

Introduction to Nuclear Fusion

Prof. Dr. Yong-Su Na

Plasma Equilibrium, Stability and Transport



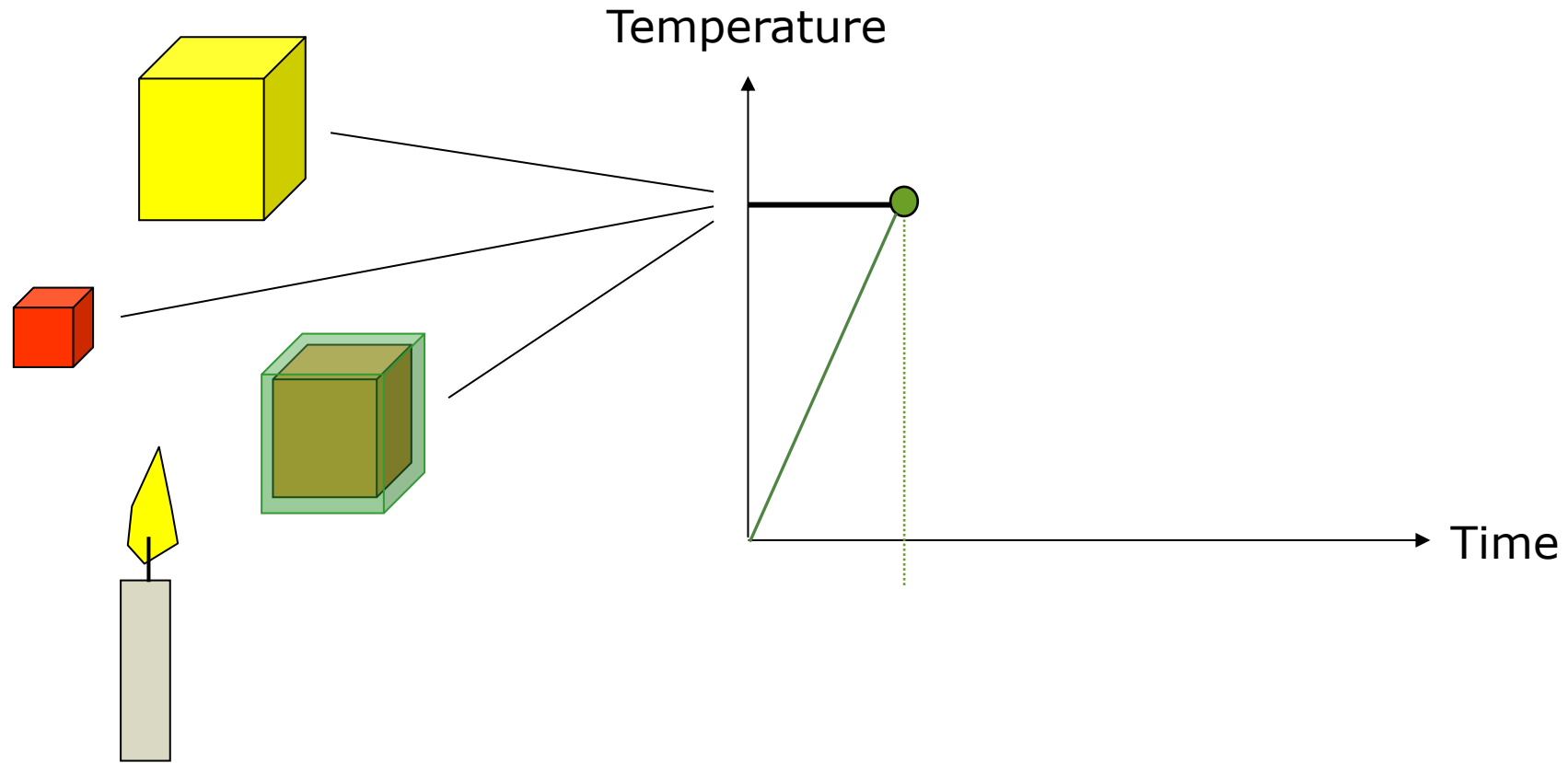
Tokamak
(magnetic pressure)

The text is written diagonally below the balloon, indicating the external magnetic pressure that maintains the equilibrium.

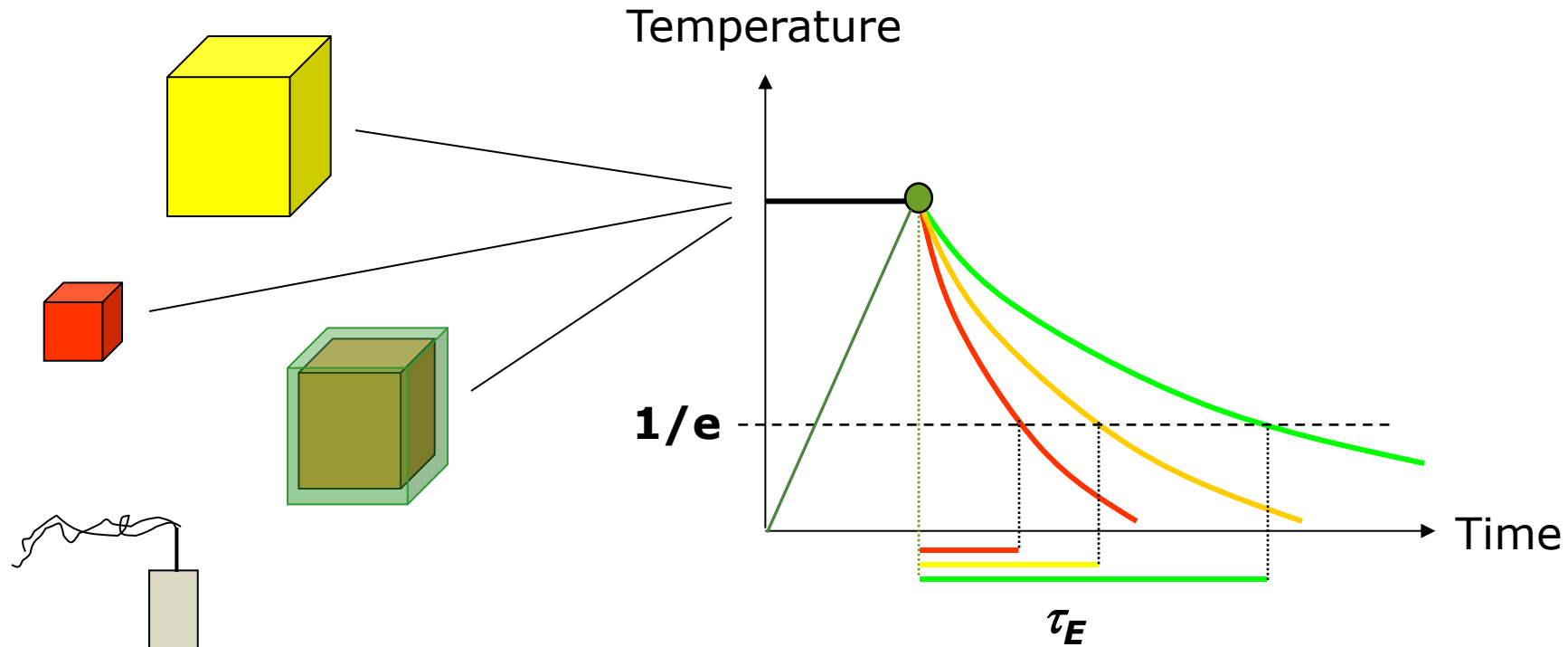


Plasma transport in a Tokamak

Energy Confinement Time



Energy Confinement Time



- τ_E is a measure of how fast the plasma loses its energy.
- The loss rate is smallest, τ_E largest if the fusion plasma is big and well insulated.

Tokamak Transport

• Transport Coefficients

$$\Gamma = -D\nabla n \quad : \text{Fick's law} \qquad D = \frac{(\Delta x)^2}{2\tau} \quad : \text{diffusion coefficient (m}^2/\text{s)}$$

$$q = -\kappa\nabla T \quad : \text{Fourier's law} \qquad D \sim v_{th}^2\tau \sim \frac{\lambda_m^2}{\tau}$$

Thermal diffusivity

$$\chi \equiv \frac{\kappa}{n} \approx D \approx \frac{(\Delta x)^2}{\tau} \approx \frac{a^2}{\tau_E} \quad \rightarrow \quad \tau_E \approx \frac{a^2}{\chi}$$

- Particle transport in fully ionised plasmas with magnetic field

$$D_{\perp} = \frac{\eta_{\perp} n \sum kT}{B^2}$$

Tokamak Transport

- **Classical Transport**

- Classical thermal conductivity (expectation): $\chi_i \sim 40\chi_e$
- Typical numbers expected: $\sim 10^{-4}$ m²/s
- Experimentally found: ~ 1 m²/s, $\chi_i \sim \chi_e$

Bohm diffusion (1946):
$$D_{\perp} = \frac{1}{16} \frac{kT_e}{eB}$$



David Bohm
(1917-1992)

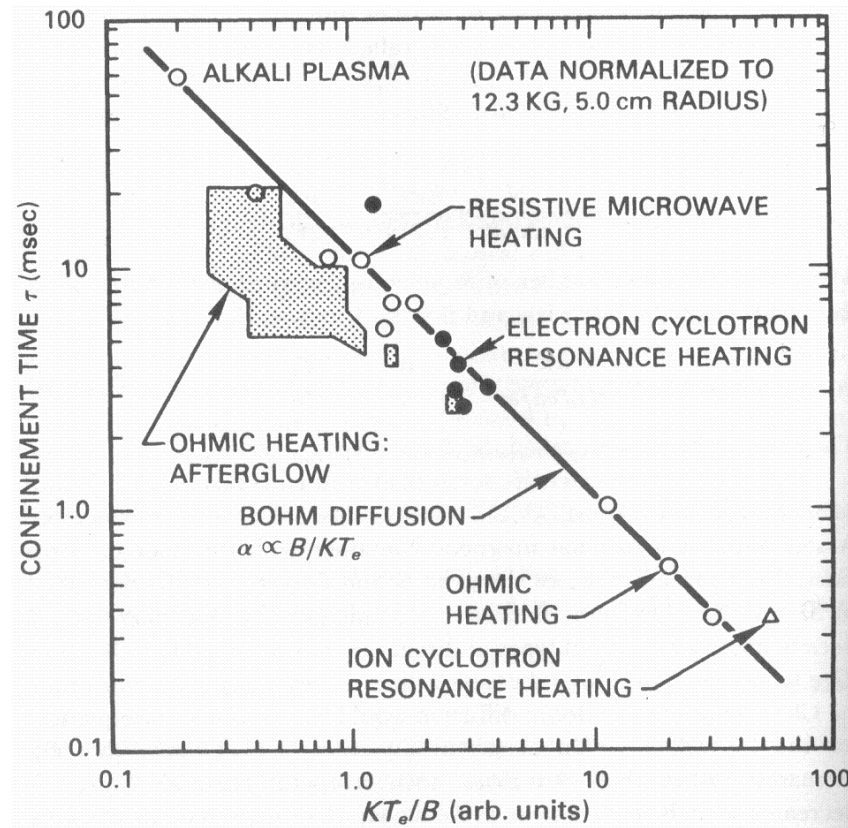


Aharonov-Bohm effect

Tokamak Transport

• Classical Transport

Bohm diffusion:
$$D_{\perp} = \frac{1}{16} \frac{kT_e}{eB}$$



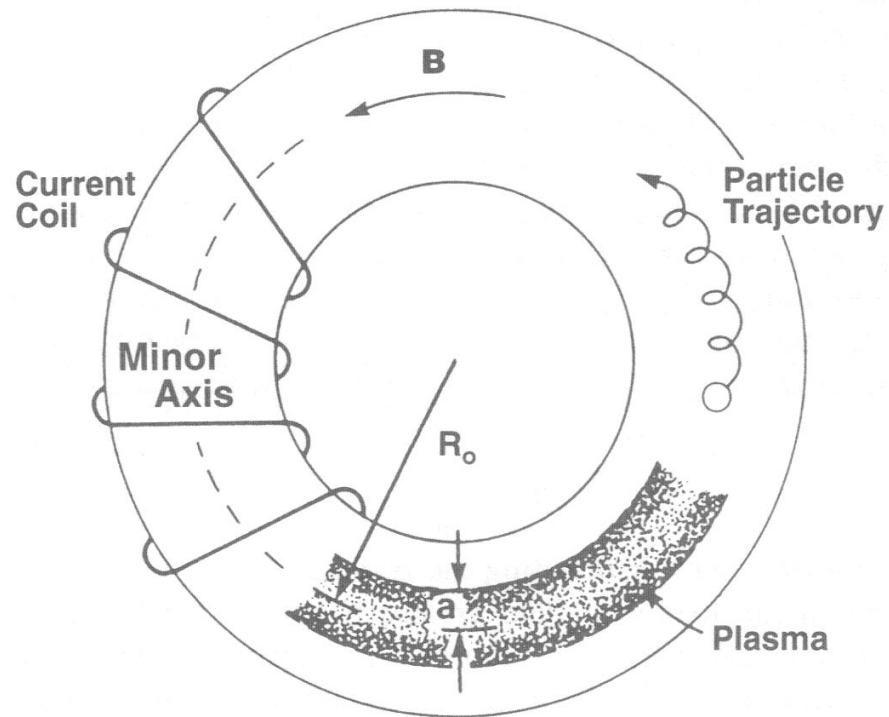
T_E in various types of discharges in the Model C Stellarator

F. F. Chen, "Introduction to Plasma Physics and Controlled Fusion" (2006)

Tokamak Transport

- Neoclassical Transport

- Major changes arise from toroidal effects characterised by inverse aspect ratio, $\epsilon = a/R_0$



Tokamak Transport

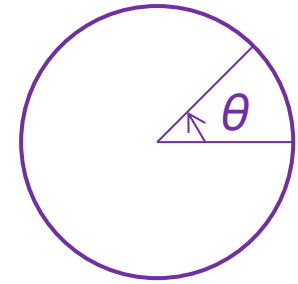
- Particle Trapping

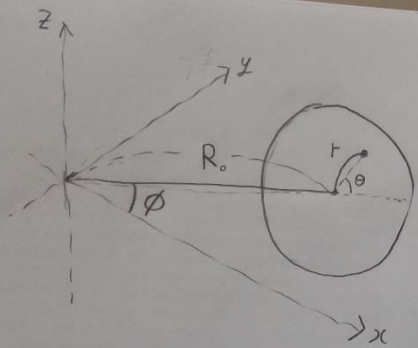
$$\nabla \cdot \vec{B} = 0$$

$$\Rightarrow \frac{1}{1 + \varepsilon \cos \theta} \left\{ \frac{1}{r} \frac{\partial}{\partial r} [r(1 + \varepsilon \cos \theta) B_r] + \frac{1}{r} \frac{\partial}{\partial \theta} [(1 + \varepsilon \cos \theta) B_\theta] + \frac{1}{r R_0} \frac{\partial (r B_\phi)}{\partial \phi} \right\} = 0$$

$$\Rightarrow B_\theta(r, \theta) = \frac{B_\theta^0(\theta = 0)}{1 + \varepsilon \cos \theta}$$

$$|B(r, \theta)| = |B_\theta(r, \theta) \hat{\theta} + B_\phi(r, \theta) \hat{\phi}| = \frac{B_0}{1 + \varepsilon \cos \theta}$$





$$\left(\begin{array}{l} \text{가정: } \frac{\partial}{\partial \phi} = 0 \\ B_r = 0 \\ J_r = 0 \end{array} \right)$$

$$\vec{r} = (R_0 + r \cos \theta) \cos \phi \hat{x} + (R_0 + r \cos \theta) \sin \phi \hat{y} + r \sin \theta \hat{z}$$

$$\frac{\partial \vec{r}}{\partial r} = \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} + \sin \theta \hat{z}$$

$$\frac{\partial \vec{r}}{\partial \theta} = -r \sin \theta \cos \phi \hat{x} - r \sin \theta \sin \phi \hat{y} + r \cos \theta \hat{z}$$

$$\frac{\partial \vec{r}}{\partial \phi} = -(R_0 + r \cos \theta) \sin \phi \hat{x} + (R_0 + r \cos \theta) \cos \phi \hat{y}$$

$$\Rightarrow \hat{r} = \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} + \sin \theta \hat{z}, \quad h_r = \left| \frac{\partial \vec{r}}{\partial r} \right| = 1$$

$$\hat{\theta} = -\sin \theta \cos \phi \hat{x} - \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z}, \quad h_\theta = \left| \frac{\partial \vec{r}}{\partial \theta} \right| = r$$

$$\hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y}, \quad h_\phi = \left| \frac{\partial \vec{r}}{\partial \phi} \right| = R_0 + r \cos \theta$$

$$\Rightarrow \nabla \cdot \vec{A} = \frac{1}{h_r h_\theta h_\phi} \left[\frac{\partial}{\partial r} (h_\theta h_\phi A_r) + \frac{\partial}{\partial \theta} (h_r h_\phi A_\theta) + \frac{\partial}{\partial \phi} (h_r h_\theta A_\phi) \right]$$

$$\Rightarrow \nabla \cdot \vec{B} = \frac{1}{r(R_0 + r \cos \theta)} \left[\frac{\partial}{\partial r} (r(R_0 + r \cos \theta) B_r) + \frac{\partial}{\partial \theta} ((R_0 + r \cos \theta) B_\theta) + \frac{\partial}{\partial \phi} (r B_\phi) \right]$$

$$= 0$$

$$\left(\begin{array}{l} \text{Axisymmetric} \rightarrow \frac{\partial}{\partial \phi} = 0 \\ \vec{B} = B_\theta \hat{\theta} + B_\phi \hat{\phi} \rightarrow B_r = 0 \end{array} \right)$$

$$\Rightarrow \nabla \cdot \vec{B} = \frac{1}{r(R_0 + r \cos \theta)} \left[\frac{\partial}{\partial \theta} (R_0 + r \cos \theta) B_\theta \right] = 0$$

$$\Rightarrow B_\theta(r, \theta) = \frac{\text{const}(r)}{R_0 + r \cos \theta} = \frac{B_0(r, \frac{\pi}{2})}{1 + \epsilon \cos \theta} \quad (\epsilon \equiv \frac{r}{R_0})$$

1/2 전 Ampere's law $\nabla \times \vec{B} = \mu_0 \vec{J}$

$$\nabla \times \vec{A} = \frac{1}{h_r h_\theta h_\phi} \begin{vmatrix} h_r \hat{r} & h_\theta \hat{\theta} & h_\phi \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ h_r A_r & h_\theta A_\theta & h_\phi A_\phi \end{vmatrix}$$

$$\vec{B} = B_\theta(r, \theta) \hat{\theta} + B_\phi(r, \theta) \hat{\phi}$$

$$\vec{J} = J_\theta(r, \theta) \hat{\theta} + J_\phi(r, \theta) \hat{\phi} \quad \text{이러}$$

$$\Rightarrow \nabla \times \vec{B} = \frac{1}{r(R_0 + r \cos \theta)} \begin{vmatrix} \hat{r} & r \hat{\theta} & (R_0 + r \cos \theta) \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \quad (\because \text{Axisymmetric}) \\ 0 & r B_\theta & (R_0 + r \cos \theta) B_\phi \end{vmatrix}$$

$$= \mu_0 J_\theta(r, \theta) \hat{\theta} + \mu_0 J_\phi(r, \theta) \hat{\phi}$$

$$r \text{ 성분이 없으므로 } \frac{\partial}{\partial \theta} (R_0 + r \cos \theta) B_\phi = 0$$

$$\Rightarrow B_\phi(r, \theta) = \frac{\text{const}(r)}{R_0 + r \cos \theta} = \frac{B_\phi(r, \frac{\pi}{2})}{1 + \epsilon \cos \theta} \quad (\epsilon = \frac{r}{R_0})$$

$$\therefore \vec{B} = B_\theta(r, \theta) \hat{\theta} + B_\phi(r, \theta) \hat{\phi}$$

$$= \frac{1}{1 + \epsilon \cos \theta} \left[B_\theta(r, \frac{\pi}{2}) \hat{\theta} + B_\phi(r, \frac{\pi}{2}) \hat{\phi} \right]$$

$$\therefore \boxed{|\vec{B}| = \frac{B_0}{1 + \epsilon \cos \theta}} \quad (B_0 = \sqrt{(B_\theta(r, \frac{\pi}{2}))^2 + (B_\phi(r, \frac{\pi}{2}))^2}) = |\vec{B}(r, \frac{\pi}{2})|)$$

\therefore Axisymmetric ($\frac{\partial}{\partial \phi} = 0$) 이고, \vec{B}, \vec{J} 의 r 성분이 없으면 $B = \frac{B_0(r)}{1 + \epsilon \cos \theta}$ 이다.

Tokamak Transport

• Particle Trapping

$$\nabla \cdot \vec{B} = 0$$

$$\Rightarrow \frac{1}{1 + \varepsilon \cos \theta} \left\{ \frac{1}{r} \frac{\partial}{\partial r} [r(1 + \varepsilon \cos \theta) B_r] + \frac{1}{r} \frac{\partial}{\partial \theta} [(1 + \varepsilon \cos \theta) B_\theta] + \frac{1}{rR_0} \frac{\partial (rB_\phi)}{\partial \phi} \right\} = 0$$

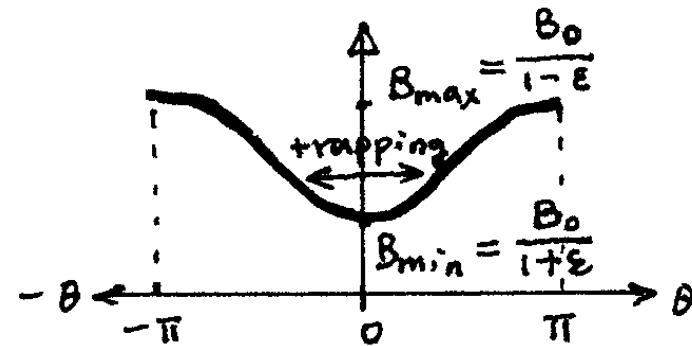
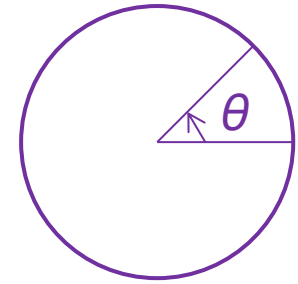
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$$|B(r, \theta)| = |B_\theta(r, \theta) \hat{\theta} + B_\phi(r, \theta) \hat{\phi}| = \frac{B_0}{1 + \varepsilon \cos \theta}$$

- Condition for trapping of particles

$$\frac{(v_{\parallel}^2)_{\max}}{(v_{\perp}^2)_{\min}} = \left(\frac{v_{\parallel}^2}{v_{\perp}^2} \right)_{\text{mid-plane}} \leq \frac{B_{\max}}{B_{\min}} - 1 = \frac{1 - \varepsilon}{1 + \varepsilon} - 1 = \frac{2\varepsilon}{1 - \varepsilon} \sim 2\varepsilon$$

$$\Rightarrow v_{\parallel}^2 \leq 2\varepsilon v_{\perp}^2$$



Tokamak Transport

• Particle Trapping

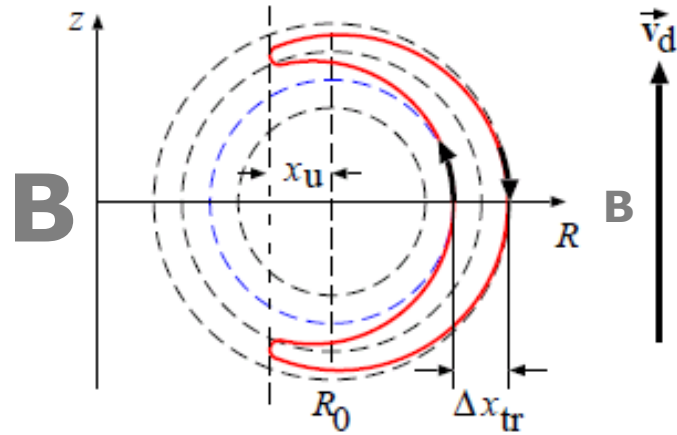
- Particle trapping by magnetic mirrors
trapped particles with banana orbits
untrapped particles with circular orbits

- Trapped fraction:
$$f_{trap} = \sqrt{1 - \frac{1}{R_m}} = \sqrt{1 - \frac{B_{min}}{B_{max}}} = \sqrt{1 - \frac{1 - \epsilon}{1 + \epsilon}} = \sqrt{\frac{2\epsilon}{1 + \epsilon}}$$

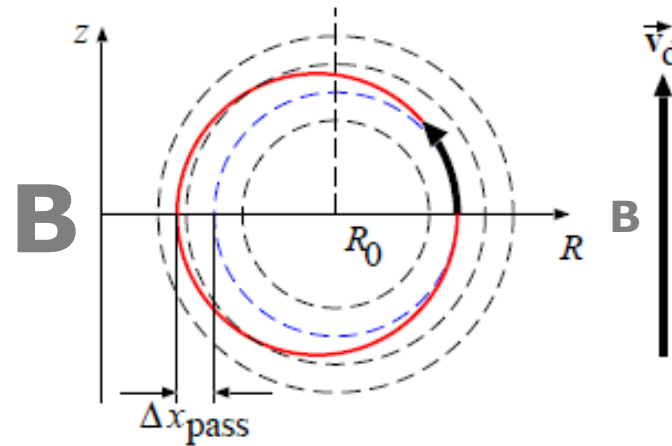
for a typical tokamak, $\epsilon \sim 1/3 \rightarrow f_{trap} \sim 70\%$

Tokamak Transport

• Particle Trapping



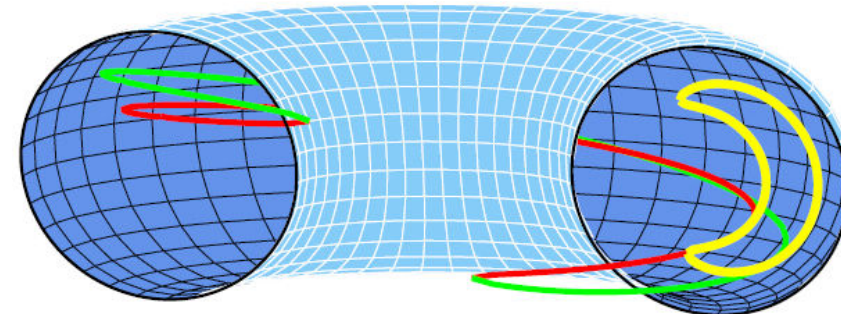
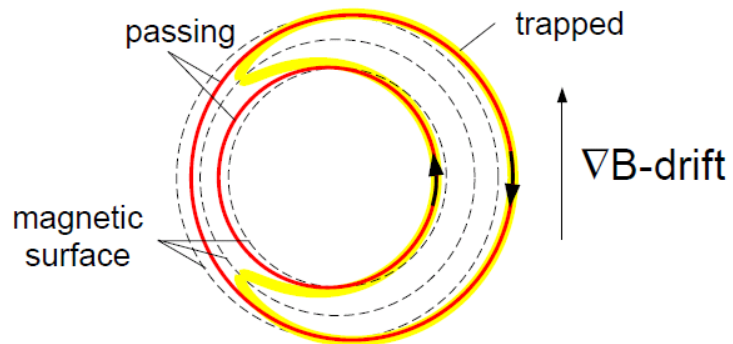
trapped particles



passing particles

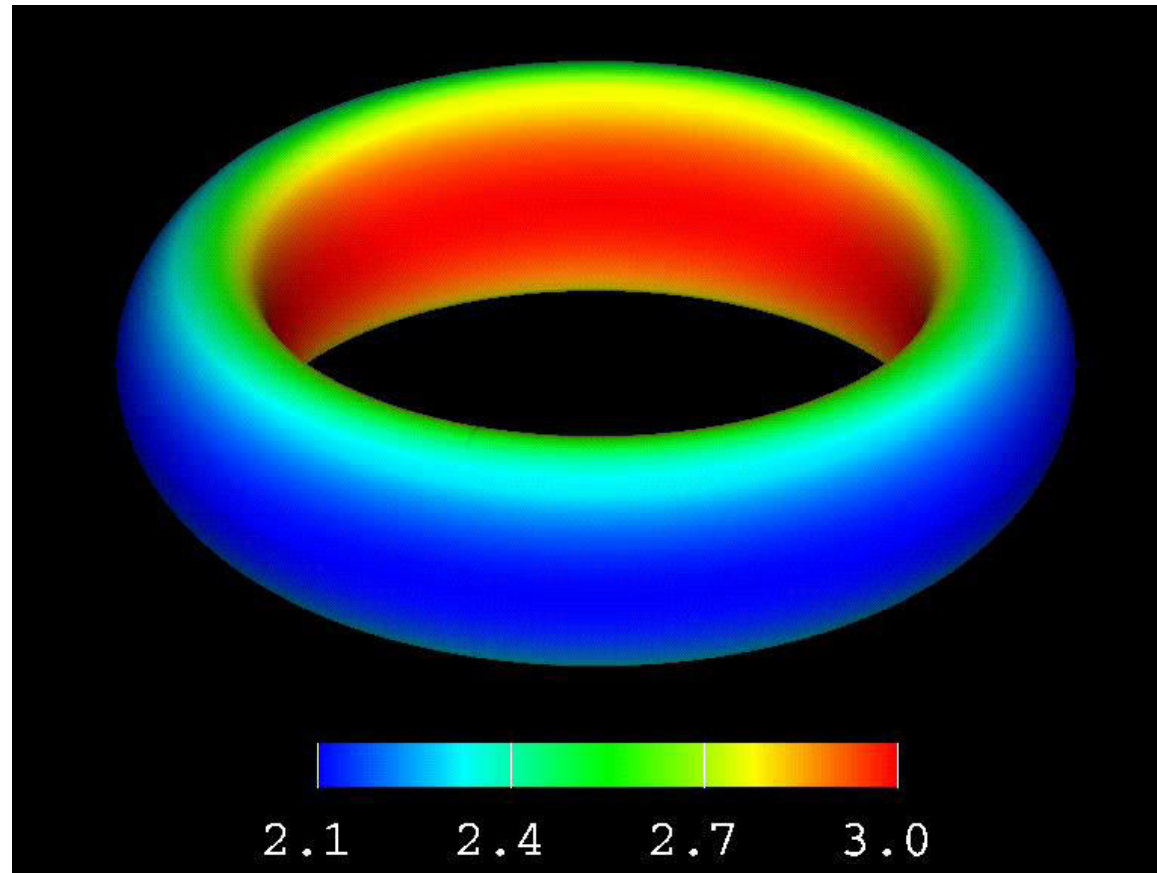
$$\mathbf{v}_{D,\nabla B} = \pm \frac{1}{2} v_{\perp} r_L \frac{\mathbf{B} \times \nabla B}{B^2}$$

$$\mathbf{v}_{D,R} = \frac{mv_{\parallel}^2}{qB_0^2} \frac{\mathbf{R}_0 \times \mathbf{B}_0}{R^2}$$



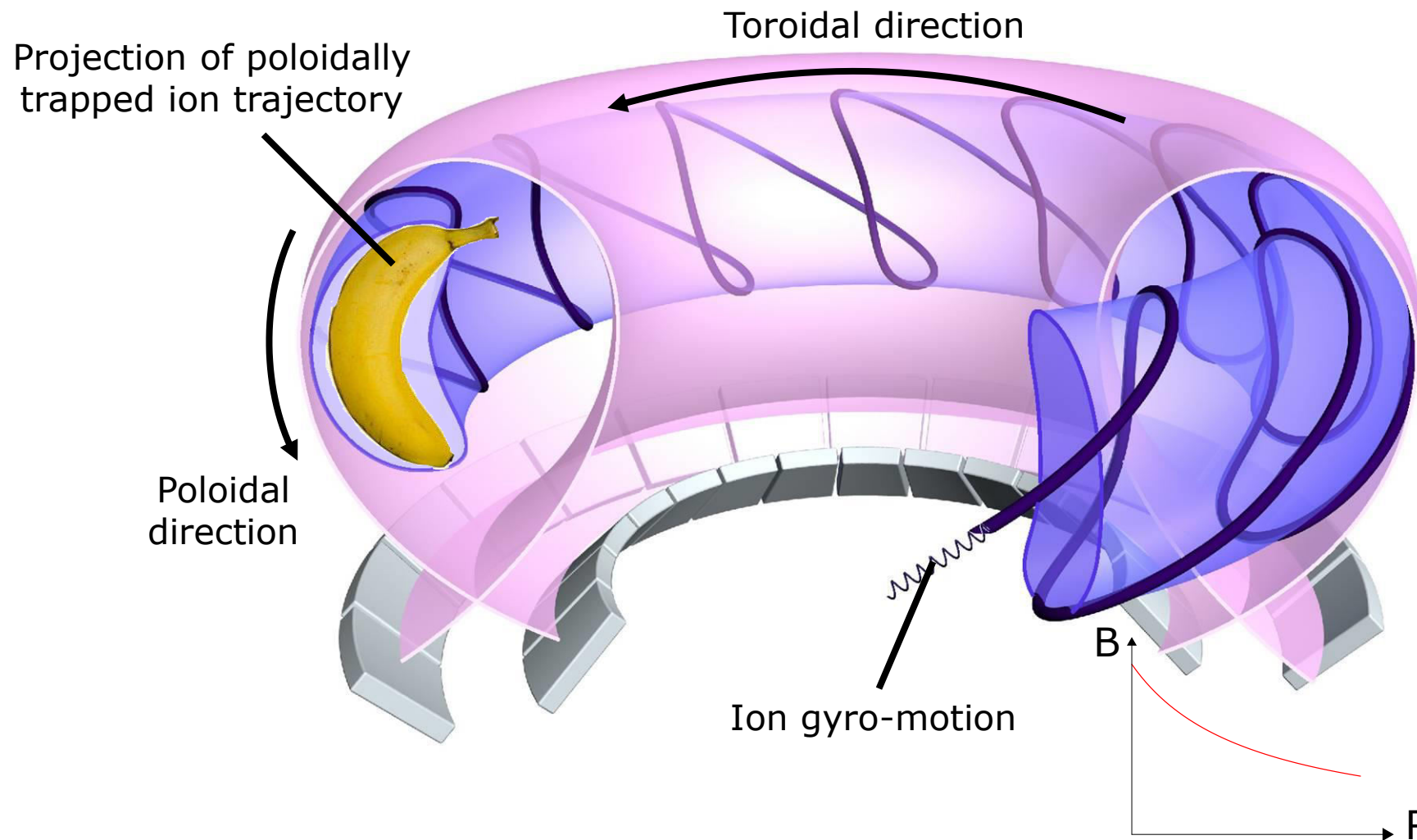
Tokamak Transport

- Particle Trapping



Tokamak Transport

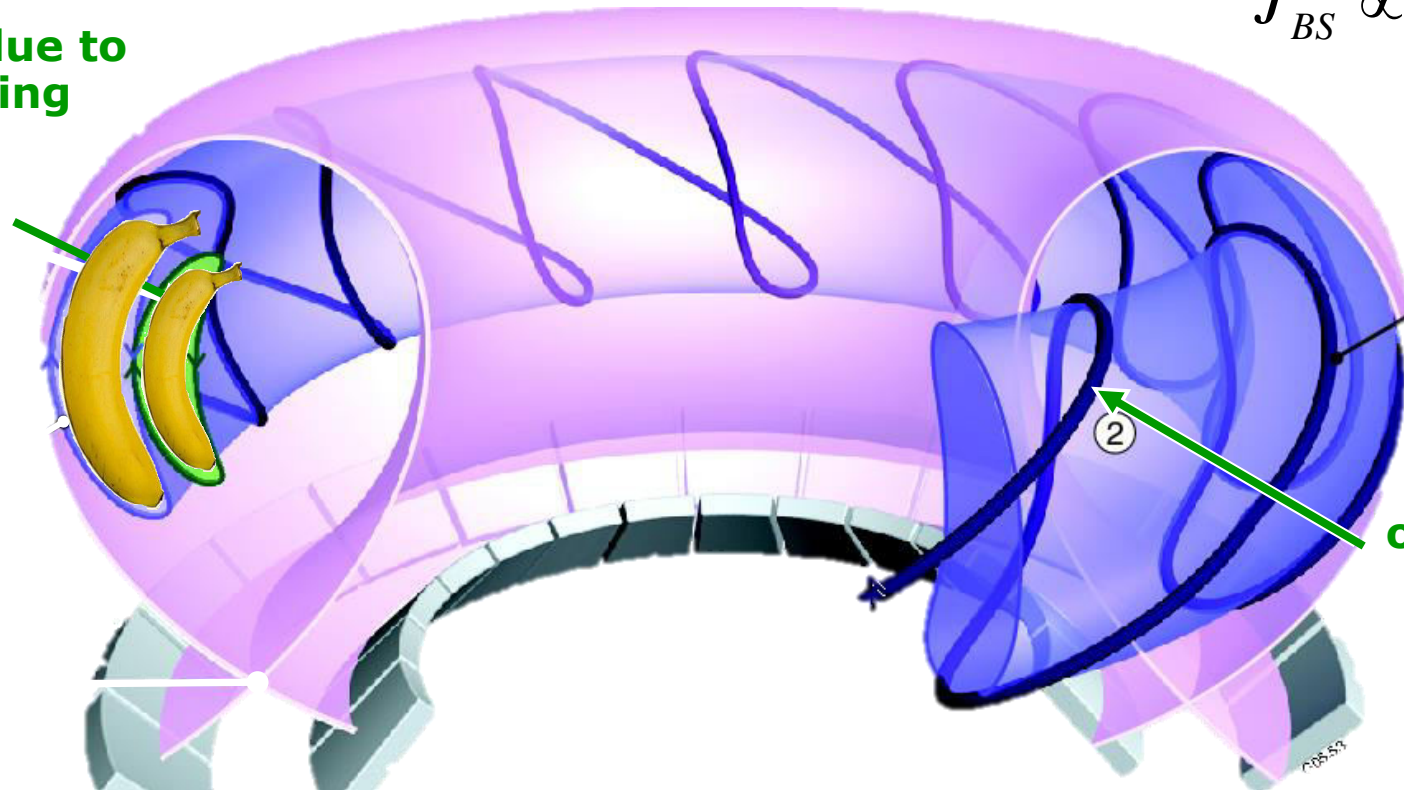
- Neoclassical Bootstrap current



Tokamak Transport

- Neoclassical Bootstrap current

Currents due to neighbouring bananas largely cancel



$$J_{BS} \propto \nabla p$$

orbits tighter where field stronger

- More & faster particles on orbits nearer the core (green .vs. blue) lead to a net "banana current".
- This is transferred to a helical bootstrap current via collisions.

Tokamak Transport

• Neoclassical Bootstrap current

야후! | 도움말 | 로그인

통합검색 통합사전

YAHOO! KOREA 통합사전

bootstrap

검색

통합사전 **NEW** 영어사전 일어사전 백과사전 국어사전 한자사전

영어사전

bootstrap [bú:tsræp]  PLAY  단어장에 추가

1. (편상화의) 손잡이 가죽.
2. <재귀용법으로> 노력하여 [자기]를 어떤 상태로 되게 하다.
3. 자동(식)의; 자급(自給)의; 자력의.

[▶ 영어사전 더보기](#)

- Named after the reported ability of Baron von Munchausen to lift himself by his bootstraps (Raspe, 1785)
- Suggested with 'Alice in Wonderland' in mind where the heroine managed to support herself in the air by her shoelaces.

Tokamak Transport

- **Bootstrap**

MEANING:

verb tr.: To help oneself with one's own initiative and no outside help.

noun: Unaided efforts.

adjective: Reliant on one's own efforts.

ETYMOLOGY:

While pulling on bootstraps may help with putting on one's boots, it's impossible to lift oneself up like that. Nonetheless the fanciful idea is a great visual and it gave birth to the idiom "to pull oneself up by one's (own) bootstraps", meaning to better oneself with one's own efforts, with little outside help. It probably originated from the tall tales of Baron Münchhausen who claimed to have lifted himself (and his horse) up from the swamp by pulling on his own hair.

In computing, booting or bootstrapping is to load a fixed sequence of instructions in a computer to initiate the operating system.

Earliest documented use: 1891.1



Baron Münchhausen lifting himself up from the swamp by his own hair
Illustrator: Theodor Hosemann

Tokamak Transport

- **Bootstrap**

“I was still a couple of miles above the clouds when it broke, and with such violence I fell to the ground that I found myself stunned, and in a hole nine fathoms under the grass, when I recovered, hardly knowing how to get out again. Looking down, I observed that I had on a pair of boots with exceptionally sturdy straps. Grasping them firmly, I pulled with all my might. Soon I had hoist myself to the top and stepped out on terra firma without further ado.”

- With acknowledgement to R. E. Raspe, *Singular Travels, Campaigns and Adventures of Baron Munchausen*, 1786. Edition edited by J. Carswell. London: The Cresset Press, 1948. Adapted from the story on p. 22(???)

Tokamak Transport

- Neoclassical Bootstrap current

Diffusion Driven Plasma Currents and Bootstrap Tokamak

by the usual toroidal coordinates. Then in the regime of low collision frequency and in the absence of any driving electric field, steady state diffusion is accompanied by a toroidal current density of magnitude

R. J.
UKAEA Res

$$j = -A \left(\frac{r}{R} \right)^{1/2} \frac{1}{B_\theta} \frac{dp}{dr} \quad (1)$$

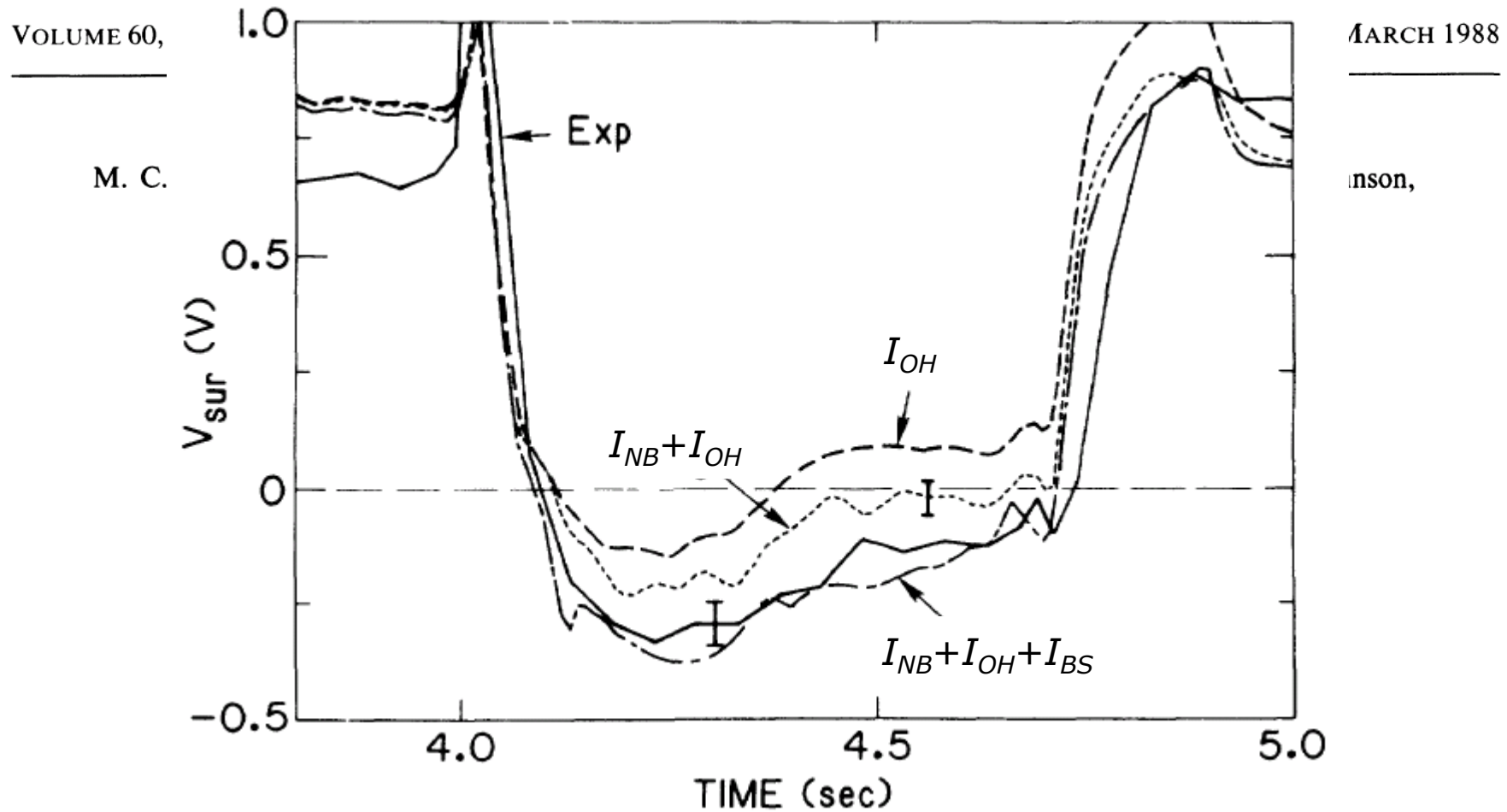
In toroid
ment
toroid
the m
to mag
currer
of Tokamak machine which operates in a steady state, unlike present pulsed designs.

where A is a coefficient whose value depends on the exact collision operator but is of order unity, and p is the plasma pressure.



Tokamak Transport

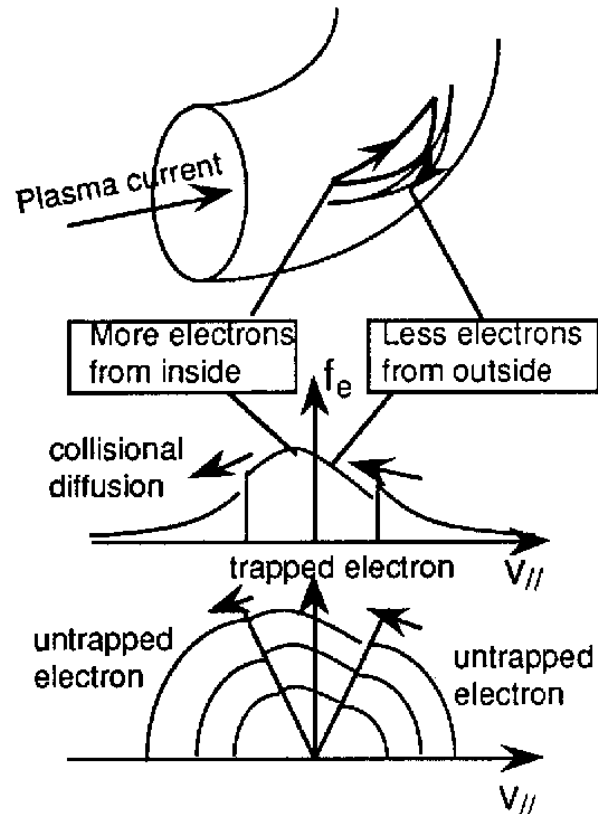
- Neoclassical Bootstrap current



Tokamak Transport

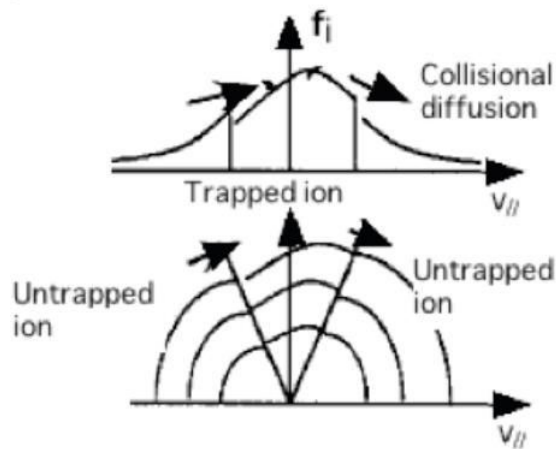
- **Neoclassical Bootstrap current**

- Trapped-electron orbits and schematics of the velocity distribution function in a collisionless tokamak plasma



Small Coulomb collision smoothes the gap and causes particle diffusion in the velocity space.

Collisional pitch angle scattering at the trapped-untrapped boundary produces unidirectional parallel flow/momentum input and is balanced by the collisional friction force between electrons and ions.



Tokamak Transport

- Neoclassical Bootstrap current

- Bootstrap current fraction

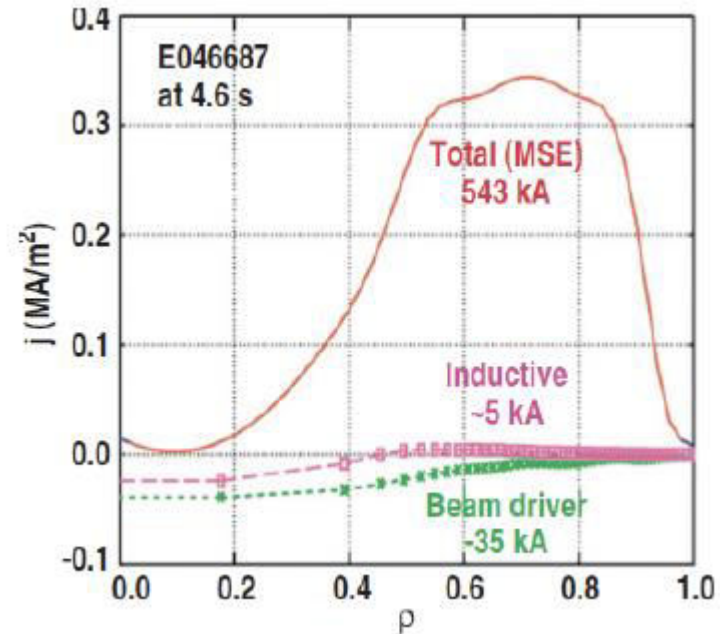
$$f_B(r) \equiv \frac{J_B}{J_\phi} \approx -1.18G\varepsilon^{1/2}\beta_p \sim \varepsilon^{1/2}\beta_p \qquad \beta_p = \frac{\langle p \rangle}{B_p^2 / 2\mu_0}$$
$$G(r) = (\ln n + 0.04 \ln T)' / (\ln r B_\theta)'$$

- In high- β tokamak, $\beta_p \sim 1/\varepsilon$, implying that $f_B \sim 1/\varepsilon^{1/2} \gg 1$:
The bootstrap current can theoretically overdrive the total current
- No obvious "anomalous" degradation of J_B due to micro-turbulence
- The bootstrap current is capable of being maintained in steady state without the need of an Ohmic transformer or external current drive.
This is indeed a favourable result as it opens up the possibility of steady state operation without the need for excessive amounts of external current drive power.
- This is critical since bootstrap current fractions on the order of $f_B > 0.7$ are probably required for economic viability of fusion reactors.

Tokamak Transport

- 100% bootstrap discharges

Y. Takase, IAEA FEC 1996, S. Coda, IAEA FEC 2008

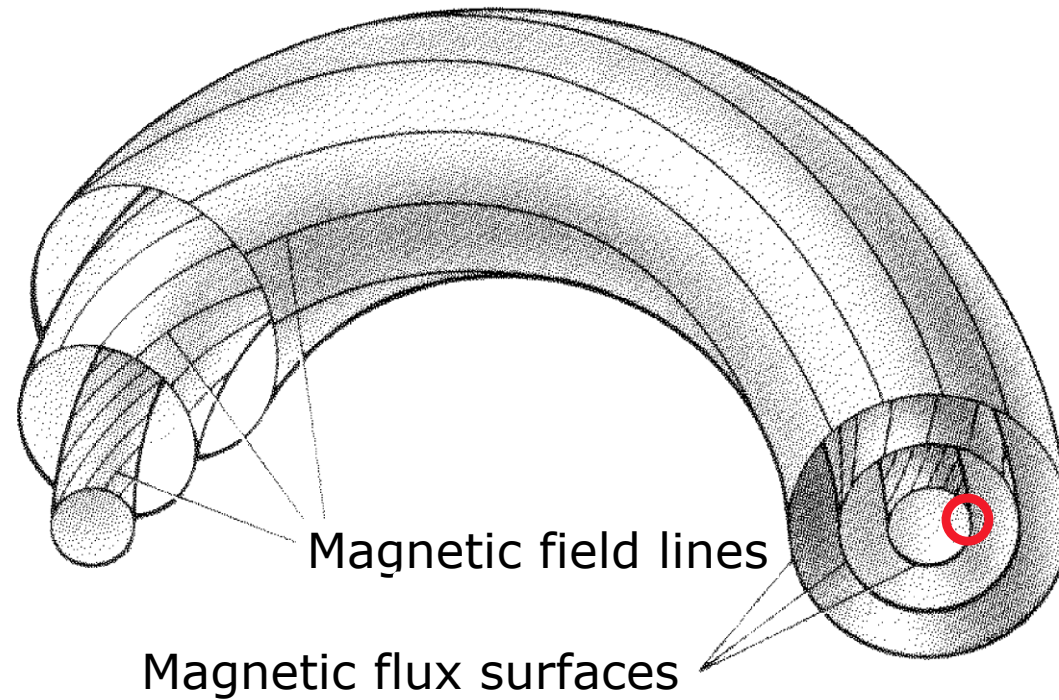


Tokamak Transport

• Particle Trapping

- Collisional excursion across flux surfaces
untrapped particles: $2r_g$ ($2r_{Li}$)

$$D = \frac{(\Delta x)^2}{2\tau} \quad : \text{diffusion coefficient (m}^2/\text{s)}$$

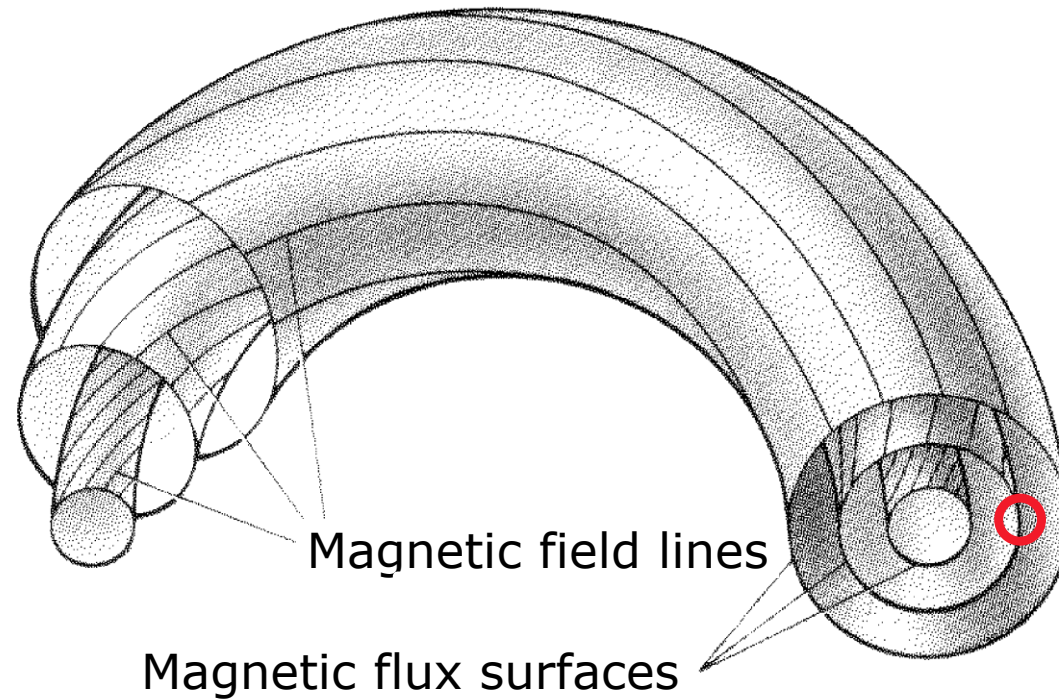


Tokamak Transport

• Particle Trapping

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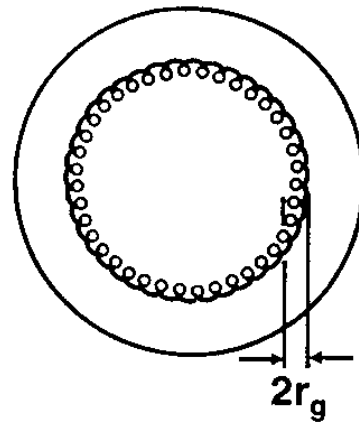
Tokamak Transport

• Particle Trapping

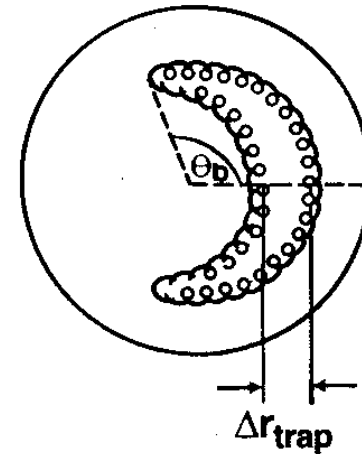
- Collisional excursion across flux surfaces

untrapped particles: $2r_g$ ($2r_{Li}$)

trapped particles: $\Delta r_{trap} \gg 2r_g$ – enhanced radial diffusion
across the confining magnetic field



Untrapped



Trapped

- If the fraction of trapped particle is large, this leakage enhancement constitutes a substantial problem in tokamak confinement.

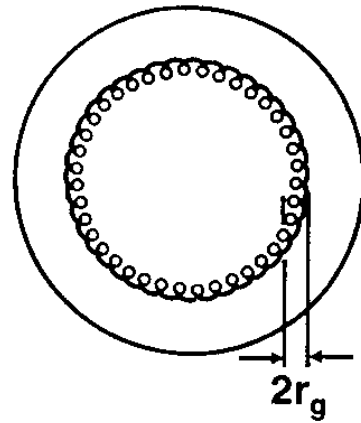
Tokamak Transport

• Particle Trapping

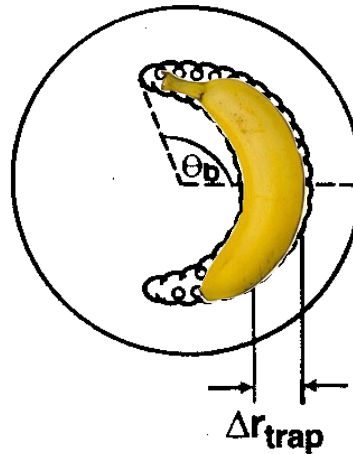
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Untrapped



Trapped

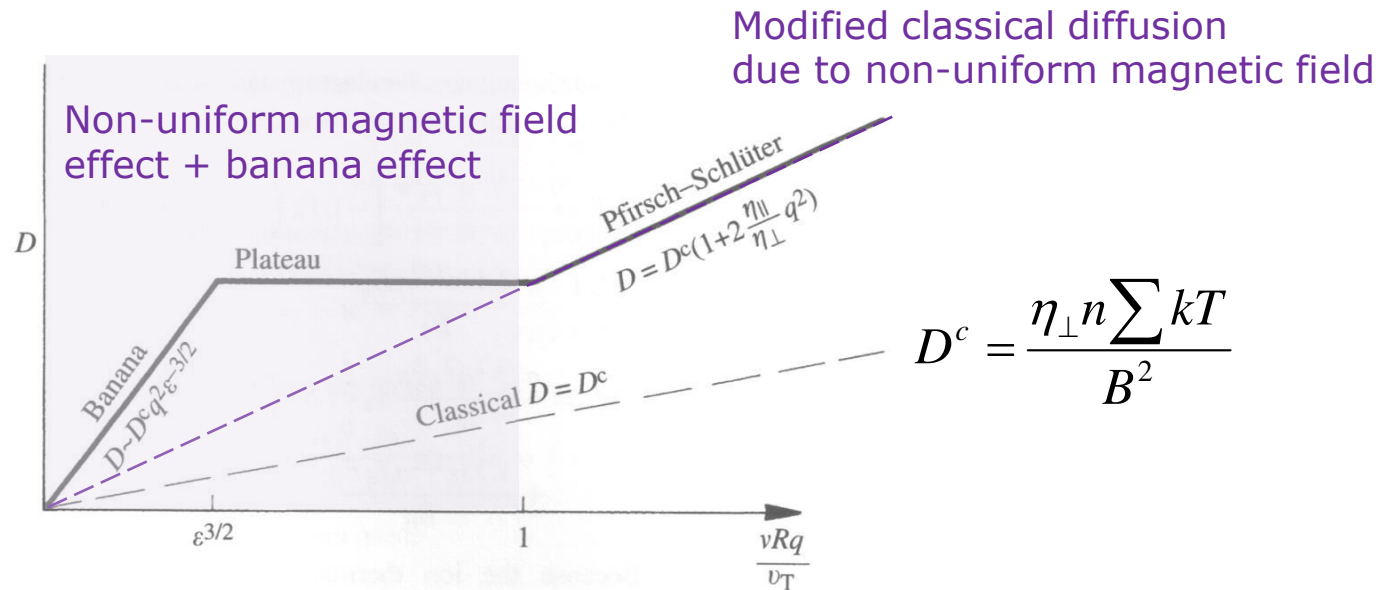
- If the fraction of trapped particle is large, this leakage enhancement constitutes a substantial problem in tokamak confinement.

Tokamak Transport

$$\Gamma = -D\nabla n \approx -\frac{(\Delta r)^2}{\tau} \nabla n : \text{Fick's law}$$

• Neoclassical Transports

- May increase D , χ up to two orders of magnitude:
 - χ_i 'only' wrong by factor 3-5
 - D , χ_e still wrong by up to two orders of magnitude!



J. Wesson, Tokamaks (2004)