

Dispersion

Dispersion examples

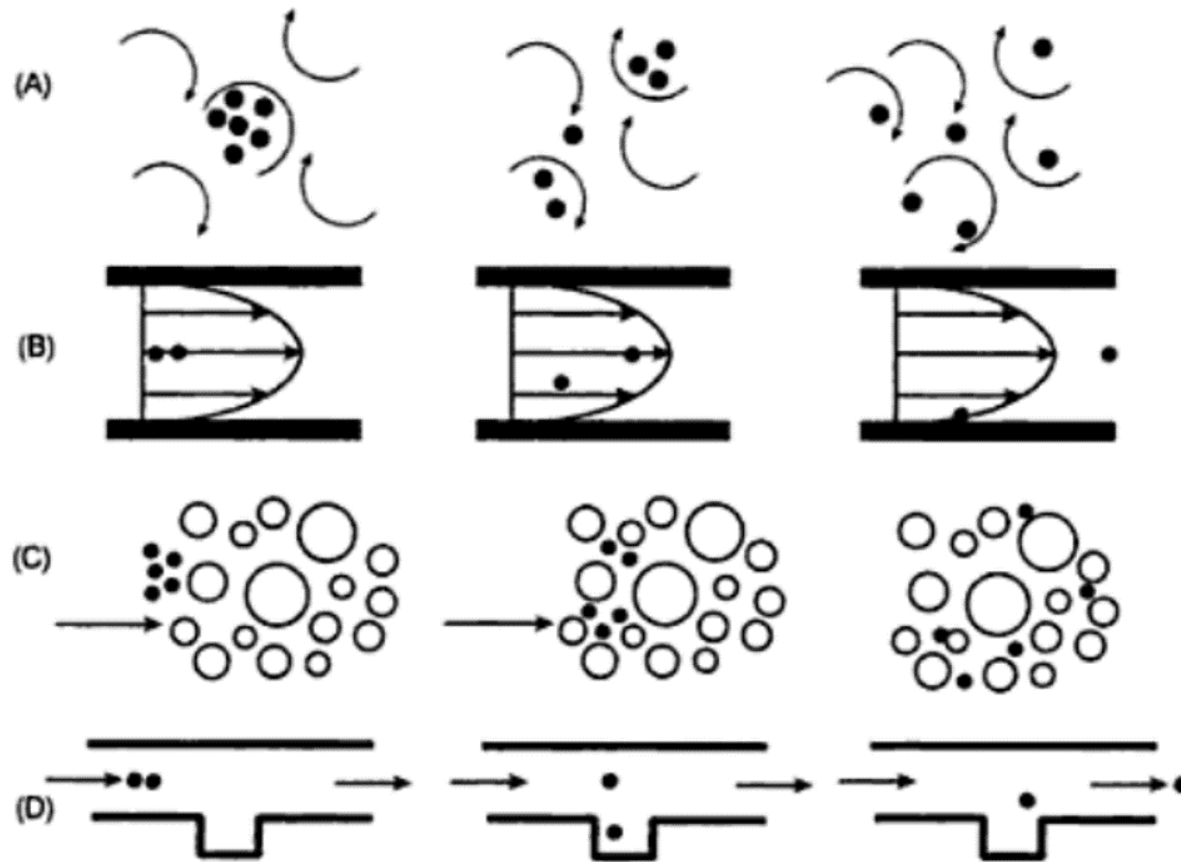
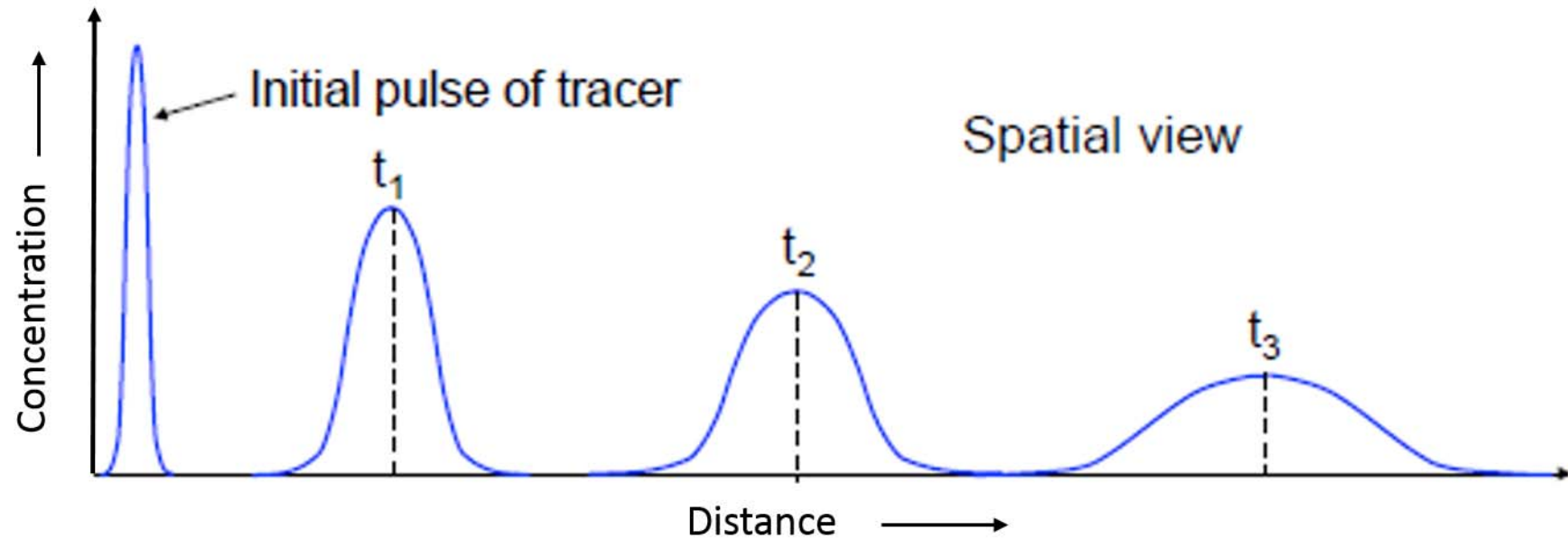


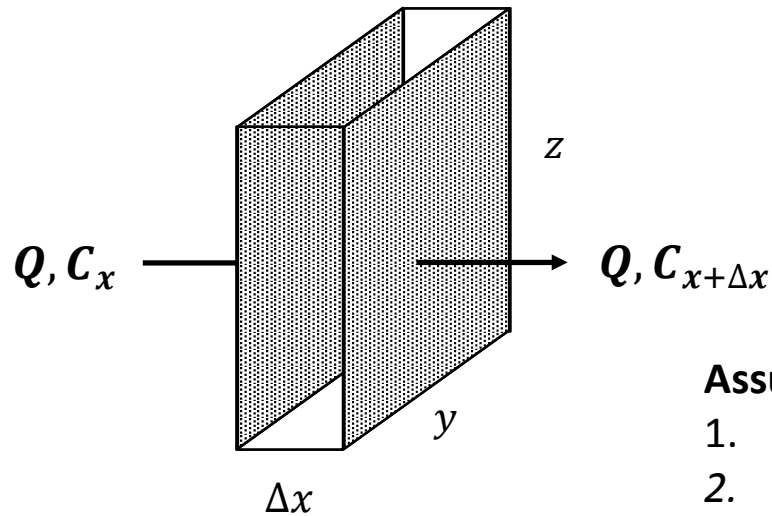
Figure 10.1 Examples of conditions that generate chemical dispersion (A) fluid eddies; (B) velocity gradients in flow in a pipe; (C) noncontinuous flow field (in porous media); (D) boundary effects.

Dispersion from pulse input of a tracer



- No change in area (tracer – mass conserved)
- Concentration vs. Time at distances x_1, x_2, x_3 ?

Mass balance, control volume



$$C_{x+\Delta x} = C_x + (\Delta C / \Delta x) \cdot \Delta x$$

control volume, $V = A \cdot \Delta x$

Assumptions

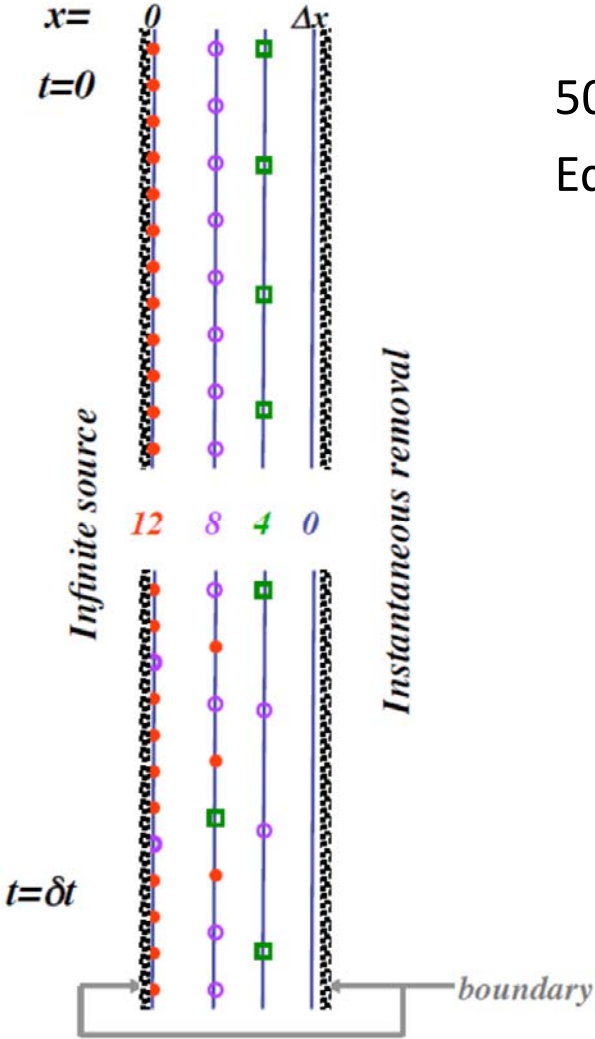
1. Flow only through 2 faces perpendicular to x-dir
2. Q, A constant
3. Instantaneous mixing within control volume

Rate of:

Accumulation = Input – Output + Net dispersion

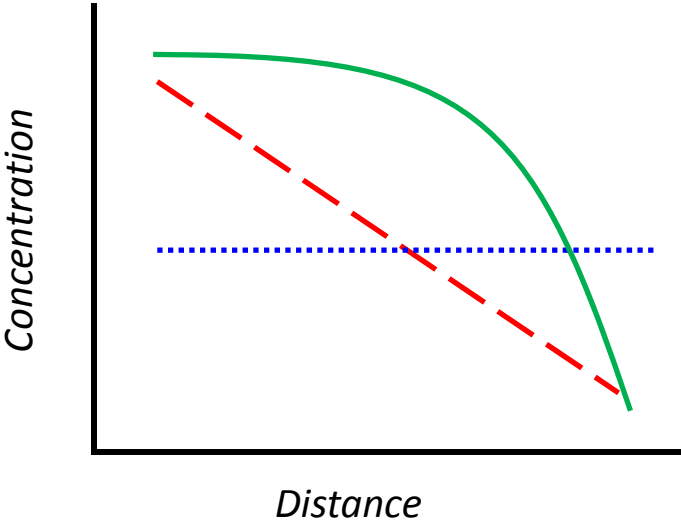
$$\frac{V\Delta C}{\Delta t} = QC_x - QC_{x+\Delta x} + \frac{\Delta M_{disp}}{\Delta t}$$

Recall molecular diffusion



50% of molecules shift position in time δt
 Equal probability of shifting right or left

When does the molecular diffusion result in concentration change with time?

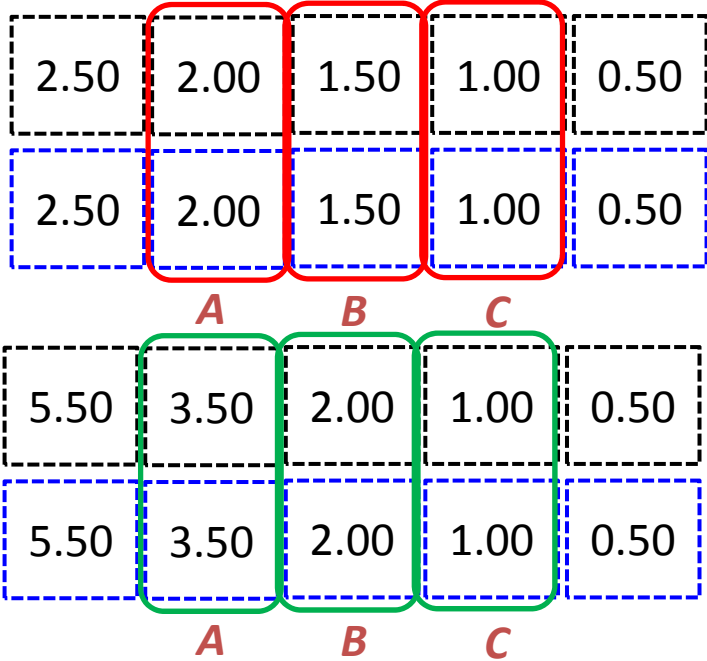


Dispersion by velocity gradient

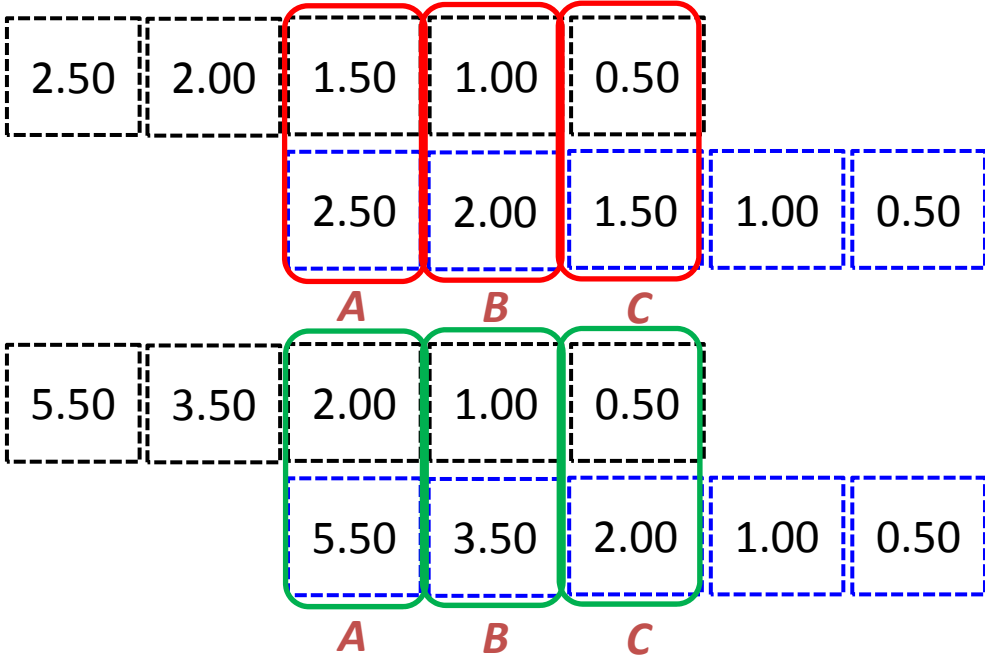
- **Turbulence -- creates velocity gradient**

Top layer moves 1 grid right & bottom layer moves 1 grid left per unit time by differential velocity

$t = 0$



$t = 1$



Modeling dispersion

- Dispersion by turbulence, etc. can be expressed by the same model as molecular diffusion
- Apply Fick's 1st law:

$$J_x = D_x' \frac{dC}{dx} \quad D_x' = \text{mechanical dispersion coefficient in x-dir [L}^2\text{/T]}$$

- The overall dispersion coefficient can be defined as the sum of molecular diffusion & mechanical dispersion coeff.

$$J_x = E_x \frac{dC}{dx}, \quad E_x = D_m + D_x'$$

E_x = overall dispersion coefficient in x-dir [L²/T]
D_m = molecular diffusion coefficient [L²/T]

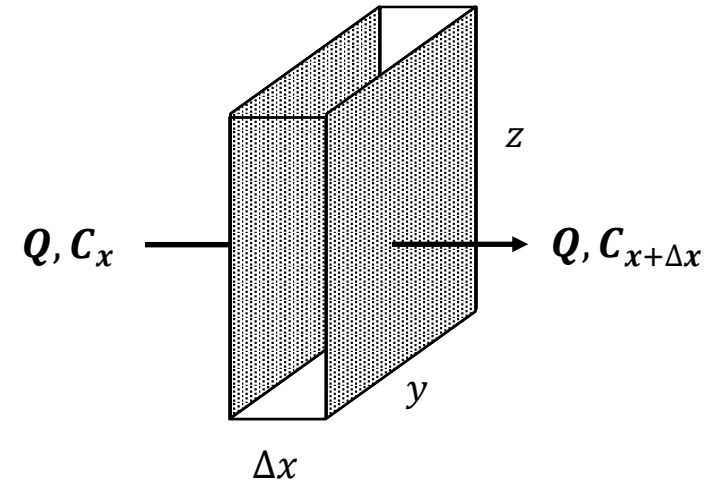
1-D advection dispersion equation

$$\frac{V\Delta C}{\Delta t} = QC_x - QC_{x+\Delta x} + \frac{\Delta M_{disp}}{\Delta t}$$

$$\frac{M_{disp,x_i}}{\Delta t} = -E_x \cdot \left(\frac{\partial C}{\partial x} \right)_{x=x_i} \times A$$

$$\frac{M_{disp,x_i+\Delta x}}{\Delta t} = E_x \cdot \left(\frac{\partial C}{\partial x} \right)_{x=x_i+\Delta x} \times A$$

$$\frac{\Delta M_{disp}}{\Delta t} = E_x \cdot A \cdot \left[\left(\frac{\partial C}{\partial x} \right)_{x=x_i+\Delta x} - \left(\frac{\partial C}{\partial x} \right)_{x=x_i} \right]$$



$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + E_x \frac{\partial^2 C}{\partial x^2}$$

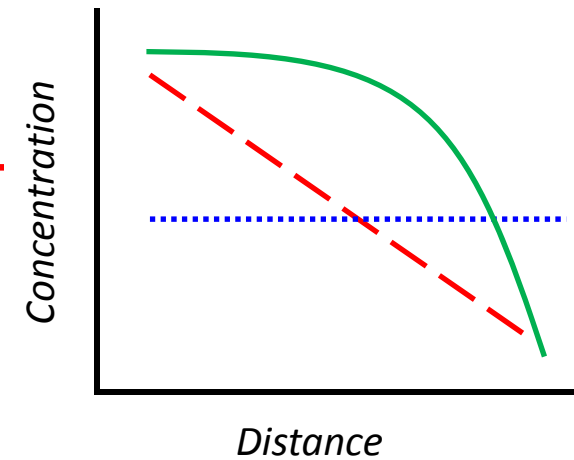
u = velocity of fluid (in x-dir) [L^2/T]

Dispersion occurs:

- **When $\partial^2 C / dx^2 \neq 0$**
- **By multiple mechanisms**
 - Molecular diffusion
 - Variable velocity, turbulence (mechanical dispersion)
 - In surface water, molecular diffusion often very small compared to mechanical dispersion
- **With or without a net advective velocity**

1-D advection dispersion equation

$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + E_x \frac{\partial^2 C}{\partial x^2}$$



Dispersion from a pulse input of tracer

Governing eq.:
$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + E_x \frac{\partial^2 C}{\partial x^2}$$

BC's & IC's: $C = 0$ at $x > 0$ & $t = 0$

$M_0 = \text{finite mass pulse at } x = 0 \text{ \& } t = 0, \quad C(0,0) = \infty$

$C = 0$ at $x \rightarrow 0$ for all t

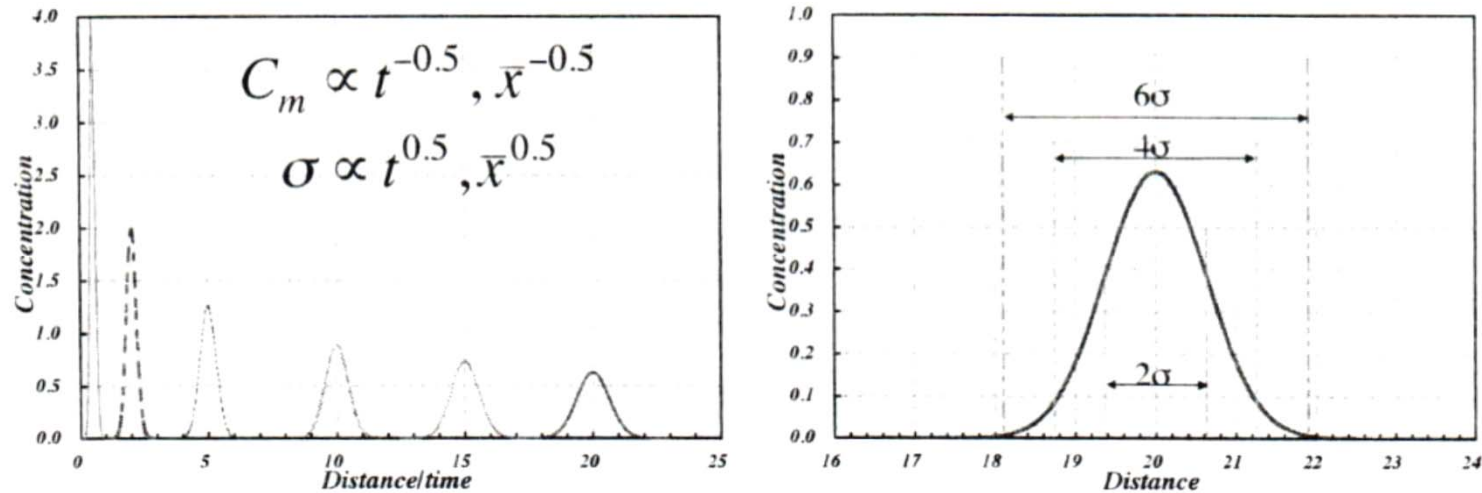
define new, dimensionless variable η and solve:

$$\eta = \frac{x - ut}{\sqrt{4E_x t}} \quad C(x, t) = C_{max} e^{-\eta^2} = \frac{M_0}{A \sqrt{4\pi E_x t}} e^{-\left[\frac{(x-ut)^2}{4E_x t}\right]}$$

A = cross-sectional area

*Solution is symmetric in space, centered at **ut**
Solution is in the form of a normal distribution with
mean = ut & **$\sigma = (2E_x t)^{0.5}$***

Dispersion from a pulse input of tracer



Mass is conserved, i.e., areas under all curves are the same

95% of the mass is located between $x \pm 2\sigma$; 99% between $x \pm 2.6\sigma$

$$C_x = 0.01C_m @ x \pm 3\sigma$$

We define: $\Delta x_{plume} = 6\sigma$

What if the concentration is observed at a certain distance, L, over time?

Peclet

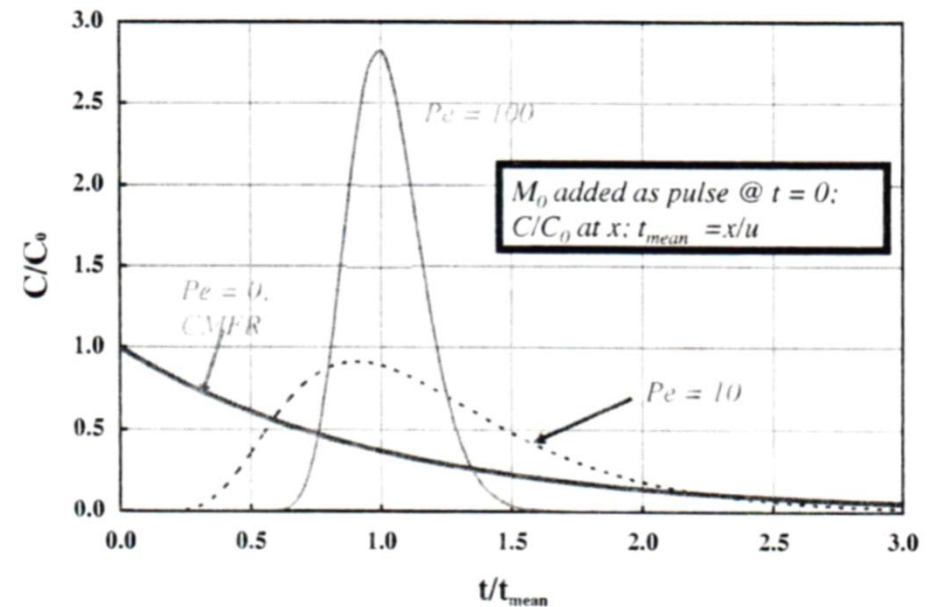
$$t_{advect} = \frac{L_x}{u_x} \quad t_{disp} = \frac{L_x^2}{E_x}$$

$$\frac{t_{disp}}{t_{advect}} = \frac{L_x^2/E_x}{L_x/u_x} = \frac{L_x u_x}{E_x} = \frac{L_x}{\alpha_x} = \mathbf{Pe}$$

For given α_x ; Pe increases with increasing length of system (river, reactor, etc.)

$Pe \rightarrow \infty$ Plug flow

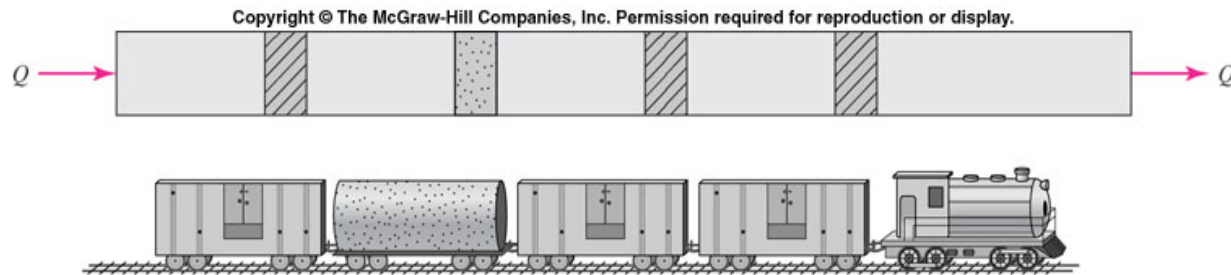
$Pe \rightarrow 0$ Completely mixed



Plug flow vs. Completely mixed reactors

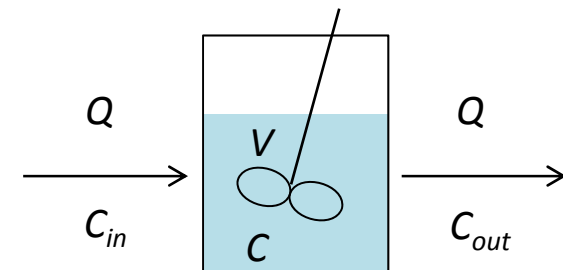
- **Plug-flow reactor (PFR)**

- Assume no mixing in the direction of flow; complete mixing in the direction perpendicular to the flow
- Long reactors (e.g., disinfection), rivers, aqueducts, pipes, etc.



- **Completely-mixed flow reactors (CMFR) or continuously-stirred tank reactors (CSTR)**

- Complete mixing of the contents of the reactors
- Common reactor setting for biological reactions, lakes, reservoirs, etc.



Advection, dispersion & reaction

Governing eq.:
$$\frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + E_x \frac{\partial^2 C}{\partial x^2} - kC$$

BC's & IC's: $C = 0$ at $x > 0$ & $t = 0$

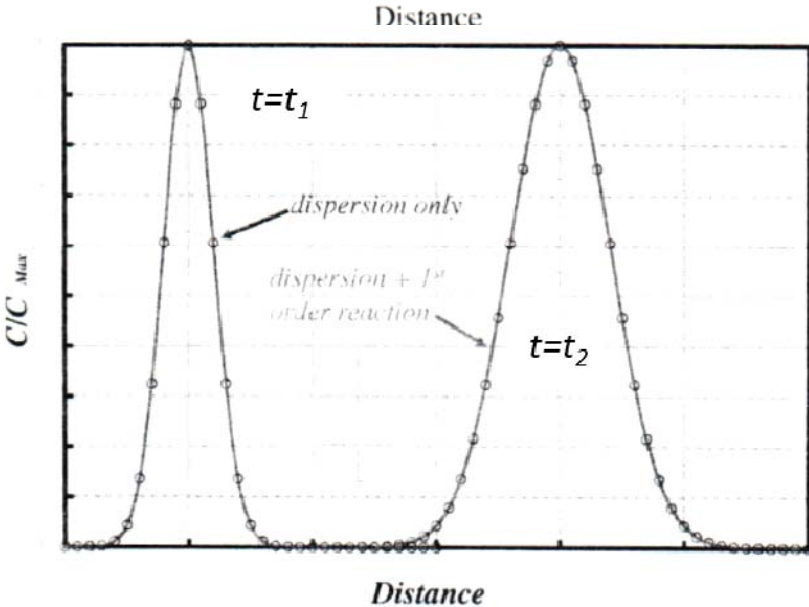
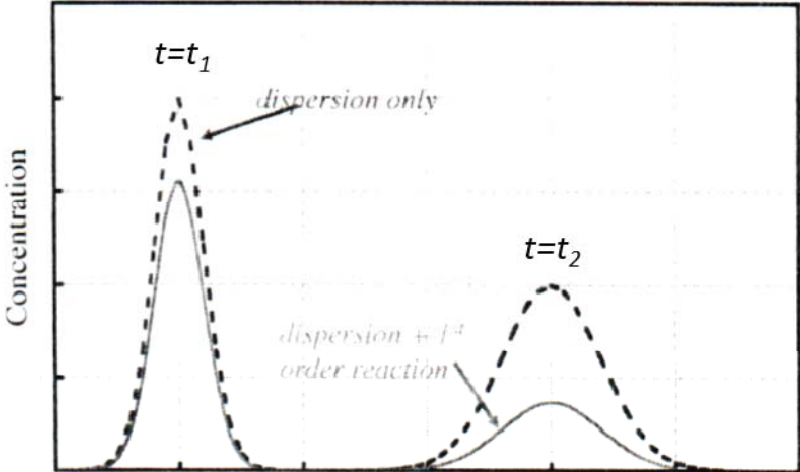
$M_0 = \text{finite mass pulse at } x = 0 \text{ \& } t = 0, \quad C(0,0) = \infty$

$C = 0$ at $x \rightarrow 0$ for all t

Because reaction is 1st order, $M_{tot,t} = M_0 e^{-kt}$

$$C(x, t) = \frac{M_0 e^{-kt}}{A \sqrt{4\pi E_x t}} e^{-\left[\frac{(x-ut)^2}{4E_x t}\right]} = \frac{M_0}{A \sqrt{4\pi E_x t}} e^{-\left[\frac{(x-ut)^2 + kt}{4E_x t}\right]}$$

Dispersion + 1st order reaction



$$C(x, t) = C_{max} e^{-\left[\frac{(x-ut)^2}{4E_x t}\right]}$$

Dispersion

$$C_{max} = \frac{M_0}{A\sqrt{4\pi E_x t}} \times e^{-kt}$$

Reaction

Steady state response for reactor at $x=L$

$$\text{Governing eq.: } \frac{\partial C}{\partial t} = -u \frac{\partial C}{\partial x} + E_x \frac{\partial^2 C}{\partial x^2} - kC$$

$$\begin{aligned} \text{BC's \& IC's: } C &= 0 \quad \text{at } x \geq 0 \quad \& \quad t = 0 \\ C &= C_I \quad \text{at } x = 0 \quad \& \quad t > 0 \end{aligned}$$

Steady state solution:

$$\frac{C_E}{C_I} = \frac{4a \cdot e^{Pe/2}}{[(1+a)^2 \cdot e^{(a \cdot Pe/2)} - (1-a)^2 \cdot e^{-(a \cdot Pe/2)}]}$$

$$a = \left[1 + \frac{4k\bar{t}}{Pe} \right]^{0.5}$$

$$Pe = \frac{u_x L}{E_x}$$

Calculations show plug flow approximation is accurate to within 1% if $Pe \geq 100$ and $(k\bar{t}/Pe) \leq 0.01$

\bar{t} = hydraulic retention time = V/Q

$$\begin{aligned} \text{PFR solution: } C_E/C_I &= e^{-k\bar{t}} \\ \text{Steady-state CSTR solution: } C_E/C_I &= (1 + k\bar{t})^{-1} \end{aligned}$$

Rivers as plug flow reactors

- **Rivers are typically relatively long, narrow & shallow**
 - Even if transverse dispersion is substantially less than longitudinal dispersion, vertical and transverse mixing is likely to be complete
 - $t_{disp} \sim L^2$

Consider the following river setting (Sacramento River, USA):

$H = 4 \text{ m}$	$E_x = 15 \text{ m}^2/\text{s}$	<i>Travel time = 80,000 seconds</i>
$W = 40 \text{ m}$	$E_y = 0.12 \text{ m}^2/\text{s}$	$t_{disp,x} = 1.1 \times 10^8 \text{ s}$
$L = 40,000 \text{ m}$	$E_z = 0.12 \text{ m}^2/\text{s}$	$t_{disp,y} = 13,000 \text{ s}$
$u_x = 0.5 \text{ m/s}$		$t_{disp,z} = 130 \text{ s}$

Dispersion coefficients in aqueous systems

Environment	$E, \text{m}^2/\text{sec}$
Estuaries (longitudinal)	$10^2 - 10^3$
Rivers (longitudinal)	$10^0 - 10^2$
Rivers (lateral)	$10^{-2} - 10^{-1}$
Surface waters (vertical)	$10^{-6} - 10^{-3}$
Pipes, ducts (normal to flow)	$10^{-5} - 10^{-2}$
Solutes in water	$10^{-10} - 10^{-8}$
Solutes in bioturbed sediments	$10^{-9} - 10^{-8}$
Solutes in compacted soils, sediments	$10^{-10} - 10^{-12}$