재료의 기계적 거동 (Mechanical Behavior of Materials)

Lecture 9 – Dislocations (Elastic Properties)

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Introduction

• Dislocations are line defects. Thus, they distort the perfect crystal lattice.

♦ This lattice distortion increases the free energy of the crystal lattice. This is a direct result of the elastic strain fields that surround dislocations.

◆ Interactions between the strain fields (i.e., the distorted regions) around dislocations (and those of other defects) ultimately determines the mechanical properties of the lattice.



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FIGURE 4.5

(a) Screw dislocation *AB* formed in a crystal. (b) Elastic distortion of a cylindrical tube simulating the distortion produced by the screw dislocation in (a).



Near the center of the dislocation along the dislocation line, the displacements are too large to be calculated with elasticity theory. Hooke's law does not apply here. This region is called the *dislocation core*. A few lattice spacings from the core, say at a distance r_0 , we can model things using elasticity theory. Hooke's law applies here. r_0 is called the *cutoff radius*. It typically has a value near *b*.



$$\varepsilon_{yz} = \frac{1}{2} \left(u_{z,y} + u_{y,z} \right)$$

$$= \frac{b}{4\pi} \frac{\cos \theta}{r}$$

$$= \frac{b}{4\pi} \frac{x}{x^2 + y^2}$$

$$\varepsilon_{xz} = \frac{1}{2} \left(u_{z,x} + u_{x,z} \right)$$

$$= -\frac{b}{4\pi} \frac{\sin \theta}{r}$$

$$= -\frac{b}{4\pi} \frac{y}{x^2 + y^2}$$

$$\varepsilon_{xx} = \varepsilon_{yy} = \varepsilon_{zz} = \varepsilon_{xy} = 0$$

$$\sigma_{yz} = \frac{Gb}{2\pi} \frac{x}{x^2 + y^2}$$

$$= \frac{Gb}{2\pi} \frac{\cos \theta}{r}$$

$$= \frac{Gb}{2\pi} \frac{\cos \theta}{r}$$

$$= -\frac{Gb}{2\pi} \frac{\sin \theta}{r}$$

$$= -\frac{b}{4\pi} \frac{y}{x^2 + y^2}$$

$$\sigma_{xx} = \sigma_{yy} = \sigma_{zz} = \sigma_{xy} = 0$$



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The pure edge dislocation has a plane strain condition since the displacement along the dislocation line, u_z , is absent. The stress field around a straight edge dislocation is obtained from the equilibrium condition.



$$\sigma_{xx} = -\frac{Gb}{2\pi(1-\nu)} \frac{y(3x^2+y^2)}{(x^2+y^2)^2}$$

$$\sigma_{yy} = \frac{Gb}{2\pi(1-\nu)} \frac{y(x^2-y^2)}{(x^2+y^2)^2}$$

$$\sigma_{zz} = \nu(\sigma_{xx} + \sigma_{yy})$$

$$= -\frac{Gb\nu}{\pi(1-\nu)} \frac{y}{x^2+y^2}$$

$$\sigma_{xy} = \frac{Gb}{2\pi(1-\nu)} \frac{x(x^2-y^2)}{(x^2+y^2)^2}$$

$$\sigma_{zx} = \sigma_{yz} = 0$$

$$\sigma_{rr} = \sigma_{\theta\theta} = -\frac{Gb}{2\pi(1-\nu)} \frac{\sin\theta}{r}$$

$$\sigma_{zz} = \nu(\sigma_{rr} + \sigma_{\theta\theta}) = -\frac{Gb\nu}{\pi(1-\nu)} \frac{\sin\theta}{r}$$

$$\sigma_{r\theta} = \frac{Gb}{2\pi(1-\nu)} \frac{\cos\theta}{r}$$

$$\sigma_{zr} = \sigma_{\theta z} = 0$$





$$\sigma_{xx} = -\frac{Gb}{2\pi(1-\nu)} \frac{y(3x^2+y^2)}{(x^2+y^2)^2}$$

$$\sigma_{yy} = \frac{Gb}{2\pi(1-\nu)} \frac{y(x^2-y^2)}{(x^2+y^2)^2}$$

$$\sigma_{zz} = \nu(\sigma_{xx} + \sigma_{yy})$$

$$= -\frac{Gb\nu}{\pi(1-\nu)} \frac{y}{x^2+y^2}$$

$$\sigma_{xy} = \frac{Gb}{2\pi(1-\nu)} \frac{x(x^2-y^2)}{(x^2+y^2)^2}$$

$$\sigma_{zx} = \sigma_{yz} = 0$$

$$\sigma_{xx} = -\frac{Gb}{2\pi r(1-\nu)} \sin\theta \cdot (2+\cos 2\theta)$$

$$\sigma_{yy} = \frac{Gb}{2\pi r(1-\nu)} \sin\theta \cdot \cos 2\theta$$

$$\tau_{xy} = \tau_{yx} = \frac{Gb}{2\pi r(1-\nu)r} \cos\theta \cdot \cos 2\theta$$

$$\sigma_{zz} = -\frac{Gb\nu}{\pi(1-\nu)r} \sin\theta$$







• *E*_{total} can be divided into two parts:

 $E_{\text{total}} = E_{\text{core}} + E_{\text{elastic (strain energy)}}$

 The core contribution is difficult to calculate. It is estimated to have a value of ≈0.5 eV/plane threaded by a dislocation.

Elastic strain energy per unit length in screw dislocation

$$\frac{E_{elast}(screw)}{l} = \int_{r_0}^{R} 2G \frac{b^2}{(4\pi r)^2} 2\pi r dr$$
$$= \frac{Gb^2}{4\pi} \int_{r_0}^{R} \frac{1}{r^2} dr = \frac{Gb^2}{4\pi} \ln\left(\frac{R}{r_0}\right)$$



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Elastic strain energy per unit length in edge dislocation



$$dE_{el}(edge) = \frac{1}{2}\sigma_{xy}dA \cdot b$$
$$dA = dx \cdot l$$

$$\frac{E_{el}(edge)}{l} = \int_{r_0}^{R} \frac{1}{2} bD \frac{x(x^2 - y^2)}{(x^2 + y^2)^2} \bigg|_{y=0} bdx$$
$$= \frac{bD}{2} \ln\left(\frac{R}{r_0}\right)$$
$$= \frac{Gb^2}{4\pi(1 - \nu)} \ln\left(\frac{R}{r_0}\right)$$

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Elastic strain energy per unit length in mixed dislocation





 $E_{\text{elastic}} = \alpha G b^2$ where $\alpha \approx 0.5 - 1.0$ OR $E_{\text{elastic}} \propto b^2$ One of the important <u>consequences</u> of this relationship is that it allows us to determine whether or not it is energetically feasible for two dislocations to react and combine to form another. This is known as <u>Frank's Rule</u>.



FIGURE 4.9 Reaction of two dislocations to form a third.

Yes if $(b_1^2 + b_2^2) > b_3^2$ No if $(b_1^2 + b_2^2) < b_3^2$ No net energy change if $(b_1^2 + b_2^2) = b_3^2$





Force Acting on a Dislocation

- Total area of slip plane : A
- Average shear displacement : (*dl ds*/A)b
- Shear force on slip plane : τA
- Work done when the element of slip occurs : $dW = \tau A (dl ds/A)b = \tau (dl ds)b$



- The glide force F on a unit length of dislocation $F=dW/(dl ds) = dW/dA = \tau b$

Glide force is always directed normal to the dislocation line.





Peach-Koehler equation







$$\mathbf{F}_{x} = \frac{Gbb'}{2\pi(1-\nu)r}\cos\theta\cos2\theta$$

$$\mathbf{F}_{y} = \frac{Gbb'}{2\pi(1-v)r} \sin\theta(2+\cos 2\theta)$$







Figure 4.13 Glide force per unit length between parallel edge dislocations with parallel Burgers vectors from equation (4.36). Unit of force F_x is $Gb^2/2\pi(1-\nu)y$. The full curve A is for like dislocations and the broken curve B for unlike dislocations.

$$\mathbf{F} = b_1 \frac{Gb_2}{2\pi(1-\nu)} \frac{x(x^2-y^2)}{(x^2+y^2)^2} \mathbf{i} + b_1 \frac{Gb_2}{2\pi(1-\nu)} \frac{y(3x^2+y^2)}{(x^2+y^2)^2} \mathbf{j}$$



FIGURE 4.15

Stable positions for two edge dislocations of (a) the same sign and (b) opposite sign.





Screw dislocation :

$$F_r = \frac{Gbb'}{2\pi r}$$

