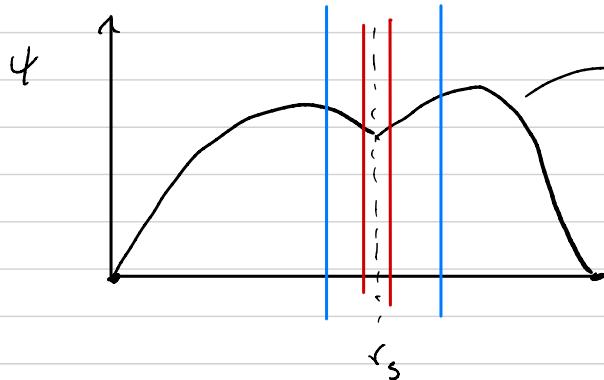


## 5/31 Resistive tearing instability - continued

## 4. Boundary layer matching

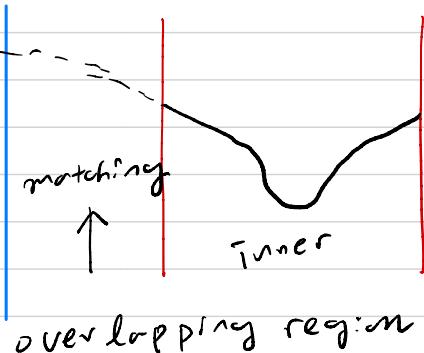
## 2. outer ideal MHD

2<sup>nd</sup> order ODE for 4



3. inner (inertia resistive) MHD

4<sup>th</sup> order ODE for  $\psi$



shortcuts are given when

## C17 Internal linear problem

$$\left[ \frac{d\ln k}{k} = \frac{d}{\theta_1} \ln 4 \right] \text{only important for matching}$$

$$\Delta'_{\text{outer}} = \frac{1}{\psi} \frac{d\psi}{dr} \left. \right|_{\begin{array}{l} r=r_s + \mathcal{O}(5) \\ r=r_s - \mathcal{O}(5) \end{array}} \quad \xrightarrow{\text{layer width}}$$

fearing mode index

$$\Delta'_{\text{outer}} \sim \Delta'_{\text{inner}} \quad \xleftarrow{\text{non-ideal layer MHID}}$$

ideal MHID

(2) Constant- $\psi$  approximation

take up as constant within ladder

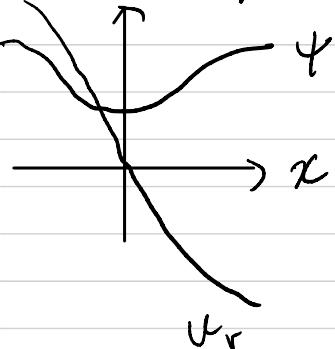
$$\Delta'_{\text{imer}} = \int_{r_s - \delta\omega}^{r_s + \delta\omega} dr \frac{d}{dr} \left( \frac{\psi'}{\psi} \right) \sim \int dr \frac{1}{\psi} \frac{d\psi}{dr} \frac{1}{r^2}$$

$$= \frac{\mu_0 \gamma}{\eta} \int dr \left( 1 + \frac{B_\theta}{\gamma} \left( 1 - \frac{n_g}{m} \right) \frac{u_r}{\psi} \right)$$

expand  $r = r_s + x$ ,  $1 - \frac{n_g}{m} \approx -\frac{g'}{g} x$ ,  $y = \frac{u_r}{\psi}$

$$\left[ \frac{\gamma \rho r^2 \frac{du_r}{dx}}{m^2} - \frac{B_\theta}{\mu} \frac{g'}{g} x \frac{d\psi}{dx} - \frac{g'}{g} \psi \right]$$

$$\frac{d^2\psi}{dx^2} = \frac{\mu_0}{\eta} \left( r\psi - B_\theta \frac{g'}{g} x u_r \right)$$



$$\frac{dy}{dx} - \left( \frac{m^2 B_\theta^2 g'^2}{\rho \eta \gamma r^2 g^2} \right) xy = - \left[ \frac{m^2 B_\theta g'}{\rho \eta r^2 g} \right] x - \frac{m^2}{\rho \eta r^2} \frac{g'}{g}$$

$$y = y_{\text{odd}} + y_{\text{even}}$$

$$\Delta'_{\text{inner}} = \frac{\mu_0 \gamma}{\eta} \int_{-\infty}^{\infty} dx \left( 1 - \frac{B_\theta g'}{\gamma g} x (y_{\text{odd}} + y_{\text{even}}) \right)$$

Now, Rescale by  $x = x/\sigma$   $y = y/\beta$

$$\rightarrow \frac{\beta}{\sigma^2} \frac{d^2Y}{dx^2} - \beta \sigma^2 \left( \right) x^2 Y = - \left[ \right] \sigma x$$

$$\frac{d^2Y}{dx^2} - \sigma^4 \left( \right) x^2 Y = - \left[ \right] \frac{\sigma^3}{\beta} x$$

layer width

$$\frac{d^2Y}{dx^2} - x^2 Y = x \quad \left( \sigma \equiv \left( \frac{\rho \eta \gamma r^2 g^2}{B_\theta^2 m^2 g'^2} \right)^{\frac{1}{4}} \right)$$

$$\beta = \left( \frac{\rho \eta r^2 g}{m^2 B_\theta^2 g'^2} \right)^{-\frac{1}{4}} \sigma^3$$

$$\rightarrow Y = \frac{x}{2} \int_0^1 dt e^{-x^2 t/2} (1-t)^{-\frac{1}{4}}$$

$$\rightarrow \Delta'_{\text{inner}} = \frac{\mu_0 \gamma \sigma}{\eta} \int_{-\infty}^{\infty} dx (1 - XY) \quad \sigma \ll x \ll 1$$


$$= \frac{\mu_0 \gamma \sigma}{\eta} \left( \frac{\pi \Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \right) = \Delta'_{\text{outer}} \equiv \Delta'$$

$$\rightarrow \gamma^{\frac{5}{4}} \frac{\mu_0}{\eta} \left( \frac{\rho \eta r^2 g^2}{B_\phi^2 n^2 g^{1/2}} \right)^{\frac{1}{4}} \left( \frac{\pi \Gamma(\frac{3}{4})}{\Gamma(\frac{1}{4})} \right) = \Delta'$$

$$\gamma = \left( \frac{\Gamma(\frac{1}{4}) r_s}{\pi \Gamma(\frac{3}{4})} \right)^{4/5} \left( \eta \frac{r_s g}{g} \right)^{2/5} (\Delta')^{4/5} \tilde{\tau}_R^{-3/5} \tilde{\tau}_A^{-2/5}$$

$$\tilde{\tau}_A = \frac{r_s}{B_\phi / (\mu_0 \rho)^{\frac{1}{2}}} \quad \tilde{\tau}_R = \frac{\mu_0 r_s^2}{\eta}$$

5. physical implications for our  $\gamma$

$\rightarrow$  surprisingly faster than  $\tilde{\tau}_R$

Furth/Killeen/Rosenbluth (FKR) '1962

ex)  $B_\phi = 5 T$ ,  $n_e = 10^{20} m^{-3}$ ,  $T_e = 5 \text{ keV}$ ,  $r_s = 1 m$

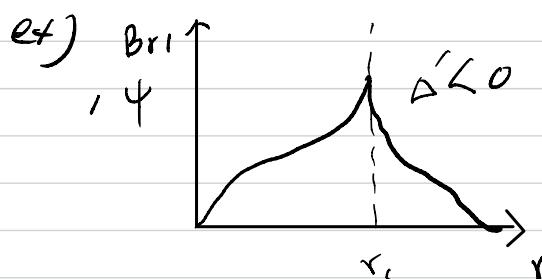
$\tilde{\tau}_A \sim 0.1 \mu s$ ,  $\tilde{\tau}_R \sim 10 \text{ min}$ ,  $\gamma \sim 70 \text{ ms}$

$\rightarrow$  unstable if  $\Delta' > 0$

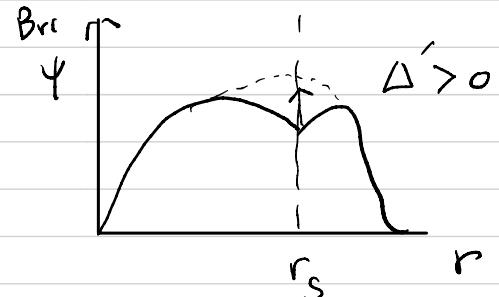
tearing mode (TM) stability

totally determined

by outer layer sol.  $\Delta'$



stable



unstable

$\rightarrow$  finite Brie  $e^{i(m\theta - n\phi)}$  of  $g = \frac{m}{n}$

Let  $B_{r_1} \sin(m\theta - n\phi)$

$$= B_{r_1} \sin\left(m(\theta - \frac{n}{m}\phi)\right) = B_{r_1} \sin(m\alpha)$$

$$\alpha \equiv \theta - \frac{n}{m}\phi = \theta - \phi/g$$

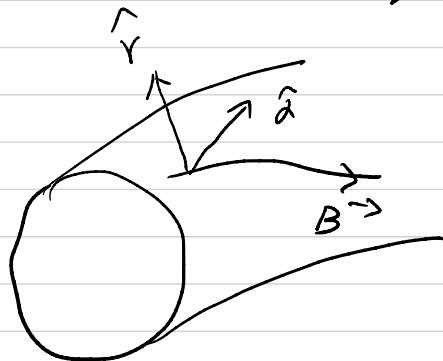
binormal to  $\hat{t}, \hat{b}$

$$\vec{B} \cdot \vec{\nabla} \alpha = \vec{B} \cdot \vec{\nabla} \theta - \vec{B} \cdot \vec{\nabla} \phi/g$$

$$= \frac{1}{r} B_\theta \left( 1 - \frac{n}{m} g \right)$$

$$\approx -\frac{1}{r_s} B_\theta \frac{g'}{g} x$$

$$\vec{B} \cdot \vec{\nabla} r = B_{r_1} \sin(m\alpha)$$



$$\frac{dr}{d\alpha} = \frac{\vec{B} \cdot \vec{\nabla} r}{\vec{B} \cdot \vec{\nabla} \alpha} \quad r = r_s + x$$

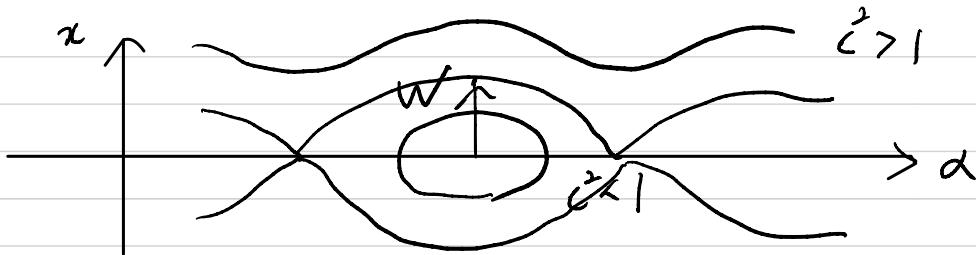
$$x \frac{dx}{d\alpha} = -r_s \frac{g B_{r_1}}{B_\theta g'} \sin(m\alpha)$$

$$\frac{1}{2} x^2 = C + \frac{r_s g B_{r_1}}{m B_\theta g'} \cos(m\alpha)$$

$$x = \pm \sqrt{C + \frac{\cos(m\alpha)}{2}}$$

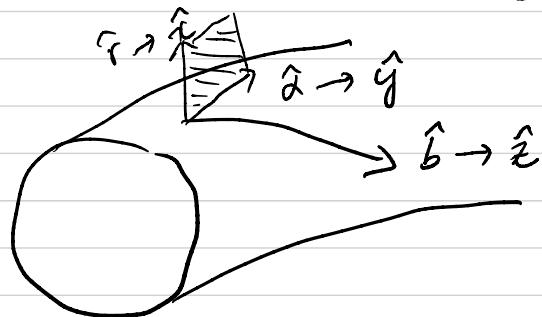
$$= \pm \sqrt{C^2 - \sin^2\left(\frac{m\alpha}{2}\right)} \quad w = \left(\frac{4r_s g}{mg' B_\theta} B_{r_1}\right)^{\frac{1}{2}}$$

half width



$\rightarrow$  finite  $B_r$ ,  $\rightarrow$  magnetic island

6. Reduced to a slab geometry



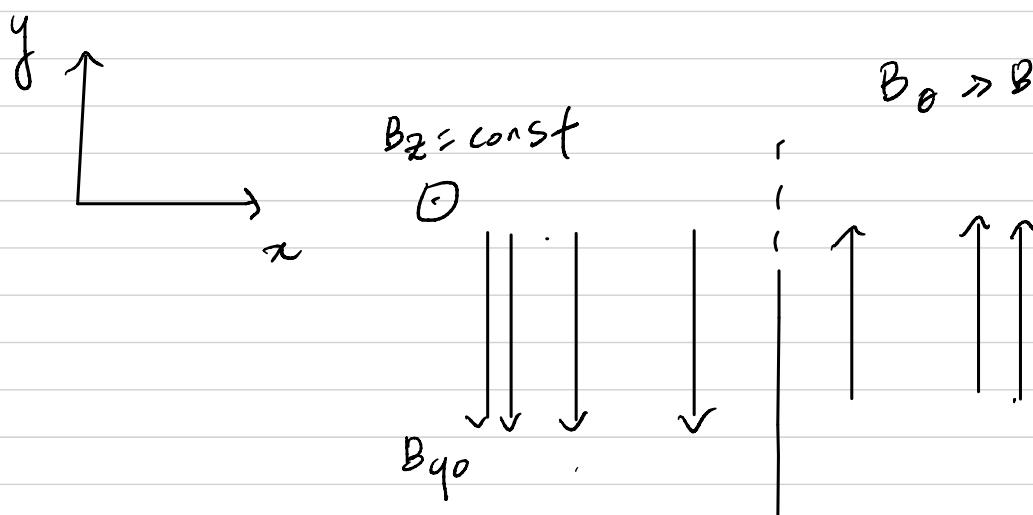
$$\vec{B} = B_\phi \hat{\phi} + B_0 \hat{\theta}$$

$$\rightarrow B_x \hat{x} + B_0 \left(1 - \frac{m}{n} \frac{q}{g}\right) \hat{y}$$

$$\approx B_x \hat{x} - B_0 \frac{q}{g} x \hat{y}$$

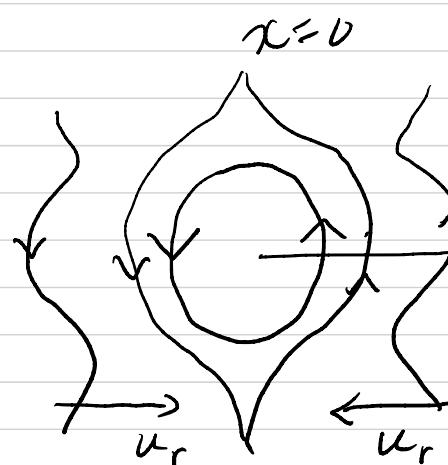
$$\rightarrow B_x \hat{x} + \frac{B_{q0}}{a} x \hat{y}$$

$$B_0 \rightarrow B_{q0}, \frac{q}{g} \rightarrow \frac{1}{a}, \frac{m}{r} \rightarrow k$$



$$\vec{B} = \vec{\psi} \times \hat{z} + B_\phi \hat{\phi}$$

$$\vec{u} = \vec{\phi} \times \hat{z} + u_r \hat{r}$$



$$\frac{\partial \vec{\psi}}{\partial t} + u_r \vec{\hat{z}} \cdot \vec{\nabla} \vec{\psi} = -n \vec{j}$$

$$\rho \left( \frac{\partial \vec{w}}{\partial t} + u_r \vec{\hat{z}} \cdot \vec{\nabla} \vec{w} \right)$$

$$= (\vec{B} \cdot \vec{\nabla}) \vec{j}$$

## 6/2 non-linear and drift instabilities

\* notes for non-linear tearing mode

{ Linear theory : assume islands are small

$$\text{width } \delta \propto (\eta\gamma)^{\frac{1}{4}} \propto (\eta \cdot \eta^{\frac{3}{5}})^{\frac{1}{4}} \propto \eta^{\frac{1}{5}} \gg \omega$$

Non-linear theory for big enough island

$$\frac{\partial \psi}{\partial t} + \vec{U}_E \cdot \vec{\nabla} \psi = -\eta \int_{\mathbb{R}} \quad \vec{U}_E = \vec{\nabla} \phi \times \hat{z}$$

Ohm's law

$$\frac{\partial \psi}{\partial t} - \vec{B} \cdot \vec{\nabla} \phi = -\eta \int_{\mathbb{R}} = \frac{\eta}{\mu_0} \vec{\nabla} \phi$$

in a slab note  $\psi = \psi_0 + \psi_1(x, t) e^{iky}$  "Fully" non-linear

Integral over magnetic islands  $\langle \vec{B} \cdot \vec{\nabla} \phi \rangle = 0$

$$\omega \frac{\partial \psi}{\partial t} \approx \frac{\eta}{\mu_0} \frac{\partial \psi}{\partial x} \Big|_{-\omega}^{\omega} \approx \frac{\eta}{\mu_0} \psi \Delta' \quad (\text{w: full width} \times \text{half width})$$

$$\frac{1}{\psi} \frac{\partial \psi}{\partial t} \approx \frac{1}{\psi} \frac{d\psi}{dw} \frac{dw}{dt} \quad \psi \propto w^2$$

$$= \frac{2}{w} \frac{dw}{dt}$$

$$\frac{dw}{dt} = \frac{\eta}{2\mu_0} \Delta'(w)$$

island grows

when  $\Delta' > 0$ , again

[Rutherford '73]

Reality, kinetic / FLR stabilizing

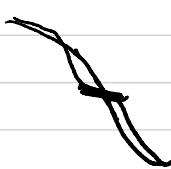
Bootstrap currents destabilizing

$$\frac{\partial \psi}{\partial t} + \vec{U}_E \cdot \vec{\nabla} \psi = -\eta \left( \int_{\mathbb{R}} + \int_{BS} \right) \quad \int_{BS} \sim \frac{e^{1/2}}{B_0} \frac{dp}{dx}$$

neoclassical tearing mode.

$$\frac{dw}{dt} = \frac{\eta}{2\mu_0} \Delta'(w) - \frac{\eta}{2} \frac{e^{1/2}}{B_0} \frac{dp}{dx} \frac{w}{|\psi|} \propto \frac{1}{w}$$

"Neoclassical tearing mode"



P

so, can be unstable ( $\frac{dw}{dt} > 0$ ) even when  $\Delta' < 0$

island saturates when  $w_{sat} \sim \mu_0 \frac{e^{1/2} dp/dx}{B_0 |\Delta'(w)|}$

## \* Resistive drift wave instabilities

- "Universal" instability even with a straight magnetic field (like  $\theta$ -pinch)
  - driven by fluid drift, density & temperature gradient
  - critical to add the "Hall" term in ohm's law
- |                               |  |  |
|-------------------------------|--|--|
| $\vec{E} = \vec{u} + \vec{B}$ | $\vec{E} = \vec{u} + \vec{B} + n\vec{j}$ | $\vec{E} = \vec{u} + \vec{B} + n\vec{j} + \left( \frac{\vec{B} \times \vec{B} - \sigma \vec{P}_e}{en} \right)$ |
| ideal MHD                     | Resistive MHD                            | Drift MHD  |

### 1. Slab model for resistive drift waves ( $x, y, z$ )

- $\vec{B}_0 = B_0 \hat{z}$  (Don't need to consider shear( $v_y'$ ))
- $\vec{f}_0 = 0$  unlike resistive MHD
- but similar to resistive MHD

$$\vec{u}_0 = 0 \quad \text{no flow in } y.$$

$$\vec{j} \cdot \vec{v} \approx \vec{j} \cdot \vec{u}_L = 0 \quad \text{Incompressibility} \quad (\vec{u}_L = \vec{\nabla}\phi \times \hat{z})$$

-  $T_i \ll T_e$  cold ion assumption

- Consider variation in equil. along with  $x$

$\rightarrow$  perturbation should be

$$\psi = \psi(x) \exp(iK_y y + iK_z z - i\omega t)$$

but let's assume

$$\sim \exp(iK_x x + iK_y y + iK_z z - i\omega t)$$

by  $K_x \gg L$  ( $L$ : scale length of equilibrium gradient)

so, it's just a wave problem  
in extended MHD.

## 2. Derivation of dispersion relation

Vorticity eq. (perp. momentum)

$$(1) \hat{z} \cdot \vec{\nabla} \times \left( \rho_0 \frac{\partial \vec{u}_1}{\partial t} \right) = \hat{z} \cdot \vec{\nabla} \times (\vec{j}_1 \times \vec{B})_1 = \vec{B}_0 \cdot \vec{\nabla} \vec{j}_z$$

Same as resistive MHD

$$\text{note } \vec{j}_z = \frac{1}{\mu_0} \left( \frac{\partial B_y}{\partial x} - i k_y B_x \right) = \frac{1}{\mu_0 k_y} \left( \frac{\partial^2}{\partial x^2} - k_y^2 \right) B_x$$

$$\uparrow \vec{\nabla} \cdot \vec{B} = 0 \quad \approx - \frac{i k_z^2}{\mu_0 k_y} B_x$$

$$\hat{z} \cdot \vec{\nabla} \times \left( \rho_0 \frac{\partial \vec{u}_1}{\partial t} \right) = -i \omega \left( \frac{\partial}{\partial x} (\rho_0 u_y) - i k_y \rho_0 u_x \right)$$

$$\vec{\nabla} \cdot \vec{u}_1 = 0 \rightarrow \approx -i \omega \rho_0 \left( \frac{\partial^2}{\partial x^2} - k_y^2 \right) u_x$$

$\rho_0 \approx \text{const.}$

$$\text{Now, } \frac{\partial^2}{\partial x^2} \sim -k_x^2 \quad k_z^2 = k_x^2 + k_y^2$$

$$\underline{\omega u_x = -k_z V_A^2 B_x / B_0}$$

(2) Ohm's law.

$$\vec{E}_1 + \vec{u}_1 \times \vec{B}_0 = n \vec{j}_1 + \frac{t}{e n} (\vec{\nabla} \times \vec{B} - \vec{\nabla} \phi)_1$$

L:  $\vec{E}_1 + \vec{u}_1 \times \vec{B}_0 = 0$ , but

$$L: E_x = n j_{||} - \frac{1}{e n} (\nabla_{||} \phi)_1$$

$$= n j_z - \frac{1}{e n} (\hat{b}_0 \vec{\nabla} \phi_1 + \hat{b}_1 \vec{\nabla} \phi_0)$$

$$= n j_z - \frac{1}{e n} (i k_z \phi_1 + \frac{B_x}{B_0} \phi_0')$$

$$\left( \frac{\partial \vec{B}}{\partial t} = -\vec{\nabla} \times (-\vec{u}_1 \times \vec{B}_0 + \vec{E}_1 \hat{z}) \right) \cdot \hat{x}$$

$$\rightarrow \omega B_x + k_z B_0 u_x = -\frac{i\eta}{\mu_0} k_\perp^2 B_x - \frac{k_y}{en} \left( ik_2 n_{e1} + \frac{B_x}{B_0} n_{eo}' \right)$$


---

(3) continuity eq

$$T_e k_{pe1} + \frac{B_x}{B_0} p_{eo}' \approx T_{eo} \left( ik n_{e1} + \frac{B_x}{B_0} n_{eo}' \right)$$

(constant  $T_e$  or  $\vec{B} \cdot \vec{\nabla} T_e = 0$ )

with  $n_e \approx n_i$

$$\rightarrow \frac{\partial n_{e1}}{\partial t} + \vec{u}_\perp \cdot \vec{\nabla} n_{eo} + \nabla_{||}(n_{eo} u_{||}) = 0$$

$\because u_e$

$$\rightarrow i\omega n_{e1} + u_x n_{eo}' + ik_2 n_{eo} u_x = 0$$

{ \* one can include  $u_1^2 = u_E^2 + u_{pe1}^2$  }

(4) parallel momentum eq. (for  $u_z$ )

$$\rho_e \frac{\partial u_{||}}{\partial t} = -(\nabla_{||} P_e)_z \quad (\because P_{||} \ll P_e)$$

$$-\imath \omega \rho_0 u_z = -T_{eo} \left( ik_2 n_{e1} + \frac{B_x}{B_0} n_{eo}' \right)$$


---

(4)  $\rightarrow$  (3)  $\rightarrow$  (2)  $\rightarrow$  (1)

( $u_z$ ,  $n_{e1}$ ,  $B_x$ ,  $u_x$ )

$$\rightarrow (\omega^2 - k_z^2 V_A^2) (\omega^2 - \omega_{ce}^2 \omega - k_z^2 c_s^2) = -\frac{i\eta}{\mu_0} k_\perp^2 \omega (\omega^2 - k_z^2 c_s^2)$$


---

$$V_A = \frac{B_0}{(\rho_0 \mu_0)^{1/2}} \quad c_s = (T_e/m)^{1/2}, \quad V_{ce} = -\frac{T_{eo}}{en_{eo} B_0} \frac{dn_{eo}}{dx}, \quad \omega_{ce} = k_y V_{ce}$$

electron diamagnetic  
velocity with const  $T_e$

### 3. Characteristics of wave instability

(i) for  $\eta \approx 0$

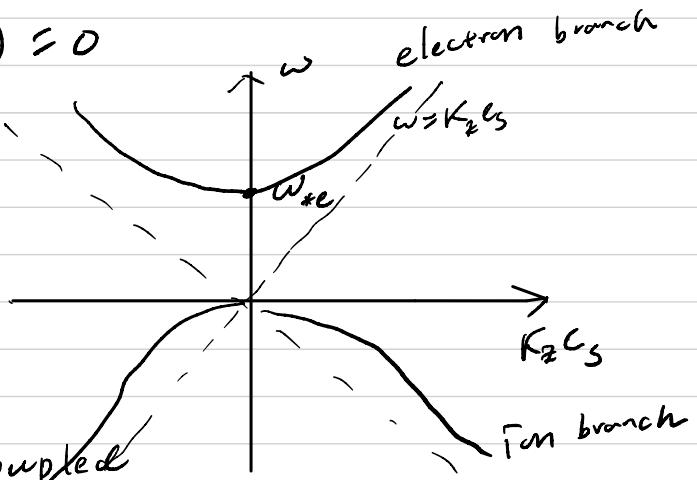
$$(\omega^2 - k_z^2 V_A^2)(\omega^2 - \omega_{ce}^2 \omega - k_z^2 c_s^2) = 0$$

↓                    ↓  
Shear Alfvén      drift wave

-  $\omega$  is all real

w/o damping or

rowth.



(ii) for  $\eta \neq 0$ , waves are coupled.

for  $\omega_{ce} \sim K_z c_s \ll K_z V_A$

(i) High frequency branch

$$\omega^2 - k_z^2 V_A^2 \approx -i\frac{\eta}{\mu_0} K_\perp^2 \omega \quad (\text{Hw # H-5})$$

(ii) Low frequency branch

$$\omega^2 - \omega_{ce}^2 \omega - k_z^2 c_s^2 = \frac{i\eta K_\perp^2}{\mu_0 K_z^2 V_A^2} \omega (\omega^2 - k_z^2 c_s^2)$$

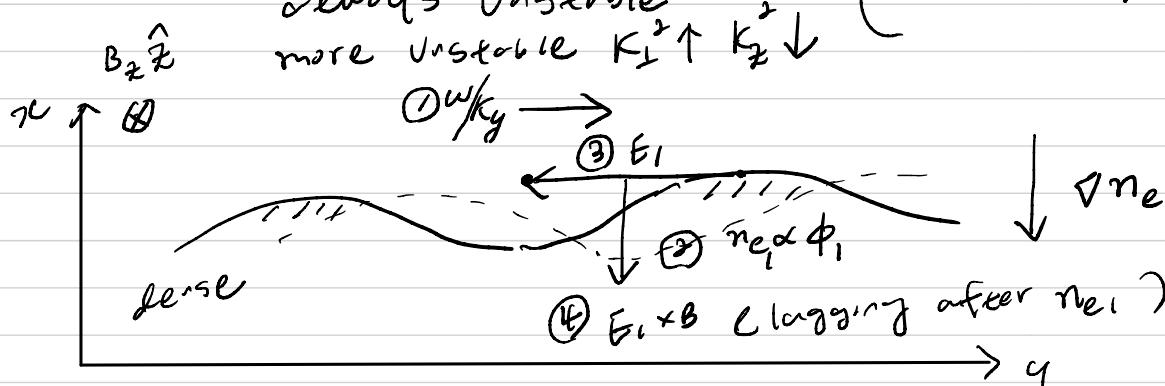
Let  $\omega \rightarrow \omega + i\gamma$  ( $\gamma \ll \omega$ )

(i)  $\gamma \approx -\eta K_\perp^2 / 2\mu_0$  Shear Alfvén damping

(ii)  $\gamma \approx \frac{\eta K_\perp^2 \omega^2 (\omega^2 - k_z^2 c_s^2)}{\mu_0 K_z^2 V_A^2 (\omega^2 + k_z^2 c_s^2)}$  drift wave growth  
(instability)

always unstable  
more unstable  $K_\perp^2 \uparrow k_z^2 \downarrow$

( $\because \omega > k_z^2 c_s^2$ .)



Source of micro-instability - small scale turbulence

$$(\omega^2 - k_z^2 V_A^2)(\omega^2 - \omega_{ce}^2 \omega - k_z^2 c_s^2) \approx i \left( \begin{array}{l} \text{collissionless drift kinetic} \\ \text{effects (e.g. ITG, ETG, TEM)} \end{array} \right)$$