

446.631A

소성재료역학  
(Metal Plasticity)

Chapter 3: Instability  
in simple tension test

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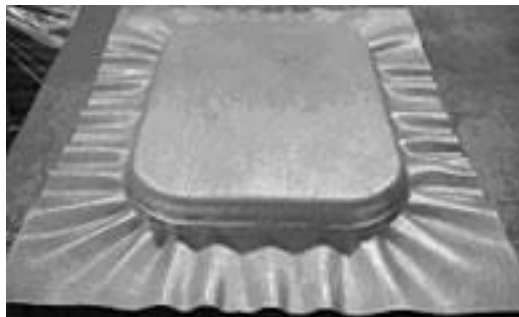
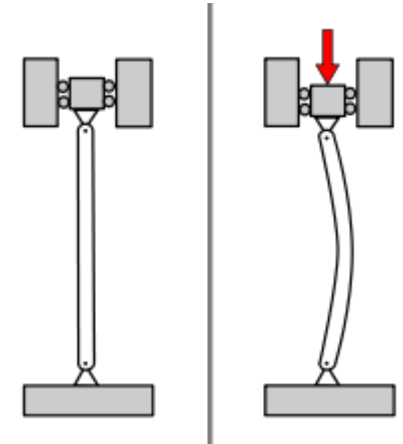
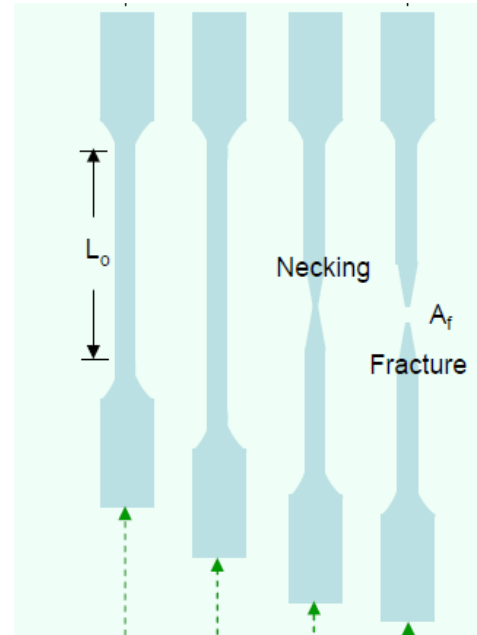
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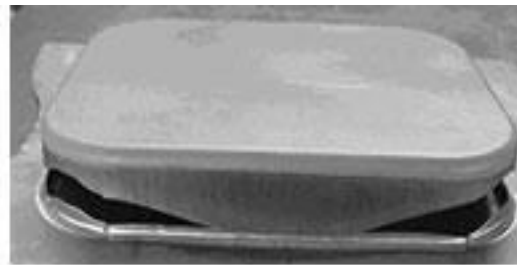
TA: Chanyang Kim (30-522)

# Instability

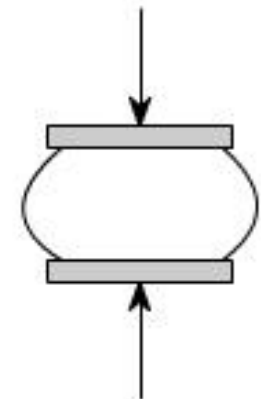
- Necking
  - ✓ sheet and bulk under tension
  - ✓ localized deformation
- Barreling
  - ✓ Bulk under compression
- Buckling
  - ✓ sheet under compression



(a)

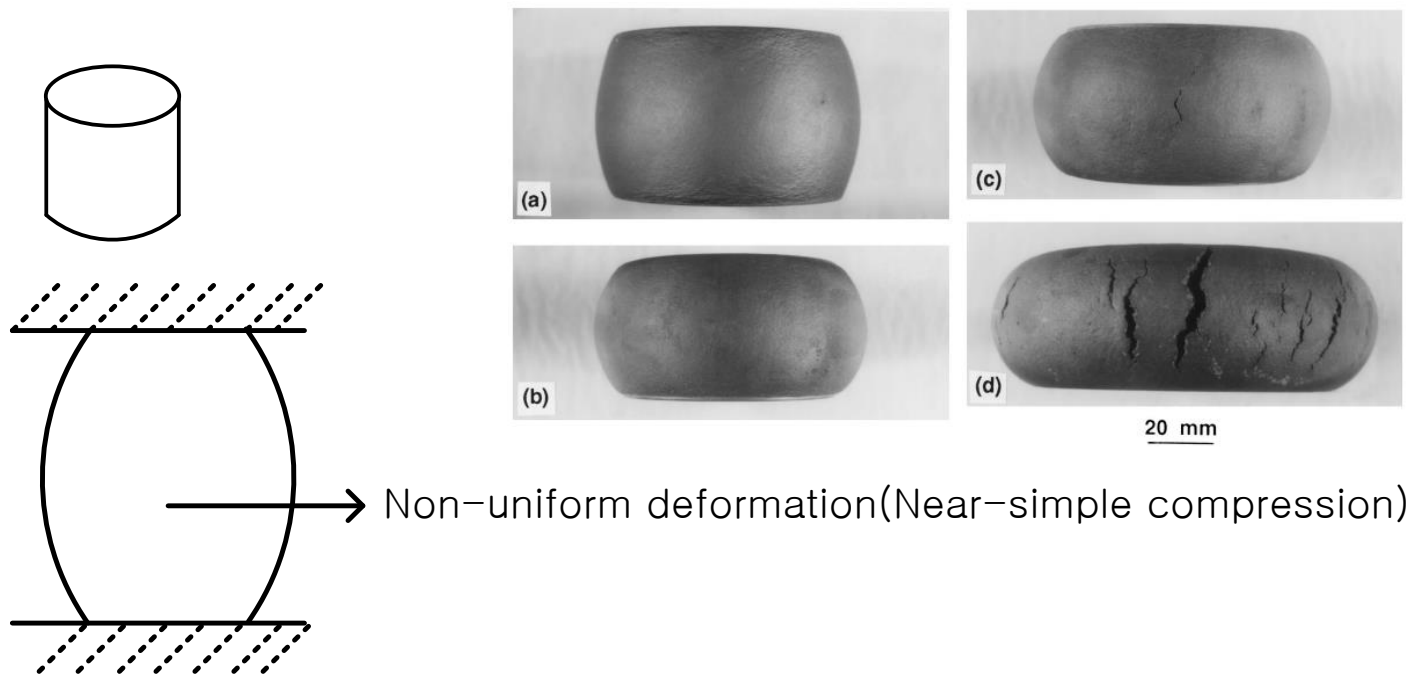


(b)



# Compression - barreling

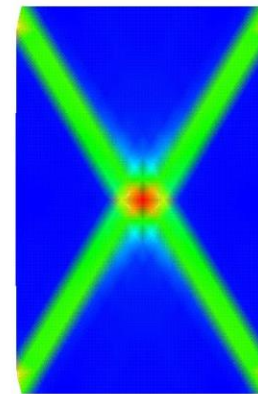
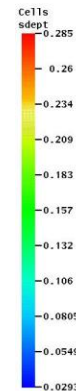
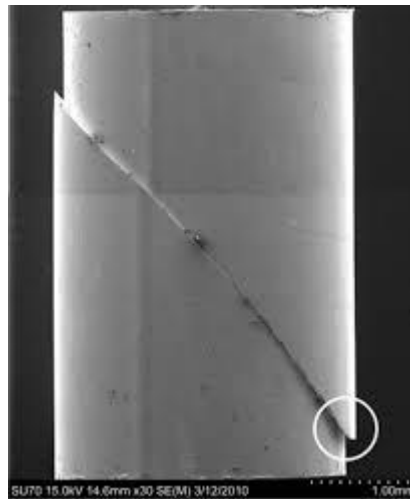
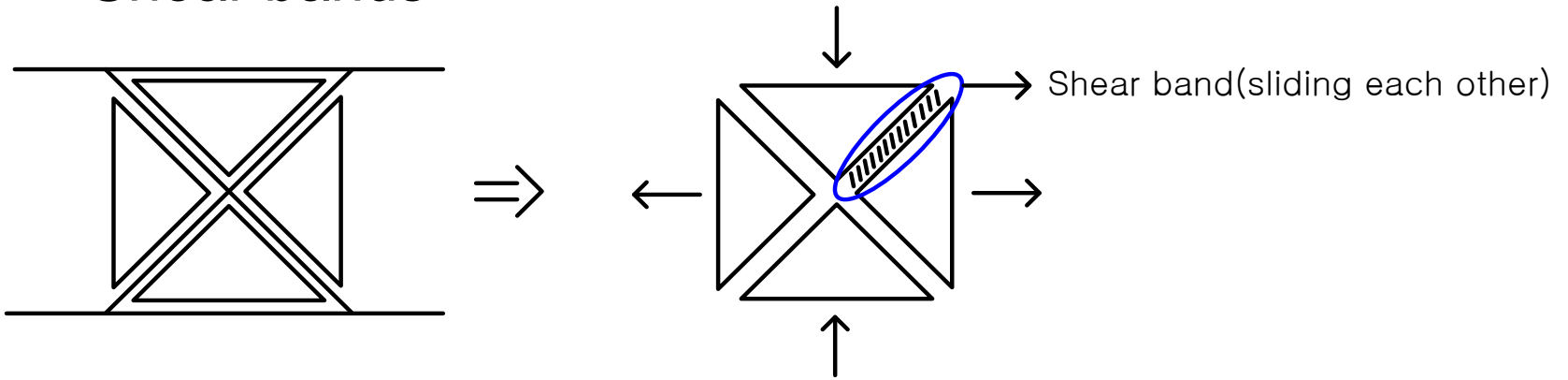
Typical specimen geometries in compressive tests



Needs good lubrication at the contact surfaces

# Compression – shear band

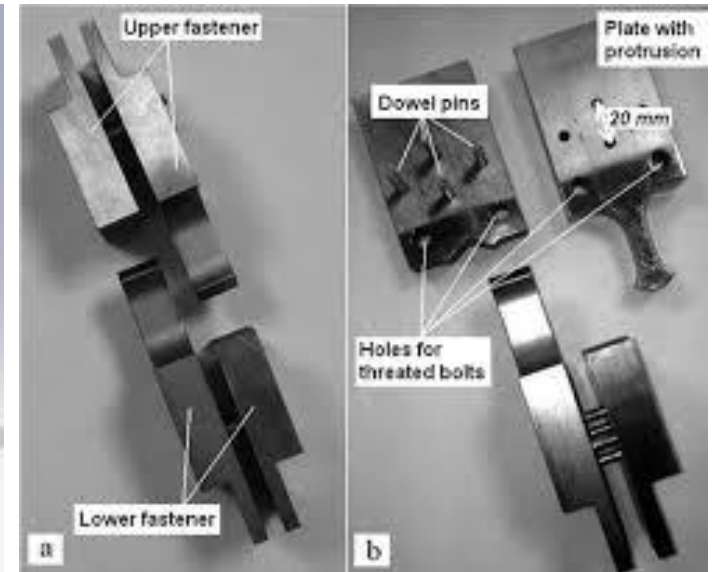
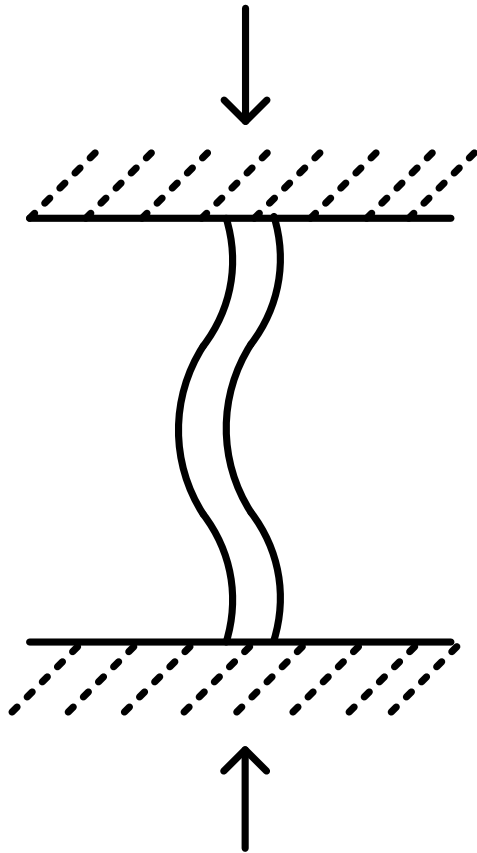
Shear bands



4.00000e-01

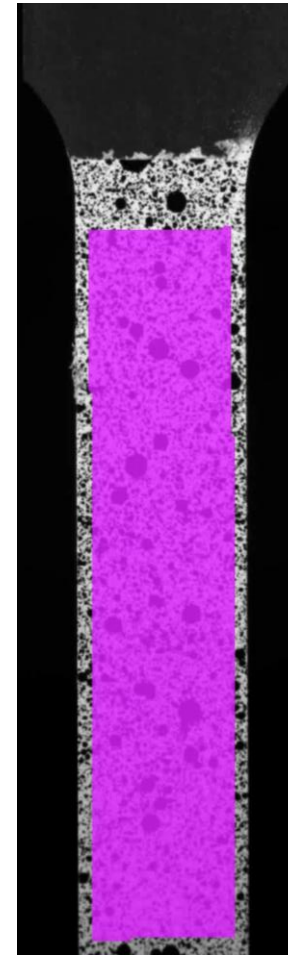
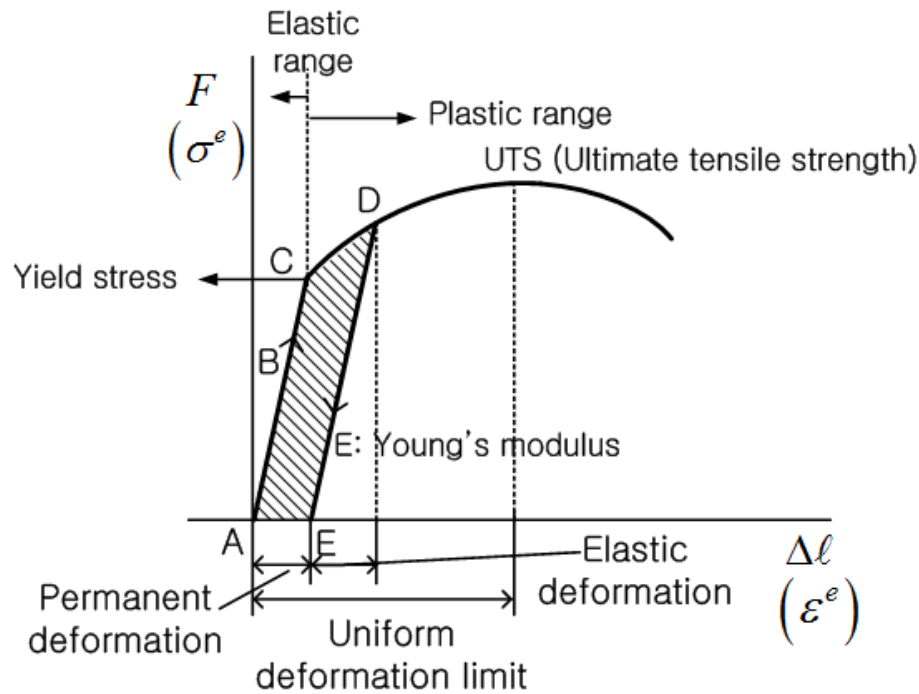
# Compression - buckling

Buckling for sheet and thin rod



Anti-buckling device

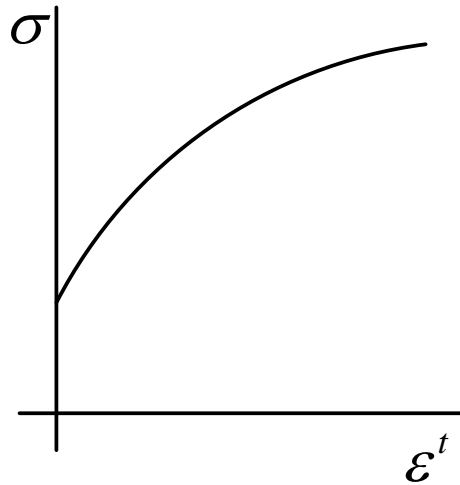
# Necking for metals



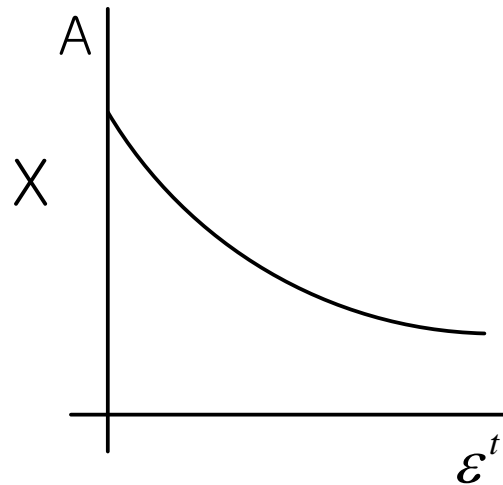
# Necking for metals

Uniform deformation limit

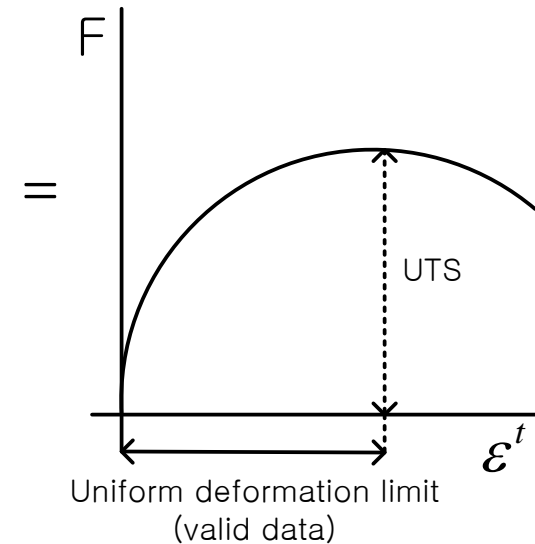
True stress



Area



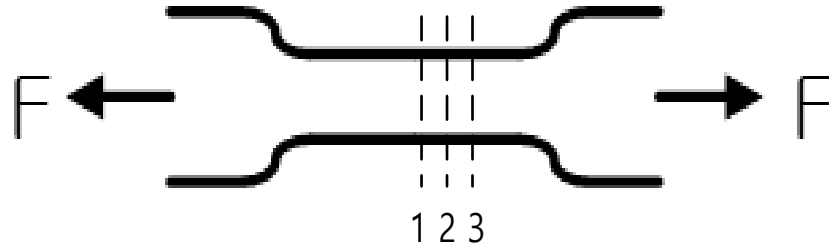
Force



$$F(\epsilon^t) = \sigma(\epsilon^t) \times A(\epsilon^t)$$

# Necking for metals

Uniform deformation limit



$A_o^1 < A_o^2 < A_o^3$  (either by real area difference or boundary constraint effect)

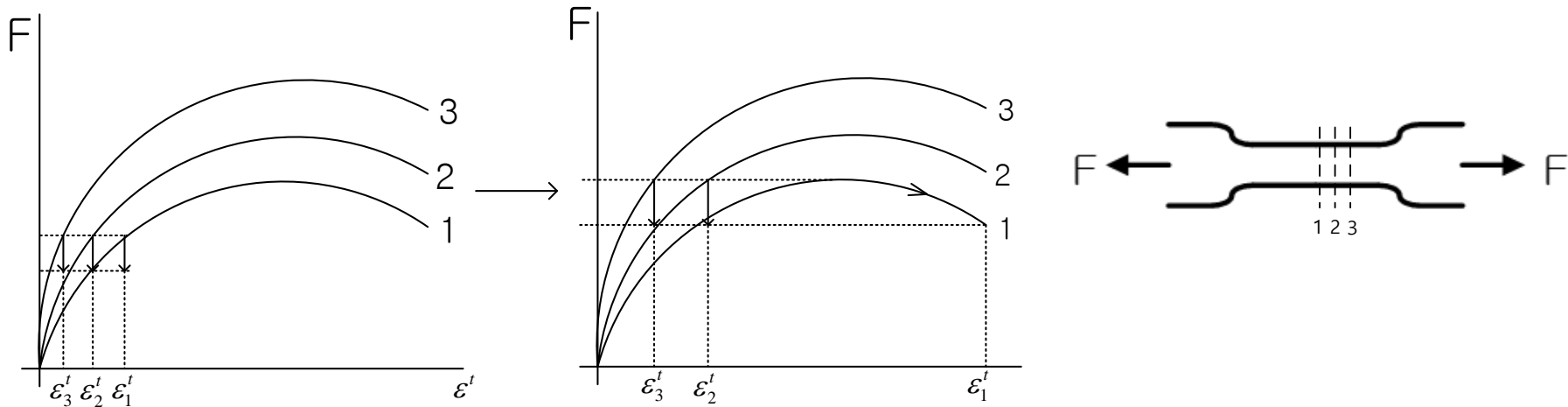
$$F = F^1 = F^2 = F^3$$

If Incompressible rigid-plasticity

$$F = \sigma A = \sigma A_o \frac{l_o}{l} = \sigma A_o e^{-\epsilon^t}$$



# Diffuse necking condition for metals



Considère criterion (or limit of uniform deformation)

$$dF = 0$$

$$F = \sigma A$$

$$dF = d\sigma A + \sigma dA = 0$$

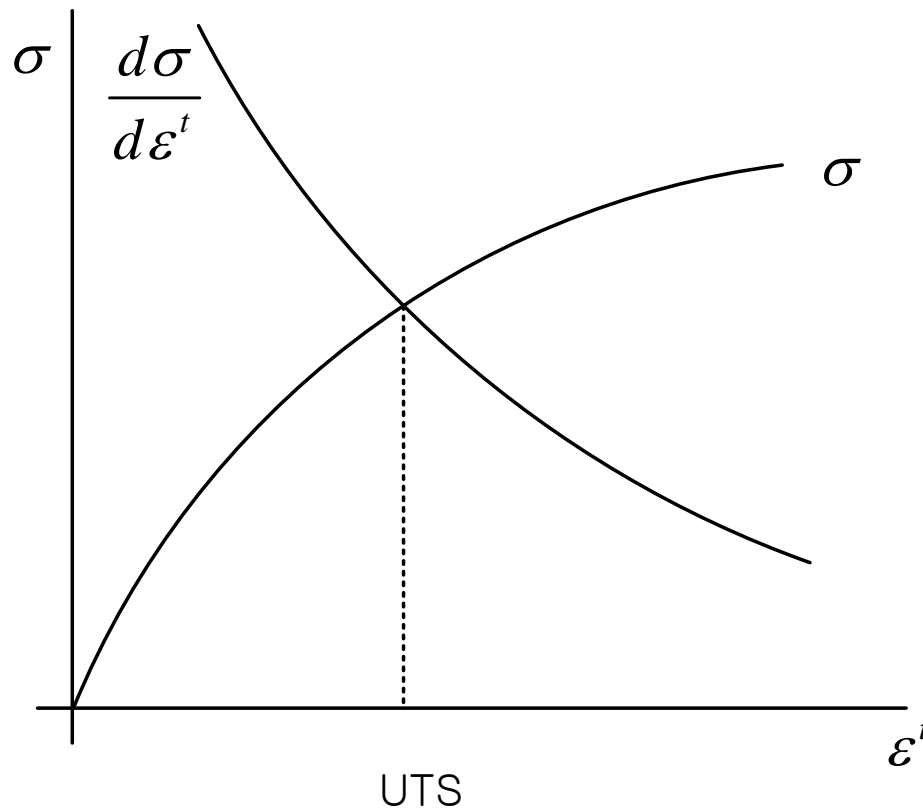
$$\frac{d\sigma}{\sigma} = -\frac{dA}{A} = \frac{dl}{l} = d\varepsilon^t$$

(volume constant  $\therefore Al = \text{Constant} \rightarrow dAl + Adl = 0$ )

$$\therefore \frac{d\sigma}{d\varepsilon^t} = \sigma \text{ (Considère criterion)}$$

# Considère condition

$$\frac{d\sigma}{d\varepsilon^t} = \sigma \quad (\text{Considère criterion})$$



# Considère condition

Hardening laws

$$\bar{\sigma} = K \bar{\varepsilon}^n \quad \text{Hollomon}$$

$$\bar{\sigma} = \bar{\sigma}_y + K \bar{\varepsilon}^n \quad \text{Ludwick}$$

$$\bar{\sigma} = K (\varepsilon_o + \bar{\varepsilon})^n \quad \text{Swift}$$

$$\bar{\sigma} = \bar{\sigma}_o - e^{-n(\bar{\varepsilon} - \varepsilon_o)} \quad \text{or} \quad \bar{\sigma} = A - B e^{-c\bar{\varepsilon}} \quad (B = e^{n\varepsilon_o}) \quad \text{Voce}$$

# Considère condition

Hollomon hardening law  $\bar{\sigma} = K\bar{\varepsilon}^n$

$$\frac{d\sigma}{d\varepsilon} = \sigma \Rightarrow k \cdot n \cdot \varepsilon^{n-1} = k \cdot \varepsilon^n$$

$$\therefore \varepsilon = n$$

Swift hardening law  $\bar{\sigma} = K(\varepsilon_o + \bar{\varepsilon})^n$

$$\frac{d\sigma}{d\varepsilon} = \sigma \Rightarrow k \cdot n \cdot (\varepsilon_o + \varepsilon)^{n-1} = k \cdot (\varepsilon_o + \varepsilon)^n$$

$$\therefore \varepsilon_o + \varepsilon = n$$

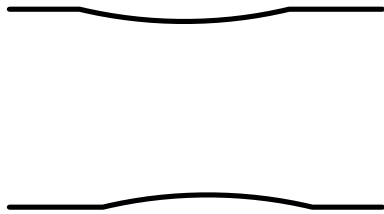
# Ductility measurement & necking

- Elongation: elongation is influenced by uniform deformation, strain hardening capacity
- Reduction of area
  - measure of deformation to produce failure and contribution from necking (or localization)
  - Due to the complicated stress state around necked region the value is dependent on the specimen geometry: not true material properties
  - RA is a structure-sensitive ductility parameter

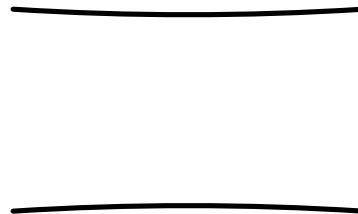
# Necking

: effect of strain rate sensitivity

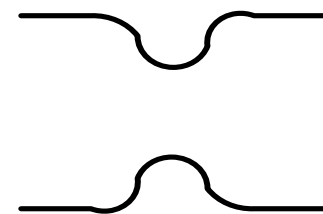
$$\bar{\sigma} = f(\bar{\epsilon}) \cdot \left( \frac{|\dot{\epsilon}|}{\dot{\epsilon}_0} \right)^m$$



$m=0$



$m>0$

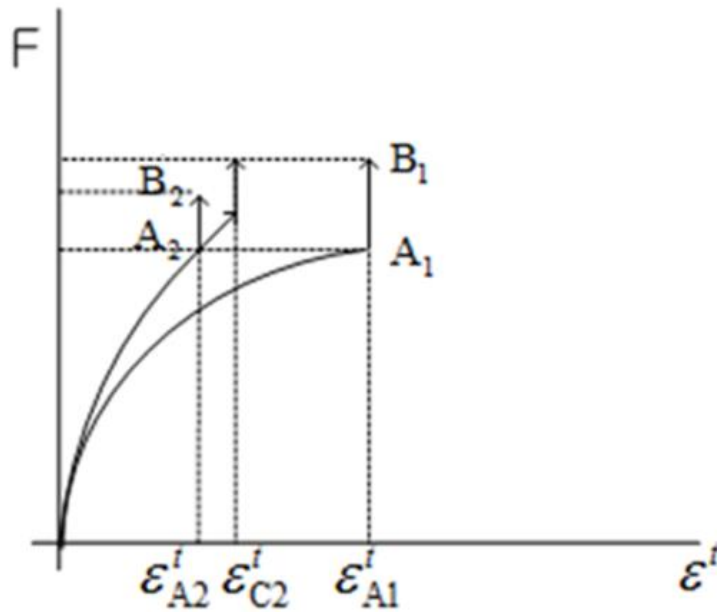


$m<0$

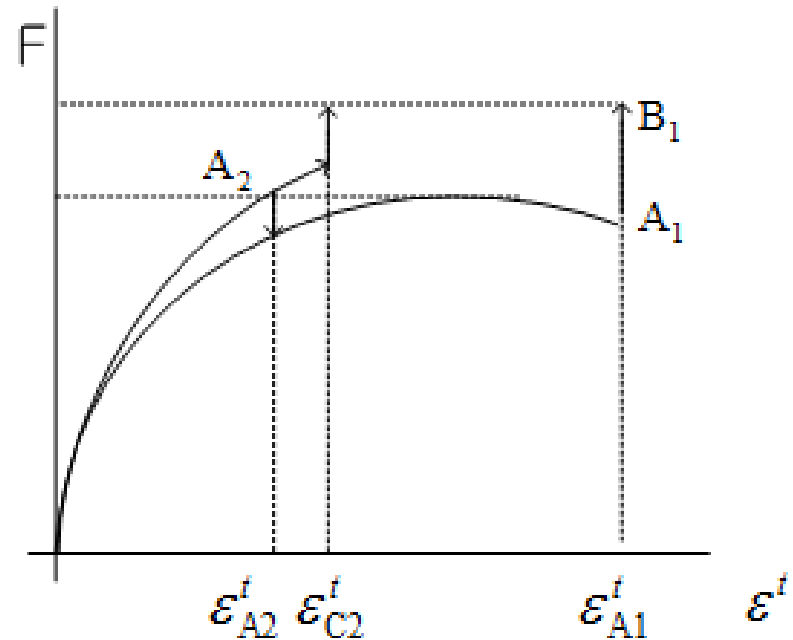
# Necking : effect of strain rate sensitivity

Positive strain rate sensitivity

→ Formation of diffuse necking is delayed

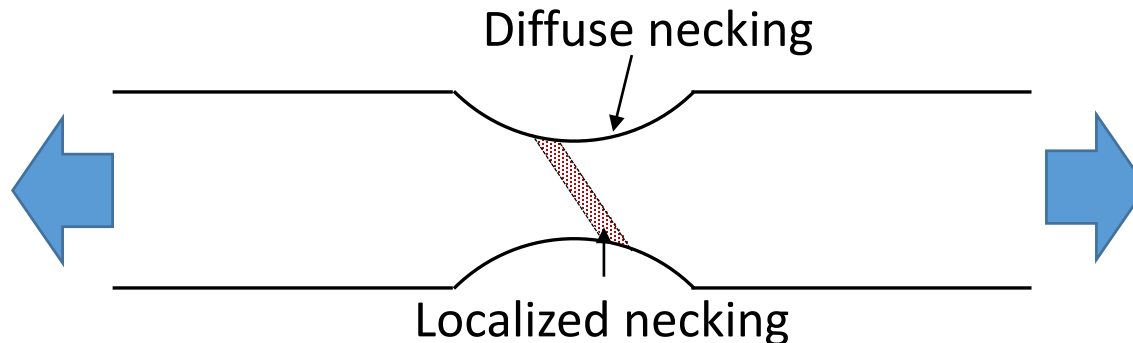


Before UTS



After UTS

# Diffuse vs localized necking



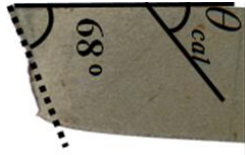





- **Diffuse necking**
  - Provide a large extent of necking on the tensile specimen similar to necking from a cylindrical specimen
  - Diffuse necking might terminate in fracture but normally followed by localized necking
- **Localized necking**
  - Localized necking is a narrow band with its size ~ specimen thickness, and a certain inclined angle ~55 degree
  - Give no change in width through the localized necking : plane strain deformation



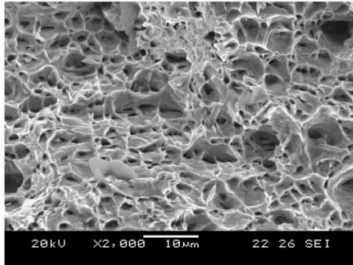
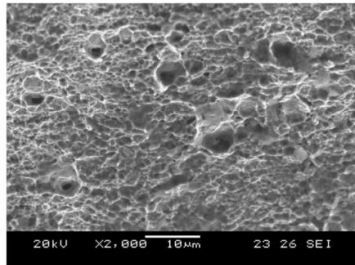
# Necking & failure

n- value and failure

Specimen shape after fracture

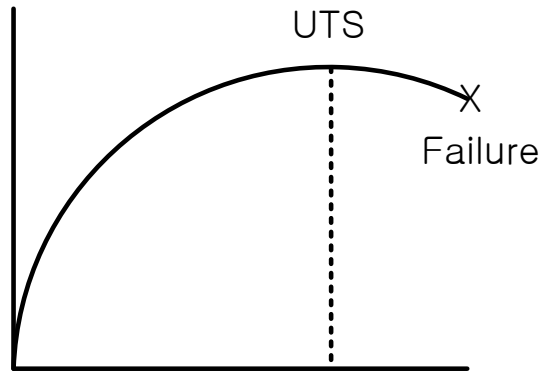
Material	340R*	DP980	TWIP940*
Fracture	Fracture with strain localization	Fracture with strain localization	Fracture without strain localization
Top view			
Side view			

Magnified fracture surface

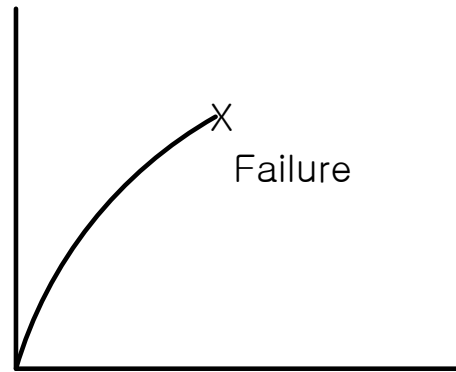
Material	340R*	TWIP940*
Fractured surfaces		

# Necking & failure

n- value and failure



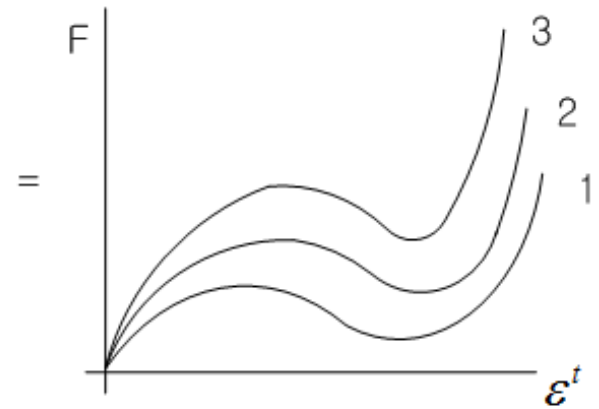
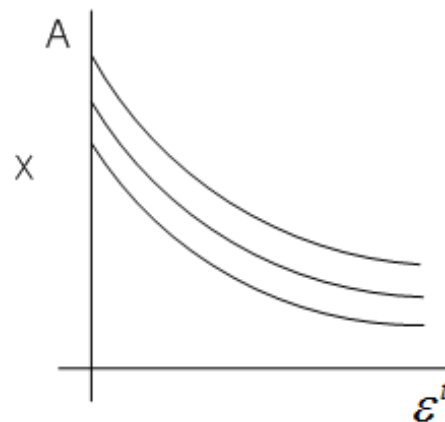
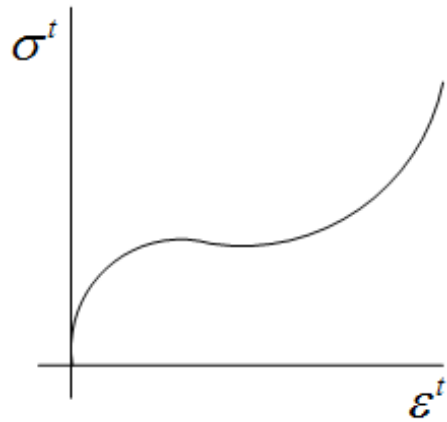
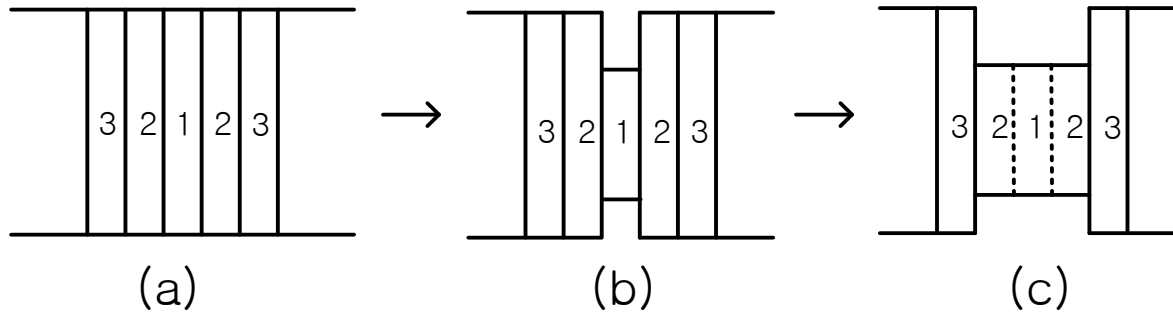
Failure after necking



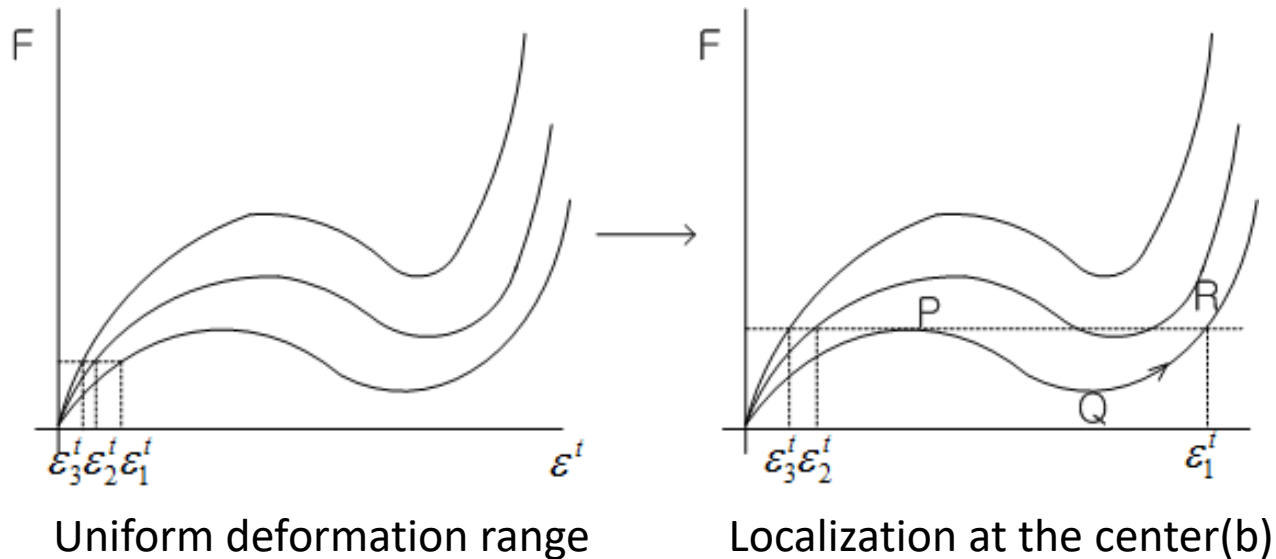
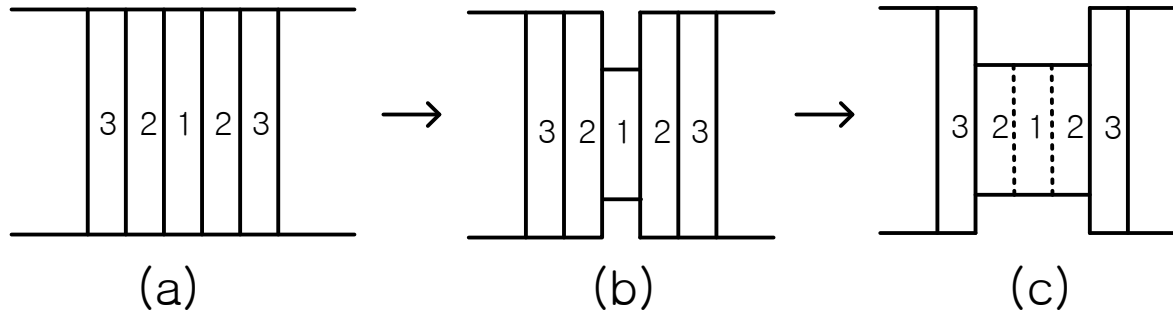
Failure before necking

- Failure after necking: the UTS point is the uniform deformation limit, after which all deformations are frozen (elastic unloading) except at the middle, leading to strain localization, diffused necking and micro-void growth till failure.
- Failure before necking: Failure does not accompany strain localization.

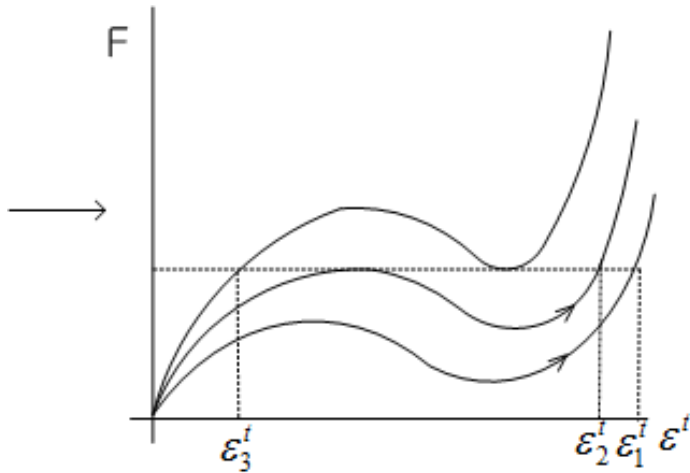
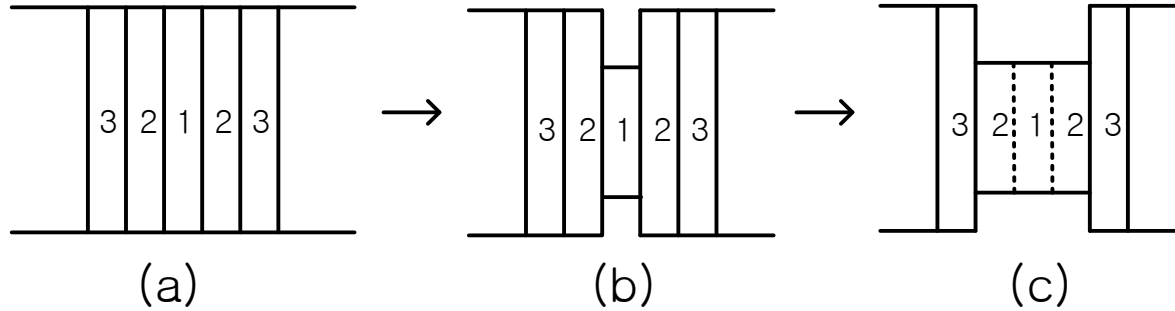
# Necking of semi-crystalline polymers



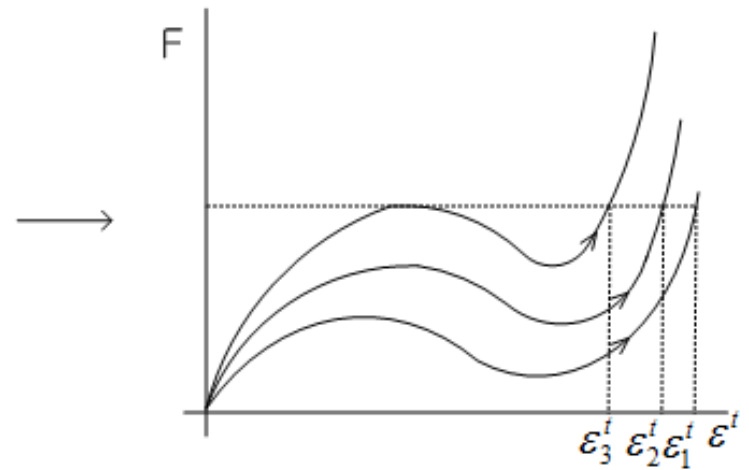
# Necking of semi-crystalline polymers



# Necking of semi-crystalline polymers



Further localization  
from element 1 to 2(c)



Extension of localization  
From element 2 to 3 (after c)