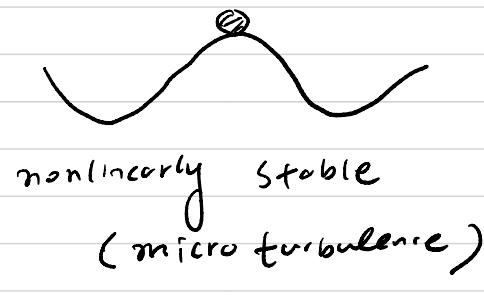
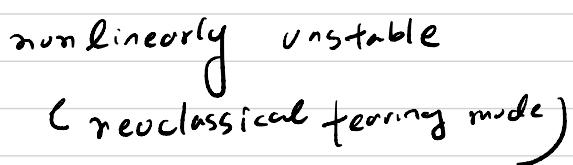
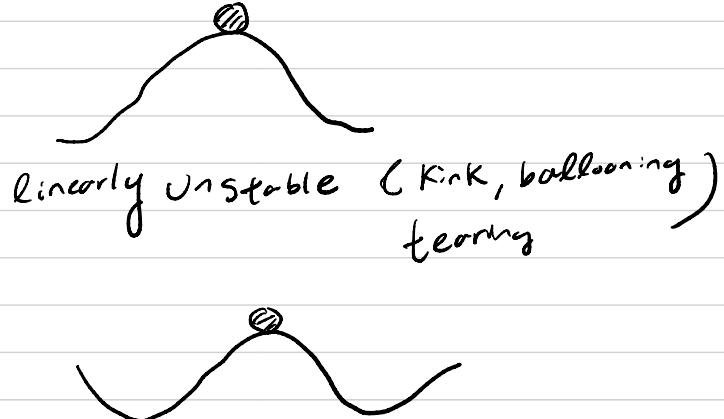
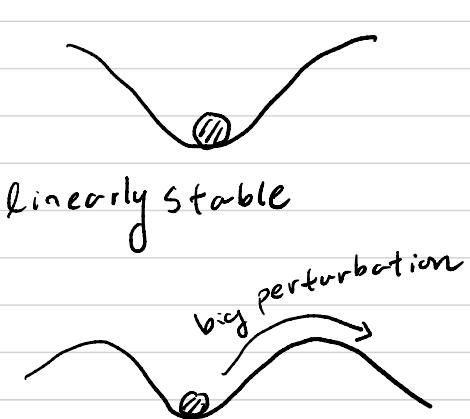


5/10 Stability assessment / Ideal MHD formulation

$$\text{equilibrium } \vec{j} \times \vec{B} = \vec{\nabla}p + (\rho \vec{v} \cdot \vec{\nabla} \vec{v} + \dots)$$

don't know yet if it's stable or not



* Formulation of linear stability

- Adds a small perturbation and see what happens

$$\vec{A}(\vec{x}, t) = \vec{A}_0(\vec{x}, 0) + \vec{A}_1(\vec{x}, t) \quad A_0 \gg A_1$$

- Assume exponential growth or damping

$$\vec{A}_1(\vec{x}, t) = A_1(\vec{x}) e^{-i\omega t}$$

- $\text{Im}(\omega) > 0$
 - Instability (Inhomogeneous media)
 - Waves (Homogeneous media)

* Ideal MHD waves

$$\frac{\partial \rho}{\partial t} + \vec{u} \cdot \vec{\nabla} \rho + \rho (\vec{\nabla} \cdot \vec{u}) = 0$$

$$\frac{\partial P}{\partial t} + \vec{u} \cdot \vec{\nabla} P + \gamma P (\vec{\nabla} \cdot \vec{u}) = 0$$

$$\frac{\partial \vec{B}}{\partial t} = -\vec{\nabla} \times \vec{E} = \vec{\nabla} \times (\vec{u} \times \vec{B})$$

$$\mu_0 \vec{j} = \vec{\nabla} \times \vec{B}$$

$$\rho \left(\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} \right) = \vec{j} \times \vec{B} - \vec{\nabla} P$$

differential eq \longrightarrow Algebraic eq.

Assume homogeneous media, $\vec{B}_0 = B_0 \hat{z}$

$$\vec{d}_0 = 0, \vec{u}_0 = 0, \vec{\nabla} P_0 = 0, \vec{\nabla} P_0 = 0$$

$$\text{Let } A_1(\vec{x}, t) = A_1 e^{i(\vec{k} \cdot \vec{x} - \omega t)}$$

Note, $\frac{d}{dt} \rightarrow -i\omega$ $\vec{\nabla} \rightarrow i\vec{k}$ for perturbed quantities.

also note, $\vec{u} \cdot \vec{\nabla} \vec{A} = \vec{u}_0 \cdot \cancel{\vec{\nabla} A_1} + \vec{u}_1 \cdot \cancel{\vec{\nabla} A_0} = 0$
 $\vec{u}_0 = 0$ homogeneity

Then combine (1)~(3) into (4)

$$\omega \vec{B}_1 = -\vec{u}_1 (\vec{k} \cdot \vec{B}_0) + \vec{B}_0 (\vec{k} \cdot \vec{u}_1)$$

$$\omega \mu_0 \vec{j}_1 = -i(\vec{k} \times \vec{u}_1) (\vec{k} \cdot \vec{B}_0) + i(\vec{k} \times \vec{B}_0) (\vec{k} \cdot \vec{u}_1)$$

$$\begin{aligned} \omega \mu_0 \vec{j}_1 \times \vec{B}_0 &= -i \left[\vec{u}_1 (\vec{k} \cdot \vec{B}_0) - \vec{k} (\vec{u}_1 \cdot \vec{B}_0) \right] (\vec{k} \cdot \vec{B}_0) \\ &\quad + i \left[\vec{B}_0 (\vec{k} \cdot \vec{B}_0) - \vec{k}^2 B_0^2 \right] (\vec{k} \cdot \vec{u}_1) \end{aligned}$$

$$\begin{aligned} (4) \quad \omega \rho_0 \mu_0 \vec{u}_1 &= \left[\vec{u}_1 (\vec{k} \cdot \vec{B}_0) - \vec{k} (\vec{u}_1 \cdot \vec{B}_0) \right] (\vec{k} \cdot \vec{B}_0) \\ &\quad - \left[\vec{B}_0 (\vec{k} \cdot \vec{B}_0) - \vec{k}^2 B_0^2 \right] (\vec{k} \cdot \vec{u}_1) + \mu_0 \gamma P_0 \vec{k} (\vec{k} \cdot \vec{u}_1) \end{aligned}$$

$$\omega \rho_1 = \rho_0 (\vec{k} \cdot \vec{u}_1) \quad (\text{not used})$$

$$\omega P_1 = \gamma P_0 (\vec{k} \cdot \vec{u}_1) \quad (1)$$

$$\omega \vec{B}_1 = -\vec{k} \times (\vec{u}_1 \times \vec{B}_0) \quad (2)$$

$$\omega \mu_0 \vec{j}_1 = -i \vec{k} \times (\vec{k} \times (\vec{u}_1 \times \vec{B}_0)) \quad (3)$$

$$\omega \rho_0 \vec{u}_1 = i(\vec{k} \times \vec{B}_0) + \vec{k} P_1 \quad (4)$$

$$\text{Let } V_A^2 = \frac{B_0^2}{\mu_0 P_0} \quad C_s^2 = \frac{\gamma P_0}{\rho_0}$$

A / fuer *Sound*

$$(4) \left| B_0^2 \right. \rightarrow (\omega^2 - k_{\parallel}^2 V_A^2) \vec{u}_i \\ = \vec{k}_{\perp} (\vec{k} \cdot \vec{u}_i) V_A^2 - \vec{k} (k_{\parallel} u_{\parallel i}) V_A^2 + \vec{k} (\vec{k} \cdot \vec{u}_i) c_s^2$$

$$\text{Let } \vec{k} = k_{\perp} \hat{y} + k_{\parallel} \hat{z} \text{ w/o loss of generality}$$

$$\vec{u}_1 = u_{1x} \hat{x} + u_{1y} \hat{y} + u_{1z} \hat{z}$$

$$(\omega^2 - k_{rr}^2 V_A^2) u_{rr} = 0$$

$$(\omega^2 - k_x^2 c_s^2 - k^2 V_A^2) u_{xy} - (k_x k_y c_s^2) u_{xz} = 0$$

$$- (k_x k_y c_s^2) u_{xy} + (\omega^2 - k_x^2 c_s^2) u_{xz} = 0$$

$$\omega^2 = k_r^2 \sqrt{A}^2$$

shear Alfvén

$$\omega^2 = \frac{1}{2} k^2 (V_A^2 + C_S^2) (1 \pm \sqrt{1 - \alpha^2})^{\frac{1}{2}} \quad \text{magnetosonic: C}$$

$$\text{where, } \alpha^2 = 4 \frac{k_r^2}{k^2} \cdot \frac{c_s^2 V_A^2}{(c_s^2 + V_A^2)^2}$$

$$-\quad 0 < \hat{\omega}^2 < 1 \quad \rightarrow \quad \omega^2 > 0$$

$\rightarrow \text{Im}(\omega) = 0 \rightarrow \text{no instability}$
 growth or damping

→ expected since no free energy source

* magnetosonic wave for low β

$$\beta \sim \frac{c_s^2}{v_A^2} \ll 1$$

$$\omega^2 \approx (k_\perp^2 + k_{\parallel}^2) v_A^2 \quad \text{fast. compressional Alfvén}$$

$$\omega^2 \approx k_{\parallel}^2 c_s^2 \quad \text{slow. sound}$$

(I) Shear Alfvén wave

$$\omega^2 = k_{\parallel}^2 v_A^2 \quad \text{Independent of } k_{\perp}$$

even if $k_{\perp} \gg k_{\parallel}$

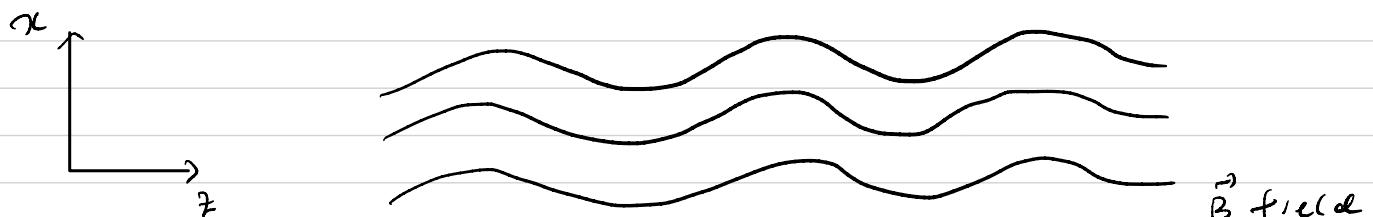
$$u_{1x} \neq 0, \quad u_{1y} = u_{1z} = 0 \quad \vec{\partial} \cdot \vec{u}_1 = 0 \quad \vec{k} \cdot \vec{u}_1 = 0$$

$$\rho_1 = p_1 = 0$$

note $\omega \vec{B}_1 = -\vec{u}_1 (\vec{k} \cdot \vec{B}_0) \times \vec{B}_1 \quad (\vec{k} \cdot \vec{u}_1)$

$$B_{1x} \propto u_1, \quad B_{1y} = B_{1z} = 0$$

$\vec{u}_1, \vec{B}_1 \perp \vec{k}$ transverse wave



- perpendicular kinetic energy

\leftrightarrow magnetic bending energy

- most dangerous

$$\vec{B}^2 = (B_0 + B_1)^2 = B_0^2 + 2\vec{B}_0 \cdot \vec{B}_1 + \vec{B}_1^2$$

\rightarrow easy to excite

$$|\vec{u}_1| \sim \frac{|\vec{B}_1|}{|\vec{k} \cdot \vec{B}_0|} \quad \vec{k} \cdot \vec{B}_0 \rightarrow 0$$

$$|\vec{B}_1| \rightarrow \vec{u}_1 \uparrow \infty$$

(II) compressional Alfvén wave

$$\omega^2 \approx (k_x^2 + k_y^2) V_A^2 \text{ for } \beta \ll 1$$

$u_{1x} \approx 0$, but $u_{1y} \neq 0$ $u_{1z} \neq 0$

$B_{1x} = 0$ $P_1 \neq 0$, $P_z \neq 0$

- but $\mu_0 P_1 / B_0 B_{1z} \ll 1$

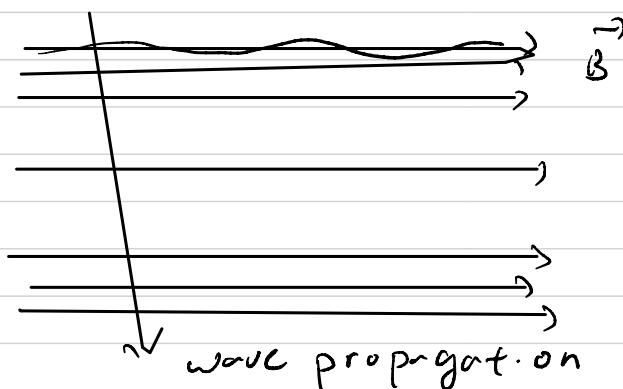
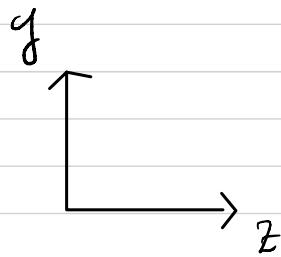
mostly due to compression of magnetic field, not plasma

- note typically $k_L \gg k_\parallel$ ($\because 2\pi R_0 \gg 2a$)

\uparrow
major radius \downarrow
minor radius

- $u_{1y} \gg u_{1z}$

nearly transverse wave

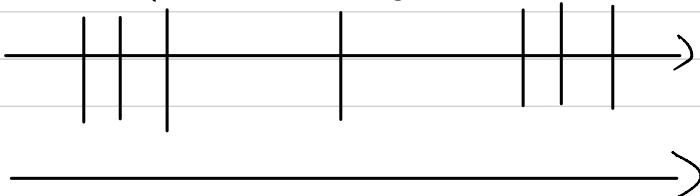
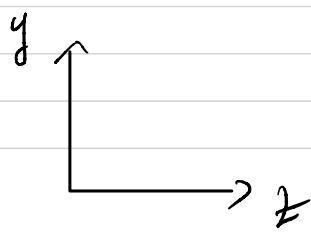


(III) Sound wave

$$\omega^2 \approx k_\parallel c_s^2, \quad u_{1x} \approx 0, \quad u_{1y} \approx 0, \quad \vec{B}_1 \approx 0$$

longitudinal wave

pressure contour



*

$$K_{\perp}^2 V_A^2 \gg K_{\parallel}^2 V_A^2 \gg K_{\parallel}^2 C_S^2$$

compressional
Alfven

shear
Alfven

sound

Ideal MHD equilibrium / stability
is as fast as at least sound wave
mostly Alfvén time scale

5/12 Ideal MHD Stability / energy principle

1. For general geometry, Ideal MHD with $\vec{u}_0 = 0$

If we express $\vec{u}_1 = \frac{\partial \vec{\xi}}{\partial t}$, where $\vec{\xi}(x, t)$ plasma displacement

$$\frac{\partial P_1}{\partial x} + \vec{u}_1 \cdot \vec{\nabla} P_0 + P_0 (\vec{\nabla} \cdot \vec{u}_1) = 0$$

$$\frac{\partial P_1}{\partial t} + \vec{u}_1 \cdot \vec{\nabla} P_0 + \gamma P_0 (\vec{\nabla} \cdot \vec{u}_1) = 0$$

$$\frac{\partial \vec{B}_1}{\partial x} = \vec{\nabla} \times (\vec{u}_1 \times \vec{B}_0)$$

$$\mu_0 \frac{\partial \vec{B}_1}{\partial t} = \vec{\nabla} \times \vec{B}_1$$

$$\rho_0 \frac{\partial \vec{u}_1}{\partial x} = \vec{j}_1 \times \vec{B}_0 + \vec{j}_0 \times \vec{B}_1 - \vec{\nabla} P_1 \quad (4)$$

$$P_1 = -\vec{\xi} \cdot \vec{\nabla} P_0 - P_0 (\vec{\nabla} \cdot \vec{\xi}) \quad (\text{not used})$$

$$P_1 = -\vec{\xi} \cdot \vec{\nabla} P_0 - \gamma P_0 (\vec{\nabla} \cdot \vec{\xi}) \quad (1)$$

$$\vec{B}_1 = \vec{\nabla} \times (\vec{\xi} + \vec{B}_0) \quad (2)$$

$$\mu_0 \frac{\partial \vec{B}_1}{\partial t} = \vec{\nabla} \times \vec{\nabla} \times (\vec{\xi} \times \vec{B}_0) \quad (3)$$

(1)~(3) into (4)

$$\rho_0 \frac{\partial^2 \vec{\xi}}{\partial t^2} = \frac{1}{\mu_0} \left[\vec{\nabla} \times \vec{\nabla} \times (\vec{\xi} \times \vec{B}_0) \right] \times \vec{B}_0 + \frac{1}{\mu_0} \left[(\vec{\nabla} \times \vec{B}_0) \times \vec{\nabla} \times (\vec{\xi} \times \vec{B}_0) \right] + \vec{\nabla} \left(\vec{\xi} \cdot \vec{\nabla} P_0 + \gamma P_0 (\vec{\nabla} \cdot \vec{\xi}) \right)$$

$\equiv \vec{F}(\vec{\xi})$: ideal MHD force operator

note one can no longer $\vec{\xi} \propto e^{i(\vec{k} \cdot \vec{x} - \omega t)}$ (x)
but still can assume $\vec{\xi} = \vec{\xi}(\vec{x}) e^{-i\omega t}$

$\omega^2 \vec{\xi} = -\vec{F}(\vec{\xi})$: normal mode equation

\rightarrow numerically more amenable than I.V.P

\rightarrow still too much information

\rightarrow works only for the system unstable

\rightarrow typically, we just want know
if the equilibrium is stable or not.

2. Energy principle

(1) note $\vec{F}(\vec{\xi})$ is self-adjoint. meaning

$$\int \vec{\eta} \cdot \vec{F}(\vec{\xi}) d\vec{x} = \int \vec{\xi} \cdot \vec{F}(\vec{\eta}) d\vec{x}$$

arbitrary trial fns.

- expected for conserved system
- can be directly proved w/ $\vec{F}'(\vec{\xi}')$

(2) self-adjointness means

(a) ω^2 is real, ω is purely $\begin{cases} \text{real} \\ \text{imaginary} \end{cases}$

$$\therefore \omega^2 \int \rho_0 |\vec{\xi}|^2 d\vec{x} = - \int \vec{\xi}^* \cdot \vec{F}(\vec{\xi}) d\vec{x}$$

$$(\omega^2)^* \int \rho_0 |\vec{\xi}|^2 d\vec{x} = - \int \vec{\xi} \cdot \vec{F}(\vec{\xi}^*) d\vec{x}$$

$$\rightarrow (\omega^2) = (\omega^2)^*$$

$\omega = 0$ at marginal point
 (not $\text{Re}(\omega) \neq 0$, $\text{Im}(\omega) = 0$)

(b) Discrete normal modes are orthogonal.

Let $\omega_m^2 \neq \omega_n^2$ (weight fcn. ρ_0)

$$\int \vec{\xi}_m \cdot (-\omega_m^2 \rho_0 \vec{\xi}_m = \vec{F}(\vec{\xi}_m)) d\vec{x}$$

$$\int \vec{\xi}_n \cdot (-\omega_n^2 \rho_0 \vec{\xi}_n = \vec{F}(\vec{\xi}_n)) d\vec{x}$$

$$(\omega_m^2 - \omega_n^2) \int \rho_0 \vec{\xi}_m \cdot \vec{\xi}_n d\vec{x} = 0$$

$$\rightarrow \int \rho_0 \vec{\xi}_m \cdot \vec{\xi}_n d\vec{x} = 0$$

(3) Variational formulation.

$$\text{note } \omega^2 = \frac{-\frac{1}{2} \int \vec{\xi}^* \cdot \vec{F}(\vec{\xi}) dx}{\frac{1}{2} \int \rho |\vec{\xi}|^2 dx} = \frac{\delta W(\vec{\xi}^*, \vec{\xi})}{K(\vec{\xi}^*, \vec{\xi})}$$

Then $\vec{\xi}(x)$ makes (maximum) ω^2 .
(minimum)

is an eigenfunction of normal mode problem

\therefore At extremum,

$$\vec{\xi} \rightarrow \vec{\xi} + \delta \vec{\xi} \text{ then } \omega^2 \rightarrow \omega^2 + \delta \omega^2$$

$$\omega^2 + \delta \omega^2 = \frac{\delta W(\vec{\xi}^*, \vec{\xi}) + \delta W(\delta \vec{\xi}^*, \vec{\xi}) + \delta W(\vec{\xi}^*, \delta \vec{\xi}) + O(\delta^2)}{K(\vec{\xi}^*, \vec{\xi}) + K(\delta \vec{\xi}^*, \vec{\xi}) + K(\vec{\xi}^*, \delta \vec{\xi}) + O(\delta^2)}$$

$$0 = \delta \omega^2 \sim \frac{\delta W(\delta \vec{\xi}^*, \vec{\xi}) + \delta W(\vec{\xi}^*, \delta \vec{\xi}) - \omega^2 (K(\delta \vec{\xi}^*, \vec{\xi}) + K(\vec{\xi}^*, \delta \vec{\xi}))}{K(\vec{\xi}^*, \vec{\xi})}$$

$$\int dx \left[\delta \vec{\xi}^* \left[\vec{F}(\vec{\xi}) + \omega^2 \rho \vec{\xi} \right] + \delta \vec{\xi} \left[\vec{F}(\vec{\xi}^*) + \omega^2 \rho \vec{\xi}^* \right] \right] = 0$$

hold if $\omega^2 \rho \vec{\xi} = -\vec{F}(\vec{\xi})$

Now, you can just minimize

$$\omega^2 = \frac{\delta W(\vec{\xi}^*, \vec{\xi})}{K(\vec{\xi}^*, \vec{\xi})}$$

to find the most unstable mode

(work when really unstable
not when stable due continuum mode
(Toed blood & Poedts (2004))

* since one can always K

without changing δW through $\vec{\xi}$,

(4) Energy principle (Bernstein '58)

Equilibrium is stable iff. $\delta W(\vec{\xi}^*, \vec{\xi}) > 0$
 for all allowable trial fns $\vec{\xi}$
 (even if $\vec{\xi}$ is not an eigenfn)

If $\vec{\xi}$ making $\delta W < 0$ exists, it's unstable

\therefore If the modes are discrete

$$\text{any } \vec{\xi} = \sum_n a_n \vec{\xi}_n$$

$$\delta W(\vec{\xi}, \vec{\xi}^*) = \frac{1}{2} \sum_n |a_n|^2 \omega_n^2$$

$\delta W < 0$ means at least one $\omega_n < 0$

\therefore Complete proof by Laval '65,
 (Freidberg Ch 8)

Now one can just minimize δW

3. Standard form of $\delta W(\vec{\xi}^*, \vec{\xi})$ $\vec{\eta} = \vec{\xi}^*$

$$\delta W = -\frac{1}{2} \int \vec{\eta} \cdot \left[\underbrace{\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}_i) \times \vec{B}_o}_{\textcircled{1}} + \underbrace{\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) \times \vec{B}_i}_{\textcircled{3}} + \underbrace{\vec{\nabla} (\vec{\xi} \cdot \vec{\nabla} P + \alpha \vec{\nabla} \cdot \vec{\xi})}_{\textcircled{2}} \right] d\vec{x}$$

$$\text{Let } \vec{\xi} = \vec{\xi}_\parallel \hat{b} + \vec{\xi}_\perp \quad \vec{B}_i = \vec{\nabla} \times (\vec{\xi}_\perp \times \vec{B})$$

$$\begin{aligned} \textcircled{1} \quad & \int \vec{\eta} \cdot (\vec{\nabla} \times \vec{B}_i) \times \vec{B}_o \\ &= \int (\vec{\nabla} \times \vec{B}_i) \cdot (\vec{B}_o \times \vec{\eta}_\perp) \\ &= \int \vec{\nabla} \cdot (\vec{B}_i \times (\vec{B} \times \vec{\eta}_\perp)) + \int \vec{B}_i \cdot \vec{\nabla} \times (\vec{B} \times \vec{\eta}_\perp) \\ &= \int (\vec{B}_i \times (\vec{B} \times \vec{\eta}_\perp)) \cdot d\vec{S} - \int \vec{B}_i \cdot (\vec{\xi}_\perp) \cdot \vec{B} \cdot (\vec{\eta}_\perp) \\ &= - \int \vec{\eta}_\perp \cdot d\vec{S} (\vec{B} \cdot \vec{B} \cdot (\vec{\xi}_\perp)) - \int \vec{B} \cdot (\vec{\xi}_\perp) \cdot \vec{B} \cdot (\vec{\eta}_\perp) \end{aligned}$$

$$\textcircled{2} \quad \int \vec{\eta}_\perp \cdot d\vec{s} \left(\gamma_P (\vec{\nabla} \cdot \vec{\xi}) \right) - \int \gamma_P (\vec{\nabla} \cdot \vec{\xi}) (\vec{\nabla} \cdot \vec{\eta})$$

$$\textcircled{3} \quad \vec{B} \cdot \left[\vec{\xi}_\perp \times \vec{B}_\parallel + \vec{\partial} (\vec{\xi}_\parallel \cdot \vec{\partial} P) \right] = 0 \quad \checkmark$$

$$\textcircled{1} + \textcircled{2} + \textcircled{3} \quad \text{leads to}, \quad \vec{\eta}_\perp = \vec{\xi}_\perp^*$$

$$\delta W = \delta W_F + \delta W_S$$

$$\delta W_F = \frac{1}{2} \int \frac{1}{\mu_0} |B_\parallel|^2 + \gamma_P |\vec{\nabla} \cdot \vec{\xi}|^2 - \vec{\xi}_\perp^* \cdot \vec{\partial} \times \vec{B}_\parallel + (\vec{\nabla} \cdot \vec{\xi}_\perp^*) (\vec{\xi}_\perp \cdot \vec{\nabla} P) d\vec{x}$$

$$\delta W_S = \frac{1}{2} \int \vec{\xi}_\perp^* \cdot d\vec{s} \left[\frac{1}{\mu_0} \vec{B} \cdot \vec{B}_\parallel - \gamma_P \vec{\nabla} \cdot \vec{\xi}_\parallel - \vec{\xi}_\perp \cdot \vec{\partial} P \right] dS$$

4. Intuitive form. Let $\vec{Q} \equiv \vec{B}_\parallel$

$$\vec{Q} = \vec{Q}_\perp + Q_{\parallel \perp} \hat{b}, \quad \vec{j} = \vec{j}_\perp + j_{\parallel \perp} \hat{b}$$

$$\delta W_F = \frac{1}{2\mu_0} \int \underbrace{|(\vec{Q}_\perp)|^2}_{\textcircled{1}} + \underbrace{\vec{B} \left| \vec{\nabla} \cdot \vec{\xi}_\perp + 2\vec{\xi}_\perp \cdot \vec{k} \right|^2}_{\textcircled{2}} + \underbrace{\mu_0 \gamma_P |\vec{\nabla} \cdot \vec{\xi}|^2}_{\textcircled{3}} \\ - \underbrace{2\mu_0 (\vec{\xi}_\perp \cdot \vec{\nabla} P) (\vec{\xi}_\perp^* \cdot \vec{k})}_{\textcircled{4}} - \underbrace{\mu_0 j_{\parallel \perp} (\vec{\xi}_\perp^* \times \hat{b}) \cdot \vec{Q}_\perp}_{\textcircled{5}} d\vec{x}$$

- $\textcircled{1}$: shear Alfvén
 - $\textcircled{2}$: compressional Alfvén
 - $\textcircled{3}$: sound wave
 - $\textcircled{4}$: pressure-driven instability
 - $\textcircled{5}$: current-driven instability
- 

* minimization of $\delta W \rightarrow (\vec{\nabla} \cdot \vec{\xi}) = 0$
by choosing $\vec{\xi}_\parallel$

5. Self-adjoint form

read Friedberg ch. 8