2017 Fall

"Phase Transformation in Materials"

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Contents in Phase Transformation

Background to understand phase transformation

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(Ch1) Thermodynamics and Phase Diagrams
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(Ch2) Diffusion: Kinetics

(Ch3) Crystal Interface and Microstructure

Representative Phase transformation

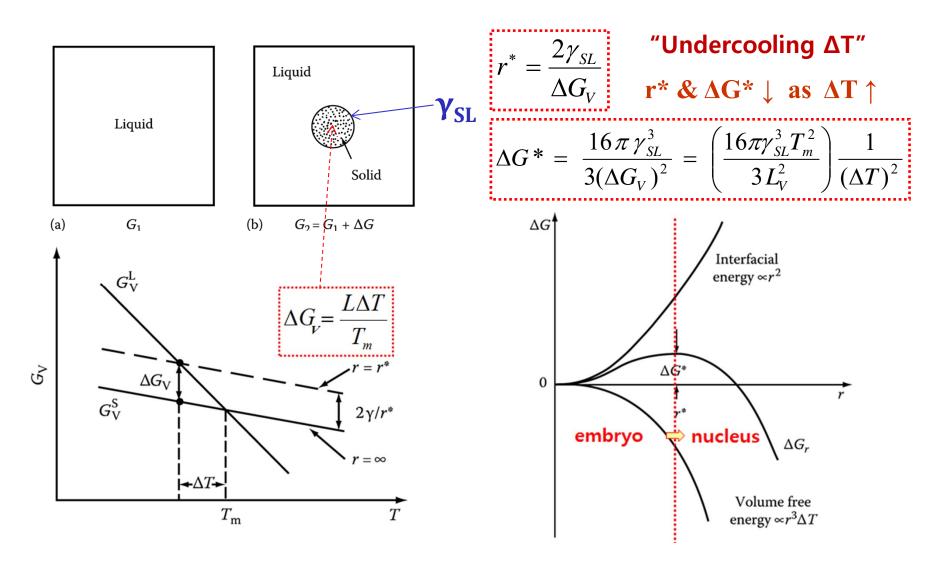
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(Ch4) Solidification: Liquid \rightarrow Solid
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(Ch5) Diffusional Transformations in Solid: Solid → Solid

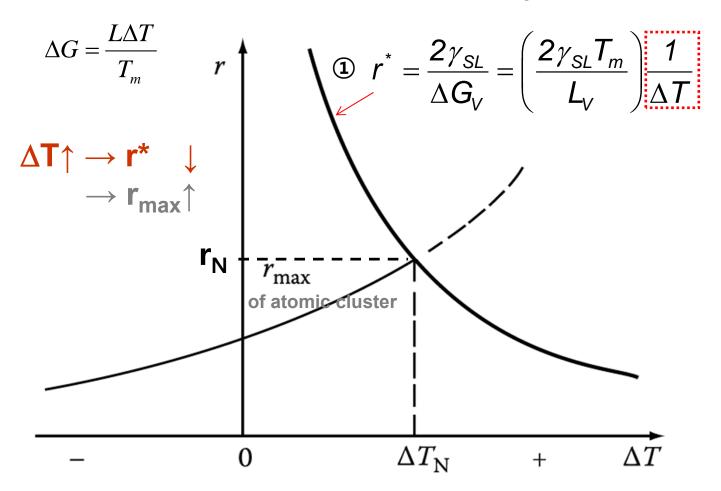
(Ch6) Diffusionless Transformations: Solid → Solid

Contents for previous class

- Nucleation in Pure Metals
- Homogeneous Nucleation



The creation of a critical nucleus ~ thermally activated process



 ΔT_N is the critical undercooling for homogeneous nucleation.

Fig. 4.5 The variation of r* and r_{max} with undercooling ΔT

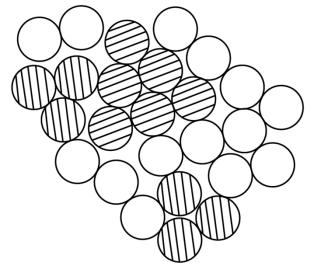
 \rightarrow Condition for nucleation: The number of clusters with r* at T < ΔT_N is negligible.

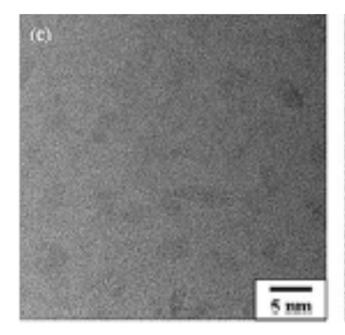
② Formation of Atomic Cluster

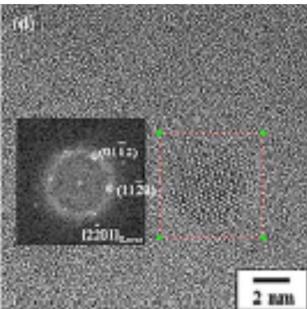
At the $T_{\rm m}$, the liquid phase has <u>a volume 2-4% greater</u> than the solid.

Fig. 4.4 <u>A two-dimensional representation of an instantaneous picture of the liquid structure.</u>

Many close-packed crystal-like clusters (shaded) are instantaneously formed.







Formation of Atomic Cluster

When the free energy of the atomic cluster with radius r is by

$$\Delta G_r = -\frac{4}{3}\pi r^3 \Delta G_V + 4\pi r^2 \gamma_{SL},$$

how many atomic clusters of radius r would exist in the presence of the total number of atoms, n₀?

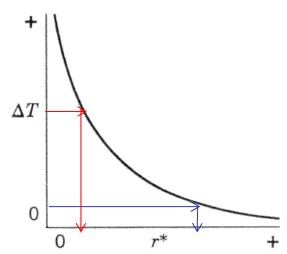
$$A_1 o A_2 o A_3 o A_4 o \cdots o A_{m-1} o A_m$$
 $n_2 = n_1 \exp\left(-\frac{\Delta G^{1 o 2}}{kT}\right)$ Excess free E associated with the cluster of $1 o 2$ atoms
 $n_m = n_1 \exp\left(-\frac{\Delta G^{1 o m}}{kT}\right)$
 $n_m = n_2 \exp\left(-\frac{\Delta G^{2 o 3}}{kT}\right)$
 $n_m = n_2 \exp\left(-\frac{\Delta G^{2 o 3}}{kT}\right)$
 $m_m = n_3 \exp\left(-\frac{\Delta G^{3 o 4}}{kT}\right)$
 $m_m = n_m \exp\left(-\frac{\Delta G^{3 o 4}}{kT}\right)$
 $m_m = n_m \exp\left(-\frac{\Delta G^{m-1 o m}}{kT}\right)$
 $m_m = n_1 \exp\left(-\frac{\Delta G^{m-1 o m}}{kT}\right)$

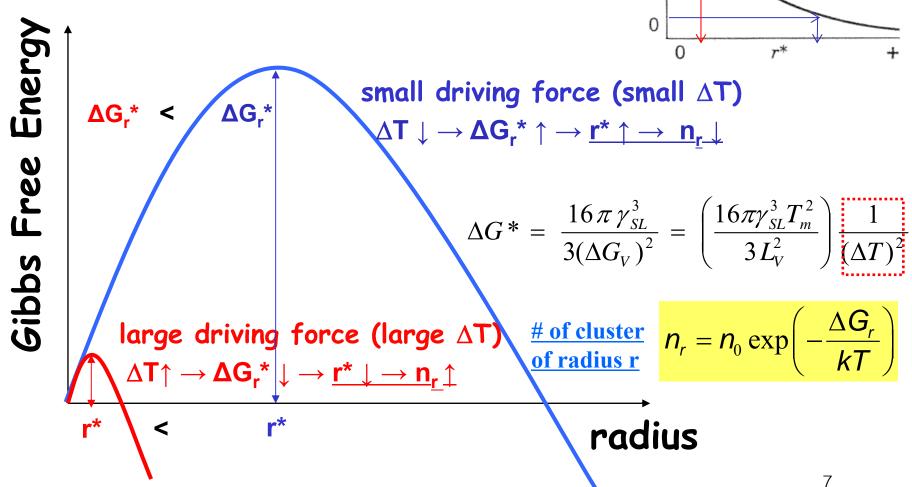
$$n_m = n_1 \exp\left(-\frac{\Delta G^{1 omega}}{kT}\right)$$
반지름 r인 구상의 군집체 수

Ster
 $n_r = n_0 \exp\left(-\frac{\Delta G_r}{kT}\right)$
 $r \uparrow \to \Delta G_r \uparrow$
embryo \Rightarrow Nucleus
 $:$ no longer part of liquid
radius
 $= n_0 \exp\left(-\frac{\Delta G_r}{kT}\right)$

Formation of Atomic Cluster

Compare the nucleation curves between small and large driving forces.





Formation of Atomic Cluster

 n_0 : total # of atoms.

 ΔG_r : excess free energy associated with the cluster

k: Boltzmann's constant

of cluster of radius r

$$n_r = n_0 \exp\left(-\frac{\Delta G_r}{kT}\right)$$

- holds for $T > T_m$ / $T < T_m$ and $r \le r^*$ Apply for all r / $r \le r^*$: no longer part of the liquid)

- n_r exponentially decreases with ΔG_r

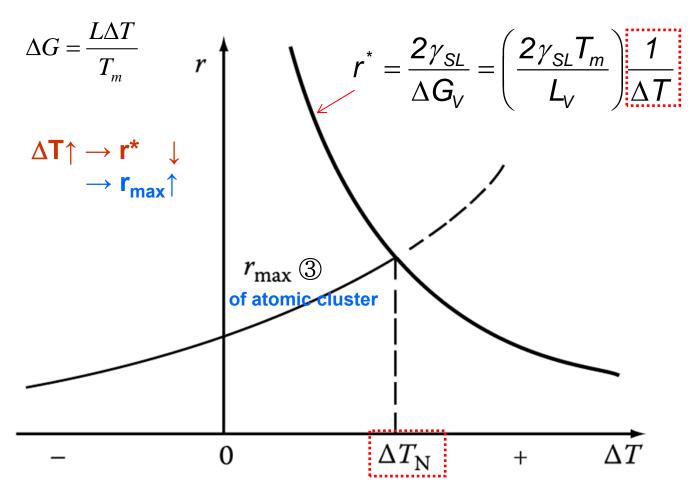
Ex. 1 mm³ of copper at its melting point (n₀: 10²⁰ atoms)

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r\downarrow \rightarrow n_r\uparrow \rightarrow \sim 10^{14} clusters of 0.3 nm radius (i.e. \sim 10 atoms)
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r \uparrow \rightarrow n_r \downarrow \rightarrow \sim 10 clusters of 0.6 nm radius (i.e. \sim 60 atoms)
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→ effectively a maximum cluster size, ~ 100 atoms $\sim 10^{-8}$ clusters mm⁻³ or 1 cluster in $\sim 10^7$ mm³

The creation of a critical nucleus ~ thermally activated process



 ΔT_N is the critical undercooling for homogeneous nucleation.

Fig. 4.5 The variation of r* and r_{max} with undercooling ΔT

4.1.2. The homogeneous nucleation rate - kinetics

How fast solid nuclei will appear in the liquid at a given undercooling?

 C_0 : atoms/unit volume

 \mathbf{C}^* : # of clusters with size of \mathbf{C}^* (critical size) 임계핵 크기의 cluster 수

$$C^* = C_0 \exp(-rac{\Delta G_{
m hom}^*}{kT})$$
 clusters / m³

The addition of one more atom to each of these clusters will convert them into stable nuclei. 한 개 원자 추가로 확산시 핵생성

Homogeneous Nucleation rate
$$N_{\rm hom} = f_0 C_o \exp(-\frac{\Delta G_{\rm hom}^*}{kT})$$
 nuclei / m³·s

$$f_{\rm o} \sim 10^{11} \, {\rm s}^{-1}$$
: frequency \propto vibration frequency energy of diffusion in liquid surface area (const.) $\Delta G^* = \left(\frac{16\pi\gamma_{SL}^3T_m^2}{3L_V^2}\right)\frac{1}{(\Delta T)^2}$ $C_{\rm o} \sim {\rm typically} \, 10^{29} \, {\rm atoms/m}^3$

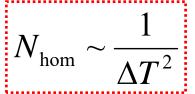
$$N_{\text{hom}} \approx 1 \text{ cm}^{-3} \text{s}^{-1} \text{ when } \Delta \text{G}^* \sim 78 \text{ kT}$$

4.1.2. The homogeneous nucleation rate - kinetics

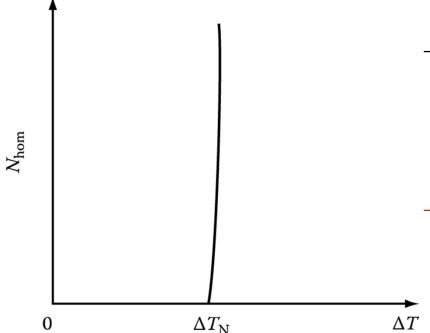
$$N_{\mathrm{hom}} pprox f_0 C_o \exp\{-rac{A}{\left(\Delta T
ight)^2}\}$$
 where $A = rac{16\pi \gamma_{SL}^3 T_m^2}{3\,L_V^2 k T}$
A = relatively insensitive to Temp.

where
$$A = \frac{16\pi \gamma_{SL}^3 T_m^2}{3 L_V^2 kT}$$

How do we define ΔT_N ?



 $N_{
m hom} \sim rac{1}{\Delta T^2} egin{array}{c} rac{
m Changes \ {
m by orders \ orde$



- → critical value for detectable nucleation
 - critical supersaturation ratio
 - critical driving force
 - critical supercooling
- \rightarrow for most metals, $\Delta T_N \sim 0.2 T_m$ (i.e. $\sim 200 K$)

Fig. 4.6 The homogeneous nucleation rate as a function of undercooling ΔT . ΔT_N is the critical undercooling for homogeneous 11 nucleation.

4.1.3. Heterogeneous nucleation

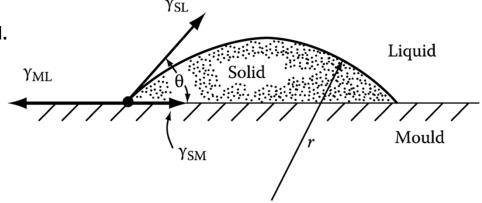
From
$$\Delta G^* = \left(\frac{16\pi\gamma_{SL}^3 T_m^2}{3I_m^2}\right) \frac{1}{(\Delta T)^2}$$

Nucleation becomes easy if $\gamma_{SL} \downarrow$ by forming nucleus from mould wall.

Fig. 4.7 Heterogeneous nucleation of spherical cap on a flat mould wall.

$$\gamma_{ML} = \gamma_{SL} \cos \theta + \gamma_{SM}$$

$$\cos\theta = (\gamma_{ML} - \gamma_{SM})/\gamma_{SL}$$



$$\Delta G_{het} = -V_{S}\Delta G_{v} + A_{SL}\gamma_{SL} + A_{SM}\gamma_{SM} - A_{SM}\gamma_{ML}$$

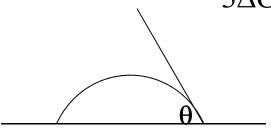
In terms of the wetting angle (θ) and the cap radius (r) (Exercise 4.6)

$$\Delta G_{het} = \left\{ -\frac{4}{3} \pi r^3 \Delta G_V + 4 \pi r^2 \gamma_{SL} \right\} S(\theta)$$

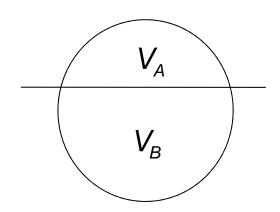
where
$$S(\theta) = (2 + \cos \theta)(1 - \cos \theta)^2 / 4$$

Barrier of Heterogeneous Nucleation

$$\Delta G^* = \frac{16\pi\gamma_{SL}^3}{3\Delta G_V^2} \cdot S(\theta) = \frac{16\pi\gamma_{SL}^3}{3\Delta G_V^2} \cdot \frac{(2-3\cos\theta+\cos^3\theta)}{4}$$



$$\Delta G_{het}^* = S(\theta) \Delta G_{hom}^*$$



$$\Delta G_{sub}^* = \Delta G_{homo}^* \left(\frac{2 - 3\cos\theta + \cos^3\theta}{4} \right)$$

$$\frac{V_A}{V_A + V_B} = \frac{2 - 3\cos\theta + \cos^3\theta}{4} = S(\theta)$$

How about the nucleation at the crevice or at the edge?

Contents for today's class

Solidification: Liquid Solid

- **Nucleation in Pure Metals**
- **Homogeneous Nucleation**

$$r^* = \frac{2\gamma_{SL}}{\Delta G_V} \Delta G^* = \frac{16\pi\gamma_{SL}^3}{3(\Delta G_V)^2} = \left(\frac{16\pi\gamma_{SL}^3 T_m^2}{3L_V^2}\right) \frac{1}{(\Delta T)^2}$$

$$r^* \& \Delta G^* \downarrow as \Delta T \uparrow$$

$$N_{\text{hom}} \approx f_0 C_o \exp\{-\frac{A}{(\Delta T)^2}\} \sim \frac{1}{\Delta T^2}$$

Heterogeneous Nucleation

$$\Delta G_{het}^* = S(\theta) \Delta G_{hom}^*$$

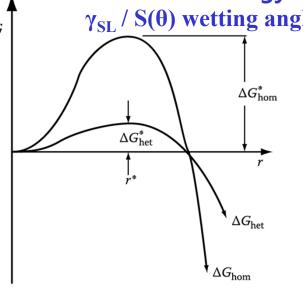
$$\frac{V_A}{V_A + V_B} = \frac{2 - 3\cos\theta + \cos^3\theta}{4} = S(\theta)$$

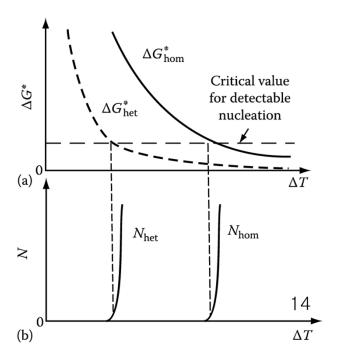
Nucleation of melting

$$\gamma_{SL} + \gamma_{LV} < \gamma_{SV}$$
 (commonly)

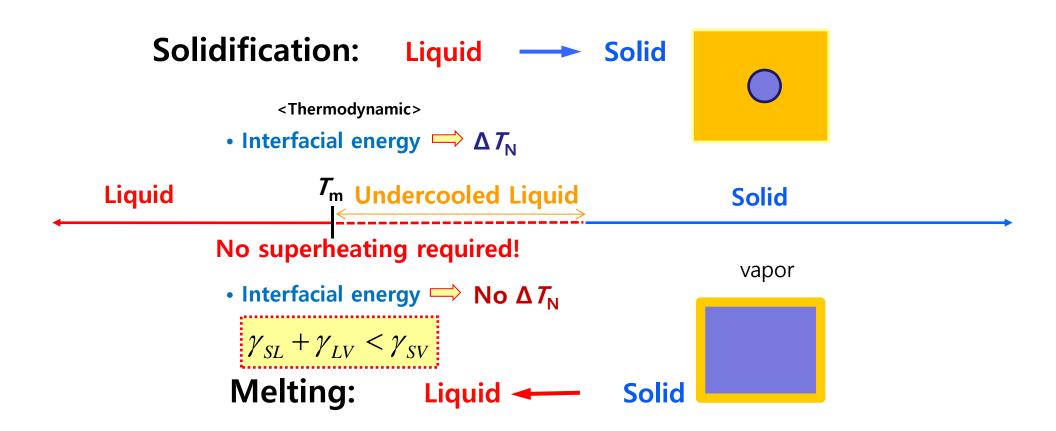
Undercooling ΔT

 Interfacial energy γ_{SL} / S(θ) wetting angle





Melting and Crystallization are Thermodynamic Transitions



Contents for today's class

Solidification: Liquid ---- Solid

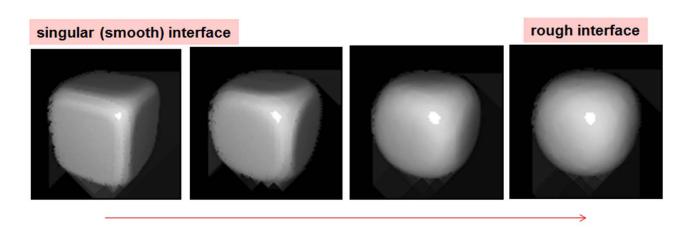
< Nucleation > &

Nucleation in Pure Metals

- < Growth >
- Equilibrium Shape and Interface Structure on an Atomic Scale
- Growth of a pure solid
- 1) Continuous growth
 - : Atomically rough or diffuse interface
- 2) Lateral growth
 - : Atomically flat of sharply defined interface
- Heat Flow and Interface Stability
- 4.3 Alloy solidification
 - Solidification of single-phase alloys
 - Eutectic solidification
 - Off-eutectic alloys
 - Peritectic solidification

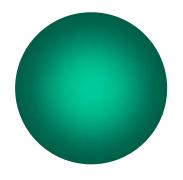
Q: Rough interface vs Singular interface?

Thermal Roughening



Heating up to the roughening transition.

Equilibrium Shape and Interface Structure on an Atomic Scale





How do you like to call them?

rough interface

singular (smooth) interface

What about the dependence of surface energy on crystal directions?

isotropic γ

anisotropic γ

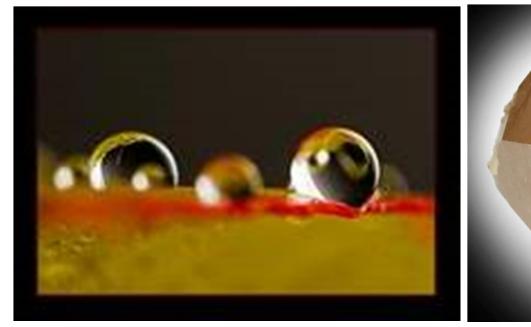
Do not vary with crystallographic orientation, i.e, γ-plots are spherical

Strong crystallographic effects, : solidify with low-index close-packed facets

Water Drops



Natural Minerals





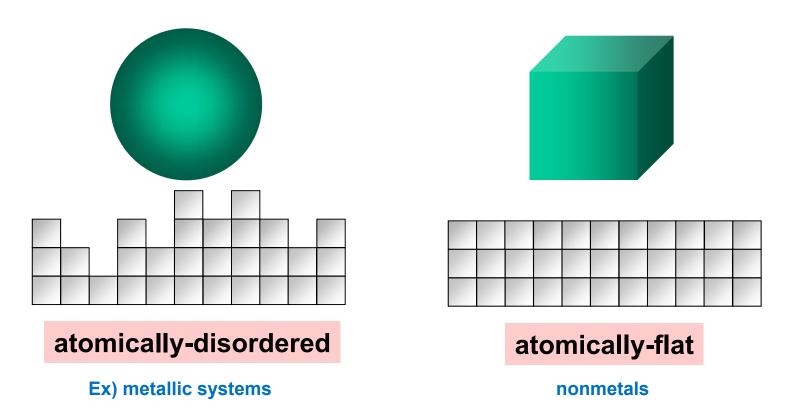


Topaz (황옥)

Stibnite (휘안광)

How differ the structure of the surface on an atomic scale?

Equilibrium Shape and Interface Structure on an Atomic Scale



Apply thermodynamics to this fact and derive more information.

Entropy-dominant

weak bonding energy

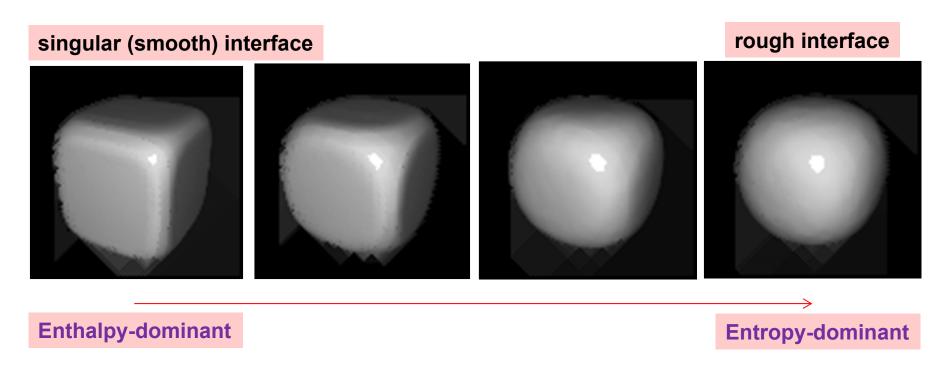
stable at high T

Enthalpy-dominant

strong bonding energy

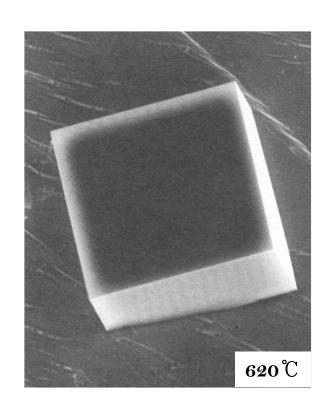
stable at low T

Thermal Roughening

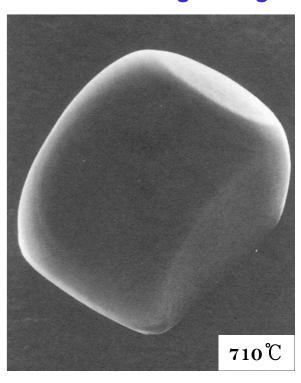


Heating up to the roughening transition.

✓ Equilibrium shape of NaCl crystal



Thermal Roughening

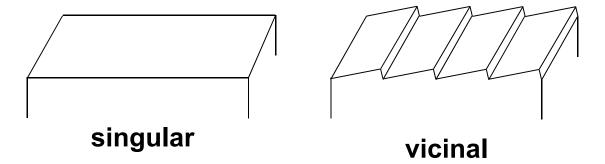


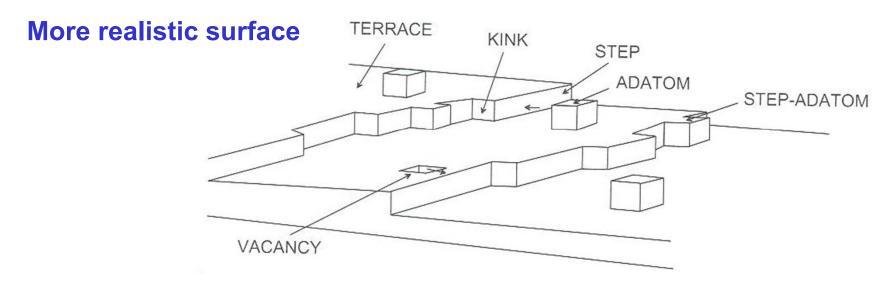
J.C. Heyraud, J.J. Metois, J. Crystal Growth, 84, 503 (1987)

Compare the kinetic barrier for atomic attachment. Which has a low growth barrier?

Atomic View

Ideal Surfaces



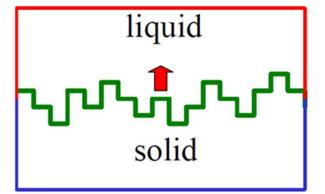


- Realistic surfaces of crystals typically look like this at low temperature
- At sufficiently high temperature, the structure becomes atomically rough (Thermal Roughening)

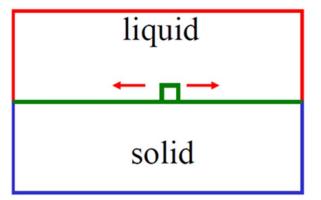
Q: What kinds of Growth in a pure solid exist?

Two types of solid-liquid interface

- a) Continuous growth
 - : Atomically rough or diffuse interface



- b) Lateral growth
- : Atomically flat of sharply defined interface

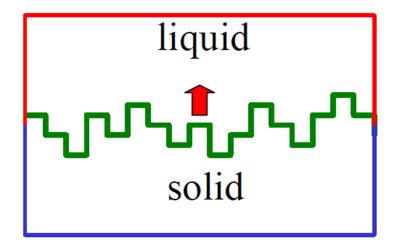


4.2. Growth of a pure solid

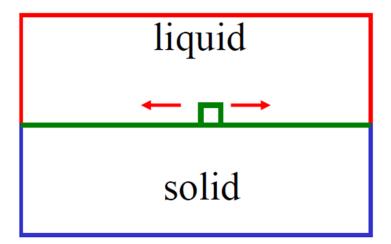
: The next step after the nucleation is growth.

Two types of solid-liquid interface

- a) Continuous growth
 - : Atomically rough or diffuse interface



- b) Lateral growth
 - : Atomically flat of sharply defined interface

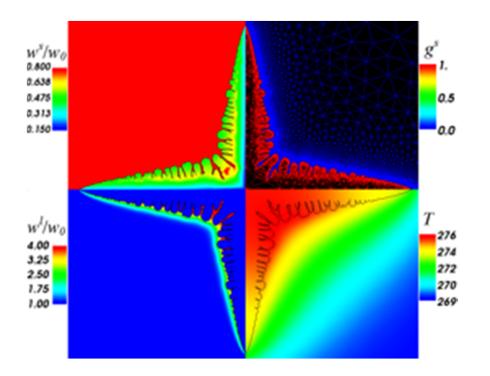


4.2. Growth of a pure solid

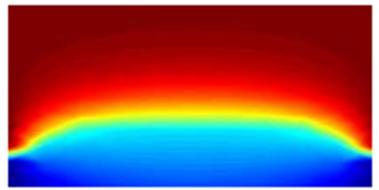
: The next step after the nucleation is growth.

Two types of solid-liquid interface

- a) Continuous growth
 - : Atomically rough or diffuse interface

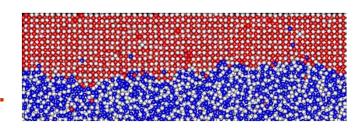


- b) Lateral growth
 - : Atomically flat of sharply defined interface



a) Continuous growth

The migration of a rough solid/liquid interface can be treated in a similar way to the migration of a random high angle grain boundary.

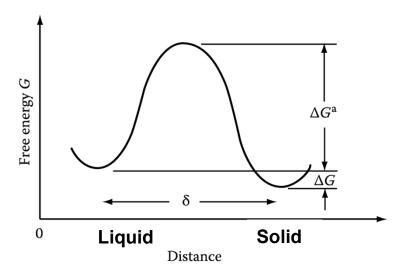


- Driving force for solidification_

$$\Delta G = \frac{L}{T_m} \Delta T_i$$

L: latent heat of melting

 ΔT_i : undercooling of the interface



Net rate of solidification_

$$\nu = k_1 \Delta T_i$$

 k_1 : properties of boundary mobility

Reference (eq. 3.21) $v = M \cdot \Delta G / V_m$

The rate of the continuous growth (typical for metals) is usually a <u>"diffusion controlled process"</u>.

Pure metal grow at a rate controlled by <u>heat transfer to the interfacial region</u>.

Alloy grow at a rate controlled by solute diffusion.

b) Lateral growth

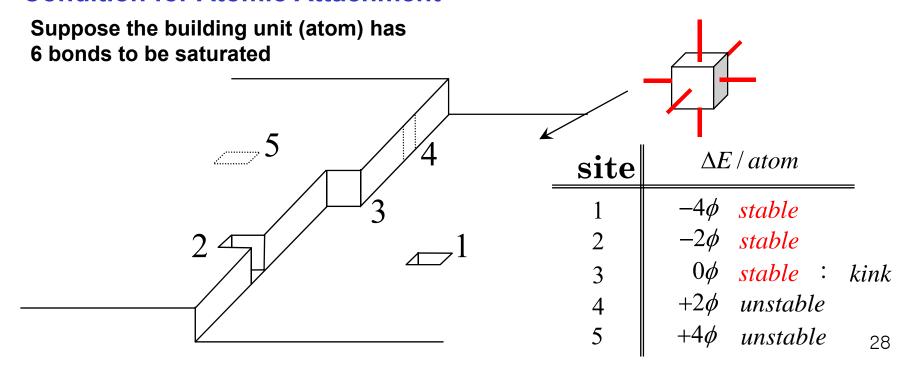
- Materials with a high entropy of melting (\sim high $T_{\rm m}$) prefer to form atomically smooth, closed-packed interfaces.
- For this type of interface the <u>minimum free energy</u> also corresponds to the <u>minimum internal energy</u>, i.e. a minimum number of broken 'solid' bonds.

Two ways in which ledges and jogs (kinks) can be provided.

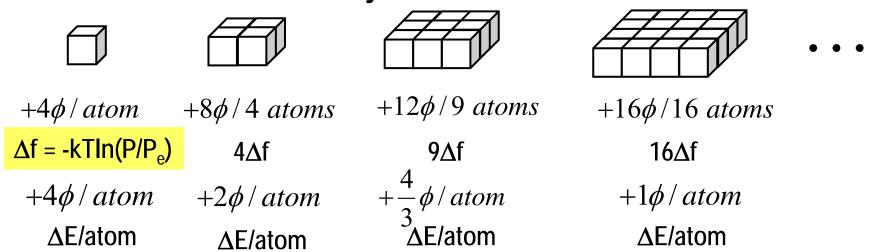
1 Surface (2-D) nucleation

② Spiral growth

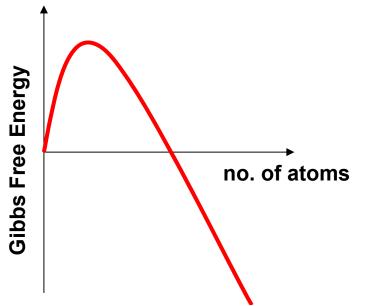
Condition for Atomic Attachment



How many unsaturated bonds are there if they are epitaxial to the underneath atomic layer?



Draw the plot showing how the free energy varies with the number of atoms in the presence of supersaturation (driving force) for growth.



→ 2-Dimensional Nucleation ①

- If large # of atoms form a disc-shaped layer,
- → <u>self-stabilized and continue to grow.</u>
- Δ*T* becomes large, r* ↓.

-
$$v \propto \exp(-k_2/\Delta T_i)$$

② Spiral growth: Growth by Screw Dislocation

<u>Crystals grown with a low supersaturation</u> were always found to have a 'growth spirals' on the growing surfaces.

- addition of atoms to the ledge cause it to rotate around the axis of screw dislocation
- If atoms add at an equal rate to all points along the step, the angular velocity of the step will be initially greatest nearest to the dislocation core.
- the spiral tightens until it reaches
 a minimum radius of r*

$$- v = k_3 (\Delta T_i)^2$$

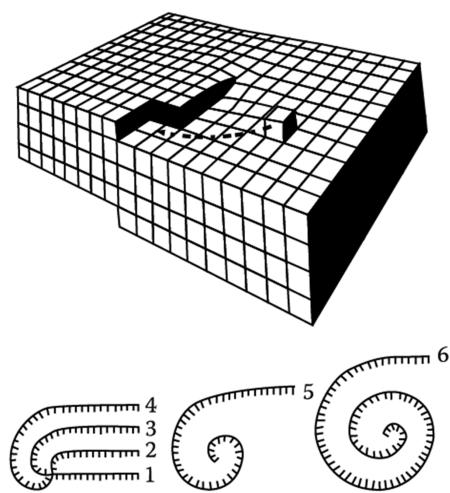
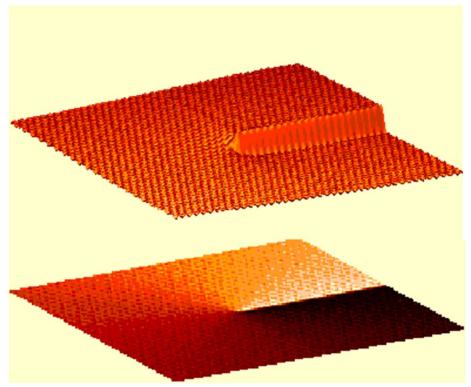


Fig. 4. 13 Spiral growth. (a) A screw dislocation terminating in the solid/liquid interface showing the associated ledge. Addition of atoms at the ledge causes it to rotate with an angular velocity decreasing away from the dislocation core so that a growth spiral develops as shown in (b).

Growth by Screw Dislocation



Burton, Cabrera and Frank (BCF, 1948) elaborated the spiral growth mechanism, assuming steps are atomically disordered...

Their interpretation successfully explained the growth velocity of crystals as long as the assumption is valid...

- ③ Growth from twin boundary → "feather crystal" under small ΔT
- another permanent source of steps like spiral growth
 - → not monoatomic height ledge but macro ledge

Kinetic Roughening

Rough interface - Ideal Growth ightarrow diffusion-controlled ightarrow dendritic growth

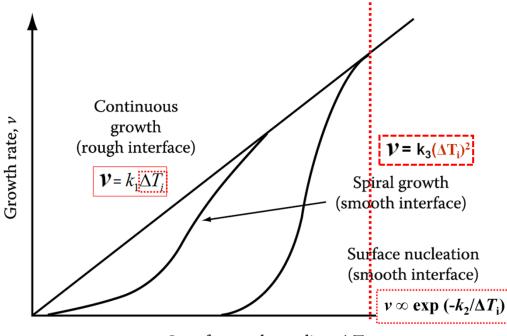
Smooth interface - Growth by Screw Dislocation Growth by 2-D Nucleation

Small $\Delta T \rightarrow$ "feather" type of growth \longleftarrow Large $\Delta T \rightarrow$ cellular/dendritic growth

The growth rate of the singular interface cannot be higher than ideal growth rate.

When the growth rate of the singular Interface is high enough, it follows the ideal growth rate like a rough interface.

→ kinetic roughening



Interface undercooling, ΔT_i

Q: Heat Flow and Interface Stability

1) Superheated liquid

: Extraction of latent heat by conduction in the crystal

2) Supercooled liquid

: conduction of latent heat into the liquid

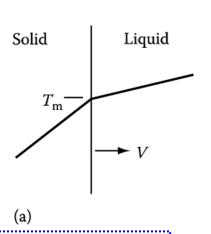
→ Development of Thermal Dendrite

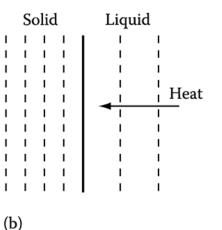
4.2.3 Heat Flow and Interface Stability - Planar interface

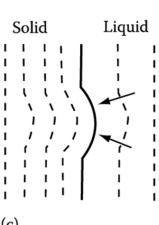
1) Superheated liquid

Consider the solidification front with heat flow from L to S.

solid growing at *v* (planar)







Heat flow away from the interface through the solid K T'

 \longleftrightarrow

 $\mathcal{K}_{L}\mathcal{T}_{L}'$ - Heat flow from the liquid

 VL_V - Latent heat generated at the interface

Heat Balance Equation

$$K_{S}T_{S}' = K_{L}T_{L}' + vL_{V}$$

K: thermal conductivity

If r is so large \to Gibbs-Thompson effect can be ignored the solid/liquid interface remain at T_m (r : radius of curvature of the protrusion)

dT/dx in the liquid ahead of the protrusion will increase more positively. T_L ? $& T_S$?

More heat to the protrusion \rightarrow melt away ν of protrusion \downarrow to match other ν in planar region

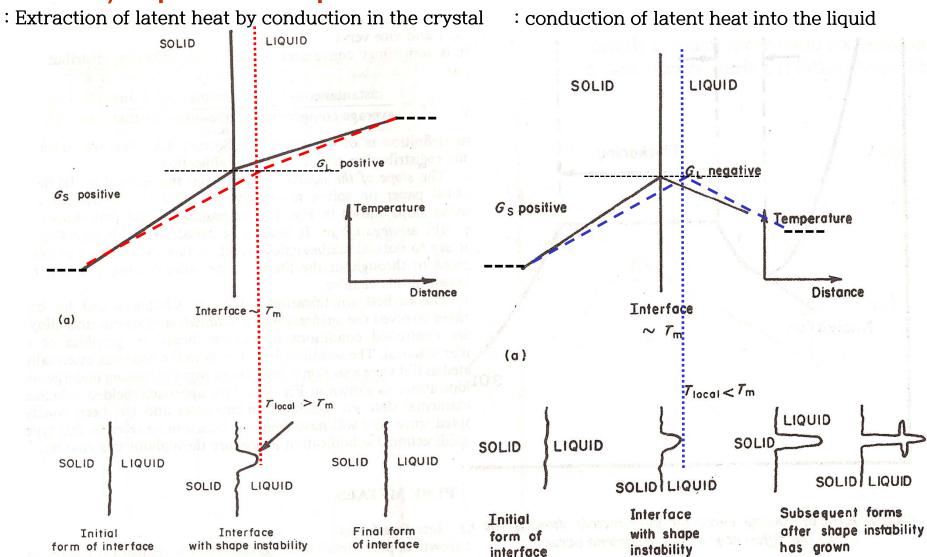
34

mould walls

"Removal of latent heat" → Heat Flow and Interface Stability

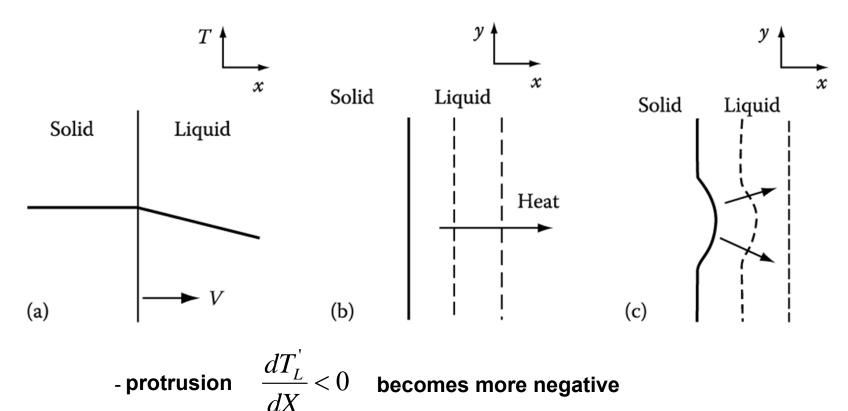
1) Superheated liquid

2) Supercooled liquid



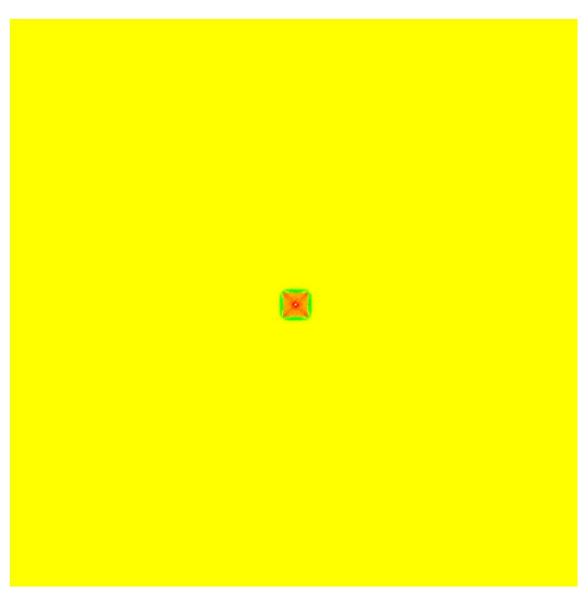
Heat Flow and Interface Stability - Planar interface

2) Solid growing into supercooled liquid



- heat flow from solid = the protrusion grows preferentially.

Solidification: Liquid → Solid



Development of Thermal Dendrite

cf) constitutional supercooling

When does heat flow into liquid?

- \rightarrow Liquid should be supercooled below $T_{\rm m}$.
- → Nucleation at impurity particles in the bulk of the liquid

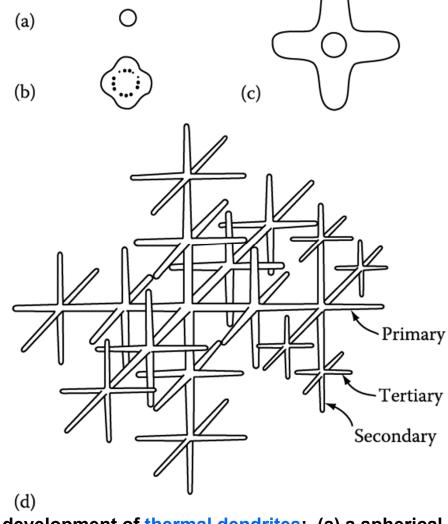


Fig. 4.17 The development of thermal dendrites: (a) a spherical nucleus; (b) the interface becomes unstable; (c) primary arms develop in crystallographic directions (<100> in cubic crystals); (d) secondary and tertiary arms develop

Q: How to calculate the growth rate (v) in the tip of a growing dendrite?

Closer look at the tip of a growing dendrite

different from a planar interface because heat can be conducted away from the tip in three dimensions.

Assume the solid is isothermal $(T'_{S} = 0)$

From

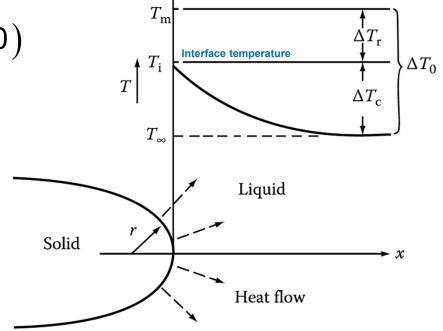
$$K_{S}T_{S}' = K_{L}T_{L}' + vL_{V}$$

If
$$T_{S}' = 0$$
, $V = \frac{-K_{L}T_{L}'}{L_{V}}$

A solution to the heat-flow equation for a hemispherical tip:

$$T_{L}'(negative) \cong \frac{\Delta T_{C}}{r} \quad \Delta T_{C} = T_{i} - T_{\infty}$$

$$v = \frac{-K_{L}T_{L}'}{L_{V}} \cong \frac{K_{L}}{L_{V}} \cdot \frac{\Delta T_{C}}{r} \qquad v \propto \frac{1}{r}$$



However, ΔT also depends on r. How?

Thermodynamics at the tip?

Gibbs-Thomson effect: melting point depression

$$\Delta G = \frac{L_V}{T_m} \Delta T_r = \frac{2\gamma}{r} \qquad \Delta T_r = \frac{2\gamma T_m}{L_V r}$$

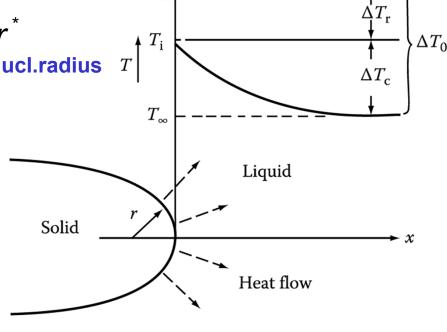
Minimum possible radius (r)?

$$r_{min}: \Delta T_r \to \Delta T_o = T_m - T_\infty \to r^*$$
The crit.nucl.radius
$$r^* = \frac{2\gamma T_m}{L_v \Delta T_o}$$

$$\Delta T_r = \frac{2\gamma T_m}{L_v r}$$

Express ΔT_r by r, r^* and ΔT_o .

$$\Delta T_r = \frac{r^*}{r} \Delta T_o$$



$$V \cong \frac{K_L}{L_V} \cdot \frac{\Delta T_c}{r} = \frac{K_L}{L_V} \cdot \frac{\left(\Delta T_0 - \Delta T_r\right)}{r} = \frac{K_L}{L_V} \cdot \frac{\Delta T_0}{r} \left(1 - \frac{r^*}{r}\right)$$

 $v \to 0$ as $r \to r^*$ due to Gibbs-Thomson effect as $r \to \infty$ due to slower heat condution

Maximum velocity?

$$\rightarrow r = 2r^*$$