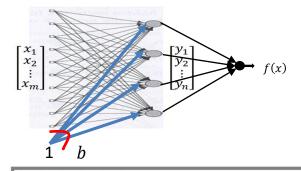
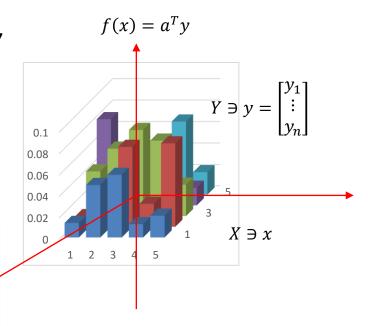
Nonlinear Mapping

$$T: X \to Y, \qquad y = \sigma(Wx + b), \qquad f(x) = a^T y$$



Universal Approximation Theorem Let ξ be a non-constant, bounded, and monotonically-increasing continuous activation function, $f:[0,1]^d\to\mathbb{R}$ continuous function, and $\epsilon>0$. Then, $\exists n$ and parameters $\mathbf{a},\mathbf{b}\in\mathbb{R}^n$, $\mathbf{W}\in\mathbb{R}^{n\times d}$ s.t.

$$\left| \sum_{i=1}^{n} a_i \xi(\mathbf{w}_i^{\top} \mathbf{x} + b_i) - f(\mathbf{x}) \right| < \epsilon \qquad \forall \mathbf{x} \in [0, 1]^d$$



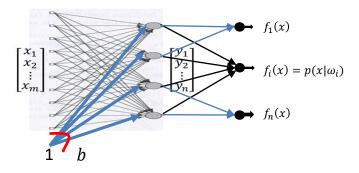
Geometric Deep Learning on graph and manifolds, Michael Bronstein, SIAM 2018, Imperial College London

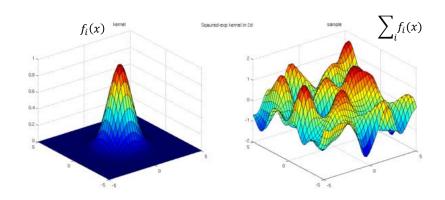
Nonlinear Mapping

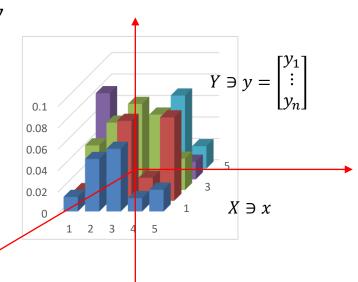


$$T: X \to Y$$
, $y = \sigma(Wx + b)$, $f_i(x) = a_i^T y$

$$f_i(x) = a_i^T y$$

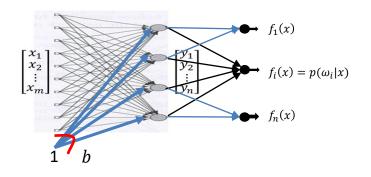


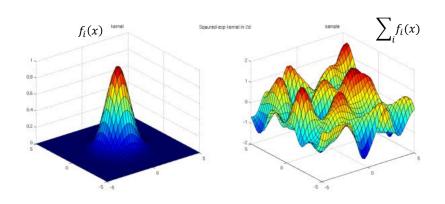


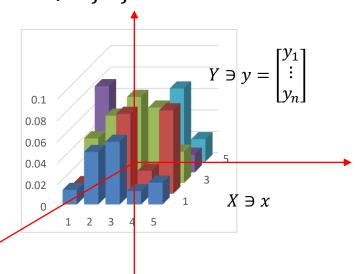


Nonlinear Mapping

$$T: X \to Y, \ y = \sigma(Wx + b), \ f_i(x) = \frac{a_i^T y}{\sum_j a_j^T y}$$
 (softmax)







Feature Dimension Reduction: PCA & LDA (I)

Jin Young Choi Seoul National University

Outline

Feature Extraction

Introduction of PCA & LDA

Principal Component Analysis (PCA)

Linear Discriminant Analysis (FLDA)

Multiple Discriminant Analysis (MDA)

Simple Enhancement of PCA/LDA

Feature Extraction

Features

Weight, Height, Width, Volume, Head size, ... Edge, Shape, Geometric Relations ... RGB Color for each pixel

SIFT, SURF, HOG, ...

Feature Extraction from Raw Data

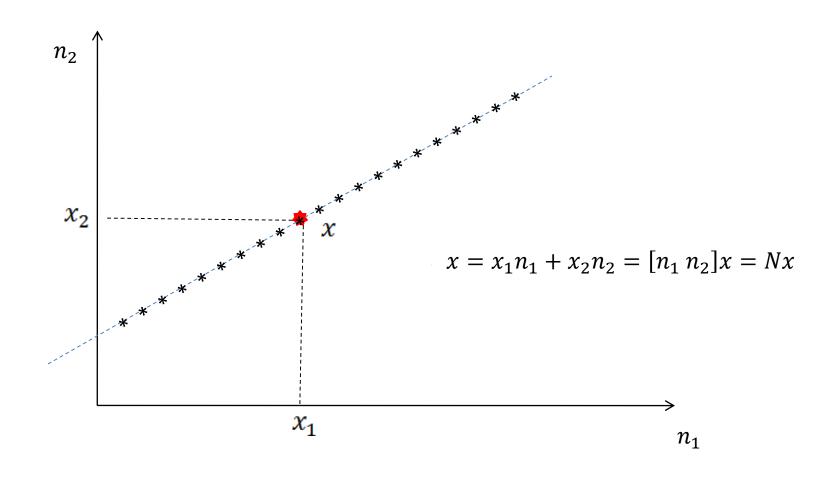
Pixel Valued Vector is raw data vector

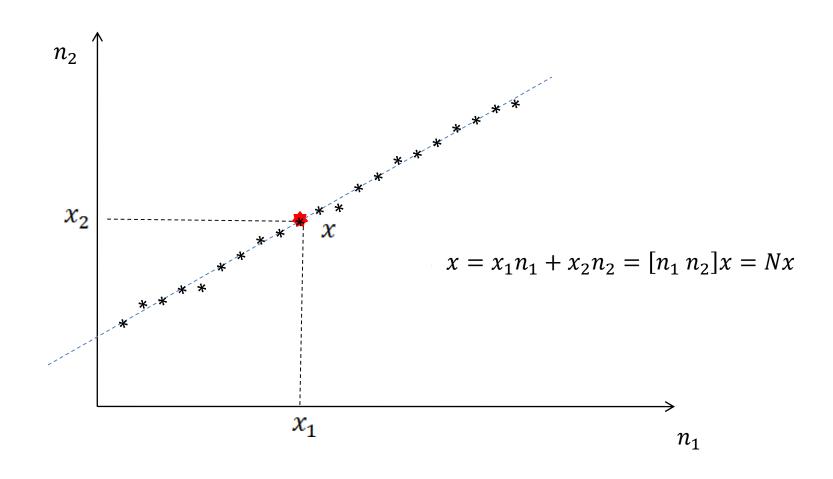
Raw data vector is redundant

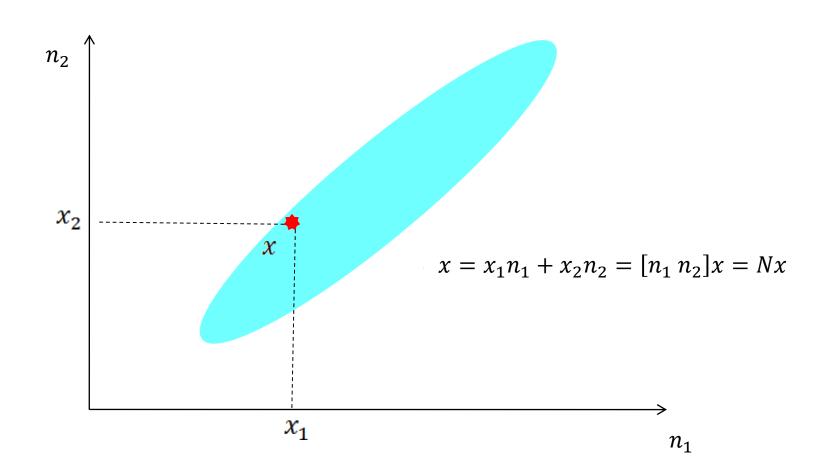
The dimension should be reduced

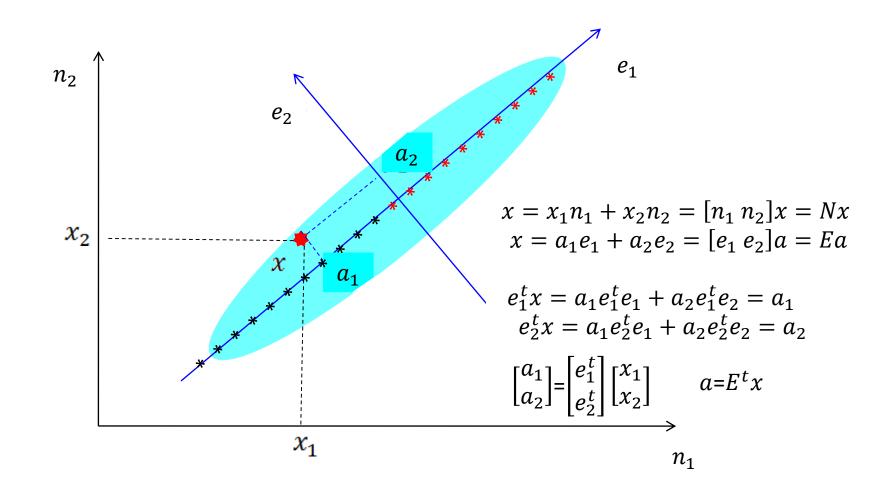
Component Analysis and Discriminants

- How to reduce excessive dimensionality?
 - Answer: Combine features highly dependent to each other.
- Linear methods project high-dimensional data onto lower dimensional space.
- Principal Components Analysis (PCA)
 - seeks the projection which <u>best represents</u> the data in a leastsquare error sense.
- Linear Discriminant Analysis (LDA) or Fisher Linear Discriminant
 - seeks the projection that <u>best separates</u> the data in a least-square discrimination error sense.

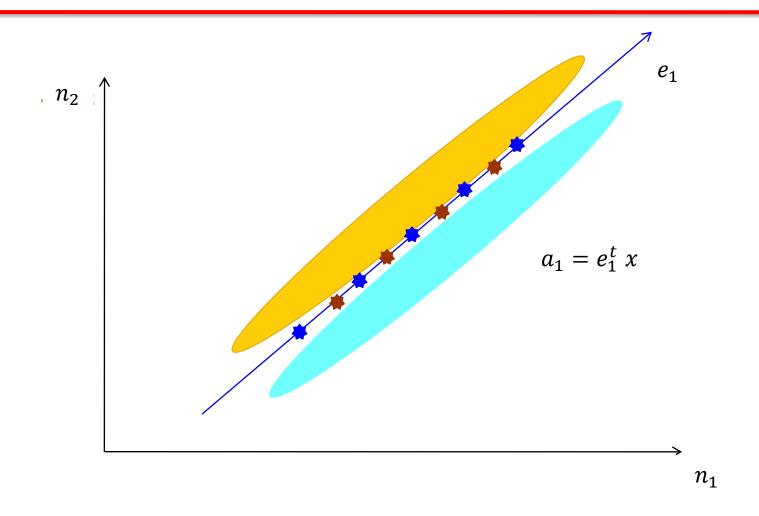




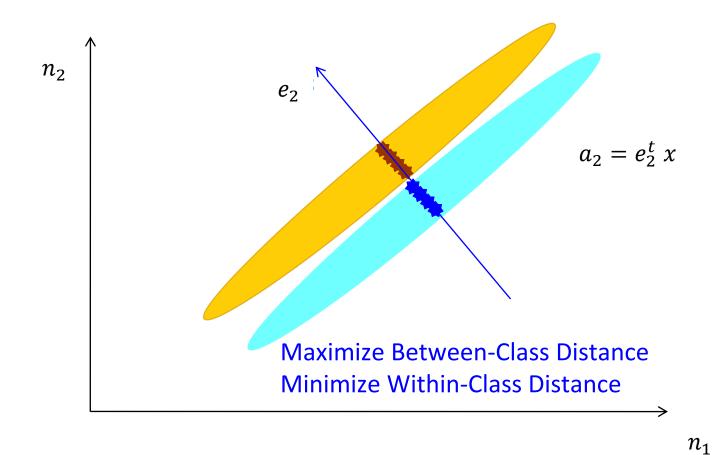




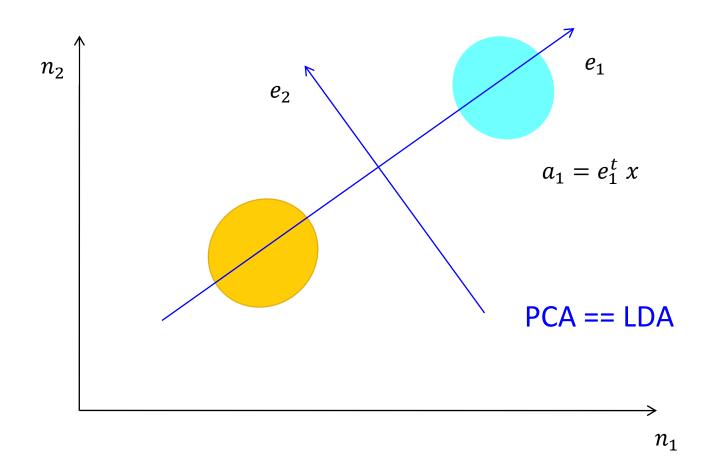
Linear Discriminant Analysis



Linear Discriminant Analysis



PCA & LDA



Principal Components Analysis (PCA)

- How to represent n d-dimensional vector samples $\{\mathbf{x}_1,...,\mathbf{x}_n\}$ by a single vector \mathbf{x}_0 ?
 - Find \mathbf{x}_0 that minimizes squared error correction function

$$J_0(\mathbf{x}_0) = \sum_{k=1}^n ||\mathbf{x}_0 - \mathbf{x}_k||^2$$
.

Principal Components Analysis (PCA)

- How to represent n d-dimensional vector samples $\{\mathbf{x}_1,...,\mathbf{x}_n\}$ by a single vector \mathbf{x}_0 ?
 - Find \mathbf{x}_0 that minimizes squared error correction function

$$J_0(\mathbf{x}_0) = \sum_{k=1}^n ||\mathbf{x}_0 - \mathbf{x}_k||^2$$
.

The solution is sample mean

$$x_0 = m = \frac{1}{n} \sum_{k=1}^{n} x_k$$

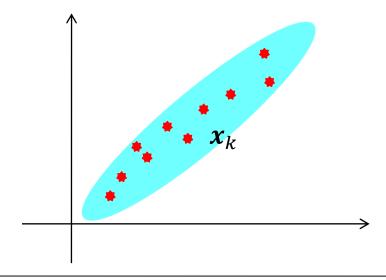
- This is zero-dimensional representation of the data set.
- One-dimensional representation by projecting the data onto a line through the sample mean reveals variability in the data.

Principal Components Analysis (PCA)

This is zero-dimensional representation of the data set.

$$x_0 = m = \frac{1}{n} \sum_{k=1}^{n} x_k$$

 One-dimensional representation by projecting the data onto a line through the sample mean reveals variability in the data.



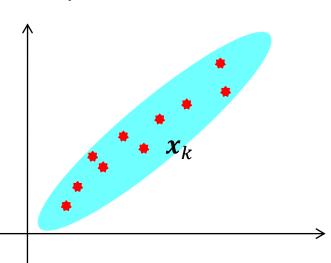
PCA; Projection

Let e be a unit vector in a direction of the line. The equation of the line

$$\mathbf{x} = \mathbf{m} + a \mathbf{e}$$

• Representing \mathbf{x}_k by $\mathbf{m} + a_k \mathbf{e}$ find "optimal" a_k set minimizing criterion function :

$$J_1(a_1,...,a_n,\mathbf{e}) = \sum_{k=1}^n ||\mathbf{m} + a_k \mathbf{e} - \mathbf{x}_k||^2.$$

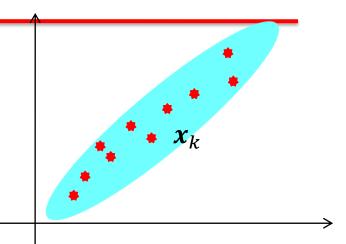


PCA; Projection

• Representing \mathbf{x}_k by $\mathbf{m} + a_k \mathbf{e}$ find "optimal" a_k set minimizing criterion function :

$$J_1(a_1,...,a_n,\mathbf{e}) = \sum_{k=1}^n ||\mathbf{m} + a_k \mathbf{e} - \mathbf{x}_k||^2.$$
from $\partial J_1 / \partial a_k = 0$

we find $a_k = \mathbf{e}^t (\mathbf{x}_k - \mathbf{m})$

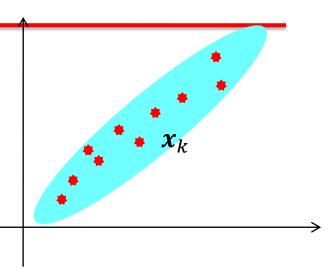


PCA; Projection

• Representing \mathbf{x}_k by $\mathbf{m} + a_k \mathbf{e}$ find "optimal" a_k

$$a_k = \mathbf{e}^t (\mathbf{x}_k - \mathbf{m})$$

How to find the best direction for e?



The least square solution: project the vector x_k onto the line in the direction of e, passing through the sample mean.

$$J_1(a_1,...,a_n,\mathbf{e}) = \sum_{k=1}^n ||\mathbf{m} + a_k \mathbf{e} - \mathbf{x}_k||^2 . \qquad a_k = \mathbf{e}^t (\mathbf{x}_k - \mathbf{m})$$

Minimize Jw.r.t e.

PCA; Scatter matrix

• Substituting a_k into $J_1(a, \mathbf{e})$ we find

$$J_{1}(a,\mathbf{e}) = \sum_{k=1}^{n} a_{k}^{2} \|\mathbf{e}\|^{2} - 2\sum_{k=1}^{n} a_{k} \mathbf{e}^{t} (\mathbf{x}_{k} - \mathbf{m}) + \sum_{k=1}^{n} ||\mathbf{x}_{k} - \mathbf{m}||^{2}$$

$$= \sum_{k=1}^{n} a_{k}^{2} - 2\sum_{k=1}^{n} a_{k}^{2} + \sum_{k=1}^{n} ||\mathbf{x}_{k} - \mathbf{m}||^{2} = -\sum_{k=1}^{n} [\mathbf{e}^{t} (\mathbf{x}_{k} - \mathbf{m})]^{2} + \sum_{k=1}^{n} ||\mathbf{x}_{k} - \mathbf{m}||^{2}$$

$$= -\sum_{k=1}^{n} \mathbf{e}^{t} (\mathbf{x}_{k} - \mathbf{m}) (\mathbf{x}_{k} - \mathbf{m})^{t} \mathbf{e} + \sum_{k=1}^{n} ||\mathbf{x}_{k} - \mathbf{m}||^{2}$$

$$= -\mathbf{e}^{t} \mathbf{S} \mathbf{e} + \sum_{k=1}^{n} ||\mathbf{x}_{k} - \mathbf{m}||^{2}$$

• where a *scatter matrix* **S** which is (n-1) times of sample covariance matrix

$$\mathbf{S} = \sum_{k=1}^{n} (\mathbf{x}_k - \mathbf{m}) (\mathbf{x}_k - \mathbf{m})^t.$$

PCA; Scatter matrix

$$J_1(a, \mathbf{e}) = -\mathbf{e}^t \mathbf{S} \mathbf{e} + \sum_{k=1}^n ||\mathbf{x}_k - \mathbf{m}||^2$$

- Vector **e** that minimizes J_1 also maximizes $e^t \mathbf{Se}$.
- So we find **e**, which maximize e^t Se

subject to constraint
$$\|e\|=1$$

- Let λ be Lagrange multiplier. $L = \mathbf{e}^t \mathbf{S} \mathbf{e} \lambda (\mathbf{e}^t \mathbf{e} 1)$
- Differentiating L with respect to **e**: $\partial L/\partial \mathbf{e} = 2\mathbf{S}\mathbf{e} 2\lambda \mathbf{e}$
- By setting to zero we see that e is an eigenvector of S:

$$\mathbf{Se} = \lambda \mathbf{e} \quad \mathbf{e}^t \mathbf{Se} = \lambda$$

• So to maximize e^t Se takes maximal λ

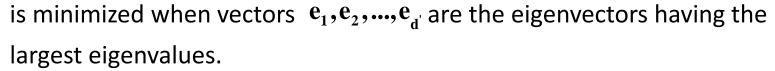
PCA; Scatter matrix

The result is easily extended to d' dimensional projection:

$$\mathbf{x}'_k = \mathbf{m} + \sum_{i=1}^{d'} a_k^i \mathbf{e}_i$$
 where $d' \le d$

The criterion function

$$J_{d'} = \sum_{k=1}^{n} \left\| \left(\mathbf{m} + \sum_{i=1}^{d'} a_k^i \mathbf{e}_i \right) - \mathbf{x}_k \right\|^2$$



• The coefficients $a_k^i = \mathbf{e}_i^t(\mathbf{x}_k - \mathbf{m})$ are principal components.

Error function

If d' < d error which is made by dropping the last terms is

$$J_{d'} = \sum_{k=1}^{n} \left\| \sum_{i=d'+1}^{d} a_k^i \mathbf{e}_i \right\|^2$$

$$= \sum_{i=d'+1}^{d} \mathbf{e}_i^t \sum_{k=1}^{n} (\mathbf{x}_k - \mathbf{m}) (\mathbf{x}_k - \mathbf{m})^t \mathbf{e}_i$$

$$= \sum_{i=d'+1}^{d} \mathbf{e}_i^t \mathbf{S} \mathbf{e}_i = \sum_{i=d'+1}^{d} \lambda_i$$

$$\mathbf{x}_{k}' = \mathbf{m}_{k} + \sum_{i=1}^{d'} a_{k}^{i} \mathbf{e}_{i}$$

$$a_{k}^{i} = \mathbf{e}_{i}^{t} (\mathbf{x}_{k} - \mathbf{m})$$

$$a_k^i = \mathbf{e}_i^t(\mathbf{x}_k - \mathbf{m})$$

This is a sum of lowest eigenvalues.

PCA – the algorithm

- Input: $X^{(n)} = \{\mathbf{x}_1, ..., \mathbf{x}_n\}, \quad \mathbf{x}_k = \langle x_1^k, ..., x_d^k \rangle$
- Take d' < d
- Output: $A^{(n)} = \{\mathbf{a}_1, ..., \mathbf{a}_n\}$ $\mathbf{a}_k = \{a_1^k, ..., a_{d'}^k\}$
- Algorithm:
 - Compute the mean of the training set $\mathbf{m} = \frac{1}{n} \sum_{k=1}^{n} \mathbf{x}_{k}$.
 - Compute the scatter matrix S.
 - Find eigenvectors of **S** and corresponding eigenvalues:

$$S\{\mathbf{e}_{i}, \lambda_{i}\}_{i=1}^{d}$$
, $\forall i : \mathbf{S}\mathbf{e}_{i} = \lambda \mathbf{e}_{i}$, $\lambda_{1} \geq \lambda_{2} \geq ... \lambda_{d}$

• Choose d' eigenvectors, and for each sample \mathbf{x}_k point compute

$$\mathbf{a}_{k} = \{\mathbf{e}_{i}^{t}(\mathbf{x}_{k} - \mathbf{m})\}_{i=1}^{d'}$$

Interim Summary

- **Principal Component Analysis**
 - ✓ Feature Extraction
 - ✓ Dimension Reduction

$$J_{d'} = \sum_{k=1}^{n} \left\| \left(\mathbf{m} + \sum_{i=1}^{d'} a_k^i \mathbf{e}_i \right) - \mathbf{x}_k \right\|^2$$

$$\mathbf{S} = \sum_{k=1}^{n} (\mathbf{x}_k - \mathbf{m}) (\mathbf{x}_k - \mathbf{m})^t.$$

$$\mathbf{Se} = \lambda \mathbf{e}$$

$$\mathbf{e}^{t}\mathbf{S}\mathbf{e}=\lambda$$

$$a_{k}^{i} = \mathbf{e}_{i}^{t}(\mathbf{x}_{k} - \mathbf{m}), i = 1, ..., d'$$

$$J_{d'} = \sum_{k=1}^{n} \left\| \left(\mathbf{m} + \sum_{i=1}^{d'} a_k^i \mathbf{e}_i \right) - \mathbf{x}_k \right\|^2$$

$$a_k^1 = \sum_{k=1}^{n} \left\| \left(\mathbf{m} + \sum_{i=1}^{d'} a_k^i \mathbf{e}_i \right) - \mathbf{x}_k \right\|^2$$

$$a_k^1 = \begin{bmatrix} \mathbf{e}_1^t \\ a_k^2 \\ \dots \\ a_k^{d'} \end{bmatrix} = \begin{bmatrix} \mathbf{e}_1^t \\ \mathbf{e}_2^t \\ \dots \\ \mathbf{e}_{d'}^t \end{bmatrix}$$

$$\mathbf{x}_k - \mathbf{m}$$

$$\mathbf{a}_k = \mathbf{E}^t(\mathbf{x}_k - \mathbf{m})$$

$$cf$$
) $\mathbf{y}_k = \mathbf{W}^t(\mathbf{x}_k - \mathbf{m})$

Feature Dimension Reduction: PCA & LDA (II)

Jin Young Choi Seoul National University

Outline

Feature Extraction

Introduction of PCA & LDA

Principal Component Analysis (PCA)

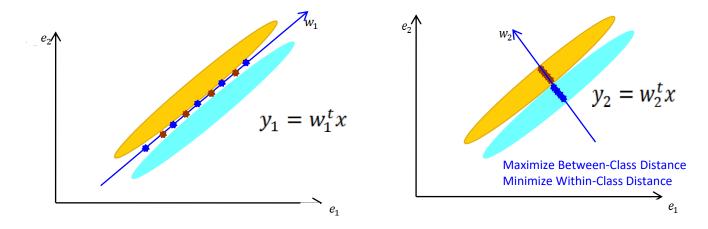
Linear Discriminant Analysis (FLDA)

Multiple Discriminant Analysis (MDA)

Simple Enhancement of PCA/LDA

Linear Discriminant Analysis: LDA

- We have n d-dimensional samples $\mathbf{x}_1,...,\mathbf{x}_n, n_1$ in a subset D_1 , labeled \mathbf{w}_1 and n_2 in a subset D_2 , labeled \mathbf{w}_2 .
- Find direction of line w, that maximally separate the data.



 Let a difference between sample means be a measure of separation of projected points

• Project samples \mathbf{x}_k onto \mathbf{w} .

$$\mathbf{y}_k = \mathbf{w}^t \mathbf{x}_k$$

- n samples Y_k are divided into the subsets Y_1 and Y_2
- Let \mathbf{m}_i be the sample mean $\mathbf{m}_i = \frac{1}{n_i} \sum_{\mathbf{x} \in D_i} \mathbf{x}$
- The sample mean for projected points

$$\tilde{m}_i = \frac{1}{n_i} \sum_{\mathbf{y} \in \mathbf{Y}_i} \mathbf{y} = \frac{1}{n_i} \sum_{\mathbf{x} \in D_i} \mathbf{w}^t \mathbf{x} = \mathbf{w}^t \mathbf{m}_i$$

Distance between the projected means is

$$|\tilde{m}_1 - \tilde{m}_2| = |\mathbf{w}^t (\mathbf{m}_1 - \mathbf{m}_2)|$$



lacktriangle A scatter for projected samples labeled ω_i

$$\tilde{s}_i^2 = \sum_{\mathbf{y} \in Y_i} (\mathbf{y} - \tilde{m}_i)^2$$

 $(1/n)(\tilde{s}_1^2 + \tilde{s}_2^2)$ is an estimate of the variance of the pooled data. $\tilde{s}_1^2 + \tilde{s}_2^2$ is called total within-class scatter of the projected samples.

• The Fisher discriminant employs $\mathbf{W}^{t}\mathbf{X}$ for which criterion

$$J(\mathbf{w}) = \frac{|\tilde{m}_1 - \tilde{m}_2|^2}{\tilde{s}_1^2 + \tilde{s}_2^2}$$

is maximum

• Define scatter matrices S_i and S_w by

$$S_i = \sum_{x \in D_i} (\mathbf{x} - \mathbf{m}_i) (\mathbf{x} - \mathbf{m}_i)^t$$

and

$$S_{w} = S_1 + S_2$$

Then

$$\tilde{s}_i^2 = \sum_{\mathbf{x} \in D_i} (\mathbf{w}^t \mathbf{x} - \mathbf{w}^t m_i)^2 = \sum_{\mathbf{x} \in D_i} \mathbf{w}^t (\mathbf{x} - m_i) (\mathbf{x} - m_i)^t \mathbf{w} = \mathbf{w}^t \mathbf{S}_i \mathbf{w}$$

Thus

$$\tilde{s}_1^2 + \tilde{s}_2^2 = \mathbf{w}^t \mathbf{S}_w \mathbf{w}$$



Similarly,

$$(\tilde{m}_1 - \tilde{m}_2)^2 = (\mathbf{w}^t \mathbf{m}_1 - \mathbf{w}^t \mathbf{m}_2)^2 = \mathbf{w}^t (\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^t \mathbf{w} = \mathbf{w}^t \mathbf{S}_B \mathbf{w}$$

 \mathbf{S}_{w} is called within-class scatter matrix (proportional to sample covariance matrix)

 $\mathbf{S}_B = (\mathbf{m}_1 - \mathbf{m}_2)(\mathbf{m}_1 - \mathbf{m}_2)^t$ is called between-class scatter matrix.

This gives the equivalent expression for Fisher's discriminant

$$J(\mathbf{w}) = \frac{\mathbf{w}^t \mathbf{S}_B \mathbf{w}}{\mathbf{w}^t \mathbf{S}_W \mathbf{w}}$$

Which vector w maximizes it?

$$\nabla_{\mathbf{w}} J(\mathbf{w}) = \frac{2\mathbf{S}_{B} \mathbf{w}}{\mathbf{w}^{t} \mathbf{S}_{W} \mathbf{w}} - \frac{\mathbf{w}^{t} \mathbf{S}_{B} \mathbf{w}}{\mathbf{w}^{t} \mathbf{S}_{W} \mathbf{w}} \frac{2\mathbf{S}_{W} \mathbf{w}}{\mathbf{w}^{t} \mathbf{S}_{W} \mathbf{w}} = 0$$

Hence one gets

$$\mathbf{S}_{B}\mathbf{w} = \lambda \mathbf{S}_{W}\mathbf{w}, \quad \lambda = \frac{\mathbf{w}^{t}\mathbf{S}_{B}\mathbf{w}}{\mathbf{w}^{t}\mathbf{S}_{W}\mathbf{w}},$$
 $\mathbf{S}_{W}^{-1}\mathbf{S}_{B}\mathbf{w} = \lambda \mathbf{w},$

or equivalently

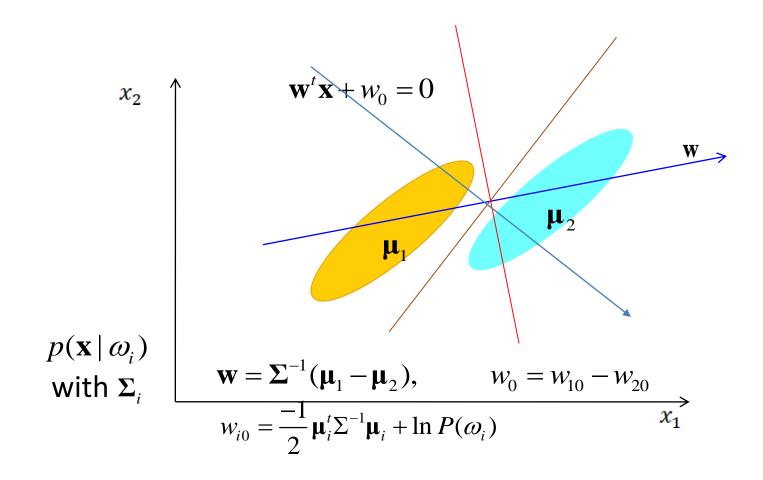
Since for any **w**, S_B **w** is always in the direction of m_1 - m_2 :

$$\mathbf{S}_{B}\mathbf{w} = (\mathbf{m}_{1} - \mathbf{m}_{2})(\mathbf{m}_{1} - \mathbf{m}_{2})^{t}\mathbf{w} = \alpha(\mathbf{m}_{1} - \mathbf{m}_{2})$$

- It is not necessary to determine the eigenvalues of $\mathbf{S}_W^{-1}\mathbf{S}_B$.
- One simply gets

$$\mathbf{w} \propto S_W^{-1}(\mathbf{m}_1 - \mathbf{m}_2)$$

- Scale factor for w is unimportant (why?).
- FLDA is one-dimensional projection



Matrix Norm

Induced Norm

$$||A||_p = \sup_{||x||_p = 1} ||Ax||_p \qquad ||A||_1 = \max_{1 \le j \le n} \sum_{i=1}^m |a_{ij}| \qquad ||A||_{\infty} = \max_{1 \le i \le m} \sum_{j=1}^n |a_{ij}|$$

Spectral (maximum singular value) norm

Schatten norm

$$\|A\|_p = \left(\sum_{i=1}^{\min\{m,\,n\}} \sigma_i^p(A)
ight)^{1/p}$$

nuclear norm

$$\|A\|_* = \operatorname{trace}ig(\sqrt{A^*A}ig) = \sum_{i=1}^{\min\{m,\,n\}}\!\sigma_i(A)$$

Frobenius Norm

$$\|A\|_{ ext{F}} = \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} |a_{ij}|^2} = \sqrt{ ext{trace}(A^{\mathsf{T}}A)} = \sqrt{\sum_{i=1}^{\min\{m,n\}} \sigma_i^2(A)} = \sup_{\|\mathbf{y}\|_2 = 1} (\sum_{\|\mathbf{y}\|_2 = 1} \mathbf{y}_i^2 \lambda_i)^{1/2} - (\lambda_i - \lambda_i)^{1/2}$$

$$f(A) = ||A||_{2} = \sigma_{\max}(A) = (\lambda_{\max}(A^{T}A))^{1/2}$$

$$||A||_{2} = \sup_{\|x\|_{2}=1} ||Ax||_{2}$$

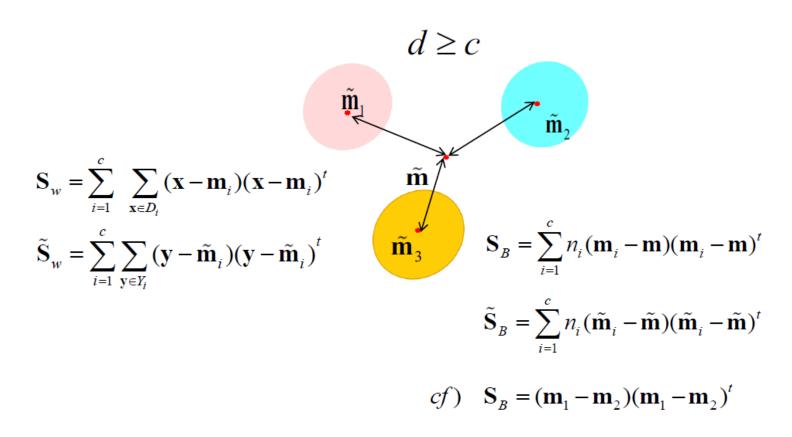
$$= \sup_{\|x\|_{2}=1} (x^{T}A^{T}Ax)^{1/2}$$

$$= \sup_{\|x\|_{2}=1} (x^{T}U^{T}\Lambda Ux)^{1/2}$$

$$= \sup_{\|y\|_{2}=1} (y^{T}\Lambda y)^{1/2} \iff y^{T}y = x^{T}U^{T}Ux = 1$$

$$= \sup_{\|y\|_{2}=1} (\sum_{\|y\|_{2}=1} y_{i}^{2}\lambda_{i})^{1/2}$$

$$= (\lambda_{\max}(X^{T}X))^{1/2}$$



- For the c -class problem we have c-1 discriminant functions.
- The projection from a d-dimensional space to a (c-1) dimension is accomplished by (c-1) discriminant functions (we assume $d \ge c$).
- Within-class scatter matrix is: $\mathbf{S}_{w} = \sum_{i=1}^{c} \mathbf{S}_{i}$ where $\mathbf{S}_{i} = \sum_{\mathbf{x} \in D_{i}} (\mathbf{x} \mathbf{m}_{i})(\mathbf{x} \mathbf{m}_{i})^{t}$ and $\mathbf{m}_{i} = \frac{1}{n_{i}} \sum_{\mathbf{x} \in D_{i}} \mathbf{x}$
- Define a total mean vector

$$\mathbf{m} = \frac{1}{n} \sum_{\mathbf{x}} \mathbf{x} = \frac{1}{n} \sum_{i=1}^{c} n_i \mathbf{m}_i$$

And total scatter matrix

$$\mathbf{S}_T = \sum_{\mathbf{x}} (\mathbf{x} - \mathbf{m}) (\mathbf{x} - \mathbf{m})^t$$

It can be transformed to

$$\mathbf{S}_{T} = \sum_{i=1}^{c} \sum_{\mathbf{x} \in D_{i}} (\mathbf{x} - \mathbf{m}_{i} + \mathbf{m}_{i} - \mathbf{m}) (\mathbf{x} - \mathbf{m}_{i} + \mathbf{m}_{i} - \mathbf{m})^{t}$$

$$= \sum_{i=1}^{c} \sum_{\mathbf{x} \in D_{i}} (\mathbf{x} - \mathbf{m}_{i}) (\mathbf{x} - \mathbf{m}_{i})^{t} + \sum_{i=1}^{c} \sum_{\mathbf{x} \in D_{i}} (\mathbf{m}_{i} - \mathbf{m}) (\mathbf{m}_{i} - \mathbf{m})^{t}$$

$$= \mathbf{S}_{W} + \sum_{i=1}^{c} n_{i} (\mathbf{m}_{i} - \mathbf{m}) (\mathbf{m}_{i} - \mathbf{m})^{t} = \mathbf{S}_{W} + \mathbf{S}_{B}$$

The between-class scatter is:

$$\mathbf{S}_B = \sum_{i=1}^{c} n_i (\mathbf{m}_i - \mathbf{m}) (\mathbf{m}_i - \mathbf{m})^t$$

For the c -class problem we have (c-1) discriminant functions. The projection from a d-dimensional space to a (c-1) dimensional space is accomplished by (c-1) discriminant functions:

$$y_i = \mathbf{w}_i^t \mathbf{x}$$
 $i = 1, ..., (c-1)$

- Taking d-by-(c-1) W matrix which columns are vectors \mathbf{W}_i , we'll get in matrix form: $\mathbf{y} = \mathbf{W}^t \mathbf{x}$
- Samples $\mathbf{X}_1, ..., \mathbf{X}_n$ are projected to $\mathbf{y}_1, ..., \mathbf{y}_n$.
- We define $\tilde{\mathbf{m}}_i = \frac{1}{n_i} \sum_{\mathbf{y} \in Y_i} \mathbf{y}$, $\tilde{\mathbf{m}} = \frac{1}{n} \sum_{\mathbf{y} \in Y_i} n_i \tilde{\mathbf{m}}_i$

$$\tilde{\mathbf{S}}_{W} = \sum_{i=1}^{c} \sum_{\mathbf{y} \in Y_{i}} (\mathbf{y} - \tilde{\mathbf{m}}_{i}) (\mathbf{y} - \tilde{\mathbf{m}}_{i})^{t}$$

$$\tilde{\mathbf{S}}_{B} = \sum_{i=1}^{c} n_{i} (\tilde{\mathbf{m}}_{i} - \tilde{\mathbf{m}}) (\tilde{\mathbf{m}}_{i} - \tilde{\mathbf{m}})^{t}$$

- It's easy to show that $\tilde{\mathbf{S}}_{w} = \mathbf{W}^{t} \mathbf{S}_{w} \mathbf{W}$ and $\tilde{\mathbf{S}}_{B} = \mathbf{W}^{t} \mathbf{S}_{B} \mathbf{W}$
- The criterion function which should be maximized is:

$$J(\mathbf{W}) = \frac{|\tilde{\mathbf{S}}_{B}|}{|\tilde{\mathbf{S}}_{W}|} = \frac{|\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W}|}{|\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W}|} = \frac{tr(\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W})}{tr(\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W})} = \frac{\sum_{i} \mathbf{w}_{i}^{t}\mathbf{S}_{B}\mathbf{w}_{i}}{\sum_{i} \mathbf{w}_{i}^{t}\mathbf{S}_{W}\mathbf{w}_{i}}$$

• Every column \mathbf{w}_i of \mathbf{W} we should be solution of generalized eigenvalue problem

$$\mathbf{S}_{W}^{-1}\mathbf{S}_{B}\mathbf{w}_{i}=\lambda_{i}\mathbf{w}_{i}$$

The criterion function which should be maximized is:

$$J(\mathbf{W}) = \frac{|\tilde{\mathbf{S}}_{B}|}{|\tilde{\mathbf{S}}_{W}|} = \frac{|\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W}|}{|\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W}|} = \frac{tr(\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W})}{tr(\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W})} = \frac{\sum_{i} \mathbf{w}_{i}^{t}\mathbf{S}_{B}\mathbf{w}_{i}}{\sum_{i} \mathbf{w}_{i}^{t}\mathbf{S}_{W}\mathbf{w}_{i}}$$

• Every column \mathbf{w}_i of \mathbf{W} we should be solution of generalized eigenvalue problem

$$\mathbf{S}_{W}^{-1}\mathbf{S}_{B}\mathbf{w}_{i} = \lambda_{i}\mathbf{w}_{i}$$

$$\mathbf{S}_{B}\mathbf{w}_{i} = \lambda_{i}\mathbf{S}_{W}\mathbf{w}_{i}$$

$$\mathbf{S}_{B}\mathbf{W} = \mathbf{S}_{W}\mathbf{W}\boldsymbol{\Lambda}$$

$$\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W} = \mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W}\boldsymbol{\Lambda}$$

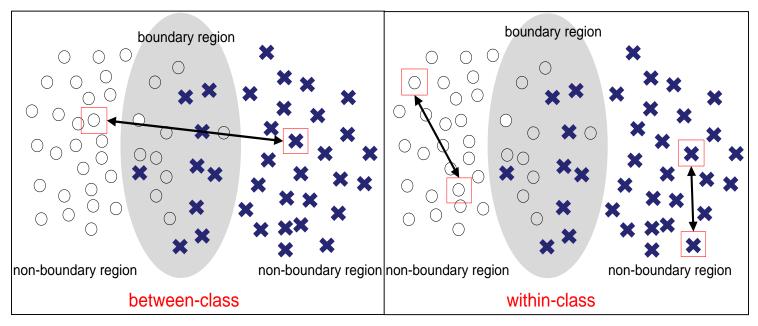
$$tr(\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W}) = tr(\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W})tr(\boldsymbol{\Lambda})$$

$$tr(\boldsymbol{\Lambda}) = \sum_{i}\lambda_{i} = \frac{tr(\mathbf{W}^{t}\mathbf{S}_{B}\mathbf{W})}{tr(\mathbf{W}^{t}\mathbf{S}_{W}\mathbf{W})}$$

- The MDA provides the way of reducing the dimensionality of the problem.
- The technique for finding probability density might not be feasible in the original space.
- The technique for finding probability density may work well after reducing the dimension of feature space.
- MDA may improve the separability of classes.

Simple Enhancement for PCA/LDA

- Significant pairs for between-class scatter matrix
 - Non-boundary patterns with the different class labels
- Significant pairs for within-class scatter matrix
 - Non-boundary patterns with the same class labels



Non-boundary Pattern Selection Algorithm

- fill Step 1. For each ${f x}_i \in {f X}$
 - Find the neighborhood defined as follows.

$$Neighbors(\mathbf{x}_i, k) = N(\mathbf{x}_i, k) \cup \{\mathbf{x}_i\}$$

where $N(\mathbf{x}_i, k)$ is the set of k nearest samples to \mathbf{x}_i by L2-norm.

■ Calculate voting probabilities of $Neighbors(\mathbf{x}_i, k)$ to each class j.

$$p_j(\mathbf{x}_i) = \frac{\sum_{\forall n \in Neighbors(\mathbf{x}_i, k)} I_j(n)}{k+1}$$

where $I_i(n)$ is 1 if the class of neighbor n is j, otherwise 0.

lacktriangle Calculate the neighborhood entropy of \mathbf{x}_i .

Neighbors_Entropy(
$$\mathbf{x}_i, k$$
) = $\sum_{j=1}^{l} p_j(\mathbf{x}_i) \log_l \frac{1}{p_j(\mathbf{x}_i)}$

lacksquare Step 2. Obtain boundary patterns $\mathbf{X}^{(B)}$ and non-boundary patterns $\mathbf{X}^{(NB)}$

$$\mathbf{X}^{(NB)} = \{\mathbf{x} | Neighbors_Entropy(\mathbf{x}, k) \leq \boxed{\theta(l)}, \mathbf{x} \in \mathbf{X} \}$$

 $\mathbf{X}^{(B)} = \mathbf{X} - \mathbf{X}^{(NB)}$

PCA using NPS (LDA in the same manner)

- Select non-boundary patterns via BNPS.
- Non-boundary patterns make up significant pairs.
- Emphasize the significant pairs.

Whole data

$$\mathbf{C}_X = \frac{1}{n-1} \sum_{i=1}^{n} (\mathbf{x}_i - \mathbf{m}) (\mathbf{x}_i - \mathbf{m})^\mathsf{T}$$

$$\mathbf{W}_{PCA} = \arg \max_{\mathbf{W}^{\mathsf{T}}\mathbf{W} = \mathbf{I}} \operatorname{tr}(\mathbf{W}^{\mathsf{T}}\mathbf{C}_{X}\mathbf{W})$$

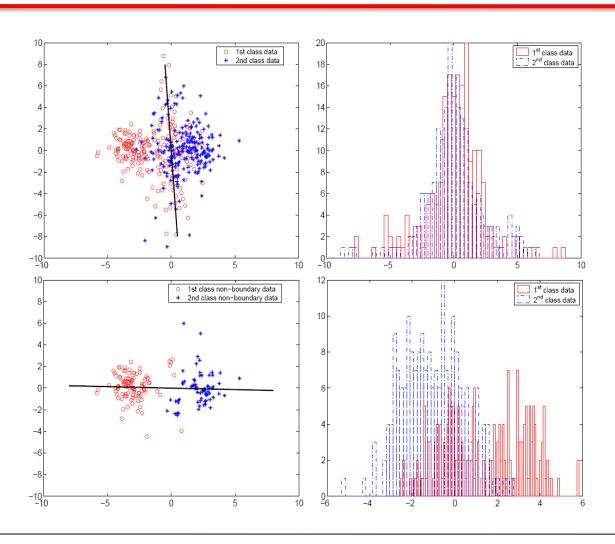


Non-boundary pattern

$$\widetilde{\mathbf{C}}_X = \frac{1}{n_{NB} - 1} \sum_{i=1}^{l} \sum_{j:y_j = i} (\mathbf{x}_j^{(NB)} - \widetilde{\mathbf{m}}) (\mathbf{x}_j^{(NB)} - \widetilde{\mathbf{m}})^\mathsf{T}$$

$$\widetilde{\mathbf{W}}_{PCA} = \arg \max_{\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{W}} = \mathbf{I}} \operatorname{tr}(\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{C}}_{X} \widetilde{\mathbf{W}})$$

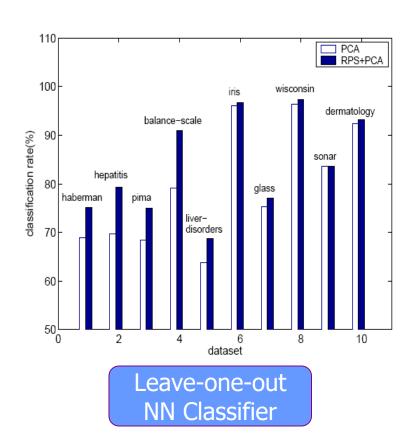
Toy Example

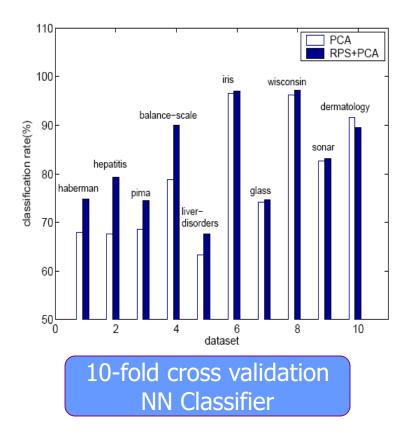


UCI Machine Learning Repository

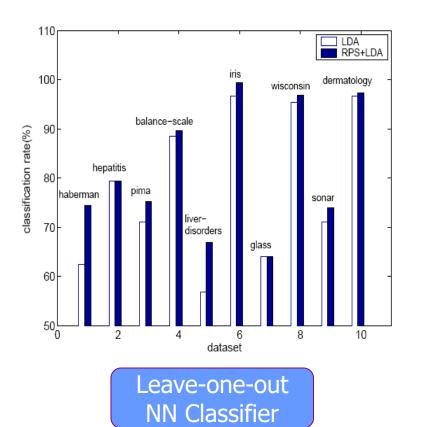
Name	# of data	# of attributes	# of classes	Missing attributes
Haberman	306	3	2	No
Hepatitis	155	19	2	Yes
Pima	768	8	2	No
Balance-scale	625	4	3	No
Liver-disorders	345	6	2	No
Iris	150	4	3	No
Glass	214	9	6	No
Wisconsin	699	9	2	Yes
Sonar	208	60	2	No
Dermatology	366	34	6	Yes

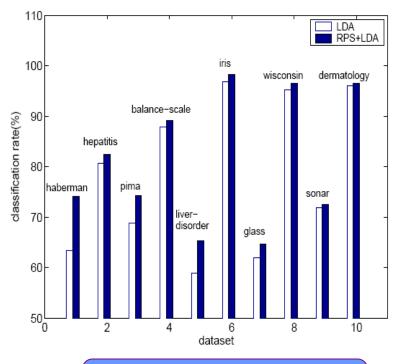
PCA vs. NPS+PCA





LDA vs. NPS+LDA





10-fold cross validation NN Classifier

Interim Summary

Fisher Linear Discriminant Analysis

$$J(\mathbf{w}) = \frac{\mathbf{w}^t \mathbf{S}_B \mathbf{w}}{\mathbf{w}^t \mathbf{S}_W \mathbf{w}} \qquad \mathbf{S}_W^{-1} \mathbf{S}_B \mathbf{w} = \lambda \mathbf{w}, \qquad \mathbf{w} \propto S_W^{-1} (\mathbf{m}_1 - \mathbf{m}_2)$$

Multiple Discriminant Analysis

$$\mathbf{S}_{B} = \sum_{i=1}^{c} n_{i} (\mathbf{m}_{i} - \mathbf{m}) (\mathbf{m}_{i} - \mathbf{m})^{t} \qquad \mathbf{S}_{W}^{-1} \mathbf{S}_{B} \mathbf{w}_{i} = \lambda_{i} \mathbf{w}_{i}$$

Simple Enhancement for PCA/LDA

$$\widetilde{\mathbf{W}}_{PCA} = \arg\max_{\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{W}} = \mathbf{I}} \mathrm{tr}(\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{C}}_{X} \widetilde{\mathbf{W}})$$

$$\widetilde{\mathbf{W}}_{LDA} = \arg \max_{\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{W}} = \mathbf{I}} \frac{\operatorname{tr}(\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{S}}^{(b)} \widetilde{\mathbf{W}})}{\operatorname{tr}(\widetilde{\mathbf{W}}^{\mathsf{T}} \widetilde{\mathbf{S}}^{(w)} \widetilde{\mathbf{W}})}$$