

Binary Search Trees

Kyunghan Lee Networked Computing Lab (NXC Lab) Department of Electrical and Computer Engineering Seoul National University https://nxc.snu.ac.kr kyunghanlee@snu.ac.kr







Outline

□ This topic covers binary search trees:

- Abstract Sorted Lists
- Background
- Definition and examples
- Implementation:
 - FindMin, FindMax, insert, erase
 - Previous smaller and next larger objects
 - Finding the *k*th object





Abstract Sorted Lists

- Previously, we discussed Abstract Lists: the objects are linearly ordered by the programmer
- We will now discuss the Abstract Sorted List:
 - The relation is based on an implicit linear ordering





Abstract Sorted Lists (ASL)

- Queries that may be made about data stored in a Sorted List ADT include:
 - Finding the smallest and largest values
 - Finding the *k*th largest value
 - Find the next larger or previous smaller objects of a given object
 - Iterate through objects within an interval [a, b]



Limitation: ASL with Array or Linked Lists

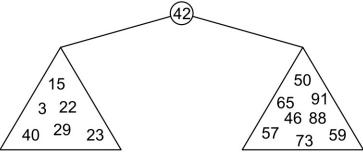
- If we implement an Abstract Sorted List using an array or a linked list, some operations take O(n)
 - To perform insertion, we may either traverse or copy, on average, O(n) objects





Binary Search Trees

- Using a binary tree, we can dictate an order on the two children
- □ We will exploit this order:
 - All objects in the left sub-tree to be less than the object stored in the root node, and
 - All objects in the right sub-tree to be greater than the object in the root object



Recursive definition: Each of the two sub-trees will themselves be binary search trees



Binary Search Trees

□ We can use this structure for searching

With a linear order, one of the following three must be true:

$$a < b \quad a = b \quad a > b$$

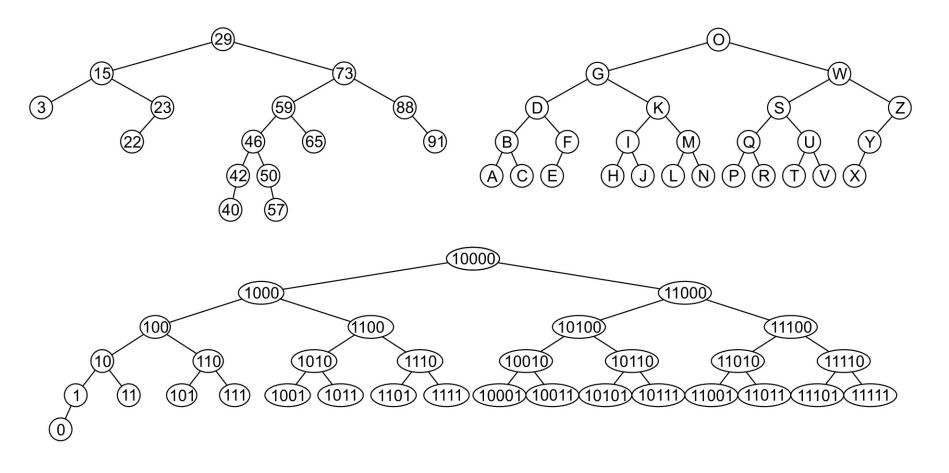
- Examine the root node and if we have not found what we are looking for:
 - If the object is less than what is stored in the root node, continue searching in the left sub-tree
 - Otherwise, continue searching the right sub-tree





Binary Search Trees: Good Example

□ Here are other examples of binary search trees:







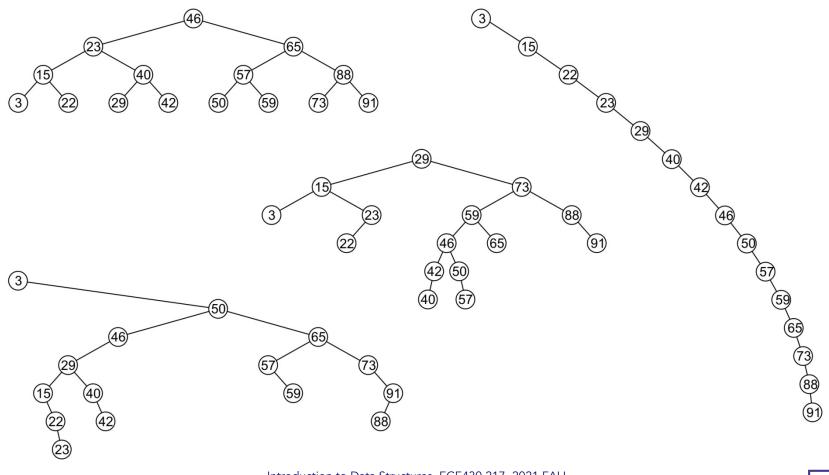
Binary Search Trees: Bad Example

- Unfortunately, it is possible to construct unbalanced binary search trees
 - (15) This is equivalent to a linked list, *i.e.*, O(n)



Binary Search Trees: More Examples

□ All these binary search trees store the same data







Note: No Duplicate Values

- We will assume that in any binary tree, we are not storing duplicate values unless otherwise stated
- You can always consider duplicate values with modifications to the algorithms we will cover





Implementation: Binary Search Trees

 \Box Design with two classes:

1) BinaryNode

Represent each node in the tree

2) BinarySearchTree

 Represent the tree, which holds the root node (an instance of BinaryNode)





Implementation: class BinaryNode

```
template <typename T>
struct BinaryNode {
    T value;
    BinaryNode *left;
    BinaryNode *right;

    BinaryNode<T>(const T &value, BinaryNode<T> *left, BinaryNode<T> *right)
        : value{value}, left{left}, right{right} {}

    BinaryNode<T>(T &&value, BinaryNode<T> *left, BinaryNode<T> *right)
        : value{std::move(value)}, left{left}, right{right} {}
};
```

Recall the concept of reference variable from "T &value"

- A value has a template based type <T>
- If <T> is not comparable, you will need to override comparison operators



Implementation: class BinarySearchTree

```
template <typename T>
class BinarySearchTree {
public:
   BinarySearchTree() : root{nullptr} {}
   const T &findMin() const;
   const T &findMax() const;
   bool find(const T &x) const;
   void insert(const T &x);
   void remove(const T &x);
   // something more ...
private:
   BinaryNode<T> *root;
   // something more ...
};
```





Finding the Minimum Object

```
const T &findMin() const {
          if (isEmpty())
              throw std::exception{};
          return findMin(root)->value;
     }
     BinaryNode<T> *findMin(BinaryNode<T> *t) const {
          if (t == nullptr)
              return nullptr;
          if (t->left == nullptr)
              return t;
          return findMin(t->left);
     }
                                                    (42)
                        (39)
                                                                                 70
         (11)
                                                                  (51
                                                                                               (99)
   8
                                                           (47
                                                                                           (96)
                    (34)
                                                                      (54)
3
                                                                            63
                                   The run time: O(h)
```





Finding the Maximum Object

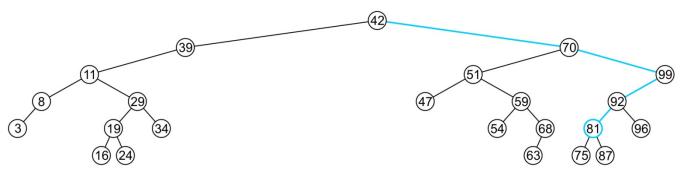
```
const T &findMax() const {
       if (isEmpty())
           throw std::exception{};
       return findMax(root)->value;
   }
   BinaryNode<T> *findMax(BinaryNode<T> *t) const {
       if (t != nullptr)
           while (t->right != nullptr)
               t = t - right;
       return t;
   }
                                               (42
                    39
                                                                                         99
      11
8
                                                                                     (96)
                (34
                                                                 (54
```

minimum/maximum values are not necessarily leaf nodes

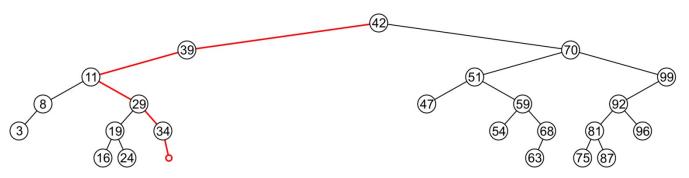


Find

- To determine membership, traverse the tree based on the linear relationship:
 - If a node containing the value is found, e.g., 81, return true



• If an empty node is reached, *e.g.*, 36, return false:





Find

□ The implementation is similar to findMin and findMax:

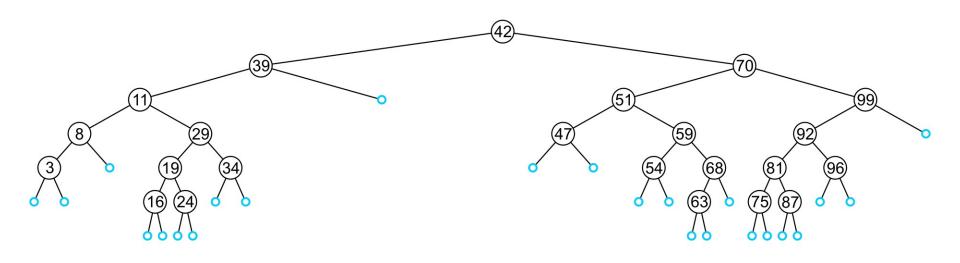
The run time is O(h)

```
bool find(const T &x) const { return contains(x, root); }
bool find(const T &x, BinaryNode<T> *t) const {
    if (t == nullptr)
        return false;
    else if (x < t->value)
        return find(x, t->left);
    else if (t->value < x)
        return find(x, t->right);
    else
        return true; // Match
}
```



 \Box An insertion will be performed at an empty node:

Any empty node is a possible location for an insertion

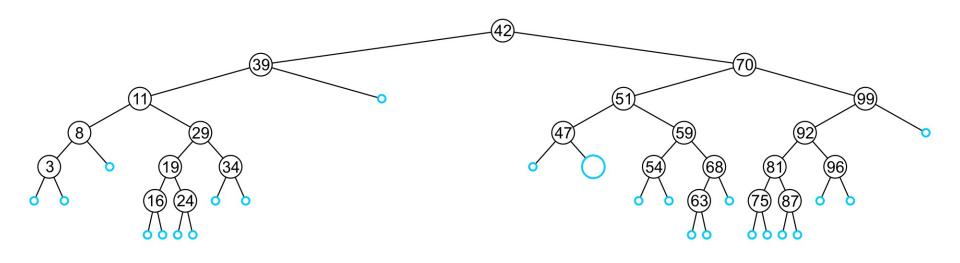


 The values which may be inserted at any empty node depend on the surrounding nodes





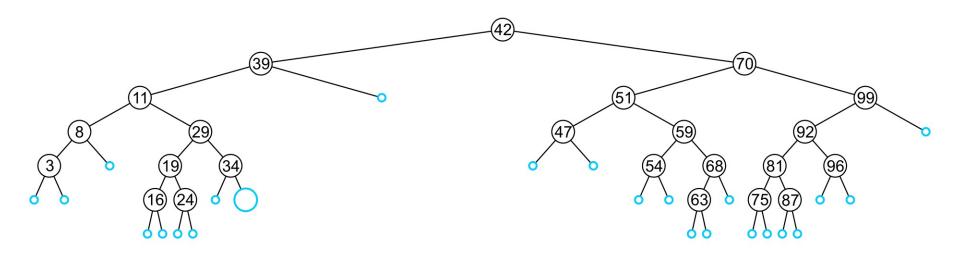
□ For example, this node may hold 48, 49, or 50







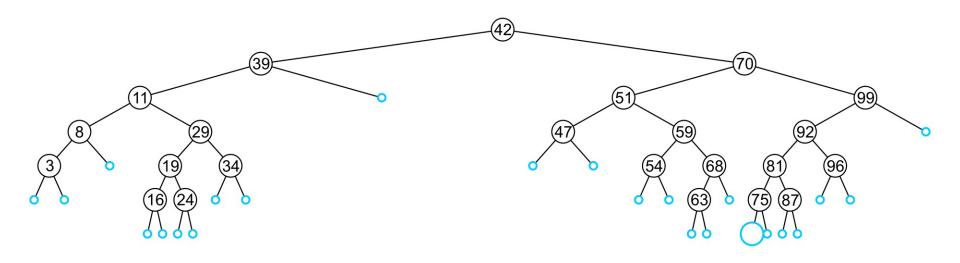
 \square An insertion at this location must be 35, 36, 37, or 38







□ This empty node may hold values from 71 to 74





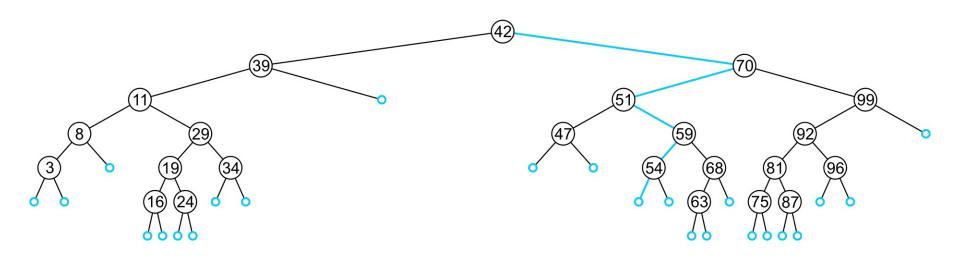


□ Like find, we will step through the tree

- If we find the object already in the tree, we will return
 - The object is already in the binary search tree (no duplicates)
- Otherwise, we will arrive at an empty node
- The object will be inserted into that location
- The run time is O(h)

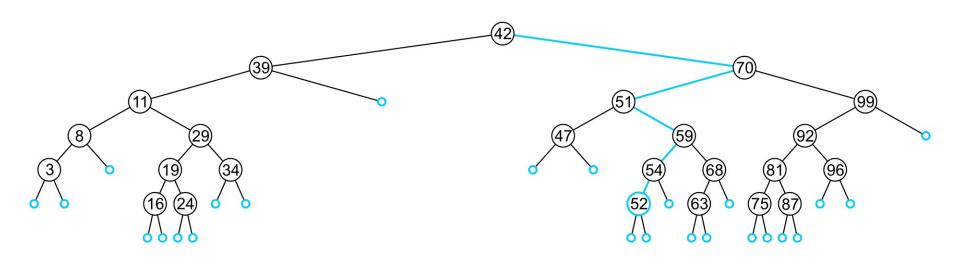


- In inserting the value 52, we traverse the tree until we reach an empty node
 - The left sub-tree of 54 is an empty node





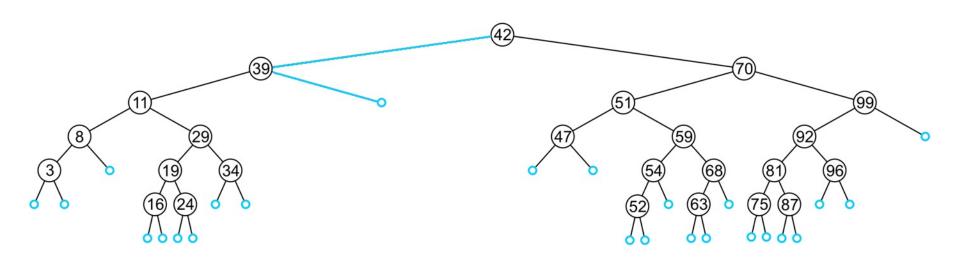
 A new leaf node is created and assigned to the member variable left







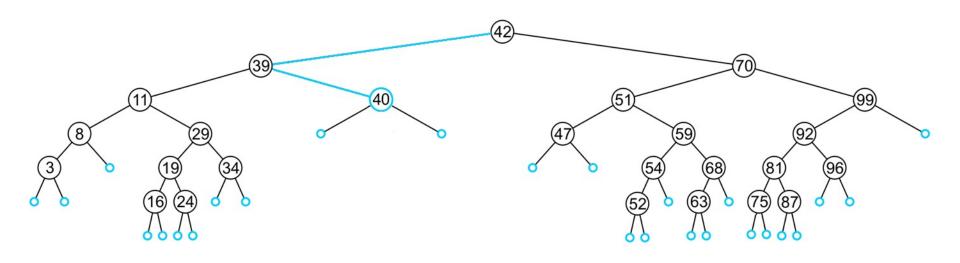
In inserting 40, we determine the right sub-tree of 39 is an empty node







 A new leaf node storing 40 is created and assigned to the member variable right







```
void insert(const T &x) { insert(x, root); }
void insert(const T &x, BinaryNode<T> *&t) {
    if (t == nullptr)
        t = new BinaryNode<T>{x, nullptr, nullptr};
    else if (x < t->value)
        insert(x, t->left);
    else if (t->value < x)
        insert(x, t->right);
    else
        ; // Duplicate; do nothing
}
```





Example questions:

 In the given order, insert these objects into an initially empty binary search tree:

```
31 45 36 14 52 42 6 21 73 47 26 37 33 8
```

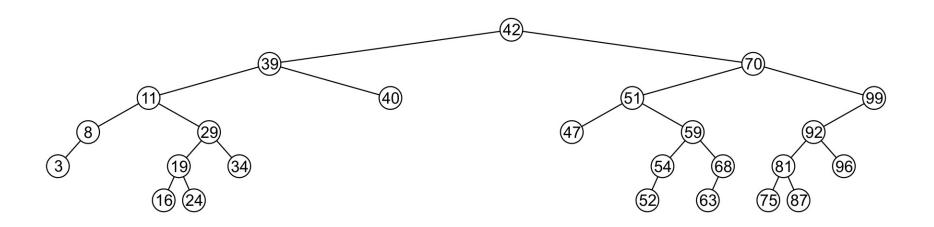
- What values could be placed:
 - To the left of 21?
 - To the right of 26?
 - To the left of 47?
- How would we determine if 40 is in this binary search tree?
- Which values could be inserted to increase the height of the tree?





Erase

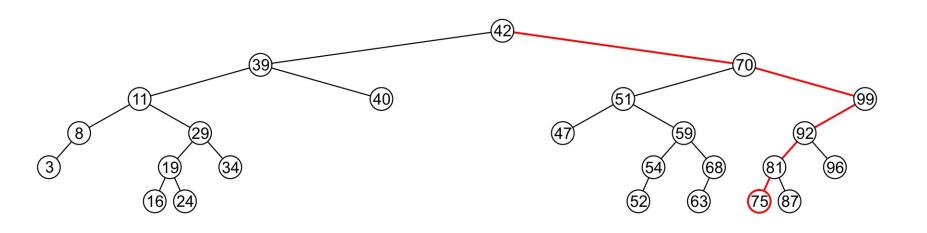
- \Box A node being erased is not always going to be a leaf node
- □ There are three possible scenarios:
 - 1) The node is a leaf node,
 - 2) It has exactly one child, or
 - 3) It has two children (it is a full node)





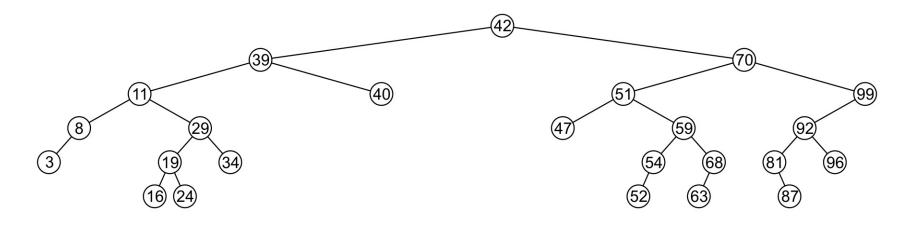


- A leaf node must be removed and the appropriate member variable of the parent is set to nullptr
 - Consider removing 75





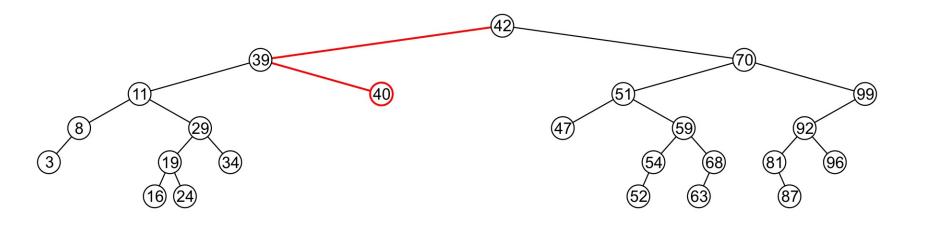
□ The node is deleted and left of 81 is set to nullptr







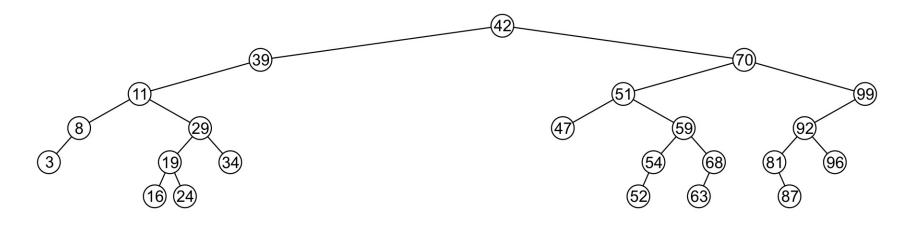
□ Erasing the node containing 40 is similar







□ The node is deleted and **right** of 39 is set to **nullptr**

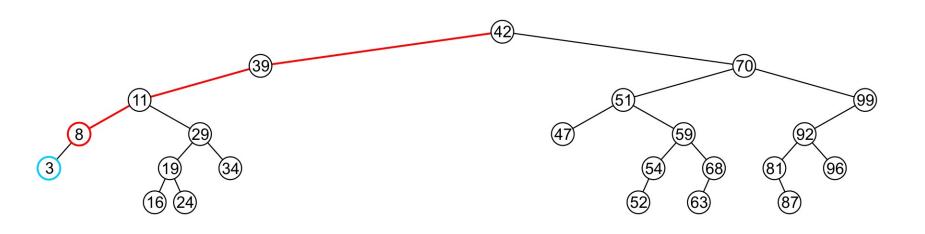






Erase: Non-leaf node w/ one child

- If a node has only one child, we can simply promote the sub-tree associated with the child
 - Consider removing 8 which has one left child

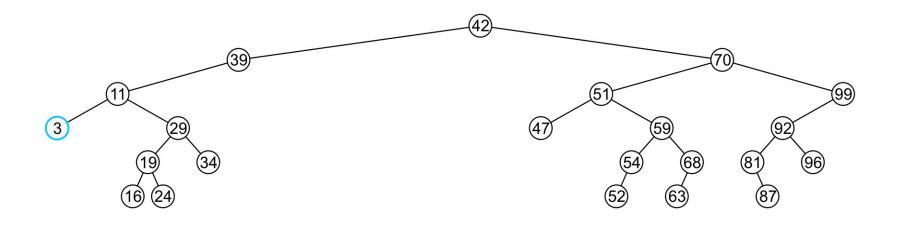






Erase: Non-leaf node w/ one child

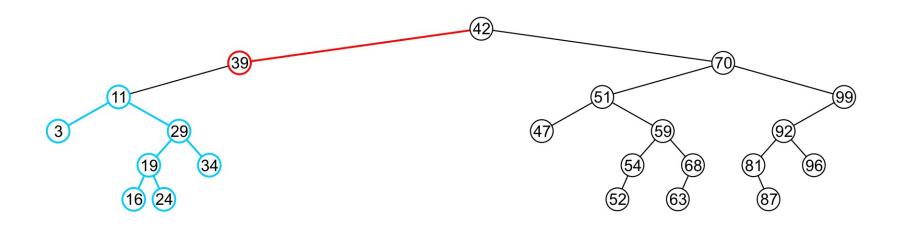
The node 8 is deleted and the left of 11 is updated to point to 3







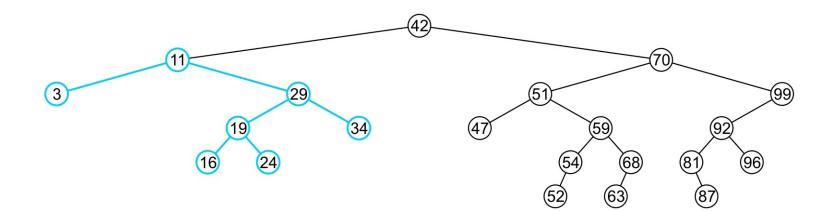
- There is no difference in promoting a single node or a sub-tree
 - To remove 39, it has a single child 11





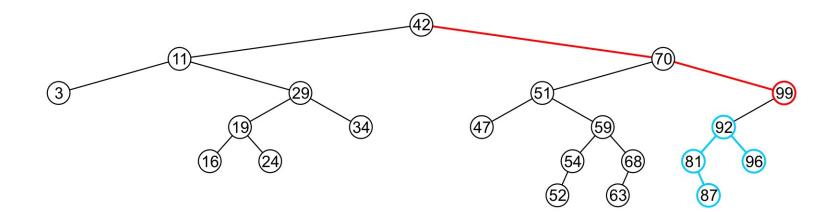


- The node containing 39 is deleted and left of 42 is updated to point to 11
 - Notice that order is still maintained





□ Consider erasing the node containing 99

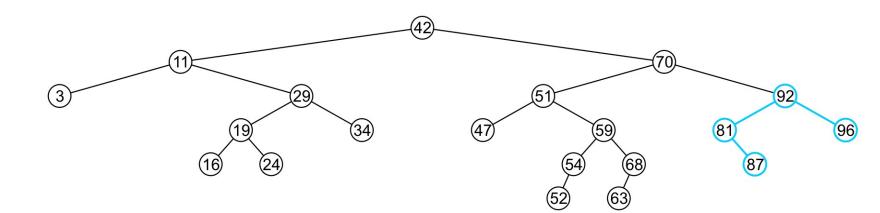






 \Box The node is deleted and the **left** sub-tree is promoted:

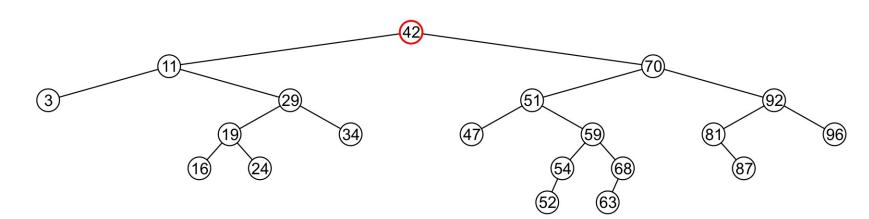
- The member variable **right** of 70 is set to point to 92
- Again, the order of the tree is maintained







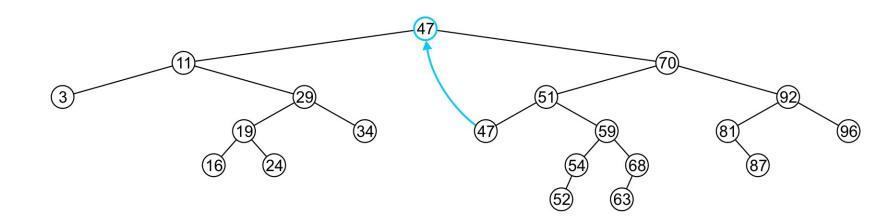
- Finally, we will consider the problem of erasing a full node, e.g., 42
- □ We will perform two operations:
 - Replace 42 with the minimum object in the right sub-tree
 - Erase that object from the right sub-tree





 \Box In this case, we replace 42 with 47

• We temporarily have two copies of 47 in the tree

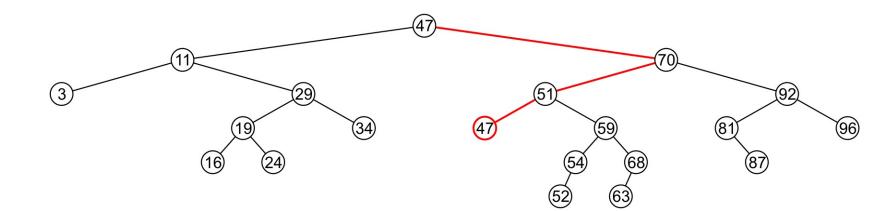






□ We now recursively erase 47 from the **right** sub-tree

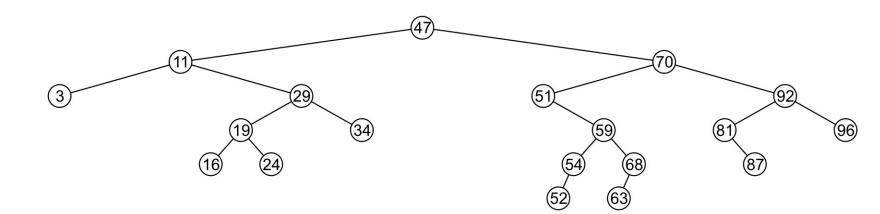
• We note that 47 is a leaf node in the right sub-tree







- Leaf nodes are simply removed and left of 51 is set to nullptr
 - Notice that the tree is still sorted

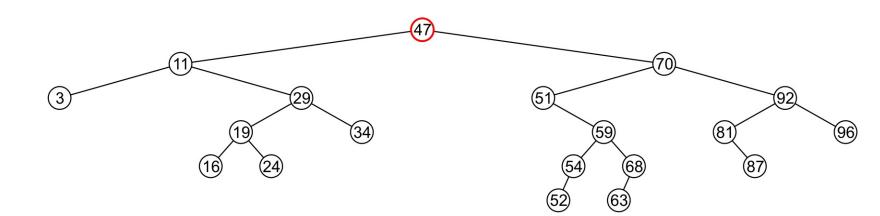






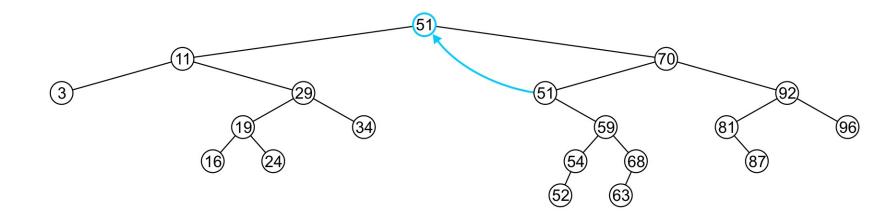
□ Suppose we want to erase the root 47 again:

- We must copy the minimum of the right sub-tree
- We could promote the maximum object in the left sub-tree and achieve similar results





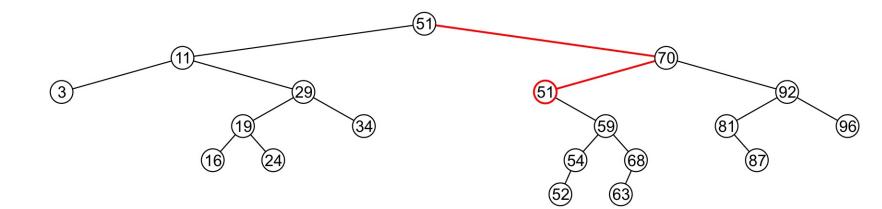
□ We copy 51 from the right sub-tree







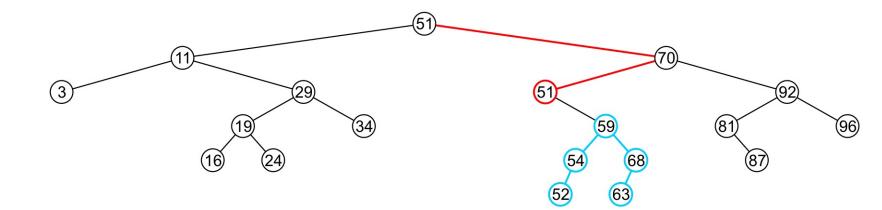
□ We must proceed by delete 51 from the right sub-tree







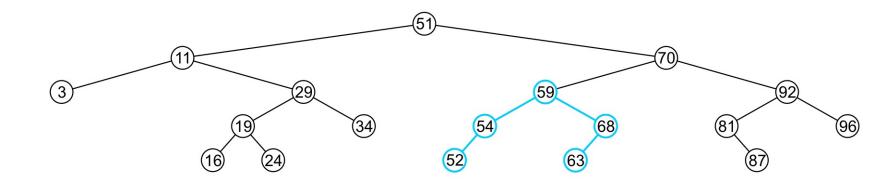
 \square In this case, the node storing 51 has just a single child







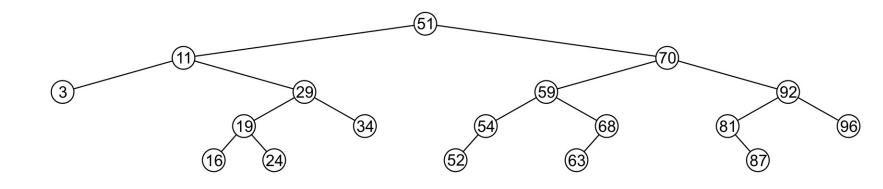
We delete the node containing 51 and assign the member variable 1eft of 70 to point to 59







 Note that after several removals, the remaining tree is still correctly sorted







```
void remove(const T &x) { remove(x, root); }
void remove(const T &x, BinaryNode<T> *&t) {
    if (t == nullptr)
        return; // Item not found; do nothing
    if (x < t->value)
        remove(x, t->left);
    else if (t->value < x)</pre>
        remove(x, t->right);
    else if (t->left != nullptr && t->right != nullptr) { // two children
            t->value = findMin(t->right)->value;
            remove(t->value, t->right);
    }
    else { // single child
        BinaryNode<T> *oldNode = t;
        t = (t->left != nullptr) ? t->left : t->right;
        delete oldNode;
    }
}
```



Other Relation-based Operations

- We will quickly consider two other relation-based queries that are very quick to calculate with an array of sorted objects:
 - Finding the previous and next values, and
 - Finding the *k*th value



- All the operations up to now have been operations which work on any container: count, insert, etc.
 - If these are the only relevant operations, use a *hash table*

Operations specific to linearly ordered data include:

- Find the next larger and previous smaller objects of a given object which may or may not be in the container
- Find the *k*th value of the container
- Iterate through those objects that fall on an interval [a, b]

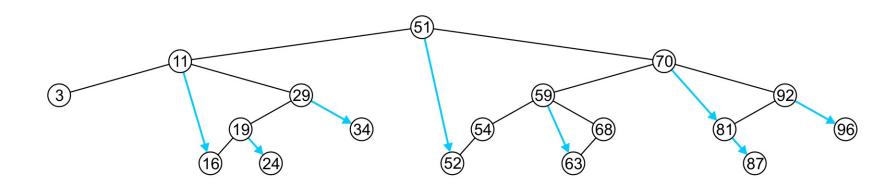
 $\hfill\square$ We will focus on finding the next largest object

The others will follow



□ To find the next largest object:

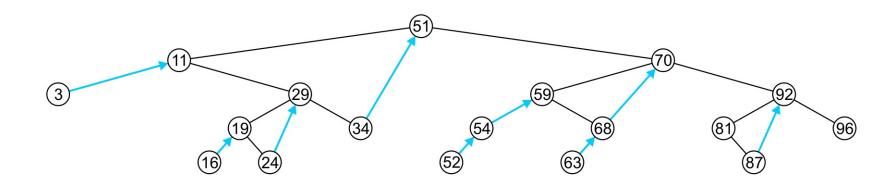
 If the node has a right sub-tree, the minimum object in that subtree is the next-largest object





□ If, however, there is no right sub-tree:

 It is the next largest object (if any) that exists in the path from the root to the node



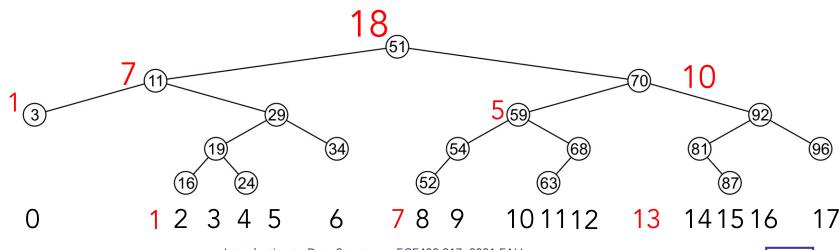


- More generally: what is the next largest value of an arbitrary object?
 - This can be found with a single search from the root node to one of the leaves — an O(h) operation
 - This function returns the object if it did not find something greater than it



Finding the *k*th Object

- Another operation on sorted lists may be finding the kth largest object
 - Recall that *k* goes from 0 to *n* 1
 - If the left-sub-tree has $\ell = k$ values, return the current node,
 - If the left sub-tree has l > k values, return the kth value of the left sub-tree,
 - Otherwise, the left sub-tree has $\ell < k$ values, so return the $(k \ell 1)^{\text{th}}$ value of the right sub-tree







Run Time: O(h)

- Almost all of the relevant operations on a binary search tree are O(h)
 - If the tree is close to a linked list, the run times is O(n)
 - Insert 1, 2, 3, 4, 5, 6, 7, ..., *n* into a empty binary search tree
 - The best we can do is if the tree is perfect: O(ln(n))
 - Our goal will be to find tree structures where we can maintain a height of Θ(ln(n))
- We will look at
 - AVL trees
 - B+ trees

both of which ensure that the height remains $\Theta(\ln(n))$





Summary

□ In this topic, we covered binary search trees

- Described Abstract Sorted Lists
- Problems using arrays and linked lists
- Definition a binary search tree
- Looked at the implementation of:
 - Empty, size, height, count
 - FindMin, FindMax, insert, erase
 - Previous smaller and next larger objects







Kyunghan Lee Networked Computing Lab (NXC Lab) Department of Electrical and Computer Engineering Seoul National University https://nxc.snu.ac.kr kyunghanlee@snu.ac.kr







Outline

- Background
- Define height balancing
- Maintaining balance within a tree
 - AVL trees
 - Difference of heights
 - Maintaining balance after insertions and erases
 - Can we store AVL trees as arrays?





Background

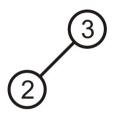
□ From previous lectures:

- Binary search trees store linearly ordered data
- Best case height: Θ(ln(n))
- Worst case height: O(n)
- Requirement:
 - Define and maintain a *balance* to ensure $\Theta(\ln(n))$ height





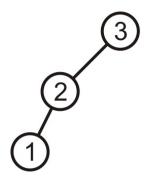
 These two examples demonstrate how we can correct for imbalances: starting with this tree, add 1:







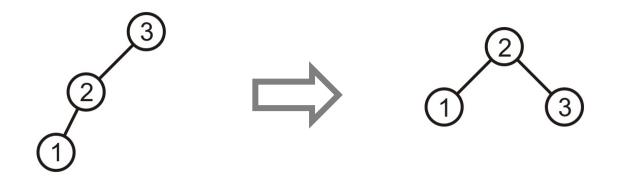
□ This is more like a linked list; however, we can fix this...







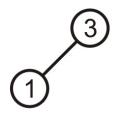
- Promote 2 to the root, demote 3 to be 2's right child, and 1 remains the left child of 2.
- □ The result is a perfect, though trivial tree







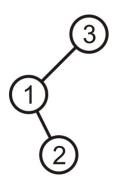
□ Alternatively, given this tree, insert 2







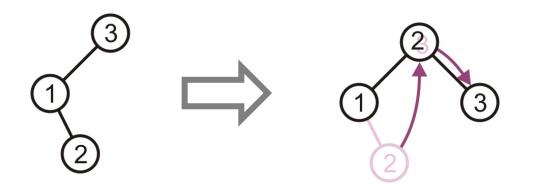
 Again, the product is a linked list; however, we can fix this, too







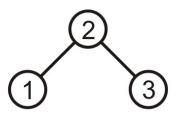
 Promote 2 to the root, and assign 1 and 3 to be its children







 \Box The result is, again, a perfect tree



 These examples may seem trivial, but they are the basis for the corrections in the next data structure we will see: AVL trees





□ We will focus on the first strategy: AVL trees

- Named after Adelson-Velsky and Landis
- Balance is defined by comparing the height of the two sub-trees
- \square Recall:
 - An empty tree has height –1
 - A tree with a single node has height 0





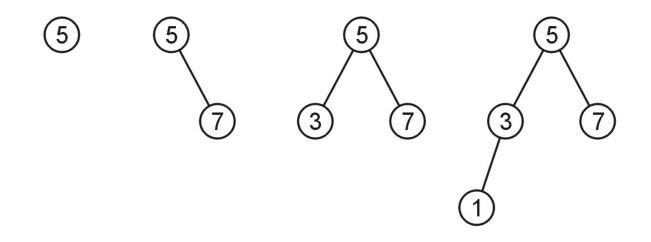
 \Box A binary search tree is said to be AVL balanced if:

- The difference in the heights between the left and right subtrees is at most 1, and
- Both sub-trees are themselves AVL trees





□ AVL trees with 1, 2, 3, and 4 nodes:

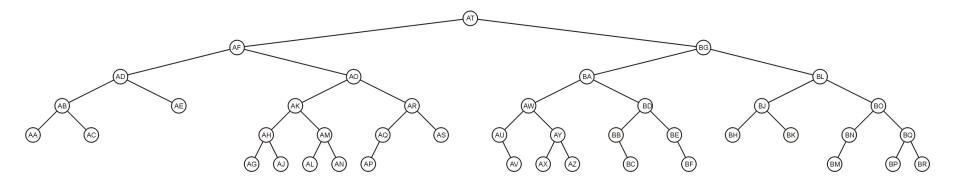






AVL Trees

□ Here is a larger AVL tree (42 nodes):



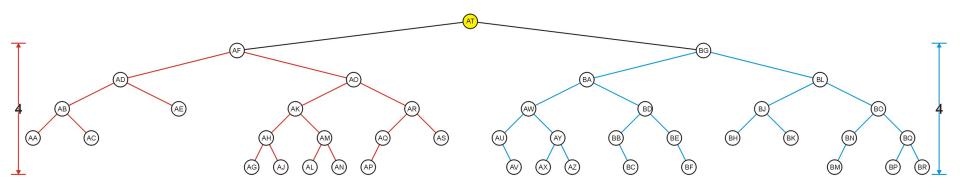




AVL Trees

□ The root node is AVL-balanced:

• Both sub-trees are of height 4:



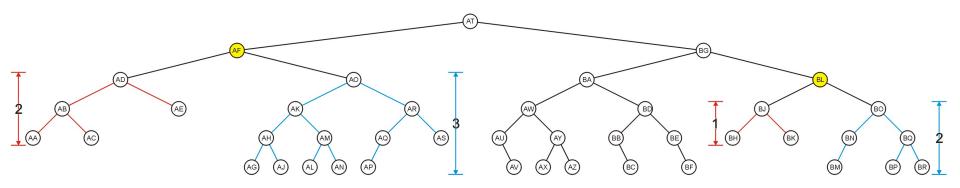




AVL Trees

 \Box All other nodes (e.g., AF and BL) are AVL balanced

The sub-trees differ in height by at most one





- By the definition of complete trees, any complete binary search tree is an AVL tree
- Thus an upper bound on the number of nodes in an AVL tree of height h is a perfect binary tree with 2^{h + 1} 1 nodes
 - What is an lower bound?
 - This will be the worst case of an AVL tree





 Let F(h) be the fewest number of nodes in a tree of height h



 \Box Can we find F(*h*)?



 \Box The worst-case AVL tree of height *h* would have:

- A worst-case AVL tree of height h 1 on one side,
- A worst-case AVL tree of height h 2 on the other, and
- The root node

□ We get: F(h) = F(h - 1) + 1 + F(h - 2)





□ This is a recurrence relation:

$$F(h) = \begin{cases} 1 & h = 0 \\ 2 & h = 1 \\ F(h-1) + F(h-2) + 1 & h > 1 \end{cases}$$

- □ The solution?
 - Note that F(h) + 1 = (F(h 1) + 1) + (F(h 2) + 1)
 - Therefore, F(h) + 1 is a Fibonacci number:

$$F(0) + 1 = 2$$
 \rightarrow $F(0) = 1$ $F(1) + 1 = 3$ \rightarrow $F(1) = 2$ $F(2) + 1 = 5$ \rightarrow $F(2) = 4$ $F(3) + 1 = 8$ \rightarrow $F(3) = 7$ $F(4) + 1 = 13$ \rightarrow $F(4) = 12$ $F(5) + 1 = 21$ \rightarrow $F(5) = 20$ $F(6) + 1 = 34$ \rightarrow $F(6) = 33$





□ This is approximately

$$F(h) \approx 1.8944 \ \phi^h - 1$$

where $\phi \approx 1.6180$ is the golden ratio

- That is, $F(h) = \Omega(\phi^h)$
- Check more: <u>https://en.wikipedia.org/wiki/Golden ratio#Relationship to Fibonacci sequence</u>

Thus, we may find the maximum value of h for a given n:

$$\log_{\phi}\left(\frac{n+1}{1.8944}\right) = \log_{\phi}\left(n+1\right) - 1.3277 = 1.4404 \cdot \lg(n+1) - 1.3277$$



1

Height of an AVL Tree: Easier Proof?

F(h) > F(h-1) + F(h-2) > 2F(h-2)

$$F(h) > 2 * F(h-2) > 2 * 2 * F(h-4) > ... > 2^{h/2}$$

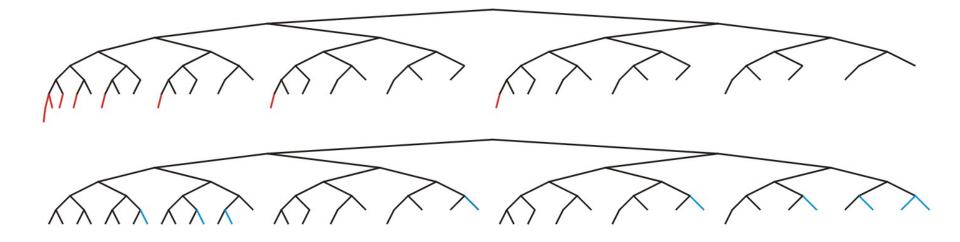
 $n > 2^{h/2}$, so $h < 2 \log(n)$





Height of an AVL Tree: Looking Good?

□ In this example, n = 88, the worst- and best-case scenarios differ in height by only 2







Height of an AVL Tree: Looking Bad?

- \square If $n = 10^6$, the bounds on h are:
 - (best) The minimum height:
 - (worst) The maximum height :

 $\log_2(10^6) - 1 \approx 19$

 $\log_{\phi}(10^{6} / 1.8944) < 28$

The AVL Tree ensures the height balance, but such a balanced tree can be quite far from the ideal, perfect binary tree.



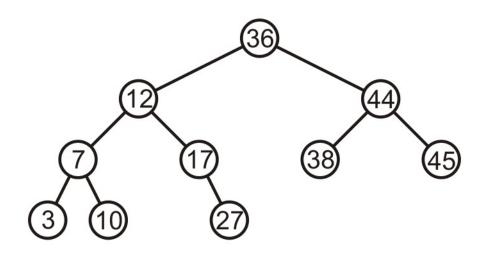


- □ To maintain AVL balance, observe that:
 - Inserting a node can increase the height of a tree by at most 1
 - Removing a node can decrease the height of a tree by at most 1





□ Consider this AVL tree



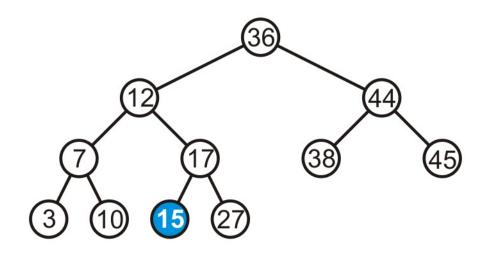




Maintaining Balance: Insert 15

□ Consider inserting 15 into this tree

In this case, the heights of none of the trees change

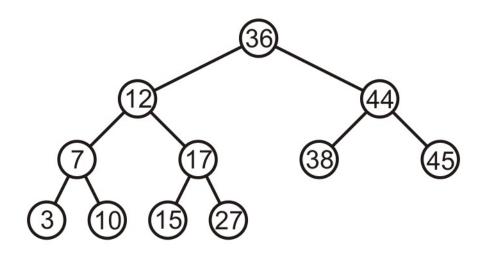






Maintaining Balance: Insert 15

□ The tree remains balanced



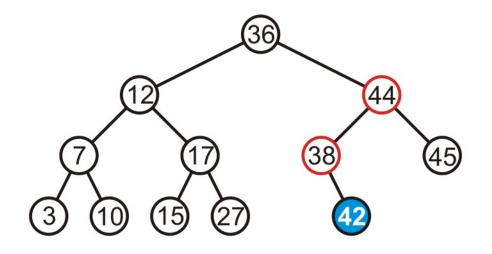




Maintaining Balance: Insert 42

□ Consider inserting 42 into this tree

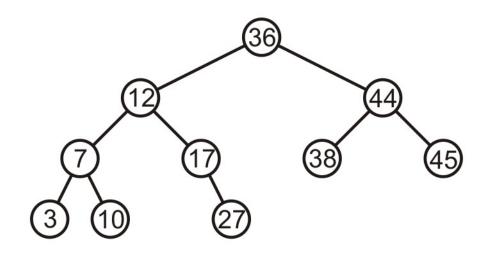
- Now we see the heights of two sub-trees have increased by one
- The tree is still balanced







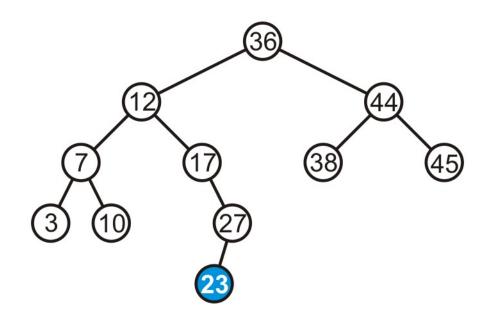
- If a tree is AVL balanced, for an insertion to cause an imbalance:
 - The heights of the sub-trees must differ by 1
 - The insertion must increase the height of the deeper sub-tree by 1







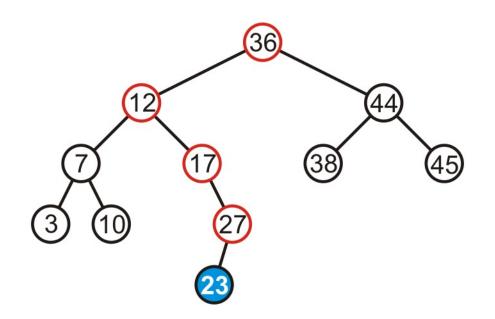
□ Suppose we insert 23 into our initial tree







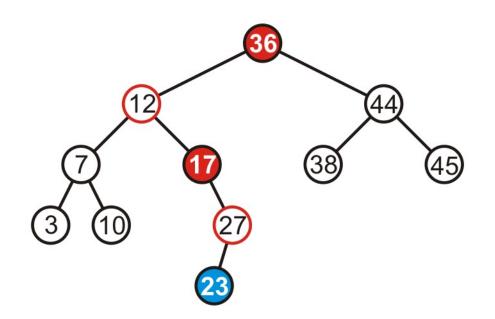
The heights of each of the sub-trees from here to the root are increased by one







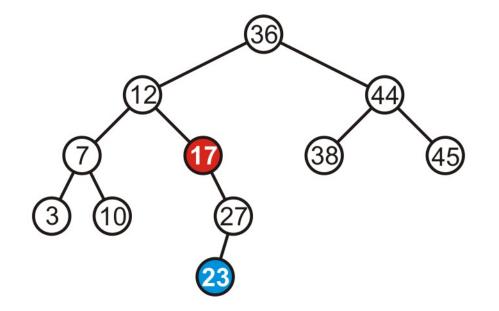
However, only two of the nodes are unbalanced:
 17 and 36







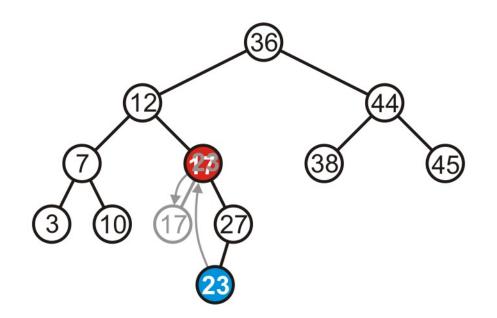
- However, only two of the nodes are unbalanced:
 17 and 36
 - We only have to fix the imbalance at the lowest node







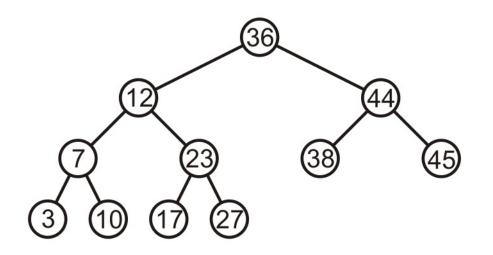
 We can promote 23 to where 17 is, and make 17 the left child of 23





□ Thus, that node is no longer unbalanced

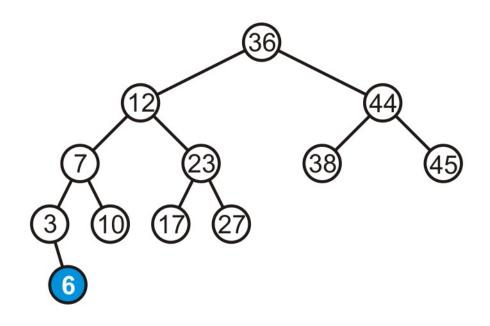
Incidentally, the root node is now balanced as well







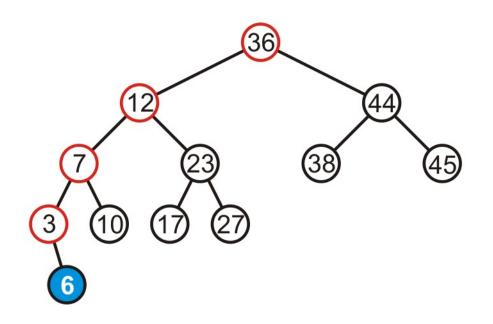
□ Consider adding 6:







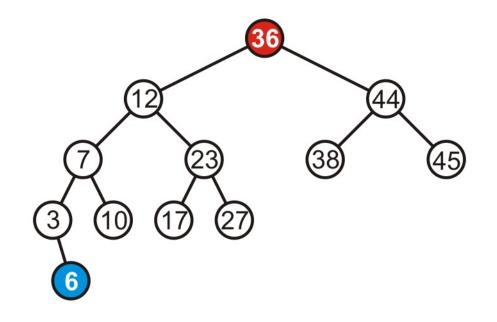
The height of each of the trees in the path back to the root are increased by one







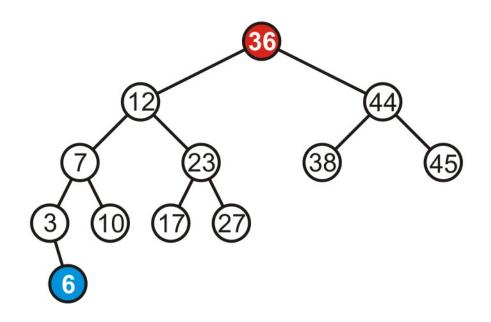
- The height of each of the trees in the path back to the root are increased by one
 - However, only the root node is now unbalanced







□ To fix this, we will look at the general case...

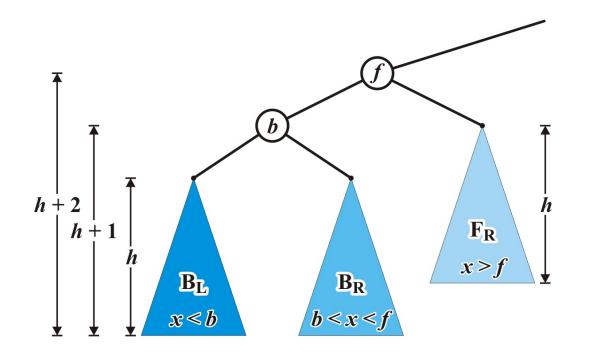






Consider the following setup

• Each blue triangle represents a tree of height *h*

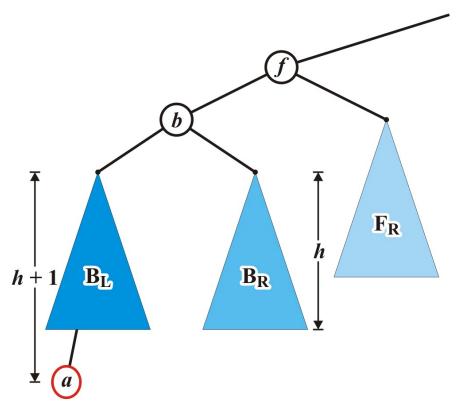






 \square Insert *a* into this tree: it falls into the left subtree B_L of *b*

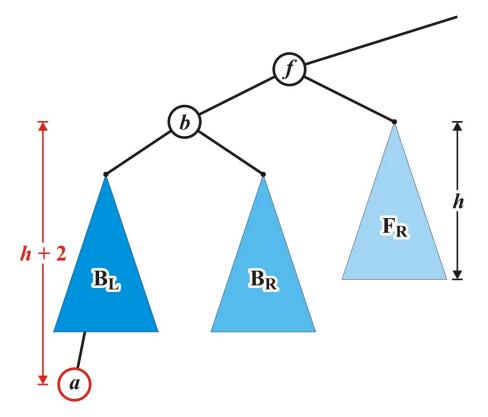
- Assume B_L remains balanced
- Thus, the tree rooted at b is also balanced





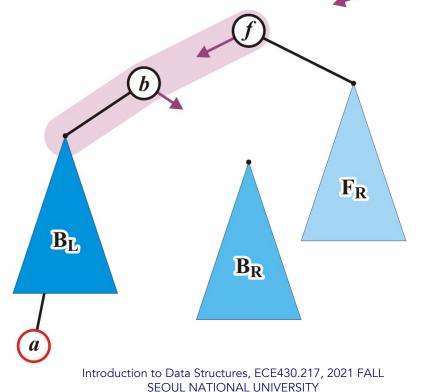


- \Box The tree rooted at node f is now unbalanced
 - We will correct the imbalance at this node



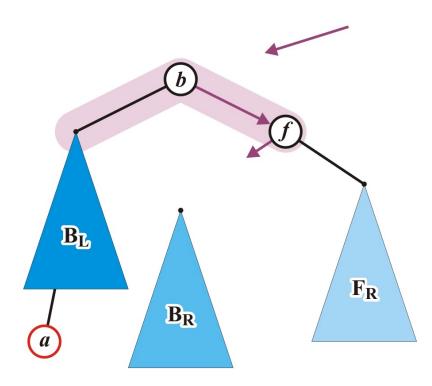


- Specifically, we will rotate these two nodes around the root:
 - Recall the first prototypical example
 - Promote node b to the root and demote node f to be the right child of b



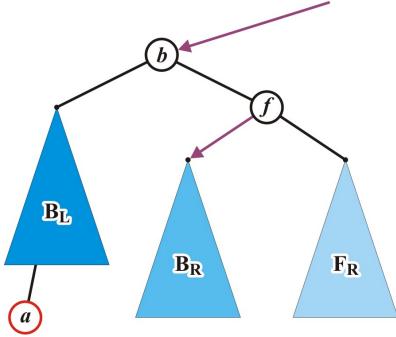


This requires the address of node *f* to be assigned to the p_right_tree member variable of node *b*





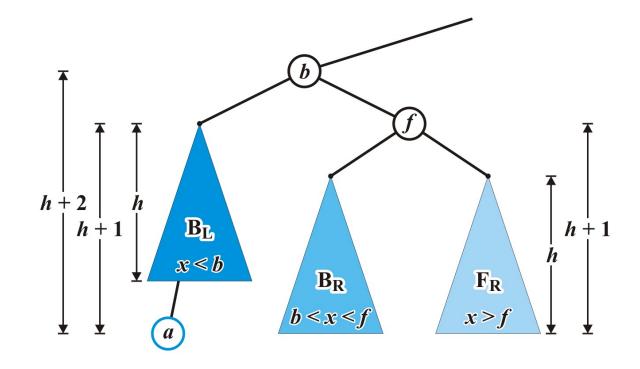
- Assign any former parent of node *f* to the address of node *b*
- Assign the address of the tree B_R to p_left_tree of node f





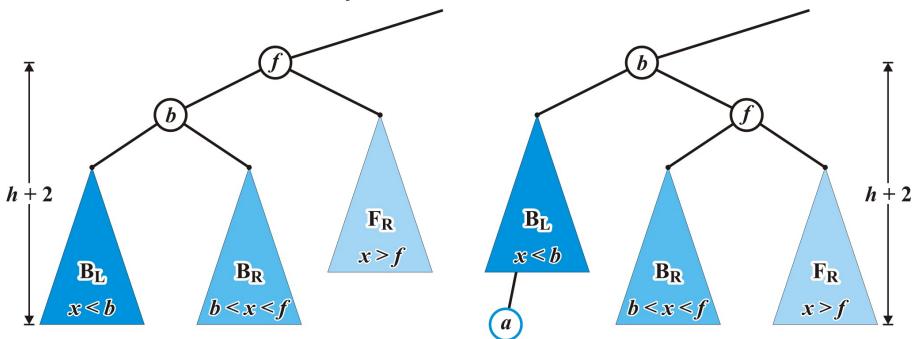


- The nodes b and f are now balanced and all remaining nodes of the subtrees are in their correct positions
 - The height of f is now h + 1 while b remains at height h + 2





- Additionally, height of the corrected tree rooted at b equals the original height of the tree rooted at f
 - Thus, this insertion will no longer affect the balance of any ancestors all the way back to the root

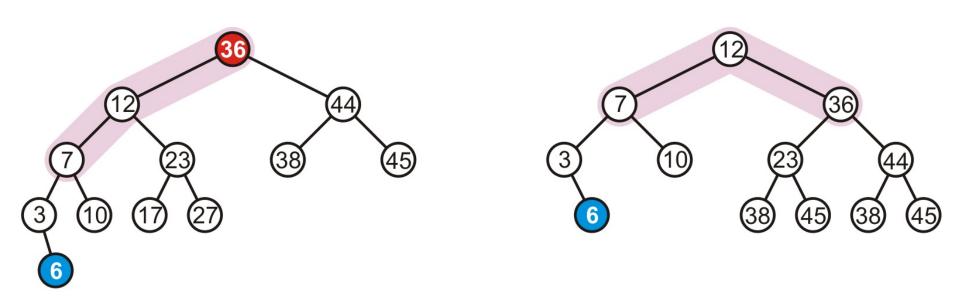








□ In our example case, the correction

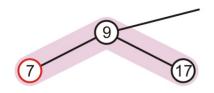


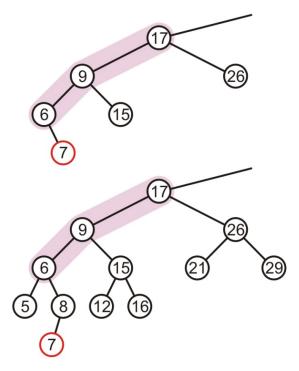


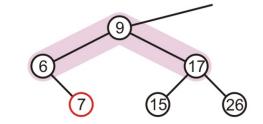
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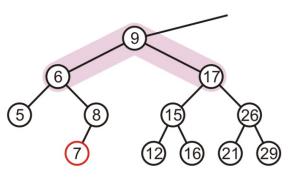


 In our three sample cases, the node is now balanced and the same height as the tree before the insertion





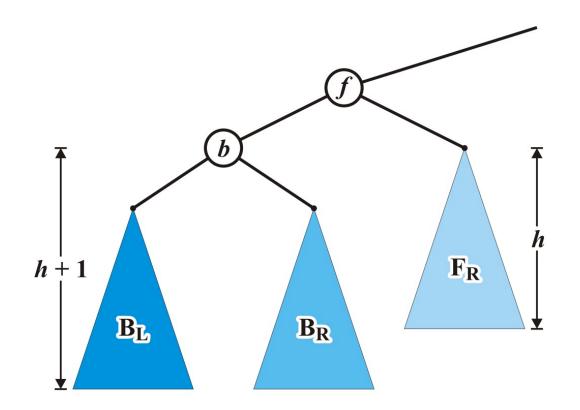






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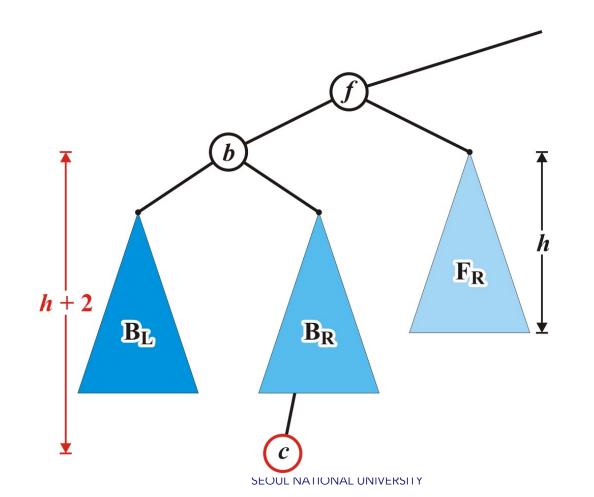
Alternatively, consider the insertion of c where b < c < f into our original tree





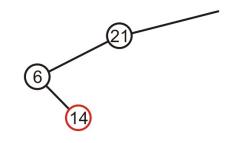


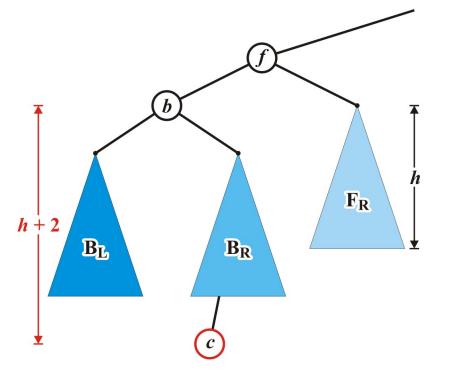
- \square Assume that the insertion of *c* increases the height of **B**_R
 - Once again, f becomes unbalanced

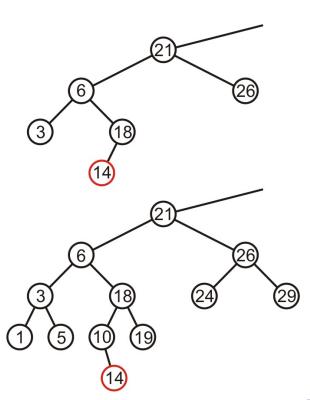




□ Here are examples of when the insertion of 14 may cause this situation when h = -1, 0, and 1





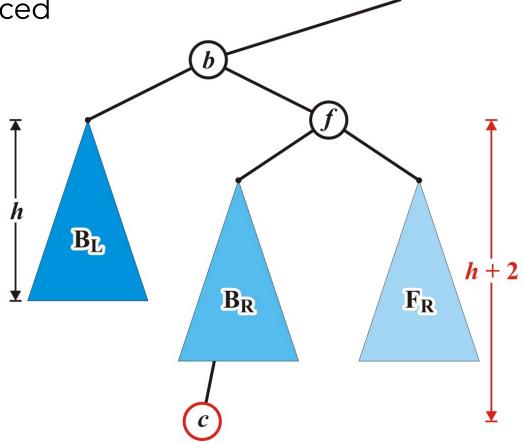




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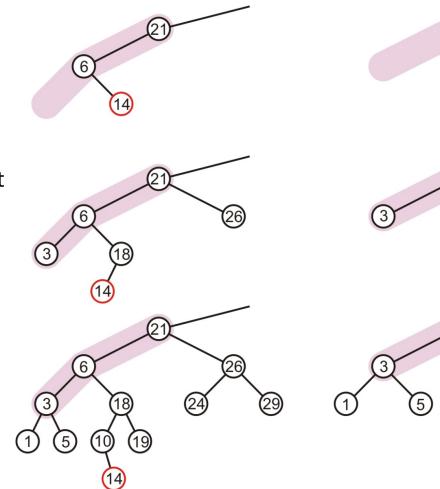


 Unfortunately, the previous correction does not fix the imbalance at the root of this sub-tree: the new root, b, remains unbalanced





- In our three sample cases with h = -1, 0, and 1, doing the same thing as before results in a tree that is still unbalanced...
 - The imbalance is just shifted to the other side







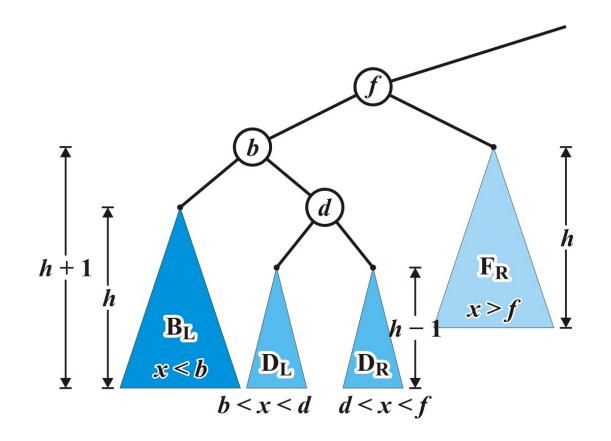
6

6



(19)

□ Re-label the tree by dividing the left subtree of f into a tree rooted at d with two subtrees of height h - 1

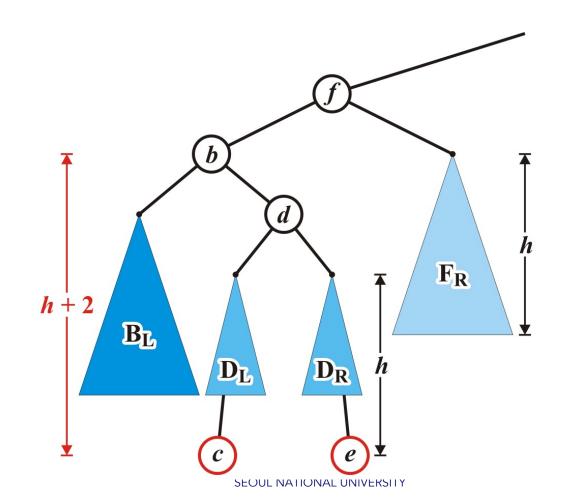






 \Box Now an insertion causes an imbalance at f

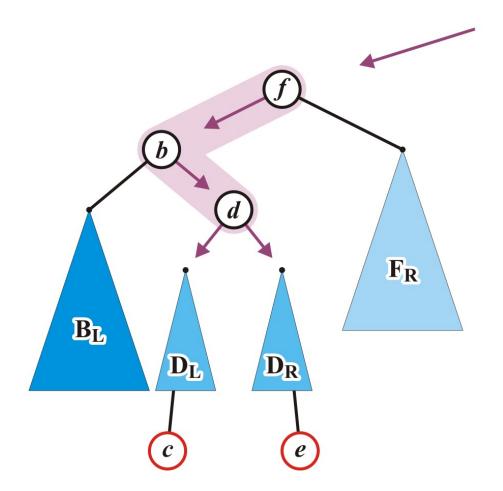
• The addition of either *c* or *e* will cause this





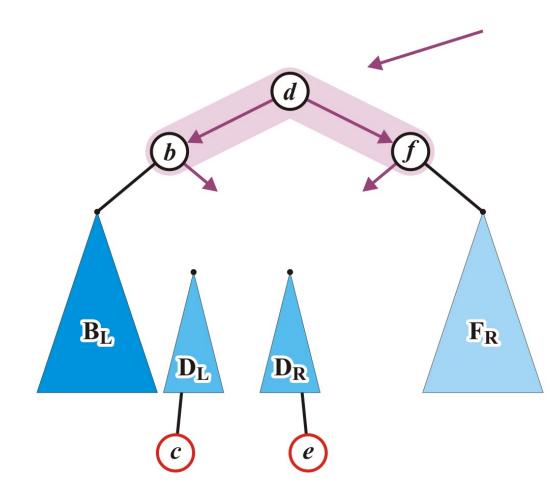


 \square We will rotate *d*, *b*, and *f*





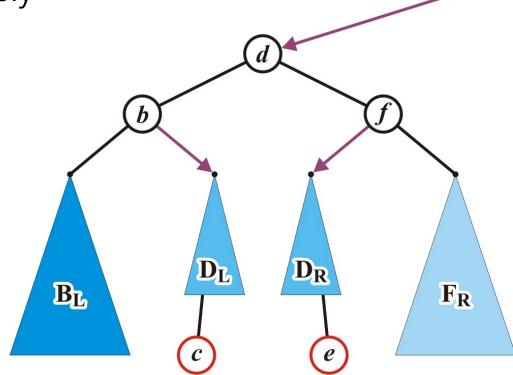
 \Box We will first rotate d, b, and f







 $\hfill\square$ Then connect D_L and D_R as a subtree of b and f, respectively

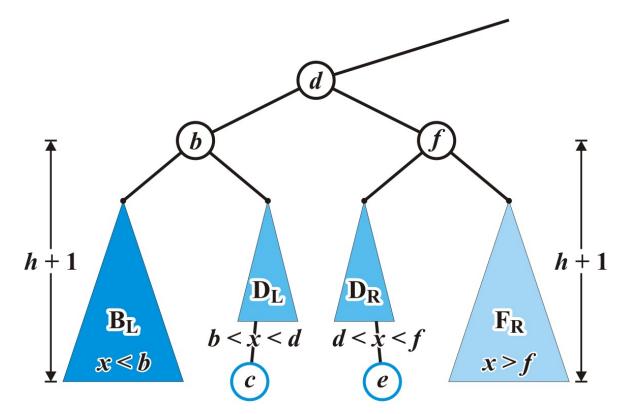






 \Box Now the tree rooted at **d** is balanced

• After the correction, height of **b** and **f** become h + 1 and **d** is h + 2

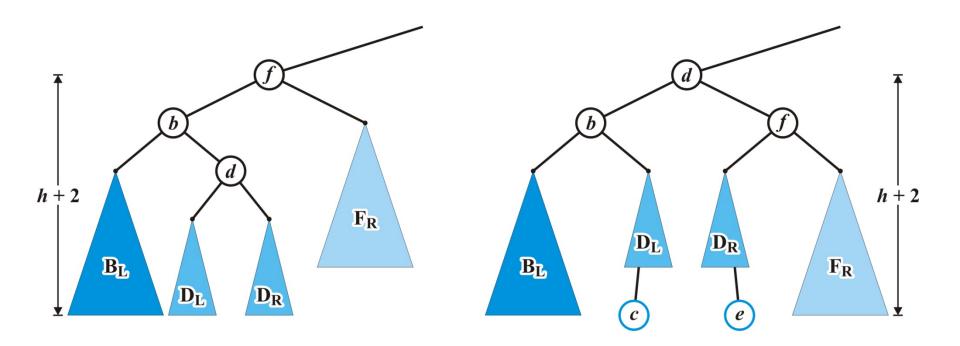






□ Again, the height of the root did not change

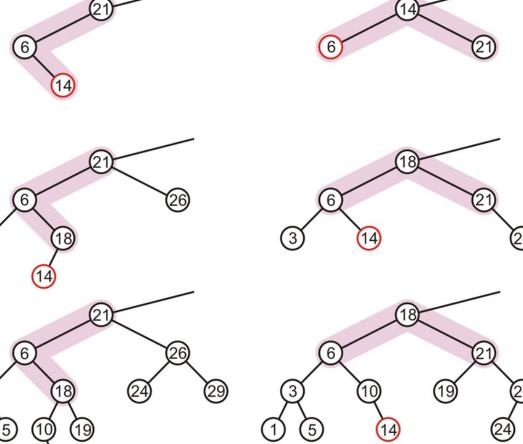
• The heights of all three nodes changed in this process







In our three sample cases with h = -1, 0, and 1, the node is now balanced and the same height as the tree before the insertion



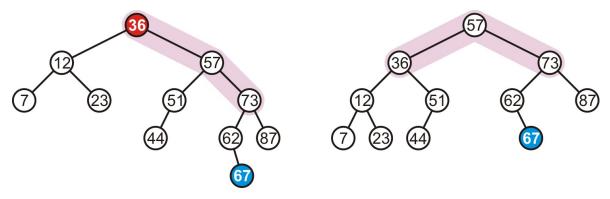


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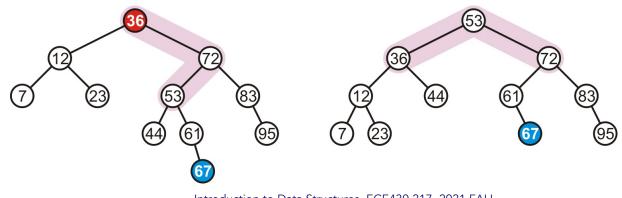


Maintaining balance: Summary

- There are two symmetric cases to those we have examined:
 - Insertions into the right-right sub-tree (Case 1)



Insertions into either the right-left sub-tree (Case 2)





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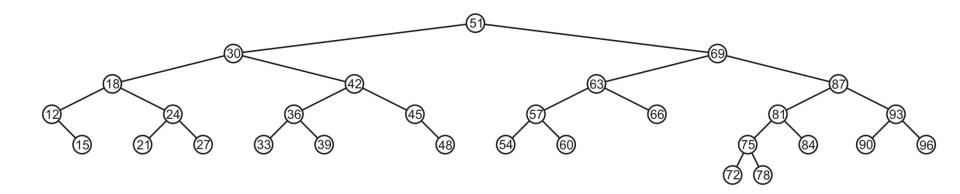


Time Complexity of Insertion

- □ Both balances (i.e., Case 1 and Case 2) are $\Theta(1)$
- □ All insertions are still $\Theta(\ln(n))$ Why?



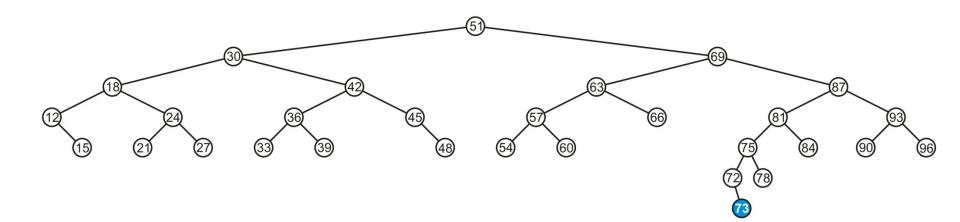
□ Consider this AVL tree







□ Insert 73



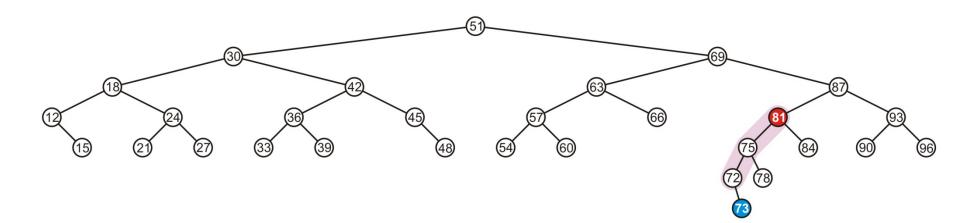


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□ The node 81 is unbalanced

A left-left imbalance

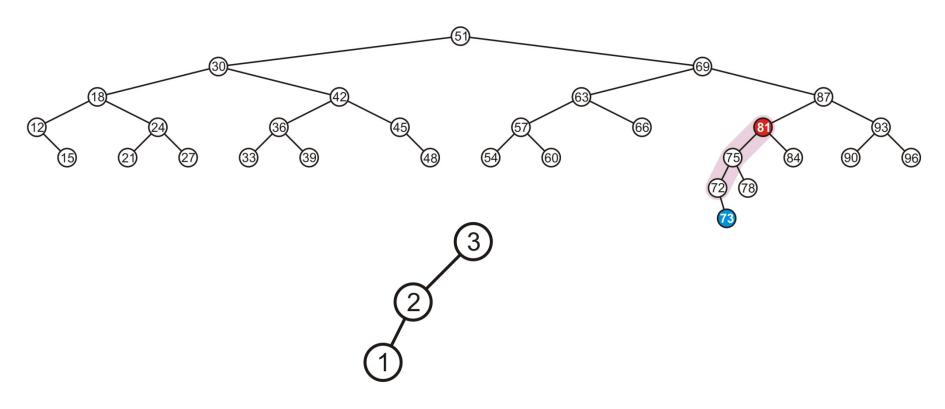






$\hfill\square$ The node 81 is unbalanced

A left-left imbalance

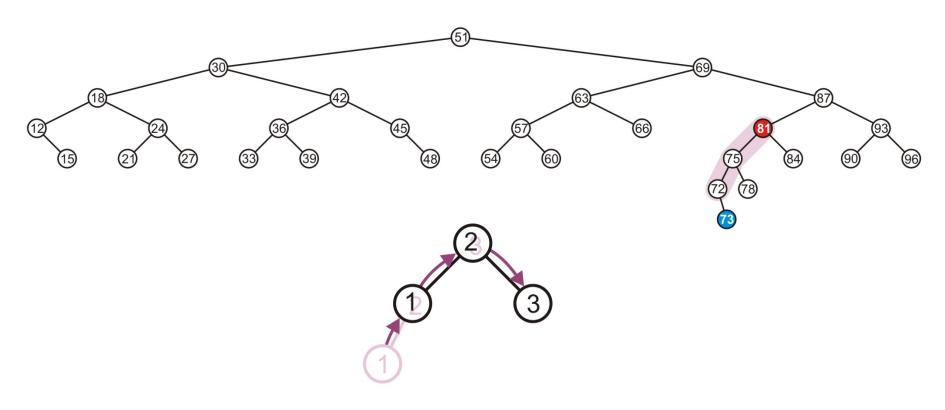






□ The node 81 is unbalanced

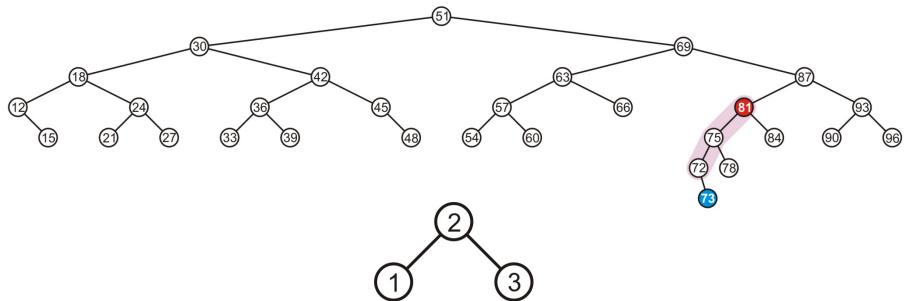
- A left-left imbalance
- Promote the intermediate node to the imbalanced node







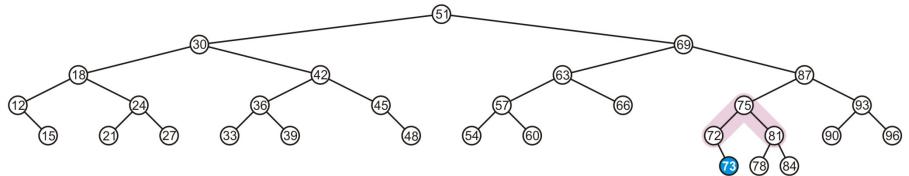
- The node 81 is unbalanced
 - A left-left imbalance
 - Promote the intermediate node to the imbalanced node
 - 75 is that node







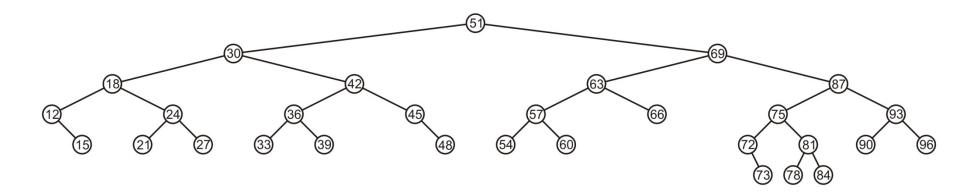
- The node 81 is unbalanced
 - A left-left imbalance
 - Promote the intermediate node to the imbalanced node
 - 75 is that node





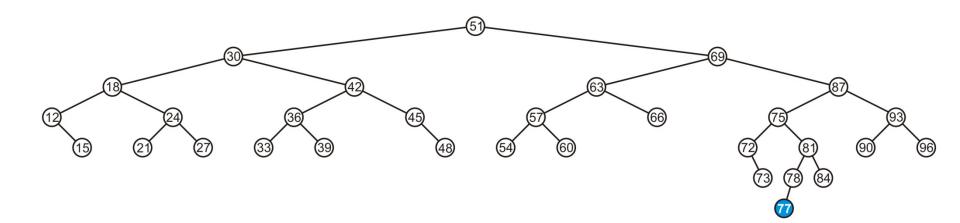


$\hfill\square$ The tree is AVL balanced





□ Insert 77



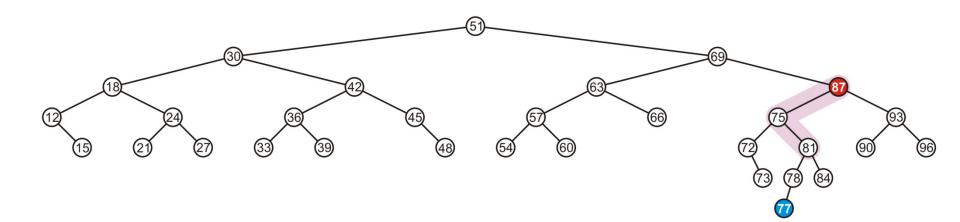


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$\hfill\square$ The node 87 is unbalanced

• A left-right imbalance

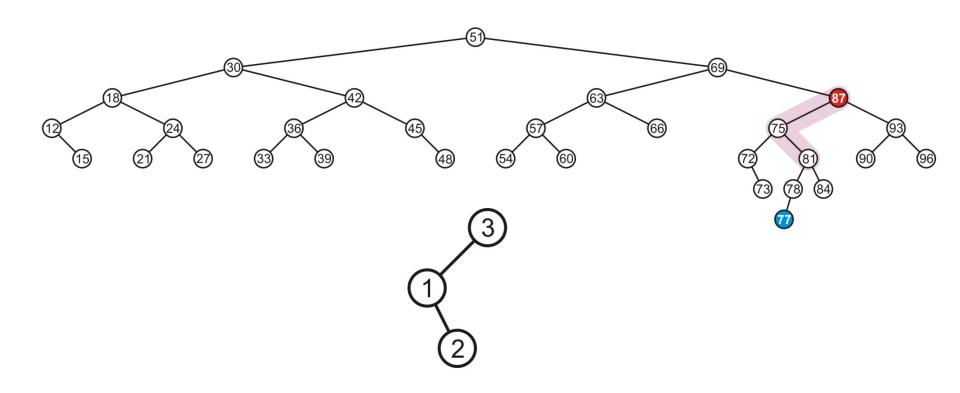






$\hfill\square$ The node 87 is unbalanced

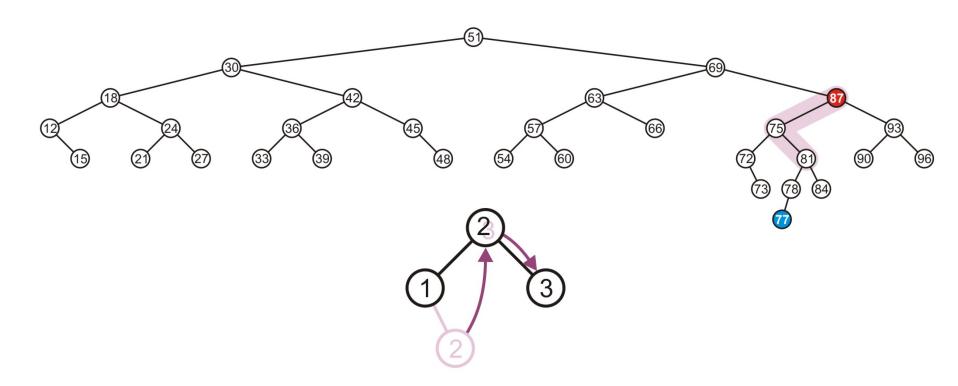
• A left-right imbalance







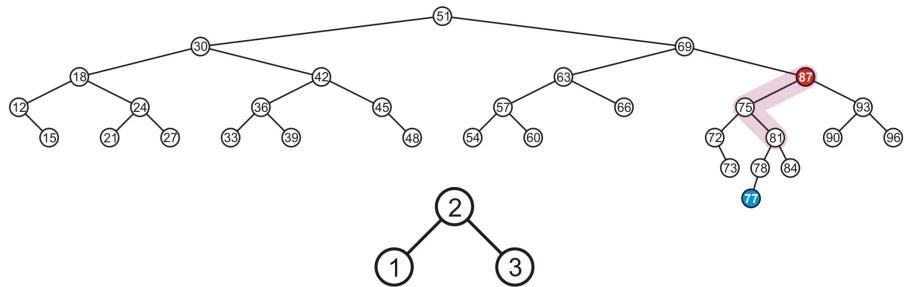
- □ The node 87 is unbalanced
 - A left-right imbalance
 - Promote the intermediate node to the imbalanced node







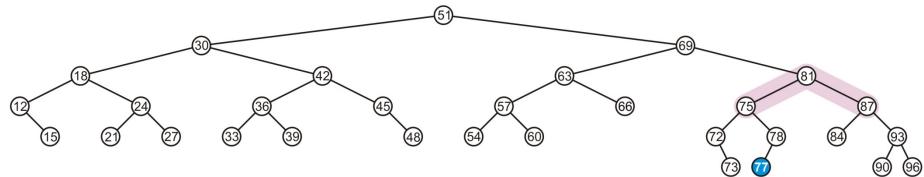
- □ The node 87 is unbalanced
 - A left-right imbalance
 - Promote the intermediate node to the imbalanced node
 - 81 is that value







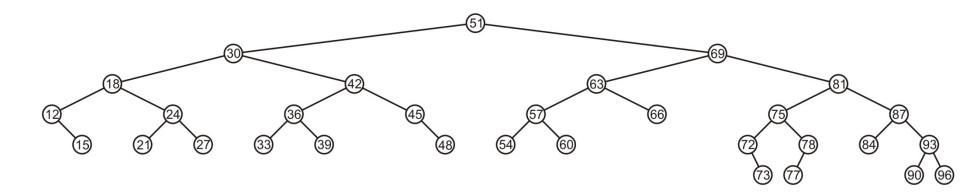
- The node 87 is unbalanced
 - A left-right imbalance
 - Promote the intermediate node to the imbalanced node
 - 81 is that value







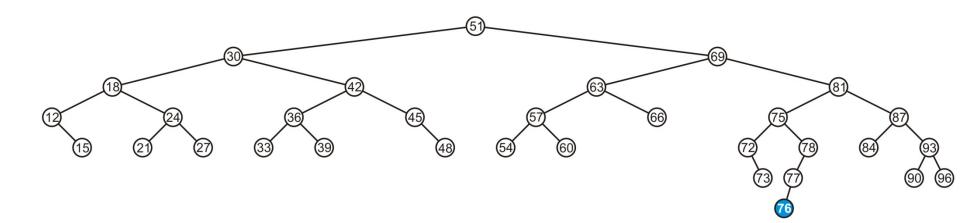
$\hfill\square$ The tree is balanced







□ Insert 76

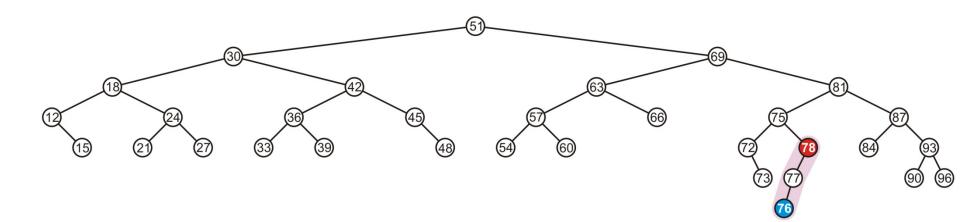






$\hfill\square$ The node 78 is unbalanced

A left-left imbalance

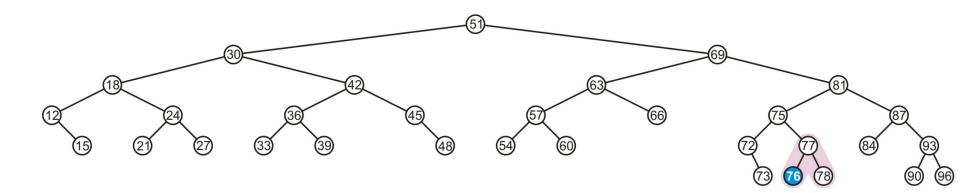






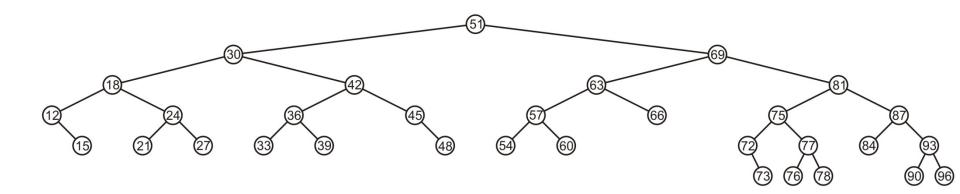
$\hfill\square$ The node 78 is unbalanced

Promote 77



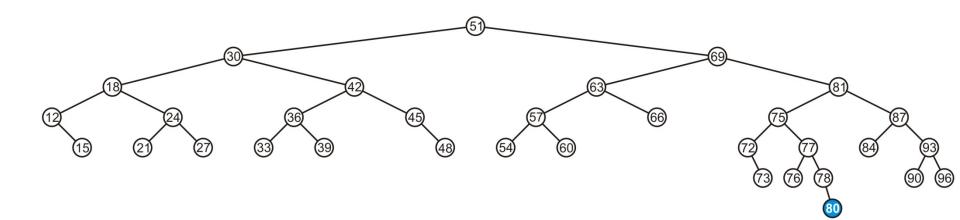


□ Again, balanced





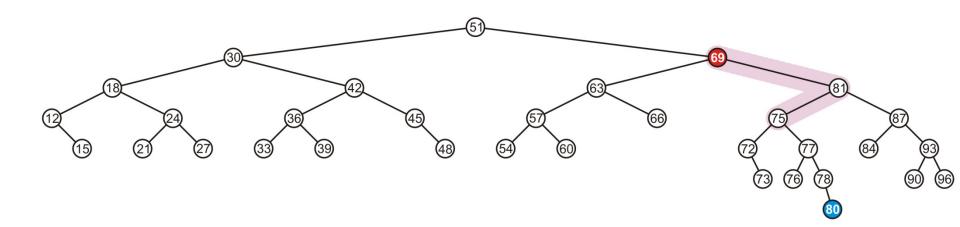
□ Insert 80







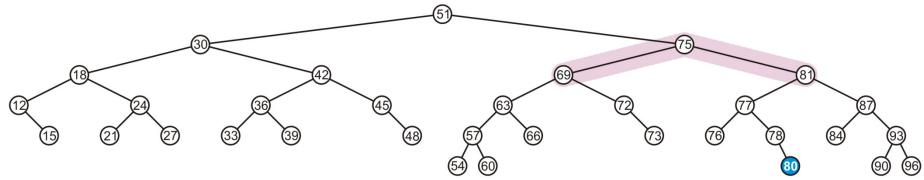
- □ The node 69 is unbalanced
 - A right-left imbalance
 - Promote the intermediate node to the imbalanced node







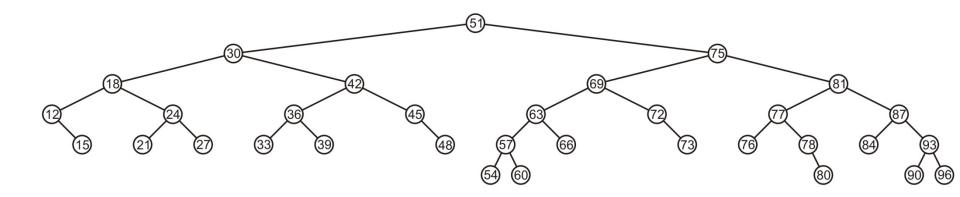
- □ The node 69 is unbalanced
 - A right-left imbalance
 - Promote the intermediate node to the imbalanced node
 - 75 is that value





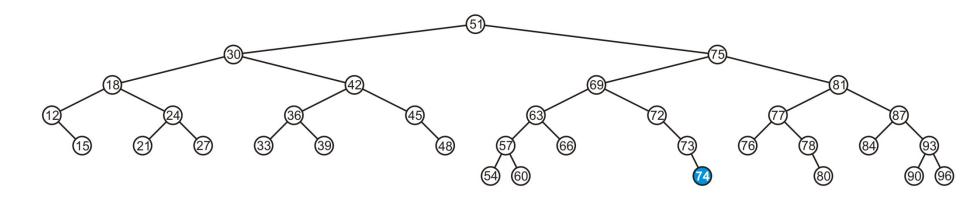


□ Again, balanced





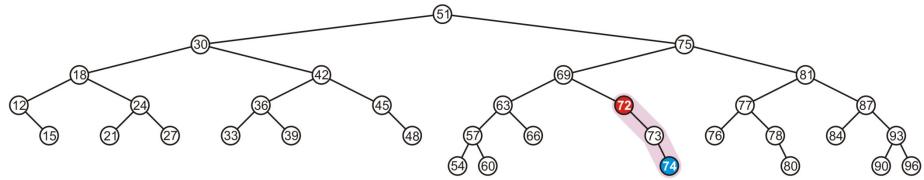
□ Insert 74







- □ The node 72 is unbalanced
 - A right-right imbalance
 - Promote the intermediate node to the imbalanced node
 - 73 is that value

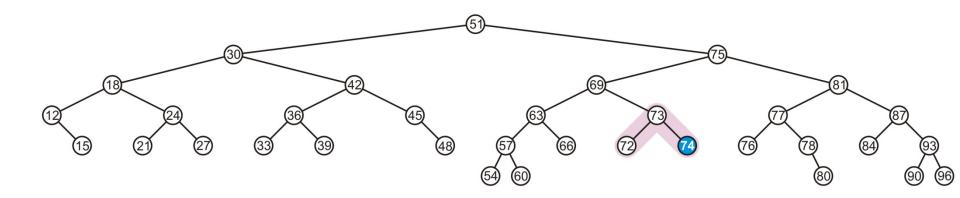






□ The node 72 is unbalanced

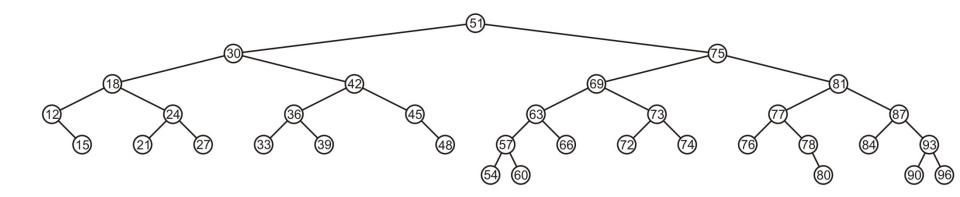
- A right-right imbalance
- Promote the intermediate node to the imbalanced node







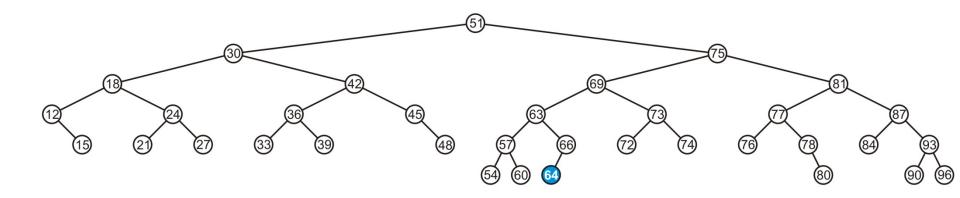
□ Again, balanced







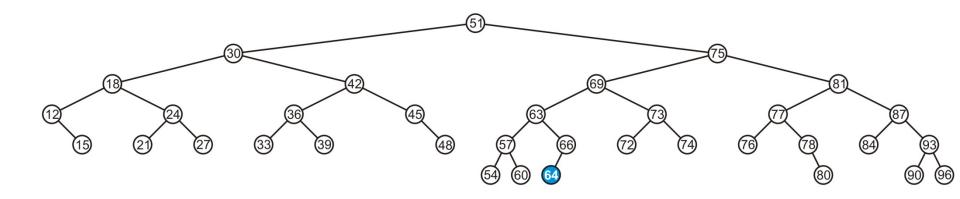
□ Insert 64







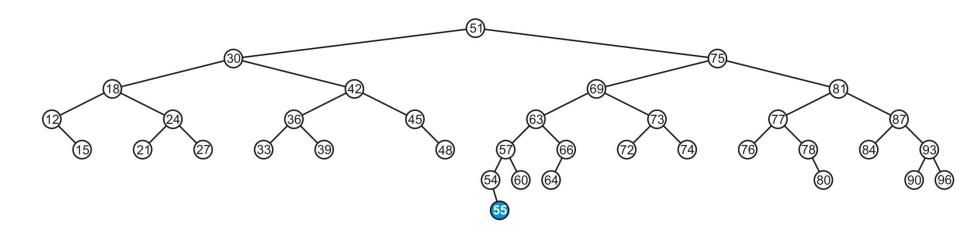
This causes no imbalances







□ Insert 55

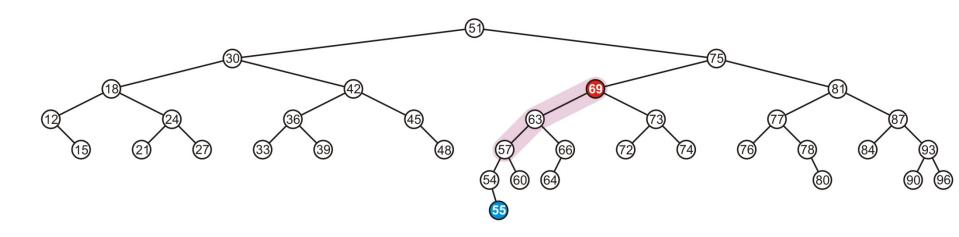






The node 69 is imbalanced

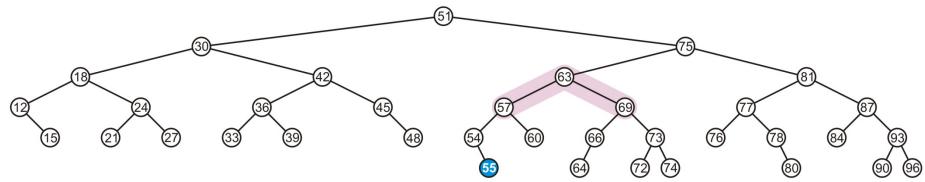
- A left-left imbalance
- Promote the intermediate node to the imbalanced node







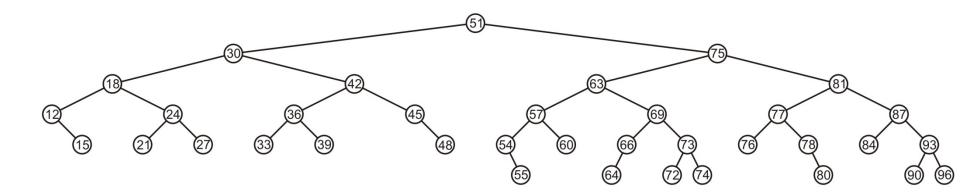
- The node 69 is imbalanced
 - A left-left imbalance
 - Promote the intermediate node to the imbalanced node
 - 63 is that value







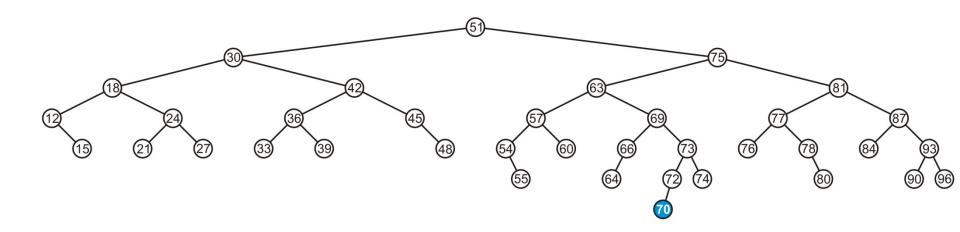
□ The tree is now balanced







□ Insert 70



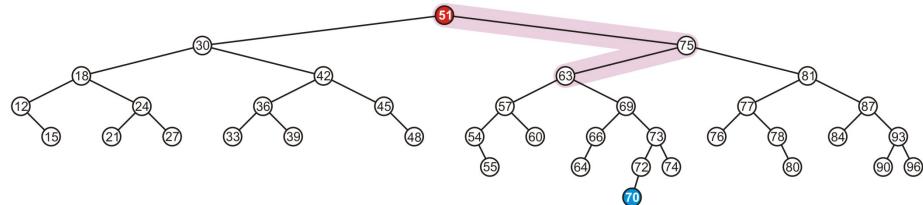


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 $\hfill\square$ The root node is now imbalanced

- A right-left imbalance
- Promote the intermediate node to the root
- 63 is that value

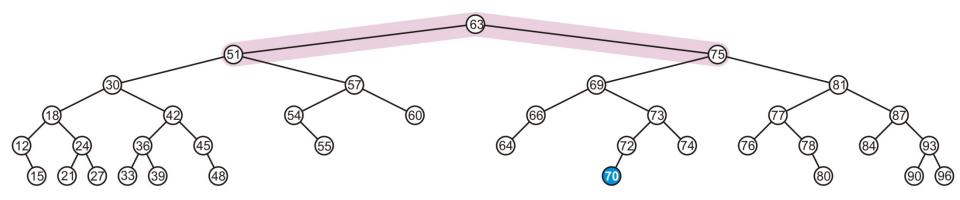






The root node is imbalanced

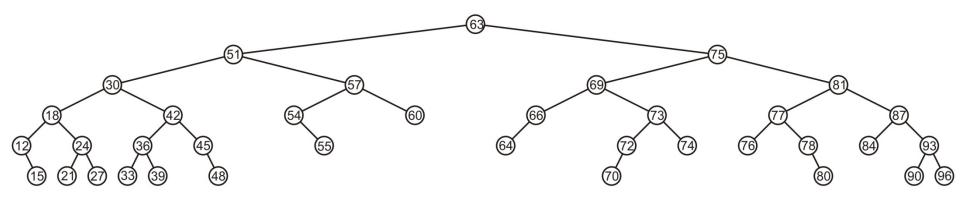
- A right-left imbalance
- Promote the intermediate node to the root







$\hfill\square$ The result is AVL balanced





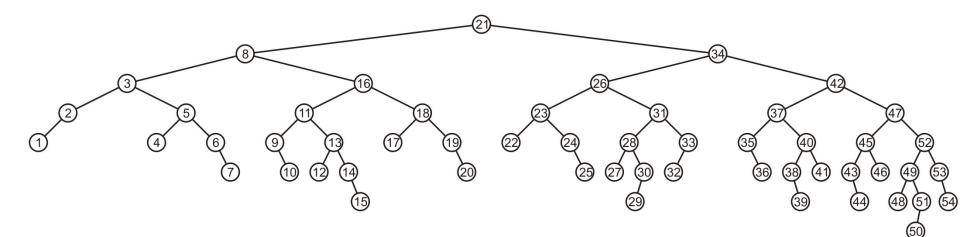


- Removing a node from an AVL tree may cause more than one AVL imbalance
 - Like insert, erase must check after it has been successfully called on a child to see if it caused an imbalance
 - Unfortunately, it may cause O(h) imbalances that must be corrected
 - Insertions will only cause one imbalance that must be fixed
 - Time complexity of deletion? Still O(h)
 - The movement of trees, however, may require that more than one node within the triplet has its height corrected





□ Consider the following AVL tree

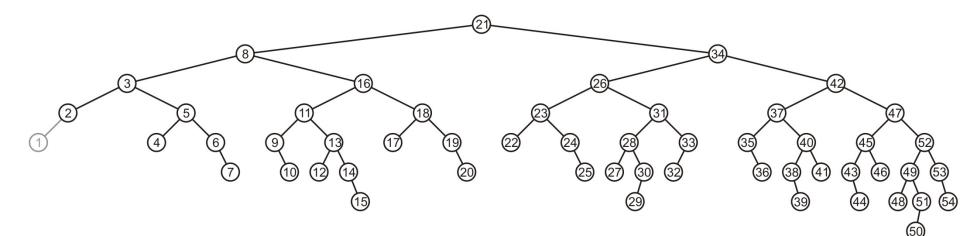








□ Suppose we erase the front node: 1

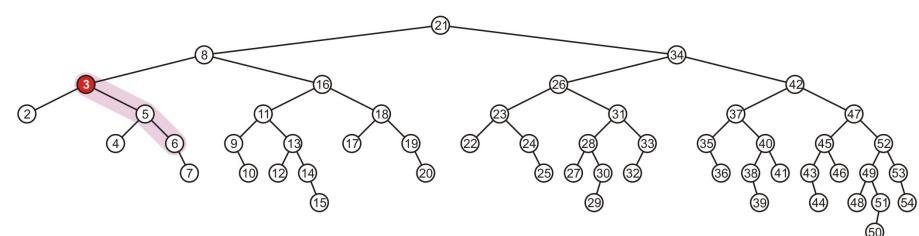








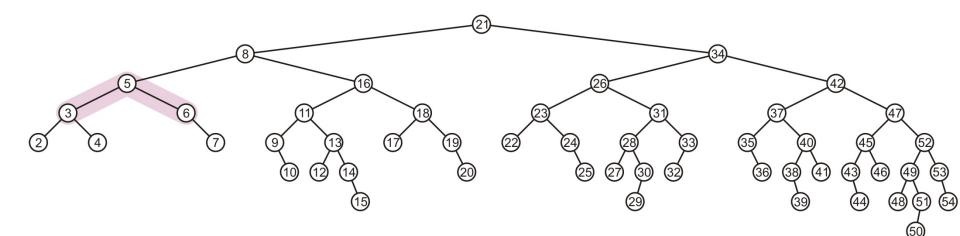
- While its previous parent, 2, is not unbalanced, its grandparent 3 is
 - The imbalance is in the right-right subtree







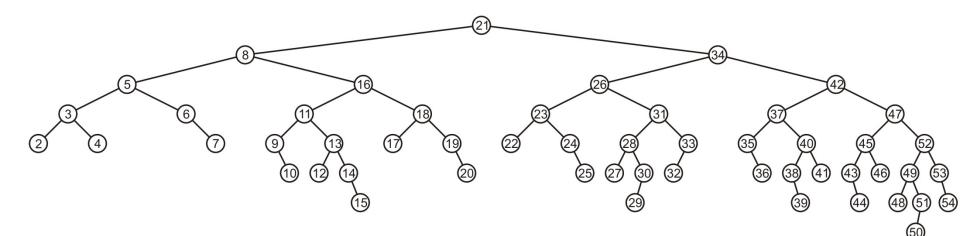
□ We can correct this with a simple balance







□ The node of that subtree, 5, is now balanced

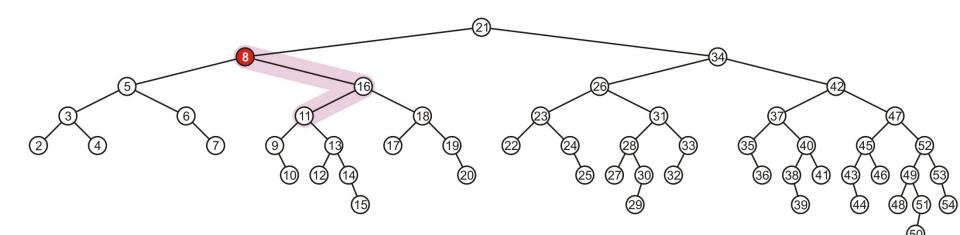






□ Recursing to the root, however, 8 is also unbalanced

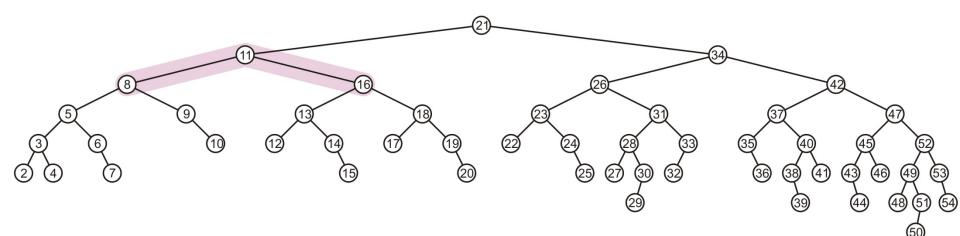
This is a right-left imbalance







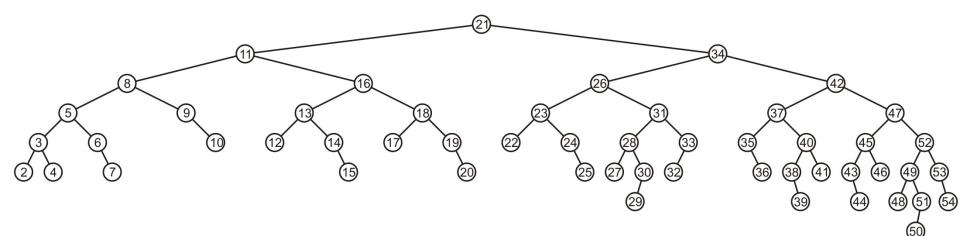
Promoting 11 to the root corrects the imbalance







\Box At this point, the node 11 is balanced

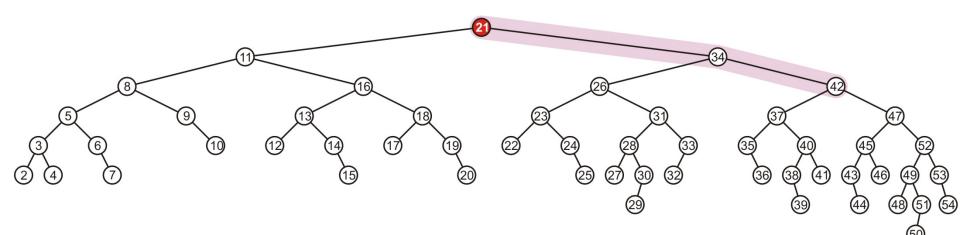






□ Still, the root node is unbalanced

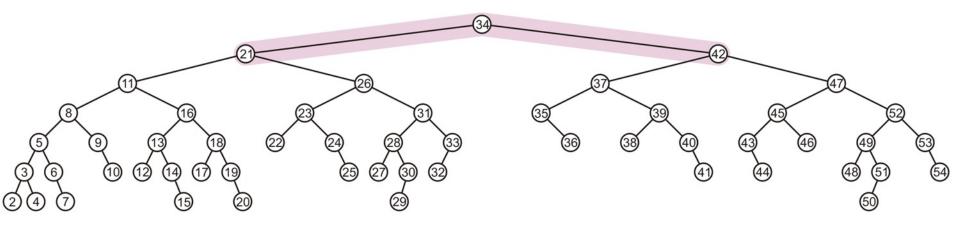
This is a right-right imbalance







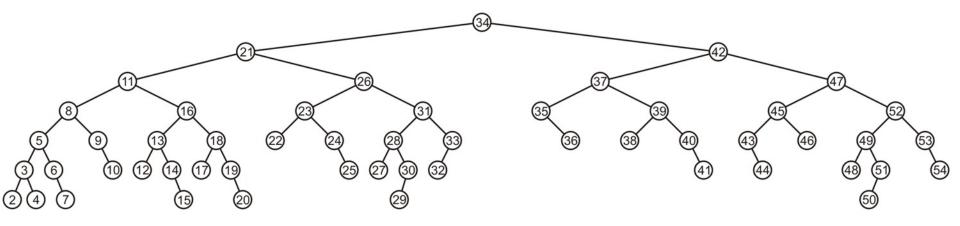
□ Again, a simple balance fixes the imbalance







□ The resulting tree is now AVL balanced







Summary

- \Box In this topic we have covered:
 - AVL balance is defined by ensuring the difference in heights is 0 or 1
 - Insertions and erases are like binary search trees
 - Each insertion requires at least one correction to maintain AVL balance
 - Erases may require O(h) corrections
 - These corrections require $\Theta(1)$ time
 - Depth is $\Theta(\ln(n))$
 - \therefore all O(h) operations are O(ln(n))







Red-Black Trees

Kyunghan Lee Networked Computing Lab (NXC Lab) Department of Electrical and Computer Engineering Seoul National University https://nxc.snu.ac.kr kyunghanlee@snu.ac.kr







Outline

 \Box In this topic, we will cover:

- The idea behind a red-black tree
- Defining balance
- Insertions and deletions
- The benefits of red-black trees over AVL trees





Red-Black Trees

- A red black tree "colors" each node within a tree either red or black
 - This can be represented by a single bit
 - In AVL trees, balancing restricts the difference in heights to at most one
 - For red-black trees, we have a different set of rules related to the colors of the nodes





AVL Vs. Red-Black Trees

	Average	Worst-case
Space	O(n)	O(n)
Lookup	O(log n)	O(log n)
Insert	O(log n)	O(log n)
Delete	O(log n)	O(log n)

	Average	Worst-case
Space	O(n)	O(n)
Lookup	O(log n)	O(log n)
Insert	O(log n)	O(log n)
Delete	O(log n)	O(log n)

AVL tree

Red-Black Tree

Asymptotic complexity for lookup/insert/delete is the same!





AVL Vs. Red-Black Trees

AVL Vs. RBTree

- AVL maintains its balance more tight than RBTree
 - Recall the definition
- AVL performs better for lookup-intensive applications
- RBTree provides faster worst-case performance for insert/delete

To quote Linux Weekly News:

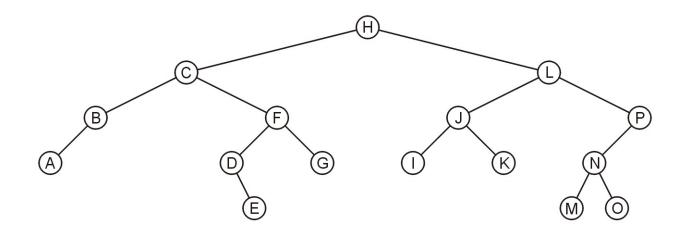
There are a number of red-black trees in use in the kernel. The deadline and CFQ I/O schedulers employ rbtrees to track requests; the packet CD/DVD driver does the same. The high-resolution timer code uses an rbtree to organize outstanding timer requests. The ext3 filesystem tracks directory entries in a red-black tree. Virtual memory areas (VMAs) are tracked with red-black trees, as are epoll file descriptors, cryptographic keys, and network packets in the "hierarchical token bucket" scheduler.





Red-Black Trees

- Define a *null path* within a binary tree as any path starting from the root where the last node is not a full node
 - Consider the following binary tree:

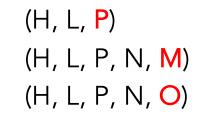


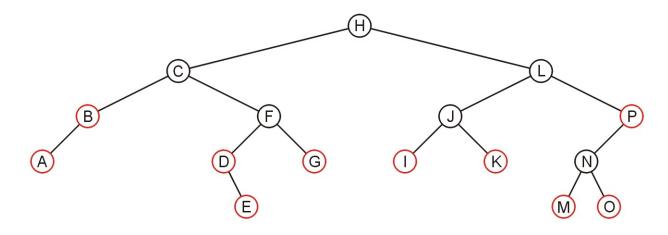




□ All null paths include: (H, C, B) (H, C, F, D) (H, C, B, A) (H, C, F, D, E) (H, L, J, K)(H, C, F, **G**)

(H, L, J, <mark>I</mark>)









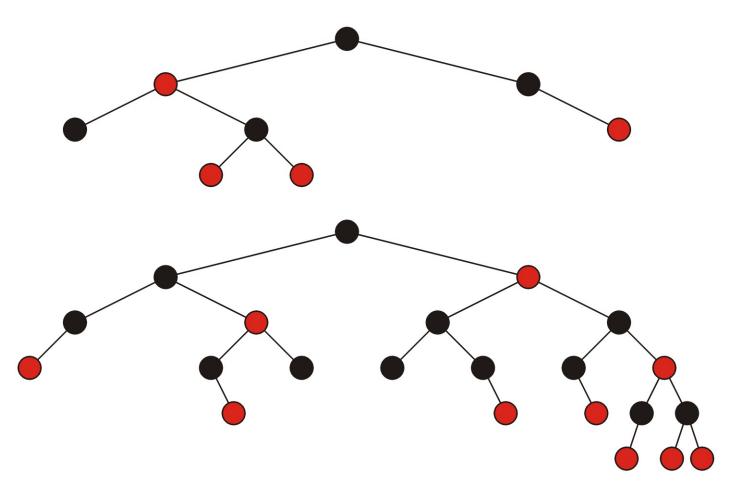
□ The three rules which define a red-black tree are

- 1. The root must be black,
- 2. If a node is red, its children must be black,
- 3. Each null path must have the same number of black nodes





□ These are two examples of red-black trees:



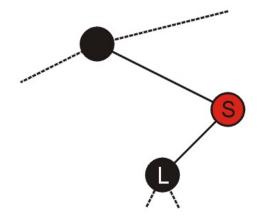


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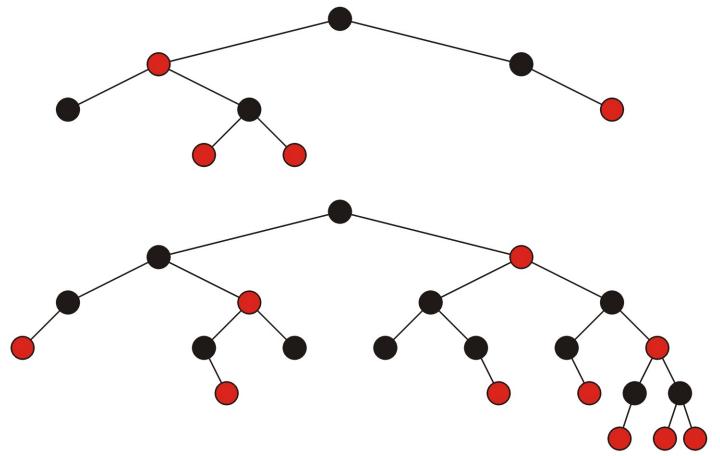
□ Theorem:

- Every red node must be either
 - A full node (with two black children), or
 - A leaf node
- □ Proof by contradiction:
 - Suppose node S has one child:
 - The one child L must be black
 - The null path ending at <mark>S</mark> has *k* black nodes
 - Any null path containing the node L will therefore have at least k + 1 black nodes





 In our two examples, you will note that all red nodes are either full or leaf nodes

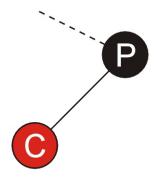




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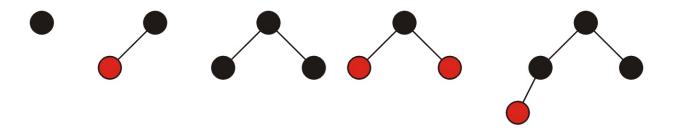


- Another consequence is that if a node P has exactly one child:
 - The one child must be red,
 - The one child must be a leaf node, and
 - The node P must be black





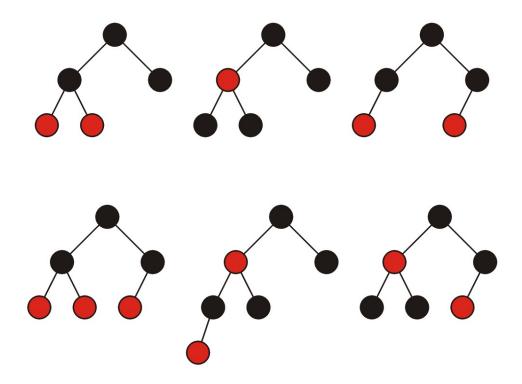
□ All red-black trees with 1, 2, 3, and 4 nodes:







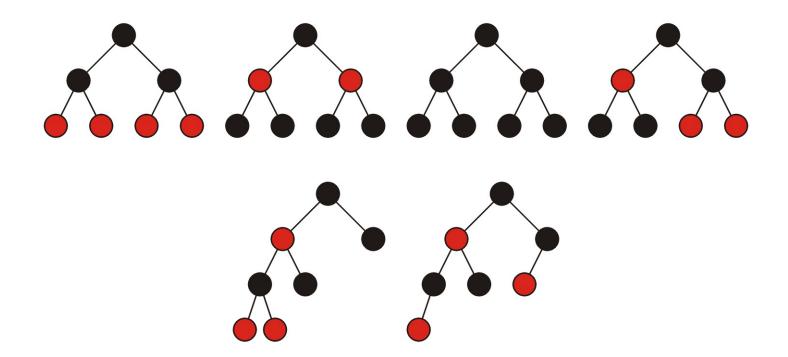
□ All red-black trees with 5 and 6 nodes:







□ All red-black trees with seven nodes—most are shallow:







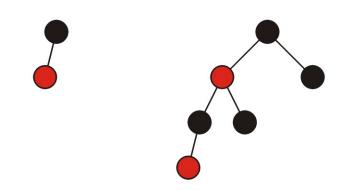
- Every perfect tree is a red-black tree if each node is colored black
- □ A complete tree is a red-black tree if:
 - each node at the lowest depth is colored red, and
 - all other nodes are colored black

 \Box What is the worst case?





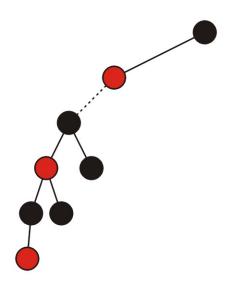
- Any worst-case red-black tree must have an alternating red-black pattern down one side
- The following are the worst-case red-black trees with 1 and 2 black nodes per null path (*i.e.*, heights 1 and 3)





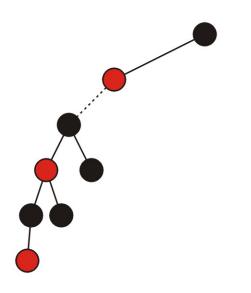


To create the worst-case for paths with 3 black nodes per path, start with a black and red node and add the previous worst-case for paths with 2 nodes





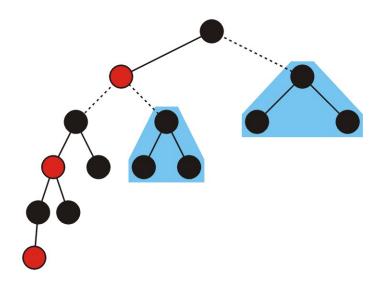
- This, however, is not a red-black tree because the two top nodes do not have paths with three black nodes
 - To solve this, add the optimal red-black trees with two black nodes per path







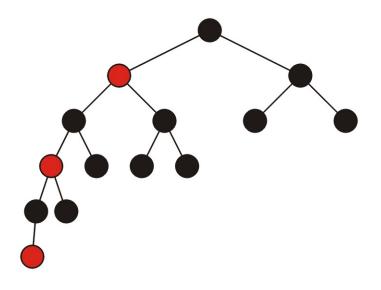
 That is, add two perfect trees with height 1 to each of the missing sub-trees







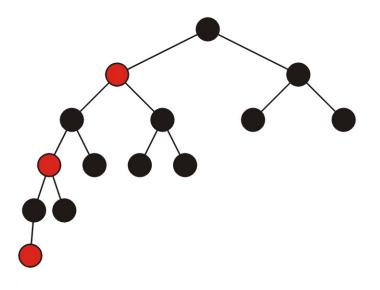
 Thus, we have the worst-case for a red-black tree with three black nodes per path (or a red-black tree of height 5)







- Note that the left sub-tree of the root has height 4 while the right has height 1
 - Thus, suggests that AVL trees may be better in maintaining "height balance"





Revisit: Red-Black Trees vs. AVL

- AVL trees are not as deep in the worst case as are redblack trees
 - Therefore, AVL trees will perform better when numerous searches are being performed,
 - However, insertions and deletions will require:
 - more rotations with AVL trees, and
 - require recursions from and back to the root
 - Thus, AVL trees will perform worse in situations where there are numerous insertions and deletions





Insertions

□ We will consider two types of insertions:

- bottom-up (insertion at the leaves), and
- top-down (insertion at the root)
- The first will be instructional and we will use it to derive the second case



Bottom-Up Insertions

- After an insertion is performed, we must satisfy all the rules of a red-black tree:
 - #1. The root must be black,
 - #2. If a node is red, its children must be black, and
 - #3. Each path from a node to any of its descendants which are not a full node (*i.e.*, two children) must have the same number of black nodes
- □ #1 and #2 are local: they affect a node and its neighbors
- #3 is global: adding a new black node anywhere will cause all of its ancestors to become unbalanced





Bottom-Up Insertions

Thus, when we add a new node, we will add a red node

- Which breaks the local rule
- But not breaking the global rule
- We will then travel up the tree to the root, while fixing the requirement #1 and #2





Bottom-Up Insertions

- If the parent of the inserted node is already black, we are done
 - Otherwise, we must correct the problem
- □ We will fix by following two steps:
 - Step #1) the initial insertion, and
 - Step #2) the recursive steps back to the root

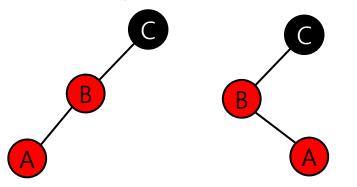




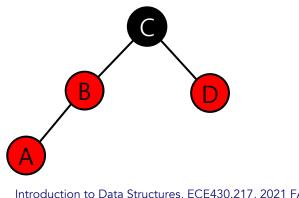
Bottom-Up Insertions: Step #1. Initial insertion

□ For the initial insertion, there are two possible cases:

• Case #1: the grandparent has one red child, or



Case #2: the grandparent has two red children

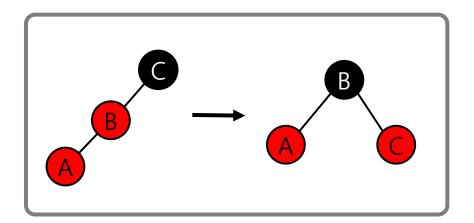


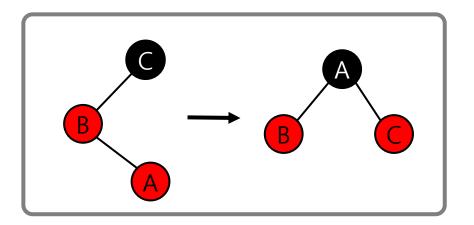




Bottom-Up Insertions: Step #1. Initial insertion

Case #1 can be fixed with a rotation. Example: Inserting A



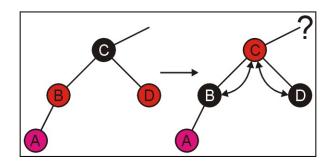


Consequently, we are finished...



Bottom-Up Insertions: Step #1. Initial insertion

□ Case #2 seems to be fixed by just swapping the colors:



However, we now may cause a problem between the parent and the grandparent....





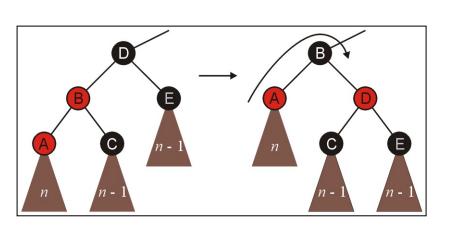
- Fortunately, dealing with problems caused within the tree are identical to the problems at the leaf nodes
- \Box Like before, there are two cases:
 - the grandparent has one red child, or
 - the grandparent has two red children



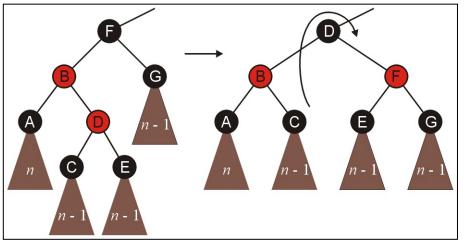


□ Suppose that A and D, respectively were swapped.

 If the grand parent had one red child (Case #1), we perform similar rotations as we have done before.



A was swapped, and the grand parent (D) has only one red child (B)

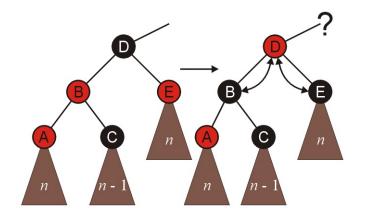


D was swapped, and the grand parent (F) has only one red child (B)





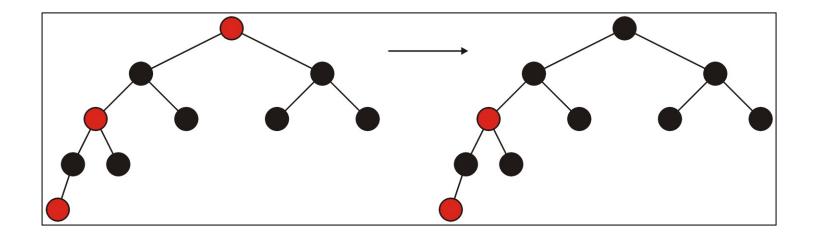
 If both children of the grandparent are red (Case #2), we swap colors, and recurs back to the root







 $\hfill\square$ If, at the end, the root is red, it can be colored black

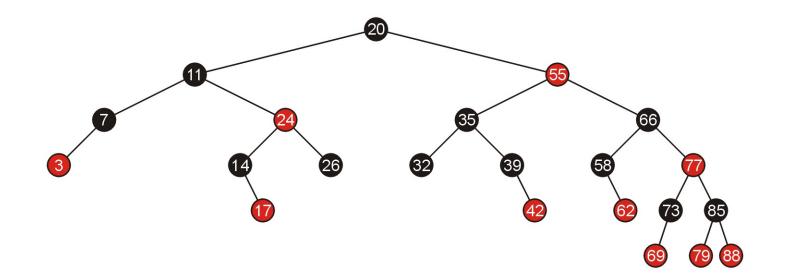






Examples of Insertions

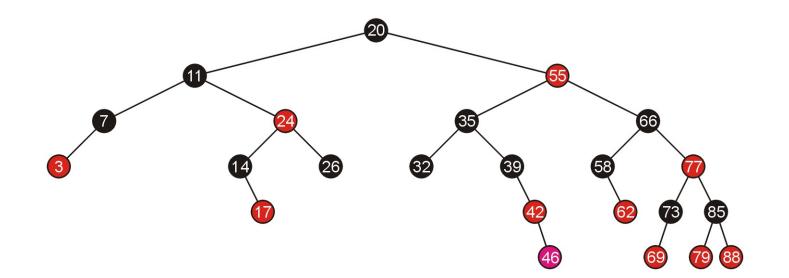
 Given the following red-black tree, we will make a number of insertions







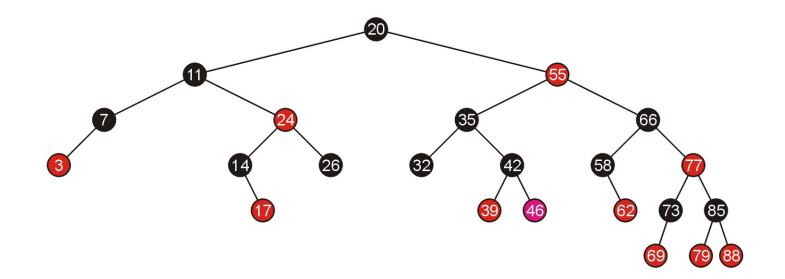
 Adding 46 creates a red-red pair which can be corrected with a single rotation







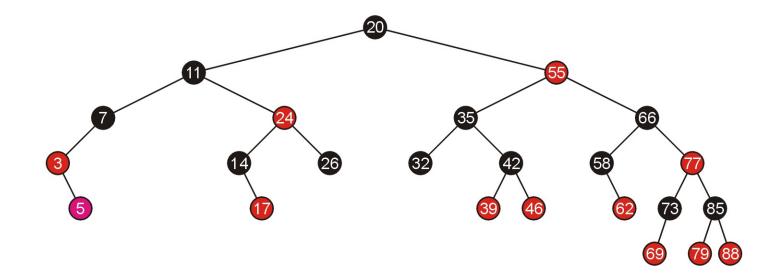
□ Because the pivot is still black, we are finished







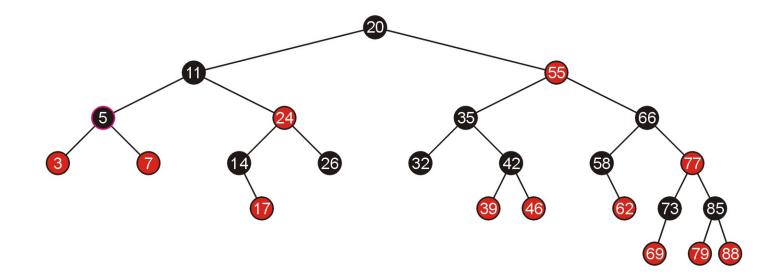
□ Similarly, adding 5 requires a single rotation







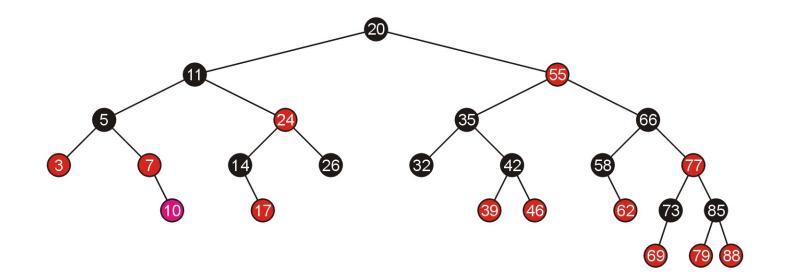
□ Which again, does not require any additional work







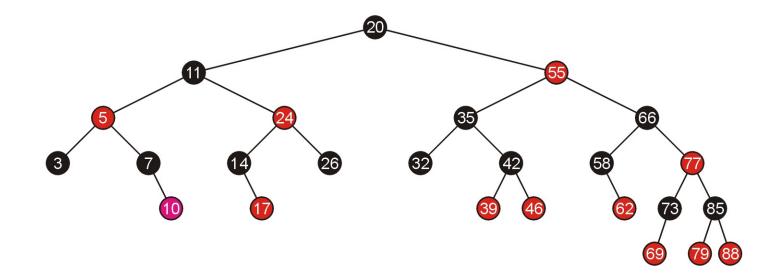
Adding 10 allows us to simply swap the color of the grand parent and the parent and the parent's sibling







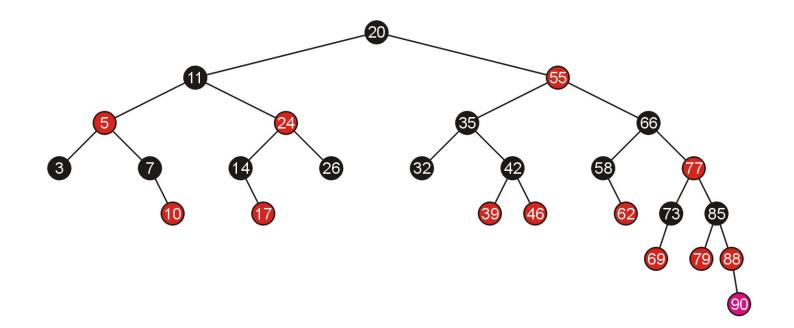
□ Because the parent of 5 is black, we are finished







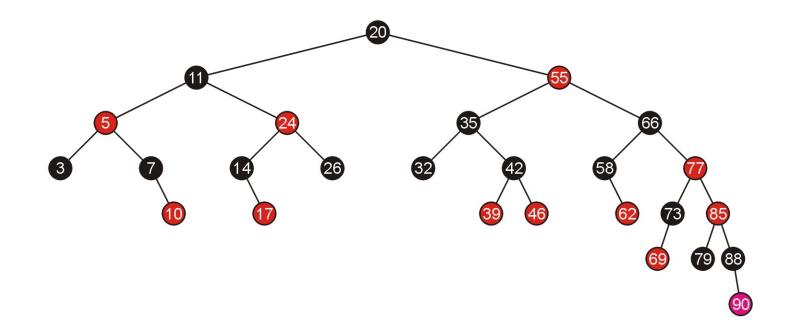
 Adding 90 again requires us to swap the colors of the grandparent and its two children







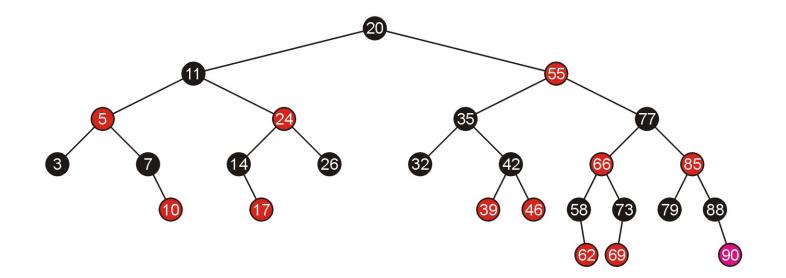
This causes a red-red parent-child pair, which now requires a rotation







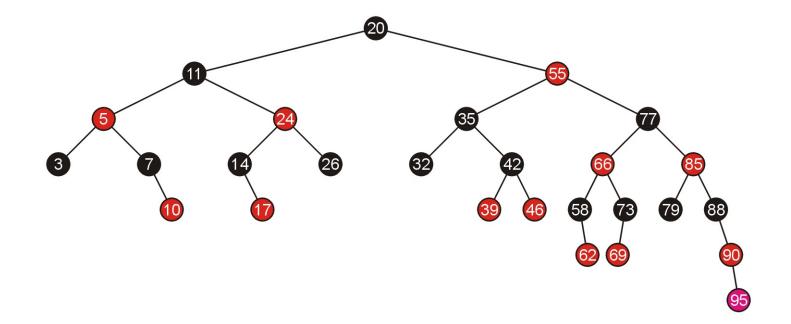
 A rotation does not require any subsequent modifications, so we are finished







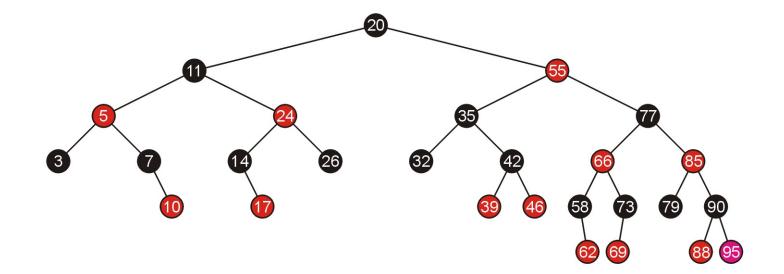
□ Inserting 95 requires a single rotation







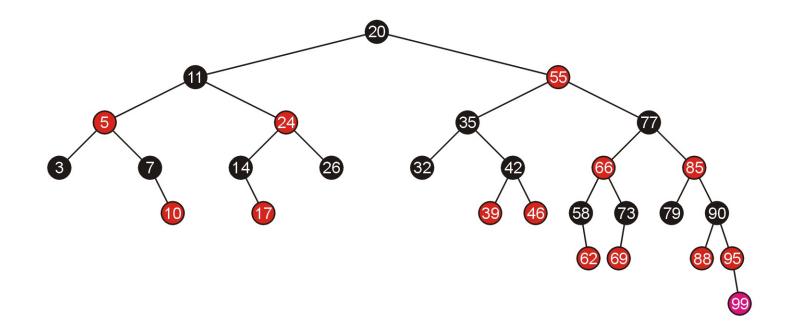
□ And consequently, we are finished







 Adding 99 requires us to swap the colors of its grandparent and the grandparent's children

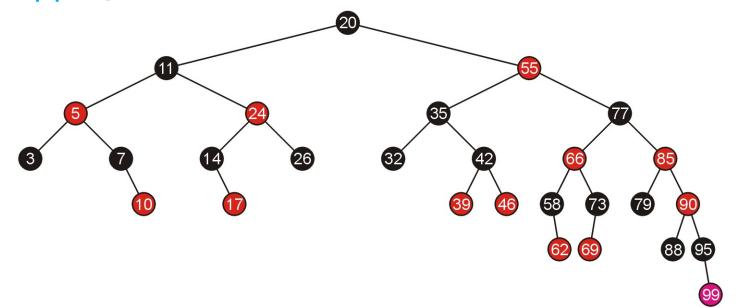








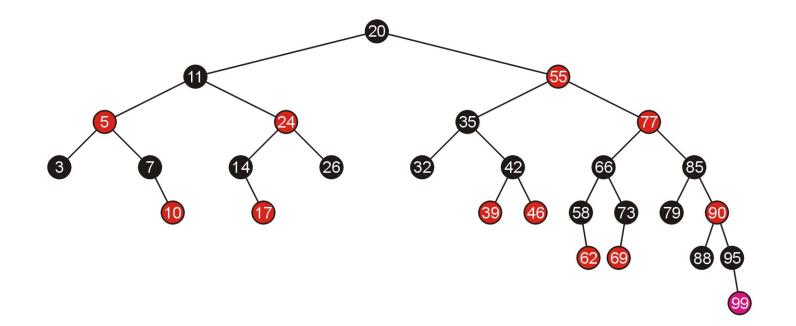
This causes another red-red child-parent conflict between 85 and 90 which must be fixed, again by swapping colors







 This results in another red-red parent-child conflict, this time, requiring a rotation

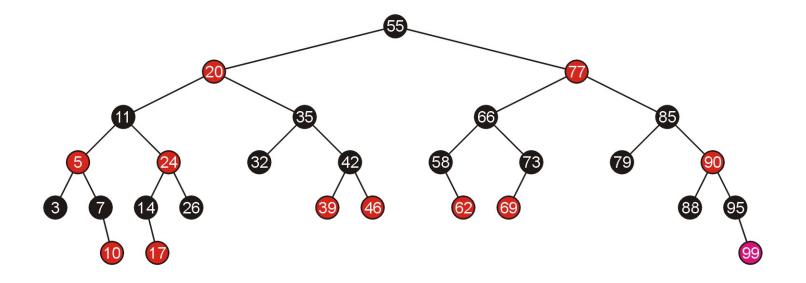








□ Thus, the rotation solves the problem







Top-Down Insertions and Deletions

- With a bottom-up insertion, it is first necessary to search the tree for the appropriate location, and only then recurs back to the root correcting any problems
 - This is similar to AVL trees
- With red-black trees, it is possible to perform both insertions and deletions strictly by starting at the root, but not requiring the recurs back to the root





Top-Down Insertions

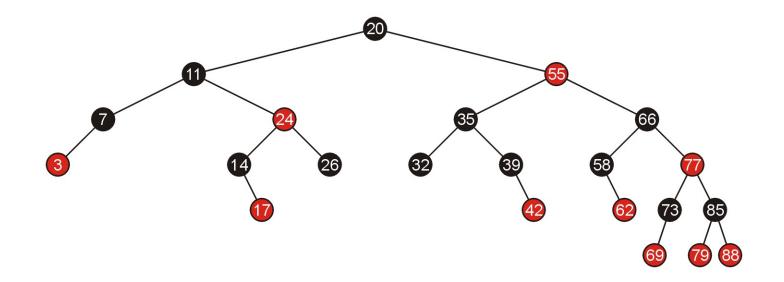
- □ The important observation is:
 - Rotations (Case #1) do not require recursive steps back to the root
 - Swapping (Case #2) may require recursive corrections going back all the way to the root
- Therefore, while moving down from the root, automatically swap the colors of any black node with two red children
 - this may require at most one rotation at the parent of the nowred node





Examples of Top-Down Insertions

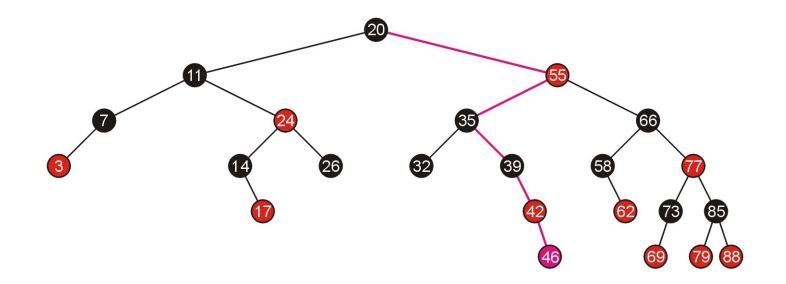
 We will start with the same red-black tree as before, but make top-down insertions (no recursion):







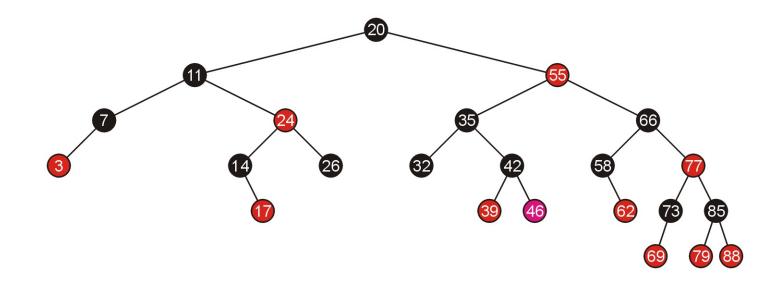
 Adding 46 does not find any (necessarily black) parent with two red children







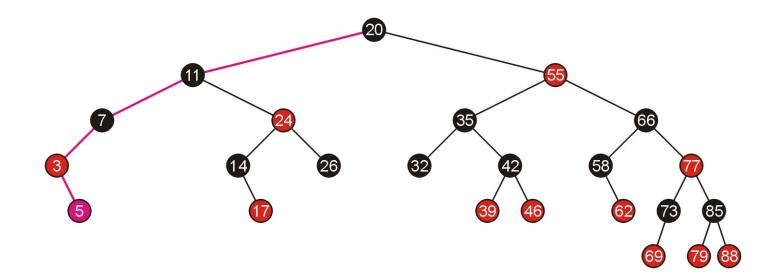
□ However, it does require one rotation at the end







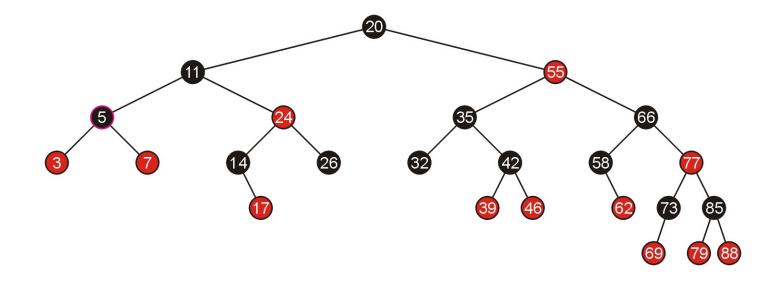
 Similarly, adding 5 does not meet any parent with two red children:







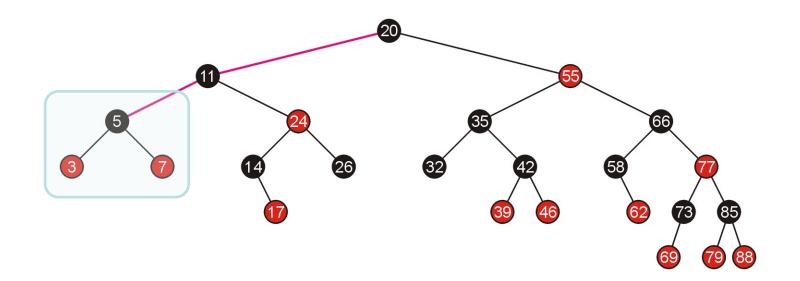
□ A rotation solves the last problem







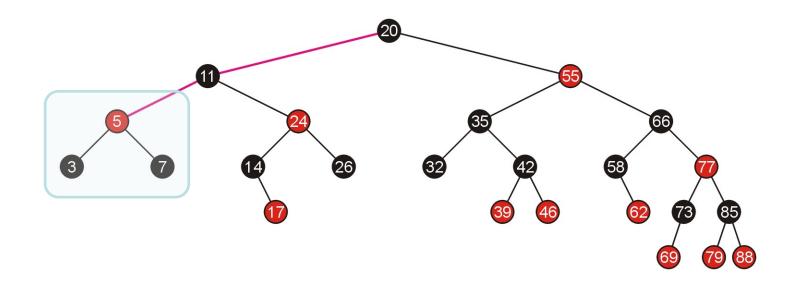
 To insert 10, we can spot that node 5 has two red children







 We swap the colors, and this does not cause a problem between 5 and 11

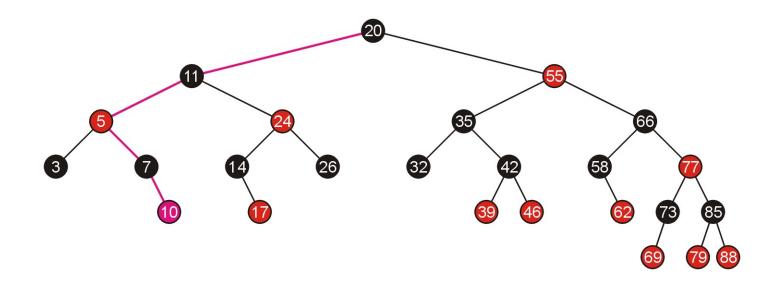






□ We continue and place 10 in the appropriate location

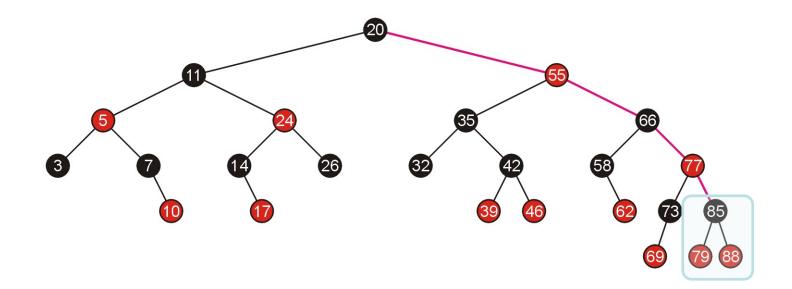
No further rotations are required







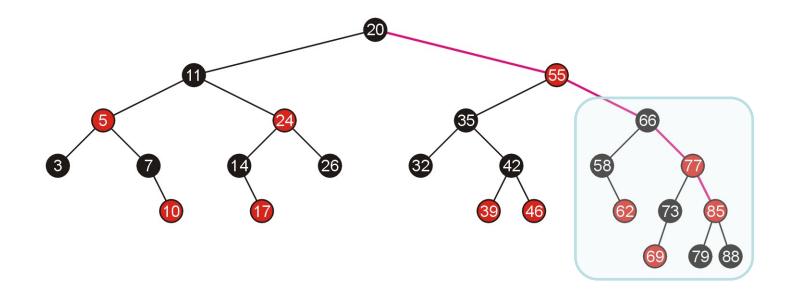
To add the node 90, we traverse down the right tree until we reach 85 which has two red children







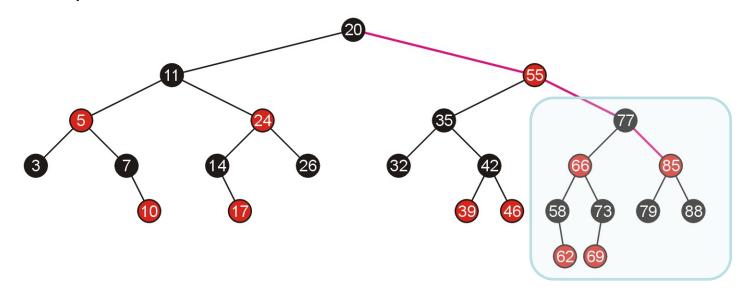
 We swap the colors, however this creates a red-red pair between 85 and its parent







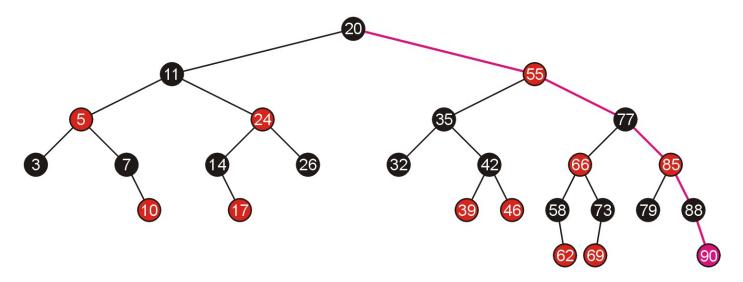
 We require only one rotation to solve this problem, and we are guaranteed that this will not cause any problem for its parents







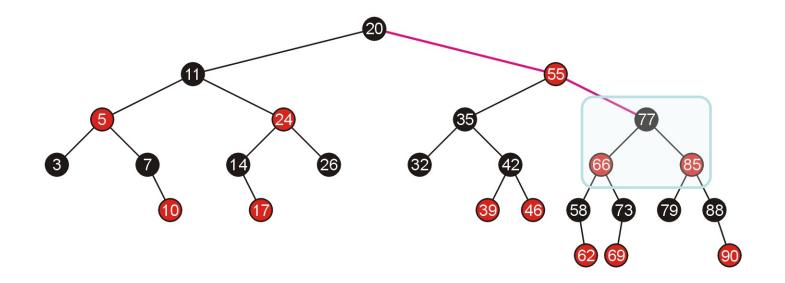
 We continue to search down the right path and add 90 in the appropriate location—no further corrections are required







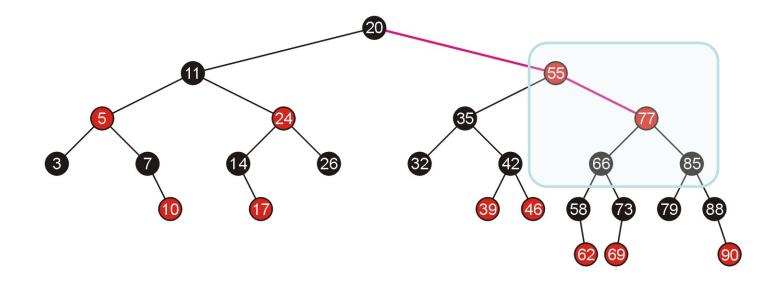
 Next, adding 95, we traverse down the right-hand until we reach node 77 which has two red children







We swap the colors, which causes a red-red parent-child combination which must be fixed by a rotation

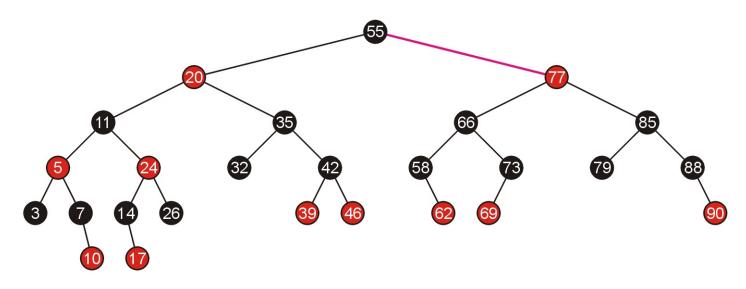






□ The rotation is around the root

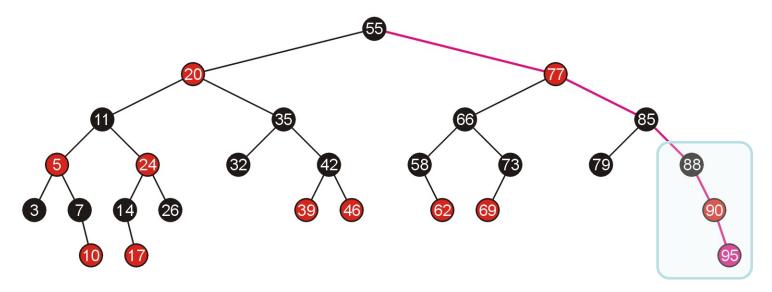
Note this rotation was not necessary with the bottom-up insertion of 95







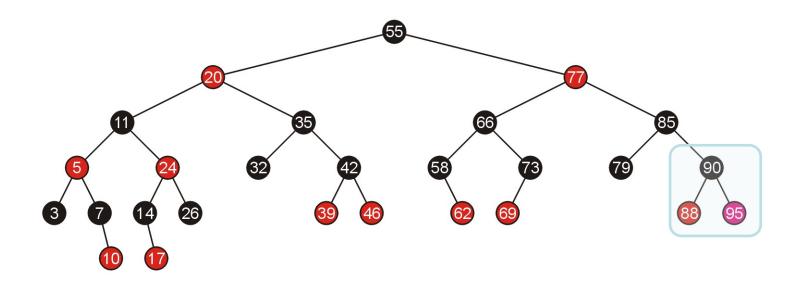
 We can now proceed to add 95 by following the righthand branch, and the insertion causes a red-red parentchild combination







- □ This is fixed with a single rotation
 - We are guaranteed that this will not cause any further problems

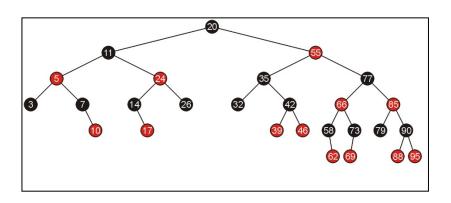


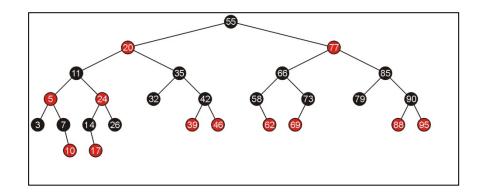




Compare Top-Down and Bottom-up Insertions

 If we compare the result of doing bottom-up insertions (left, seen previously) and top-down insertions (right), we note the resulting trees are different, but both are still valid red-black trees

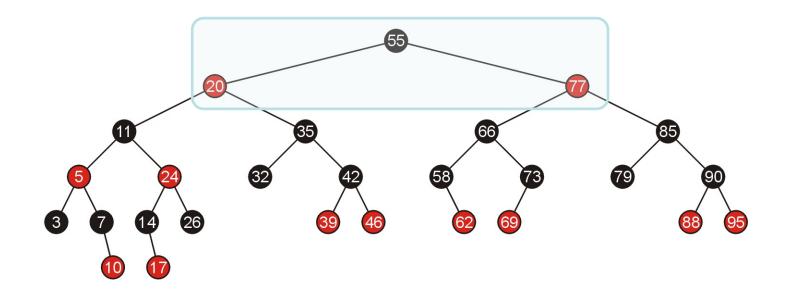








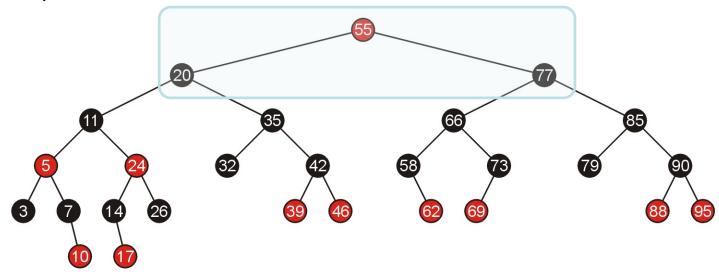
 If we add 99, the first thing we note is that the root has two red children, and therefore we swap the colors







 At this point, each path to a non-full node still has the same number of black nodes, however, we violate the requirement that the root is black

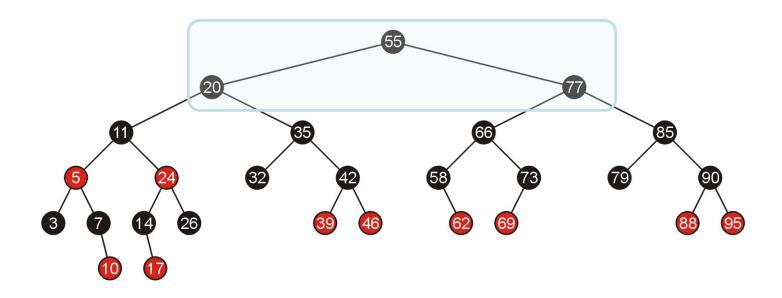






□ We change the color of the root to black

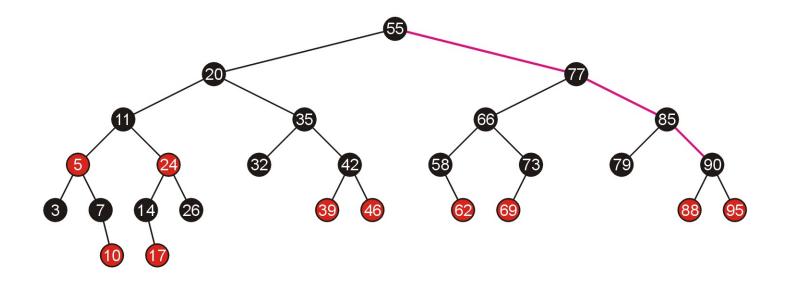
This adds one more black node to each path







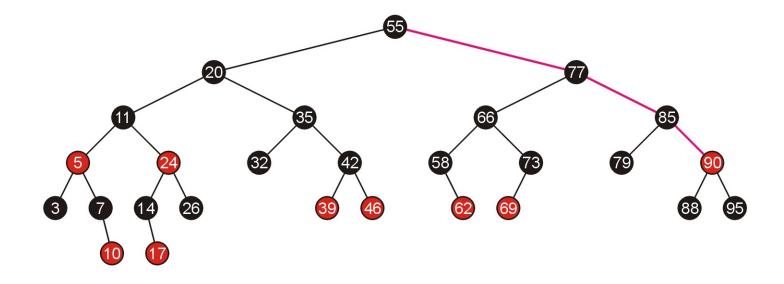
 Moving to the right, we now reach node 90 which has two red children and therefore we swap the colors







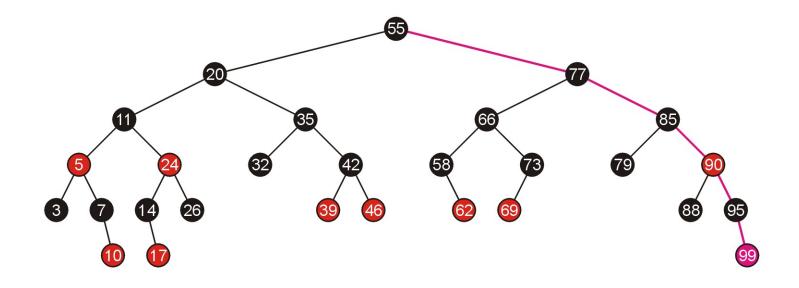
We continue down the right to add 99







 This does not violate any of the rules of the red-black tree and therefore we are finished

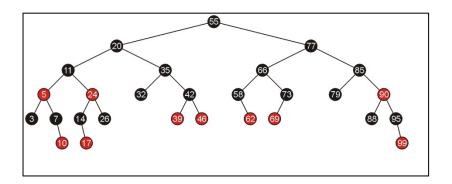


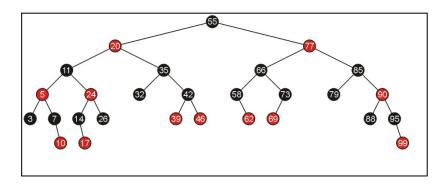




Compare Top-Down and Bottom-up Insertions

 Again, comparing the result of doing bottom-up insertions (left) and top-down insertions (right), we note the resulting trees are different, but both are still valid red-black trees



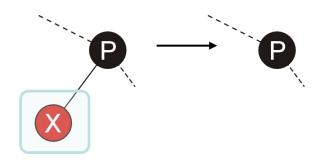




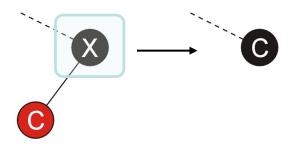


Top-Down Deletions: Easy cases

 If we are deleting a red leaf node X, then we are finished



 If we are deleting a node X with one child, we only need to replace the value of the deleted node with the value of the leaf node







- If we are deleting a full node, we use the same strategy used in standard binary search trees:
 - replace the node with the minimum element in the right subtree
 - then delete that element from the right sub-tree



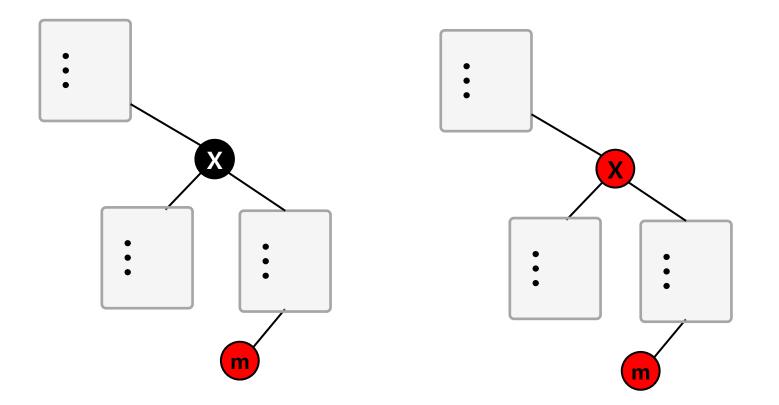


- □ That minimum element must be:
 - Case #1: a red leaf node,
 - Case #2: a black node with a single red leaf node, or
 - Case #3: a black leaf node
- \Box The first two cases are easy to solve.
- For the last case, take the similar top-down insertion strategies.
- See why RBTree is difficult? You should handle all different cases (nicely).





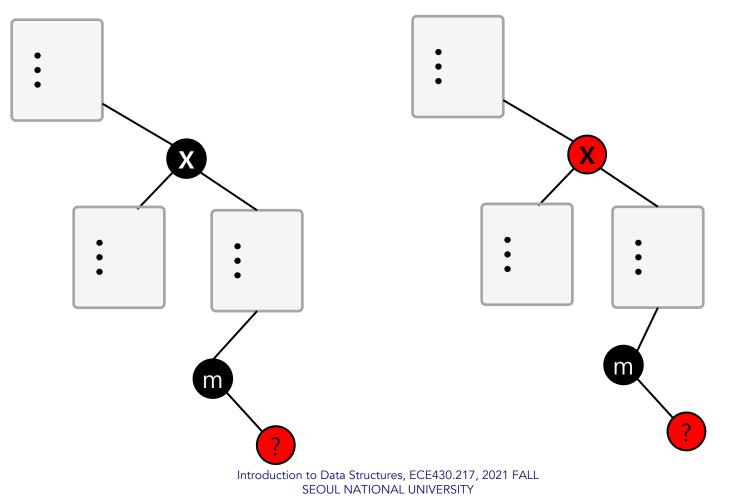
- □ That minimum element must be either:
 - Case #1: a red leaf node → Easy to solve





□ That minimum element must be either:

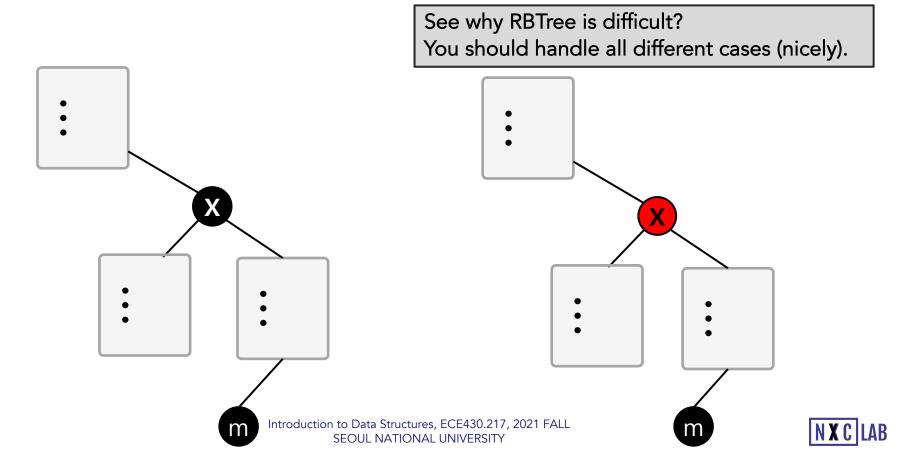
• Case #2: a black node with a single red leaf node \rightarrow Easy to solve





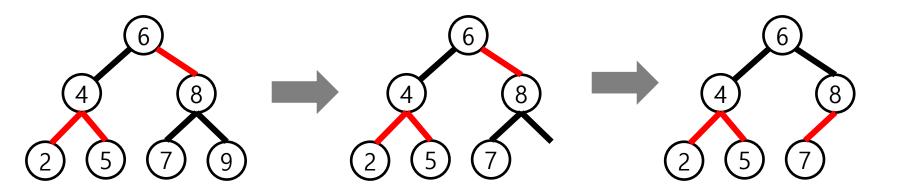
□ That minimum element must be either:

- Case #3: a black leaf node
 - \rightarrow take the similar top-down insertion strategies.



□ Case # 3: Examples

Delete 9



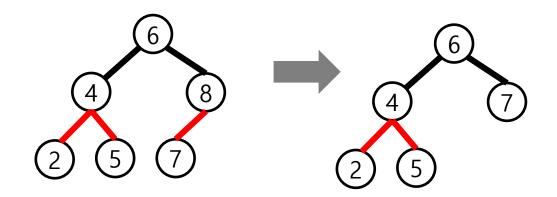
Remove 9, but the black height of node 8 becomes an issue Swapping the color solves the problem







- □ Case # 3: Examples
 - Delete 8



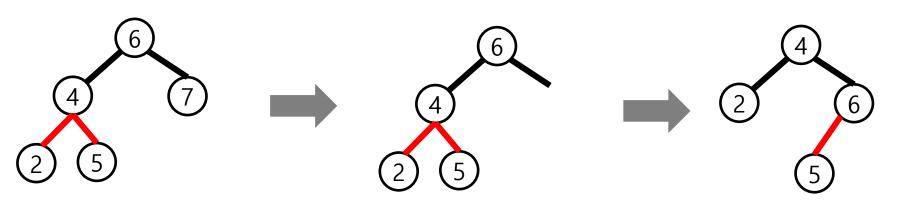
Deleting 8 is an easy case





□ Case # 3: Examples

Delete 7



Remove 7, then the black height of 6 becomes unbalanced Rotate and recolor solves the problem





Red-Black Trees

□ In this topic, we have covered red-black trees

- simple rules govern how nodes must be distributed based on giving each node a color of either red or black
- insertions and deletions may be performed without recursing back to the root
- only one bit is required for the "color"
- this makes them, under some circumstances, more suited than AVL trees

References

- [1] Cormen, Leiserson, and Rivest, Introduction to Algorithms, McGraw Hill, 1990.
- [2] Weiss, Data Structures and Algorithm Analysis in C++, 3^{rd} Ed., Addison Wesley.







B-Tree and B+Tree

Kyunghan Lee Networked Computing Lab (NXC Lab) Department of Electrical and Computer Engineering Seoul National University https://nxc.snu.ac.kr kyunghanlee@snu.ac.kr







Outline

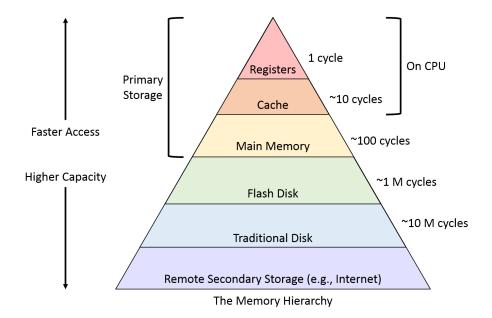
- Memory issues in designing data structures
 B-Tree
- □ B+Tree





Memory Considerations

- When we discuss data structures, we never specifically mention where the data would be stored.
- In fact, memory hierarchy suggests that the design of data structures should be well aware of it







Memory and Data Structures

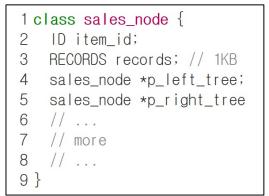
- Memory things to think about when designing data structures
 - Access speed
 - Cost per memory size
 - The unit size of access
 - Stream access vs. Random access



Tree for very large datasets

□ Suppose you got very many pieces of information

- e.g., $n = 2^{30}$
- Suppose each piece has 1KB data
- Examples
 - Student records, where each piece holds each student's report
 - Sales history, where each piece holds sale records per item
- If you design the tree to store such data
 - The number of nodes: 2³⁰
 - Each node will occupy at least 1KB
 - Total? At lest 1TB







Issues: Tree for very large datasets

- Two performance issues
 - #1: How many times do you need to access the memory?
 - Relevant to the height of a tree
 - Binary search tree
 - ✓ Best case
 - ✓ Worst case
 - AVL Tree
 - ✓ Best case
 - ✓ Worst case
 - #2: Can you store 1TB in the fast memory?
 - No, your main memory is (very likely) smaller than 1TB
 - So you will need to store the tree in the slow memory (i.e., a disk)





Ideas

□ Solution to #1: Multiple keys per node

- Load multiple keys at once
- Reduce the height of the tree
- Trees with this feature
 - M-Way Search Trees, B-Tree, B+Tree

□ Solution to #2: No data in the internal nodes

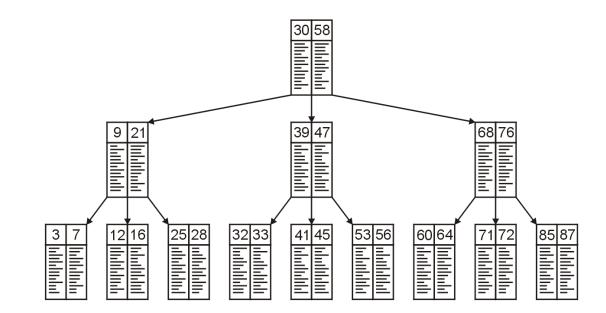
- Leaf nodes hold both keys/data, and internal nodes only hold keys
- You "may" not need to access the slow memory when accessing the internal nodes
- Trees with this feature
 - B+Tree





M-Way Search Trees

 M-Way Search Trees: A search tree with maximum branching factor M

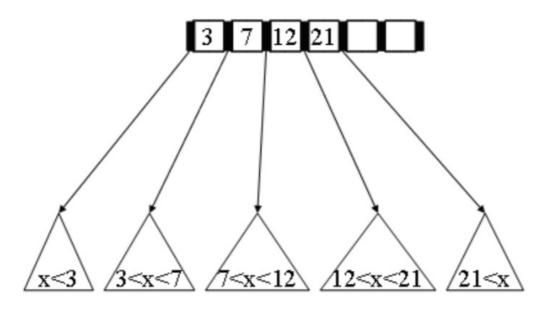






B-Trees

- □ Each node has keys up to M-1 keys
- Order property
 - Subtree between two keys x and y contain leaves with values v such that x < v < y







B-Tree Structure Property ($M \ge 3$)

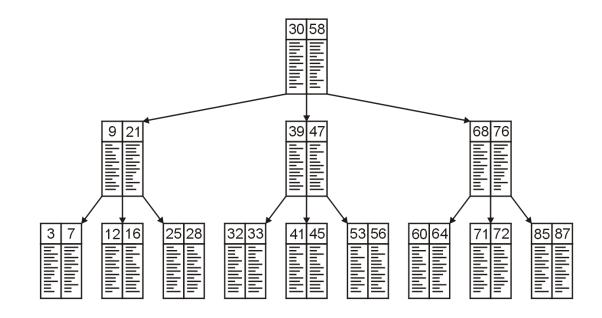
- □ Root (special case)
 - Has between 2 and M children (or root could be a leaf node)
- Internal nodes
 - Store up to M 1 keys
 - Have between [M/2] and M children
- □ Leaf nodes
 - Store between [M/2] 1 and M 1 sorted keys
 - All at the same depth





B-Tree: Example

\square B-Tree with M = 3







B+Trees

Internal nodes have no data

- Only leaf nodes have data
- \square Each internal node still has (up to) M 1 keys
- Order property
 - Subtree between two keys x and y contain leaves with values v such that x ≤ v < y
 - Note the symbol, '≤'

\Box Leaf nodes have up to L sorted keys

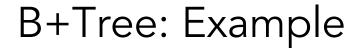


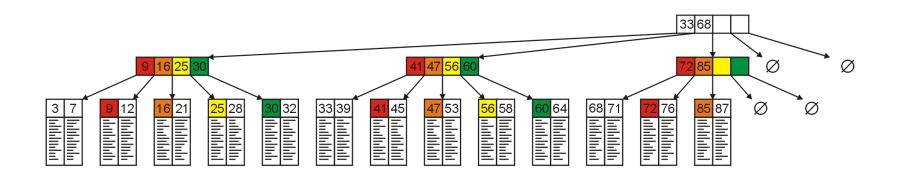


B+Tree Structure Property

- □ Root (special case)
 - Has between 2 and M children (or root could be a leaf node)
- Internal nodes
 - Store up to M 1 keys
 - Have between [M/2] and M children
- □ Leaf nodes
 - Where data is stored
 - All at the same depth
 - Contain between [L/2] and L data items











Disk Friendliness of B+Tree

Many keys stored in a node

- All brought to memory/cache in one disk access
- Internal nodes contain only keys
 - Only leaf nodes contain actual data
 - Much of tree structure can be loaded into memory irrespective of data object size
 - Data actually resides in disk



Comparison: B+Tree vs. AVL Tree

- □ Suppose again you have $n = 2^{30}$ items
 - AVL Tree
 - Height: 43
 - B+Tree where M=256, L=256
 - Height: 4.3
- If you consider other factors, things are getting more interesting
 - The size of each item
 - The size of Cache
 - The size of DRAM
 - ...

We never talked about the costs to balance the tree though





Maintain the Balance of B+ Tree

- □ How to make B+ Tree balanced?
 - Insertion idea (bottom-up approach)
 - Step 1: Insert an item to the leaf
 - Step 2: If the node overflows, 1) split the node and 2) add the key to the parent
 - Step 3: If the parent overflows, go back to step 2
 - You may need to increase the height
 - Deletion idea (bottom-up approach)
 - Step 1: Remove an item from the leaf
 - Step 2: If the node underflows, 1) adopt from (or merge with) the neighbor and 2) update the parent
 - Step 3: If the parent underflows, go back to step 2
 - You may need to decrease the height





Applications

Databases

- Index structure for MySQL
- A hash table can be a better option (will cover later)
- □ File systems
 - Apple's HFS+, Microsoft NTFS, Linux's EXT4 and btrfs

Real-world challenges in designing and implementing trees

- Parallel access: Multi-core processors are everywhere
- Distributed storage: Too large to store in a single computing node
- You will learn more from advanced courses: operating systems, computer architecture, database, etc.





References

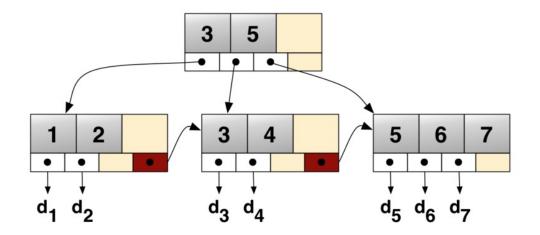
[1] Wikipedia, http://en.wikipedia.org/wiki/B+_tree

[2] Cormen, Leiserson, and Rivest, Introduction to Algorithms, McGraw Hill, 1990, Ch. 19, p.381-99.

[3] Weiss, Data Structures and Algorithm Analysis in C++, 3rd Ed., Addison Wesley, §4.7, p.159-64.

[4] Lecture slides by Brian Curless,

https://courses.cs.washington.edu/courses/cse326/08sp/lectures/markup/11-b-trees-markup.pdf



B+Tree: Leafs are linked listed [1]



Introduction to Data Structures, ECE430.217, 2021 FALL SEOUL NATIONAL UNIVERSITY

