

# Link Layer

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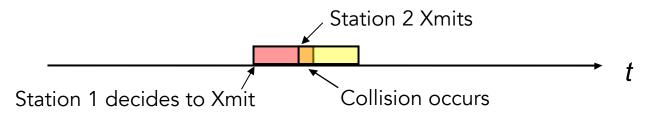


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## Collision

 Collision: Two or more users' transmissions overlap (in time) resulting in packet loss



- Recognition: Some way of recognizing that a collision has occurred and signaling users involved

  - (b) Use a positive ACK with timeout
  - (c) Stations listen and detect their own collisions ← bus architectures
- Retransmission: After a collision, attempt again after some random time has elapsed (back-off)
  - The amount of time is specified by a collision resolution protocol.





- $\square$  N stations
  - Each station transmits  $\lambda$  (new) packets/sec
  - Arrival of (new) packets from each station is Poisson
  - Fixed Packet lengths with transmission time = m

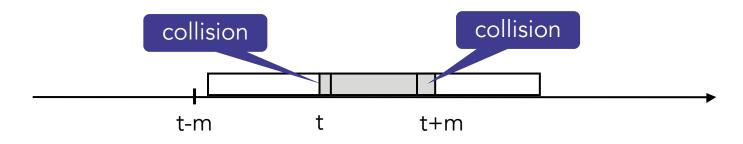
Normalized throughput (S) =  $\frac{\text{Rate of transmitting new packets}}{\text{Max. channel transmission rate}}$ =  $\frac{N\lambda \text{ packets/sec}}{\frac{1}{m} \text{ packets/sec}}$ 

- Additional assumption: retransmitted packets are also Poisson distributed
  - Not true: Since retransmissions depend on collision instance
  - Okay if random retransmission delay is long





- □ Let  $\lambda'$  be total rate of packets attempting transmission, then  $\lambda' \ge \lambda$
- □ Let G be actual traffic intensity or utilization, then  $G = N\lambda'm$
- $\Box$  Consider a typical packet transmitted at time t
  - Any transmissions by any station between times t m and t + m will cause a collision.







 $\Box \operatorname{Pr}\{\operatorname{Successful\ transmission}\}$ 

- $= \Pr\{\text{No arrivals in } [t m, t + m] \mid \text{An arrival occurs at } t\}$
- $= \Pr\{\text{No arrivals in } [t m, t + m]\}$
- $= \Pr\{\text{No arrivals in time interval of } 2m\}$

 $=e^{-N\lambda'(2m)}$ 

 $\Box \quad \text{From } G = N\lambda' m,$ 

 $P_s = \Pr{\{\text{Successful transmission}\}} = e^{-2G}$ 

Recall that Poisson process gives 
$$\P\{N(t)=n\}=rac{(\lambda t)^n}{n!}e^{-\lambda t}$$

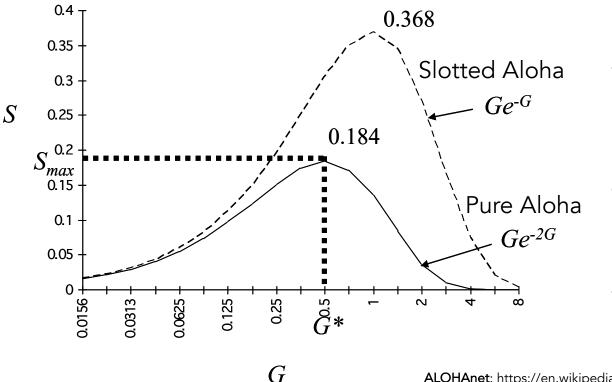
$$\Box \text{ Also, } P_s = \frac{\# \text{ of successfully transmitted packets}}{\# \text{ of totally transmitted packets}}$$
$$= \frac{(\text{throughput with new packets})}{(\text{throughput with all packets})} \xrightarrow{\longrightarrow} S$$
$$G$$
$$\Box \text{ Hence, } P_s = \frac{S}{G}$$



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Pure Aloha throughput:  $S = Ge^{-2G}$ • S has the peak value  $S_{max} = \frac{1}{2e}$ , when  $G = G^* = \frac{1}{2}$ 



For Aloha, the max throughput is 18% of channel capacity.

Thus it is suitable for either low traffic rate, or for highly bursty traffic

ALOHAnet: https://en.wikipedia.org/wiki/ALOHAnet#ALOHA\_protocol





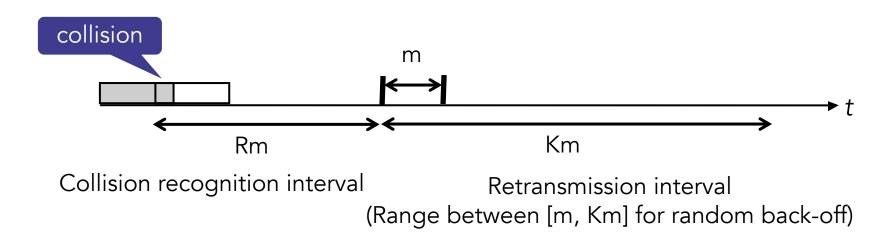
### Time Delay Analysis of Pure Aloha

- Our simple throughput analysis of Pure Aloha is "independent" of the retransmission policy
  - However, for time delay analysis, we need to specify the retransmission policy
- □ Retransmission Policy:
  - Suppose that each message lengths is of *m* seconds
  - If a collision occurs, we choose an arbitrary time interval, whose length is equivalent to K-message unit times ( $K \cdot m$ )
  - Retransmission randomly occurs in the interval, i.e., following the uniform distribution





## Time Delay Analysis of Pure Aloha



### □ Collision cognition interval:

- Retransmission will take place, only after the sender noticed that a collision has occurred
- Let the round-trip delay plus processing time required to obtain the collision information be *R* intervals (times *m*)





### Time Delay Analysis of Pure Aloha

 $\Box$  Let *D* be average time for a successful transmission

$$D = m + Rm + E\left(Rm + \frac{K+1}{2}m\right)$$
 Average delay of  
m is message transmission time ( $\in$ [m, Km])

where m is message transmission time ( $\in$ [m, Km]) Rm is recognition time E is expected number of retransmissions

Note that

 $1 + E = \frac{\text{avg. } \# \text{ of attempted transmissions}}{\text{avg. } \# \text{ of successful transmissions}} = \frac{G}{S} \longleftarrow S = Ge^{-2G}$ 

□ Hence,

$$D = m + Rm + (e^{2G} - 1) \cdot \left( Rm + \frac{K + 1}{2}m \right)$$

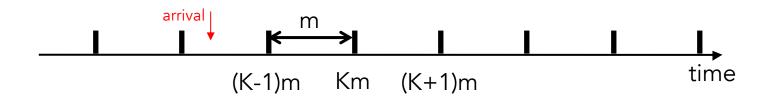




## Slotted Aloha

□ Time is slotted into units of message transmission times

- Messages can only be transmitted <u>at beginning of time slot</u>
- Collision occurs if another message is transmitted at the same time slot (This message arrives during ((K-1)m, Km))



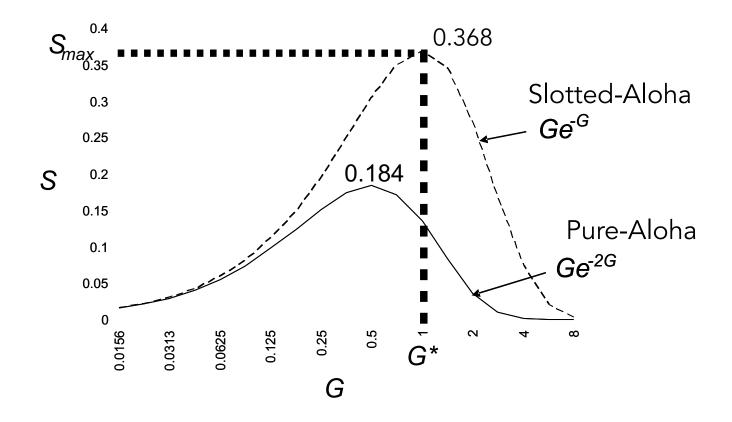
□ Following the same line of analysis as Pure Aloha,  $Pr{Success} = e^{-G}, S = Ge^{-G}$   $D = 1.5m + Rm + (e^{G} - 1) \cdot \left(Rm + 0.5m + \frac{K+1}{2}m\right)$ Try to get this result by yourself





### Throughput Analysis of Slotted Aloha

Slotted Aloha throughput:  $S = Ge^{-G}$ • S has the peak value  $S_{max} = \frac{1}{e}$ , when  $G = G^* = 1$ 



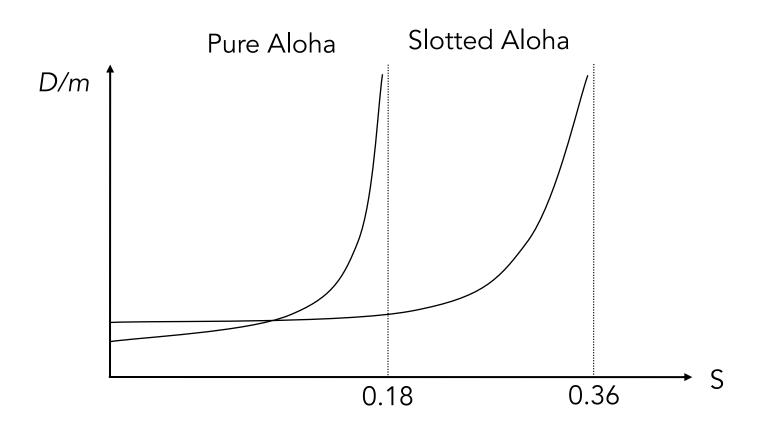


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### Performance Comparison

Throughput-delay curve



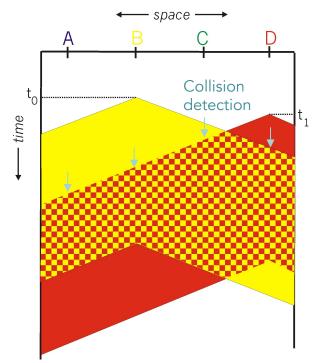


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Carrier Sense Multiple Access with Collision Detection

- All stations listen for transmissions on the line (carrier sense)
- A station can transmit only if it detects an idle channel
  - Listen-before-talk
- Two or more stations sensing an idle channel at same time may cause collisions
- Stations detecting a collision abort their transmission immediately.



http://www2.ic.uff.br/~michael/kr1999/5-datalink/5\_03-LAN.htm





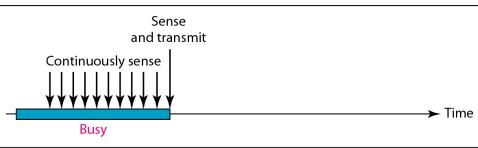
### $\Box$ In case that the channel is busy

- There are variants based on what to do when the channel is sensed busy
- 1-persistent: Attempt transmission as soon as channel is sensed idle (Ethernet)
- p-persistent: Attempt transmission with probability p once channel goes idle. With probability (1-p), wait for a propagation delay interval τ and try again!
- Non-persistent: Reschedule after a <u>random waiting</u> time, sense channel and if idle, transmit, if busy, repeat.

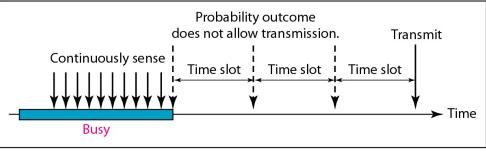




1-persistent



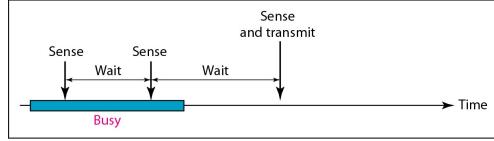
a. 1-persistent

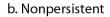


#### p-persistent

non-persistent

c. p-persistent









### After a collision is detected

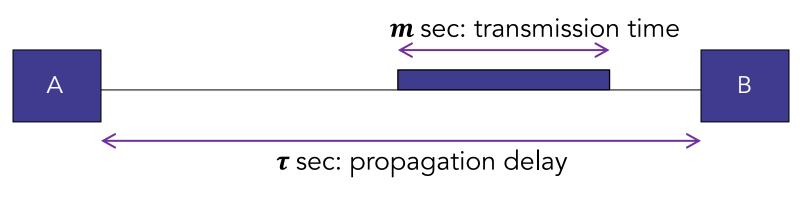
- Current packet transmission is aborted
- A retransmission attempt is made at a random time, uniformly chosen within a given time interval (similar to Aloha)
- Each time a collision occurs (for the same packet), this time interval is "doubled" (up to a maximum value) thereby reducing chance of collisions
- Known as binary exponential backoff.





□ All carrier sense protocols rely on stations being able to

- Sense that a transmission has ended, soon after its completion
- Sense that a transmission has started, soon after it begins
- Need  $a = \tau/m \ll 1$  for high throughput
- □ Suitable for
  - Local Area Network (small  $\tau$ )
  - Large Networks that are low speed (large m)

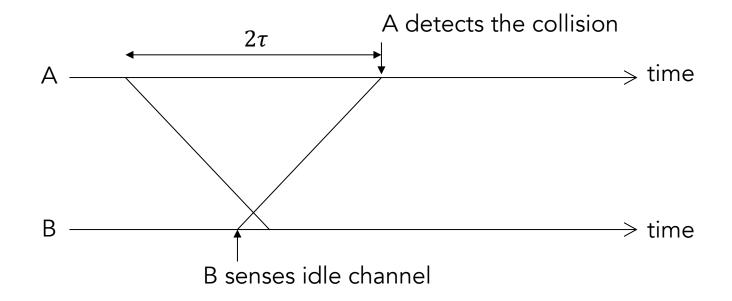






□ Collision

- Suppose that a collision takes place between A's & B's transmission
- In the worst case, it takes  $2\tau$  sec for A & B to detect the collision and turn off their transmissions

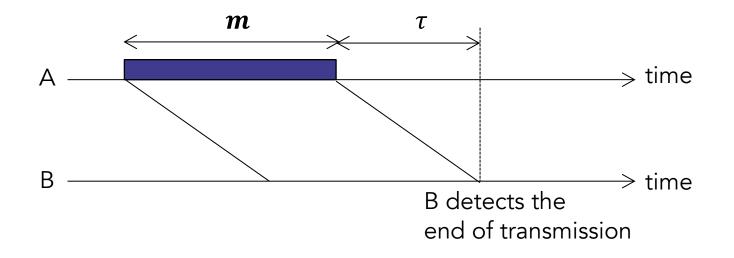






□ Sensing

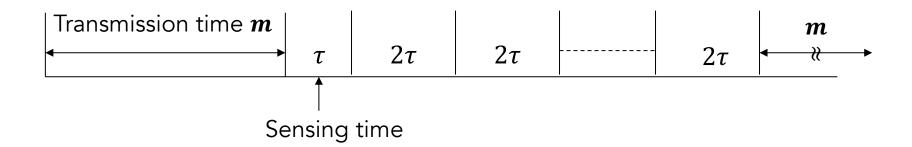
 After A finishes transmission, it takes τ seconds for B to determine that A has finished transmission (idle channel)







Considering intervals for both collision and sensing, we consider  $\tau$  and  $2\tau$  intervals after transmission as follows:



- □ Let J denote the expected number of  $2\tau$  intervals before a successful transmission taking place
  - J depends on the retransmission policy, e.g., binary exponential back-off etc.





 $\square$  Worst-case calculation of transmission time  $t_v$ 

- t<sub>v</sub> is the time interval between two successful transmissions
- Given J collisions, it takes  $2\tau J$  units of time to resolve it

 $t_v = m + \tau + 2\tau J = m(1 + a(1 + 2J)), \text{ where } a = \tau/m$ 

Use a simple model of retransmissions backed by simulation

- Assume length of collision interval is geometrically distributed in units of  $2\tau$ , with parameter  $v = Pr\{no \text{ collision happens}\}$
- Then  $\Pr\{\text{collision interval} = n \cdot 2\tau\} = v(1-v)^{n-1}$

$$J = \sum_{k=1}^{\infty} kv(1-v)^{k-1} = \frac{1}{v}$$

• So we focus on finding *v*.





- Assume n stations are involved
  - Each station attempts to transmit in a 2τ interval with probability p, independent of others
  - $p = \Pr\{A \text{ station wants to transmits in a } 2\tau \text{ interval}\}$ 
    - $v = \Pr\{\text{no collisions happening}\}$ 
      - $= \Pr\{\text{exactly one station transmits}\}$

$$= np(1-p)^{n-1}$$

- $p = \frac{1}{n}$  will maximize v and provides the greatest chances of success
  - $\rightarrow$  maximized  $v \rightarrow$  smallest J
  - → max (worst-case) throughput.





$$\square \text{ Now, by setting } p = \frac{1}{n'} \text{ we obtain that}$$
$$v_{\max} = \left(1 - \frac{1}{n}\right)^{n-1} \to e^{-1}, \text{ as } n \to \infty$$
$$t_v = m(1 + a(1 + 2J)) = m(1 + a(1 + 2e))$$
$$\max \text{ throughput } \lambda_{\max} = \frac{1}{t_v} = \frac{1}{m(1 + a(1 + 2e))}$$

### $\Box \ \, \operatorname{Let} \rho = m \lambda_{\max}$

• Recall  $a = \tau/m$ : transmission time (m) must be much larger than the propagation delay ( $\tau$ ) for system to work well

• If 
$$a=0.1$$
,  $ho<0.6$ 

• If a = 0.01,  $\rho < 0.94$ .





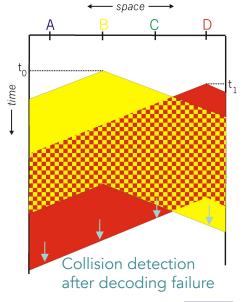
### CSMA/CA

□ Carrier Sense Multiple Access with Collision Avoidance

- Wireless MAC protocols (like Wi-Fi) often use Collision Avoidance with carrier-sense mechanism
- Carrier Sense: When a node wishes to transmit a packet, it first waits until the channel is idle
- Collision avoidance: Use of a random backoff number within the maximum congestion window size

### □ Why not CSMA/CD?

- A wireless station may NOT send data and receive collision signals at the same time
- Collision may NOT be detected in wireless networks
  - Signal fading often prevents a station of one end from hearing a collision at the other end.

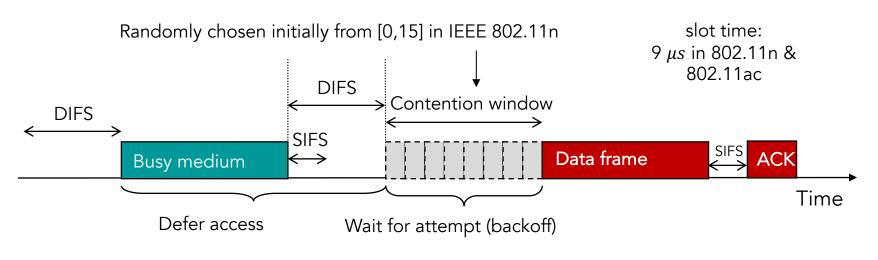




### CSMA/CA (802.11 DCF (distributed coordinate function))

□ Interframe spacing (of Wi-Fi; IEEE 802.11)

- Short IFS (SIFS): Typically to complete exchange in progress (i.e., between data frame and ACK), SIFS is less than DIFS
- DCF IFS (DIFS): Time to detect idle medium
- Backoff time is (contention window) x (slot time)
  - Contention window ( $cw_i$ ) at time slot *i* is chosen randomly from [0, CW[i]-1].
  - CW[i] starts from CW<sub>min</sub> (e.g., 16) and is doubled when collision happens until it grows to  $Cw_{max}$  (e.g., 256, 512, 1024)
  - CW[i] resets to CW<sub>min</sub> when a packet transmission is successful





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## Example of CSMA/CA Backoff

