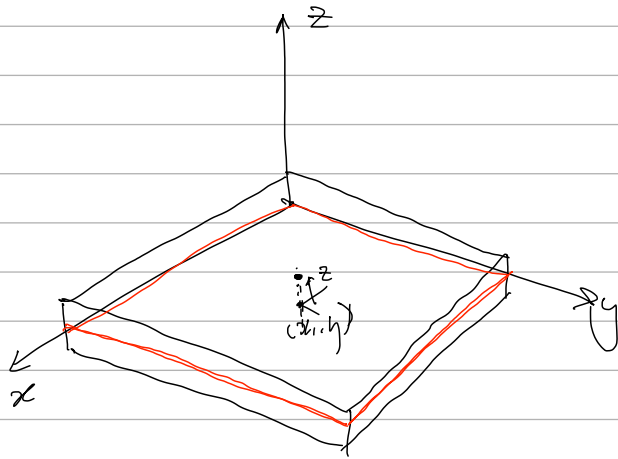


B.4. Plates and shells

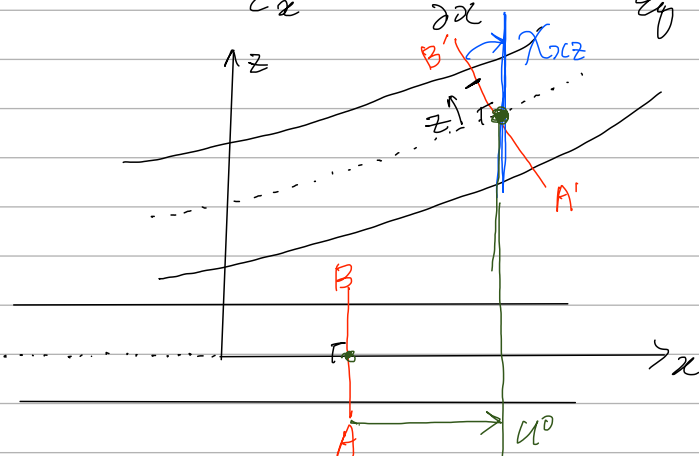
Axial loads : bars, columns
 Torsional : shafts
 Bending : beams



Reference plane ($z=0$)
 \rightarrow Plate's mid-plane

Strains in the reference plane

$$\epsilon_x^0 = \frac{\partial u^0}{\partial x} \quad \epsilon_y^0 = \frac{\partial v^0}{\partial y} \quad \gamma_{xy}^0 = \frac{\partial u^0}{\partial y} + \frac{\partial v^0}{\partial x}$$



Kirchhoff hypothesis : normal to the reference surface remain normal and straight

$$\chi_{xz} = \frac{\partial w^0}{\partial x}$$

$$u = u^0 - z \chi_{xz}$$

$$= u^0 - z \frac{\partial w^0}{\partial x}$$

Similarly

$$v = v^0 - z \frac{\partial w^0}{\partial y}$$

Strain fields

$$\epsilon_x = \frac{\partial u}{\partial x} = \frac{\partial u^0}{\partial x} - z \frac{\partial^2 w^0}{\partial x^2}$$

$$\epsilon_y = \frac{\partial v}{\partial y} = \frac{\partial v^0}{\partial y} - z \frac{\partial^2 w^0}{\partial y^2}$$

$$\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \frac{\partial u^0}{\partial y} + \frac{\partial v^0}{\partial x} - z \frac{2 \partial^2 w^0}{\partial x \partial y}$$

$$\begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix} = \begin{Bmatrix} \epsilon_x^0 \\ \epsilon_y^0 \\ \gamma_{xy}^0 \end{Bmatrix} + z \begin{Bmatrix} \hat{k}_x \\ \hat{k}_y \\ \hat{k}_{xy} \end{Bmatrix}$$

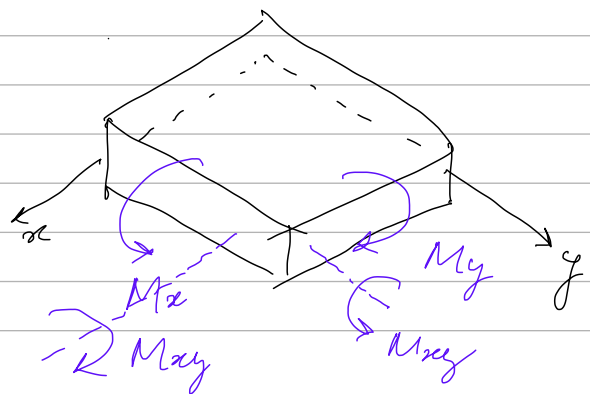
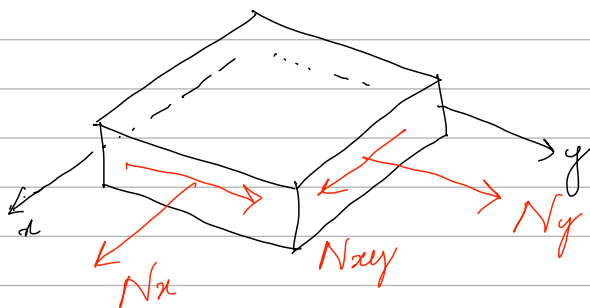
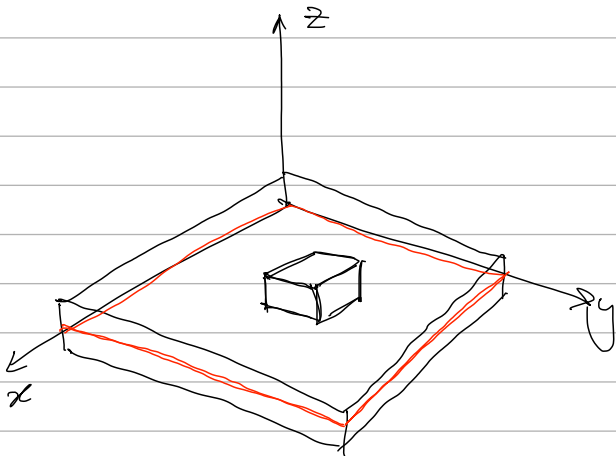
$$\hat{k}_x = -\frac{\partial^2 w^0}{\partial x^2} = -k_x \quad \left(= \frac{\partial^2 w^0}{\partial x^2} \right)$$

$$\hat{k}_y = -\frac{\partial^2 w^0}{\partial y^2} = -k_y$$

$$\hat{k}_{xy} = -\frac{2 \partial^2 w^0}{\partial x \partial y} = -2k_{xy}$$

↑ curvatures of plate

↑ curvatures of surface



$$N_x = \int_{-t/2}^{t/2} \sigma_x dz$$

$$N_y = \int_{-t/2}^{t/2} \sigma_y dz$$

$$N_{xy} = \int_{-t/2}^{t/2} \tau_{xy} dz$$

in-plane forces
per unit length

$$M_x = \int_{-t/2}^{t/2} z \cdot \sigma_x dz$$

$$M_y = \int_{-t/2}^{t/2} z \cdot \sigma_y dz$$

$$M_{xy} = \int_{-t/2}^{t/2} z \cdot \tau_{xy} dz$$

in-plane moments
per unit length

Plate theory

$$\begin{bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{bmatrix} = \begin{bmatrix} A & B \\ B & D \end{bmatrix} \begin{bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \\ \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{bmatrix}$$

[A] : in-plane stiffness

[D] : bending stiffness

[B] : in-plane & out-of-plane coupling stiffness
(bending - extension coupling stiffness)

B.5.1. Isotropic plate under plane stress

$$\begin{Bmatrix} \underline{\varepsilon_x} \\ \underline{\varepsilon_y} \\ \underline{\gamma_{xy}} \end{Bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & 0 \\ -\nu & 1 & 0 \\ 0 & 0 & \frac{E}{G} \end{bmatrix} \begin{Bmatrix} \underline{\sigma_x} \\ \underline{\sigma_y} \\ \underline{\tau_{xy}} \end{Bmatrix}$$

compliance matrix

$\frac{E}{G} \rightarrow 2(1+\nu)$

$G = \frac{E}{2(1+\nu)}$

$$\begin{aligned} \nu \varepsilon_x &= \frac{1}{E} (\sigma_x - \nu \sigma_y) \cdot \nu \\ \varepsilon_y &= \frac{1}{E} (-\nu \sigma_x + \sigma_y) \end{aligned}$$

$$\nu \varepsilon_x + \varepsilon_y = \frac{1-\nu^2}{E} \sigma_y$$

$$\rightarrow \sigma_y = \frac{E}{1-\nu^2} (\nu \varepsilon_x + \varepsilon_y)$$

stiffness matrix

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{Bmatrix}$$

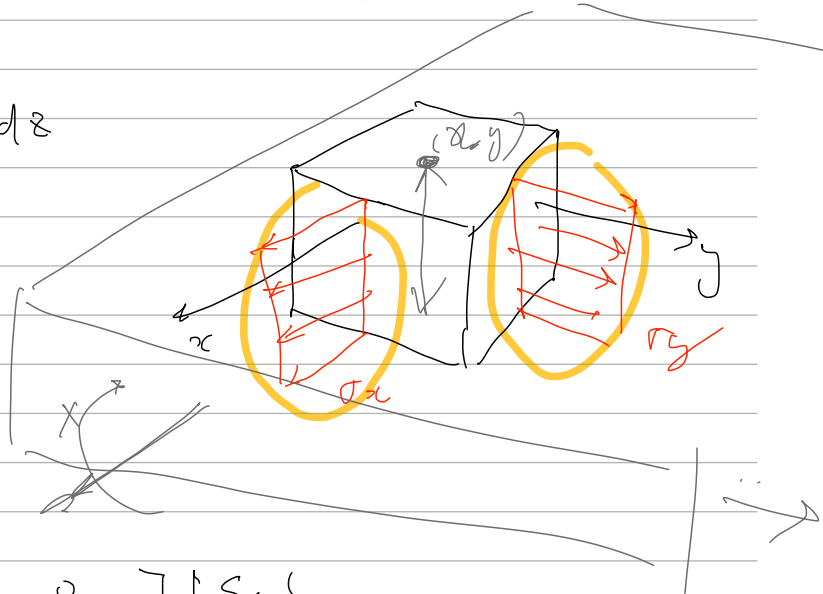
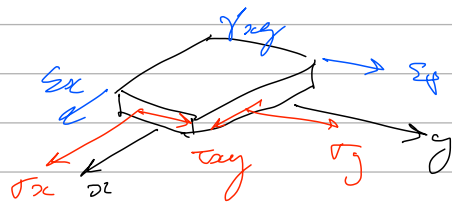
$$N_x = \int_{-t/2}^{t/2} \sigma_x dz$$

$$= \int_{-t/2}^{t/2} \frac{E}{1-\nu^2} (\varepsilon_x + \nu \varepsilon_y) dz$$

$$= \frac{E t}{1-\nu^2} (\varepsilon_x + \nu \varepsilon_y)$$

$$N_y = \quad -$$

$$N_{xy} = \quad -$$



$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \end{Bmatrix} = \frac{E t}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{Bmatrix}$$

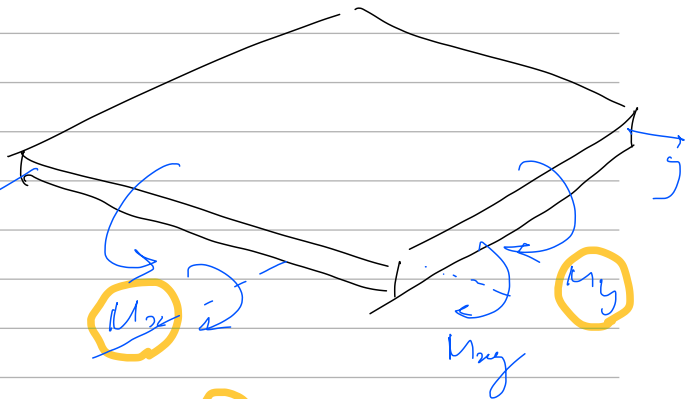
if $\nu = \frac{1}{3}$

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \end{Bmatrix} = \frac{9}{8} E t \begin{bmatrix} 1 & \frac{1}{3} & 0 \\ \frac{1}{3} & 1 & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \begin{Bmatrix} \epsilon_x \\ \epsilon_y \\ \gamma_{xy} \end{Bmatrix}$$

[A] matrix

$$M_x = \int_{-t/2}^{t/2} z \sigma_x dz$$

$$= \int_{-t/2}^{t/2} z \frac{E}{1-\nu^2} (z \hat{\epsilon}_x + \nu z \hat{\epsilon}_y) dz$$



$$\begin{pmatrix} \begin{Bmatrix} N_x \\ N_y \\ N_{xy} \end{Bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} z \hat{\epsilon}_x \\ z \hat{\epsilon}_y \\ z \hat{\epsilon}_{xy} \end{Bmatrix} \end{pmatrix}$$

Kx, Ky, Kxy?

$$= \frac{E}{1-\nu^2} \left[(\hat{\epsilon}_x + \nu \hat{\epsilon}_y) \int_{-t/2}^{t/2} z^2 dz \right]$$

$$= \frac{E}{1-\nu^2} \left[(\hat{\epsilon}_x + \nu \hat{\epsilon}_y) \cdot \frac{z^3}{3} \Big|_{-t/2}^{t/2} \right]$$

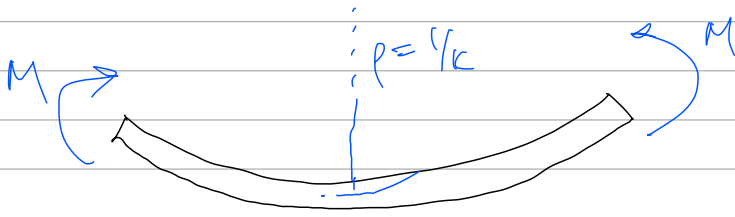
$$M_x = \frac{E t^3}{12(1-\nu^2)} (\hat{\epsilon}_x + \nu \hat{\epsilon}_y)$$

[D] matrix

$$\begin{Bmatrix} M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \frac{E t^3}{12(1-\nu^2)} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{Bmatrix} \hat{\epsilon}_x \\ \hat{\epsilon}_y \\ \hat{\epsilon}_{xy} \end{Bmatrix}$$

$$\begin{Bmatrix} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_{xy} \end{Bmatrix} = \begin{bmatrix} \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} & 0 \\ 0 & \frac{E t^3}{12(1-\nu^2)} \end{bmatrix} \begin{Bmatrix} \hat{\epsilon}_x \\ \hat{\epsilon}_y \\ \hat{\epsilon}_{xy} \\ \hat{\epsilon}_x \\ \hat{\epsilon}_y \\ \hat{\epsilon}_{xy} \end{Bmatrix}$$

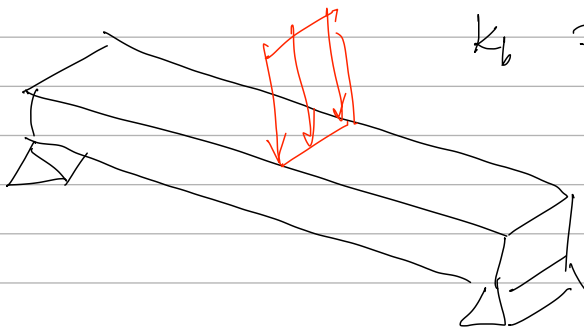
c-f. Euler beam theory



$$k = \frac{\text{loading } M}{\text{material } E \cdot \text{geometry } I}$$

$$M = \frac{E t^3}{12(1-\nu^2)} \hat{k}_x$$

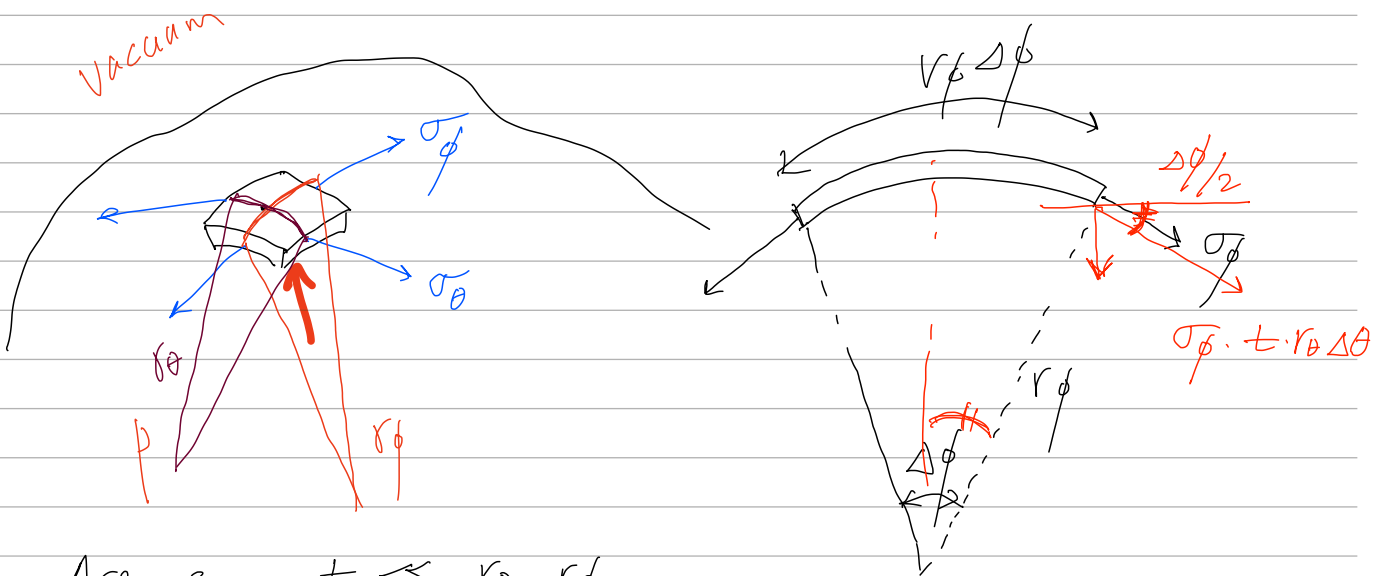
$$\hat{k}_x = \frac{M \cdot b (1-\nu^2)}{E \cdot \frac{5t^3}{12}}$$



$$k_b \approx k_p \times 1.1$$



B.6. Equilibrium equations for shells



Assume $t \ll r_\theta, r_\phi$

$$p \cdot r_\phi \Delta\phi \cdot r_\theta \Delta\theta - [\sigma_\phi t r_\theta \Delta\theta \cdot \sin \frac{\Delta\phi}{2}] \times 2$$

$$- [\sigma_\theta t r_\phi \Delta\phi \cdot \sin \frac{\Delta\theta}{2}] \times 2 = 0$$

$$\Delta\phi, \Delta\theta \approx 0 \rightarrow \sin \frac{\Delta\phi}{2} \approx \frac{\Delta\phi}{2} \quad \sin \frac{\Delta\theta}{2} \approx \frac{\Delta\theta}{2}$$

$$p r_\phi r_\theta \Delta\phi \Delta\theta = \sigma_\phi t r_\theta \Delta\theta \Delta\phi + \sigma_\theta t r_\phi \Delta\theta \Delta\phi$$

$$\frac{p}{t} = \frac{\sigma_\phi}{r_\phi} + \frac{\sigma_\theta}{r_\theta} \quad : \text{Membrane equation}$$

$$\left(N_\phi = \int \sigma_\phi dz = \sigma_\phi \cdot t, \quad N_\theta = \sim \right)$$

$$p = \frac{N_\theta}{r_\theta} + \frac{N_\phi}{r_\phi}$$

$$\rightarrow p \ll \sigma_\phi, \sigma_\theta$$

