

Last lecture

Rigid body motion \rightarrow linear \vec{a}
rotational $\vec{\alpha}$

isobar ($p = \text{constant}$) $\perp \nabla p$

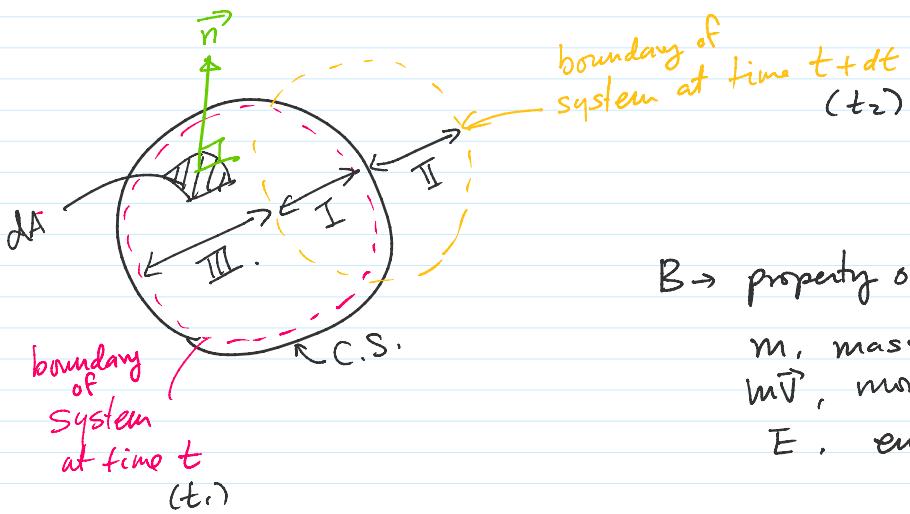
Reynolds Transport Theorem \rightarrow enables application of
(RTT) conservations (for Lagrangian system)
to control volume (Eulerian view)

Today: RTT
mass conservation to C.V.
momentum " "

Test #1 Oct 14 in class offline \Rightarrow will cover what we covered up to Oct?

RTT.

C.V. fixed
in space.



B \rightarrow property of system. $B = \frac{d\mathbf{B}}{dm}$

m, mass

$m\vec{V}$, momentum

E, energy

$\frac{1}{V}$

System

$$B \text{ at } t_1, B_{I,t_1} + B_{III,t_1}$$

$$B \text{ at } t_2, B_{I,t_2} + B_{II,t_2}$$

$$\frac{dB_{\text{system}}}{dt} = \frac{DB}{Dt} = \lim_{\substack{(t_2-t) \rightarrow 0 \\ \Delta t}} \frac{B_{I,t_2} + B_{III,t_2} - (B_{I,t_1} + B_{III,t_1})}{(t_2 - t_1)}$$

$$= \lim_{\Delta t \rightarrow 0} \frac{B_{I,t_2} + B_{III,t_2} - (B_{I,t_1} + B_{III,t_1}) + B_{II,t_2} - B_{II,t_1}}{\Delta t}$$

amount of B which has left C.V.
amount of B which came into C.V.

$$= \frac{dB_{\text{C.V.}}}{dt} + \frac{B_{II,t_2} - B_{II,t_1}}{\Delta t}$$

Reynolds Transport Theorem

$$\frac{dB_{\text{system}}}{dt} = \frac{DB}{Dt} = \frac{d}{dt} \int_{\text{C.V.}} \beta \rho dV + \int_{\text{C.S.}} \beta \rho (\vec{V} \cdot \vec{n}) dA$$

$$B_{\text{C.V.}} = \int_{\text{C.V.}} \beta \rho dV$$

$$\frac{d\beta_{\text{system}}}{dt} = \frac{DB}{Dt} = \frac{d}{dt} \int_{c.v.} \beta \rho dV + \int_{C.S.} \beta \rho (\vec{v} \cdot \vec{n}) dA$$

$$B_{c.v.} = \int_{c.v.} B \rho dV$$

$$1. \frac{Dm}{Dt} = 0$$

Rate of change in system's B.

$$2. \frac{D(\vec{m}^j)}{Dt} = \vec{\epsilon F}$$

$$3. \frac{DE}{Dt} = \dot{Q} - \dot{W}$$

Rate of change in B inside C.V.

Flux of B
into and out of C.V.

Question

$$\int_{c.s.} \beta \varrho(\vec{r},\vec{n}) dA \quad ?$$

$$\text{Net Volume flow rate} = \int_{C.S.} (\vec{V} \cdot \vec{n}) dA = Q$$

$$\underline{\text{Mass flow rate}} = \int_{\text{S.E.}} \varphi (\vec{J} \cdot \vec{n}) dA = \dot{m}$$

$$\text{Net flux of } B = \int_{\text{c.s.}} B \cdot \vec{f}(\vec{v} \cdot \vec{n}) dA$$

\vec{n} = unit normal vector pointing outward from dA
 \hookrightarrow (perpendicular to dA)

IT IS VERY IMPORTANT TO CLEARLY SHOW THE C.V. THAT YOU CHOOSE

Mass conservation.

$$\frac{Dm}{Dt} = \frac{d}{dt} \int_{c.v.} \varphi dVol + \int_{c.s.} \varphi (\vec{V} \cdot \vec{n}) dA$$

examples:

The diagram illustrates Bernoulli's principle for fluid flow around a circular cylinder. The flow is from left to right, as indicated by the velocity vector V_1 at the inlet. The fluid passes around the cylinder, which is labeled with a circled '1'. At the exit, the velocity is V_2 . The cross-sectional area at the inlet is A_1 , and at the exit, it is A_2 . The pressure is shown as P_1 at the inlet and P_2 at the exit. The Bernoulli equation is applied along a vertical line through the center of the cylinder, showing that the total head (sum of pressure and kinetic energy) remains constant across the flow field.

Assumptions.

- ## 1. Steady

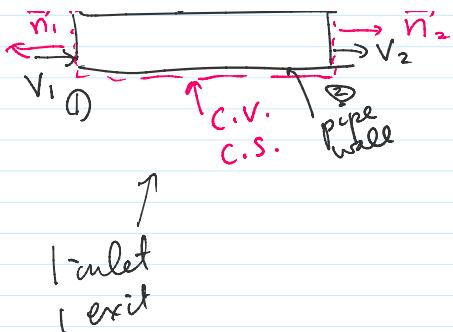
3. no leakage thru
wall ($\vec{V} \cdot \vec{n} = 0$)

2. 1-D (velocity has one component)

$$\frac{Dm}{Dt} = \rho = \frac{d}{dt} \int_{c.v.} \varphi dV_0 + \int_{c.s.} \varphi (\vec{v} \cdot \vec{n}) dA$$

$$0 = \int_A \rho V_2 dA_2 - \int_{A_1} \rho V_1 dA_1 + \int_W \rho (V_W n_W) dA_W$$

$$\dot{m}_1 = \dot{m}_2 = \varphi V A$$



$$\therefore \dot{m}_1 = \dot{m}_2 = \rho V A$$

$\dot{m}_1 = \dot{m}_2$ $V = \text{constant}$

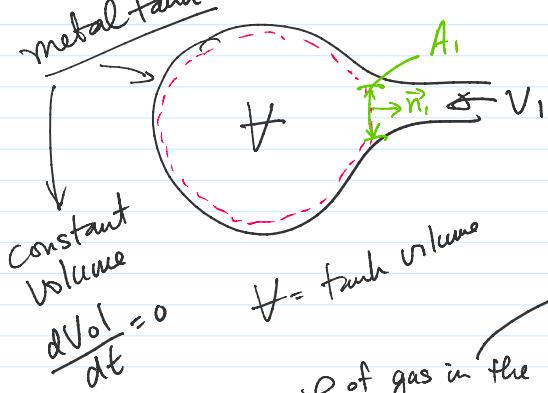
$Q_1 = Q_2 \quad \text{if } \rho = \text{constant.}$

$V_1 = V_2 \quad \text{if } A_1 = A_2$

examples with multiple inlets & exits

example: filling a tank with gas.

1. Uniform velocity at I



$$\frac{Dm}{Dt} = 0 = \frac{d}{dt} \int_{C.V.} \rho dV_0 + \int \rho (\vec{v} \cdot \vec{n}) dA$$

$$O = \frac{d}{dt} \int_{C.V.} \rho dVol - \rho, V, A,$$

$$\frac{df}{dt} = \frac{f_1 V_1 A_1}{t}$$

Unsteady problem

Momentum Conservation for a fixed C.V.

$$\underline{B = m\vec{v}}$$

$$\beta = \vec{v}$$

$$\frac{D(m\vec{V})}{Dt} = \vec{\varepsilon}_F = \frac{d}{dt} \left[\int_{c.v.} \varphi \vec{V} dVol \right] + \int_{c.s.} \varphi \vec{V} (\vec{V} \cdot \vec{n}) dA.$$

\vec{V} → absolute velocity in fixed frame.

$$\vec{F} = \vec{F}_B + \vec{F}_P + \vec{F}_C + \vec{F}_{\text{solid}}$$

\vec{F} \vec{F}_B + \vec{F}_P + \vec{F}_C + \vec{F}_{solid}

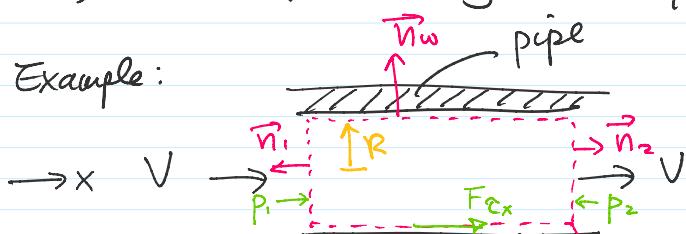
↑ ↑ ↓ ↓

body pressure shear.

F_{solid} if C.V. cuts through a solid surface.

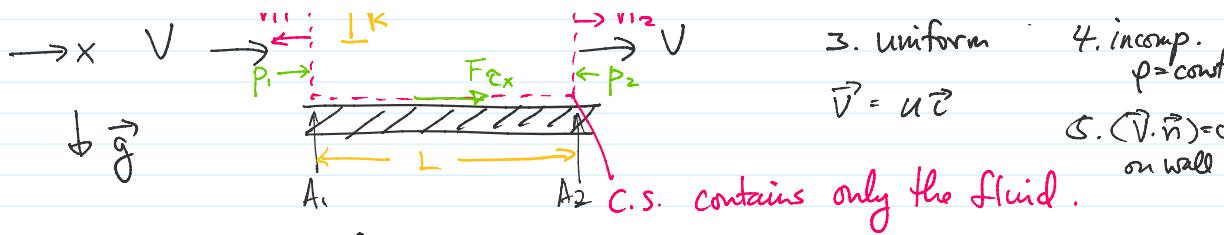
External forces acting on the system contained in the C.V.

Example:



Assumptions

1. steady
 2. $I - D \rightarrow \cancel{\star} \cancel{\star}$
 3. uniform
 4. incomp.
 $\rho = \text{const.}$
 $\vec{U} = u \vec{r}$



$$\sum F_x = F_{px} + F_{2x} + F_{gx} = \frac{d}{dt} \int \rho u dV_{\text{vol}} + \int \rho u (\vec{v} \cdot \vec{n}) dA$$

assume shear force acts in $+x$ dir.

$$P_1 A_1 - P_2 A_2 + F_{gx} = \int_{A_2} \rho V_2^2 dA - \int_{A_1} \rho V_1^2 dA = \dot{m}_2 V_2 - \dot{m}_1 V_1$$

shear force
by the
wall on
fluid

$$\text{but } \frac{Dm}{Dt} = 0 \Rightarrow \dot{m}_2 = \dot{m}_1 = \dot{m}$$

$$Q_2 = Q_1$$

$$\therefore \underline{P_1 A_1 - P_2 A_2 + F_{gx}} = \dot{m} (V_2 - V_1)$$

Now if assume 5. $A_1 = A_2 \rightarrow V_2 = V_1$

$$6. \frac{\partial V}{\partial x} = 0 \quad (\text{fully developed flow})$$

7. far away from inlet/exit

8. circular pipe with radius R
and C.V. length L

then

$$\underline{(P_1 - P_2) A + \tau 2\pi R L = 0}$$

$$\underbrace{\frac{P_1 - P_2}{L} = -\frac{2\tau}{R}}_{> 0}$$

because flow goes from 1 to 2, $P_1 > P_2$

therefore $\underline{\tau < 0}$. \rightarrow shear stress acts in direction opposite to the assumed direction.

Last lecture

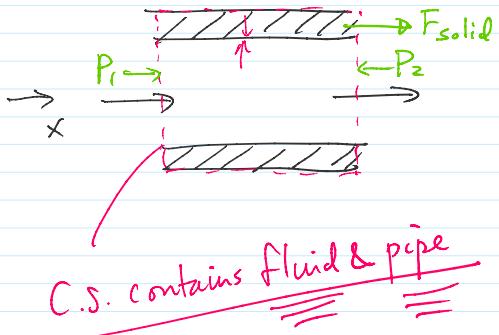
Reynolds Transport Theory (RTT)

Mass conservation
Momentum conservationHW #3 3 - 7, 9, 14, 18, 25, 35
45, 49, 55

Due Oct. 5

Test #1 Oct. 14 in-class OFFLINE!

Continuation from previous lecture

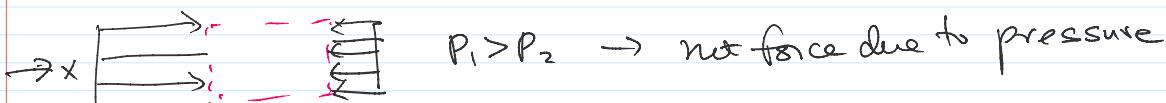
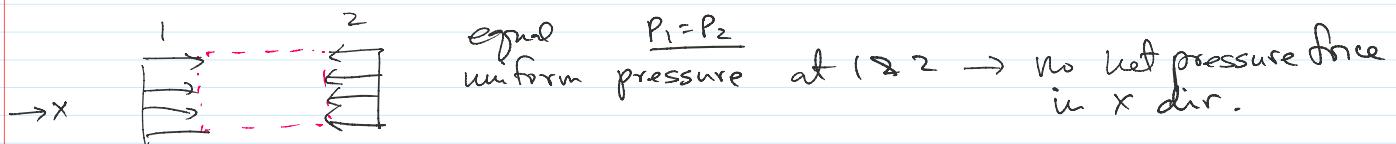
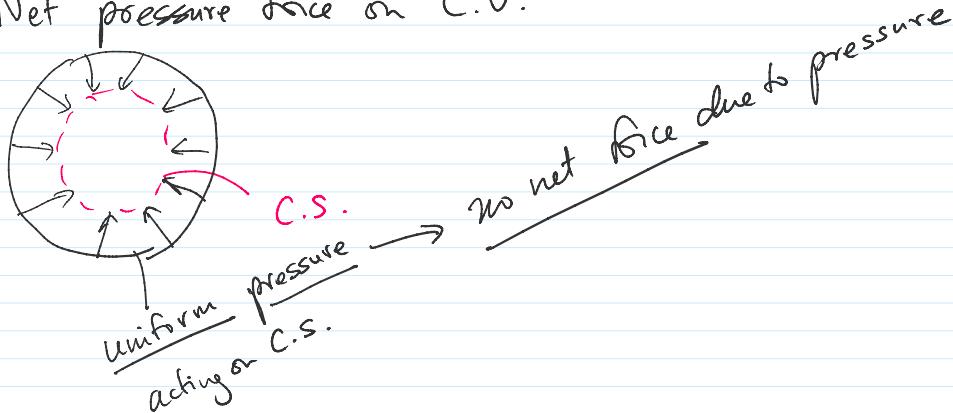


This time, C.V. contains pipe & fluid.

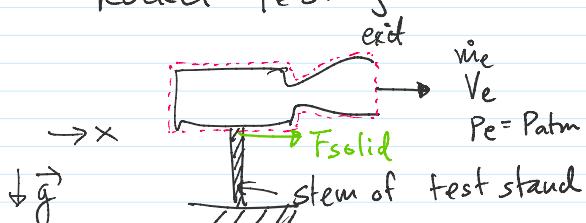
∴ Forces acting on system inside the C.V.

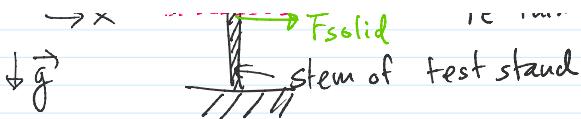
$$P_1 A_1 - P_2 A_2 + F_{solid} = \dot{m}(V_2 - V_1)$$

Net pressure force on C.V.



Rocket testing.

uniform pressure on C.S. → no net pressure force
no shear force



static rocket firing test

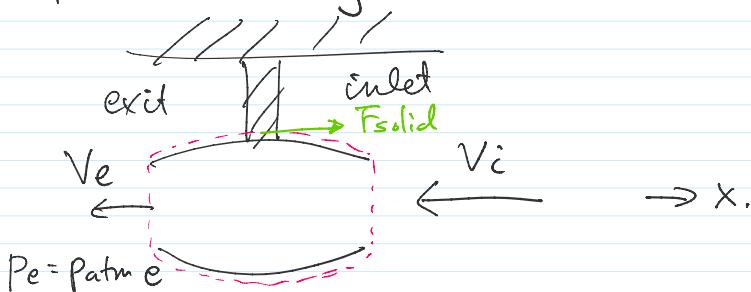
2.

$$\sum \vec{F} = F_{\text{solid}} = \frac{d}{dt} \int_{\text{c.v.}} \rho \vec{V} dV_{\text{vol}} + \int \rho \vec{V} (\vec{V} \cdot \vec{n}) dA$$

- Assume
1. 1-D (x dir)
2. steady

rocket thrust $F_{\text{solid}} = \dot{m}_e V_e$

Gas turbine testing

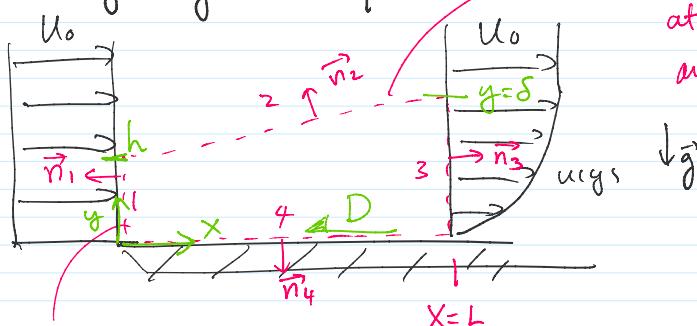


No net pressure force
shear force.

$$F_{\text{solid}} = -\dot{m}_e V_e + \dot{m}_i V_i$$

\uparrow momentum going out at exit \uparrow momentum coming into inlet

Boundary layer analysis.



choose the streamline at $y = h$ at $x = 0$ and at $y = \delta$ at $x = L$

b = depth into the page.

δ = boundary layer thickness.

C.S.: surface 2 \rightarrow streamline

Contains only the fluid.

drag due to shear stress on fluid by plate

Assume

1. Uniform p. $\frac{\partial p}{\partial x} = \frac{\partial p}{\partial y} = 0$ 3. steady
2. viscous. 4. incomp

$$\sum \vec{F} = \vec{F}_P + \vec{F}_{\text{body}} - D = \frac{d}{dt} \int_{\text{c.v.}} \rho \vec{V} dV_{\text{vol}} + \int \rho \vec{V} (\vec{V} \cdot \vec{n}) dA$$

$$-D = \int_{(1)} + \int_{(2)} + \int_{(3)} + \int_{(4)} = -\rho U_0^2 b h + \rho b \int_0^\delta u^2 dy. \quad (1)$$

mass conservation

$$\int_{\text{c.v.}} \rho u dy = \text{constant}$$

velocity ($\frac{m}{s}$)

100%

mass conservation

$$D = \rho b U_0^2 \int_0^\delta \frac{u}{U_0} \left(1 - \frac{u}{U_0}\right) dy.$$

von Karman 1921
(2)

force (N)

velocity ($\frac{m}{s}$)

$h?$

θ momentum thickness

Powerful: Can estimate force from velocity.

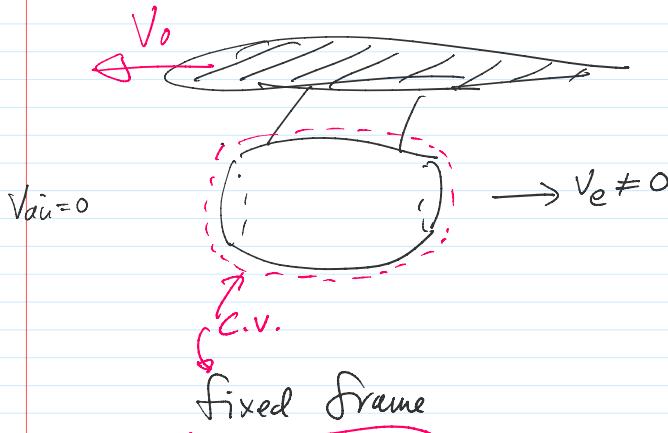
mass: $\frac{Dm}{Dt} = 0 = \frac{d}{dt} \int_{C.V.}^0 \rho \Delta V \Omega + \int_{C.S.} \rho (\vec{v} \cdot \vec{n}) dA = \int_0 + \int_{\theta} + \int_{\theta} + \int_{\theta}$

$$0 = \int_0^\delta \cancel{\rho u b} dy - \cancel{\rho u b h}$$

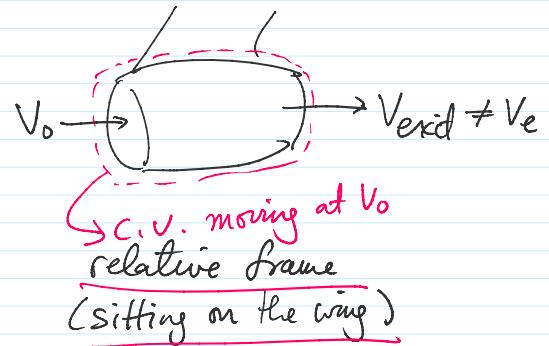
$\rho h = \int_0^\delta u dy.$

mass conservation

Momentum theorem referred to coordinate moving at constant velocity.



unsteady in fixed frame.



steady in relative frame.

