

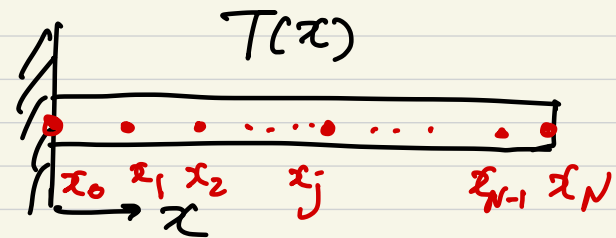
Banded matrix

diff'l eq. $\xrightarrow{\text{numerical method}}$ system of algebraic eqs.

① ODE (ordinary diff'l eq.)

$$\frac{d^2 T}{dx^2} - \alpha^2 T = Q(x)$$

↑ internal source



Introduce a discrete set of points x_j , $j=0, 1, 2, \dots, N$
↳ grid points

Find $T(x_j)$ or T_j .

• Finite difference method (FDM)

Taylor series expansion $h_j = x_{j+1} - x_j$: grid spacing

$h = h_1 = h_2 \dots$: uniform grid spacing

$$T(x_{j+h}) = T(x_j) + h \frac{dT}{dx} \Big|_j + \frac{1}{2} h^2 \frac{d^2 T}{dx^2} \Big|_j + \frac{1}{6} h^3 \frac{d^3 T}{dx^3} \Big|_j + \frac{1}{24} h^4 \frac{d^4 T}{dx^4} \Big|_j + \dots$$

$$- \left[T(x_{j-1}) = \text{"} - \text{"} + \text{"} - \text{"} + \text{"} \dots \right]$$

$$\Rightarrow T(x_{j+h}) - T(x_{j-1}) = 2h \frac{dT}{dx} \Big|_j + \frac{1}{3} h^3 \frac{d^3 T}{dx^3} \Big|_j + \dots$$

$$\Rightarrow \boxed{\frac{dT}{dx} \Big|_j = \frac{T(x_{j+h}) - T(x_{j-1})}{2h}} - \frac{1}{6} h^2 \frac{d^3 T}{dx^3} \Big|_j + \dots$$

↑
Second-order FDM

leading error term $\mathcal{O}(h^2)$

$$+ \left[\begin{array}{c} \text{"} \\ \text{"} \end{array} \right]$$

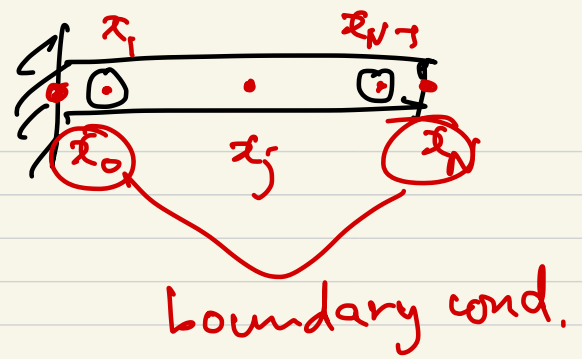
$$T(x_{j+h}) + T(x_{j-1}) = 2T(x_j) + h^2 \frac{d^2 T}{dx^2} \Big|_j + \frac{1}{12} h^4 \frac{d^4 T}{dx^4} \Big|_j + \dots$$

$$\Rightarrow \boxed{\frac{d^2 T}{dx^2} \Big|_j = \frac{T(x_{j+h}) - 2T(x_j) + T(x_{j-1}))}{h^2}} - \frac{1}{12} h^2 \frac{d^4 T}{dx^4} \Big|_j + \dots$$

• Second-order FDM

leading error term $\mathcal{O}(h^2)$

→ Substitute this into diff'l eq.



$$\textcircled{a} \quad j, \begin{cases} \frac{T_{j+1} - 2T_j + T_{j-1}}{h^2} - \alpha^2 T_j = Q_j, & \bullet \\ T_0 = 0 & \bullet \\ T_N = S & \bullet \end{cases} \quad j=1, 2, \dots, N-1$$

System of algebraic eqs.

$$\rightarrow \begin{cases} T_{j+1} - (2 + h^2 \alpha^2) T_j + T_{j-1} = h^2 Q_j \\ T_0 = 0 \\ T_N = S \end{cases}$$

$$j=1: T_2 - (2 + h^2 \alpha^2) T_1 + \underbrace{T_0}_0 = h^2 Q_1 \quad \bullet$$

$$j=2: T_3 - (\quad " \quad) T_2 + T_1 = h^2 Q_2$$

⋮

$$j=N-1: \underbrace{T_N}_S - (\quad " \quad) T_{N-1} + T_{N-2} = h^2 Q_{N-1}$$

$$\begin{bmatrix}
 -(2+h^2d^2) & 1 & 0 & \dots & 0 \\
 1 & -(2+h^2d^2) & 1 & 0 & \dots & 0 \\
 \dots & \dots & 1 & -(2+h^2d^2) & 1 & 0 & \dots & 0 \\
 0 & \dots & \dots & 0 & 1 & -(2+h^2d^2)
 \end{bmatrix}
 \begin{bmatrix}
 T_1 \\
 T_2 \\
 \vdots \\
 T_j \\
 \vdots \\
 T_{N-1}
 \end{bmatrix}
 =
 \begin{bmatrix}
 h^2Q_1 \\
 h^2Q_2 \\
 \vdots \\
 h^2Q_j \\
 \vdots \\
 h^2Q_{N-1} - f
 \end{bmatrix}$$

tri-diagonal matrix $Ax = b$

banded matrix : non-zero elements only around the main diagonal.

↳ arises from FDM of diff'l eqs.

tri-diagonal matrix : $B[a_i, b_i, c_i]$

$$a_i = 1, b_i = -(2+h^2d^2), c_i = 1$$

↖ Sparse matrix

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix} \quad \begin{matrix} \begin{matrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{matrix} \\ \times \end{matrix}$$

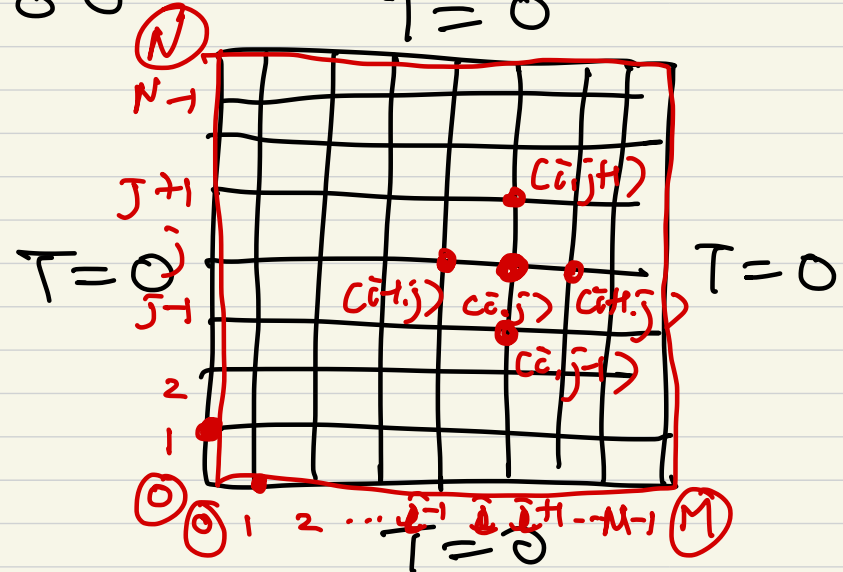
$T=0$

② PDE (partial diff eq.)

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = Q(x,y)$$

↑
internal source

$$\begin{aligned} \Delta x_i &= \Delta x_i \\ x_{i+1} - x_i &= h \\ y_{j+1} - y_j &= h \end{aligned} \quad \left. \begin{array}{l} \text{uniform} \\ \text{grid spacings} \end{array} \right\}$$



2nd-order FDM

$$\frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{h^2} + \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{h^2} = Q_{i,j}$$

$i=1, 2, \dots, M-1$
 $j=1, 2, \dots, N-1$

$(M-1) \times (N-1)$

$$\rightarrow T_{\bar{i}+1, \bar{j}} - 4T_{\bar{i}, \bar{j}} + T_{\bar{i}-1, \bar{j}} + T_{\bar{i}, \bar{j}+1} + T_{\bar{i}, \bar{j}-1} = h^2 Q_{\bar{i}, \bar{j}}$$

$$M = 4$$

$$\bar{i}=1, \bar{j}=1: \underline{T_{2,1}} - 4\underline{T_{1,1}} + \overset{0}{\circ} \underline{T_{0,1}} + \underline{T_{1,2}} + \overset{0}{\circ} \underline{T_{1,0}} = h^2 Q_{1,1}$$

$$N = 4$$

$$\bar{i}=2, \bar{j}=1: \underline{T_{3,1}} - 4\underline{T_{2,1}} + \underline{T_{1,1}} + \underline{T_{2,2}} + \overset{0}{\circ} \underline{T_{2,0}} = h^2 Q_{2,1}$$

⋮

$$\bar{i}=3, \bar{j}=3: \overset{0}{\circ} \underline{T_{4,3}} - 4T_{3,3} + T_{2,3} + \overset{0}{\circ} \underline{T_{3,4}} + T_{3,2} = h^2 Q_{3,3}$$

9 unknowns

$T_{1,1} \dots T_{3,3}$

$$\Rightarrow \begin{bmatrix} -4 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -4 & 1 & 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -4 & 0 & 0 & 1 & 0 & 0 & 0 \\ \hline 1 & 0 & 0 & -4 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & -4 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -4 & 0 & 0 & 1 \\ \hline 0 & 0 & 0 & 1 & 0 & 0 & -4 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & -4 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & -4 \end{bmatrix} \begin{bmatrix} T_{1,1} \\ T_{2,1} \\ T_{3,1} \\ \hline T_{1,2} \\ T_{2,2} \\ T_{2,3} \\ \hline T_{1,3} \\ T_{2,3} \\ T_{3,3} \end{bmatrix} = \begin{bmatrix} h^2 Q_{1,1} \\ h^2 Q_{2,1} \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ h^2 Q_{3,3} \end{bmatrix}$$

Block-tridiagonal matrix

$$\begin{pmatrix} B_1 & C_1 & 0 & \dots & 0 \\ A_2 & B_2 & C_2 & 0 & \dots & 0 \\ & & \ddots & \ddots & \ddots & \\ 0 & & & \ddots & \ddots & \\ & & & & & 0 \end{pmatrix}$$

⑤ Solution technique

• diagonal matrix

$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

• lower triangular matrix

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} \quad \downarrow$$

• upper triangular matrix

$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} \quad \uparrow$$

* Gauss elimination (GE) : to make upper triangular matrix

$$\begin{cases} 4x_2 - x_3 = 5 \\ x_1 + x_2 + x_3 = 6 \\ 2x_1 - 2x_2 + x_3 = 1 \end{cases} \rightarrow \begin{pmatrix} 0 & 4 & -1 \\ 1 & 1 & 1 \\ 2 & -2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 5 \\ 6 \\ 1 \end{pmatrix}$$

Interchange the first two rows.

$$\rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 4 & -1 \\ 2 & -2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 6 \\ 5 \\ 1 \end{pmatrix}$$

Subtract twice the first row from last row.

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 4 & -1 \\ 0 & -4 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 6 \\ 5 \\ -11 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 4 & -1 \\ 0 & 0 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 6 \\ 5 \\ -6 \end{pmatrix}$$

Stop of GE

or, augmented matrix x

$$\begin{pmatrix} 0 & 4 & -1 & | & 5 \\ 1 & 1 & 1 & | & 6 \\ 2 & -2 & 1 & | & 1 \end{pmatrix}$$

GE

$$\begin{pmatrix} 1 & 1 & 1 & | & 6 \\ 0 & 4 & -1 & | & 5 \\ 0 & 0 & -2 & | & -6 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & | & 6 \\ 0 & 4 & 0 & | & 8 \\ 0 & 0 & -2 & | & -6 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & | & 6 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & | & 1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 3 \end{pmatrix}$$

→ $x_1 = 1, x_2 = 2, x_3 = 3$

"Gauss-Jordan elimination"

• General matrix system

$$Ax = b$$

$n \times n$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}$$

GE

To eliminate a_{21} , $d_2 = a_{21}/a_{11}$
 multiply the first row by d_2 , and subtract from 2nd row.
 Continue until all elts. below a_{11} are eliminated.

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a'_{22} & \dots & a'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a'_{n2} & \dots & a'_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b'_2 \\ \vdots \\ b'_n \end{pmatrix}$$

By same way (we drop ') for convenience)

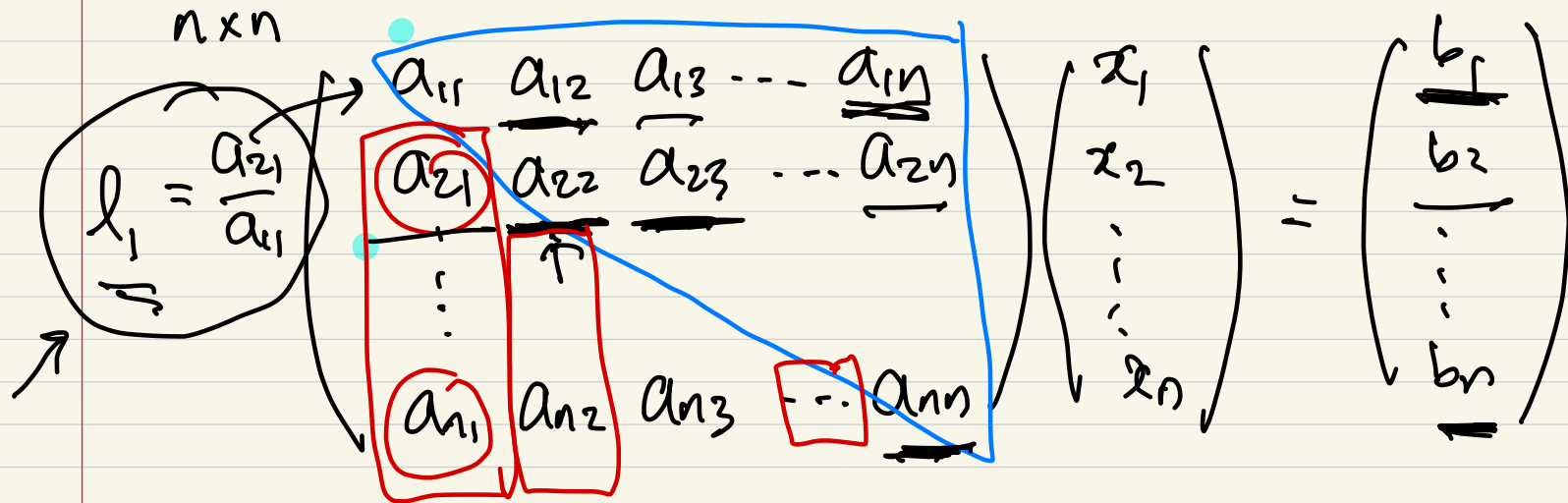
$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad \uparrow \text{step of GE}$$

backward sweep

$$\begin{cases} x_n = b_n / a_{nn} \\ x_{n-1} = (b_{n-1} - a_{n-1,n} x_n) / a_{n-1,n-1} \\ x_j = (b_j - \sum_{k=j+1}^n a_{jk} x_k) / a_{jj} \quad j = n-1, n-2, \dots, 1 \end{cases}$$

① Operation counts for obtaining solution of $Ax=b$

$Ax=b$ A : full matrix



GE: To eliminate $a_{21} : 1 \text{ } \oplus$, nM , nA

To " the first col. : $(n-1) \text{ } \oplus$, $n(n-1)M$, $n(n-1)A$

To " " second " : $(n-2) \text{ } \oplus$, $(n-1)(n-2)M$,

\vdots : $(n-1)(n-2)A$

To " " $(n-1)^{\text{th}}$ col. : $1 \text{ } \oplus$, $1 \cdot 2M$, $2A$

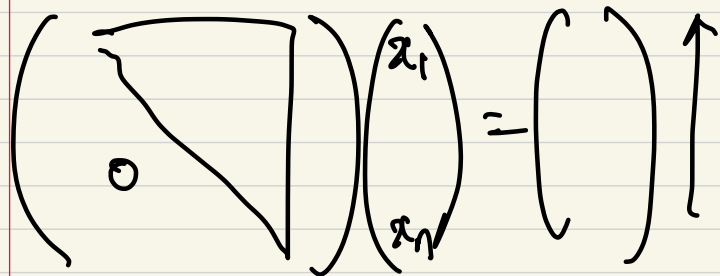
Total divisions : $\sum_{k=1}^{n-1} k = \frac{1}{2}n(n-1)$

total multiplications: $\sum_{k=1}^{n-1} k(k+1) = \frac{1}{3}(n^3 - n)$

$\Rightarrow \frac{1}{2} n(n-1) \text{ } \mathcal{O}(n^2/2)$, $\frac{1}{3}(n^3 - n) \text{ } \mathcal{O}(n^3/3)$, $\frac{1}{3}(n^3 - n) \text{ } \mathcal{O}(\sum_{k=1}^{n-1} k^2 = \frac{1}{6}n(n+1)(2n+1))$

\Rightarrow Gauss elimination requires $\mathcal{O}(n^3/3)$ $\mathcal{O}(n^3)$

Backward sweep



$$x_n = b_n / a_{nn}$$

$$x_j = (b_j - \sum_{k=j+1}^n a_{jk} x_k) / a_{jj}, \quad j = n-1, n-2, \dots, 1$$

for each j , $1 \text{ } \mathcal{O}(n-j) \text{ } M$, $(n-j) \text{ } A$

total $\sum_{j=1}^{n-1} (n-j) = \frac{1}{2} n(n-1) \text{ } A$, $\frac{1}{2} n(n-1) \text{ } M$ $\mathcal{O}(n^2)$

total divisions: $n \text{ } \mathcal{O}(n)$

negligible as compared to GE requiring $\mathcal{O}(n^3)$ for $n \gg 1$.

Gauss-Jordan elimination \rightarrow exactly same operation counts.

* Tri-diagonal matrix

$$L_1 = \frac{a_2}{b_1} \begin{pmatrix} b_1 & c_1 & 0 & \dots & 0 \\ a_2 & b_2 & c_2 & 0 & \dots & 0 \\ 0 & a_3 & b_3 & c_3 & & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & a_n & b_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{pmatrix}$$

To eliminate a_2 ,
 $1D, 2M, 2D$

To make 0,
 $(n-1)D, 2(n-1)M, 2(n-1)A$

$$GE \rightarrow O(n)$$

after GE,

$$\begin{pmatrix} b_1 & c_1 & \phi & & \\ & b'_2 & c'_2 & \phi & \\ & \phi & \ddots & \ddots & \phi \\ & & & & b'_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} f_1 \\ f'_2 \\ \vdots \\ f'_n \end{pmatrix}$$

backward sweep

$$x_n = f'_n / b'_n$$

$$x_j = (f'_j - c'_j x_{j+1}) / b'_j$$

for $j = n-1, \dots, 1$

$$\rightarrow nD, (n-1)M, (n-1)A \rightarrow O(n)$$

Total operations: $(2n-1)D$, $3(n-1)M$, $3(n-1)A$
→ $O(n)$ operations for tri-diagonal matrix system.

⑥ Computation of inverse matrix

$$AB = I \quad B = [\underline{b}_1, \underline{b}_2, \dots, \underline{b}_n]$$

$$AB = [Ab_1, Ab_2, \dots, Ab_n] = I$$

$$\rightarrow Ab_1 = e_1, Ab_2 = e_2, \dots, Ab_n = e_n,$$

$$e_j = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}_j$$

Augmented matrix $[A \ e_1 \ e_2 \ e_3 \ \dots \ e_n] = [AI]$

Perform Gauss-Jordan on this augmented matrix.

ex) $A = \begin{pmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$

$$A^{-1} = ?$$

$$Ax = b$$

$$x = A^{-1}b$$

tri-diagonal matrix

$$\begin{pmatrix} -2 & 1 & 0 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 1 & 0 & 1 & 0 & 0 \\ 0 & -\frac{3}{2} & 1 & \frac{1}{2} & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} -2 & 1 & 0 & 1 & 0 & 0 \\ 0 & -\frac{3}{2} & 1 & \frac{1}{2} & 1 & 0 \\ 0 & 0 & \frac{5}{2} & \frac{1}{3} & \frac{2}{3} & 1 \end{pmatrix}$$

$$\rightarrow \dots \rightarrow \begin{pmatrix} 1 & 0 & 0 & -\frac{1}{5} & -\frac{1}{5} & \frac{1}{5} \\ 0 & 1 & 0 & -\frac{1}{5} & \frac{1}{5} & \frac{2}{5} \\ 0 & 0 & 1 & -\frac{1}{5} & \frac{2}{5} & \frac{3}{5} \end{pmatrix} \Rightarrow A^{-1} : \text{full matrix}$$

* inverse of a banded matrix is a full matrix.

operation counts for $A^{-1} : n^3$ of each M and A
(full matrix A) \sim similar to that of AB

If A^{-1} is not needed, it should not be computed.

① LU decomposition

$$Ax = b \xrightarrow{\text{GEB}} Ux = c$$

$$Ax = b \rightarrow x = A^{-1}b$$

$$\downarrow$$

$$\frac{LU}{z} x = b \rightarrow \begin{matrix} Lz = b & \mathcal{O}(n^2) \\ Ux = z & \mathcal{O}(n^2) \end{matrix}$$

operation of multiplication of one row by a constant and subtract from another row can be performed by a matrix multiplication.

e.g. multiply 1st row by e_{21} ($= -a_{21}/a_{11}$) and add to 2nd row.

$$E_{21} = \begin{pmatrix} 1 & & & & & \\ & e_{21} & & & & \\ & & 1 & & & \\ & & & \ddots & & \\ & & & & 1 & \\ & & & & & \ddots \\ & & & & & & 0 \end{pmatrix} \quad a_1 = \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix} \rightarrow E_{21} a_1 = \begin{pmatrix} a_{11} \\ 0 \\ a_{31} \\ \vdots \\ a_{n1} \end{pmatrix}$$

$$E_{31} = \begin{pmatrix} 1 & & & & & \\ & & 1 & & & \\ & & & \ddots & & \\ & & & & 1 & \\ & & & & & \ddots \\ & & & & & & 0 \end{pmatrix} \quad e_{31} = -a_{31}/a_{11} \rightarrow E_{31} a_1 = \begin{pmatrix} a_{11} \\ a_{21} \\ 0 \\ \vdots \\ a_{n1} \end{pmatrix}$$

$$E_{31} E_{21} = \begin{pmatrix} 1 & & & & & \\ & e_{21} & & & & \\ & e_{31} & & & & \\ & & 1 & & & \\ & & & \ddots & & \\ & & & & 1 & \\ & & & & & \ddots \\ & & & & & & 0 \end{pmatrix} \rightarrow E_{31} E_{21} a_1 = \begin{pmatrix} a_{11} \\ 0 \\ 0 \\ a_{21} \\ \vdots \\ a_{n1} \end{pmatrix}$$

To eliminate the 1st col.,

$$E_1 = \begin{pmatrix} 1 & & & \\ e_{21} & 1 & & 0 \\ e_{31} & & \ddots & \\ \vdots & & & \ddots \\ e_{n1} & & & & 1 \end{pmatrix}$$

$$e_{j1} = -a_{j1}/a_{11}$$

$$E_1 A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a'_{22} & \dots & a'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a''_{n2} & \dots & a''_{nn} \end{pmatrix}$$

↘ 0

To eliminate everything below a'_{22}

$$E_2 = \begin{pmatrix} 1 & & & \\ 0 & 1 & & 0 \\ \vdots & e_{32} & 1 & \\ \vdots & \vdots & & \ddots \\ 0 & e_{n2} & 0 & \ddots & 1 \end{pmatrix}$$

$$e_{j2} = -a'_{j2}/a'_{22}$$

$$E_2 E_1 A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a'_{22} & \dots & a'_{2n} \\ \vdots & 0 & a''_{33} & \dots & a''_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \vdots & \dots & a''_{nn} \end{pmatrix}$$

↙ upper triangular matrix

$$\rightarrow \underbrace{E_{n-1} E_{n-2} \dots E_2 E_1 A}_{= E} = U$$

= E : lower triangular matrix

$$EA = U \rightarrow A = \begin{pmatrix} E^{-1} \\ \vdots \end{pmatrix} U$$

$$E^{-1} E_1 A = A$$

Let's undo E_1 process.

$$E_{21} = \begin{pmatrix} 1 & & & \\ e_{21} & 1 & & \\ 0 & & \ddots & \\ 0 & & & 1 \end{pmatrix} \rightarrow E_{21}^{-1} = \begin{pmatrix} 1 & & & \\ -e_{21} & 1 & & \\ 0 & & \ddots & \\ 0 & & & 1 \end{pmatrix} \quad E_{21}^{-1} E_{21} A = A$$

multiply 1st row by $-e_{21}$ and add to 2nd row.

$$\rightarrow E_{21}^{-1} = \begin{pmatrix} 1 & & & 0 \\ -e_{21} & 1 & & \\ -e_{31} & & \ddots & \\ \vdots & & & \\ -e_{n1} & & & 1 \end{pmatrix}, \quad E_2^{-1} = \dots, \quad E_3^{-1} = \dots$$

$O(n^3)$
↓

$$EA = U \rightarrow E_{n-1} E_{n-2} \dots E_1 A = U$$

$$A = \underbrace{E_1^{-1} E_2^{-1} \dots E_{n-2}^{-1} E_{n-1}^{-1}}_{L} U = LU$$

lower triangular matrix
w/ 1's on the main diagonal

$$Ax = b \rightarrow \underbrace{LU}_Z x = b$$

$$Lz = b \rightarrow \begin{pmatrix} l_{11} & & & 0 \\ l_{21} & l_{22} & & \\ \vdots & & \ddots & \\ l_{n1} & l_{n2} & \dots & l_{nn} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad \downarrow \quad \mathcal{O}(n^2)$$

forward sweep : $z_1 = b_1 / l_{11}$
 $z_j = (b_j - \sum_{k=1}^{j-1} l_{jk} z_k) / l_{jj}''$, $j=2, 3, \dots, n$

$Ux = z$: backward sweep $\rightarrow \mathcal{O}(n^2)$ to get x
 LU decomposition $\rightarrow \mathcal{O}(n^3)$: expensive!

$$Ax = b \quad \begin{cases} \rightarrow x = A^{-1}b \\ \rightarrow LUx = b \end{cases} \quad \left. \vphantom{\begin{cases} \rightarrow x = A^{-1}b \\ \rightarrow LUx = b \end{cases}} \right\} \text{direct solution}$$

$$A = \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} \rightarrow A^{-1} = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

\hookrightarrow LU much easier

What if $a_{dd} = 0$?

$$\begin{pmatrix} 0 & 5 & -1 \\ 1 & 1 & 1 \\ 2 & -2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

→ row exchange

↓
permutation matrix

$$P = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\rightarrow PA = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 5 & -1 \\ 2 & -2 & 1 \end{pmatrix}$$

$$\rightarrow Ax = b$$

$$\rightarrow PAx = Pb \rightarrow LUx = Pb = b'$$