# Week 4 Classification (Part III)

Seokho Chi Professor | Ph.D. SNU Construction Innovation Lab



Source: Tan, Kumar, Steinback (2006)



# **Neural Networks**

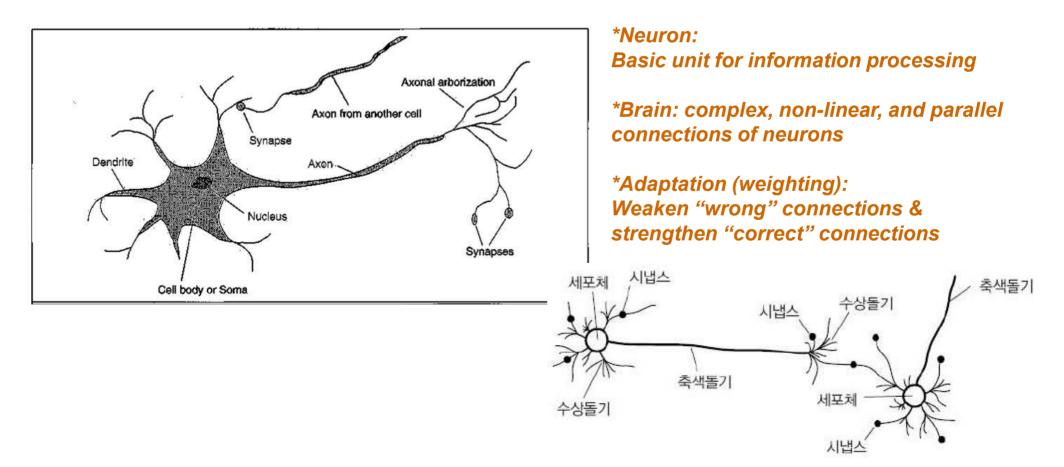
- Machine learning algorithm
  - Computer learning mechanism based on experiences, examples, and predictions
  - Upgrade performance as learning time goes by

- Analogy to Biological Systems "Human Brain"
- Massive Parallelism allowing for computational efficiency

# Neuron

- The cell that perform information processing in the brain
- Fundamental functional unit of all nervous system tissue
- Each neuron consists of :

CELL BODY, DENDRITES, AXON, and SYNAPSE.

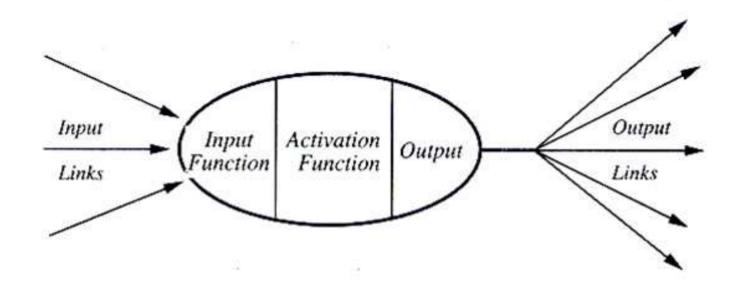


# **Definition of Neural Network**

 A Neural Network is a system composed of many simple processing elements operating in parallel which can acquire, store, and utilize experiential knowledge

- Components
- Each element is a node called unit
- Units are connected by links
- Each link has a numeric weight
  - Weight explains the importance of links
  - Machine learning controlling and training weights repeatedly

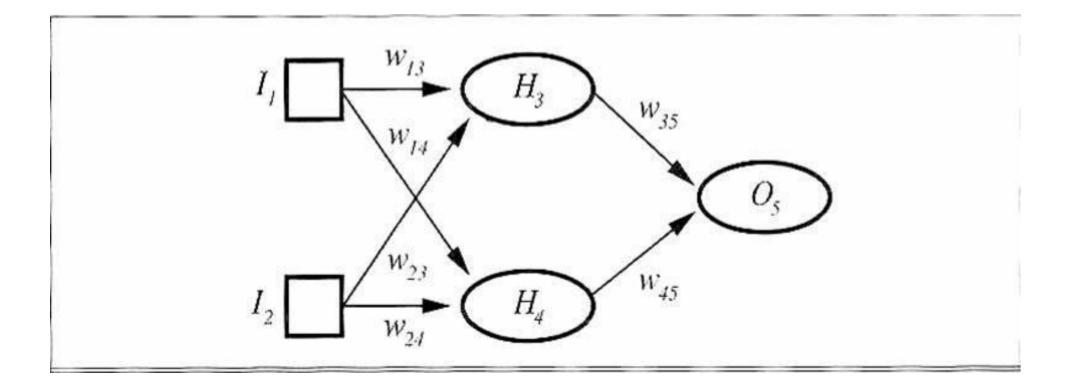
### **Computing Elements**



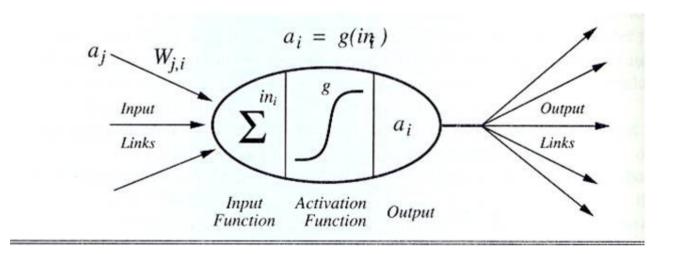
Require decisions on:

- The number of units to use
- The type of units required
- Connection between the units

### **Neural Network Example**



# **NN Computing Unit**



- 2 components: Linear and Non-linear
- Linear: Input function
  - calculate weighted sum of all inputs
- Non-linear: Activation function

- transform sum into activation level

$$in_i = \sum_j W_{j,i}a_j = \mathbf{W}_i \cdot \mathbf{a}_i$$

$$a_i \leftarrow g(in_i) = g\left(\sum_j W_{j,i}a_j\right)$$

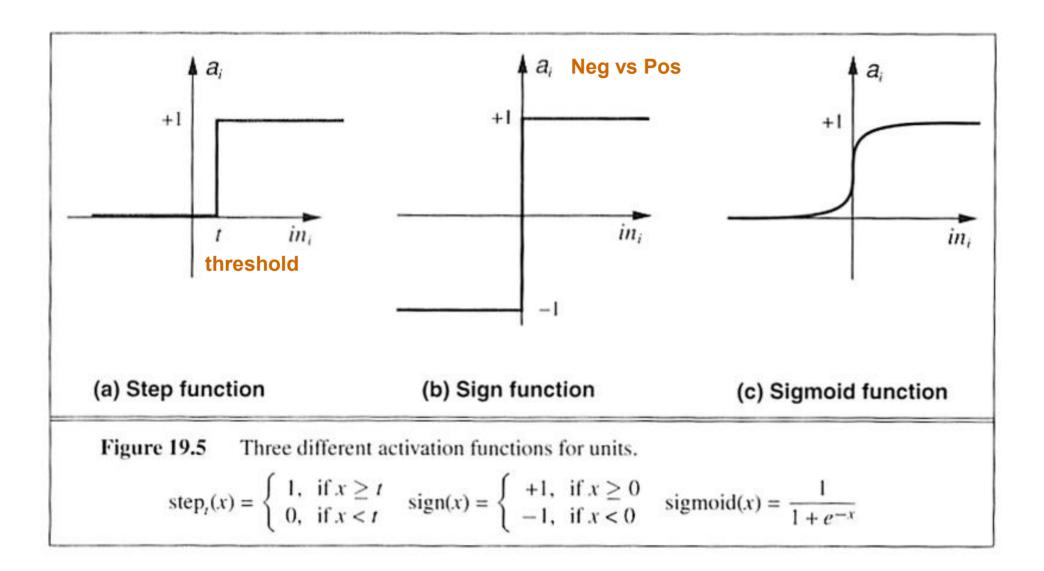
# **Activation Functions**

Use different functions to obtain different models

 Compare sum of inputs with the threshold value
 Output becomes "0", "-1", etc. if sum is smaller
 Output becomes "+1" if sum is same or larger
 → "activated"

- 3 most common choices
  - 1) Step function
  - 2) Sign function
  - 3) Sigmoid function

### **Activation Functions**



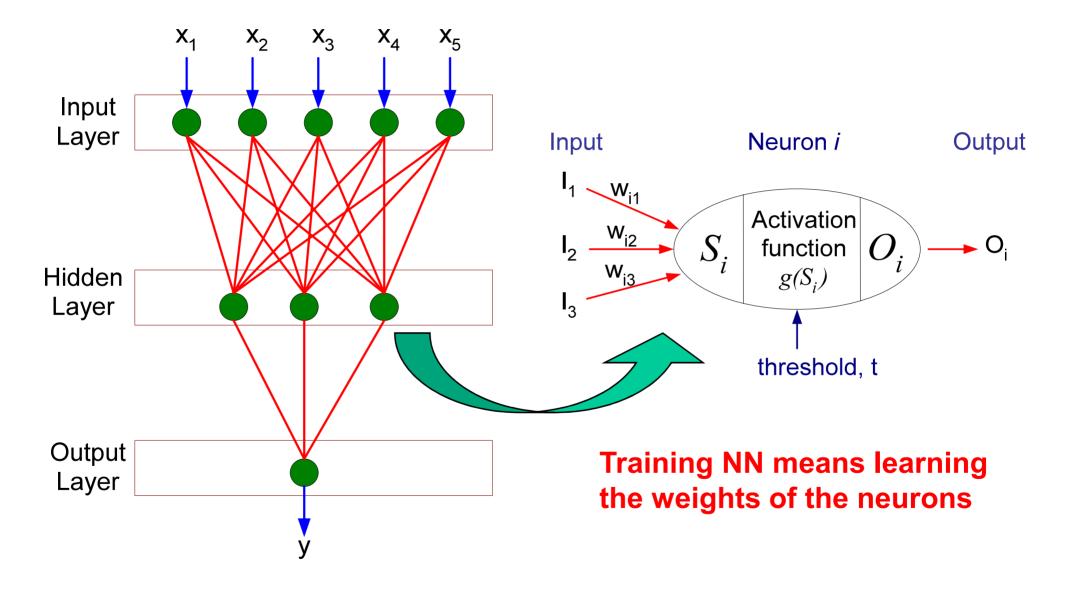
# Feed-forward Neural Networks (FF NN)

- Arranged in layers
- Each unit is linked only in the unit in next layer

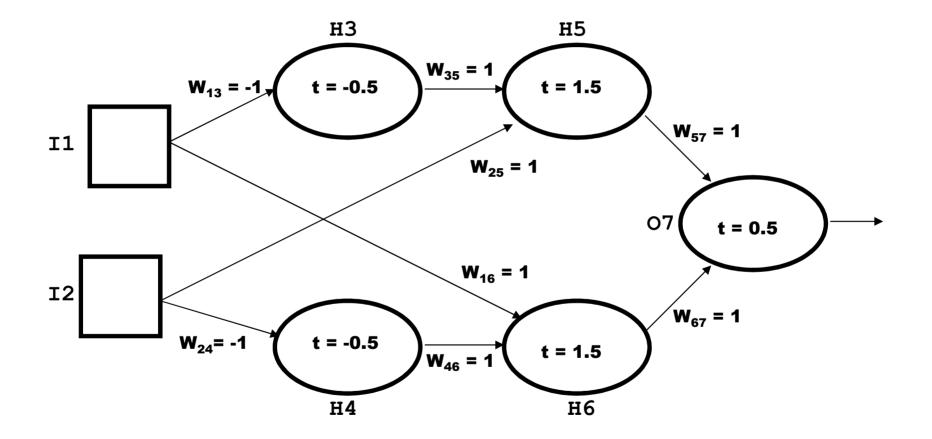
 No units are linked between the same layer, back to the previous layer or skipping a layer (only go in one direction)

 Computations can proceed uniformly from input to output units

### General Structure of FF NN



### Feed-Forward Example



### **Network Layers**

- Networks without hidden layer are called a "perceptron"
- Multi-layer Networks: Have one or more layers of hidden units
- With two possibly very large hidden layers, it is possible to implement any function

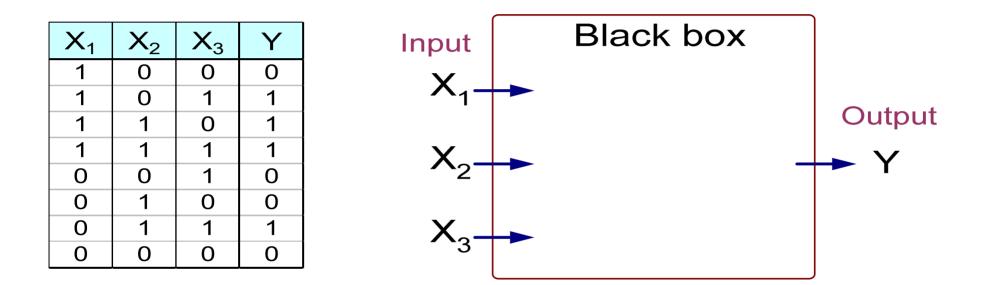
# NN Learning

- Initial network has a randomly assigned weights
- Weight adjustments are made to reduce the difference between the observed and predicted values

- Need to repeat the update phase several times in order to achieve convergence.

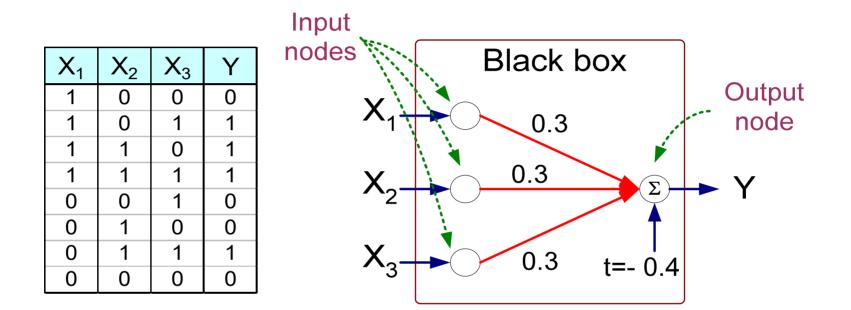
- Updating process is divided into epochs, each epoch updates all the weights of the process.

# Artificial Neural Networks (ANN)



Output Y is 1 if at least two of the three inputs are equal to 1.

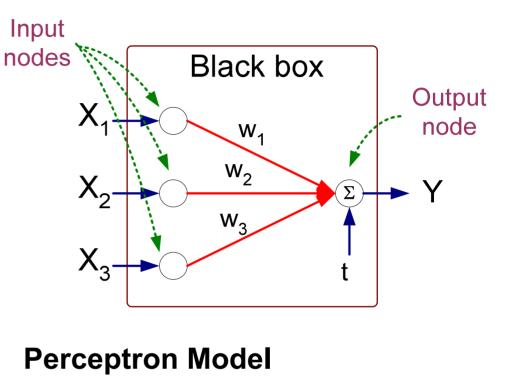
### Artificial Neural Networks (ANN)



$$Y = I(0.3X_1 + 0.3X_2 + 0.3X_3 - 0.4 > 0)$$
  
where  $I(z) = \begin{cases} 1 & \text{if } z \text{ is true} \\ 0 & \text{otherwise} \end{cases}$ 

# Artificial Neural Networks (ANN)

- Model is an assembly of inter-connected nodes and weighted links
- Output node sums up each of its input value according to the weights of its links
- Compare output node against some threshold t



$$Y = sign(\sum_{i} w_i X_i - t)$$

# Introduction to Backpropagation

- In 1969 a method for learning in multi-layer network, Backpropagation, was invented by Bryson and Ho.
- The Backpropagation algorithm is a sensible approach for dividing the contribution of each weight.
- Can model complex functions

# Backpropagation Algorithm

The ideas of the algorithm can be summarized as follows:

Computes the error term for the output units using the observed error

 From output layer, repeat propagating the error term back to the previous layer and updating the weights between the two layers until the earliest hidden layer is reached

### References

Han, J. and Kamber, M. (2001) Data Mining: Concepts and

Techniques, 1st edition, Morgan Kaufmann.

Russel, S. and P. Norvig (1995). Artificial Intelligence: A

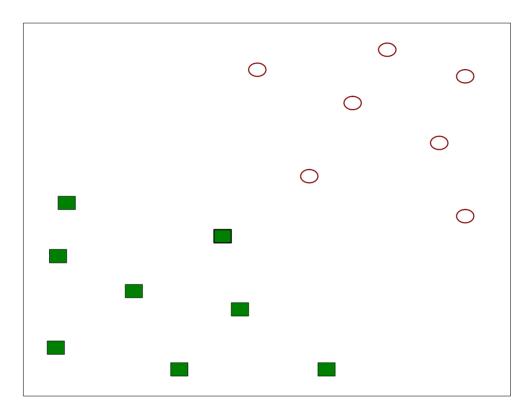
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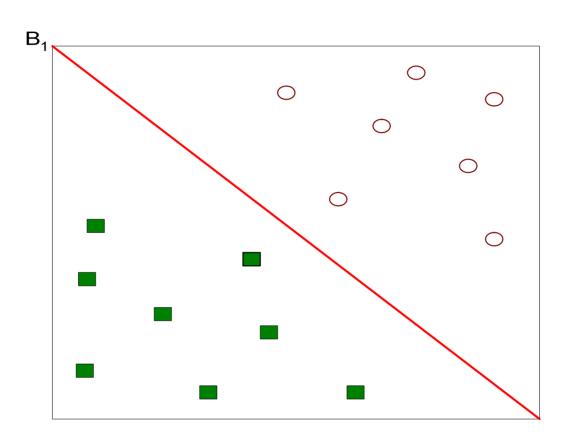
Data Mining, 1st edition, Addison-Wesley.

# Support Vector Machines (SVM)

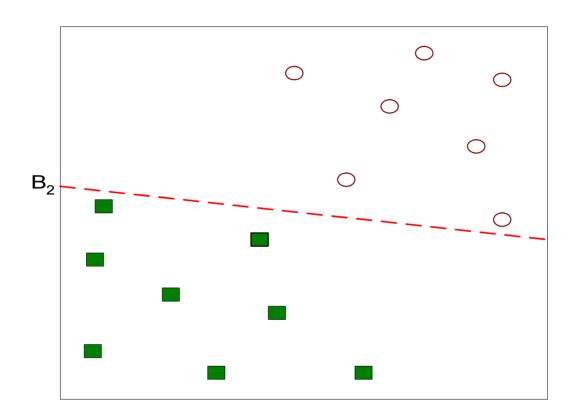
#### Non-probabilistic binary linear classifier



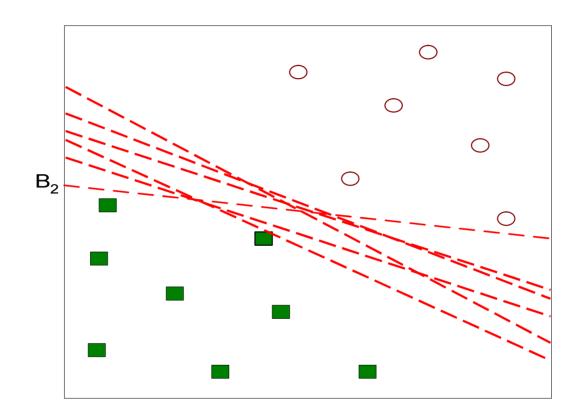
Find a linear hyperplane (decision boundary) that will separate the data



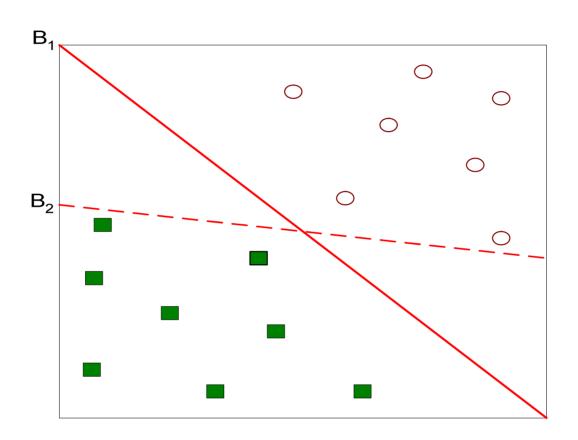
One Possible Solution



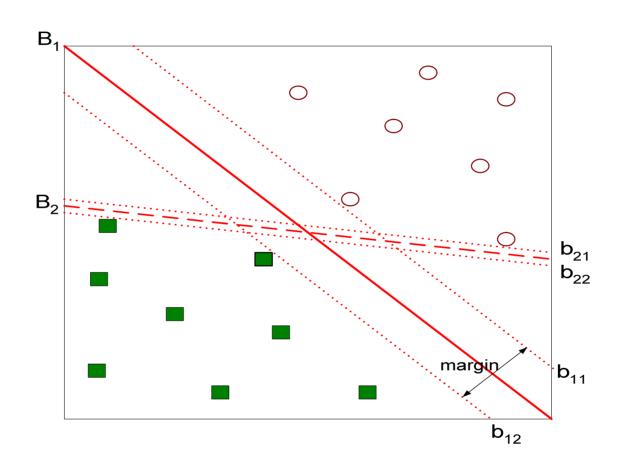
Another possible solution



Other several possible solutions



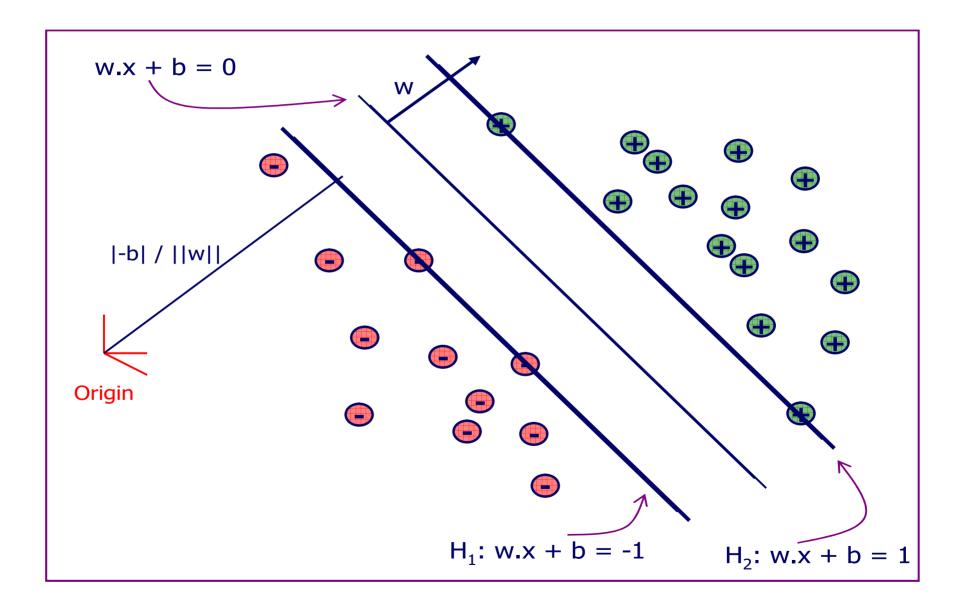
- Which one is better? B1 or B2?
- How do you define better?



- Find hyperplane maximizes the margin
  - $\rightarrow$  Better generalization errors  $\rightarrow$  B1 is better than B2

(smaller margin  $\rightarrow$  slight perturbations to the decision boundary can have a significant result)

### SVM – Model Building



# SVM – Model Building

### Formulation:

Suppose that all training data satisfy the following constraints

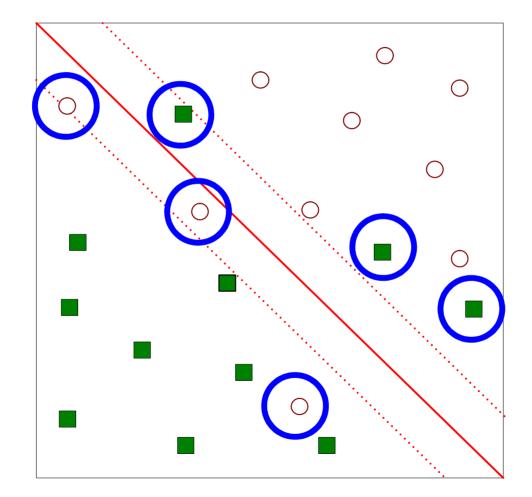
$$x_i \cdot w + b \ge +1 \quad for \ y_i = +1$$
$$x_i \cdot w + b \le -1 \quad for \ y_i = -1$$

These can be combined into one set of inequalities

$$y_i(x_i \cdot w + b) - 1 \ge 0 \quad \forall i$$

## **Support Vector Machines**

• What if the problem is not linearly separable?



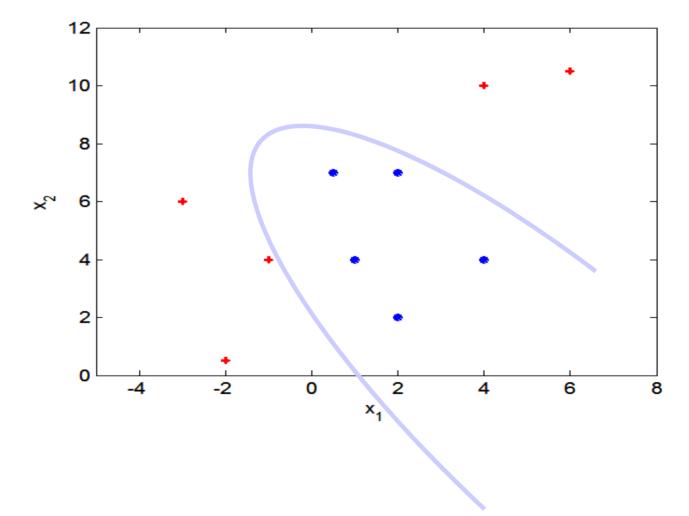
# **Support Vector Machines**

- What if the problem is not linearly separable?
  - Introduce slack variables  $\xi_i$  (EAFOI)
    - Soft Margin method
    - Which measures the degree of misclassification of the data
    - Subject to:

$$f(\vec{x}_i) = \begin{cases} 1 & \text{if } \vec{w} \bullet \vec{x}_i + b \ge 1 - \xi_i \\ -1 & \text{if } \vec{w} \bullet \vec{x}_i + b \le -1 + \xi_i \end{cases}$$

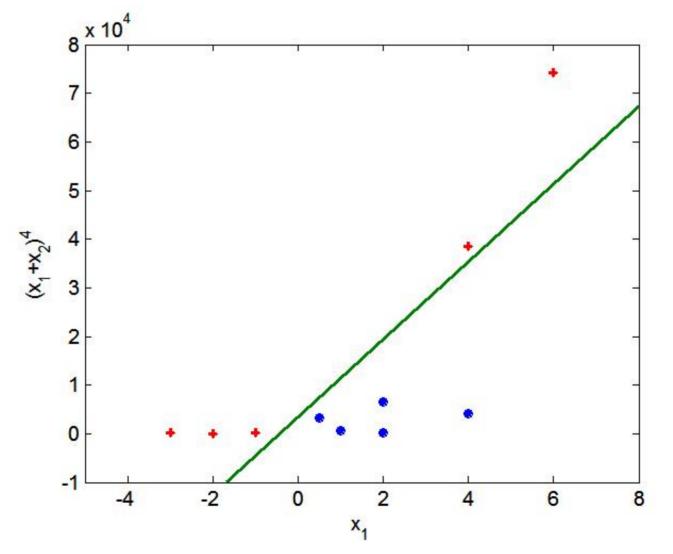
### **Nonlinear Support Vector Machines**

What if decision boundary is not linear?



### **Nonlinear Support Vector Machines**

Transform data into higher dimensional space



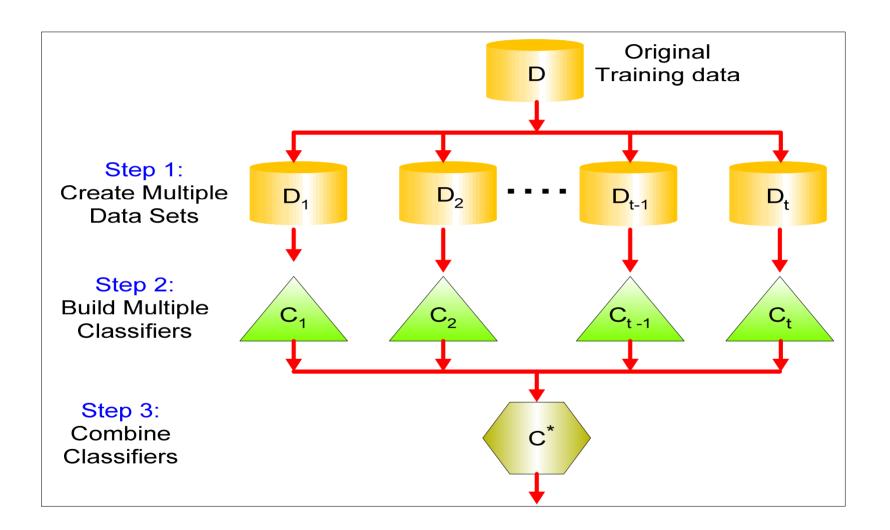
# SVM - Advantages

- Mathematical formulation → Objective quantification
- High dimensional feature spaces → Advantages for multi-dimensional analysis
- Easier generalization

# **Ensemble Methods**

- Construct a set of classifiers from the training data (also known as classifier combination)
- Predict class label of previously unseen records by aggregating predictions made by multiple classifiers

### General Idea



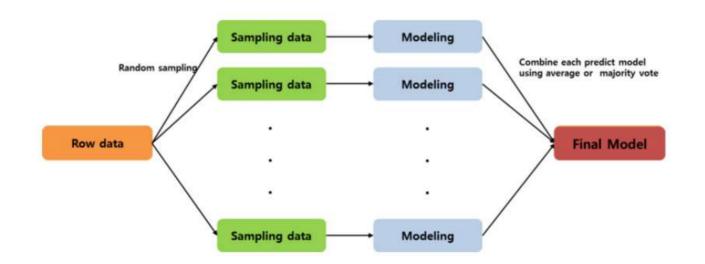
# Why does it work?

- Suppose there are 25 base classifiers
  - Each classifier has error rate,  $\epsilon = 0.35$
  - The ensemble classifier predicts the class label of a test example by taking a majority vote on the predictions
  - Assume classifiers are independent (thus their errors are uncorrelated)
  - Probability that the ensemble classifier makes a wrong prediction: more than half of the classifiers (13 and more) predict wrong

$$\sum_{i=13}^{25} {\binom{25}{i}} \varepsilon^{i} (1-\varepsilon)^{25-i} = 0.06$$

# **Examples of Ensemble Methods**

- How to generate an ensemble of classifiers?
  - Bagging (Bootstrap Aggregating): repeatedly samples from a data set with replacement according to a uniform probability distribution (모집단의 성질에 대해 표본을 통해 추정할 수 있는 것처럼 표본의 성질에 대해서도 재표본을 통해 추정할 수 있다는 개념: 무작위 추출 → 표본통계 → 이를 반복)



# **Examples of Ensemble Methods**

 Boosting: an iterative procedure used to adaptively change the distribution of training examples so that the base classifiers will focus on examples that are hard to classify → add erroneous samples into the training data for model building

