# 457.646 Topics in Structural Reliability In-Class Material: Class 09

### III. Structural Reliability (Component) - continued

#### **IDENTIFY OF STREET** STREET, S

- **5** Joint distribution models with marginal & corr. coeff (contd.)
- a) Morgenstern:  $F_{X_i}(x_i)$ ,  $i = 1, ..., n \& \alpha_{ij}$  but  $\left| \rho_{ij} \right| < 0.30$
- b) Nataf model (Nataf, 1962)
  - ★ Joint PDF by Nataf model

Note:

$$F_{X_i}(x_i) = \Phi(z_i)$$
  
$$f_{X_i}(x_i)dx_i = \varphi(z_i)dz_i$$

★  $\rho'_{ij}$  (corr. coeff. b/w  $Z_i$  and  $Z_j$ )?

$$\rho_{ij} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \left( ----- \right) \left( ----- \right) f_{X_i X_j}(x_i, x_j) dx_i dx_j$$
  
$$\therefore \rho_{ij} = \int \int \left( ----- \right) \left( ------ \right) \phi_2(z_i, z_j; \rho'_{ij}) ----- dz_i dz_j$$

In general,  $\left| \rho_{ij}^{\prime} \right| \qquad \left| \rho_{ij} \right|$ 

 $\therefore \left| \rho_{ij} \right| \le A < 1 \text{ may not cover the whole range of } \rho_{ij}$ 

 $\rho'_{ij} \cong F \cdot \rho_{ij}$  Liu & ADK (Table 4~6) for pairs of selected distribution types

Table 9: Range of  $\rho_{ij}$  ~ wider (than Morgenstern)

Later used for transformation of dependent RVs into  $\mathbf{U} \sim N(\mathbf{0}, \mathbf{I})$ 

 $\leq 0$ 

X Z U

## © Elementary Structural Reliability Problem

Describe the failure event in terms of \_\_\_\_\_\_ & \_\_\_\_\_

**①** Failure :  $g(\mathbf{x}) = g(-, -) =$ 



② Failure probability :  $P_f = P( \leq 0)$ 

$$P_{f} = \iint f_{R,S}(r,s) dr ds$$
$$= \iint f_{R|S}(r|s) \cdot f_{s}(s) dr ds$$
$$= \iint f_{R|S}(r|s) dr f_{s}(s) ds$$
$$= \int f_{s}(s) ds$$





OR

$$P_{f} = \iint_{r \le s} f_{s|R}(s|r) f_{R}(r) ds dr$$
$$= \iint_{r \le s} f_{s|R}(s|r) ds f_{R}(r) dr$$
$$= \iint_{r \ge s} \left[ \int_{r \ge s} f_{R}(r) dr \right] f_{R}(r) dr$$
if s.i = 
$$\int_{r \ge s} \int_{r \ge s} f_{R}(r) dr$$



3 Reliability Index by "Safety Margin,"  $\beta_{SM}$ 

M =

: Safety Margin

Failure :  $\{R - S \le 0\}$   $\Leftrightarrow \{ \le 0 \}$ 

$$\Leftrightarrow \{U_M \leq \}$$

\* Standardization

$$U_{M} = \underbrace{M}_{Var[U_{M}]} = \underbrace{E[U_{M}]}_{Var[U_{M}]} =$$

For *n* RVs,

$$U = L^{-1}D^{-1}(X - M)$$

$$\therefore P_f = P(U_M \le ) = F_{U_M} ()$$

$$= F_{U_M} ()$$





 $F_{U_M}$ : depends on distribution of R and S

e.g. special case ~ R and S are jointly normal

Then  $U_M \sim$ 

Therefore  $P_f = F_{U_M}(-\beta_{SM}) =$ 

\* A. Cornell (1968. ACI codes)

Assumed R&S are jointly normal & used  $\beta_{SM}$  to compute  $P_f$ 

 $\mu_F =$ 

 $\sigma_F^2 =$ 

## ④ Reliability Index by "Safety Factor"

 $F = \ln - \ln - \ln$ Failure :{  $\leq 0$ } (\* used for LRFD  $\phi R_n \geq \sum \gamma_k Q_k$ )  $\Leftrightarrow \{ \leq 0 \}$  $\Leftrightarrow \{u_F \leq - - - \}$  $\therefore \beta_{SF} = ----- P_f = F_{u_F} (- )$ 

⇒ special case: R & S are jointly lognormal

$$\begin{split} U_F \sim \\ \therefore P_f &= \Phi( ) \\ \mu_F^{(LN)} &= \\ \sigma_F^{(LN)} &= \\ \beta_{SF}^{(LN)} &= \frac{\ln\left(r \cdot \sqrt{\frac{1+\delta_s^2}{1+\delta_R^2}}\right)}{\sqrt{\ln(1+\delta_R^2) - 2\ln(1+\rho_{RS}\delta_R\delta_S) + \ln(1+\delta_S^2)}}, \ r = \frac{\mu_R}{\mu_s} \end{split}$$

Safety factor-based reliability-index when R & S are jointly lognormal

# 457.646 Topics in Structural Reliability In-Class Material: Class 10

## Second moment reliability index $\beta_{\text{MVFOSM}}$

#### MVFOSM

- Failure :  $g(\mathbf{x}) \le 0$  (NOT "elementary")
- Use ( ) & ( ) only. Therefore, can't compute P<sub>f</sub> (index, not method)
   Ang & Cornell (1974) ASCE Journal of Structural Engineering



i.e. equivalent limit-state functions could give different  $\beta_{\text{MVFORM}}$ 

$$g_{1}(x) = X_{1}^{2} + 3X_{2} < 0$$

$$g_{2}(x) = \frac{g_{1}(x)}{X_{1}^{2}} = 1 + 3\frac{X_{2}}{X_{1}^{2}} < 0$$
equivalent  $\Rightarrow$  the same  $\beta_{MVFORM}$ ?

### Example: lack of invariance of MVFOSM

Consider a structural reliability problem with two random variables  $X_1$  and  $X_2$ . The mean vector and the covariance matrix of  $X_1$  and  $X_2$  are

$$\mathbf{M}_{\mathbf{x}} = \begin{bmatrix} 5\\10 \end{bmatrix}, \quad \mathbf{\Sigma}_{\mathbf{x}\mathbf{x}} = \begin{bmatrix} 4 & 5\\5 & 25 \end{bmatrix}$$

**<u>Case 1:</u>**  $g(X_1, X_2) = X_1^2 + 3X_2$ Gradient  $\nabla g = [2X_1 \quad 3]$ . At the mean point  $\mathbf{X} = \mathbf{M}_{\mathbf{X}}$ ,  $\nabla g = [10 \quad 3]$ . First order approximation on  $\mu_g$  and  $\sigma_g^2$ :  $\mu_g \cong 5^2 + 3 \times 10 = 55$   $\sigma_g^2 \cong \nabla g \mathbf{\Sigma}_{\mathbf{X}\mathbf{X}} \nabla g^{\mathrm{T}} = 925$   $\beta_{MVFOSM} = \frac{\mu_g}{\sigma_g} = \frac{55}{\sqrt{925}} = 1.81$   $P_f = \Phi(-1.81) = 0.0351$  **<u>Case 2:</u>**  $g(X_1, X_2) = 1 + \frac{3X_2}{X_1^2}$   $\nabla g = [-6X_2X_1^{-3} \quad 3X_1^{-2}]$ . At the mean point  $\mathbf{X} = \mathbf{M}_{\mathbf{X}}$ ,  $\nabla g = [-0.48 \quad 0.12]$ .  $\mu_g \cong 1 + 3 \times 10/25 = 2.20$   $\sigma_g^2 \cong \nabla g \mathbf{\Sigma}_{\mathbf{X}\mathbf{X}} \nabla g^{\mathrm{T}} = 0.706$   $\beta_{MVFOSM} = \frac{\mu_g}{\sigma_g} = \frac{2.20}{\sqrt{0.706}} = 2.62$  $P_f = \Phi(-2.62) = 0.00440$ 

Although the two limit-state functions are equivalent ones with the same failure domains, the second order reliability method yields different reliability indices and failure probability estimates.

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Summary:

$$\beta_{SM} = \frac{\mu_M}{\sigma_M} = \frac{\mu_R - \mu_S}{\sqrt{\sigma_R^2 + \sigma_S^2 - 2\sigma_R \sigma_S \rho_{RS}}}$$
$$\beta_{SF} = \frac{\mu_F}{\sigma_F}, \text{ for LN } \beta_{SF} = \frac{\lambda_R - \lambda_S}{\sqrt{\zeta_R^2 + \zeta_S^2 - 2\zeta_R \zeta_S \rho_{\ln R \ln S}}}$$
$$\beta_{MVFOSM} = \frac{\mu_g^{FO}}{\sigma_g^{FO}} = \frac{g(\mathbf{M}_{\mathbf{X}})}{\nabla g(\mathbf{M}_{\mathbf{X}}) \boldsymbol{\Sigma}_{\mathbf{XX}} \nabla g(\mathbf{M}_{\mathbf{X}})^{\mathrm{T}}} \quad (\text{Oct1974})$$

# ${\ensuremath{\textcircled{@}}}$ Hasofer-Lind Reliability Index, $\,\beta_{\scriptscriptstyle HL}\,$ (JEM, May 1974)





### **Linear Limit-State Function**

$$g(\mathbf{x}) = a_0 + \mathbf{a}^{\mathrm{T}} \mathbf{x}$$
  
=  $a_0 + \mathbf{a}^{\mathrm{T}} ($  )  
=  $a_0 + \mathbf{a}^{\mathrm{T}} \mathbf{M} + \mathbf{a}^{\mathrm{T}} \mathbf{D} \mathbf{L} \mathbf{u}$   
=  $b_0 + \mathbf{b}^{\mathrm{T}} \mathbf{u} = G(\mathbf{u})$ 

VS

$$\beta = \frac{\mu_G}{\sigma_G} = \frac{b_0}{\|\mathbf{b}\|}$$



Can have +/\_ sign

always positive

For 
$$G(\mathbf{u}) = b_0 + \mathbf{b}^{\mathrm{T}}\mathbf{u}$$



 $b_o = G(\mathbf{0}) <$  ( (in failure domain)  $\beta < 0$  $b_o = G(\mathbf{0}) > 0$ (in safe domain)  $\beta > 0$  Seoul National University Dept. of Civil and Environmental Engineering

i. 
$$\boldsymbol{\alpha} = -\frac{\nabla G}{\|\nabla G\|}$$
 : "Negative normalized gradient vector"

: Unit row vector pointing toward the \_\_\_\_\_ domain

e.g. linear function : 
$$\boldsymbol{\alpha} = -\frac{\mathbf{b}^{\mathrm{T}}}{\|\mathbf{b}\|}$$

ii.  $\mathbf{u}^*$  : "Design point"

"Most probable failure point (MPP)"

"Beta point"

e.g. linear function : 
$$\mathbf{u}^* \equiv -b_0 \frac{\mathbf{b}}{\|\mathbf{b}\|^2}$$

iii.

$$\beta_{HL} \equiv \alpha u^*$$

#### Hasofer-Lind Reliability Index

 $\begin{cases} |\beta_{HL}| : \text{distance between origin and } \mathbf{u}^* \\ \text{sign} : \text{directions of } \boldsymbol{\alpha} \text{ and } \mathbf{u}^* \end{cases}$ 

e.g. linear function : 
$$\beta_{HL} = \frac{b_0}{\|\mathbf{b}\|} \left( = \frac{\mu_G}{\sigma_G} \right)$$
  
 $P_f = F_{u_g}(-\beta_{HL})$   
 $P_f = F_{u_g}(-\beta_{HL})$   
(reliable) (less reliable)  
 $\Rightarrow G, g \sim N$   
 $P_f = \Phi(-\beta_{HL})$