Mid-term Exam

- 4월26일(월)
- **15:30~17:00**
- 33동 225,226,327,328,330,331



재료의 기계적 거동 (Mechanical Behavior of Materials)

VISCOELASTICITY (점탄성)

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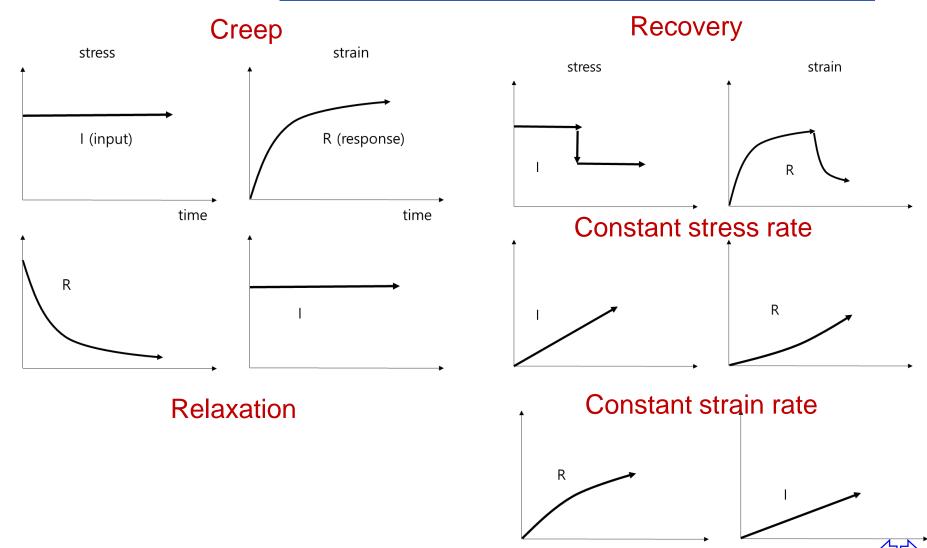
Viscoelasticity

- Elastic materials deform with stress and quickly return to their original state if the stress is removed due to the bond stretching along crystallographic planes in an ordered solid
- Viscous materials, like honey, resist shear flow and strain with time when a stress is applied due to the diffusion of atoms or molecules inside an amorphous material.
- Viscoelasticity is the property of materials that exhibit both viscosity and elasticity during deformation and time-dependent strain.

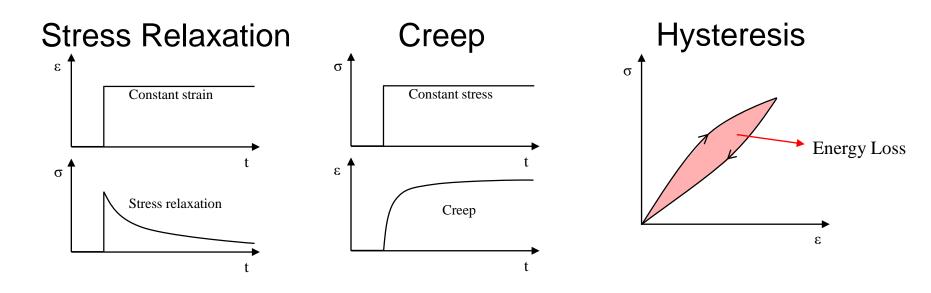
Viscoelasticity

- **Creep:** Increase in strain with time as the stress or load is kept constant. Typical creep behavior shows that strain increases with time at a decreasing rate followed by a constant rate and finally increasing rate.
- **Recovery:** When the applied load is reduced (or instantly decreased), the strain decreases with time, partially or completely. i.e., anelastic, inelastic, elastic aftereffect
- Relaxation: Stress decreases with time when a strain is kept constant

Viscoelasticity



Phenomenon of Viscoelastic Materials



- If the stress is held constant, the strain increases with time (creep)
- If the strain is held constant, the stress decreases with time (stress relaxation)
- If a cyclic loading is applied, **hysteresis occurs**, leading to a dissipation of mechanical energy $\oint \sigma d\varepsilon$



Constitutive models for linear viscoelasticity

$\sigma = \sigma(t) \qquad \varepsilon = \varepsilon(t)$

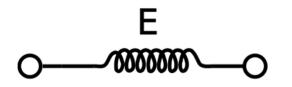
Since its viscous component,

the stress-strain relation of viscoelastic materials is

time-dependent!

Constitutive models for linear viscoelasticity

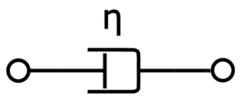
Viscoelasticity can be divided to elastic components and viscous components. We can model viscoelastic materials as **linear combinations** of *springs* and *dashpots*.



The *springs* represent the *elastic* components.

$$\sigma = E\varepsilon$$

where *E* is the elastic modulus of the material.



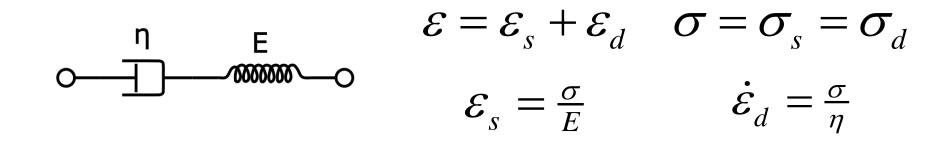
The *dashpots* represent the *viscous* components (perfect viscous fluid).

$$\sigma = \eta \frac{d\varepsilon}{dt} = \eta \dot{\varepsilon}$$

where η is the viscosity of the material and $d\varepsilon/dt$ is the strain rate.

* No immediate extension takes place at zero time when a sudden load is applied (like a rigid body)

Maxwell Model



A purely viscous damper and purely elastic spring connected *in series*.

$$\dot{\varepsilon} = \dot{\varepsilon}_s + \dot{\varepsilon}_d = \frac{\dot{\sigma}}{E} + \frac{\sigma}{\eta}$$



Maxwell Model
$$\dot{\varepsilon} = \dot{\varepsilon}_s + \dot{\varepsilon}_d = \frac{\dot{\sigma}}{E} + \frac{\sigma}{\eta}$$
Stress Relaxation
 $(\varepsilon = const. (\dot{\varepsilon} = 0))$ $(\varepsilon = const. (\dot{\varepsilon} = 0))$ $G_{(t)} = \frac{\sigma(t)}{\varepsilon} = E \cdot e^{-\frac{E}{\eta}t}$ $G_M(t) = \frac{\sigma(t)}{\varepsilon} = E \cdot e^{-\frac{E}{\eta}t}$ $Maxwell Model $\dot{\varepsilon} = \dot{\varepsilon}_s + \dot{\varepsilon}_d = \frac{\dot{\sigma}}{E} + \frac{\sigma}{\eta}$ Stress Relaxation
 $(\sigma = const. (\dot{\sigma} = 0))$ $(\sigma = const. (\dot{\sigma} = 0))$ $J_{(t)} = \frac{\sigma(t)}{\varepsilon} = \frac{\sigma(t)}{\varepsilon} = E \cdot e^{-\frac{E}{\eta}t}$ $J_M(t) = \frac{\varepsilon(t)}{\sigma} = \frac{1}{E} + \frac{1}{\eta}t$$

In creep, actual strain rate decreases with time!



Maxwell Model

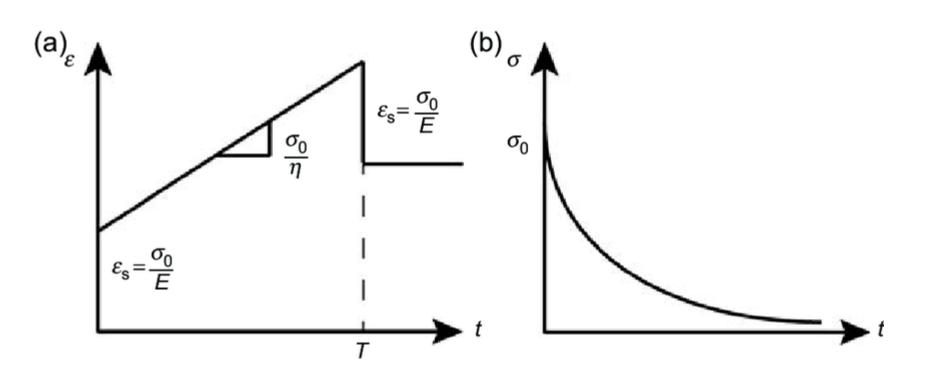
Creep Compliance J(t)

Relaxation Modulus G(t)

 $d\sigma$



Maxwell Model

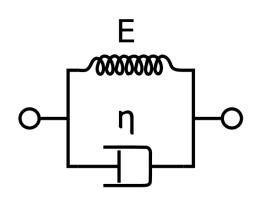


Creep & recovery

Relaxation



Voigt-Kelvin (V-K) Model



$$\varepsilon = \varepsilon_s = \varepsilon_d$$
 $\sigma = \sigma_s + \sigma_d$
 $\sigma_s = E \cdot \varepsilon$ $\sigma_d = \eta \cdot \dot{\varepsilon}$

A purely viscous damper and purely elastic spring connected *in parallel*.

$$\sigma = \sigma_s + \sigma_d = E\varepsilon + \eta \dot{\varepsilon}$$

* When a constant stress is applied, the dashpot prevent instantaneous extension of spring and each component supports a portion of applied stress



V-K Model
$$\sigma = \sigma_s + \sigma_d = E\varepsilon + \eta \dot{\varepsilon}$$
Stress Relaxation
 $(\varepsilon = const. (\dot{\varepsilon} = 0))$
 I_d Creep
 $(\sigma = const. (\dot{\sigma} = 0))$
 I_d G(t) f f Relaxation Modulus $G(t)$ Creep Compliance Function $J(t)$ $G_{V-K}(t) = \frac{\sigma(t)}{\varepsilon} = E$ $J_{V-K}(t) = \frac{\varepsilon(t)}{\sigma} = \frac{1}{E}(1 - e^{-\frac{E}{\eta}t})$ Actual stress is not constantActual stress is not constant

2021-04-05

in viscoelastic materials.



V-K Model

Creep Compliance J(t)

$$d\varepsilon + \frac{E}{\eta}\varepsilon dt = \frac{\sigma_0}{\eta}dt$$
$$\varepsilon(t) = \frac{\sigma_0}{E} \left[1 - \exp(-\frac{E}{\eta}t)\right]$$

$$J_{V-K}(t) = \frac{\varepsilon(t)}{\sigma} = \frac{1}{E} (1 - e^{-\frac{E}{\eta}t})$$

Relaxation Modulus G(t)

$$\sigma_0 = E\varepsilon_0 = const$$

$$G_{V-K}(t) = \frac{\sigma(t)}{\varepsilon} = E$$

No relaxation is predicted by the Kelvin model



V-K Model

Recovery

At time t=t1, stress is suddenly reduced to zero!!

$$\varepsilon(t) = \frac{\sigma_0}{E} \left[1 - \exp(-\frac{E}{\eta}t) \right] \qquad 0 \le t \le t_1$$

Let,
$$\frac{E}{\eta} = \frac{1}{\tau}$$
 $t' = t - t_1$

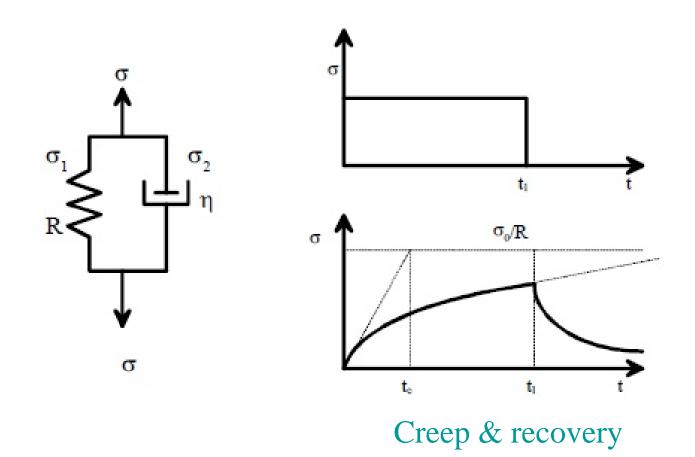
$$d\varepsilon + \frac{\varepsilon}{\tau} dt' = 0 \qquad t \ge t_1$$

$$\varepsilon(t) = \varepsilon_1 \exp(-\frac{1}{\tau}t') \quad \text{or} \quad \varepsilon(t) = \frac{\sigma_0}{E} \left[\exp(\frac{t_1}{\tau}) - 1\right] \exp(-\frac{1}{\tau}t) \qquad t \ge t_1$$



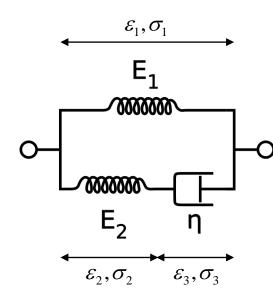
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V-K Model





Standard Linear Solid(Zener) Model



A Maxwell model and a purely elastic spring connected in parallel (three-parameter standard model)

$$\varepsilon = \varepsilon_1 = \varepsilon_2 + \varepsilon_3$$
$$\sigma = \sigma_1 + \sigma_2$$
$$\sigma_2 = \sigma_3$$

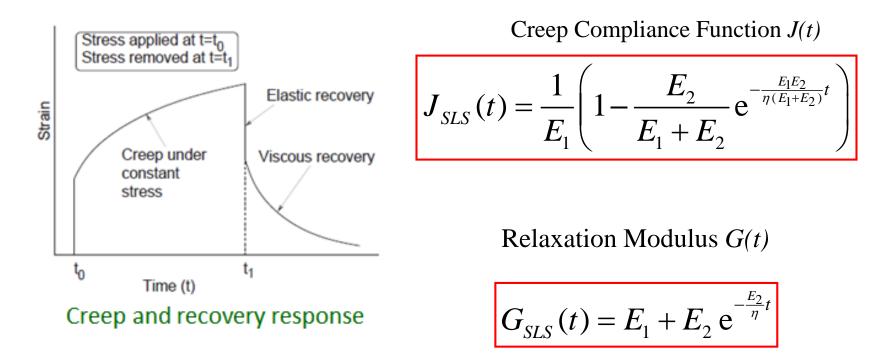
$$\eta(E_1 + E_2)\dot{\varepsilon} + E_1E_2\varepsilon = \eta\dot{\sigma} + E_2\sigma$$

$$\langle \downarrow \downarrow \rangle$$

SLS Model

 $\eta(E_1 + E_2)\dot{\varepsilon} + E_1E_2\varepsilon = \eta\dot{\sigma} + E_2\sigma$

Homework #1 – Derive the following two equations



It matches well to real linear viscoelastic behaviors!



Comparison of Several Models

Model	Creep compliance function $J(t)$	Relaxation modulus $G(t)$
Maxwell	$\frac{1}{E} \left(1 + \frac{E}{\eta} t \right)$	$E \mathrm{e}^{-rac{E}{\eta}t}$
Voigt-Kelvin	$\frac{1}{E} \left(1 - \mathrm{e}^{-\frac{E}{\eta}t} \right)$	$E + \eta \delta(t)$
Standard Linear Solid (Zener)	$\frac{1}{E_1} \left(1 - \frac{E_2}{E_1 + E_2} e^{-\frac{E_1 E_2}{\eta(E_1 + E_2)}t} \right)$	$E_1 + E_2 \mathrm{e}^{-\frac{E_2}{\eta}t}$



Comparison of Several Models

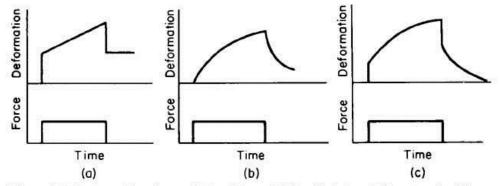


Figure 2.11:3 Creep functions of (a) a Maxwell, (b) a Voigt, and (c) a standard linear solid. A negative phase is superposed at the time of unloading.

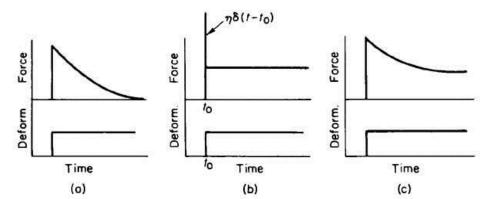


Figure 2.11:4 Relaxation functions of (a) a Maxwell, (b) a Voigt, and (c) a standard linear solid.

Homework #2 E_2 0000000 E_1 000000 η

Homework #11) Derive relaxation modulus and creep compliance2) Discuss the recovery response of the unit

Due on April ??

2021-04-05

